

# Machine Learning and Photonics

## Math Foundations: Numerical Differentiation

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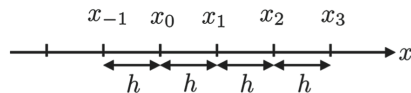
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If  $f(t, x)$  exists, you can determine speed and acceleration!

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# Numerical Grid

- 1 **Numerical grid:** An evenly spaced set of points over the domain of a function (i.e., the independent variable), over some interval.
- 2 The **spacing** or **step size** of a numerical grid: The distance between adjacent points on the grid.
- 3 If  $x$  is a numerical grid, then  $x_j$  is the  $j^{\text{th}}$  point in the numerical grid and  $h$  is the spacing between  $x_{j-1}$  and  $x_j$ .



# Numerical Grid: 1D vs 2D

Both in MATLAB and Python, you can easily create a numerical grid using `linspace`

```
linspace(0, 2, 5) ==> [0 0.5000 1.0000 1.5000 2.0000]
```

However, be careful

```
logspace(0, 2, 5) ==> [1.0000 3.1623 10.0000 31.6228 100.0000]
```

## 2D Grid

You can use *meshgrid* to create a 2D mesh. TRY IT!

Question: Can you drive an analytical expression for `logspace(a, b, N)`?

# Finite Difference Approximating Derivatives

The derivative  $f'(x)$  of a function  $f(x)$  at the point  $x = a$  is defined as:

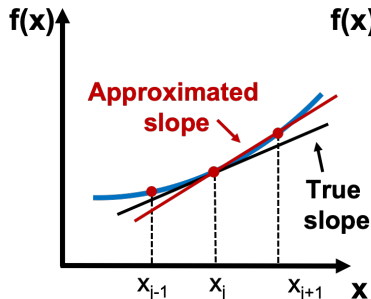
$$f'(a) = \lim_{x \rightarrow a} \frac{f(x) - f(a)}{x - a}$$

- The derivative at  $x = a$  is the slope at this point.
- In **finite difference** approximations of this slope, we can use values of the function in the neighborhood of the point  $x = a$  to achieve the goal.

# Finite Difference Approximating Derivatives (Cont...)

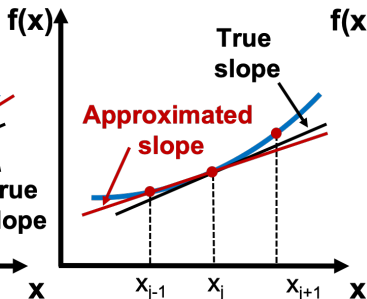
To estimate the slope of the function at  $x_j$

**Forward difference**



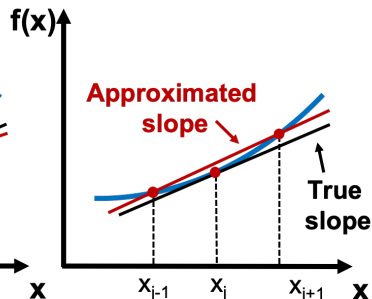
$$f'(x_j) = \frac{f(x_{j+1}) - f(x_j)}{x_{j+1} - x_j}$$

**Backward difference**



$$f'(x_j) = \frac{f(x_j) - f(x_{j-1})}{x_j - x_{j-1}}$$

**Central difference**



$$f'(x_j) = \frac{f(x_{j+1}) - f(x_{j-1}))}{x_{j+1} - x_{j-1}}$$

# Finite Difference Approximating Derivatives with Taylor Series

For an arbitrary function  $f(x)$  the Taylor series of  $f$  around  $a = x_j$  is

$$f(x) = \frac{f(x_j)(x - x_j)^0}{0!} + \frac{f'(x_j)(x - x_j)^1}{1!} + \frac{f''(x_j)(x - x_j)^2}{2!} + \frac{f'''(x_j)(x - x_j)^3}{3!} + \dots$$

If  $x$  is on a grid of points with spacing  $h$ , we can compute the Taylor series at  $x = x_{j+1}$  to get

$$f(x_{j+1}) = \frac{f(x_j)(x_{j+1} - x_j)^0}{0!} + \frac{f'(x_j)(x_{j+1} - x_j)^1}{1!} + \frac{f''(x_j)(x_{j+1} - x_j)^2}{2!} + \frac{f'''(x_j)(x_{j+1} - x_j)^3}{3!} + \dots$$

# Finite Difference Approximating Derivatives with Taylor Series

Substituting  $h = x_{j+1} - x_j$  and solving for  $f'(x_j)$  gives the equation

$$f'(x_j) = \frac{f(x_{j+1}) - f(x_j)}{h} + \left( -\frac{f''(x_j)h}{2!} - \frac{f'''(x_j)h^2}{3!} - \dots \right).$$

The terms that are in parentheses are called **higher order terms** of  $h$ , which can be rewritten as

$$-\frac{f''(x_j)h}{2!} - \frac{f'''(x_j)h^2}{3!} - \dots = h(\alpha + \epsilon(h)),$$

where  $\alpha$  is some constant, and  $\epsilon(h)$  is a function of  $h$  that goes to zero as  $h$  goes to 0.

# Finite Difference Approximating Derivatives with Taylor Series

We use the abbreviation " $\mathcal{O}(h)$ " for  $h(\alpha + \epsilon(h))$ , and in general, we use the abbreviation " $\mathcal{O}(h^p)$ " to denote  $h^p(\alpha + \epsilon(h))$ .

Substituting  $\mathcal{O}(h)$  into the previous equations gives

$$f'(x_j) = \frac{f(x_{j+1}) - f(x_j)}{h} + \mathcal{O}(h).$$

This gives the **forward difference** formula for approximating derivatives as

$$f'(x_j) \approx \frac{f(x_{j+1}) - f(x_j)}{h},$$

and we say this formula is  $\mathcal{O}(h)$ .

By computing the Taylor series around  $a = x_j$  at  $x = x_{j-1}$  and again solving for  $f'(x_j)$ , you can get the **backward difference** formula



# Central Difference Approximation with Taylor Series

First, let's compute the Taylor series around  $a = x_j$  at both  $x_{j+1}$  and  $x_{j-1}$

$$f(x_{j+1}) = f(x_j) + f'(x_j)h + \frac{1}{2}f''(x_j)h^2 + \frac{1}{6}f'''(x_j)h^3 + \dots$$

and

$$f(x_{j-1}) = f(x_j) - f'(x_j)h + \frac{1}{2}f''(x_j)h^2 - \frac{1}{6}f'''(x_j)h^3 + \dots$$

Then let's subtract them

$$f(x_{j+1}) - f(x_{j-1}) = 2f'(x_j)h + \frac{2}{3}f'''(x_j)h^3 + \dots,$$

Finally, solve for  $f'(x_j)$  (Note: this time it's  $\mathcal{O}(h^2)$ ) $\implies$

$$f'(x_j) \approx \frac{f(x_{j+1}) - f(x_{j-1}))}{2h}.$$

# More Points ==> Higher Accuracy

Let's take the Taylor series of  $f$  around  $a = x_j$  and compute the series at

$x = x_{j-2}, x_{j-1}, x_{j+1}, x_{j+2}$

$$f(x_{j-2}) = f(x_j) - 2hf'(x_j) + \frac{4h^2f''(x_j)}{2} - \frac{8h^3f'''(x_j)}{6} + \frac{16h^4f^{(4)}(x_j)}{24} - \frac{32h^5f^{(5)}(x_j)}{120} + \dots$$

$$f(x_{j-1}) = f(x_j) - hf'(x_j) + \frac{h^2f''(x_j)}{2} - \frac{h^3f'''(x_j)}{6} + \frac{h^4f^{(4)}(x_j)}{24} - \frac{h^5f^{(5)}(x_j)}{120} + \dots$$

$$f(x_{j+1}) = f(x_j) + hf'(x_j) + \frac{h^2f''(x_j)}{2} + \frac{h^3f'''(x_j)}{6} + \frac{h^4f^{(4)}(x_j)}{24} + \frac{h^5f^{(5)}(x_j)}{120} + \dots$$

$$f(x_{j+2}) = f(x_j) + 2hf'(x_j) + \frac{4h^2f''(x_j)}{2} + \frac{8h^3f'''(x_j)}{6} + \frac{16h^4f^{(4)}(x_j)}{24} + \frac{32h^5f^{(5)}(x_j)}{120} + \dots$$

# More Points ==> Higher Accuracy

To get the  $h^2$ ,  $h^3$ , and  $h^4$  terms to cancel out, we can compute

$$f(x_{j-2}) - 8f(x_{j-1}) + 8f(x_{j+1}) - f(x_{j+2}) = 12hf'(x_j) - \frac{48h^5 f''''(x_j)}{120}$$

which can be rearranged to

$$f'(x_j) = \frac{f(x_{j-2}) - 8f(x_{j-1}) + 8f(x_{j+1}) - f(x_{j+2}))}{12h} + O(h^4).$$

# Some Tips

Both in MATLAB and Python, you can compute finite differences directly. For a vector  $f$ , the command  $d = \text{diff}(f)$ ; and  $d = \text{np.diff}(f)$ , respectively, produces an array  $d$  in which the entries are the differences of the adjacent elements in the initial array  $f$ .  
i.e.,  $d(i) = f(i+1) - f(i)$ .

The length of  $d$  will be  $N - 1$ , assuming  $f$  has  $N$  data points.

## Example: $f(x) = \cos(x)$

```
: import numpy as np
import matplotlib.pyplot as plt
plt.style.use('seaborn-poster')
%matplotlib inline
```

Note that *matplotlib inline* allows us to have the plots directly below the cell in the notebook.

```
: # step size
h = 0.1
# define grid
x = np.arange(0, 2*np.pi, h)
# compute function
y = np.cos(x)

# compute vector of forward differences
forward_diff = np.diff(y)/h
# compute corresponding grid
x_diff = x[:-1:]
# compute exact solution
exact_solution = -np.sin(x_diff)
```

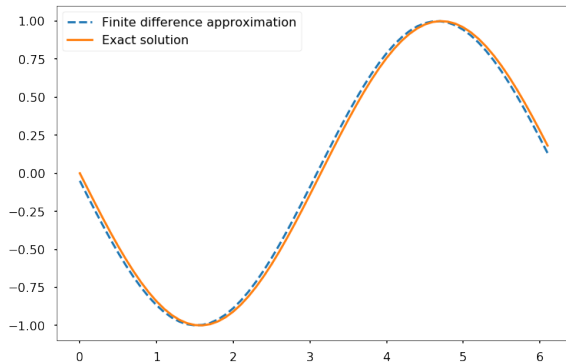


## Example: $f(x) = \cos(x)$ (Cont...)

```
# Plot solution
plt.figure(figsize = (12, 8))
plt.plot(x_diff, forward_diff, '--', \
         label = 'Finite difference approximation')
plt.plot(x_diff, exact_solution, \
         label = 'Exact solution')
plt.legend()
plt.show()

# Compute max error between
# numerical derivative and exact solution
max_error = max(abs(exact_solution - forward_diff))
print(max_error)
```

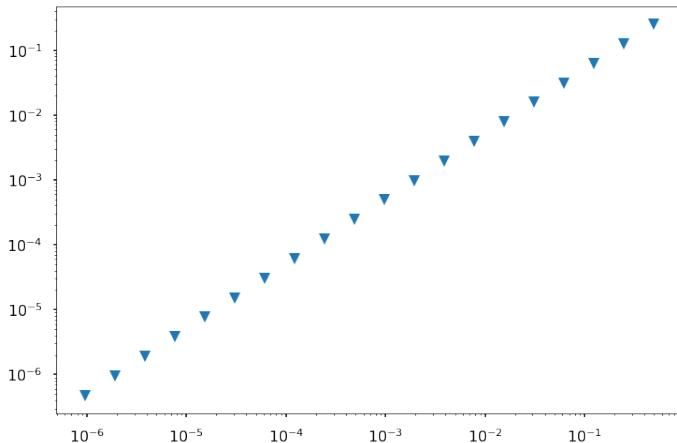
## Example: $f(x) = \cos(x)$ (Cont...)



Maximum Error: 0.04999

## Example: $f(x) = \cos(x)$ (Cont...)

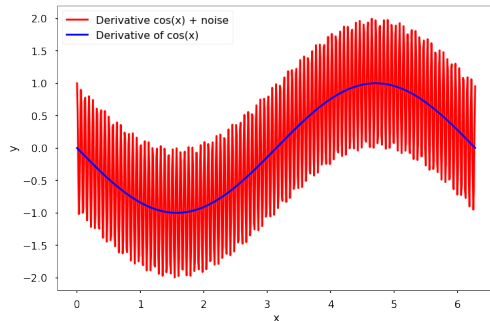
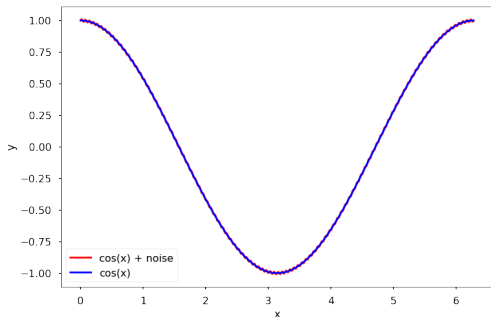
### Step-size vs. Maximum Error





# Numerical Differentiation with Noise

Consider  $f(x) = \cos(x)$  vs.  $f_{\epsilon,\omega}(x) = \cos(x) + \epsilon \sin(\omega x)$  where  $0 < \epsilon \ll 1$  is a very small number and  $\omega$  is a large number, e.g.  $\epsilon = 0.01$  and  $\omega = 100$



# Approximating of Higher Order Derivatives

Let's take the Taylor series around  $a = x_j$  and then compute it at  $x = x_{j-1}$  and  $x_{j+1}$

$$f(x_{j-1}) = f(x_j) - hf'(x_j) + \frac{h^2 f''(x_j)}{2} - \frac{h^3 f'''(x_j)}{6} + \dots$$

and

$$f(x_{j+1}) = f(x_j) + hf'(x_j) + \frac{h^2 f''(x_j)}{2} + \frac{h^3 f'''(x_j)}{6} + \dots$$

If we add these two equations together, we get

$$f(x_{j-1}) + f(x_{j+1}) = 2f(x_j) + h^2 f''(x_j) + \frac{h^4 f''''(x_j)}{24} + \dots,$$

and with some rearrangement gives the approximation

$$f''(x_j) \approx \frac{f(x_{j+1}) - 2f(x_j) + f(x_{j-1}))}{h^2},$$

and is  $\mathcal{O}(h^2)$ .