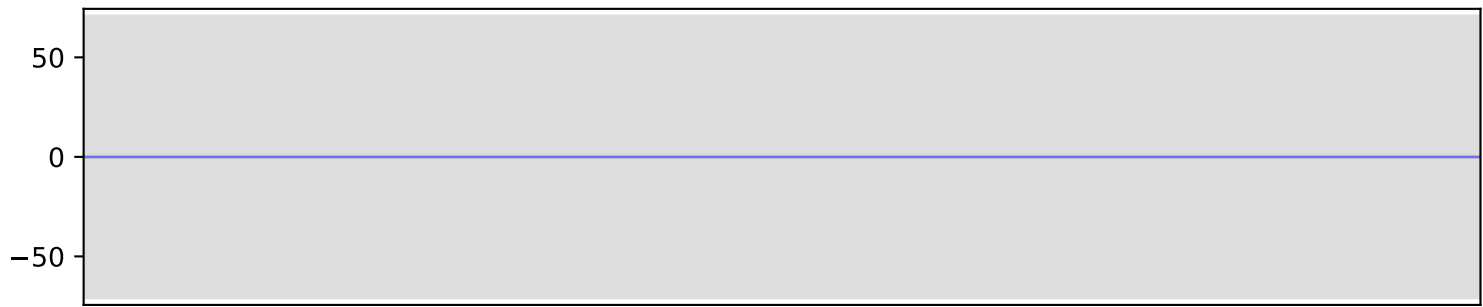
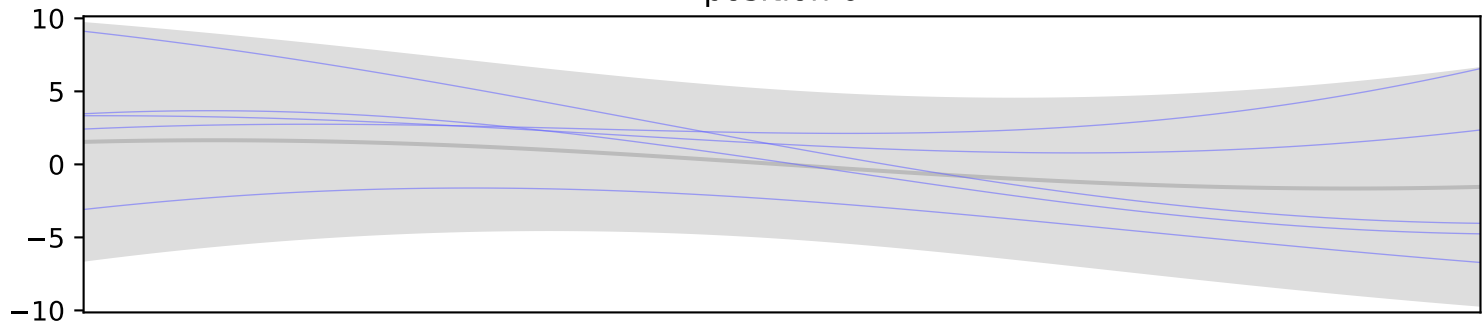


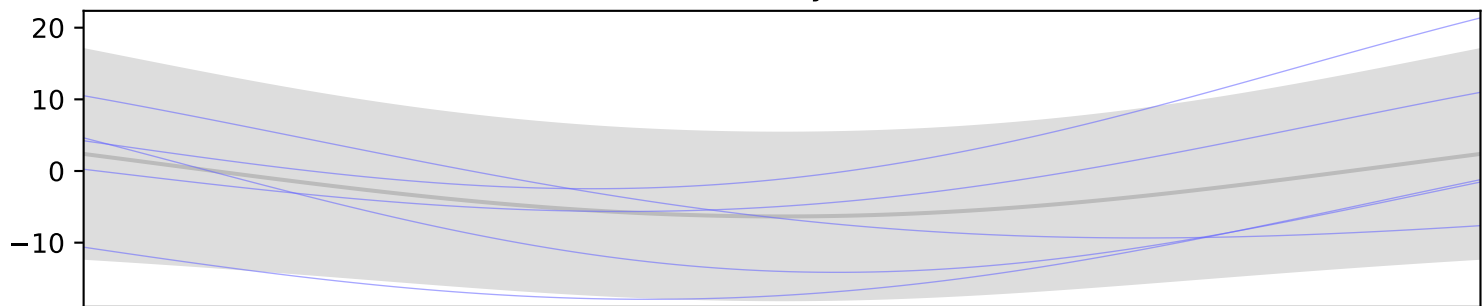
torque 0



position 0



velocity 0



gains 0

