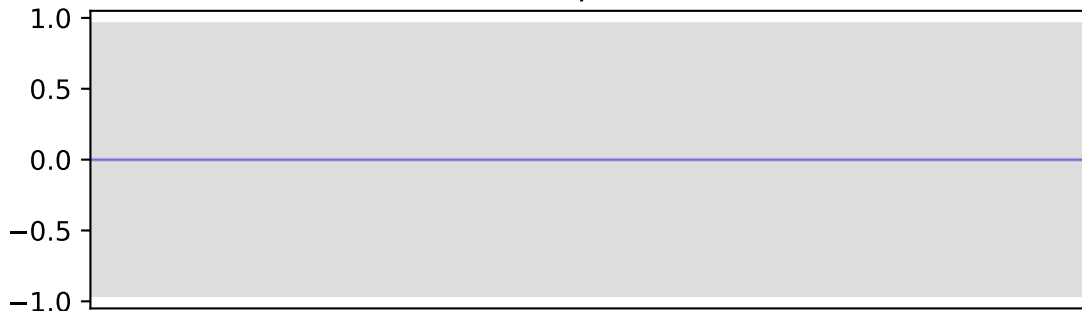
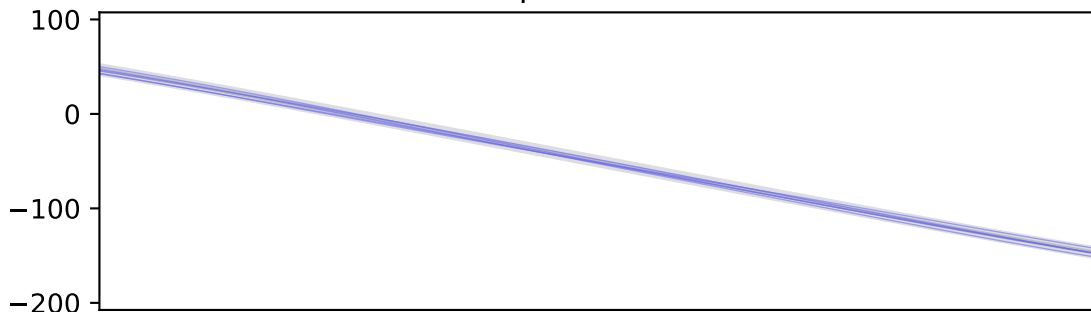


torque 0



position 0



velocity 0

