



PA#3: Malloc Dynamic Memory Allocator

SCE213 (Operating Systems)
Spring 2022

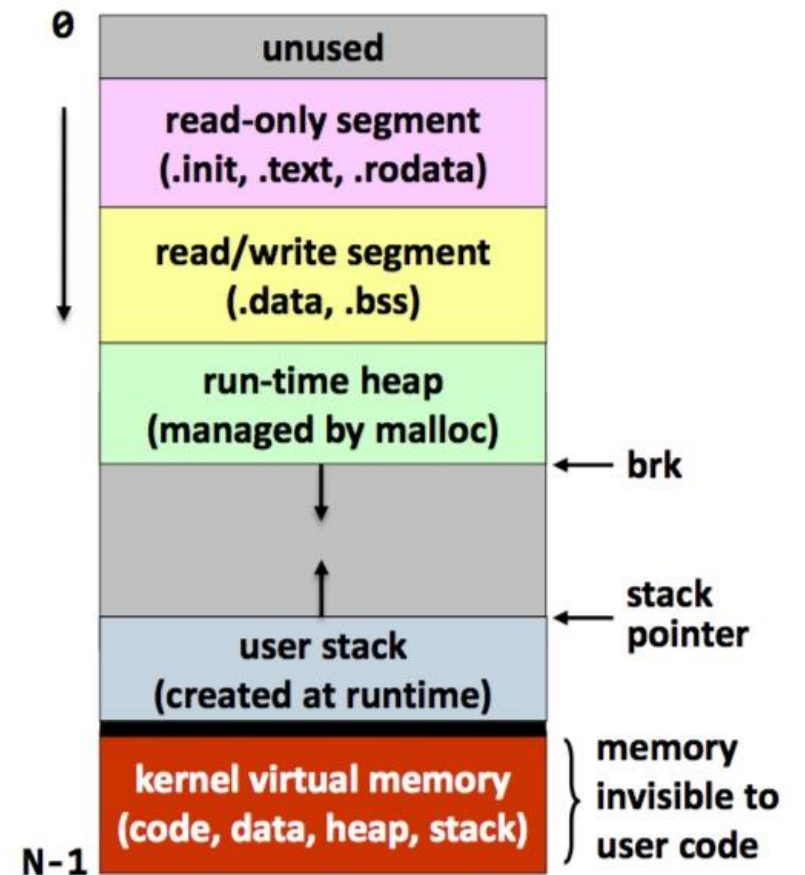
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Goal

- Dynamic Memory Allocator
 - Implement the dynamic memory allocation functions:
 - `my_malloc()`
 - `my_realloc()`
 - `my_free()`
 - The functions behave similarly to the POSIX standard functions, such as `malloc()`, `realloc()`, `free()`

Process Address Space

- Process's abstract view of memory
 - Static area
 - Code & Data
 - Dynamic area
 - Allocated at runtime
 - Can grow or shrink
 - Stack & Heap



Dynamic Area (Stack & Heap)

- Stack
 - The region of the stack that provides the execution environment of a *particular* call to a function
 - The function arguments and local variables is stored in stack
- Heap
 - Unlike stack memory, heap memory is allocated explicitly by programmers and it won't be deallocated until it is explicitly freed
 - Heap memory is managed by `malloc()`, `realloc()`, `free()`, etc.

External Fragmentation in Heap

- There is enough aggregate heap memory, but no single free block is large enough

p1 = malloc(4)



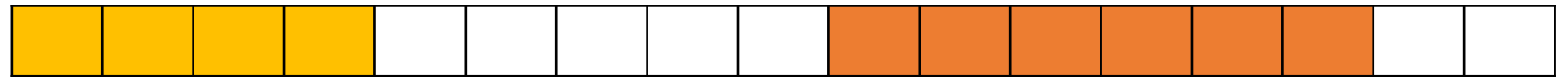
p2 = malloc(5)



p3 = malloc(6)



free(p2)



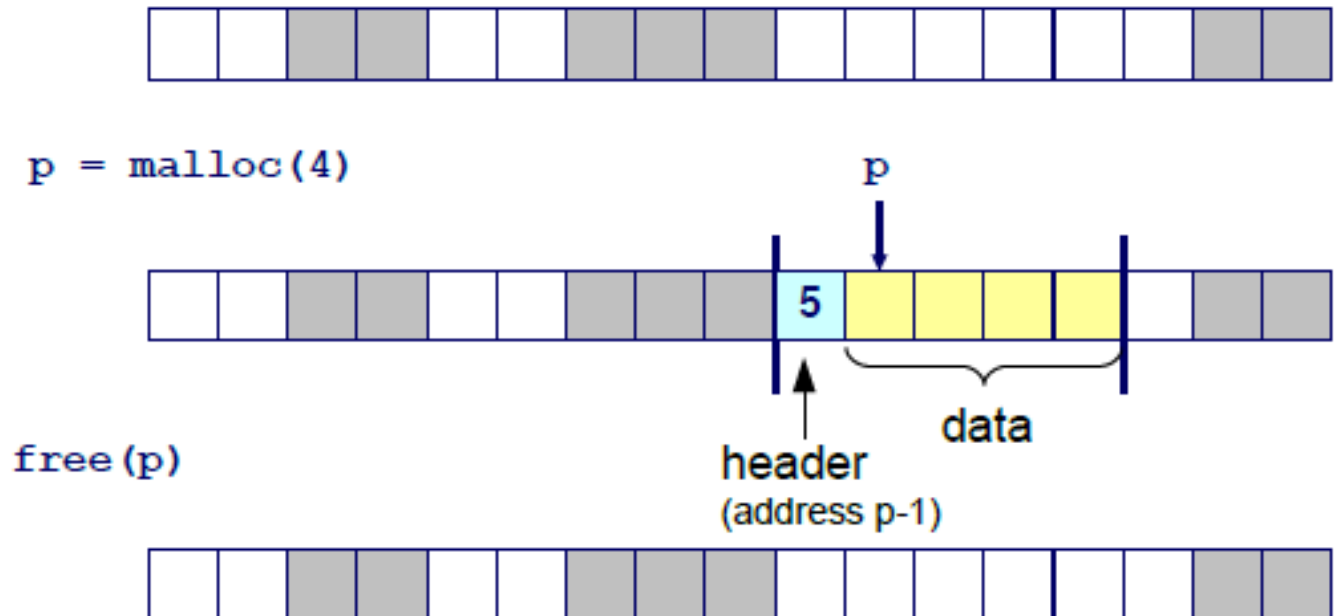
p4 = malloc(6)

Oops! (what would happen now?)

Depends on the pattern of future requests
Difficult to plan for

Implementation issues you need to solve!

- How do I know how much memory to free just given a pointer?
- Keep the length of the block in the header preceding the block
- Requires an extra word for every allocated block

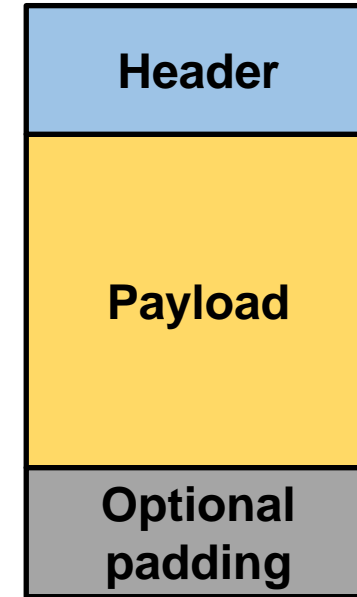


Keeping Track of Free Blocks

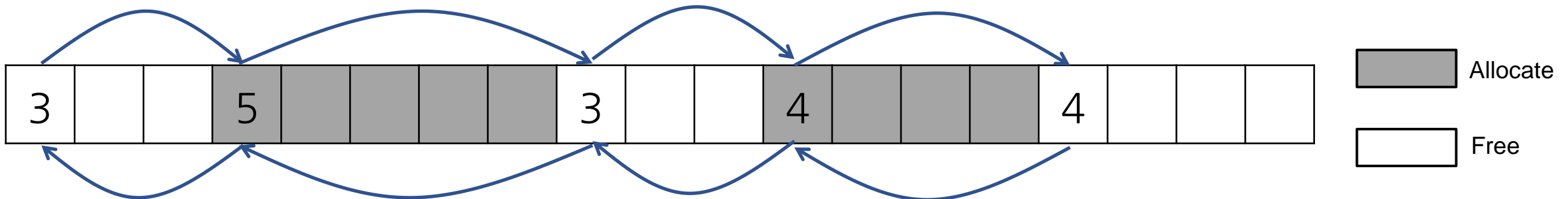
- One of the biggest jobs of an allocator is knowing where the free memory is
- The allocator's approach to this problem affects:
 - Throughput - time to complete a **malloc()** or **free()**
 - Space utilization - amount of extra metadata used to track location of free memory
- There are many approaches to free space management

Free List

- For each block we need both size and allocation status
- **Header** contain metadata
 - Allocation status
 - Size
 - List_head
- Payload: application data

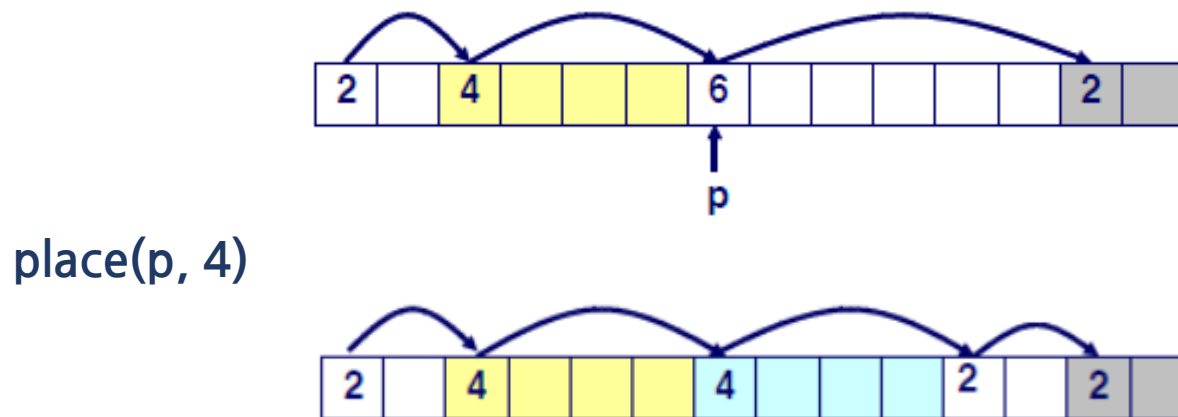


Memory Block

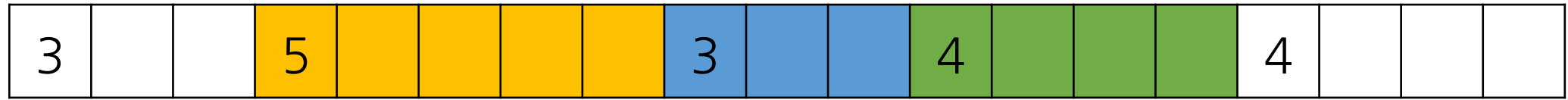


Allocating a Block

- Splitting free blocks
 - Since allocated space might be smaller than free space, we may need to split the free block that we're allocating within

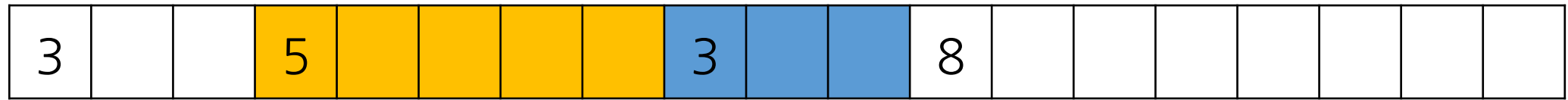


Free List: Bidirectional Coalescing



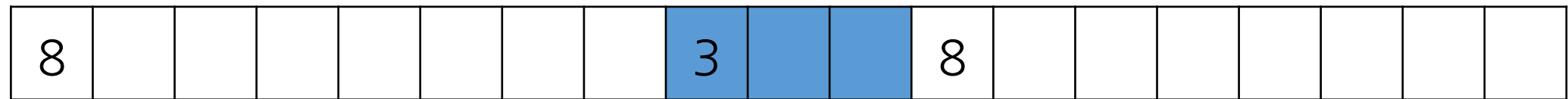
free(p1)

p1



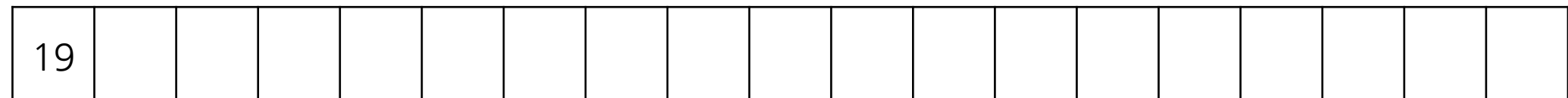
free(p2)

p2



free(p3)

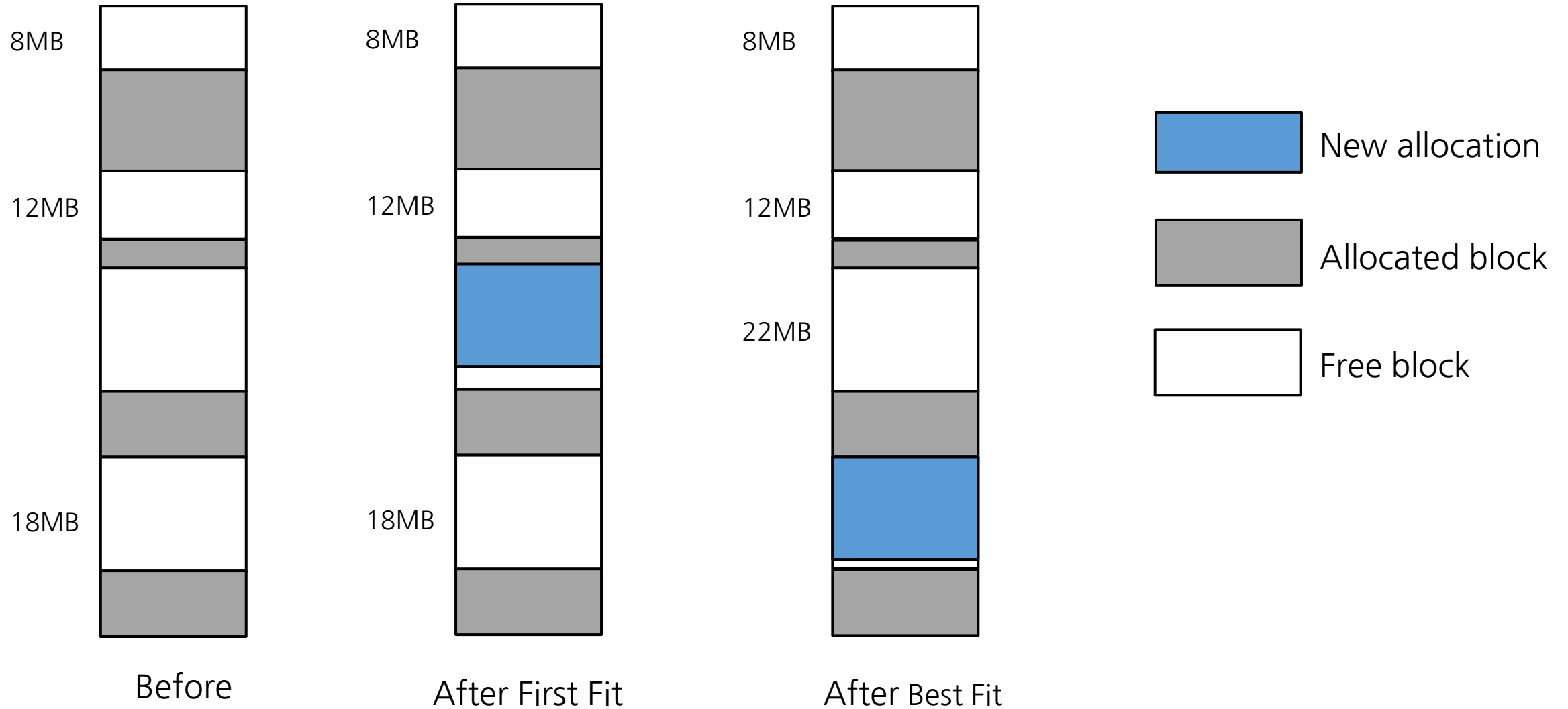
p3



How do we find a free block?

- There are dynamic partitioning placement algorithm
 - First Fit
 - Start scanning from the beginning of the heap
 - Traverse each block until (a) we find a free block and (b) the block is large enough to handle the request.
 - Best Fit
 - Traverse all free blocks and considers the smallest free block that is adequate.
 - Try to find a free block which is close to actual memory size needed.

Placement Algorithm



So what should I do for PA#3?

- Implement dynamic memory allocation functions
 - `my_malloc()`
 - `my_realloc()`
 - `my_free()`
- You should only `sbrk()` to implement `my_malloc()` and `my_realloc()` instead `malloc()` family functions
 - `sbrk()` increments the program's data space by increment bytes
 - You will get 0 pts if you use it
- All allocation sizes are aligned by **32 bytes**

PA#3: Deliverables

- Submission by June 27th, 11:59 PM
 - Submit only **malloc.c** for the code
- [PAsubmit](#)
 - Start project by cloning PA#3 repository
git clone <https://github.com/csl-ajou/sce213-project3>