

Dynamical Systems & Applications — 26/09/23

# An introduction to Topological Data Analysis

## Part I/IV: Topological invariants

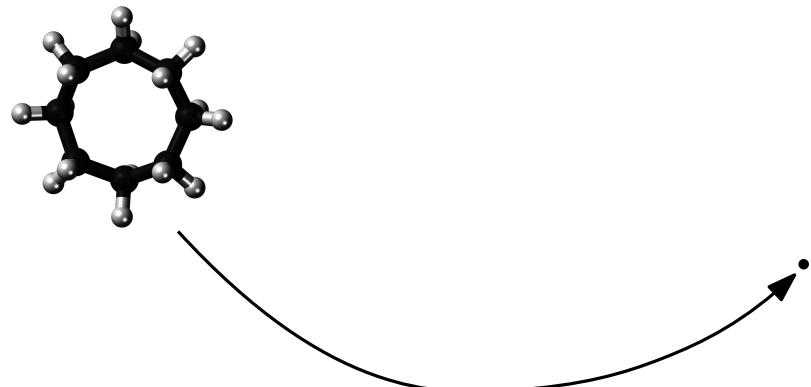
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[Martin, Thompson, Coutsias and Watson, [Topology of cyclo-octane energy landscape, 2010](#)]

The cyclo-octane molecule  $C_8H_{16}$  contains 24 atoms.

Each atom has 3 spatial coordinates.

Hence a conformation of a molecule can be summarized by **a point** in  $\mathbb{R}^{72}$  ( $3 \times 24 = 72$ ).

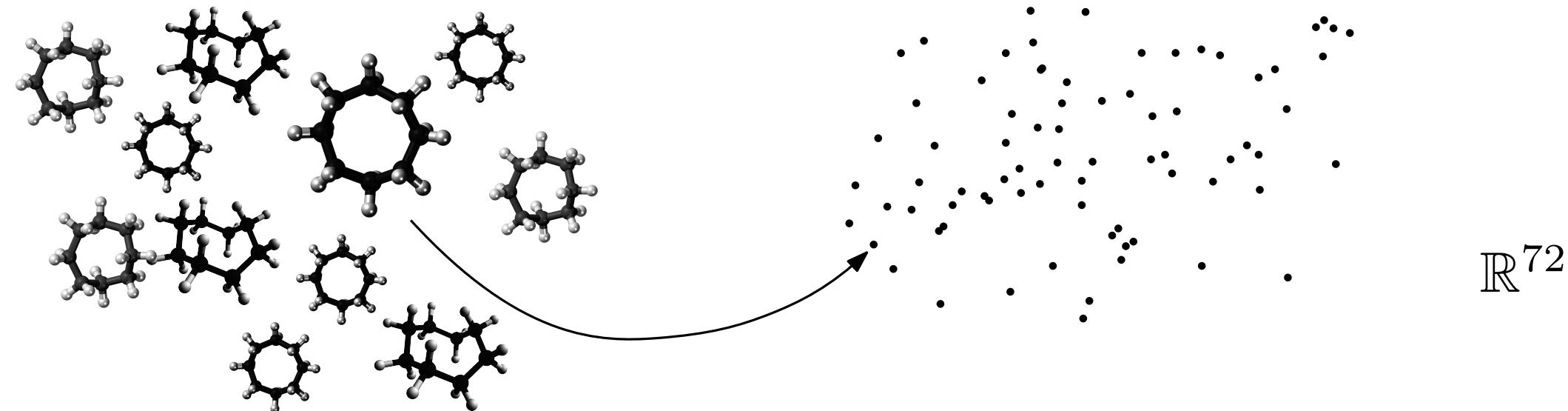


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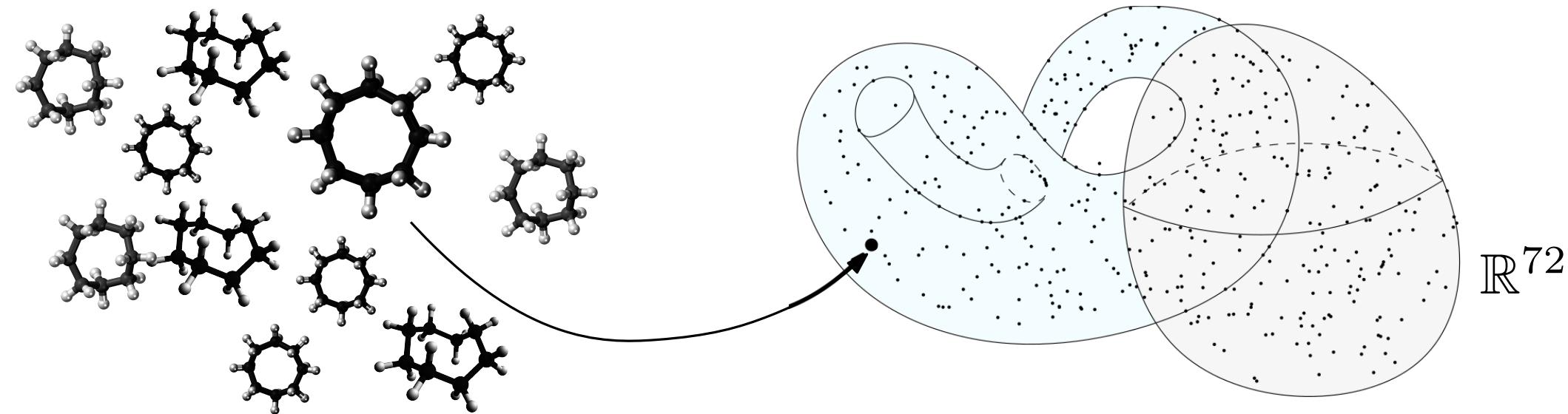
By considering a lot of such molecules, we obtain a **point cloud** in  $\mathbb{R}^{72}$ .

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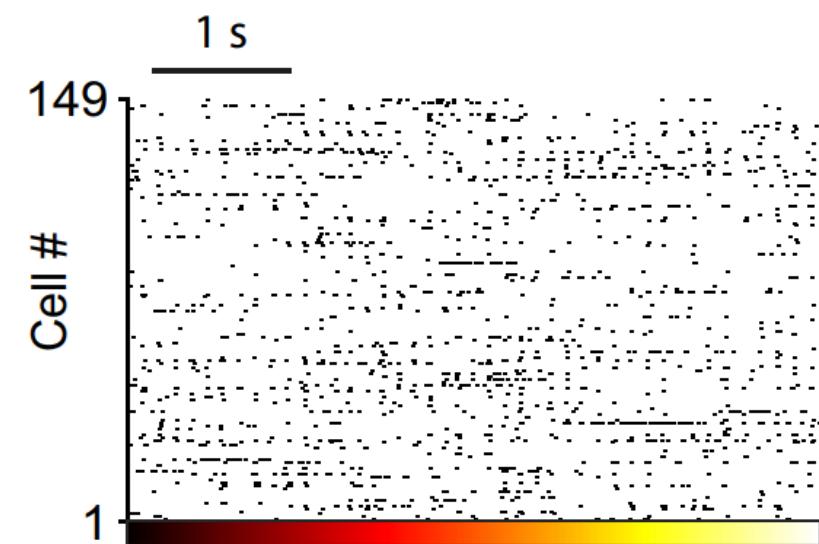
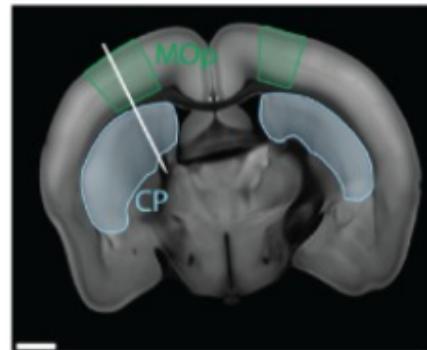
By considering a lot of such molecules, we obtain a **point cloud** in  $\mathbb{R}^{72}$ .

The authors show that this point cloud lies close to a small dimensional object: **the union of a sphere and a Klein bottle**.

# Aperitivo topológico — Neurofisiología 3/37 (1/2)

[Richard J. Gardner et al, Toroidal topology of population activity in grid cells, 2022]

The authors recorded spikes of grid cells from rat brains. Then, they applied dimensionality reduction to the firing matrix.

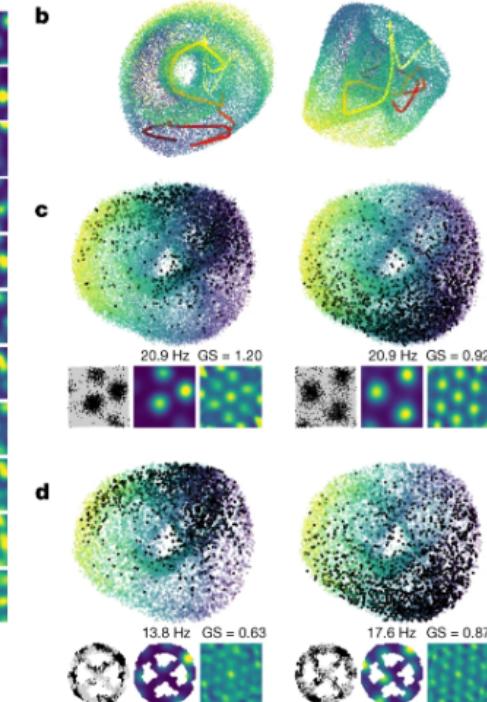
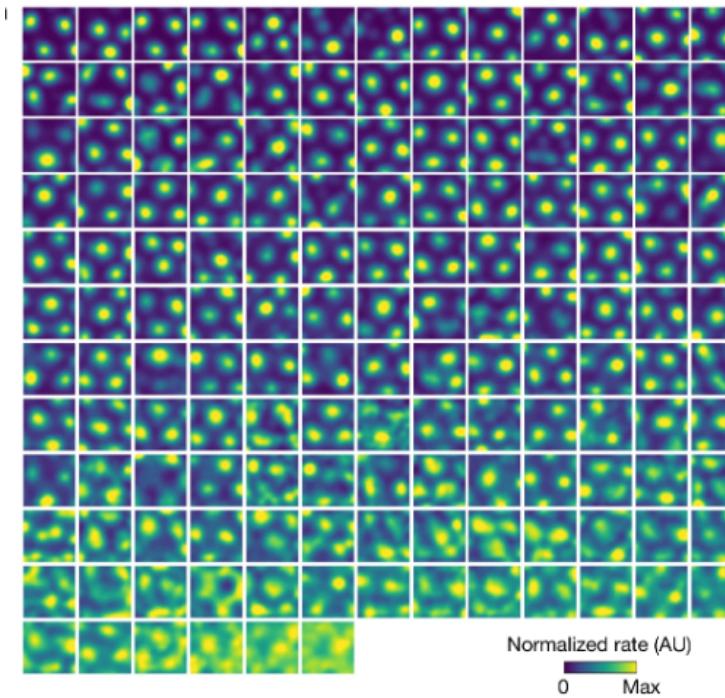
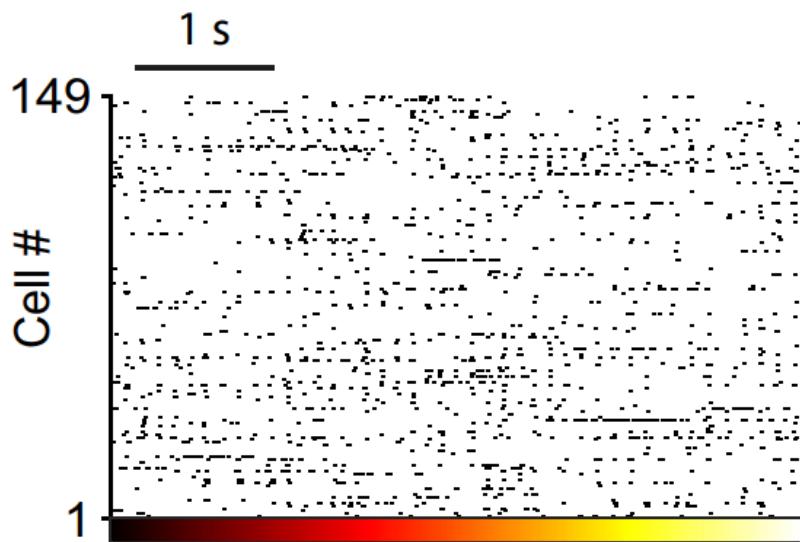
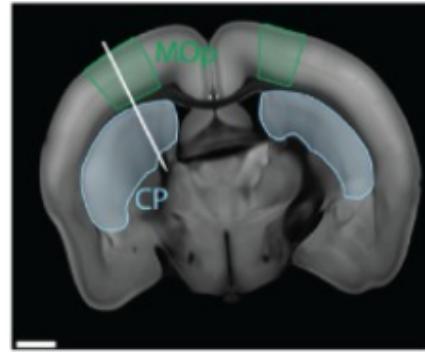


# Aperitivo topológico — Neurofisiología 3/37 (2/2)

[Richard J. Gardner et al, Toroidal topology of population activity in grid cells, 2022]

The authors recorded spikes of grid cells from rat brains. Then, they applied dimensionality reduction to the firing matrix.

By applying persistent homology, they observed the homology of a **torus**.



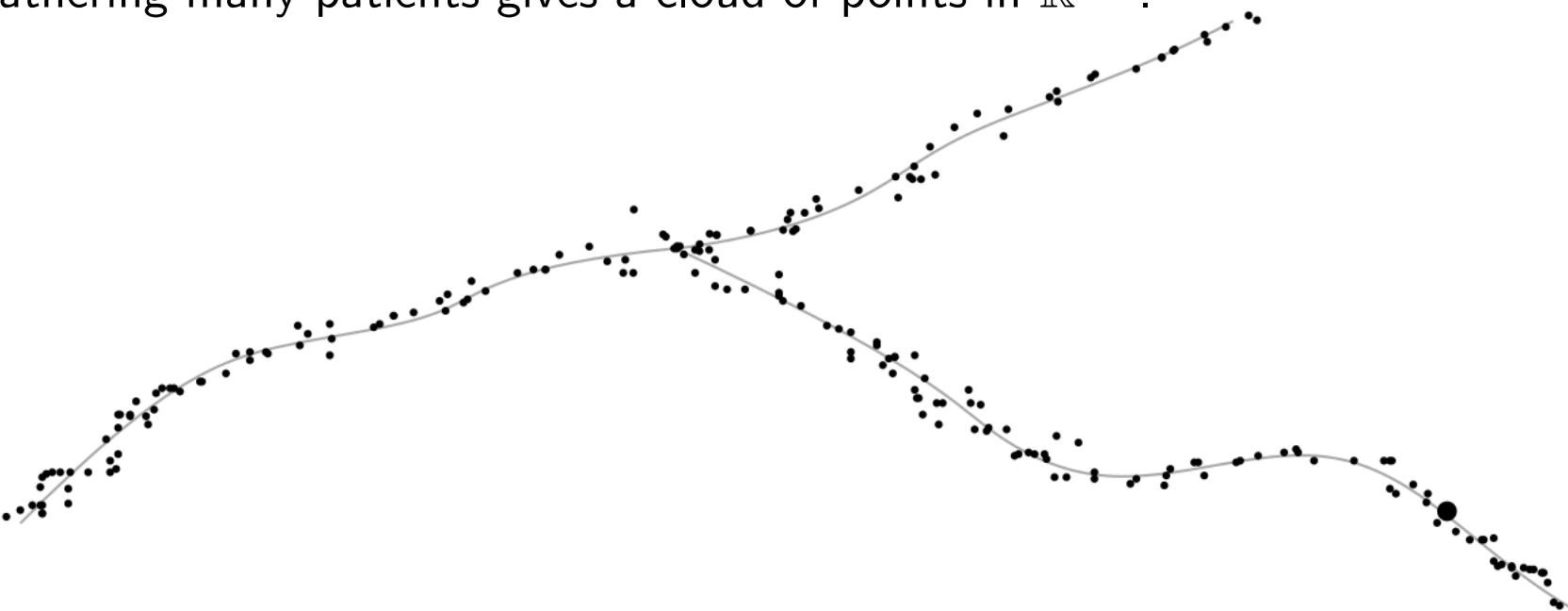
[Topology based data analysis identifies a subgroup of breast cancers with a unique mutational profile and excellent survival, Monica Nicolau, Arnold J Levine, and Gunnar Carlsson, *Proceedings of the National Academy of Sciences*, 2011]

The authors study tissues from patients infected by breast cancer. They obtain 262 genomic variables per patient.

$$(x_1, x_2, \dots, x_{262})$$

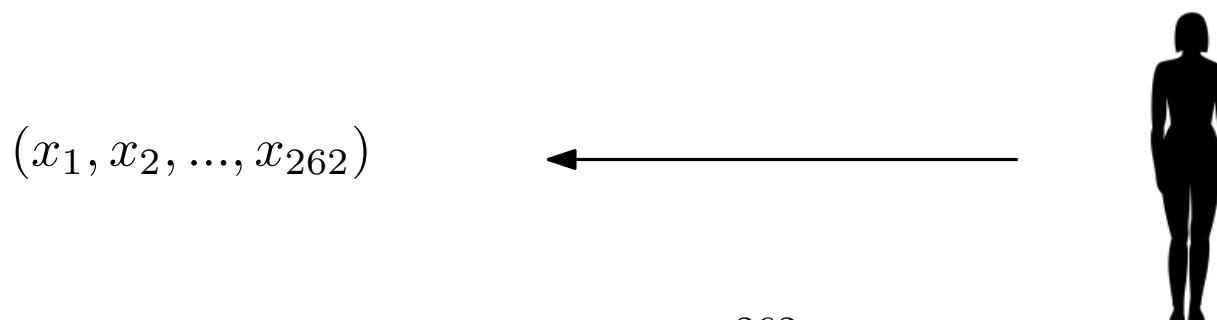


Gathering many patients gives a cloud of points in  $\mathbb{R}^{262}$ .



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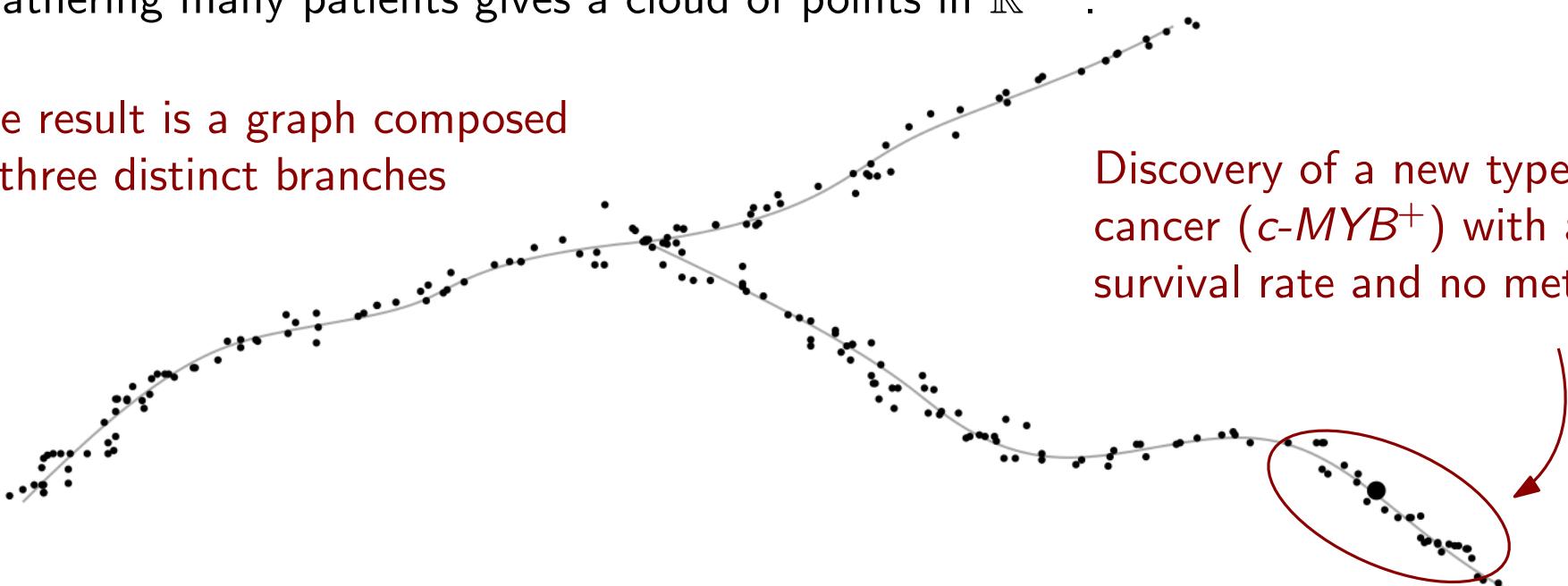
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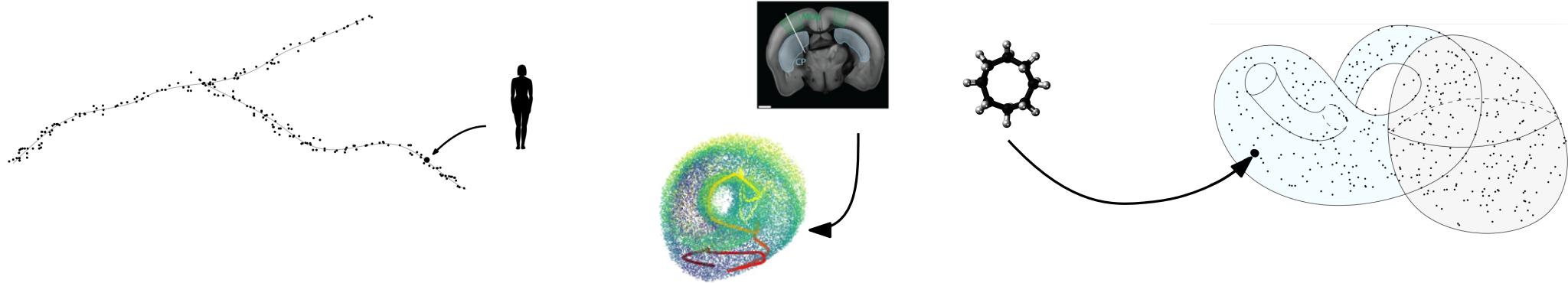
The result is a graph composed  
of three distinct branches

Discovery of a new type of breast  
cancer (*c-MYB<sup>+</sup>*) with a 100%  
survival rate and no metastases

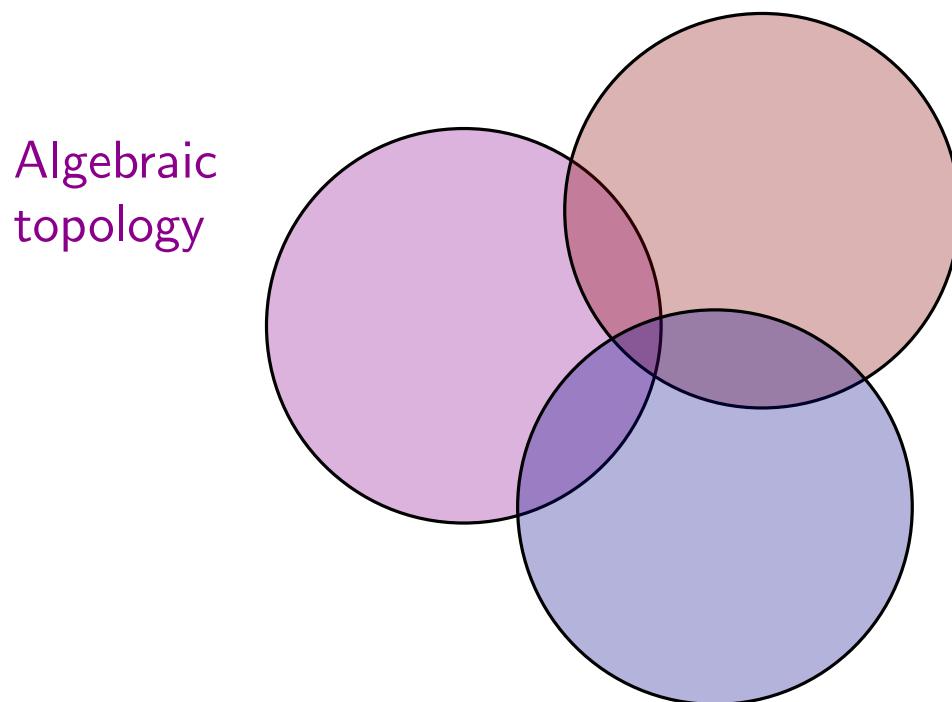


# Qual é a forma dos dados?

5/37



Topological Data Analysis (TDA) allows to **explore** and **understand** the topology of datasets.



Algebraic  
topology

Computational  
geometry

Data analysis & Machine  
learning

# Part I/IV: Topological invariants

Tuesday 26th

# Part II/IV: Homology

Thursday 28th

# Part III/IV: Persistent Homology

Tuesday 3rd

# Part IV/IV: Python tutorial

Thursday 5th

# I - Topology

- 1 - History
- 2 - Topological spaces

# II - Comparing topological spaces

- 1 - Homeomorphism equivalence
- 2 - Homotopy equivalence

# III - Topological invariants

- 1 - Embeddability
- 2 - Number of connected components
- 3 - Euler characteristic
- 4 - Betti numbers

# Algumas figuras históricas

8/37 (1/3)



Euler

1736: *Solutio problematis ad geometriam situs pertinentis*



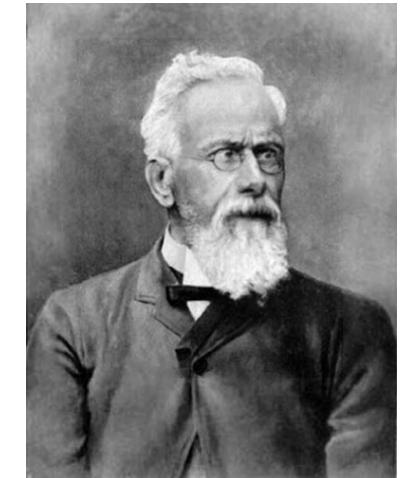
Möbius

1865: *Bestimmung des Inhaltes eines Polyëders*



Riemann

1857: *Theorie der Abel'schen Functionen*



Betti

1871: *Sopra gli spazi di un numero qualunque di dimensioni*

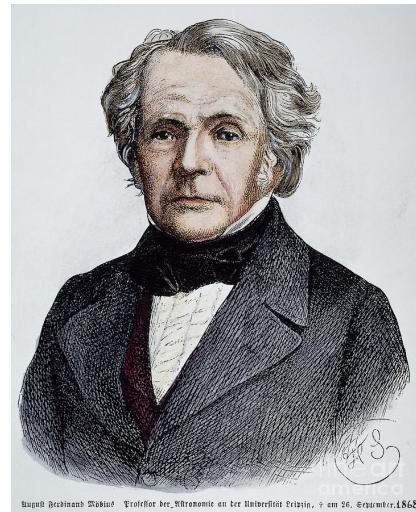
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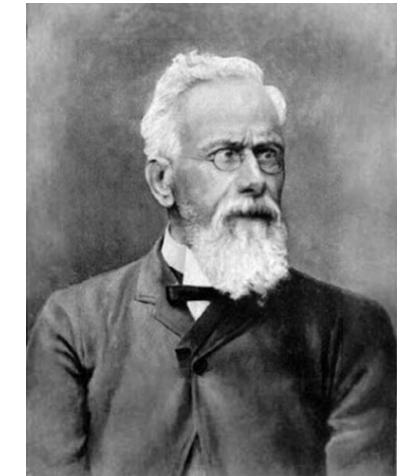
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Poincaré

1895: Analysis Situs

Toute 3-variété compacte sans bord et simplement connexe est-elle homéomorphe à la 3-sphère ?

[Cinquième complément à l'analysis situs, 1904]

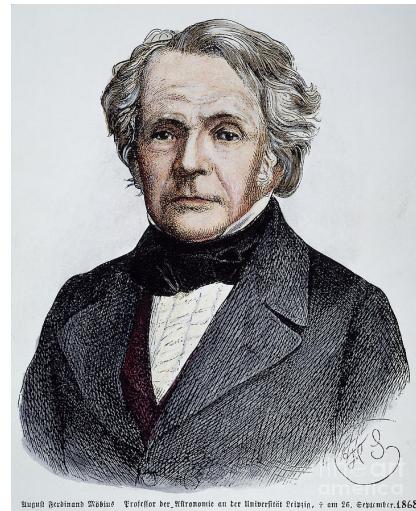
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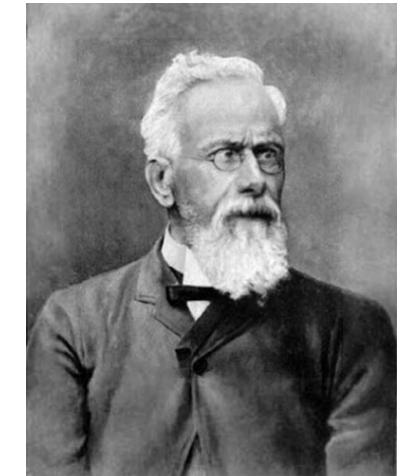
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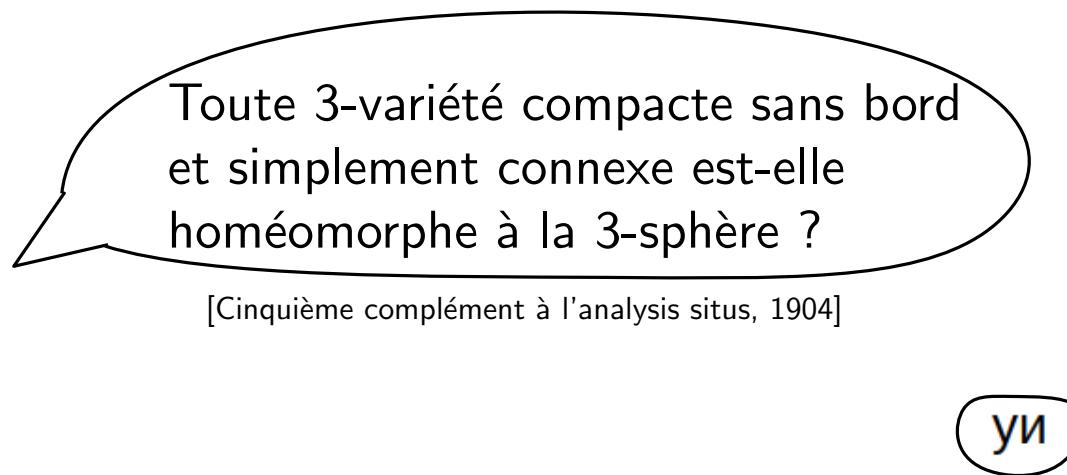
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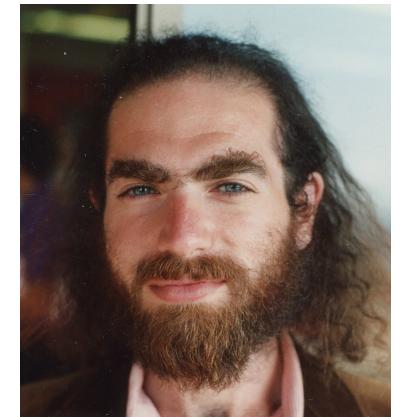


Poincaré

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и



Perelman

2002: The entropy formula for the Ricci  
flow and its geometric applications

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In topology we study **topological spaces**.

**Definition:** a topological space is a set  $X$  endowed with a collection of **open sets**  $\{O_\alpha \mid \alpha \in A\}$ , with  $O_\alpha \subset X$ , such that

- $\emptyset$  and  $X$  are open sets,
- an infinite union of open sets is an open set,
- a finite intersection of open sets is an open set.

**Definition:** Given two topological spaces  $X$  and  $Y$ , a map  $f: X \rightarrow Y$  is **continuous** if for every open set  $O \subset Y$ , the preimage  $f^{-1}(O)$  is an open set of  $X$ .

$$X \xrightarrow{\hspace{1cm}} Y$$

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translation in  
 $\epsilon$ - $\delta$  calculus

One can think of **subsets**  $X \subset \mathbb{R}^n$  and  $Y \subset \mathbb{R}^m$ ,

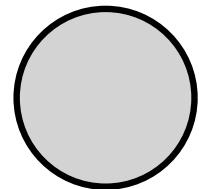
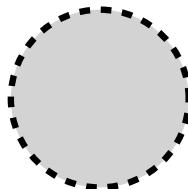
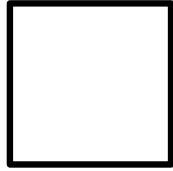
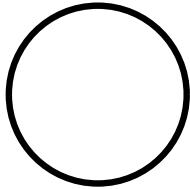
and maps  $f: X \rightarrow Y$  **continuous** in the following sense:

$$\forall x \in X, \forall \epsilon > 0, \exists \eta > 0, \forall y \in X, \|x - y\| < \eta \implies \|f(x) - f(y)\| < \epsilon.$$

1 - We can build a topological space by seeing it as a **subspace** of another one.

In  $\mathbb{R}^n$ , we can define:

- the unit sphere  $\mathbb{S}_{n-1} = \{x \in \mathbb{R}^n \mid \|x\| = 1\}$
- the unit cube  $\mathcal{C}_{n-1} = \{(x_1, \dots, x_n) \in \mathbb{R}^n \mid \max(|x_1|, \dots, |x_n|) = 1\}$
- the open balls  $\mathcal{B}(x, r) = \{y \in \mathbb{R}^n \mid \|x - y\| < r\}$
- the closed balls  $\overline{\mathcal{B}}(x, r) = \{y \in \mathbb{R}^n \mid \|x - y\| \leq r\}$



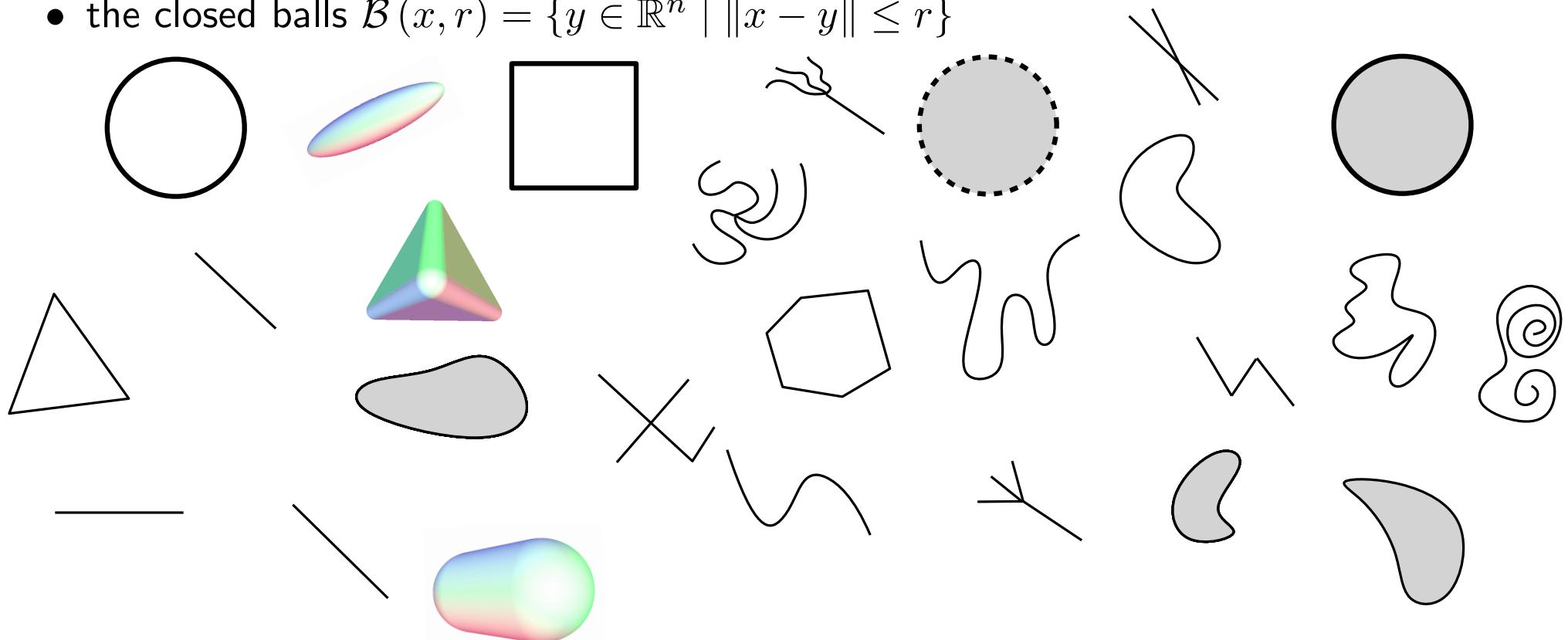
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11/37 (2/9)

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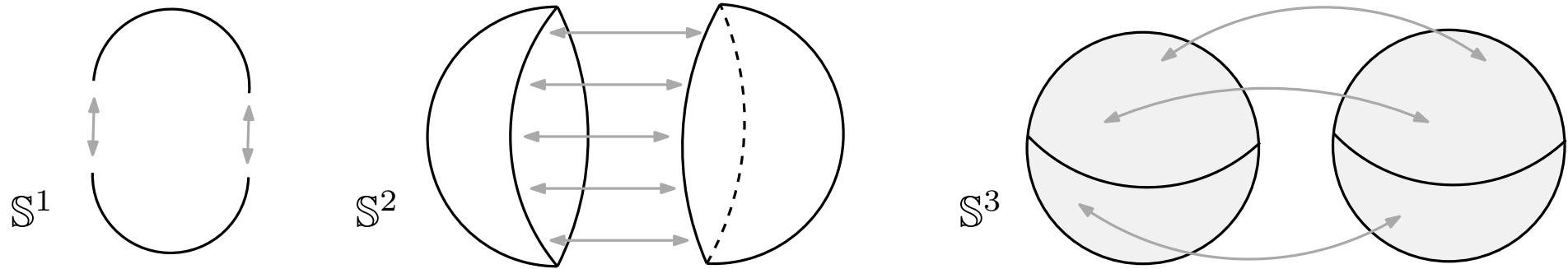
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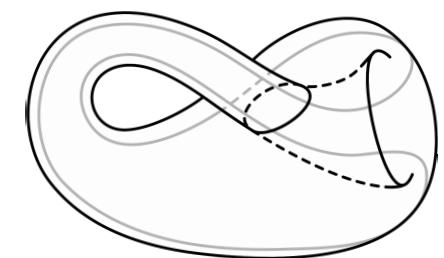
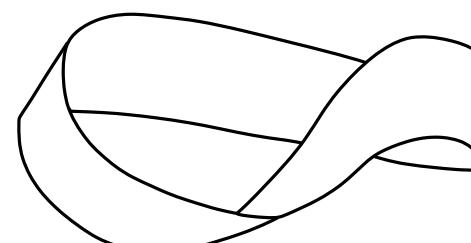
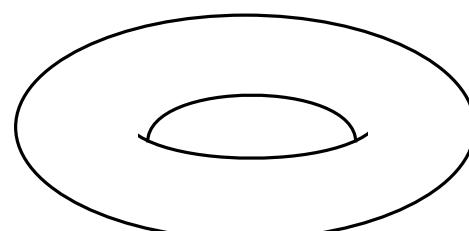
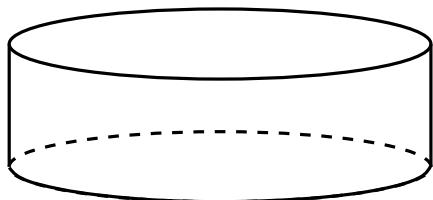
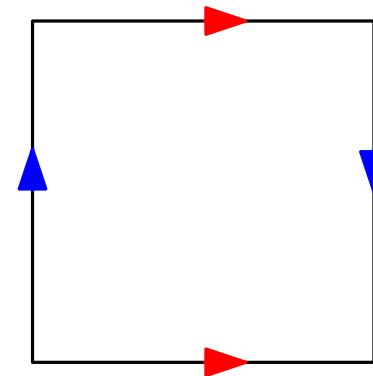
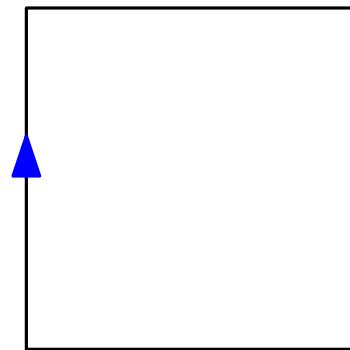
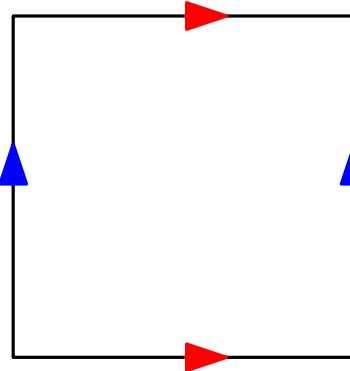
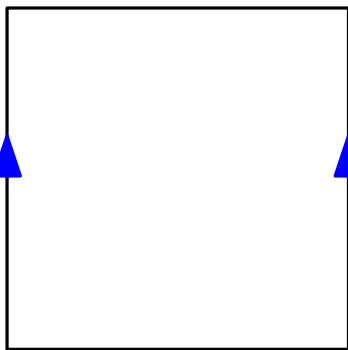


Most of the time, we do not have a nice algebraic definition...

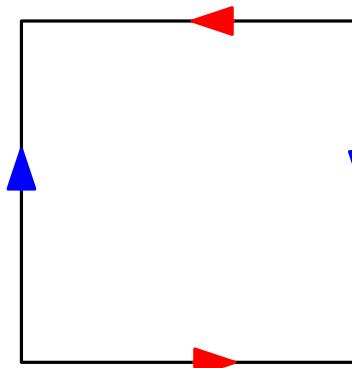
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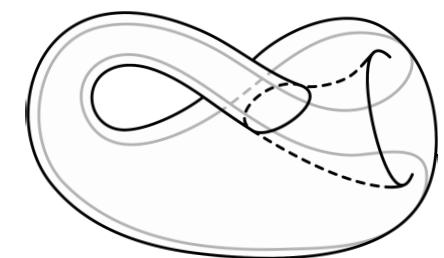
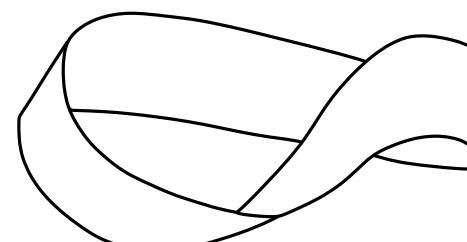
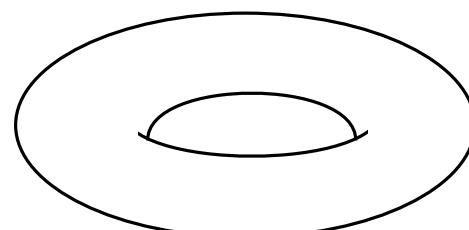
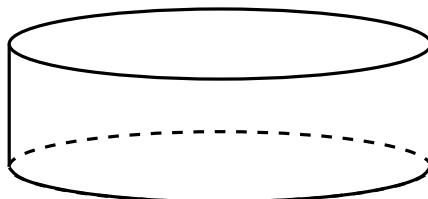
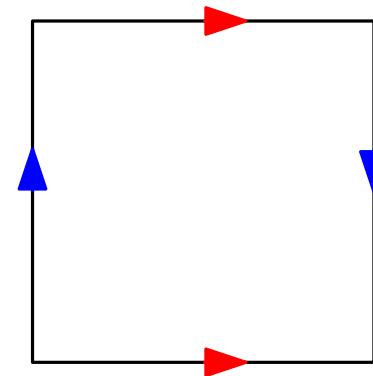
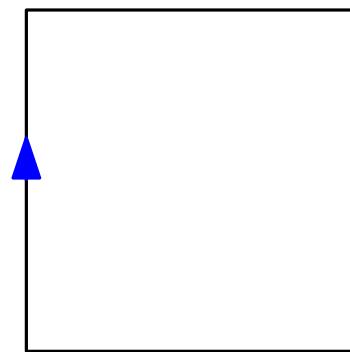
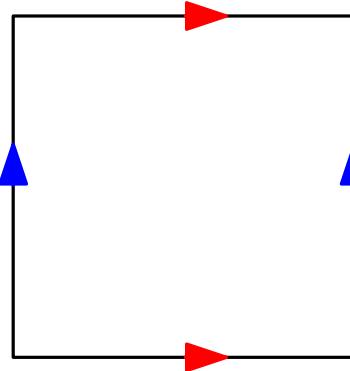
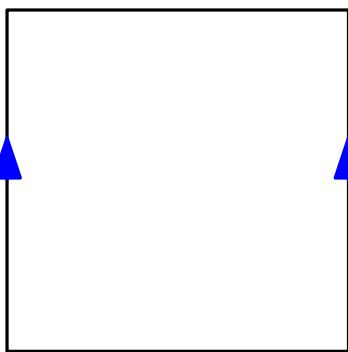
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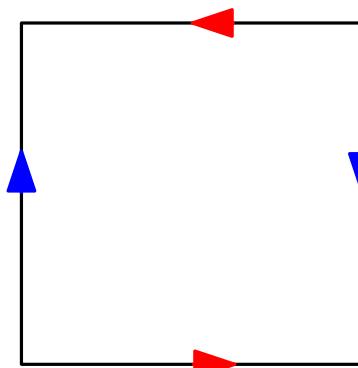
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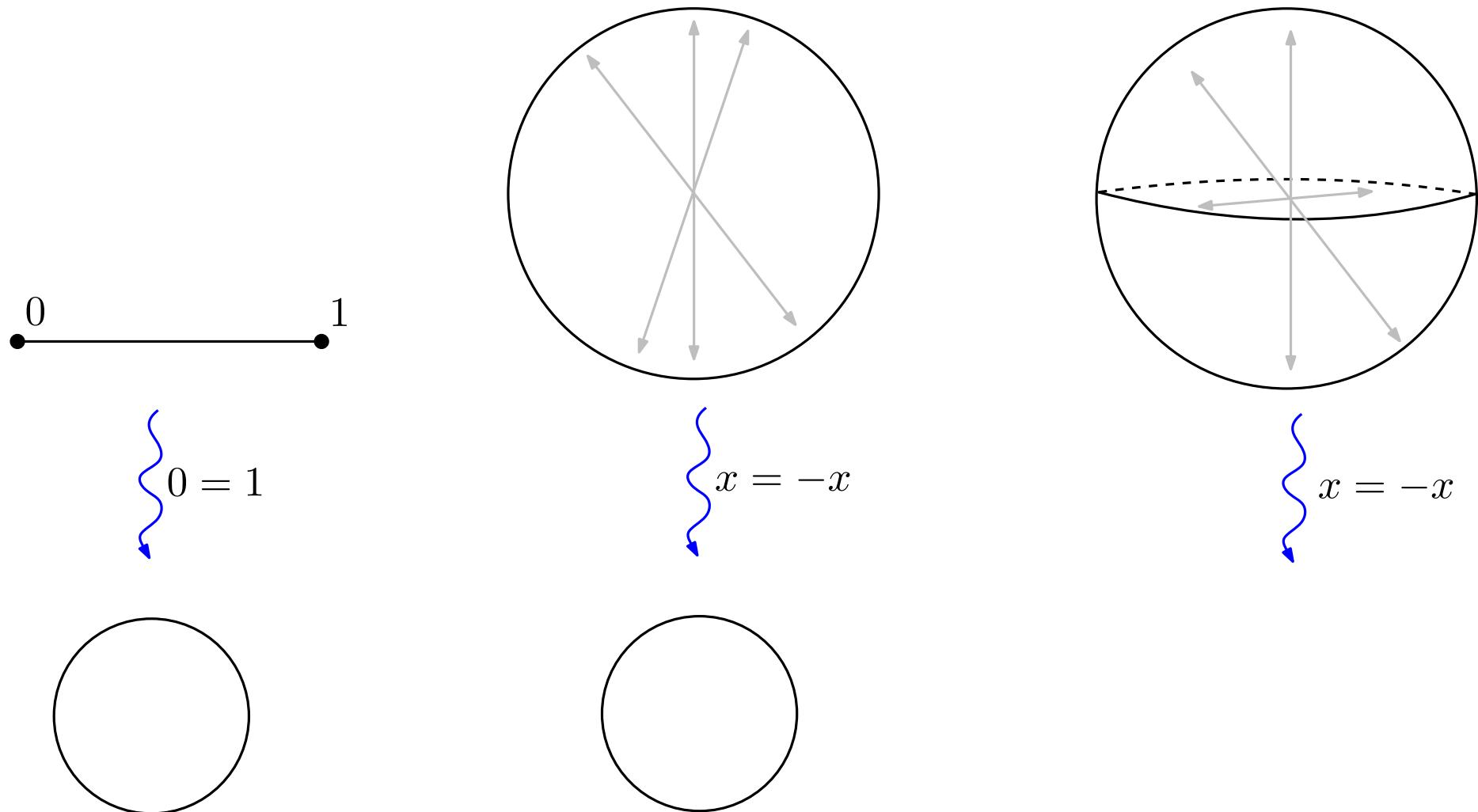


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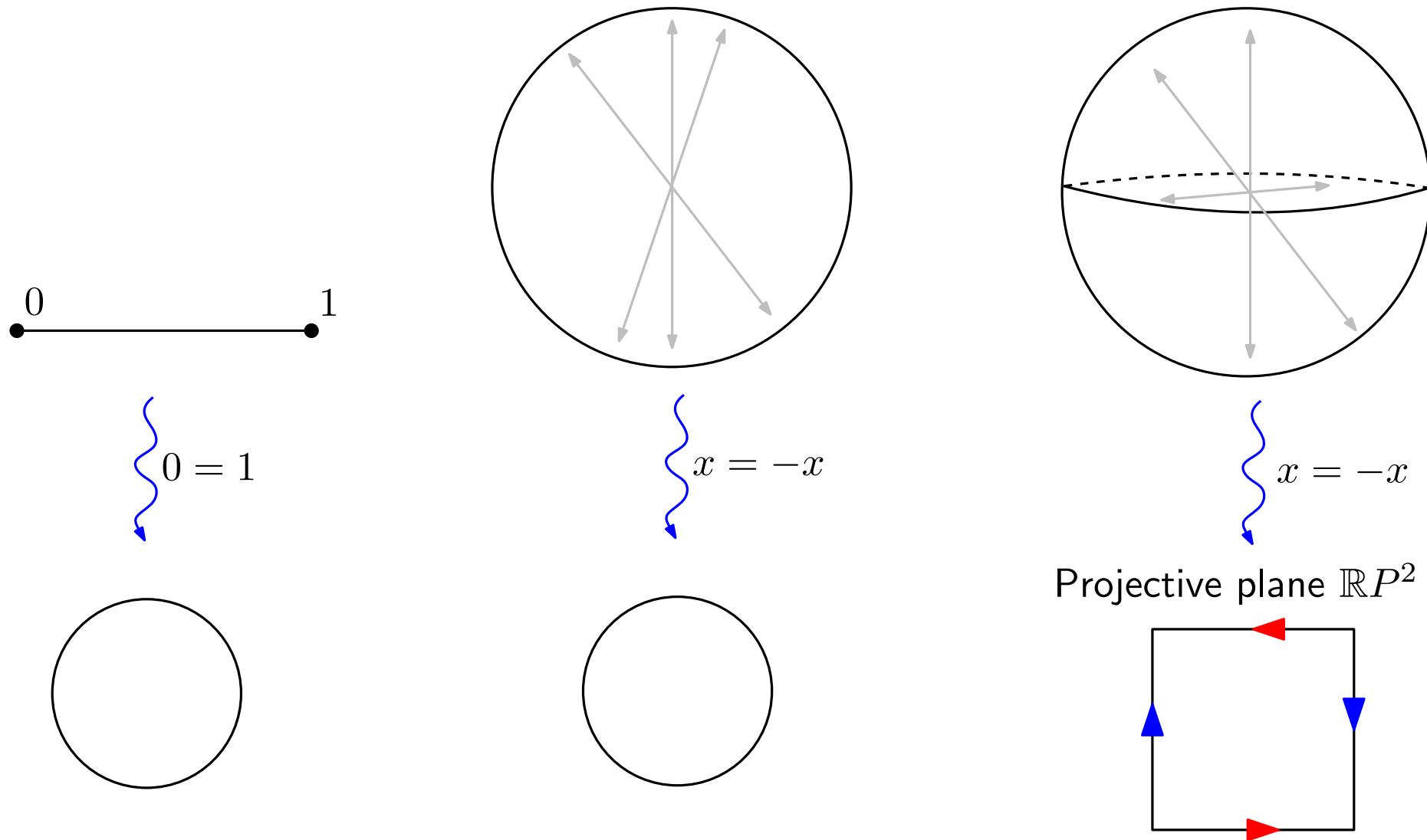


Projective plane  $\mathbb{R}P^2$

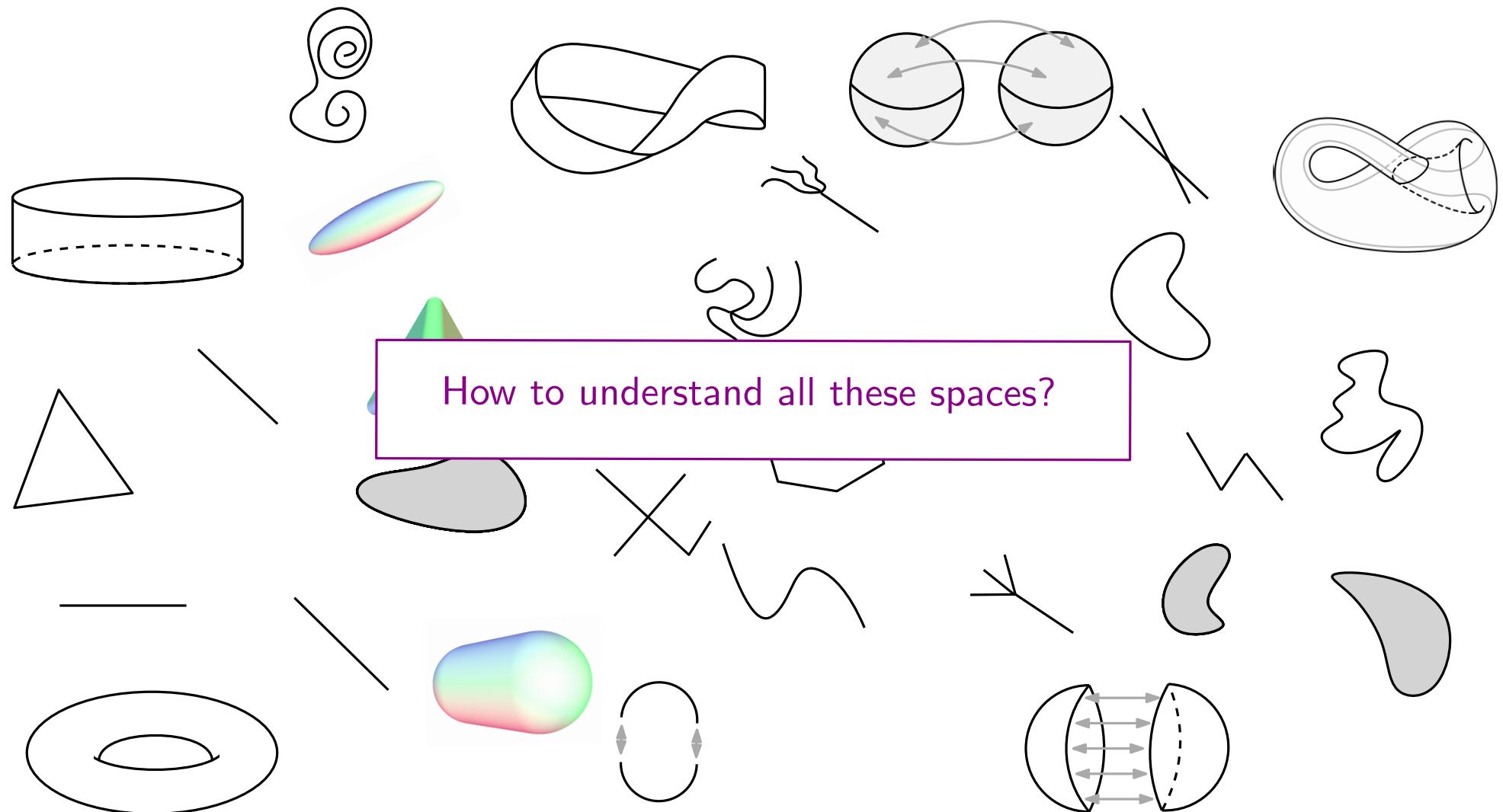
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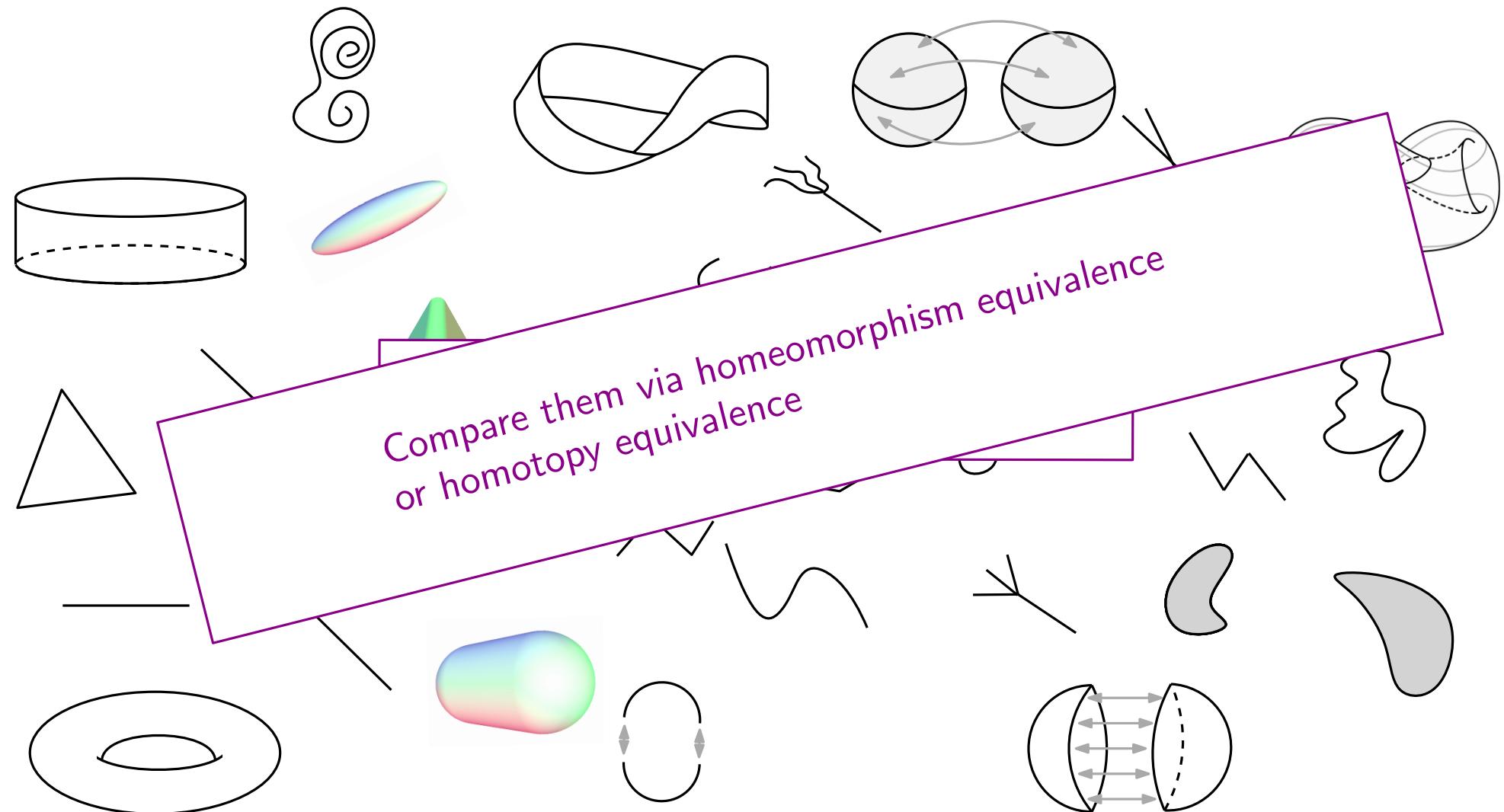
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# Construção de espaços topológicos

11/37 (9/9)

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1 - Homeomorphism equivalence

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# III - Topological invariants

1 - Embeddability

2 - Number of connected components

3 - Euler characteristic

4 - Betti numbers

**Definition:** Let  $X$  and  $Y$  be two topological spaces, and  $f: X \rightarrow Y$  a map.

We say that  $f$  is a **homeomorphism** if

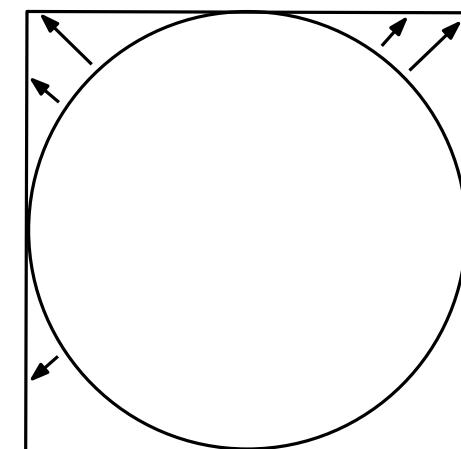
- $f$  is a bijection,
- $f: X \rightarrow Y$  is continuous,
- $f^{-1}: Y \rightarrow X$  is continuous.

If there exist such a homeomorphism, we say that the two topological spaces are **homeomorphic**.

**Example:** The unit circle and the unit square are homeomorphic via

$$f: \mathbb{S}_1 \longrightarrow \mathcal{C}$$

$$(x_1, x_2) \longmapsto \frac{1}{\max(|x_1|, |x_2|)}(x_1, x_2)$$



**Interpretation:** Homeomorphisms allow 'continuous deformations'.

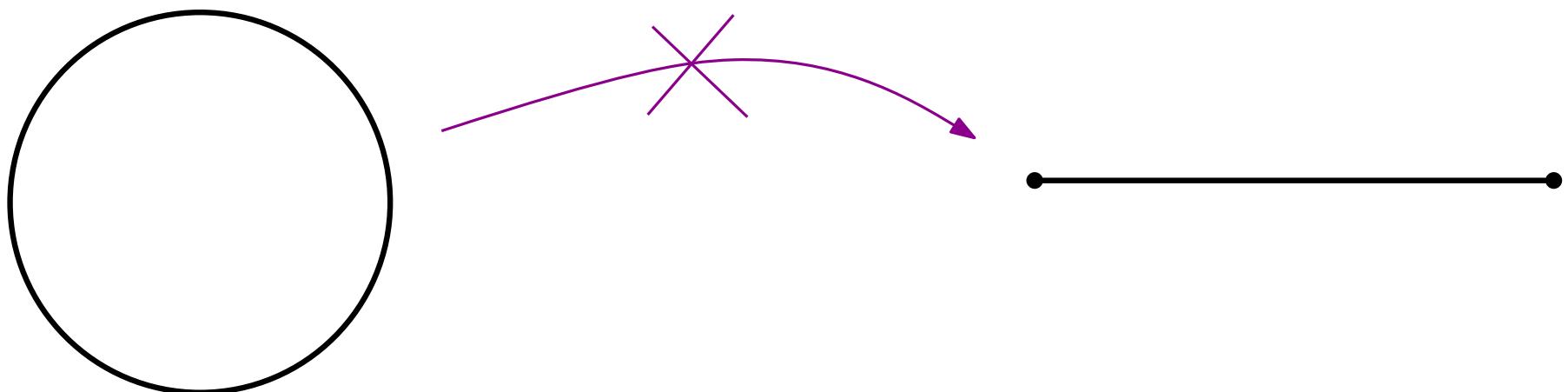
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**Example:** The unit circle and the interval  $[0, 1]$  are not homeomorphic.



**Interpretation:** Homeomorphisms allow 'continuous deformations'.

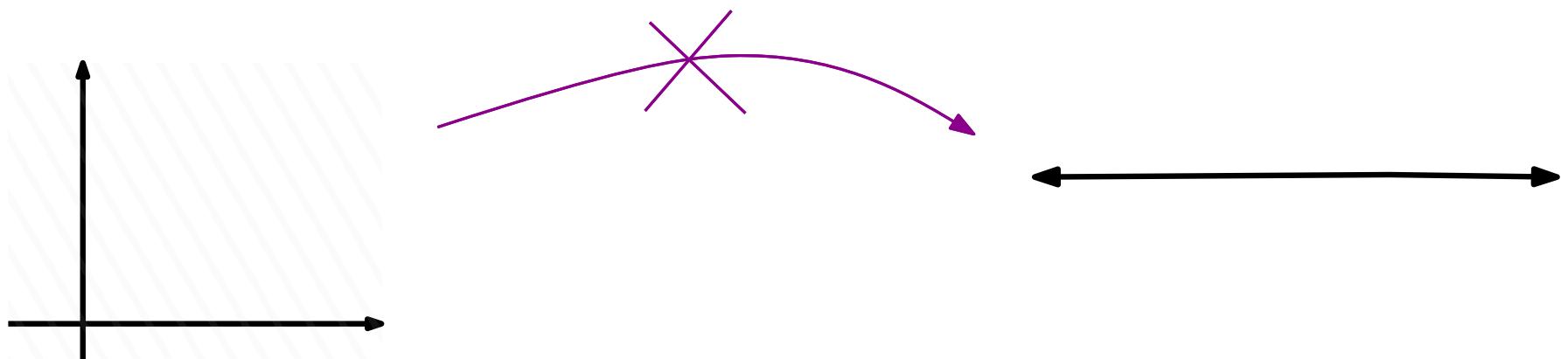
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If there exist such a homeomorphism, we say that the two topological spaces are **homeomorphic**.

**Example (Invariance of domain):** [Brouwer, 1912] If  $n \neq m$ , the Euclidean spaces  $\mathbb{R}^n$  and  $\mathbb{R}^m$  are not homeomorphic.



**Interpretation:** Homeomorphisms allow 'continuous deformations'.

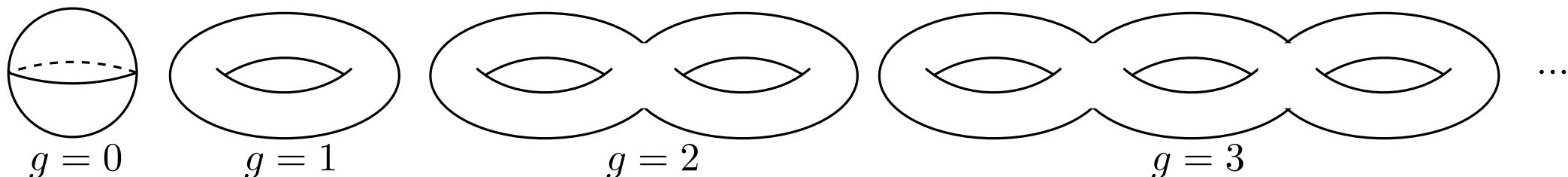
**Definition:** Let  $X$  and  $Y$  be two topological spaces, and  $f: X \rightarrow Y$  a map.

We say that  $f$  is a **homeomorphism** if

- $f$  is a bijection,
- $f: X \rightarrow Y$  is continuous,
- $f^{-1}: Y \rightarrow X$  is continuous.

If there exist such a homeomorphism, we say that the two topological spaces are **homeomorphic**.

**Example (Classification of surfaces):** [Möbius, Jordan, von Dyck, Dehn and Heegaard, Alexander, Brahana, 1863-1921] If  $g \neq g'$ , the surfaces of genus  $g$  and  $g'$  are not homeomorphic.

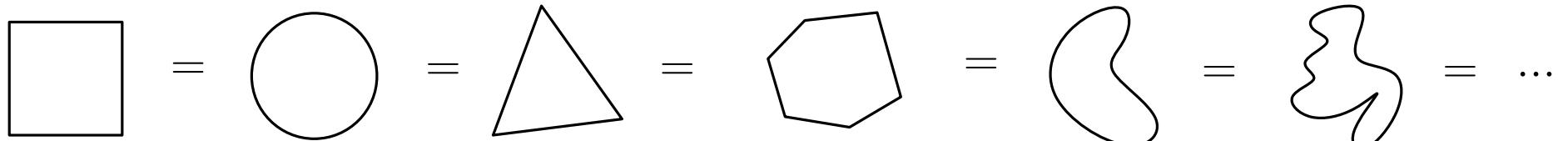


**Interpretation:** Homeomorphisms allow 'continuous deformations'.

# Classes de homeomorfismo

14/37 (1/5)

We can gather topological spaces that are homeomorphic

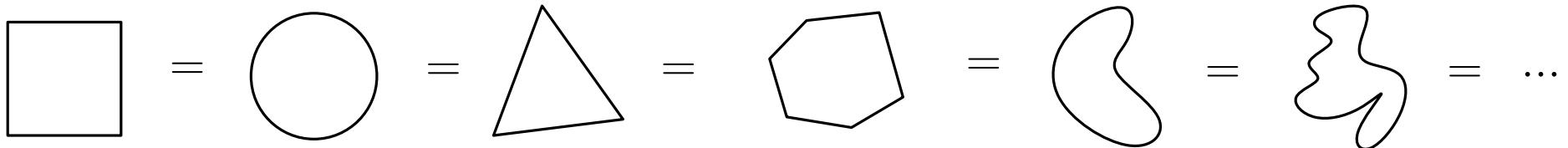


the class of circles

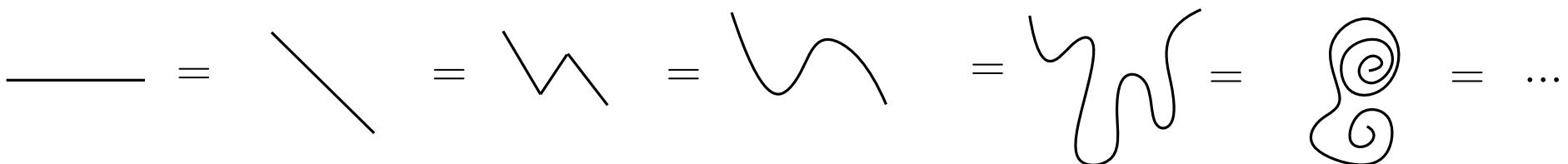
# Classes de homeomorfismo

14/37 (2/5)

We can gather topological spaces that are homeomorphic



the class of circles

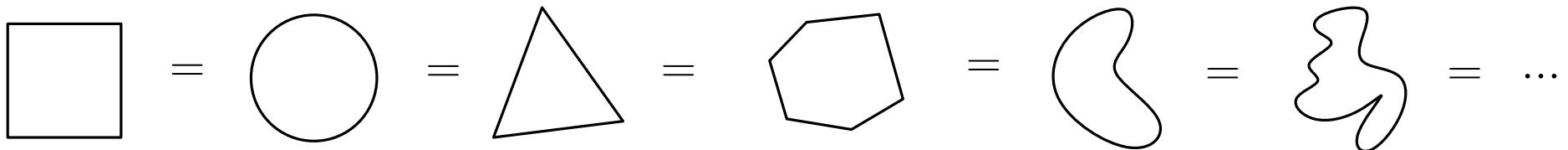


the class of intervals

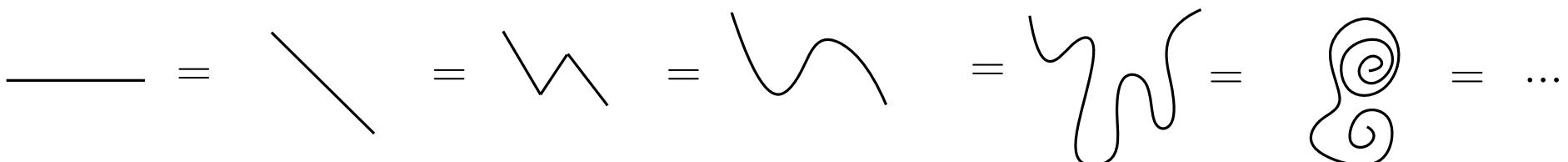
# Classes de homeomorfismo

14/37 (3/5)

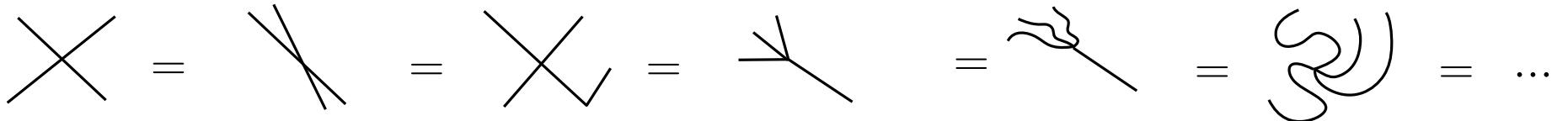
We can gather topological spaces that are homeomorphic



the class of circles



the class of intervals

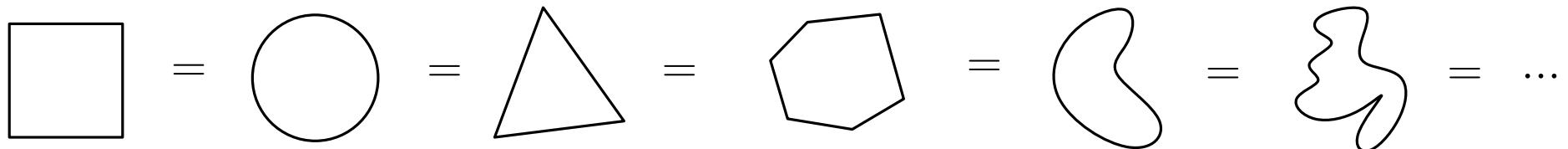


the class of crosses

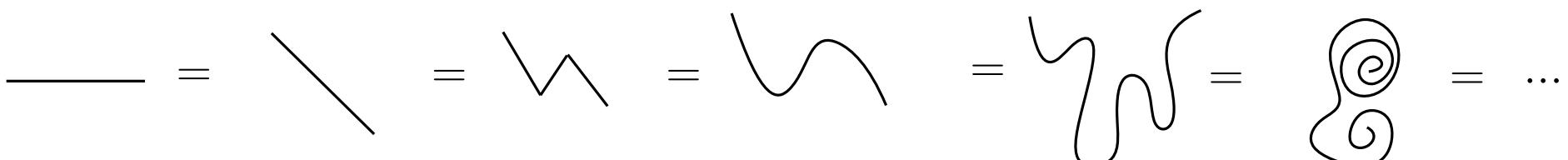
# Classes de homeomorfismo

14/37 (4/5)

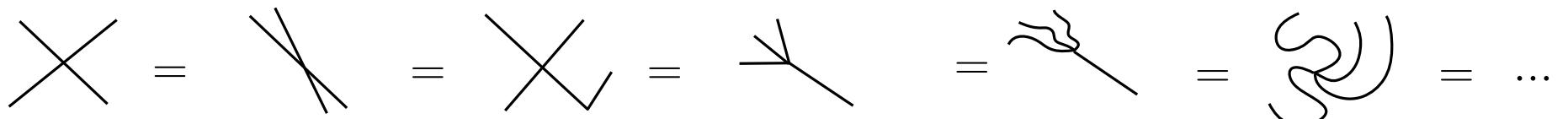
We can gather topological spaces that are homeomorphic



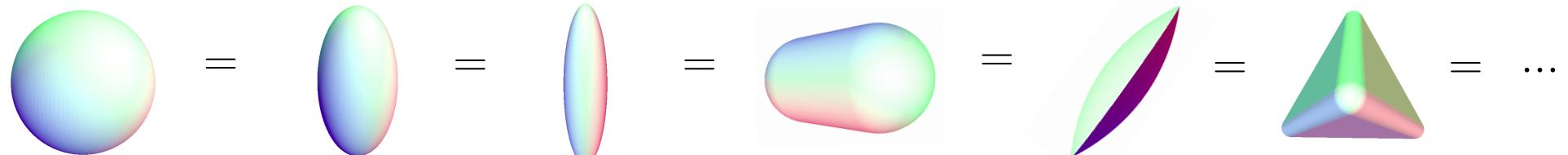
the class of circles



the class of intervals

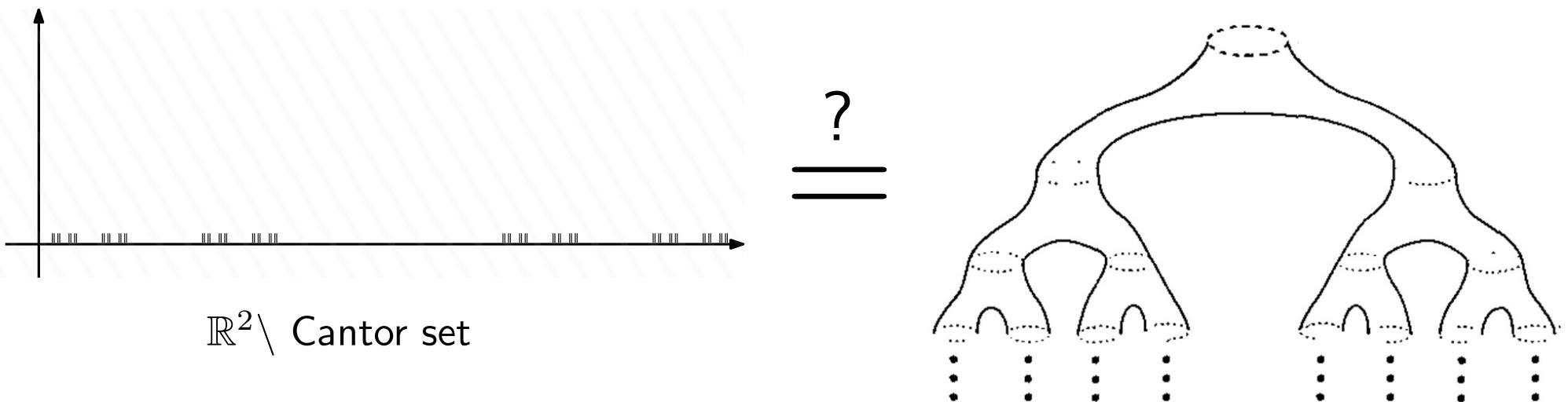


the class of crosses



the class of spheres

In general, it may be complicated to determine whether two spaces are homeomorphic.



To answer this problem, we will use the notion of **invariant**.

# I - Topology

1 - History

2 - Topological spaces

# II - Comparing topological spaces

1 - Homeomorphism equivalence

2 - Homotopy equivalence

# III - Topological invariants

1 - Embeddability

2 - Number of connected components

3 - Euler characteristic

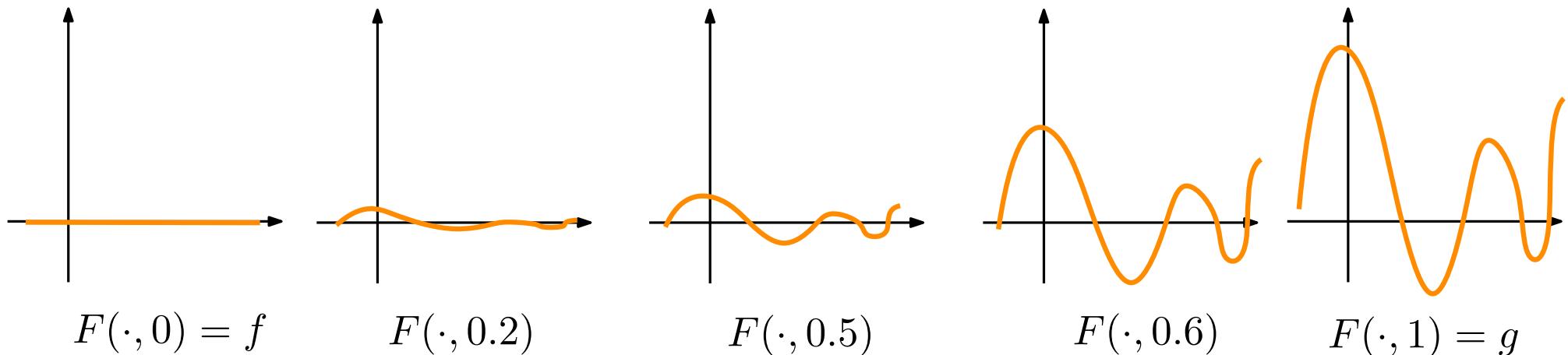
4 - Betti numbers

**Definition:** Let  $X, Y$  be two topological spaces, and  $f, g: X \rightarrow Y$  two continuous maps. A **homotopy** between  $f$  and  $g$  is a map  $F: X \times [0, 1] \rightarrow Y$  such that:

- $x \mapsto F(x, 0)$  is equal to  $f$ ,
- $x \mapsto F(x, 1)$  is equal to  $g$ ,
- $F: X \times [0, 1] \rightarrow Y$  is continuous.

If such a homotopy exists, we say that the maps  $f$  and  $g$  are **homotopic**.

**Example:** Homotopy between  $f: \mathbb{R} \rightarrow \mathbb{R}$  and  $g: \mathbb{R} \rightarrow \mathbb{R}$ .



# Homotopies

16/37 (2/3)

**Definition:** Let  $X, Y$  be two topological spaces, and  $f, g: X \rightarrow Y$  two continuous maps. A **homotopy** between  $f$  and  $g$  is a map  $F: X \times [0, 1] \rightarrow Y$  such that:

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If such a homotopy exists, we say that the maps  $f$  and  $g$  are **homotopic**.

**Example:** The map  $F: (x, t) \in \mathbb{S}^1 \times [0, 1] \mapsto (\cos(\theta) + 2t, \sin(\theta) + 2t)$  is a homotopy between

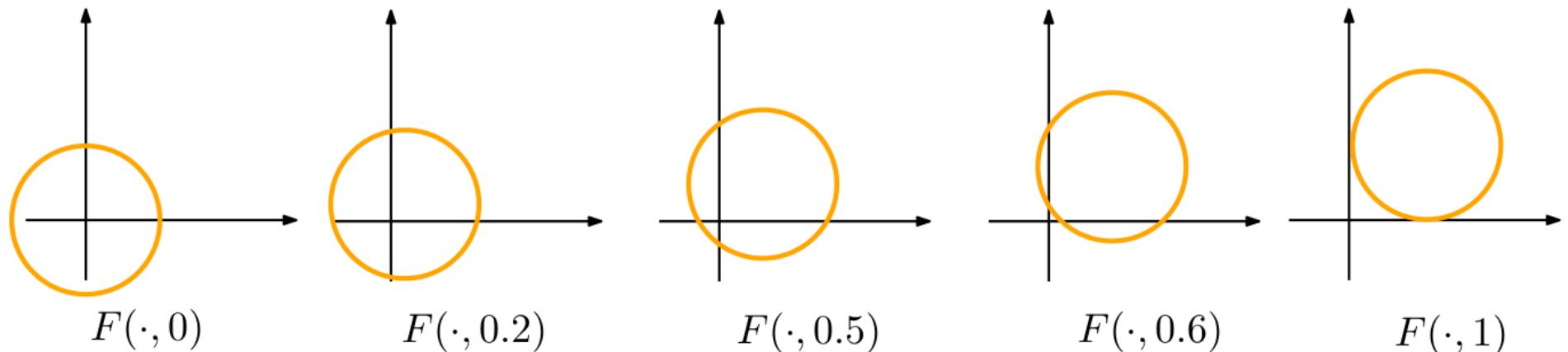
$$f: \mathbb{S}^1 \rightarrow \mathbb{R}^2$$

$$\theta \mapsto (\cos(\theta), \sin(\theta))$$

and

$$g: \mathbb{S}^1 \rightarrow \mathbb{R}^2$$

$$\theta \mapsto (\cos(\theta) + 2, \sin(\theta) + 2)$$



# Homotopies

16/37 (3/3)

**Definition:** Let  $X, Y$  be two topological spaces, and  $f, g: X \rightarrow Y$  two continuous maps. A **homotopy** between  $f$  and  $g$  is a map  $F: X \times [0, 1] \rightarrow Y$  such that:

- $x \mapsto F(x, 0)$  is equal to  $f$ ,
- $x \mapsto F(x, 1)$  is equal to  $g$ ,
- $F: X \times [0, 1] \rightarrow Y$  is continuous.

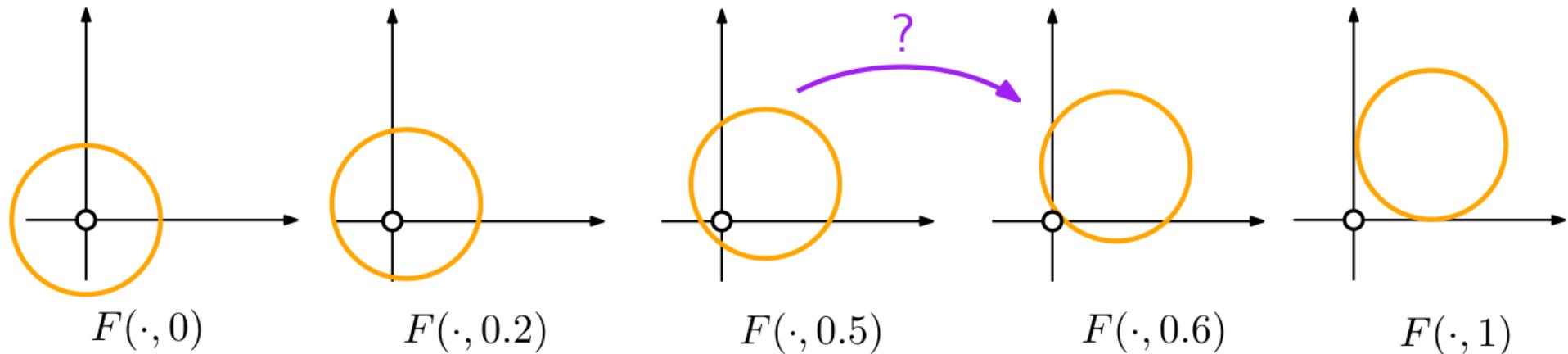
If such a homotopy exists, we say that the maps  $f$  and  $g$  are **homotopic**.

not well-defined

**Example:** The map  $F: (x, t) \in \mathbb{S}^1 \times [0, 1] \mapsto (\cos(\theta) + 2t, \sin(\theta) + 2t)$  ~~is a homotopy~~ between

$$f: \mathbb{S}^1 \rightarrow \mathbb{R}^2 \setminus \{0\}$$
$$\theta \mapsto (\cos(\theta), \sin(\theta))$$

$$g: \mathbb{S}^1 \rightarrow \mathbb{R}^2 \setminus \{0\}$$
$$\theta \mapsto (\cos(\theta) + 2, \sin(\theta) + 2)$$



This is not true anymore if we remove the origin from the plane.

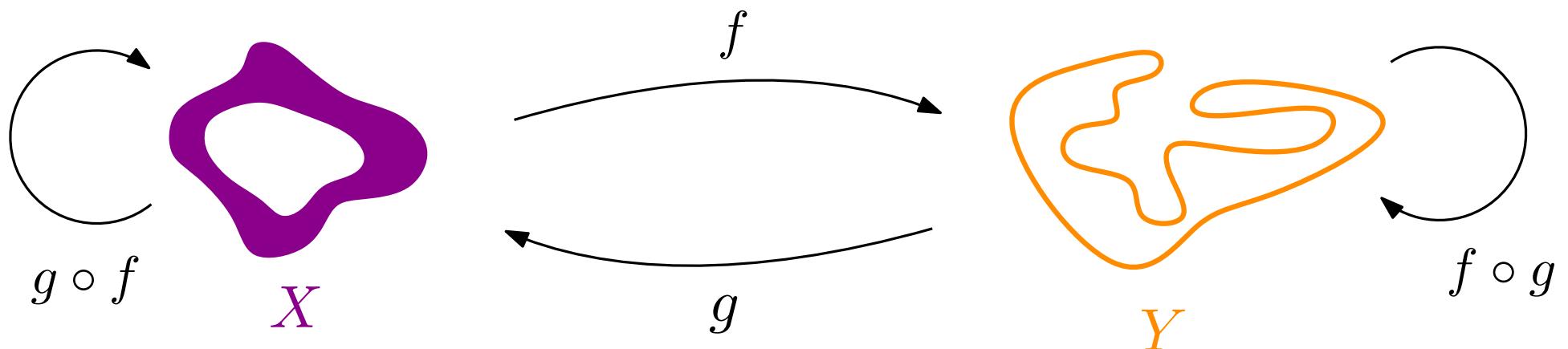
# Equivalência de homotopia

17/37 (1/4)

**Defintion:** Let  $X$  and  $Y$  be two topological spaces. A **homotopy equivalence** between  $X$  and  $Y$  is a pair of continuous maps  $f: X \rightarrow Y$  and  $g: Y \rightarrow X$  such that:

- $g \circ f: X \rightarrow X$  is homotopic to the identity map  $\text{id}: X \rightarrow X$ ,
- $f \circ g: Y \rightarrow Y$  is homotopic to the identity map  $\text{id}: Y \rightarrow Y$ .

If such a homotopy equivalence exists, we say that  $X$  and  $Y$  are **homotopy equivalent**.



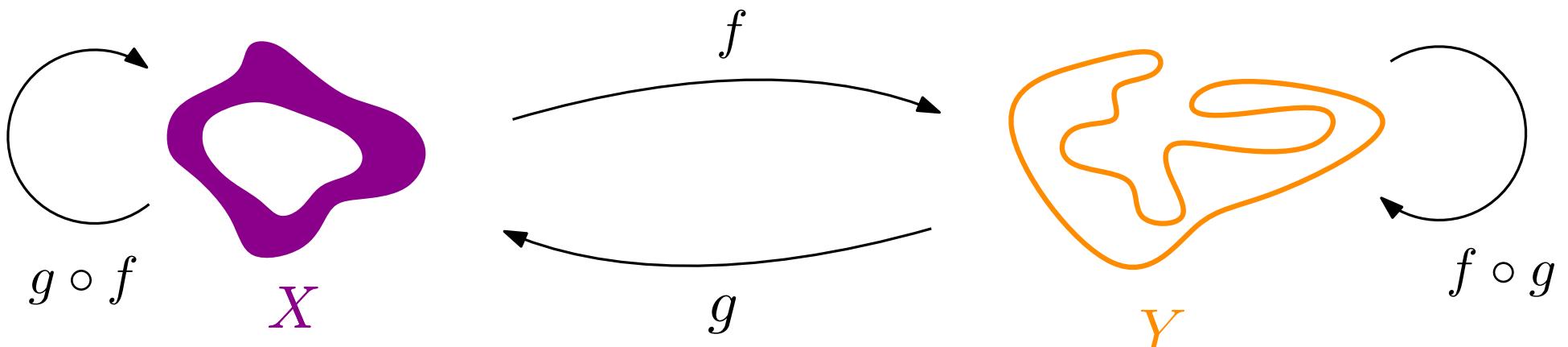
# Equivalência de homotopia

17/37 (2/4)

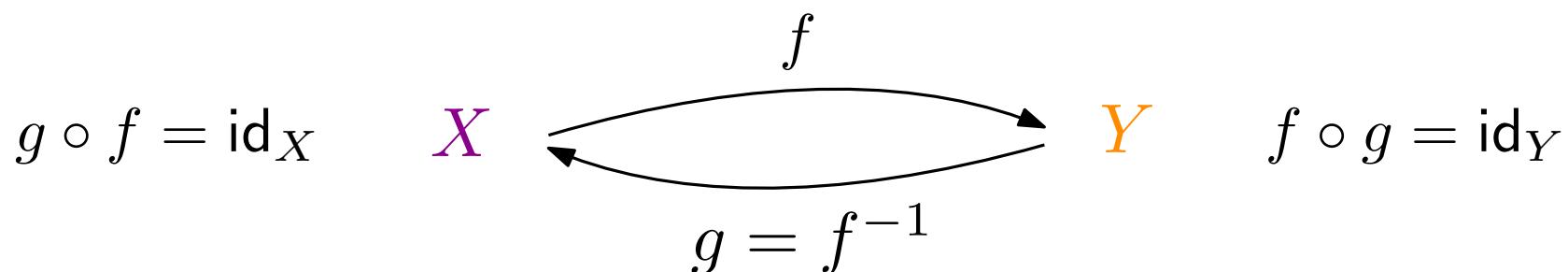
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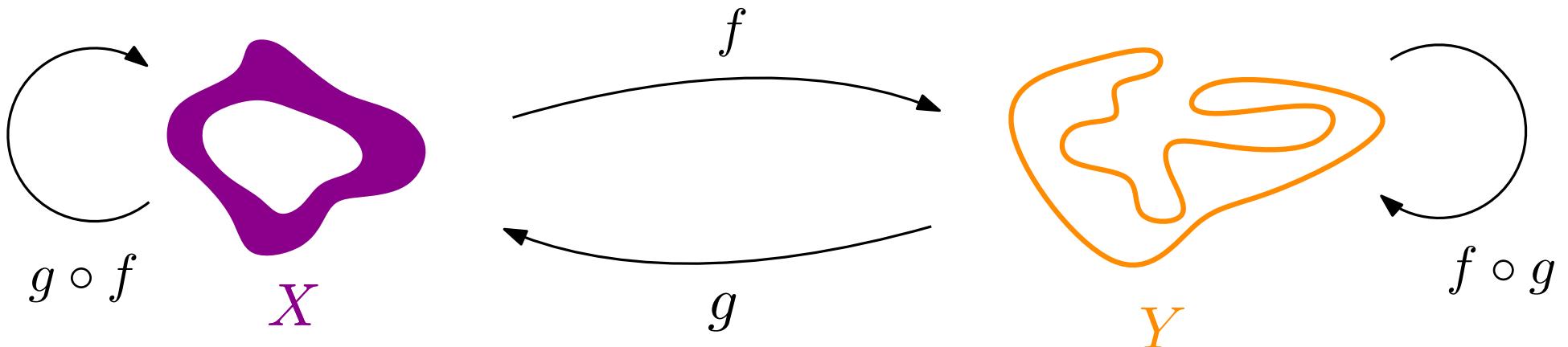
**Observation:** A homotopy equivalence is a weaker formulation of homeomorphism.



**Defintion:** Let  $X$  and  $Y$  be two topological spaces. A **homotopy equivalence** between  $X$  and  $Y$  is a pair of continuous maps  $f: X \rightarrow Y$  and  $g: Y \rightarrow X$  such that:

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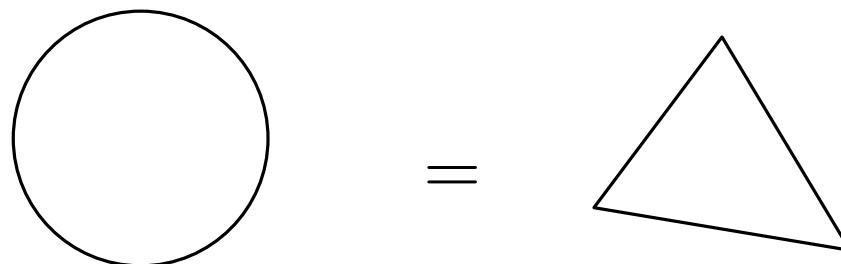
**Observation:** A homotopy equivalence is a weaker formulation of homeomorphism.

**Proposition:** If two topological spaces are homeomorphic, then they are homotopy equivalent.

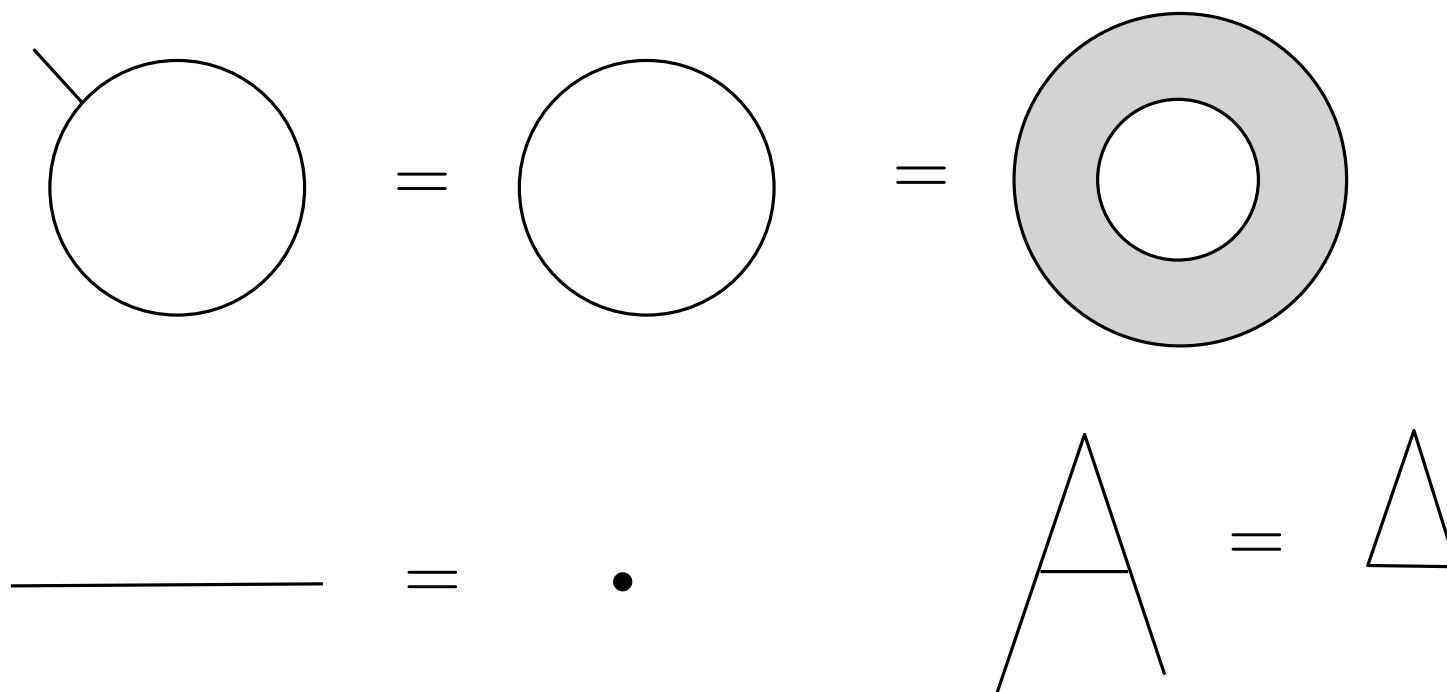
# Equivalência de homotopia

17/37 (4/4)

Homotopy equivalence allows to continuously **deform** the space



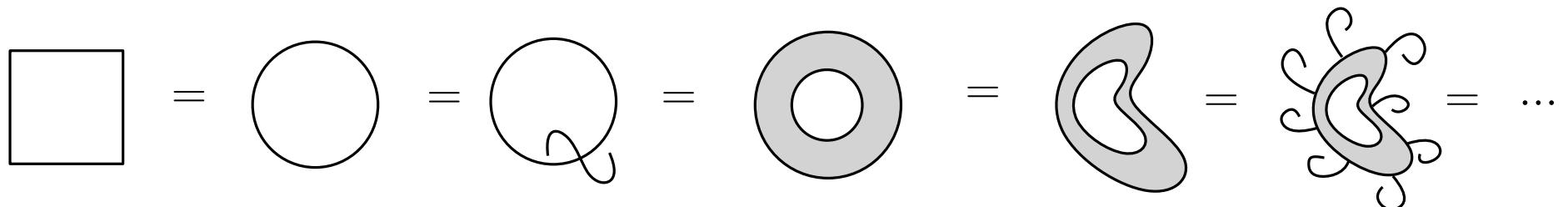
and to **retract** it.



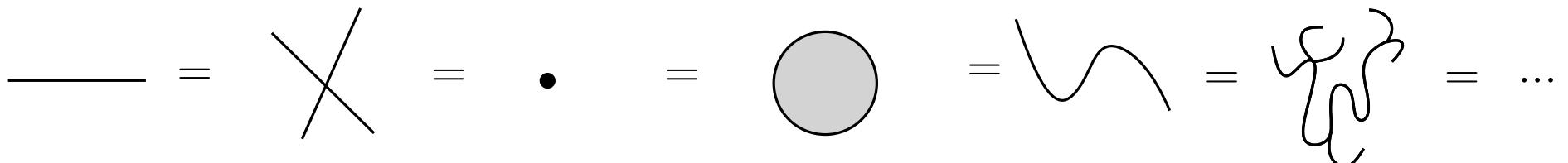
# Classes de homotopia

18/37 (1/3)

Just as before, we can classify topological spaces according to this relation, and obtain **classes of homotopy equivalence**:



the class of circles



the class of points

the class of spheres, the class of torii, the class of Klein bottles, ...

Example: Classification, up to homotopy equivalence, of the alphabet.

A      B      C      D      E      F

G      H      I      J      K      L

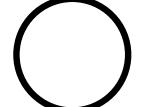
M      N      O      P      Q      R

S      T      U      V      W      X

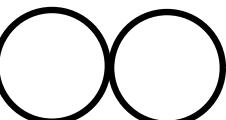
Y      Z

Example: Classification, up to homotopy equivalence, of the alphabet.

A D O P Q R

$\approx$  

B

$\approx$  

C E F G H I J K L

M N S T U V W X Y Z

$\approx$  

# I - Topology

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2 - Topological spaces

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2 - Homotopy equivalence

# III - Topological invariants

1 - Embeddability

2 - Number of connected components

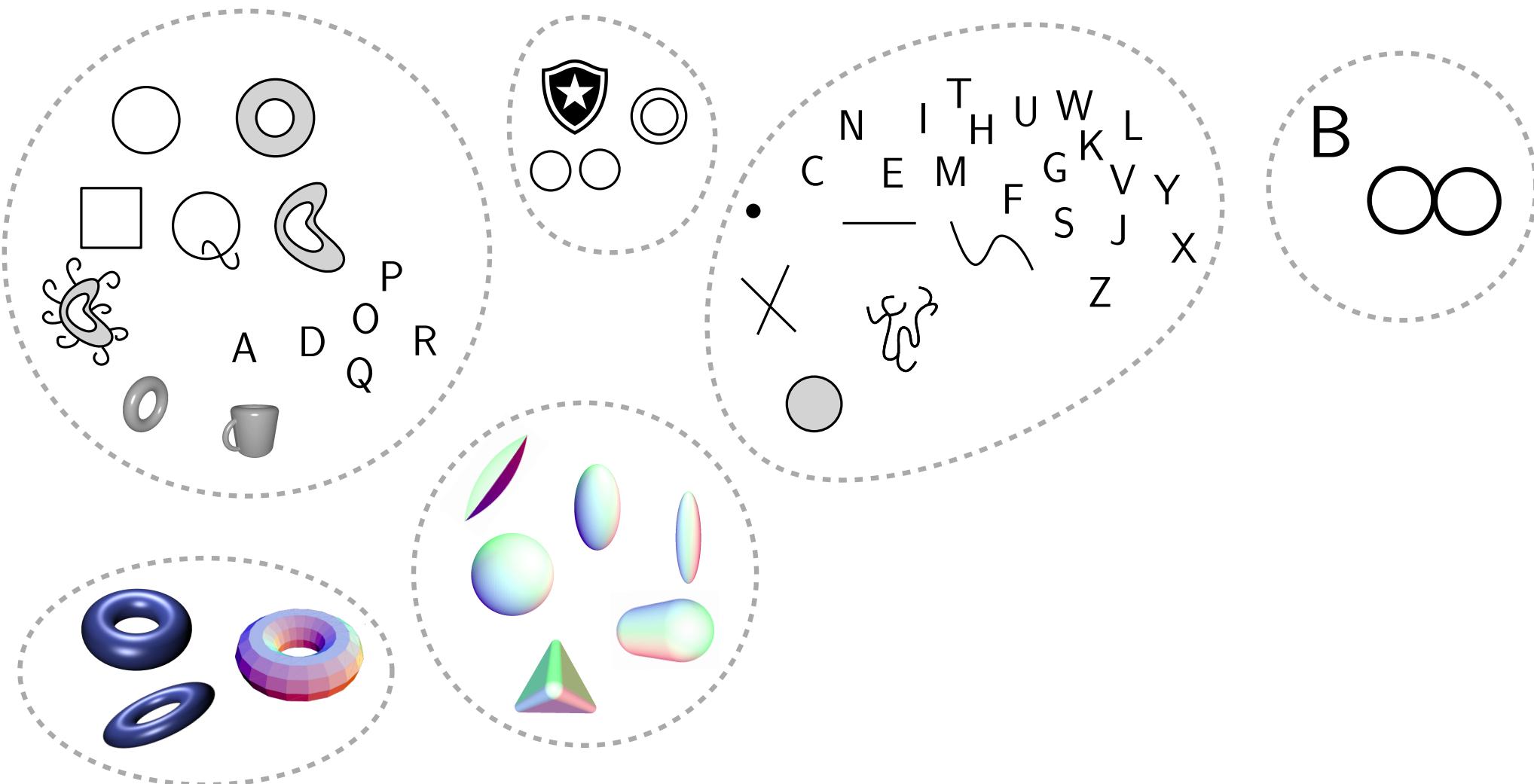
3 - Euler characteristic

4 - Betti numbers

# Características comuns

20/37 (1/2)

We gathered topological spaces into homotopy classes.

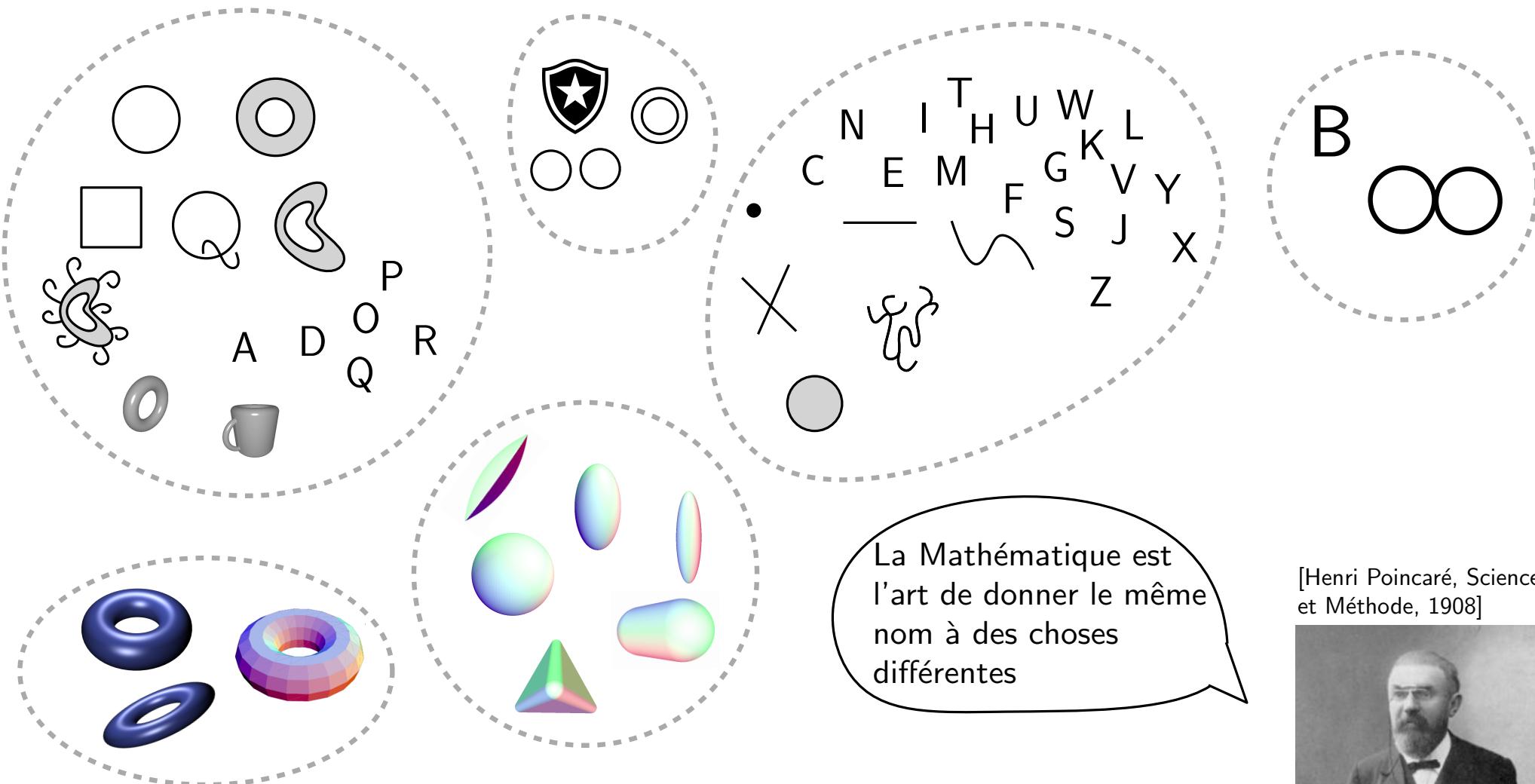


- Given a topological space  $X$ , how to recognize in which class it belongs?
- What are the common **features** of spaces in a same class?

# Características comuns

20/37 (2/2)

We gathered topological spaces into homotopy classes.



[Henri Poincaré, Science et Méthode, 1908]



- Given a topological space  $X$ , how to recognize in which class it belongs?
- What are the common **features** of spaces in a same class?

# I - Topology

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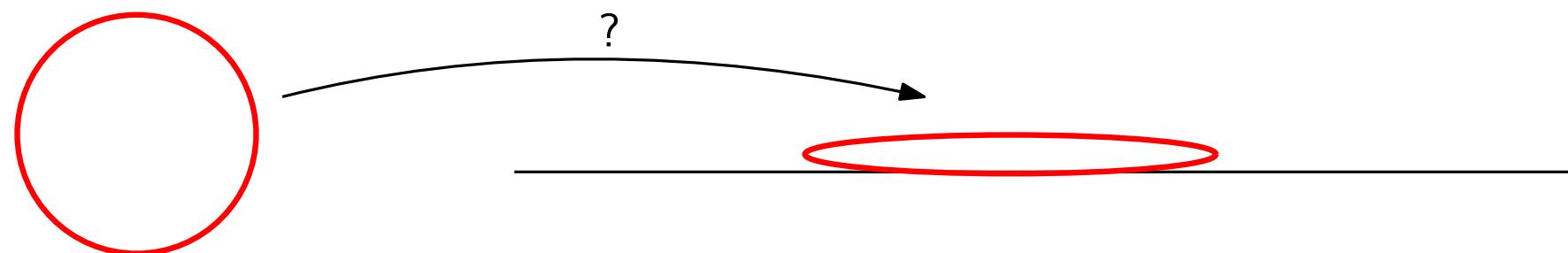
4 - Betti numbers

**Definition:** Let  $n \in \mathbb{N}$ . A topological space  $X$  is **embeddable** in  $\mathbb{R}^n$  if there exists a continuous injective map  $X \rightarrow \mathbb{R}^n$ .

**Example:** The interval  $(0, 1)$  is embeddable in  $\mathbb{R}$ .



The circle  $\mathbb{S}^1$  is not.

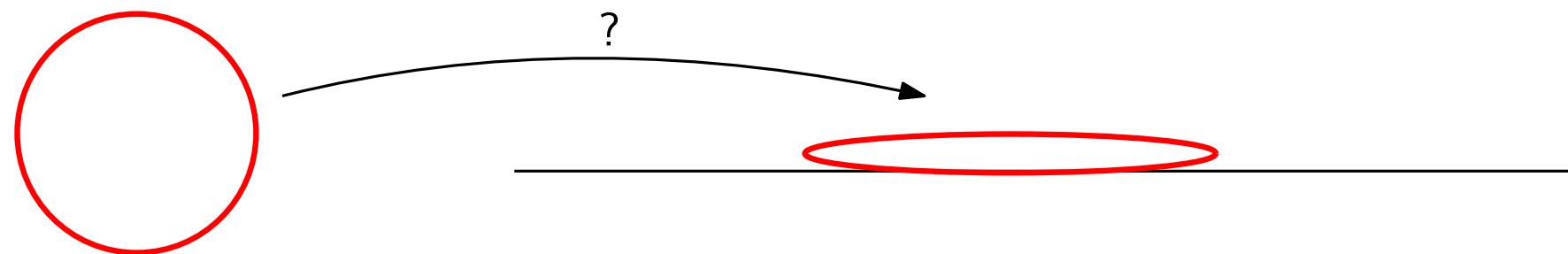


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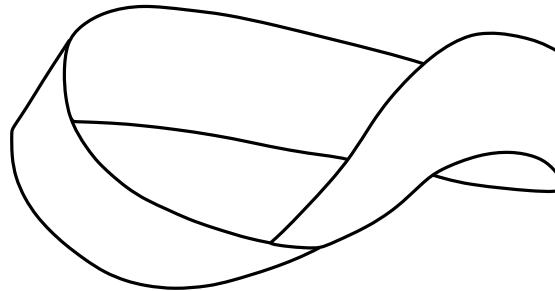
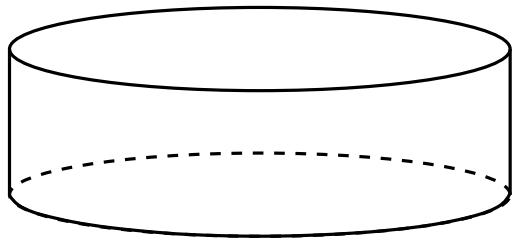
**Proposition:** Let  $n \in \mathbb{N}$ . If two spaces  $X$  and  $Y$  are homeomorphic, then either both are embeddable in  $\mathbb{R}^n$ , or neither.

We say that ‘being embeddable in  $\mathbb{R}^n$ ’ is an **invariant of homeomorphism classes**. It can be used to show that two spaces are not homeomorphic.

# Propriedade de invariância - na teoria 23/37 (1/5)

**Proposition:** Let  $n \in \mathbb{N}$ . If two spaces  $X$  and  $Y$  are homeomorphic, then either both are embeddable in  $\mathbb{R}^n$ , or neither.

**Example:** The cylinder and the Möbius strip are not homeomorphic.



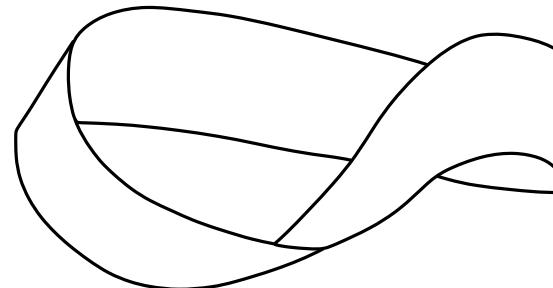
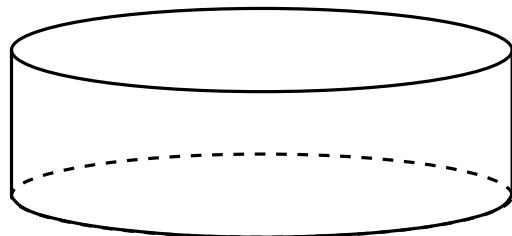
Indeed, the cylinder can be embedded in  $\mathbb{R}^2$  (as an annulus).

If the strip was homeomorphic to the cylinder, then it would be also embeddable in  $\mathbb{R}^2$ .

# Propriedade de invariância - na teoria 23/37 (2/5)

**Proposition:** Let  $n \in \mathbb{N}$ . If two spaces  $X$  and  $Y$  are homeomorphic, then either both are embeddable in  $\mathbb{R}^n$ , or neither.

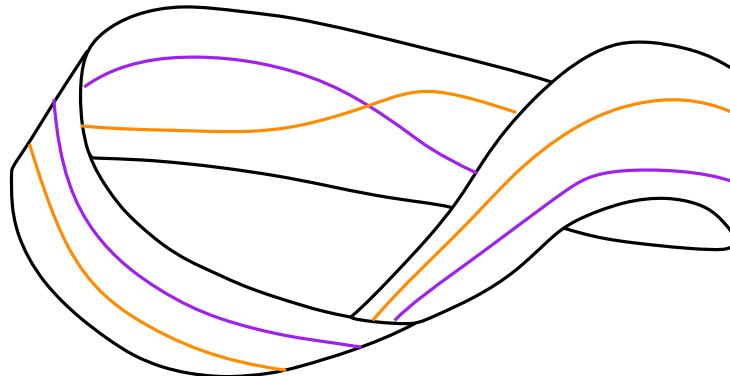
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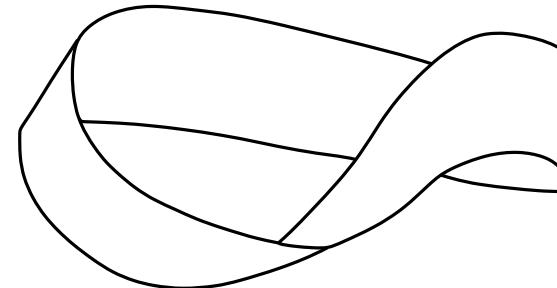
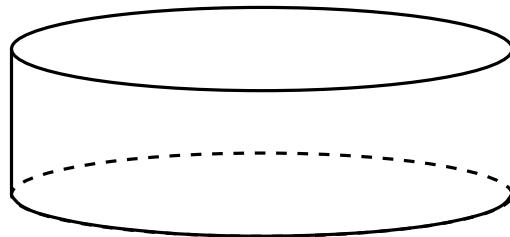
We draw two circles on the strip,  $C_1$  and  $C_2$ , that only intersect once.



# Propriedade de invariância - na teoria 23/37 (3/5)

**Proposition:** Let  $n \in \mathbb{N}$ . If two spaces  $X$  and  $Y$  are homeomorphic, then either both are embeddable in  $\mathbb{R}^n$ , or neither.

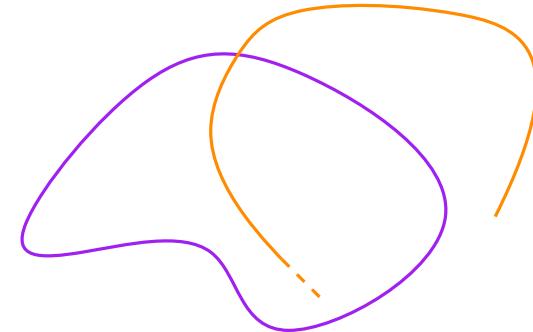
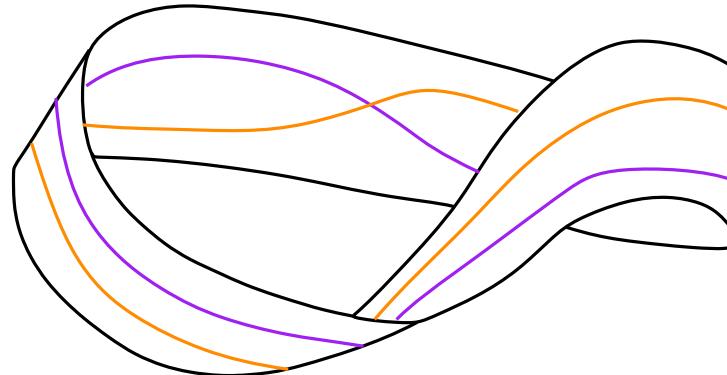
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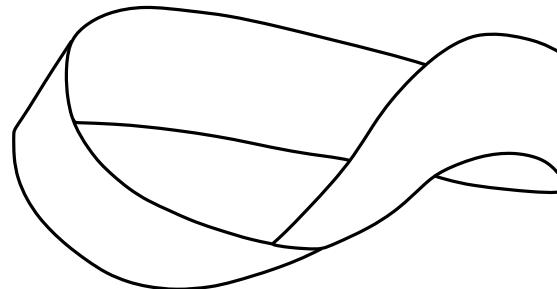
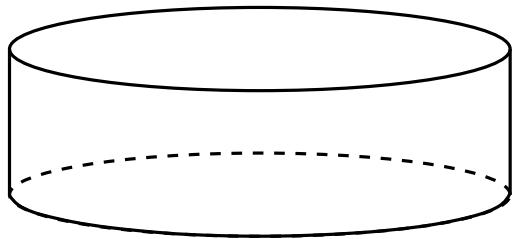
Embedded in  $\mathbb{R}^2$ , the circles  $C_1$  and  $C_2$  only intersect once.

This is impossible by Jordan's theorem.

# Propriedade de invariância - na teoria 23/37 (4/5)

**Proposition:** Let  $n \in \mathbb{N}$ . If two spaces  $X$  and  $Y$  are homeomorphic, then either both are embeddable in  $\mathbb{R}^n$ , or neither.

**Example:** The cylinder and the Möbius strip are not homeomorphic.



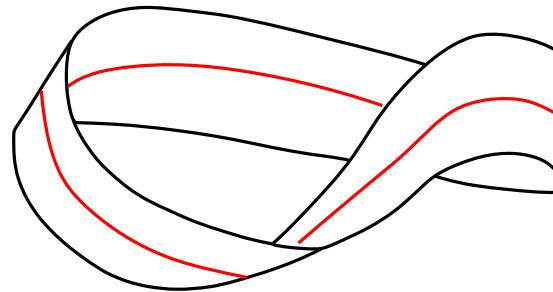
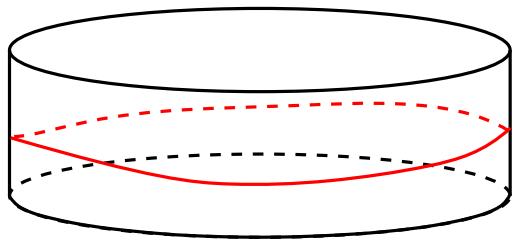
**Remark:** The property ‘being embeddable in  $\mathbb{R}^n$ ’ is **not** an invariant of *homotopy* classes.

Indeed, the space and the cylinder are homotopy equivalent, but only one of them is embeddable in  $\mathbb{R}^2$ .

# Propriedade de invariância - na teoria 23/37 (5/5)

**Proposition:** Let  $n \in \mathbb{N}$ . If two spaces  $X$  and  $Y$  are homeomorphic, then either both are embeddable in  $\mathbb{R}^n$ , or neither.

**Example:** The cylinder and the Möbius strip are not homeomorphic.



**Remark:** The property ‘being embeddable in  $\mathbb{R}^n$ ’ is **not** an invariant of *homotopy classes*.

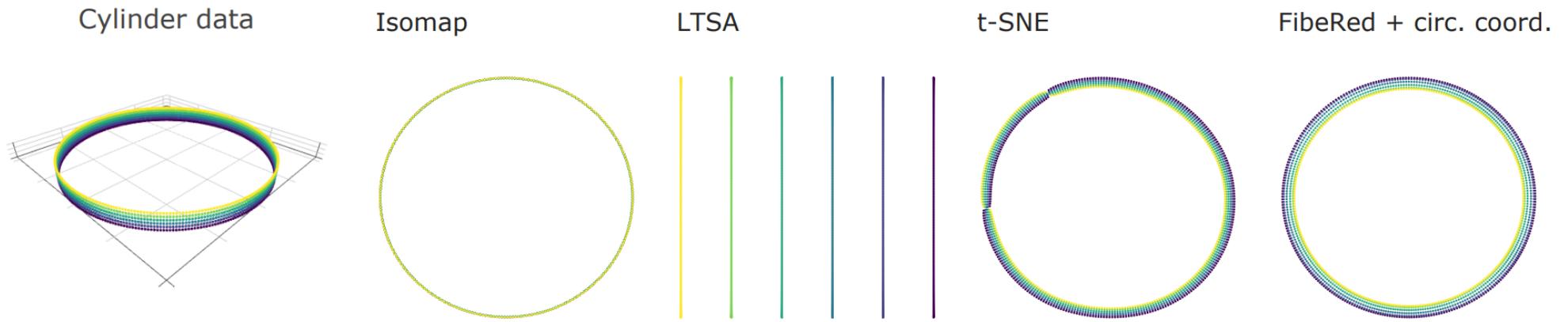
Indeed, the space and the cylinder are homotopy equivalent, but only one of them is embeddable in  $\mathbb{R}^2$ .

They can both be retracted onto their **inner circle**.

# Propriedade de invariância - nas aplicações

24/37

In applications, finding an embedding corresponds to the problem of **dimensionality reduction**.



Illustrations from [Luis Scoccola, Jose A. Perea, [Fiberwise dimensionality reduction of topologically complex data with vector bundles](#), 2022]

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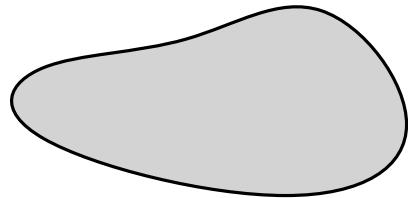
3 - Euler characteristic

4 - Betti numbers

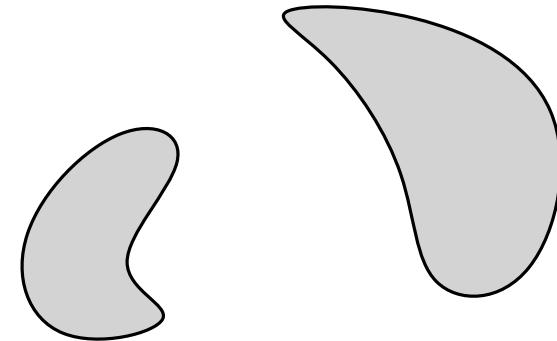
# Componentes conexas

26/37 (1/4)

**Definition:** A subset  $X \subset \mathbb{R}^n$  is (path-) **connected** if for every  $x, y \in X$ , there exists a continuous map  $f: [0, 1] \rightarrow X$  such that  $f(0) = x$  and  $f(1) = y$ .



connected space

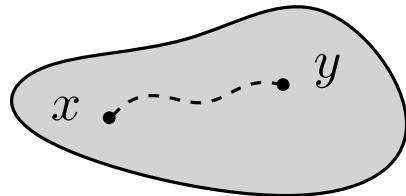


non-connected space

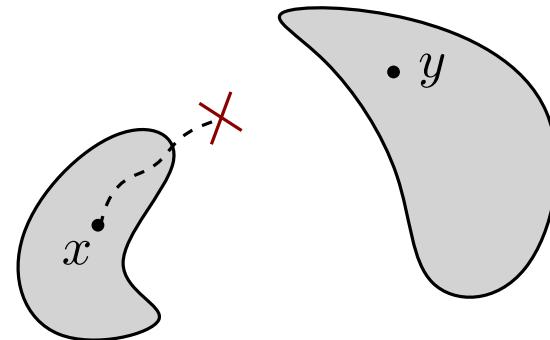
# Componentes conexas

26/37 (2/4)

**Definition:** A subset  $X \subset \mathbb{R}^n$  is (path-) **connected** if for every  $x, y \in X$ , there exists a continuous map  $f: [0, 1] \rightarrow X$  such that  $f(0) = x$  and  $f(1) = y$ .



connected space

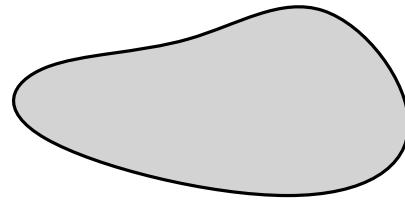


non-connected space

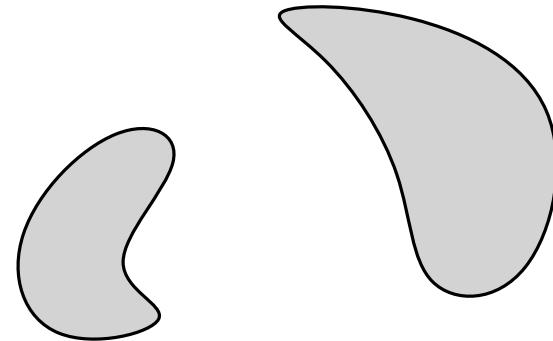
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26/37 (3/4)

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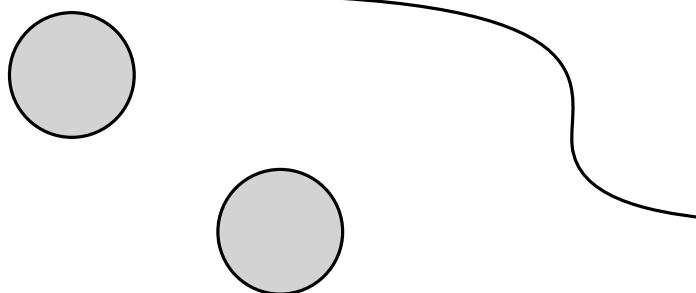
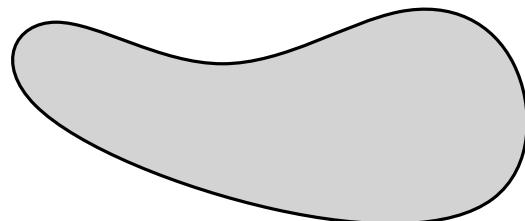


connected space



non-connected space

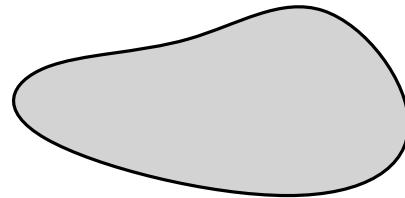
More generally, any topological space  $X$  can be partitioned into **connected components**.



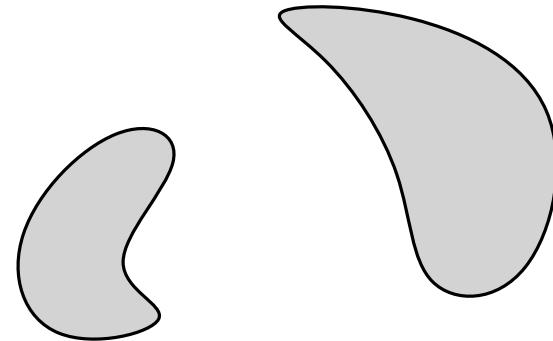
# Componentes conexas

26/37 (4/4)

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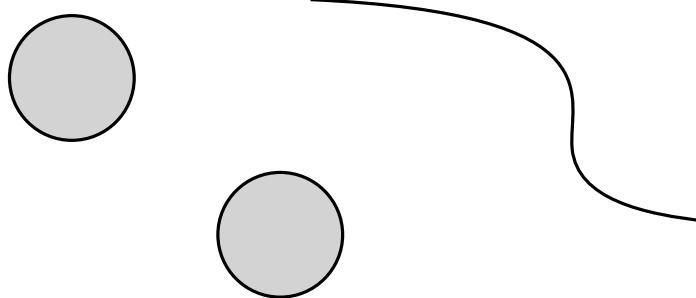
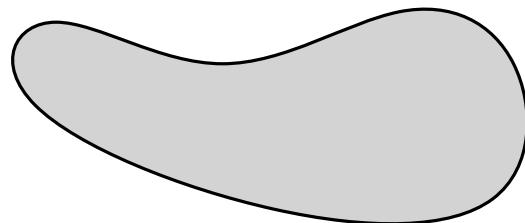


connected space



non-connected space

More generally, any topological space  $X$  can be partitioned into **connected components**.



**Proposition:** If two spaces  $X$  and  $Y$  are homotopy equivalent, then they have the same number of connected components.

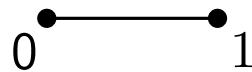
# Propriedade de invariância - na teoria 27/37 (1/5)

**Proposition:** If two spaces  $X$  and  $Y$  are homotopy equivalent, then they have the same number of connected components.

**Consequence:** If two spaces  $X$  and  $Y$  are homeomorphic, then they have the same number of connected components.

**Example:** The subsets  $[0, 1]$  and  $[0, 1] \cup [2, 3]$  of  $\mathbb{R}$  are not homeomorphic, neither homotopy equivalent.

Indeed, the first one has one connected component, and the second one two.

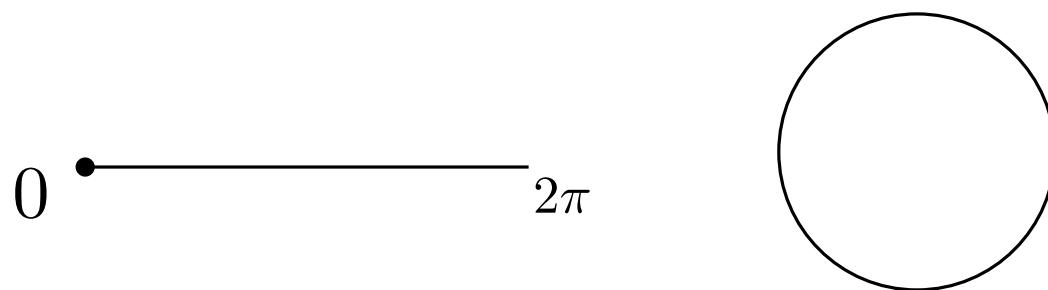


# Propriedade de invariância - na teoria 27/37 (2/5)

**Proposition:** If two spaces  $X$  and  $Y$  are homotopy equivalent, then they have the same number of connected components.

**Example:** The interval  $[0, 2\pi)$  and the circle  $\mathbb{S}_1 \subset \mathbb{R}^2$  are not homeomorphic.

We will prove this by contradiction. Suppose that they are homeomorphic. By definition, this means that there exists a map  $f: [0, 2\pi) \rightarrow \mathbb{S}_1$  which is continuous, invertible, and with continuous inverse.

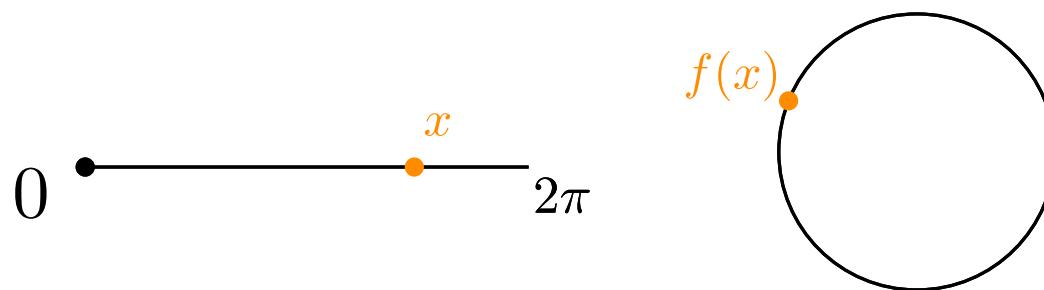


# Propriedade de invariância - na teoria 27/37 (3/5)

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Let  $x \in [0, 2\pi)$  such that  $x \neq 0$ . Consider the subsets  $[0, 2\pi) \setminus \{x\} \subset [0, 2\pi)$  and  $\mathbb{S}_1 \setminus \{f(x)\} \subset \mathbb{S}_1$ , and the induced map

$$g: [0, 2\pi) \setminus \{x\} \rightarrow \mathbb{S}_1 \setminus \{f(x)\}.$$

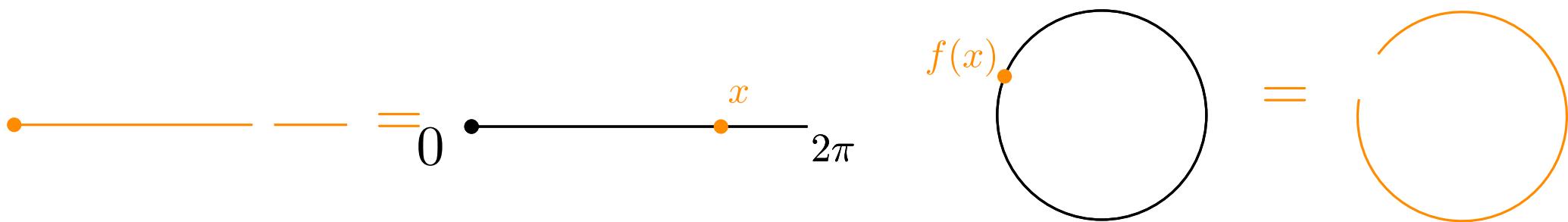
The map  $g$  is a homeomorphism.

# Propriedade de invariância - na teoria 27/37 (4/5)

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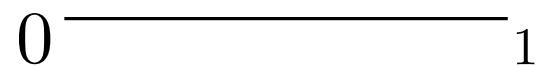
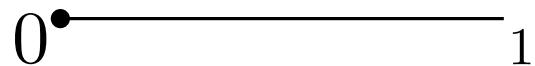
The map  $g$  is a homeomorphism.

Moreover,  $[0, 2\pi) \setminus \{x\}$  has two connected components, and  $\mathbb{S}_1 \setminus \{f(x)\}$  only one. This is absurd.

# Propriedade de invariância - na teoria 27/37 (5/5)

**Proposition:** If two spaces  $X$  and  $Y$  are homotopy equivalent, then they have the same number of connected components.

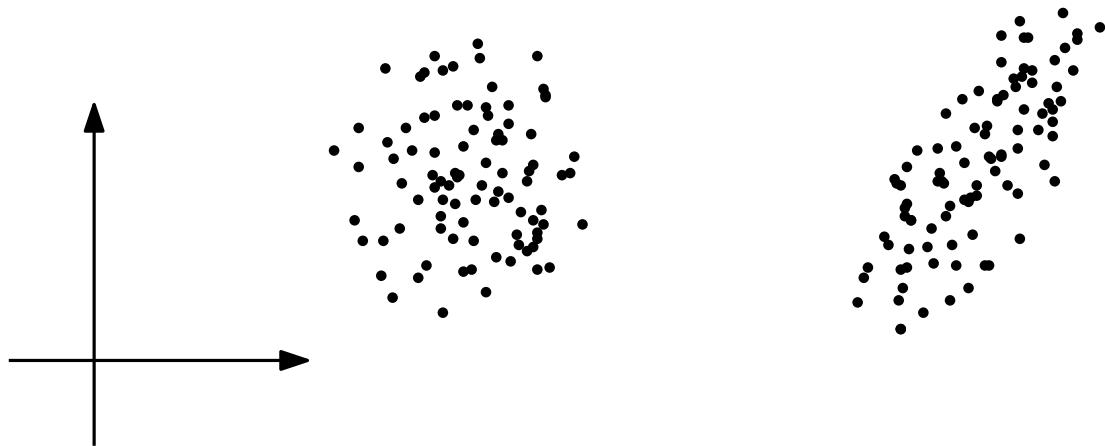
**Homework:** The intervals  $[0, 1)$  and  $(0, 1)$  are not homeomorphic.



# Propriedade de invariância - nas aplicações

28/37 (1/3)

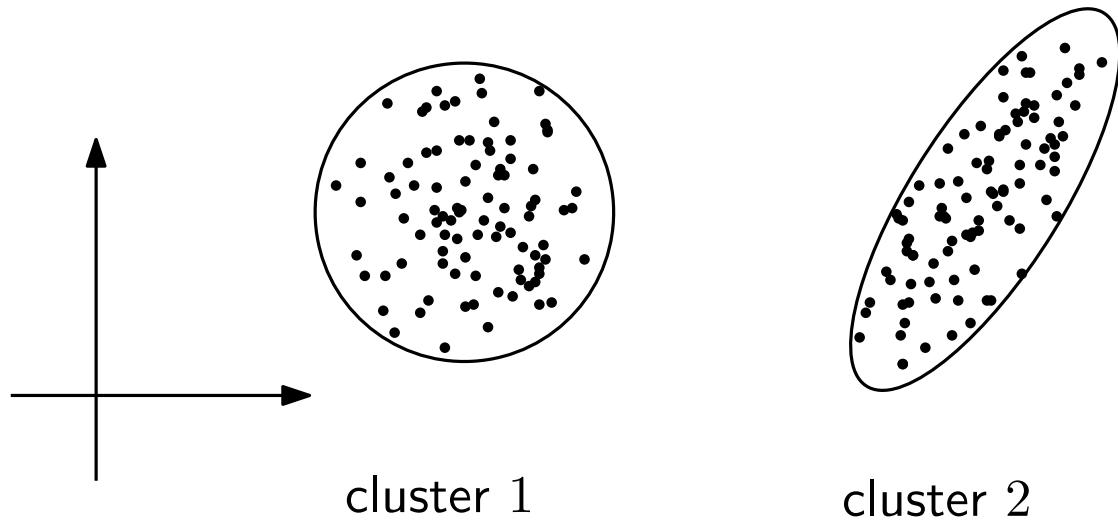
In applications, finding connected components corresponds to a **classification** task.



# Propriedade de invariância - nas aplicações

28/37 (2/3)

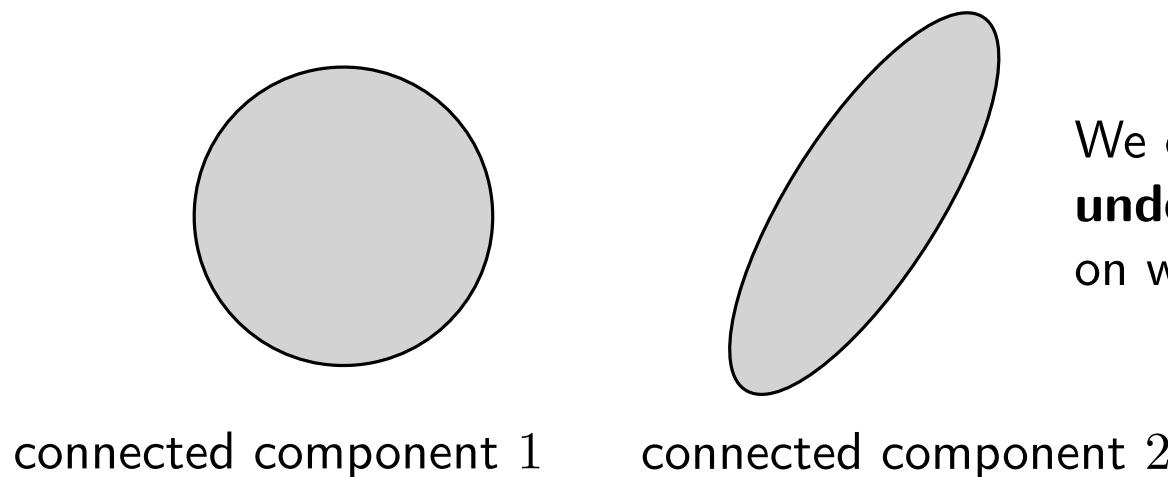
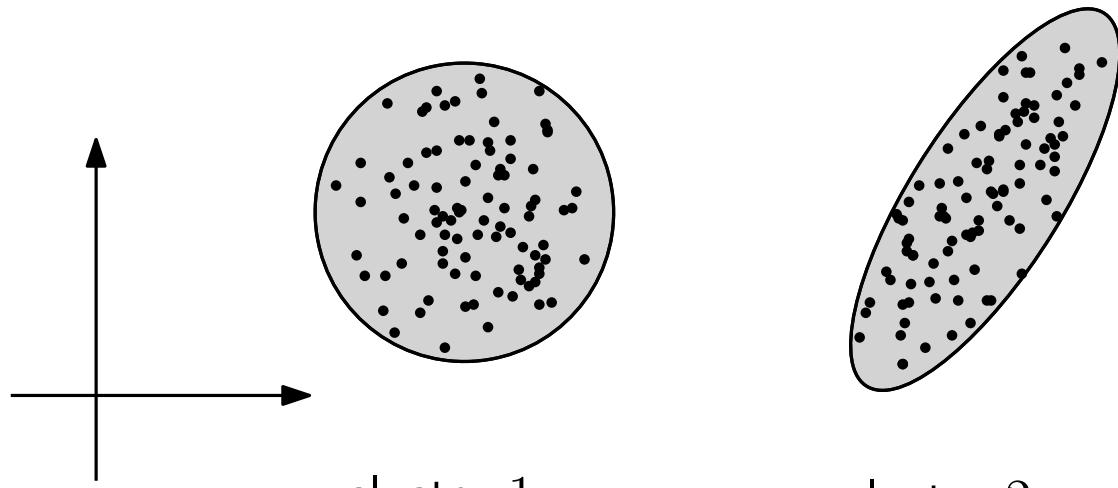
In applications, finding connected components corresponds to a **classification** task.



# Propriedade de invariância - nas aplicações

28/37 (3/3)

In applications, finding connected components corresponds to a **classification** task.



We can think of these sets as an **underlying topological space**, on which the points are sampled.

# I - Topology

1 - History

2 - Topological spaces

# II - Comparing topological spaces

1 - Homeomorphism equivalence

2 - Homotopy equivalence

# III - Topological invariants

1 - Embeddability

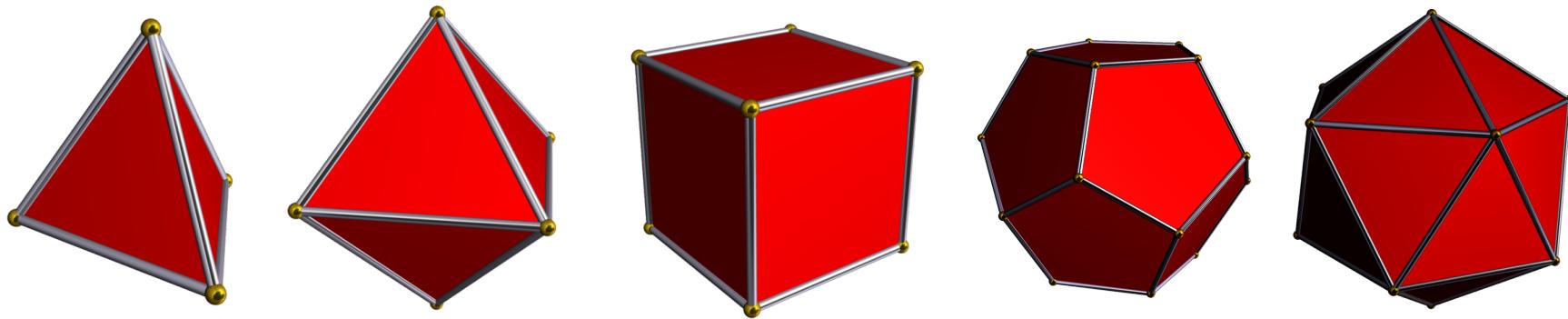
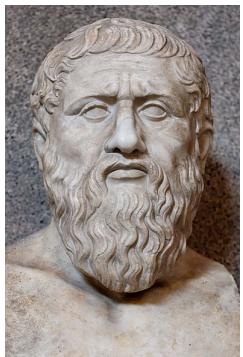
2 - Number of connected components

3 - Euler characteristic

4 - Betti numbers

# Característica de Euler

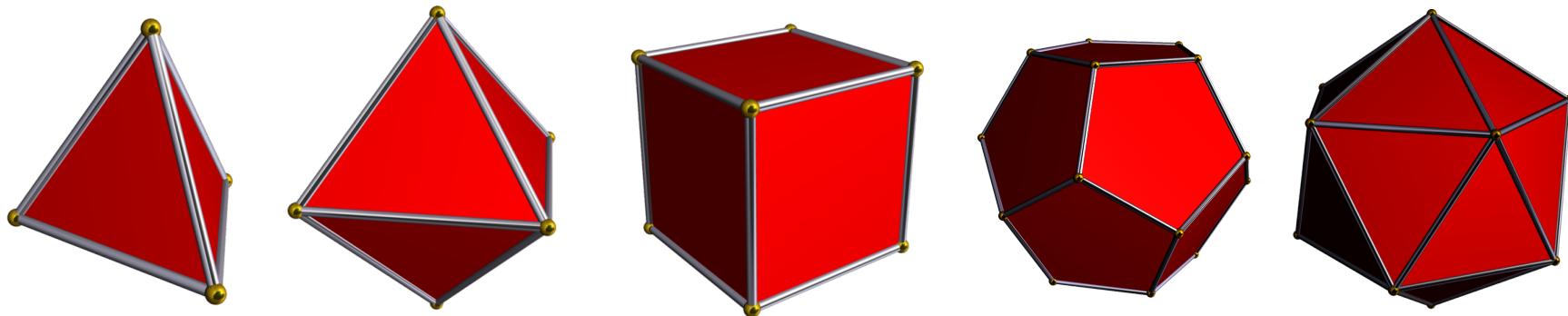
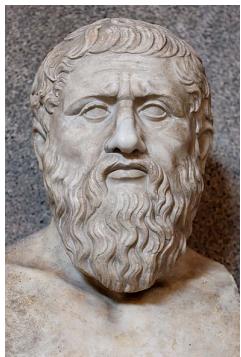
30/37 (1/10)



number of faces	4	8	6	12	20
number of edges	6	12	12	30	30
number of vertices	4	6	8	20	12
$\chi$	2	2	2	2	2

# Característica de Euler

30/37 (2/10)



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number of edges	6	12	12	30	30
number of vertices	4	6	8	20	12
$\chi$	2	2	2	2	2



**Proposition [Euler, 1758]:** In any convex polyhedron, we have  
number of faces – number of edges + number of vertices = 2

**Definition:** Let  $V$  be a set (called the set of *vertices*). A **simplicial complex** over  $V$  is a set  $K$  of subsets of  $V$  (called the *simplices*) such that, for every  $\sigma \in K$  and every non-empty  $\tau \subset \sigma$ , we have  $\tau \in K$ .

The **dimension** of a simplex  $\sigma \in K$  is defined as  $|\sigma| - 1$ .

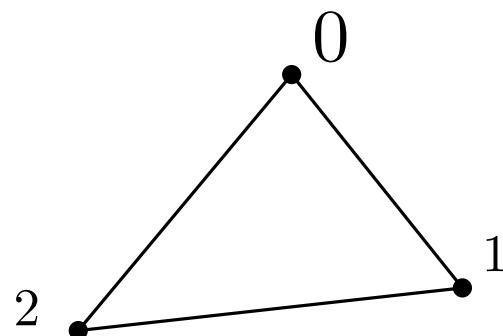
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**Example:** Let  $V = \{0, 1, 2\}$  and

$$K = \{[0], [1], [2], [0, 1], [1, 2], [0, 2]\}.$$

This is a simplicial complex.



It contains three simplices of dimension 0 ( $[0]$ ,  $[1]$  and  $[2]$ ) and three simplices of dimension 1 ( $[0, 1]$ ,  $[1, 2]$  and  $[0, 2]$ ).

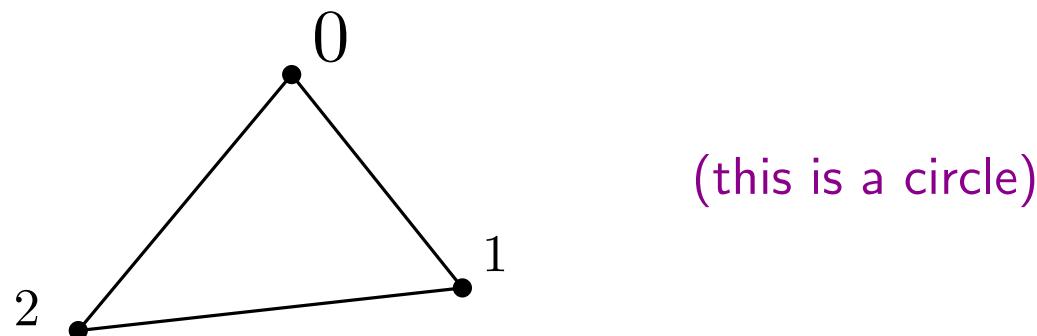
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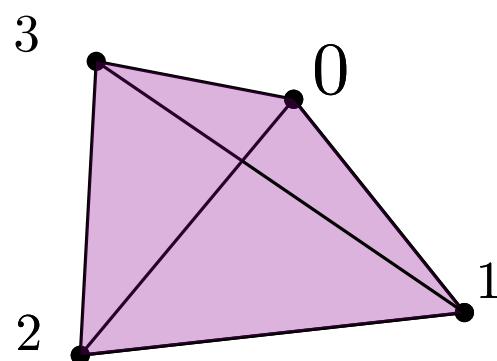
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**Example:** Let  $V = \{0, 1, 2, 3\}$  and

$$K = \{[0], [1], [2], [3], [0, 1], [1, 2], [2, 3], [3, 0], [0, 2], [1, 3], [0, 1, 2], [0, 1, 3], [0, 2, 3], [1, 2, 3]\}$$

It a simplicial complex.



It contains four simplices of dimension 0 ( $[0]$ ,  $[1]$ ,  $[2]$  and  $[3]$ ), six simplices of dimension 1 ( $[0, 1]$ ,  $[1, 2]$ ,  $[2, 3]$ ,  $[3, 0]$ ,  $[0, 2]$  and  $[1, 3]$ ) and four simplices of dimension 2 ( $[0, 1, 2]$ ,  $[0, 1, 3]$ ,  $[0, 2, 3]$  and  $[1, 2, 3]$ ).

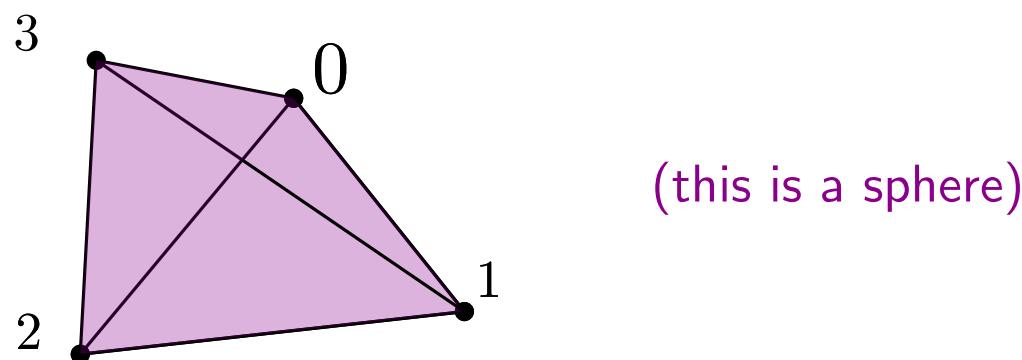
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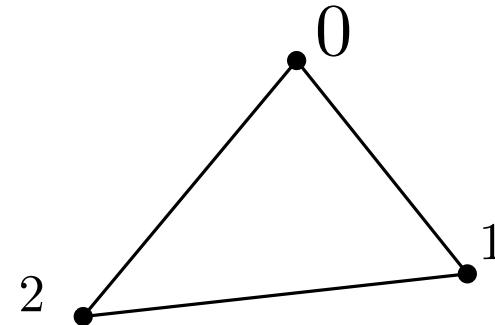
It contains four simplices of dimension 0 ( $[0]$ ,  $[1]$ ,  $[2]$  and  $[3]$ ), six simplices of dimension 1 ( $[0, 1]$ ,  $[1, 2]$ ,  $[2, 3]$ ,  $[3, 0]$ ,  $[0, 2]$  and  $[1, 3]$ ) and four simplices of dimension 2 ( $[0, 1, 2]$ ,  $[0, 1, 3]$ ,  $[0, 2, 3]$  and  $[1, 2, 3]$ ).

**Definition:** Let  $K$  be a simplicial complex of dimension  $n$ . Its **Euler characteristic** is the integer

$$\chi(K) = \sum_{0 \leq i \leq n} (-1)^i \cdot (\text{number of simplices of dimension } i).$$

**Example:** The simplicial complex  $K = \{[0], [1], [2], [0, 1], [1, 2], [2, 0]\}$  has Euler characteristic

$$\chi(K) = 3 - 3 = 0$$

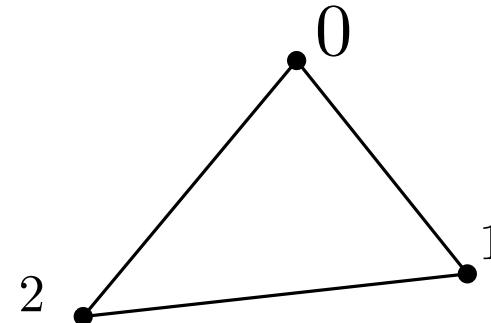


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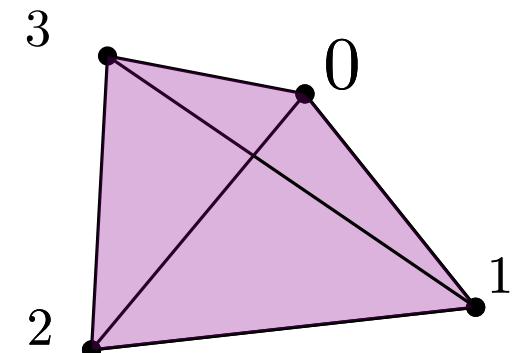
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**Example:** The simplicial complex

$K = \{[0], [1], [2], [3], [0, 1], [1, 2], [2, 3], [3, 0], [0, 2], [1, 3], [0, 1, 2], [0, 1, 3], [0, 2, 3], [1, 2, 3]\}$  has Euler characteristic

$$\chi(K) = 4 - 6 + 4 = 2$$



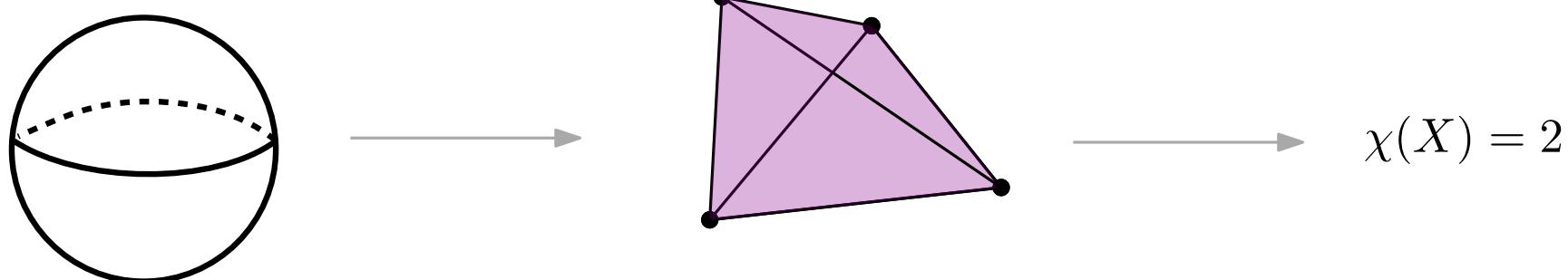
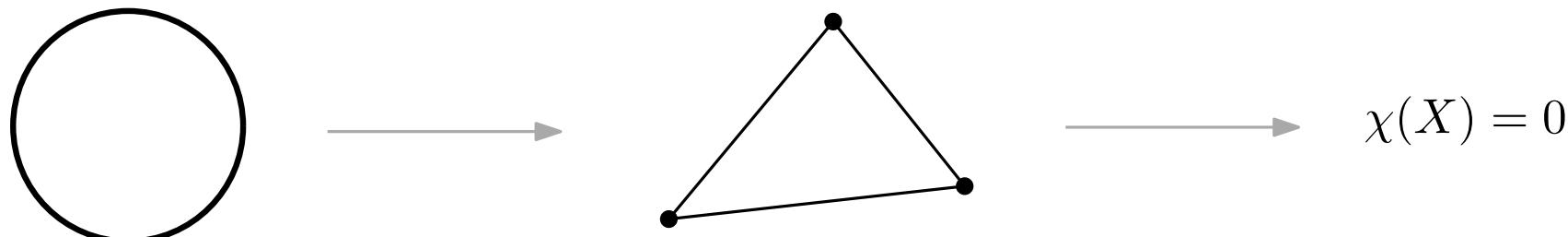
# Característica de Euler

30/37 (10/10)

**Definition:** Let  $K$  be a simplicial complex of dimension  $n$ . Its **Euler characteristic** is the integer

$$\chi(K) = \sum_{0 \leq i \leq n} (-1)^i \cdot (\text{number of simplices of dimension } i).$$

**Definition:** Let  $X$  be a topological space. Its **Euler characteristic** is defined as the Euler characteristic of a *triangulation* of  $X$ .



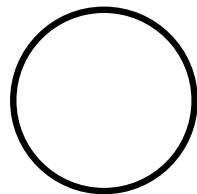
# Propriedade de invariância - na teoria 31/37 (1/2)

**Proposition:** If  $X$  and  $Y$  are two homotopy equivalent topological spaces, then  $\chi(X) = \chi(Y)$ .

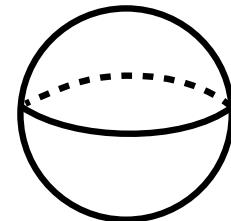
Therefore, the Euler characteristic is an **invariant** of homotopy equivalence classes.

We can use this information to prove that two spaces are not homotopy equivalent.

**Example:** The circle has Euler characteristic 0, and the sphere Euler characteristic 2. Therefore, they are not homotopy equivalent.



$$\chi(S_1) = 0$$



$$\chi(S_2) = 2$$

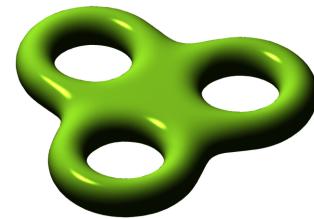
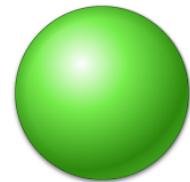
# Propriedade de invariância - na teoria 31/37 (2/2)

**Proposition:** If  $X$  and  $Y$  are two homotopy equivalent topological spaces, then  $\chi(X) = \chi(Y)$ .

Therefore, the Euler characteristic is an **invariant** of homotopy equivalence classes.

We can use this information to prove that two spaces are not homotopy equivalent.

**Example (Classification of surfaces):** The homeomorphism classes of *connected and compact surfaces* are classified by their Euler characteristic.



...

$\chi$

2

0

-2

-4

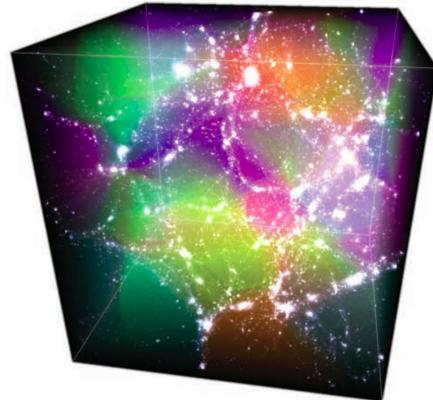
$2 - 2 \times \text{genus}$

# Propriedade de invariância - nas aplicações

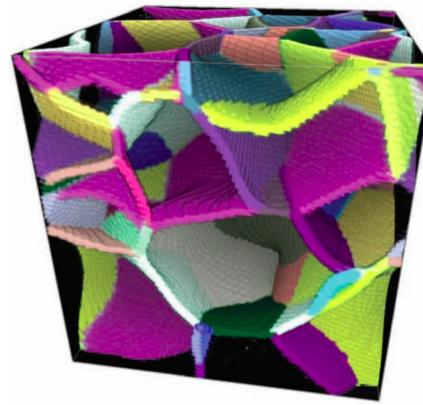
32/37 (1/2)

The Euler characteristic contains information about the homeomorphism class (and homotopy class) of the space.

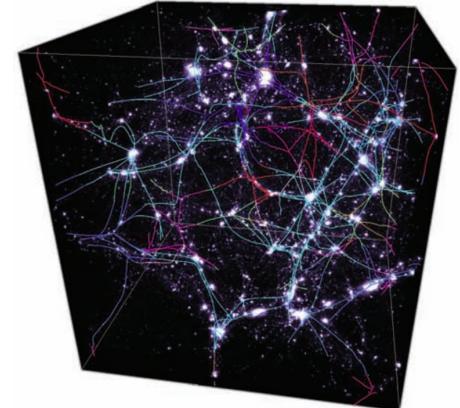
[T. Sousbie, [The persistent cosmic web and its filamentary structure](#), 2011]



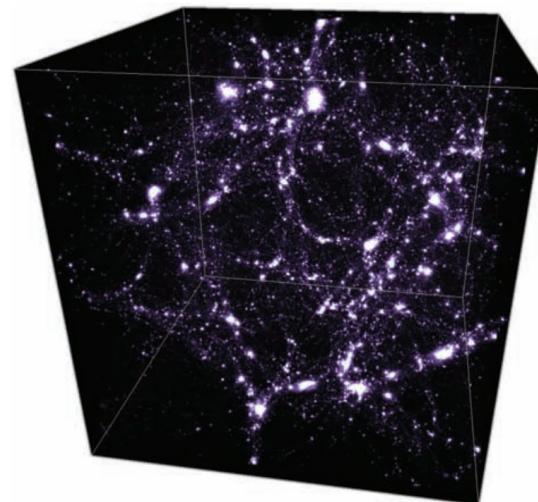
seen as an object of dimension 3



of dimension 2



of dimension 1

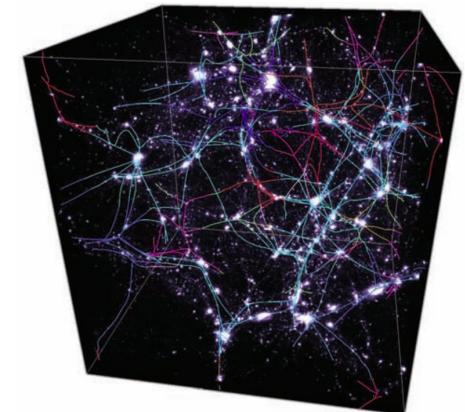
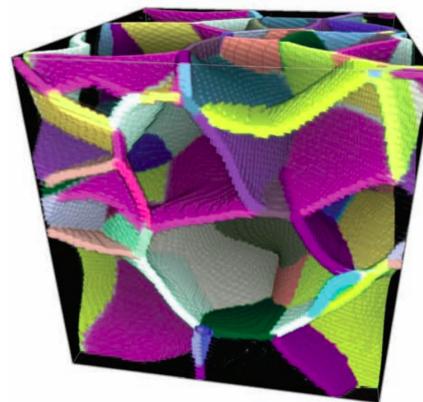
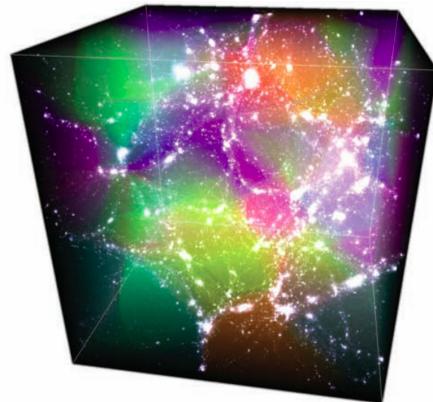


# Propriedade de invariância - nas aplicações

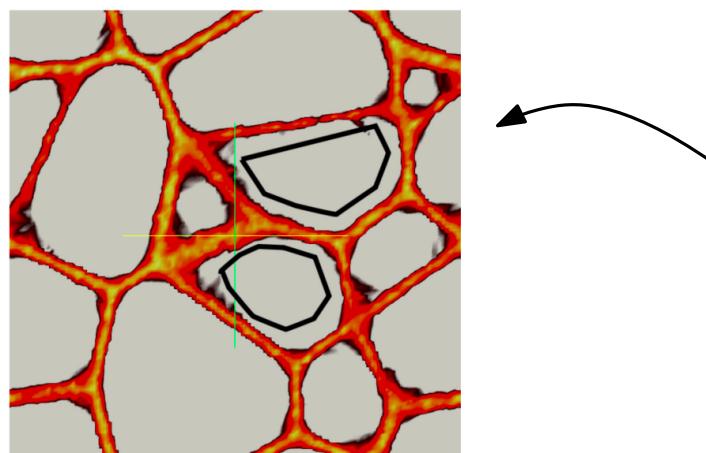
32/37 (2/2)

The Euler characteristic contains information about the homeomorphism class (and homotopy class) of the space.

[T. Sousbie, [The persistent cosmic web and its filamentary structure](#), 2011]



[P. Pranav, H. Edelsbrunner, R. de Weygaert, G. Vegter, M. Kerber, B. Jones and M. Wintraecken, [The topology of the cosmic web in terms of persistent Betti numbers](#), 2016]



The Euler characteristic 'counts' the number of holes

# I - Topology

1 - History

2 - Topological spaces

# II - Comparing topological spaces

1 - Homeomorphism equivalence

2 - Homotopy equivalence

# III - Topological invariants

1 - Embeddability

2 - Number of connected components

3 - Euler characteristic

4 - Betti numbers

For any topological space  $X$ , one defines a sequence of integers

$$\beta_0(X), \quad \beta_1(X), \quad \beta_2(X), \quad \beta_3(X), \quad \dots$$

called the **Betti numbers**.

Construction of Betti numbers:

For any topological space  $X$ , one defines a sequence of integers

$$\beta_0(X), \quad \beta_1(X), \quad \beta_2(X), \quad \beta_3(X), \quad \dots$$

called the **Betti numbers**.

Construction of Betti numbers: rendez-vous on Thursday! (based on homology theory)

Example: Let us give some examples instead.

$X$	●	○	○ -	○ ○	○ ○
$\beta_0(X)$	1	1	1	1	2
$\beta_1(X)$	0	1	0	2	2
$\beta_2(X)$	0	0	1	0	0

For any topological space  $X$ , one defines a sequence of integers

$$\beta_0(X), \quad \beta_1(X), \quad \beta_2(X), \quad \beta_3(X), \quad \dots$$

called the **Betti numbers**.

Construction of Betti numbers: rendez-vous on Thursday! (based on homology theory)

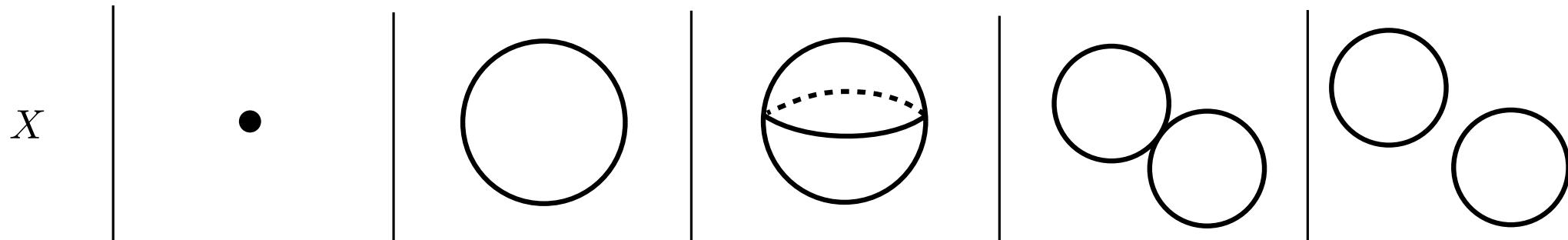
Example: Let us give some examples instead.

$X$	●	○	○ -	○ ○	○ ○
$\beta_0(X)$	1	1	1	1	2
$\beta_1(X)$	0	1	0	2	2
$\beta_2(X)$	0	0	1	0	0

**Interpretation:** We have:

- $\beta_0(X)$  is the number of connected components of  $X$
- $\beta_1(X)$  is the number of 'holes' in  $X$
- $\beta_2(X)$  is the number of 'voids' in  $X$
- ...

**Example:** Let us give some examples instead.

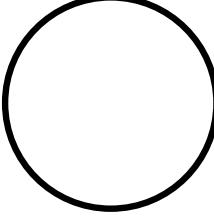
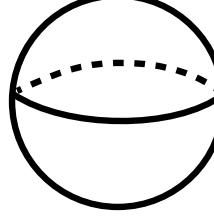
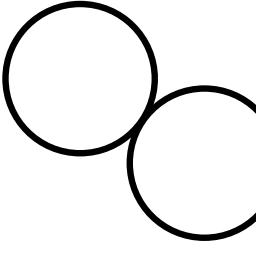
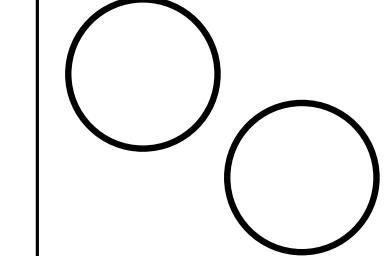


	$X$				
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$\beta_1(X)$	0	1	0	2	2
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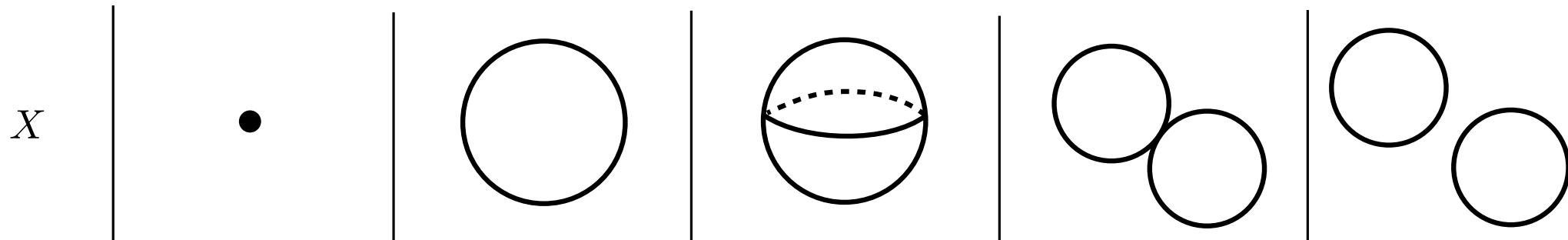
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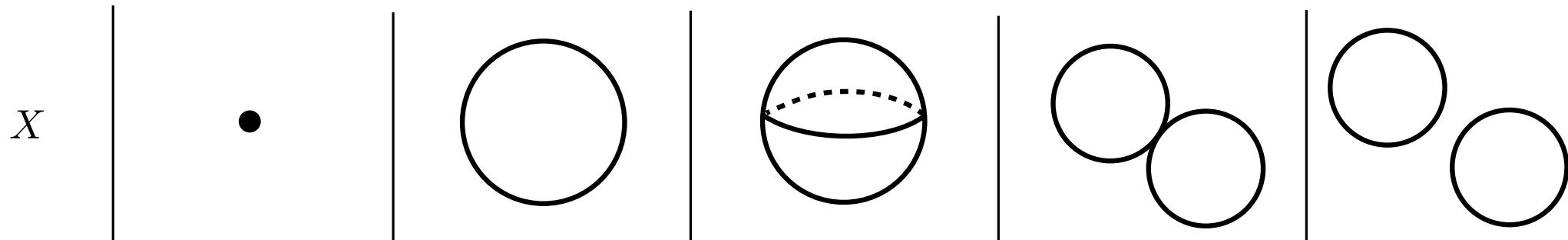


$X$					
$\beta_0(X)$	1	1	1	1	2
$\beta_1(X)$	0	1	0	2	2
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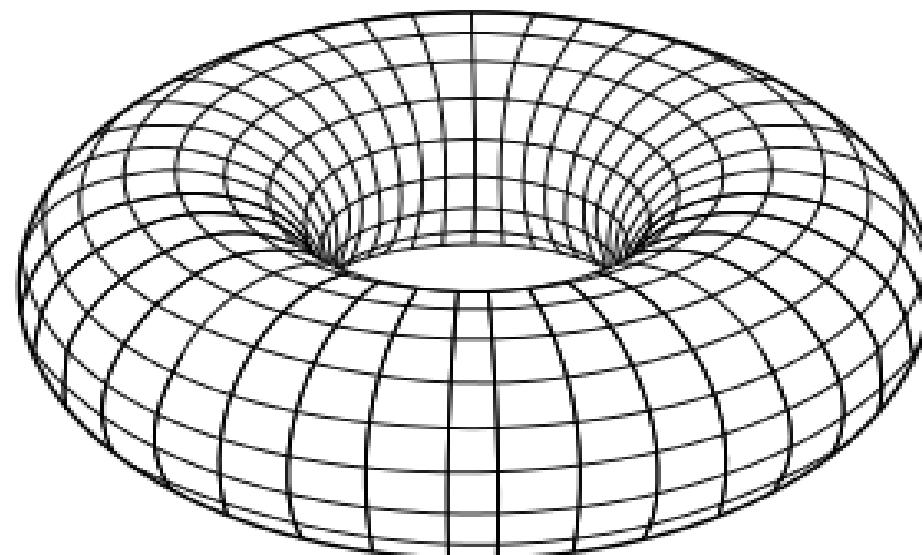
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$\beta_0(X)$	1	1	1	1	2
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- ...

**Example:** Betti numbers of the torus:

$$\beta_0(X) = 1, \quad \beta_1(X) = 2, \quad \beta_2(X) = 1, \quad \beta_3(X) = 0, \quad \dots$$

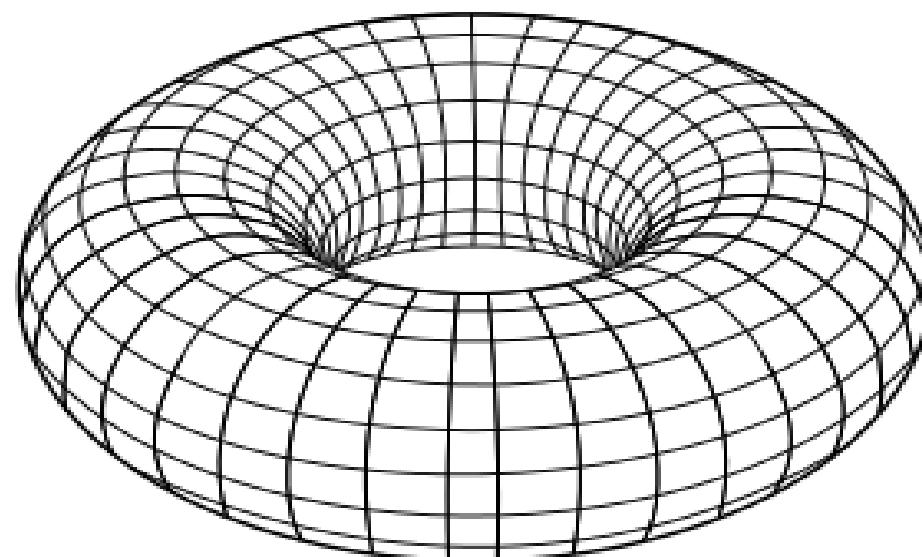


**Interpretation:** We have:

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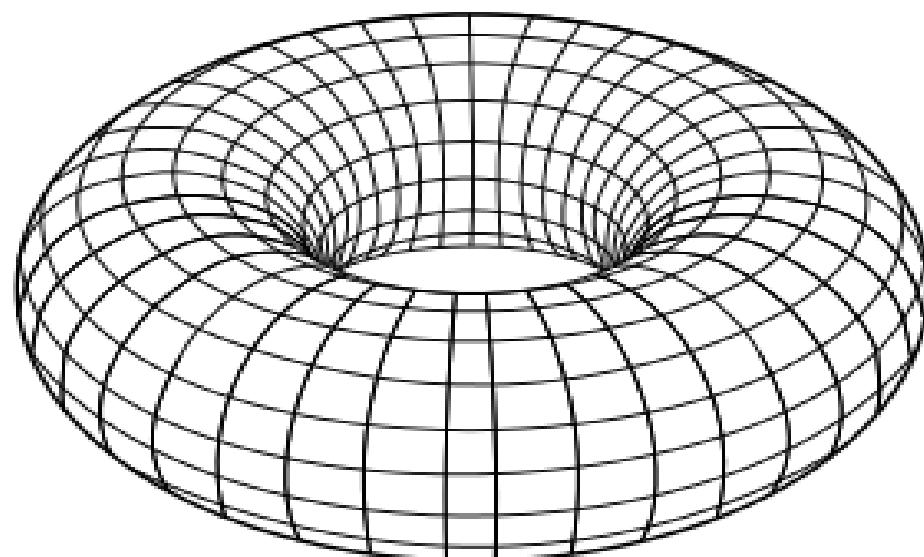


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- $\beta_1(X)$  is the number of 'holes' in  $X$
- $\beta_2(X)$  is the number of 'voids' in  $X$
- ...

**Example:** Betti numbers of the torus:

$$\beta_0(X) = 1, \quad \beta_1(X) = 2, \quad \boxed{\beta_2(X) = 1}, \quad \beta_3(X) = 0, \quad \dots$$

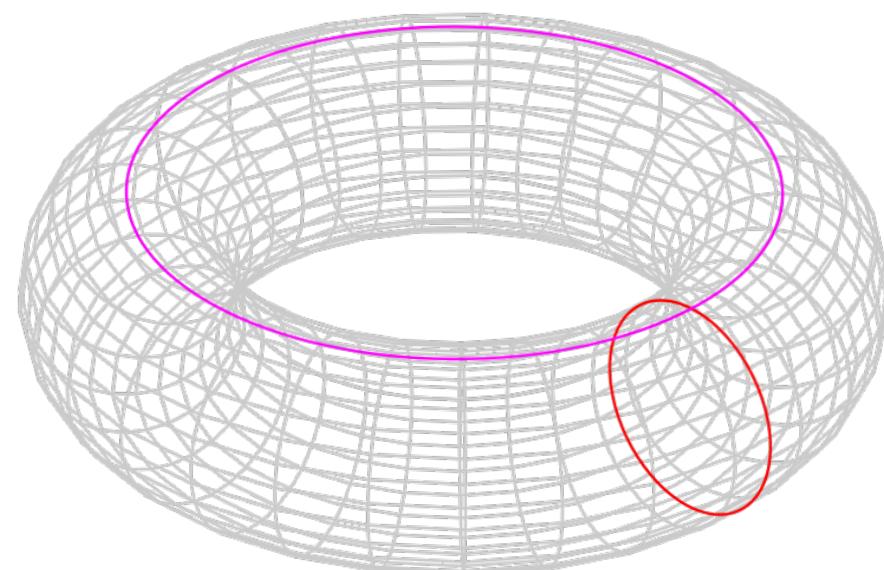


**Interpretation:** We have:

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- $\beta_1(X)$  is the number of 'holes' in  $X$
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**Example:** Betti numbers of the torus:

$$\beta_0(X) = 1, \quad \boxed{\beta_1(X) = 2,} \quad \beta_2(X) = 1, \quad \beta_3(X) = 0, \quad \dots$$



# Propriedade de invariância - na teoria

35/37 (1/2)

**Proposition:** If two spaces  $X$  and  $Y$  are homotopy equivalent, then they have the same Betti numbers.

As a consequence, two spaces with different Betti numbers cannot be homotopy equivalent.

**Example:** The  $n$ -dimensional sphere  $\mathbb{S}^n \subset \mathbb{R}^{n+1}$  has Betti numbers

$$\begin{aligned}\beta_i(X) &= 1 \quad \text{if } i = 0 \text{ or } n, \\ \beta_i(X) &= 0 \quad \text{else.}\end{aligned}$$

Hence, if  $n \neq m$ , then  $\mathbb{S}^n$  and  $\mathbb{S}^m$  are not homotopy equivalent.

# Propriedade de invariância - na teoria 35/37 (2/2)

**Proposition:** If two spaces  $X$  and  $Y$  are homotopy equivalent, then they have the same Betti numbers.

As a consequence, two spaces with different Betti numbers cannot be homotopy equivalent.

**Example (Brouwer's invariance of domain):**

Let us show that  $\mathbb{R}^n$  and  $\mathbb{R}^m$ , with  $n \neq m$ , are not homeomorphic.

Let  $h: \mathbb{R}^n \rightarrow \mathbb{R}^m$  be a homeomorphism.

Choose any  $x \in \mathbb{R}^n$  and consider the restricted map

$$h: \mathbb{R}^n \setminus \{x\} \longrightarrow \mathbb{R}^m \setminus \{h(x)\}$$

It is still a homeomorphism.

But  $\mathbb{R}^n \setminus \{x\}$  is homotopic to the sphere  $\mathbb{S}^{n-1}$ , and  $\mathbb{R}^m \setminus \{x\}$  is homotopic to the sphere  $\mathbb{S}^{m-1}$

We have seen before that  $\mathbb{S}^{n-1}$  and  $\mathbb{S}^{m-1}$  are homotopic if and only if  $m = n$ . This is a contradiction.

# Propriedade de invariância - nas aplicações

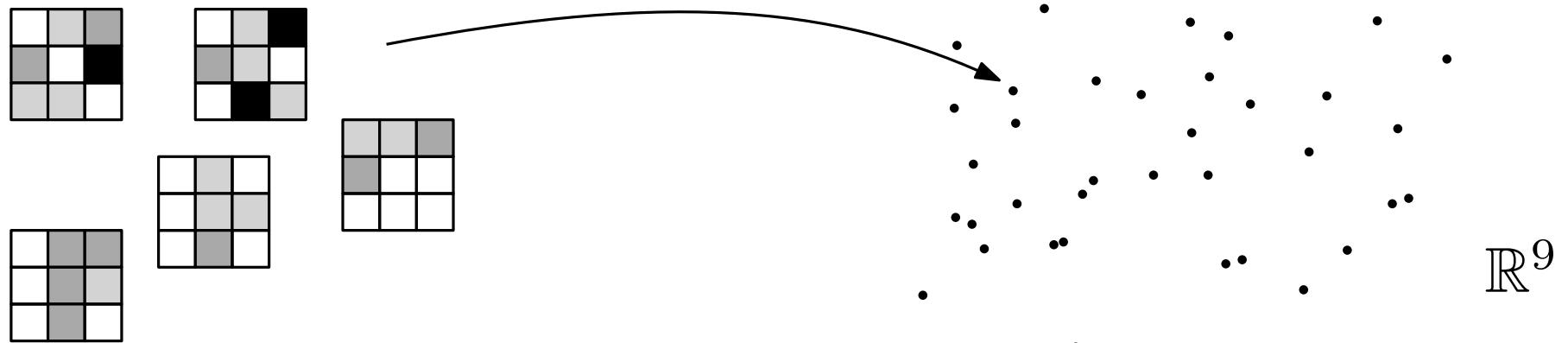
36/37 (1/2)

The Betti numbers contain information about the space we study.

[G. Carlsson, T. Ishkhanov, V. de Silva, and A. Zomorodian, [On the Local Behavior of Spaces of Natural Images](#), 2008.]

From a large collection of natural images, the authors extract  $3 \times 3$  patches.

Since it consists of 9 pixels, each of these patches can be seen as a 9-dimensional vector, and the whole set as a point cloud in  $\mathbb{R}^9$ .



They observe that the point cloud lies close to a shape whose Betti numbers (over  $\mathbb{Z}/2\mathbb{Z}$ ) are

$$\beta_0(X) = 1, \quad \beta_1(X) = 2, \quad \beta_2(X) = 1, \quad \beta_3(X) = 0$$

# Propriedade de invariância - nas aplicações

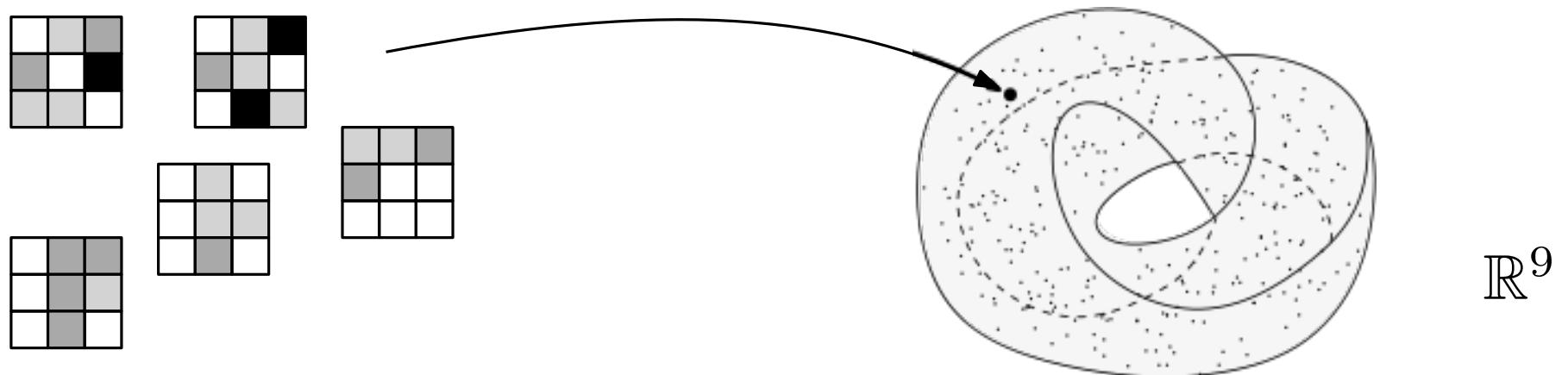
36/37 (2/2)

The Betti numbers contain information about the space we study.

[G. Carlsson, T. Ishkhanov, V. de Silva, and A. Zomorodian, [On the Local Behavior of Spaces of Natural Images](#), 2008.]

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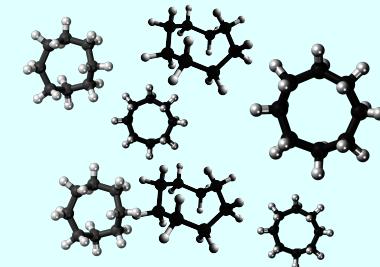
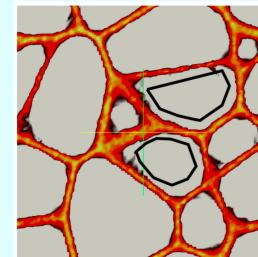
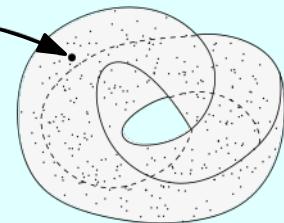
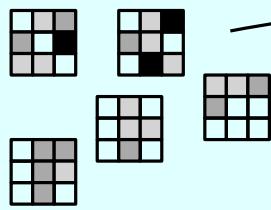
$$\beta_0(X) = 1, \quad \beta_1(X) = 2, \quad \beta_2(X) = 1, \quad \beta_3(X) = 0$$

These are the Betti numbers of a Klein bottle!

(and the authors actually show that the dataset concentrates near a Klein bottle embedded in  $\mathbb{R}^9$ .)

# Conclusão

We can find interesting topology in datasets.



**Invariants of homotopy classes** allow to describe and understand them.

$$\beta_0(X) = 1, \quad \beta_1(X) = 2, \quad \beta_2(X) = 1$$

Thursday 28th: a stronger invariant, **homology**.

Tuesday 3rd: how to compute these invariants in practice? **persistent homology**.

Thursday 5th: **python tutorial** with the gudhi library.

A course about TDA: <https://raphaeltinarrage.github.io/EMAp.html>