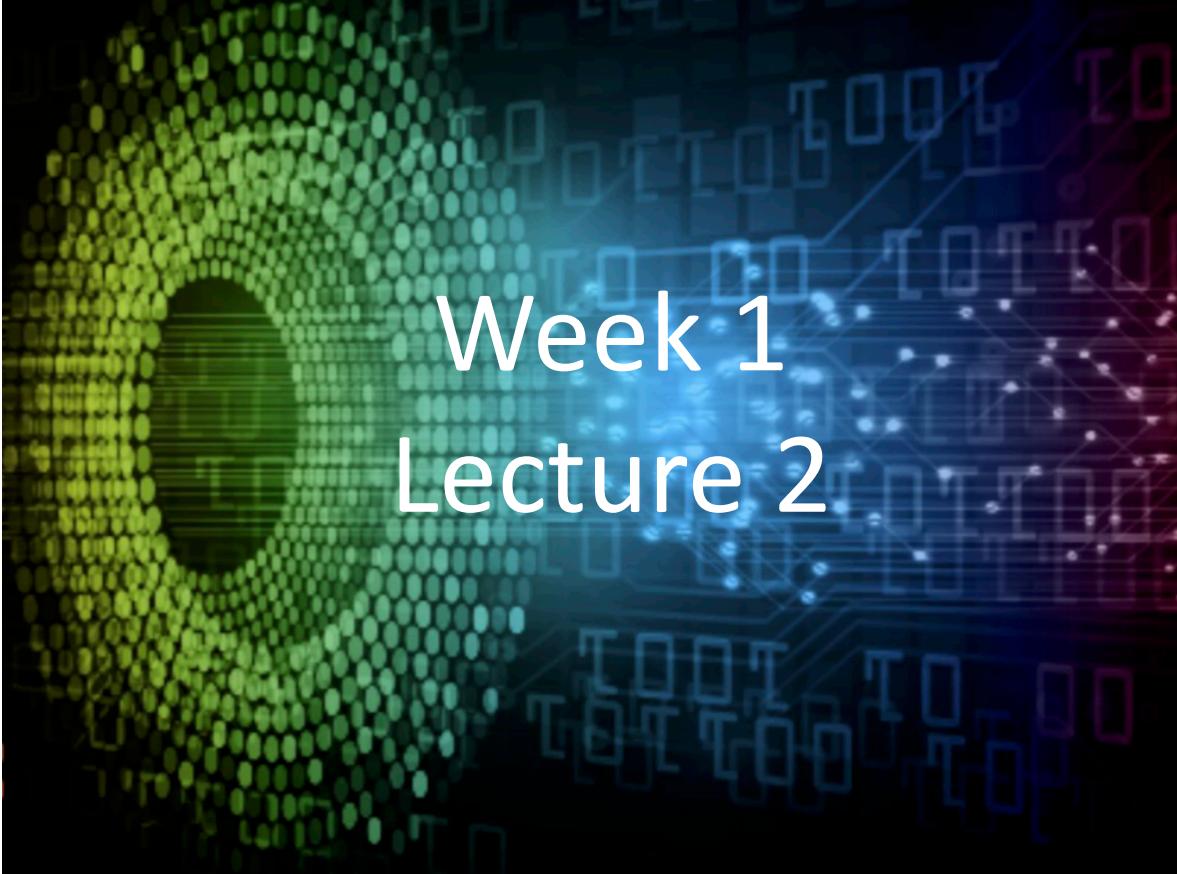


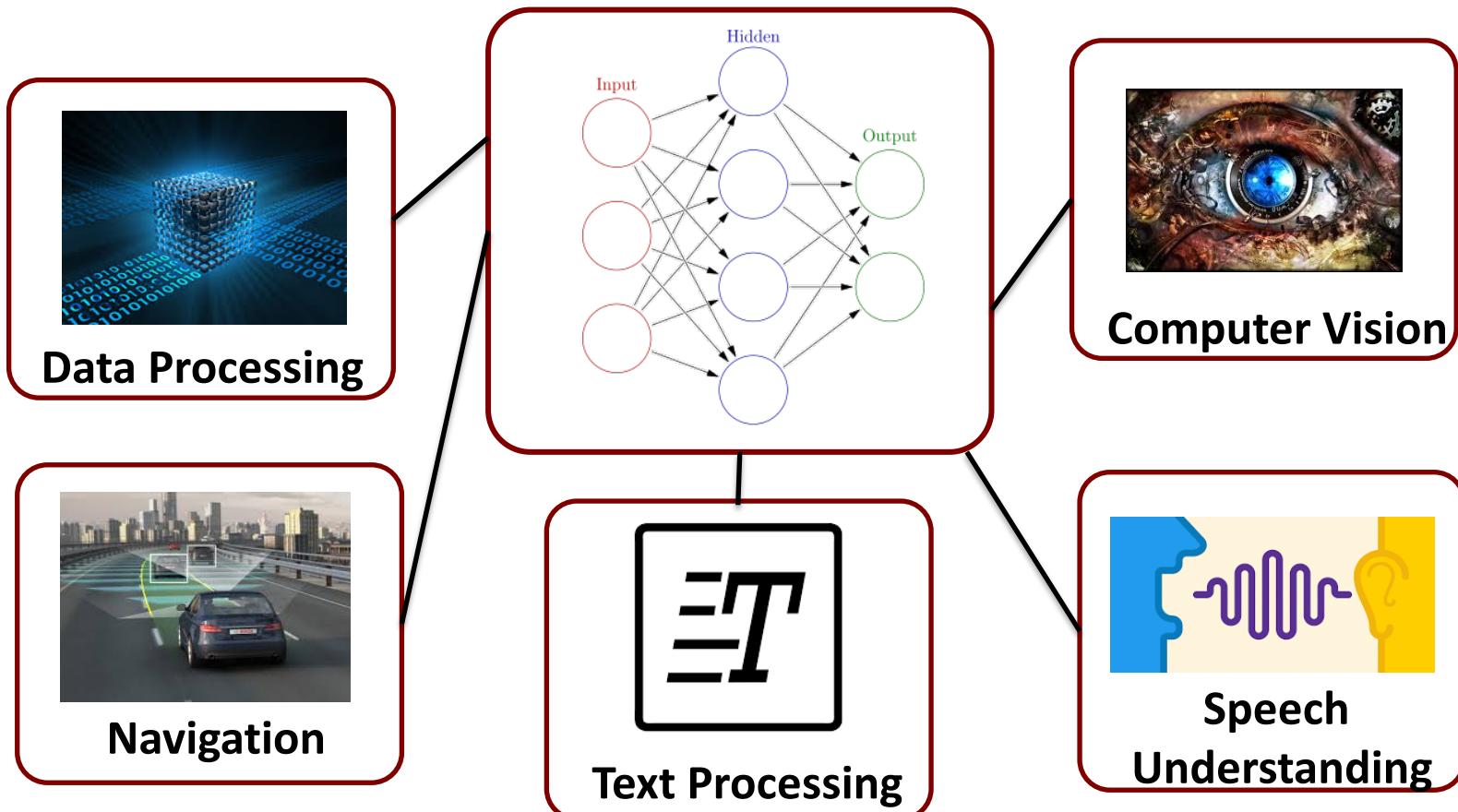
Introduction to Deep Learning Applications and Theory



Week 1
Lecture 2

ECE 596 / AMATH 563

Previous Lecture: Artificial Neural Nets (ANN)

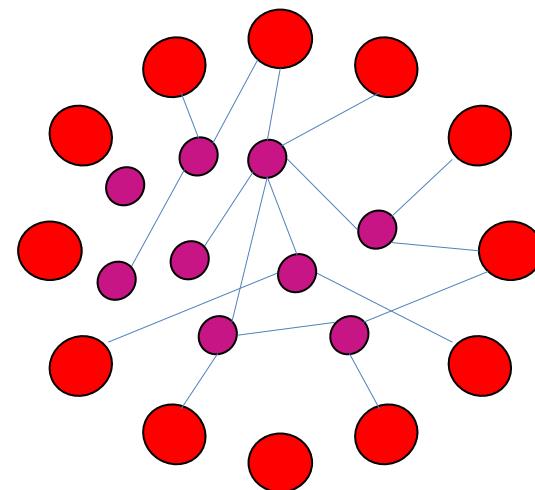
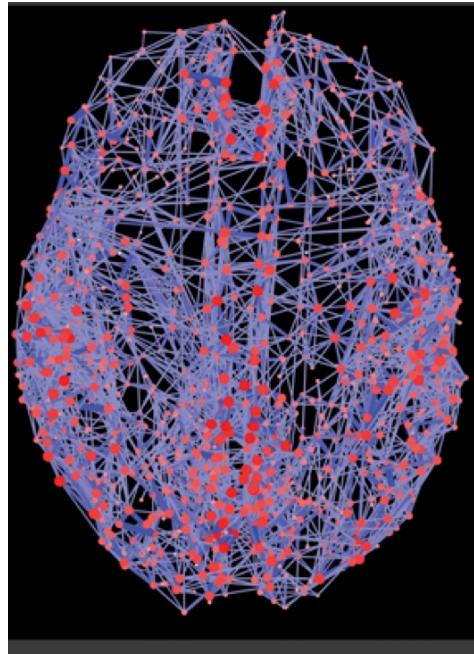


Previous Lecture: Neural Networks / DL

“Deep Learning is the new electricity”

Andrew Ng

This Lecture: Learning from the Brain



Neurons and Networks



Properties of Brain Networks and Learning

1. Neurons: simple computational units
2. Well connected
3. Parallelism and Recurrence
4. Hierarchically structured
5. Learning
 1. Features
 2. Changing connections

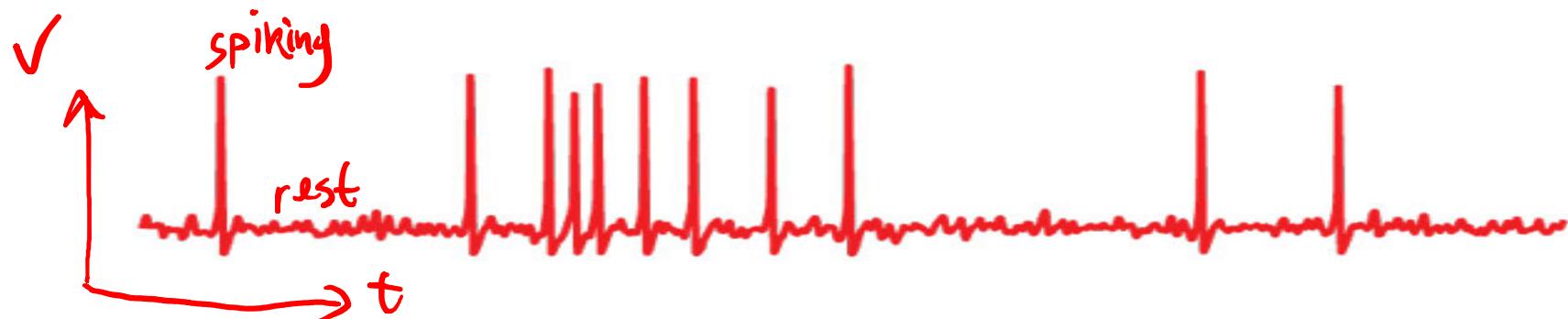
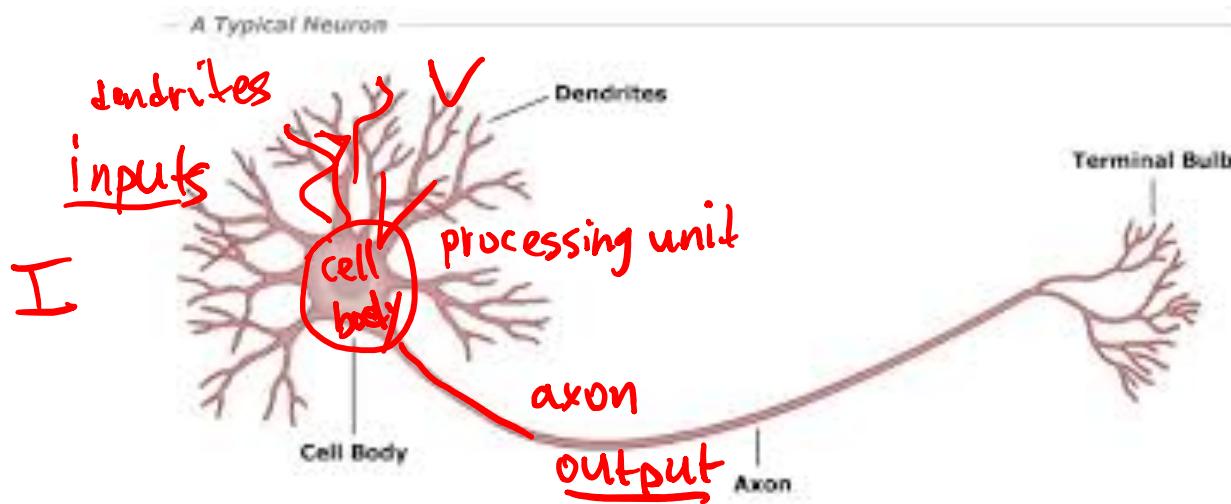
Construct

INN

Train / Learn

Brain Neuronal Networks

- Neurons: simple computational units



Brain Neuronal Networks

1. Neurons: simple computational units

Spike train

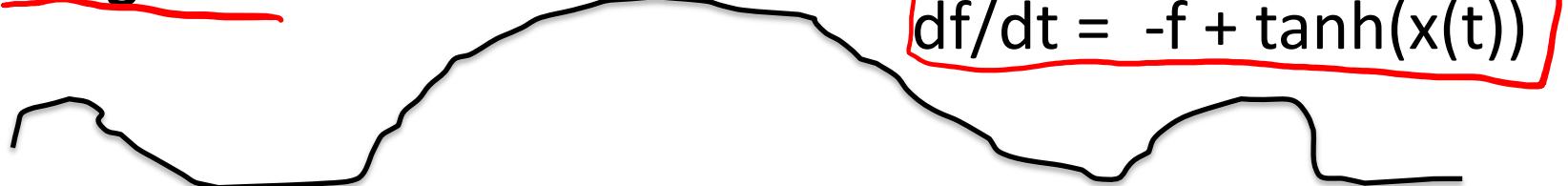


Binary

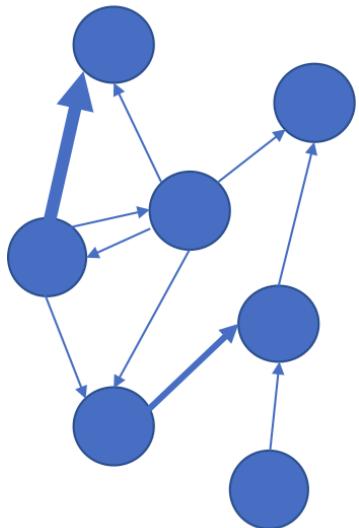
0	1	0	0	1	1	1	1	0						
---	---	---	---	---	---	---	---	---	--	--	--	--	--	--

Firing rate

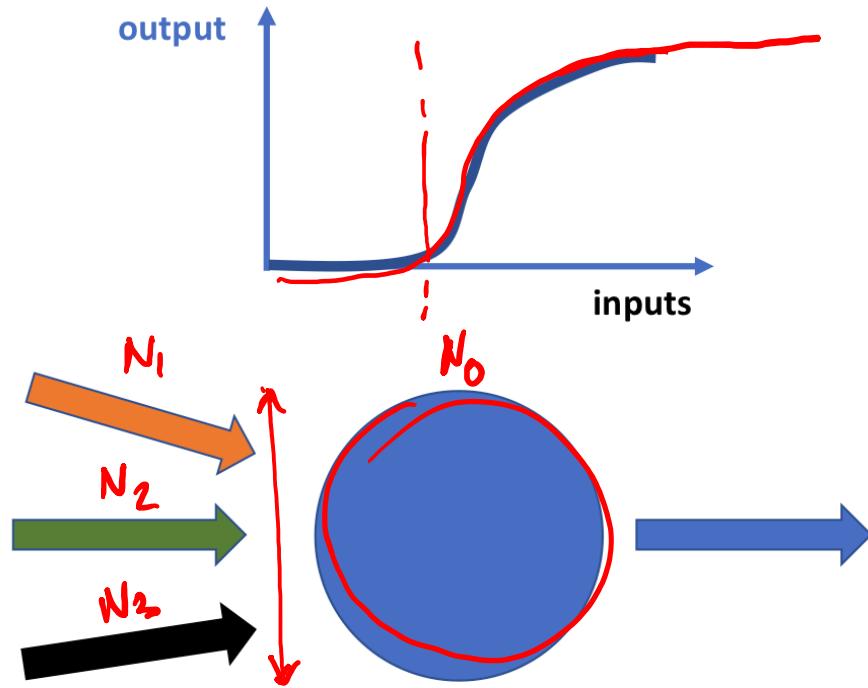
$$\frac{df}{dt} = -f + \tanh(x(t))$$



Firing rate units



Firing-rate model

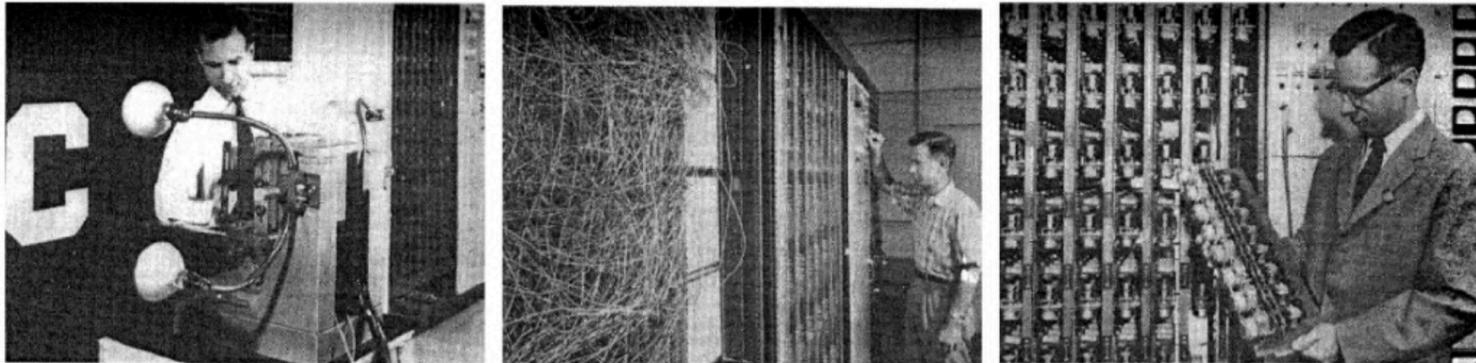


inputs (synapses):
from other units

neuron:
firing-rate unit

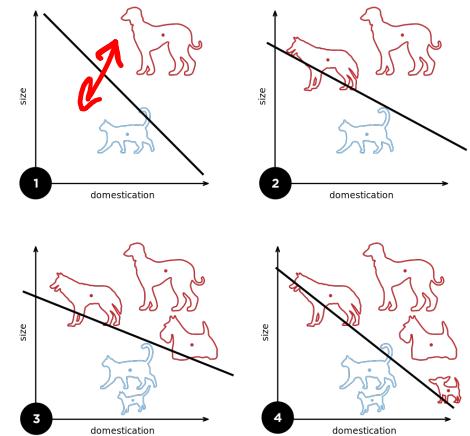
output:
to other units

Perceptron



$$f(x) = \begin{cases} 1 & \text{if } \underline{w} \cdot \underline{x} + b > 0 \\ 0 & \text{otherwise} \end{cases}$$

Network trains its weights based on **labeled training** data, i.e. optimizes **cost** function between expected outputs and actual outputs



The perceptron, 1957

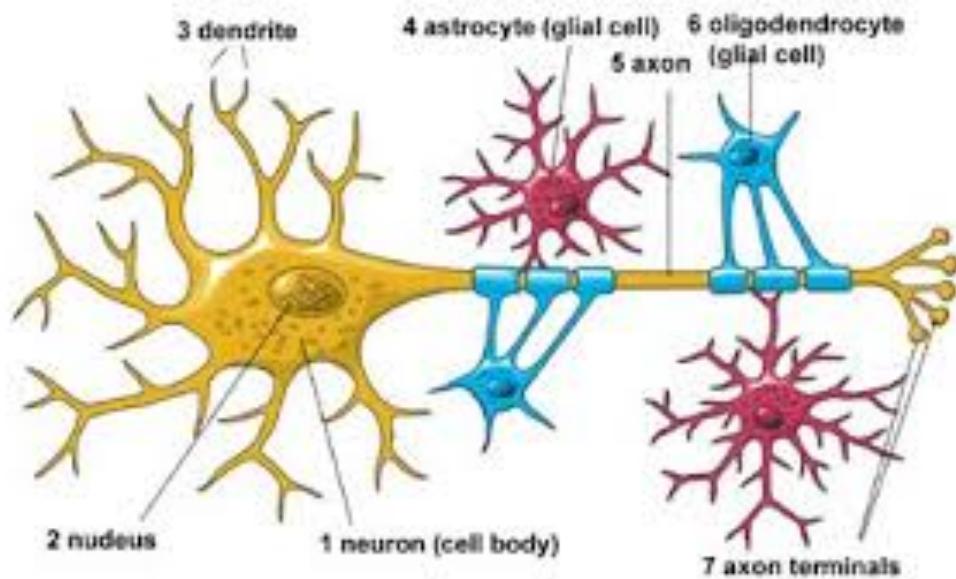
Neuronal Networks

2. Well Connected

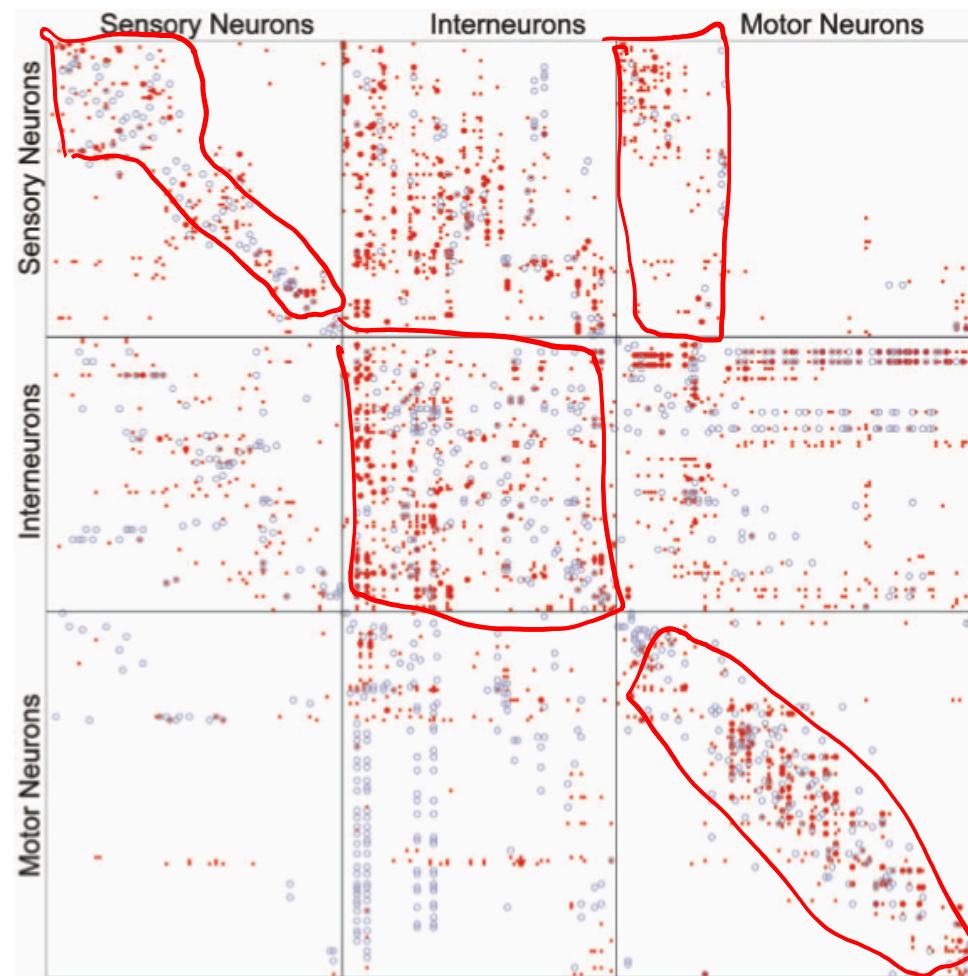
Human Brain

10^{11} neurons

10^{14} connections (synapses)



Connectome

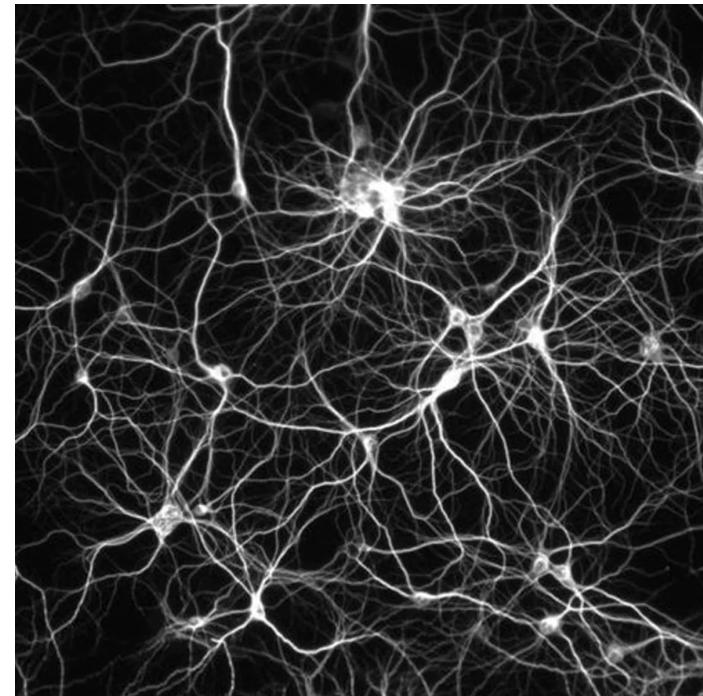


C. elegans
300 neurons

Neuronal Networks

3. Parallelism

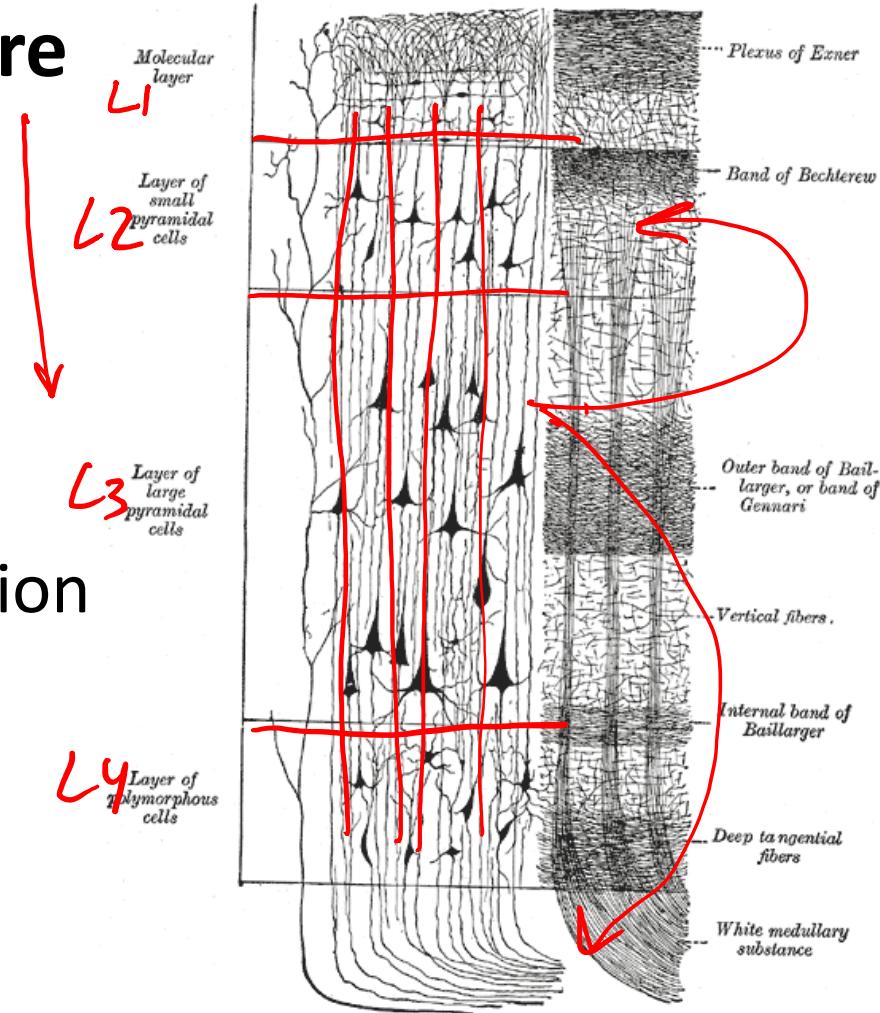
- Computations done on various scales
- Many recurrences



Hierarchical Layered Structure

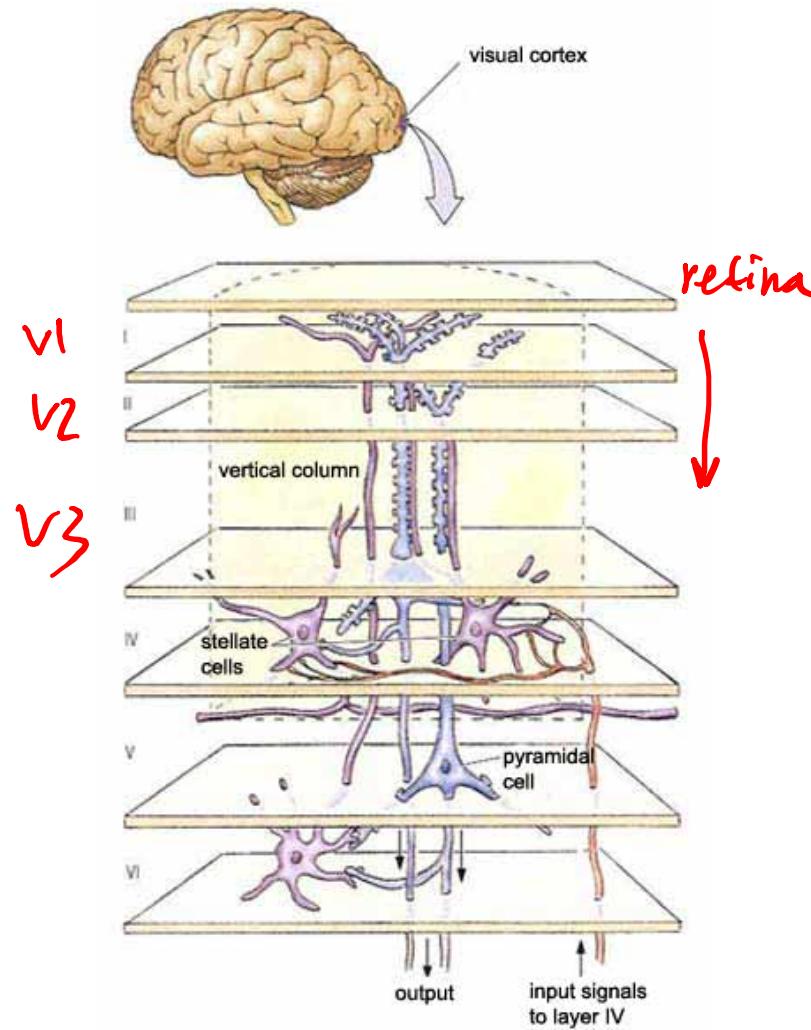
4. Hierarchical Structure on System Level

- Layers
- Columns
- Defined Flow
- Functional Organization
- Feedback



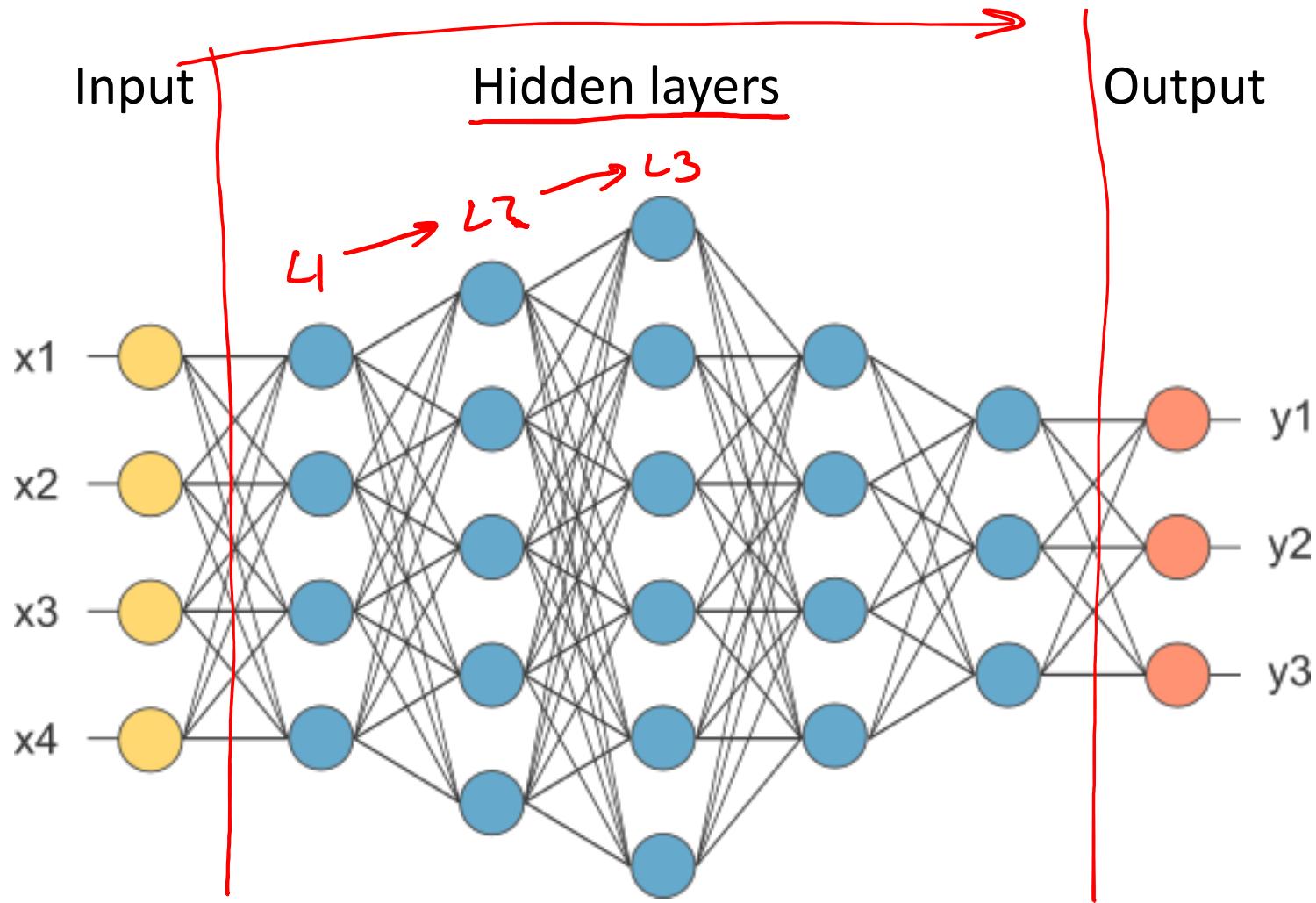
Cerebral cortex

The Visual Cortex

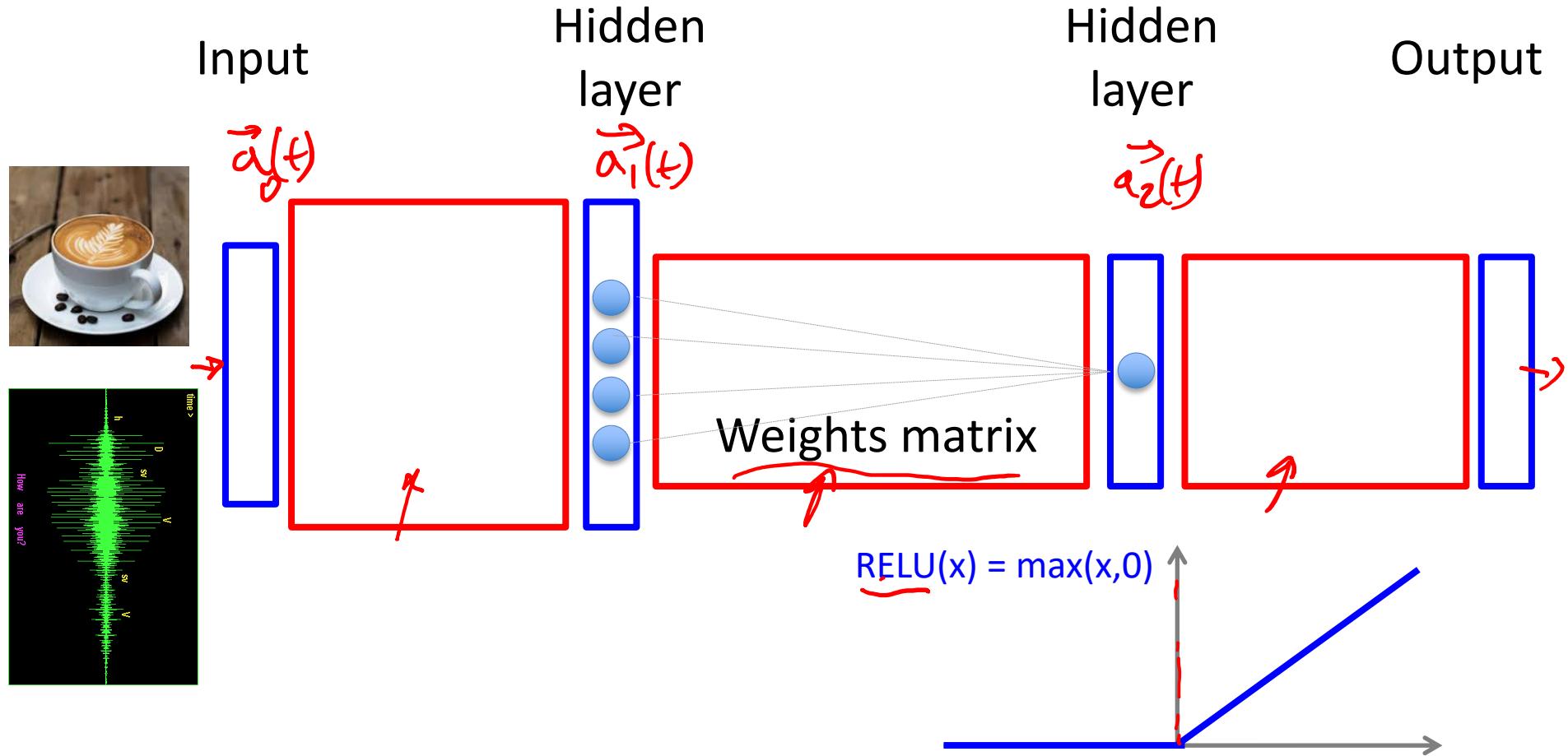


Cerebral cortex

Deep Neural Networks



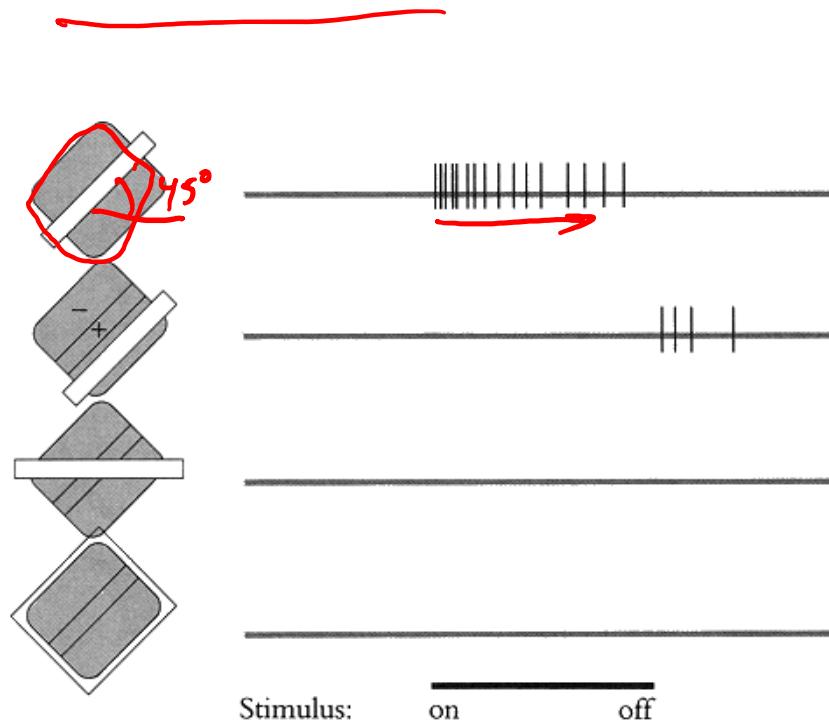
Deep Neural Networks - Forward Propagation



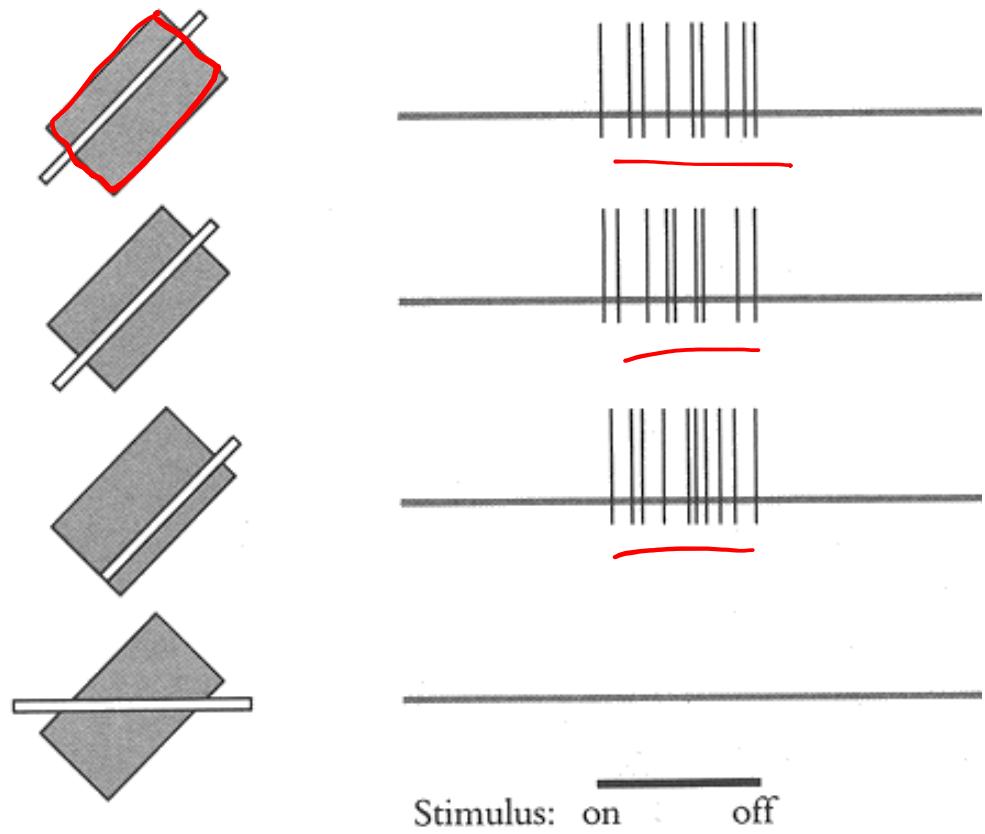
- Multiple layers of simple units
- Each unit computes a weighted sum of its inputs
- Weighted sum is passed through a nonlinear function
- The learning algorithm changes the **weights**

Visual System

Simple Cells



Complex Cells



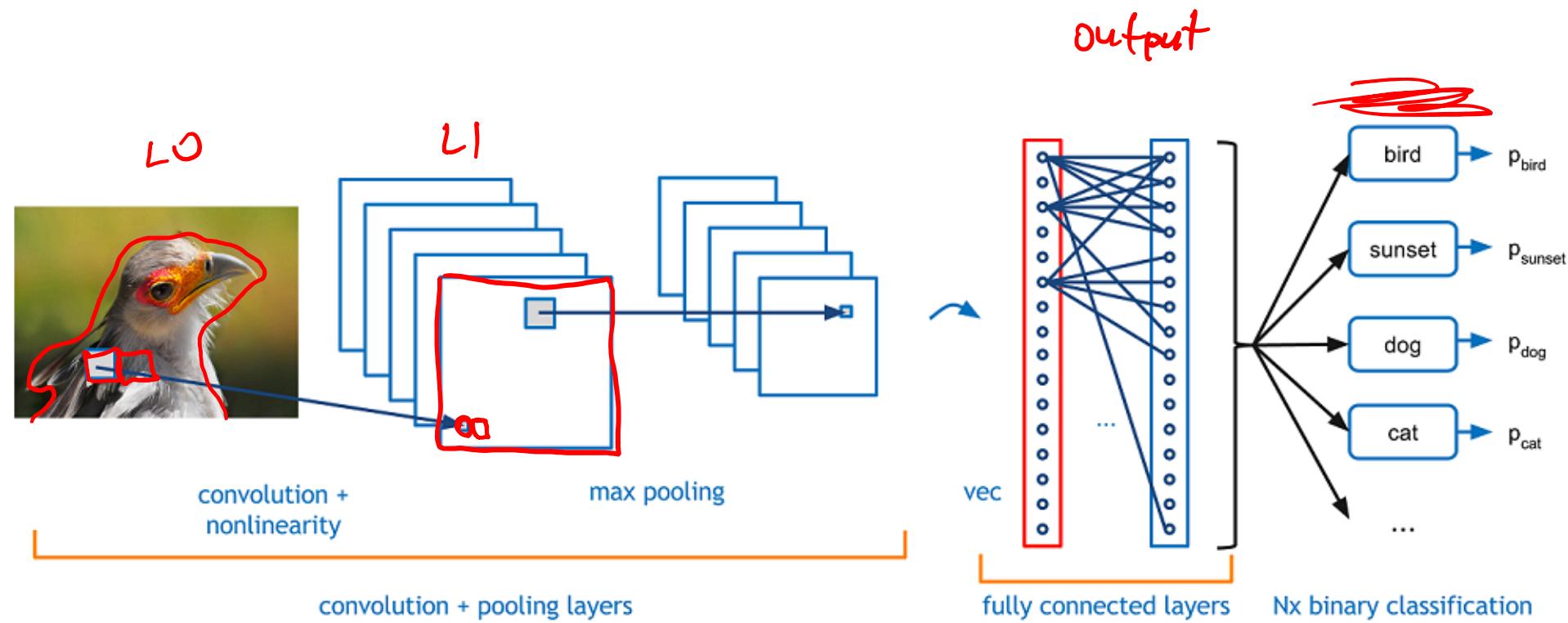
Receptive Fields, Hubel & Weisel, 1959-62 (Nobel Prize)



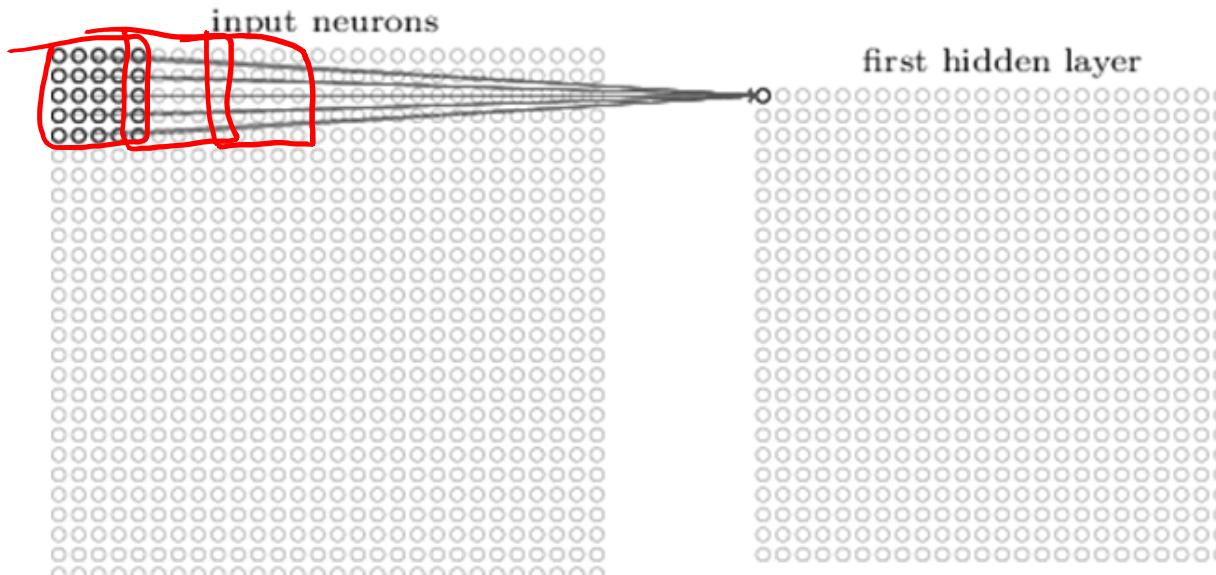
Receptive Fields, Hubel & Weisel (Nobel Prize)

~~Complex cortical cell~~

Convolutional Nets (CNNs)



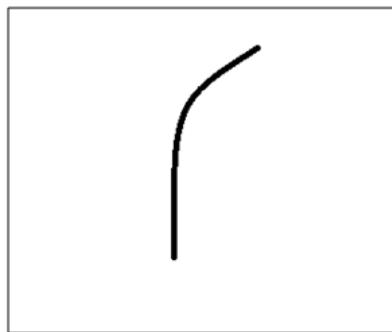
Convolutional Nets



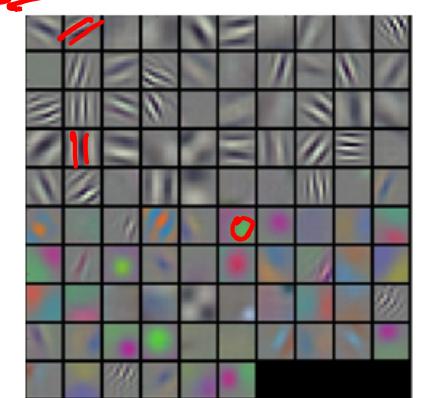
Visualization of 5×5 filter convolving around an input volume and producing an activation map

0	0	0	0	0	30	0
0	0	0	0	30	0	0
0	0	0	30	0	0	0
0	0	0	30	0	0	0
0	0	0	30	0	0	0
0	0	0	30	0	0	0
0	0	0	0	0	0	0

Pixel representation of filter



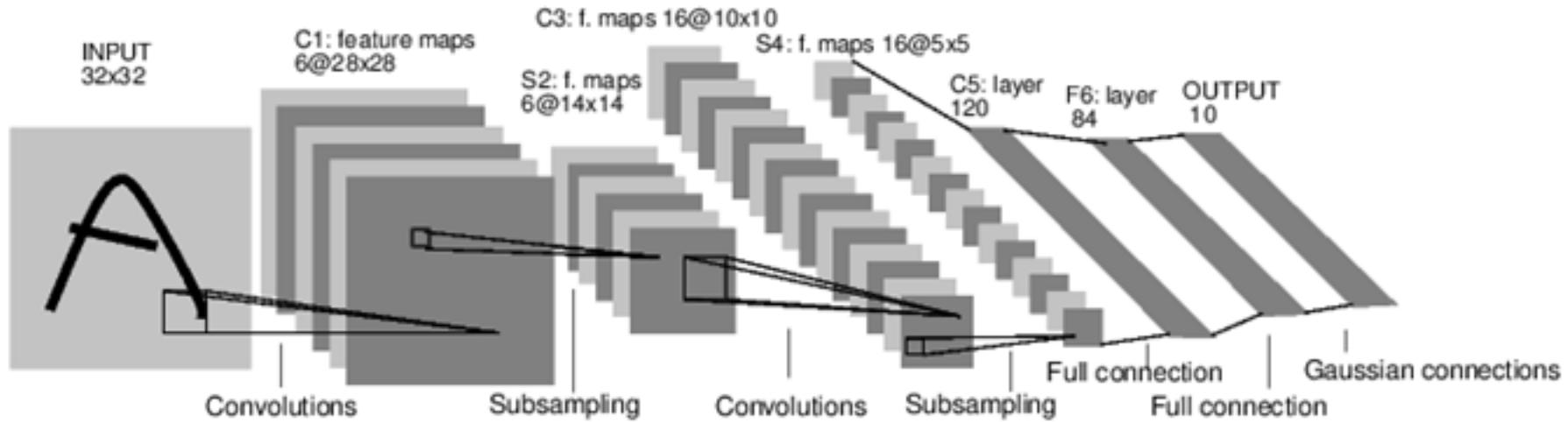
Visualization of a curve detector filter



Visualizations of filters

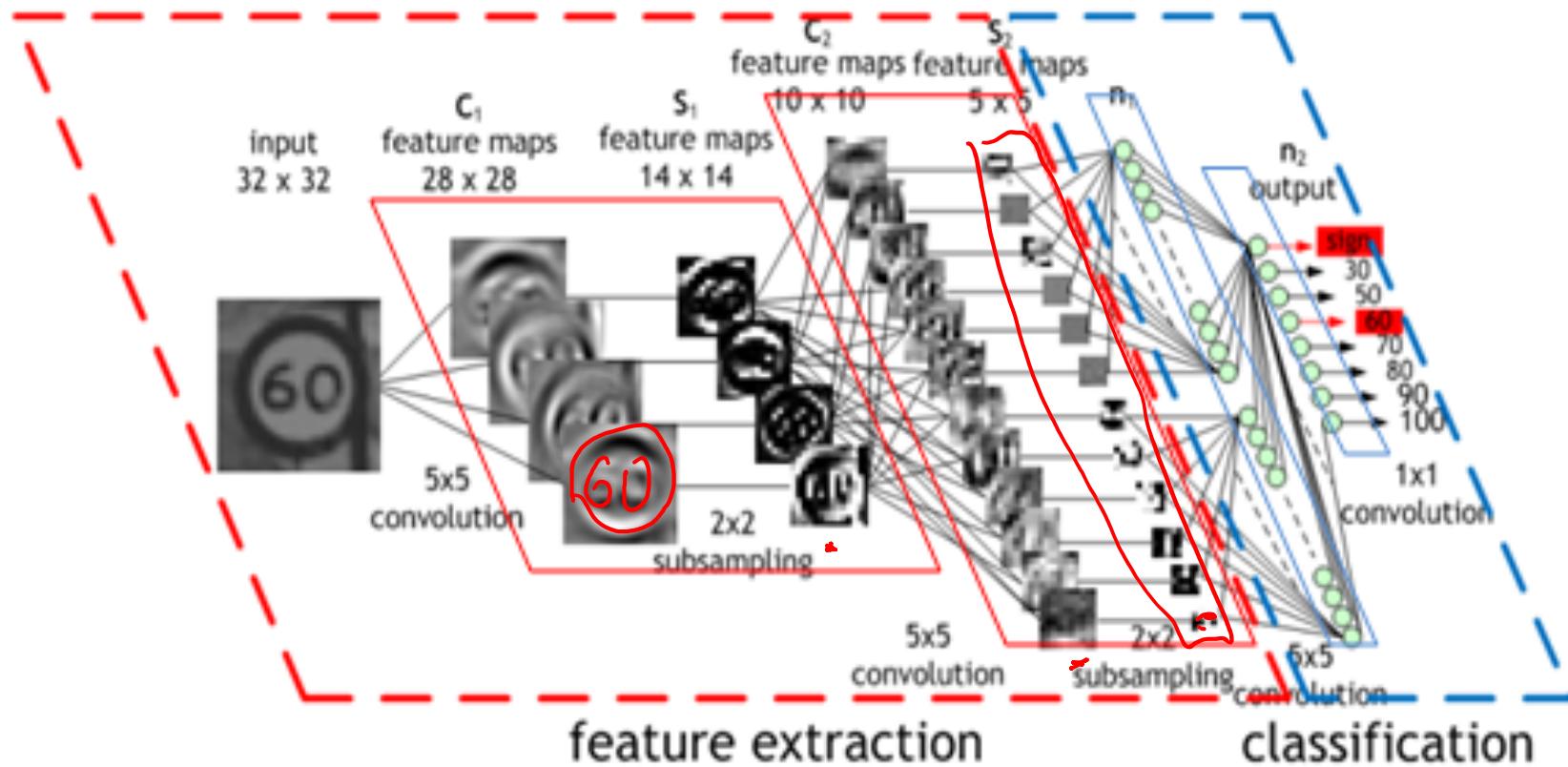
Convolutional Nets

- LeNet 5 (Handwriting recognition)



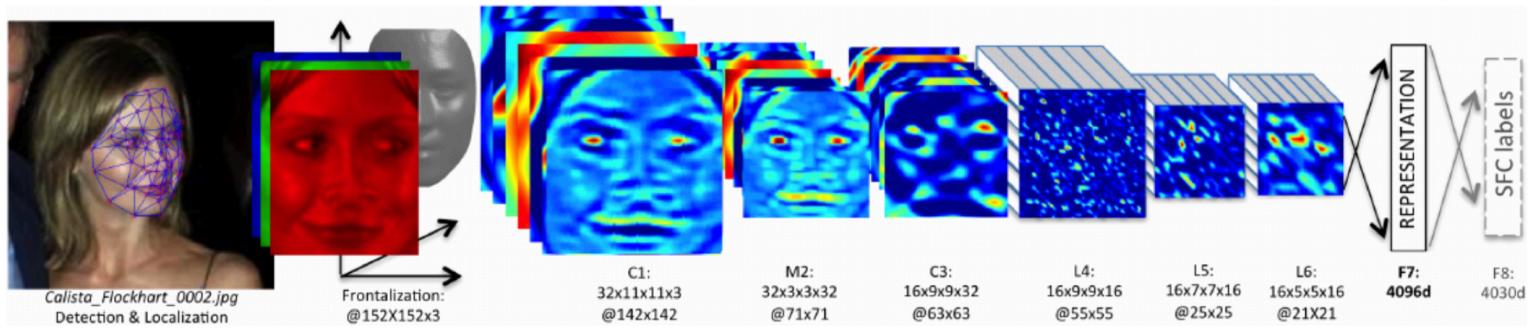
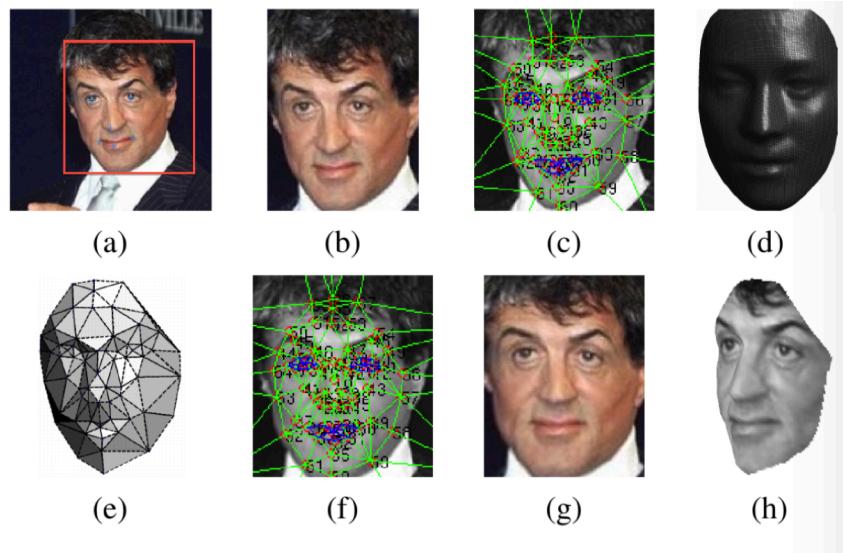
A Full Convolutional Neural Network (LeNet)

Convolutional Nets



Deep Faces - Face Recognition

- Deployed at Facebook for each uploaded photo
> 1 Billion photos per day

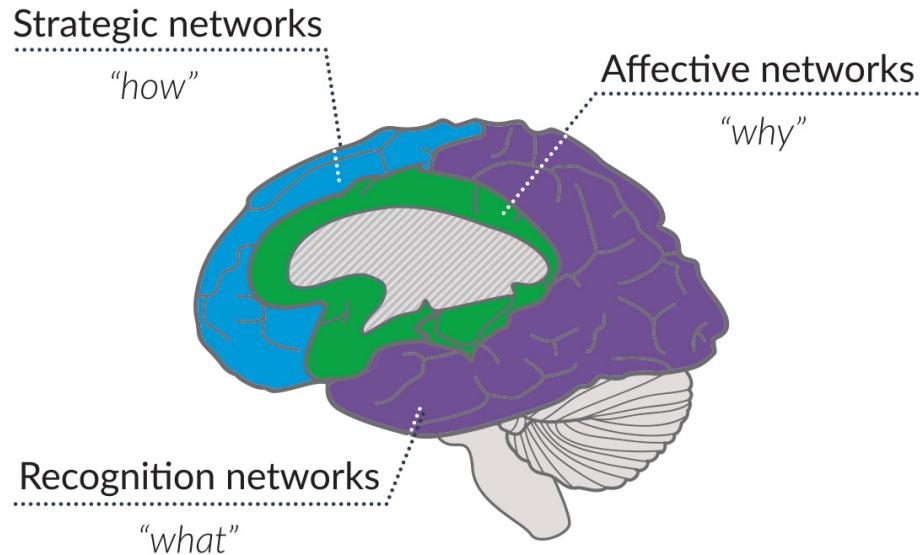


Taigman et al. 2014

Learning



Learning

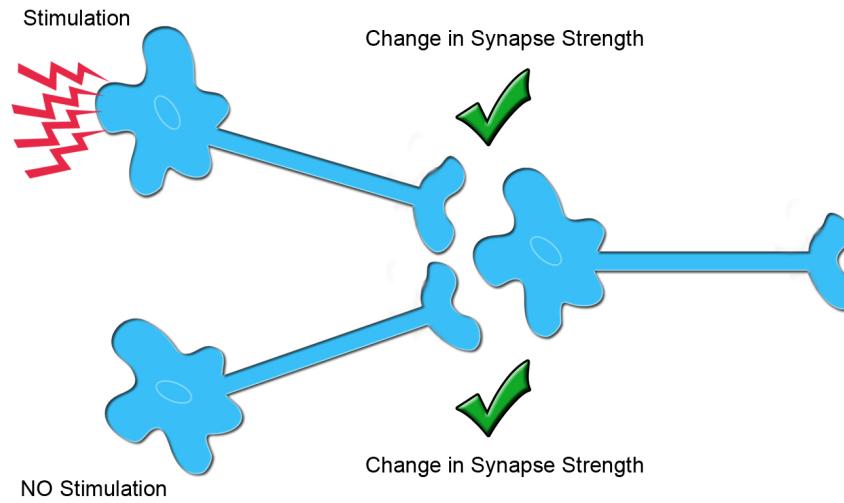


cost function

5.1 Feature Extraction

- Classification/Recognition
- Regression Direct
- Regression Indirect

Learning



5.2 Synaptic Plasticity

- Adaptive connections
- The “strength” of synapses changes

Training (Learning)

- Supervised Learning

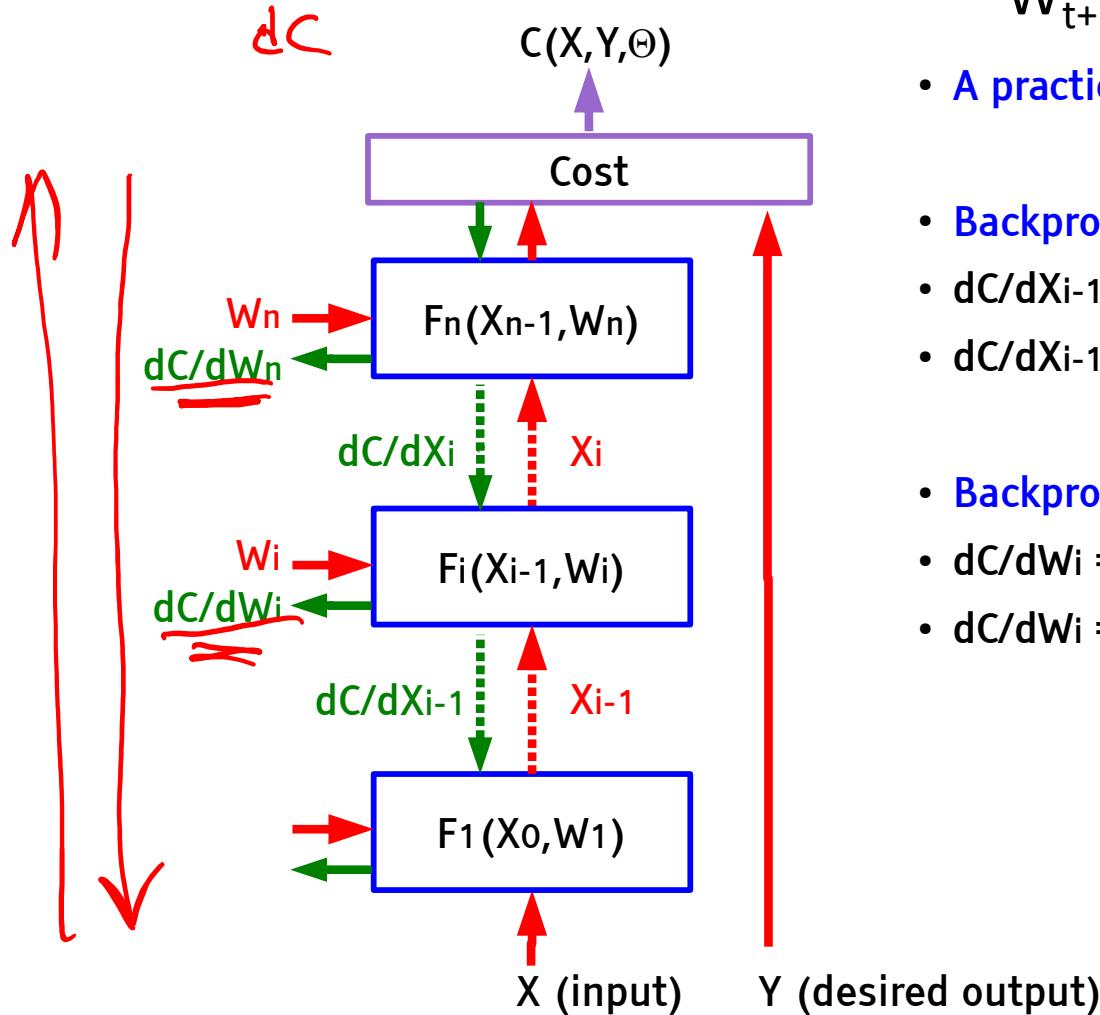
Network trains its weights based on **labeled training** data,
i.e. optimizes cost function between expected outputs and
actual outputs

$$\underline{D} = \{\{x_1, d_1\}, \{x_2, d_2\}, \dots, \{x_m, d_m\}\}$$

↑ ↑
input label

$$J = \sum_k (y_k - d_k)^2$$

Back Propagation



$$W_{t+1} = W_t - \alpha \frac{dC}{dW_t}$$

- A practical Application of Chain Rule

- Backprop for the state gradients:

- $\frac{dC}{dX_{i-1}} = \frac{dC}{dX_i} \cdot \frac{dX_i}{dX_{i-1}}$
- $\frac{dC}{dX_i} = \frac{dC}{dX_i} \cdot \frac{dF_i(X_{i-1}, W_i)}{dX_i}$

- Backprop for the weight gradients:

- $\frac{dC}{dW_i} = \frac{dC}{dX_i} \cdot \frac{dX_i}{dW_i}$
- $\frac{dC}{dW_i} = \frac{dC}{dX_i} \cdot \frac{dF_i(X_{i-1}, W_i)}{dW_i}$

Training (Learning)

- **Supervised Learning**

Network trains its weights based on **labeled training** data,
i.e. optimizes **cost** function between expected outputs and
actual outputs

$$D = \{\{x_1, d_1\}, \{x_2, d_2\}, \dots, \{x_m, d_m\}\}$$

Training (Learning)

- Unsupervised Learning

Network trains its weights based on **unlabeled training** data, i.e. no clear **cost** function. Clustering often used to create labels (Hebbian Learning). Requires more data.

- Reinforcement Learning

Network trains its weights based on **trials where correct decisions are rewarded**. Requires much more data - many trials. Cannot be done in real time.

Summary

Properties of Brain Networks and Learning

1. Neurons: simple computational units
 2. Well connected
 3. Parallelism and Recurrence
 4. Hierarchically structured
 5. Learning
 1. Features
 2. Changing connections
- architectures
of NN

Lab Preview

DL Platform Setup

- Python Programming Setup
- Python Platforms for DL
- Introduction to Numpy
- Plotting with Matplotlib
- Preparing Data for Machine Learning

Implement your own network
(perceptron)



Next

- Machine Learning Basics
- Neural Networks Building Blocks
 - Neurons
 - Integration
 - Activation
 - Layers
 - Training