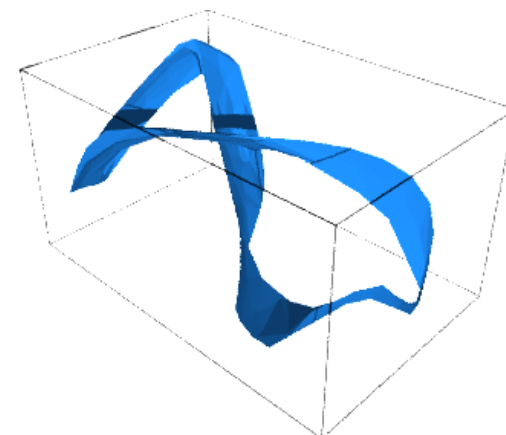
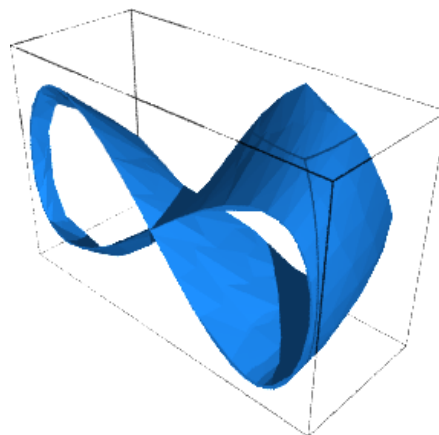
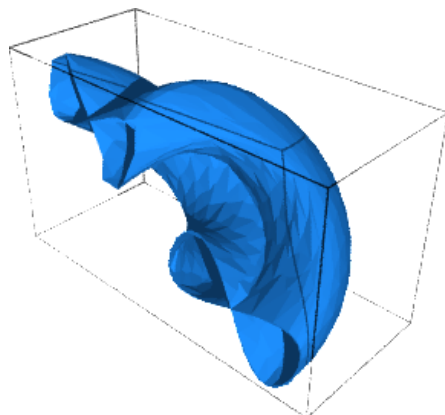
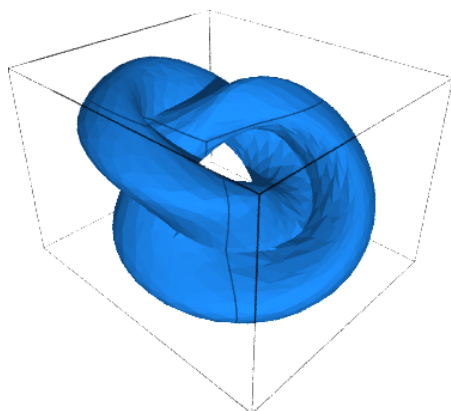


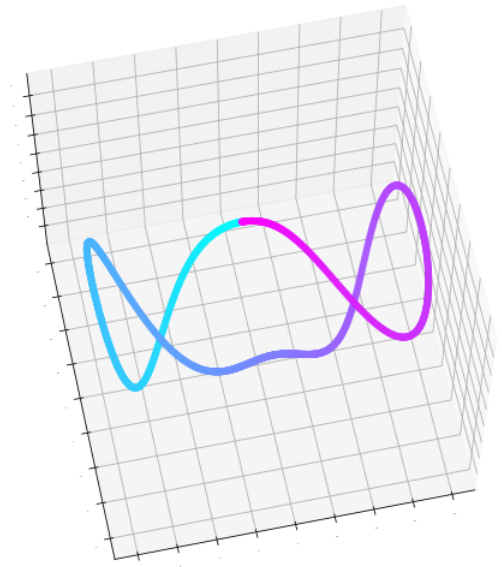
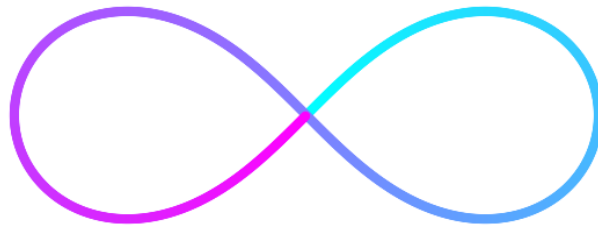
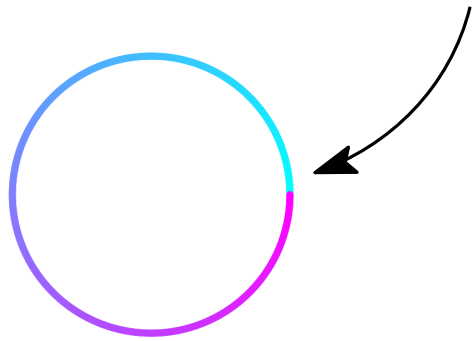
# Recovering the homology of immersed manifolds

Raphaël Tinarrage

*[arxiv.org/abs/1912.03033](https://arxiv.org/abs/1912.03033)*



embedded manifold

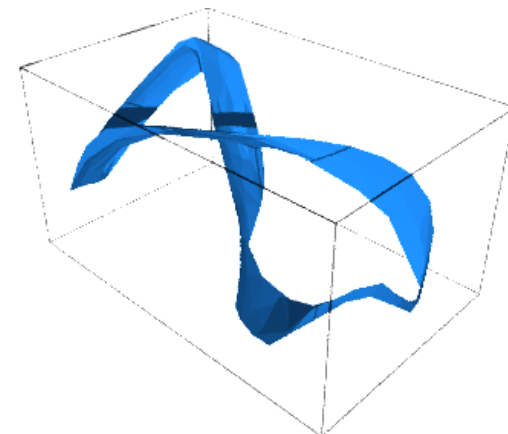
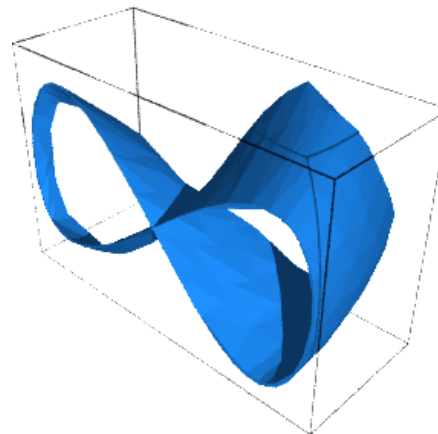
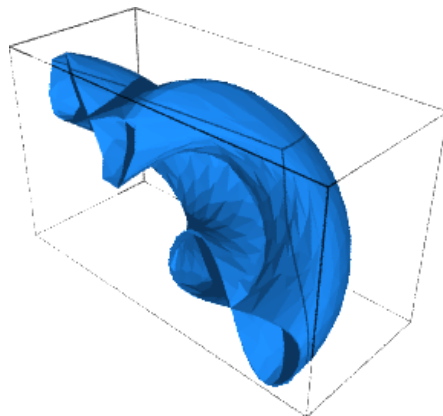
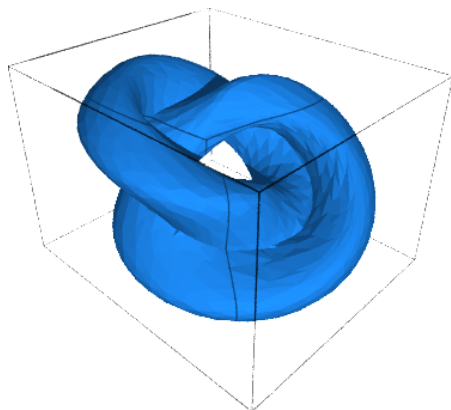


## Recovering the homology of immersed manifolds

Raphaël Tinarrage

(may self-intersect)

[arxiv.org/abs/1912.03033](https://arxiv.org/abs/1912.03033)



# Statement of the problem

We are observing an immersed manifold  $\mathcal{M} \subset \mathbb{R}^n$ .

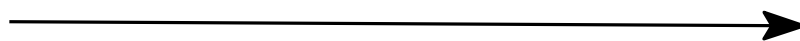
Abstract manifold

Immersion

Immersed manifold

$\mathcal{M}_0$

$u$



$\mathcal{M} = u(\mathcal{M}_0) \subset \mathbb{R}^n$

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Abstract manifold

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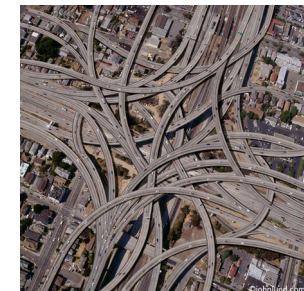
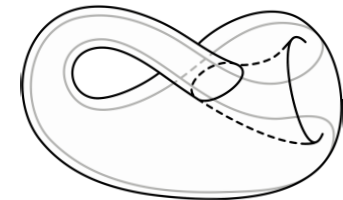
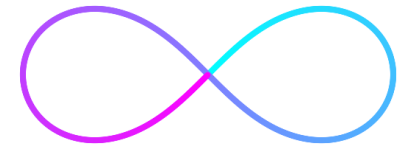
$\mathcal{M}_0$

$u$

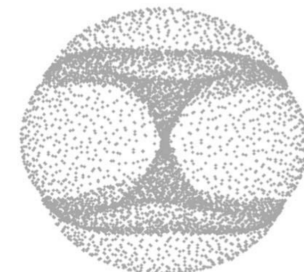
$\mathcal{M} = u(\mathcal{M}_0) \subset \mathbb{R}^n$



Klein bottle



Klein bottle  $\cup$  sphere



# Statement of the problem

We are observing an immersed manifold  $\mathcal{M} \subset \mathbb{R}^n$ .

Abstract manifold

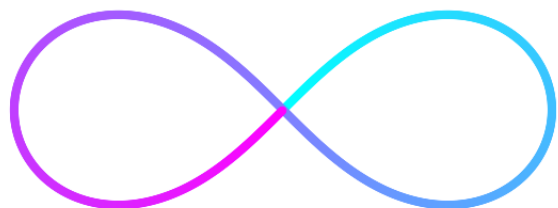
Immersion

Immersed manifold

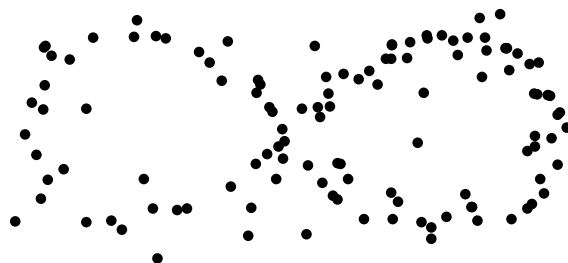
$$\mathcal{M}_0 \xrightarrow{u} \mathcal{M} = u(\mathcal{M}_0) \subset \mathbb{R}^n$$

**Question 1:** Given  $\mathcal{M}$ , compute the (singular) homology groups of  $\mathcal{M}_0$ .

**Question 2:** Given  $X \subset \mathbb{R}^n$  close to  $\mathcal{M}$ , compute the homology groups of  $\mathcal{M}_0$ .



$\mathcal{M}$



$X$

$$H_0 = \mathbb{Z}/2\mathbb{Z}$$

$$H_1 = \mathbb{Z}/2\mathbb{Z}$$

# Statement of the problem

We are observing an immersed manifold  $\mathcal{M} \subset \mathbb{R}^n$ .

Abstract manifold

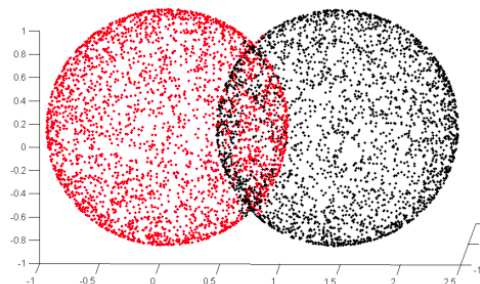
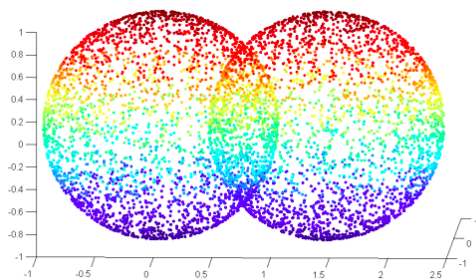
Immersion

Immersed manifold

$$\mathcal{M}_0 \xrightarrow{u} \mathcal{M} = u(\mathcal{M}_0) \subset \mathbb{R}^n$$

## A bit of context

- [Arias-Castro, Ery, Gilad Lerman and Teng Zhang. Spectral clustering based on local PCA.]

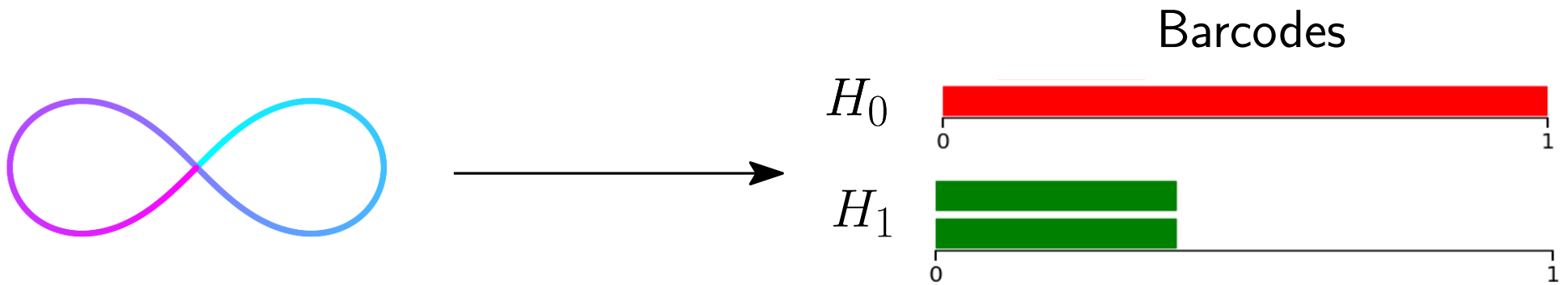


- [Memoli, Smith and Wan. The Wasserstein transform.]
- [Díaz Martínez, Mémoli and Mio. The shape of data and probability measures.]

## Our method

We will use persistent homology.

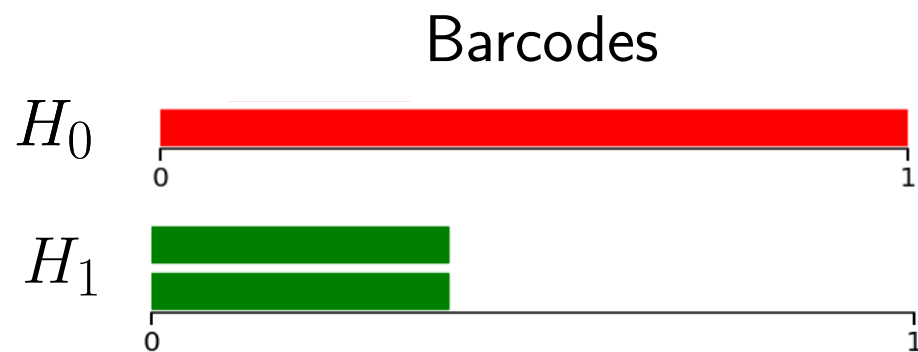
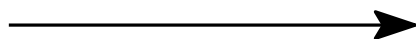
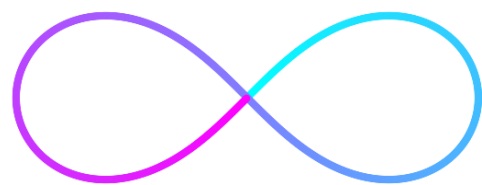
Unfortunately, the persistent homology of the Čech filtration of  $\mathcal{M}$  does not reveal the homology of  $\mathcal{M}_0$ .



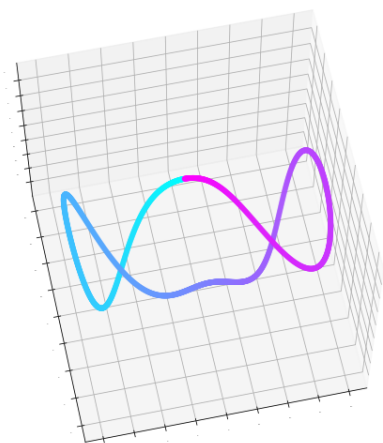
## Our method

We will use persistent homology.

Unfortunately, the persistent homology of the Čech filtration of  $\mathcal{M}$  does not reveal the homology of  $\mathcal{M}_0$ .



We will try to lift  $\mathcal{M}$  in a higher dimensional space, where the Čech filtration reveals a circle.





## Our method

How to lift  $\mathcal{M}$ ?

$$\mathcal{M}_0 \xrightarrow{u} \mathcal{M} \subset \mathbb{R}^n$$

$$x_0 \mapsto u(x_0)$$

$$\mathcal{M}_0 \xrightarrow{\check{u}} \check{\mathcal{M}} \subset \mathbb{R}^n \times \mathbb{R}^m$$

$$x_0 \mapsto (u(x_0), \textcolor{red}{f}(x_0))$$

Choose  $f$  such that  $\check{u}$  is an embedding.

# Our method

How to lift  $\mathcal{M}$ ?

$$\begin{array}{ccc} \mathcal{M}_0 & \xrightarrow{u} & \mathcal{M} \subset \mathbb{R}^n \\ x_0 & \mapsto & u(x_0) \\ \mathcal{M}_0 & \xrightarrow{\check{u}} & \check{\mathcal{M}} \subset \mathbb{R}^n \times \mathbb{R}^m \\ x_0 & \mapsto & (u(x_0), f(x_0)) \end{array}$$

lifted manifold  
lift space

Choose  $f$  such that  $\check{u}$  is an embedding.

Our choice is

$$f: x_0 \mapsto T_{x_0} \mathcal{M}_0$$

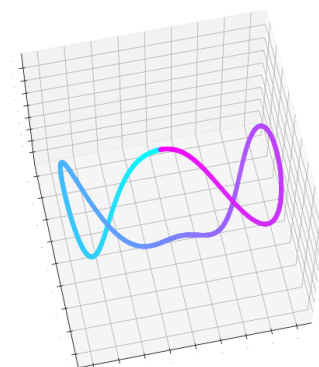
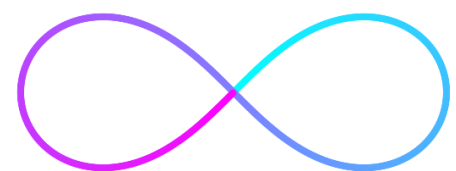
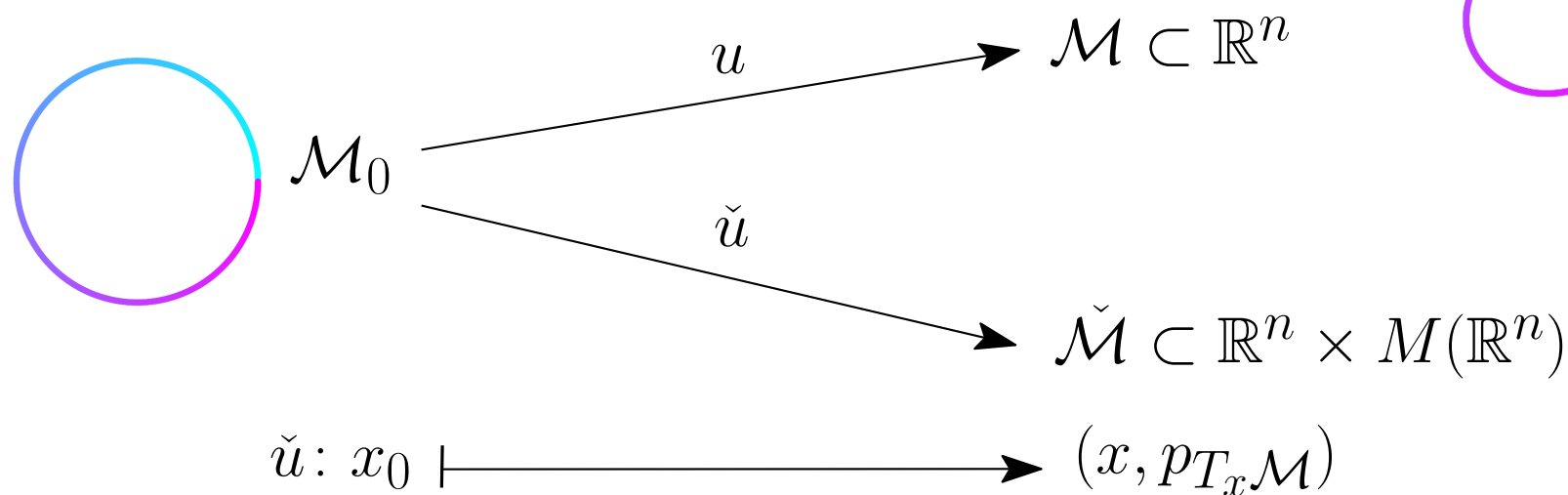
(tangent space of  $\mathcal{M}_0$  at  $x_0$ )

- $\check{u}$  is an embedding under a reasonable assumption
- we are actually estimating the tangent bundle of  $\mathcal{M}_0$   
[T., Computing Stiefel-Whitney classes of line bundles]

# Our method

## Notations:

- $u: \mathcal{M}_0 \rightarrow \mathcal{M} \subset \mathbb{R}^n$  is an immersion
- For  $x_0 \in \mathcal{M}_0$ ,  $x = u(x_0)$
- For  $x_0 \in \mathcal{M}_0$ ,  $T_x \mathcal{M}$  denotes the tangent space of  $\mathcal{M}_0$  seen in  $\mathbb{R}^n$
- $M(\mathbb{R}^n)$  denotes the space of  $n \times n$  matrices
- $p_{T_x \mathcal{M}} \in M(\mathbb{R}^n)$  denotes the orthogonal projection matrix on  $T_x \mathcal{M}$
- *Lift space*:  $\mathbb{R}^n \times M(\mathbb{R}^n)$
- *Lifted manifold*:  $\check{\mathcal{M}} = \{(x, p_{T_x \mathcal{M}}), x_0 \in \mathcal{M}_0\} \subset \mathbb{R}^n \times M(\mathbb{R}^n)$
- *Lifting map*:  $\check{u}: \mathcal{M}_0 \rightarrow \check{\mathcal{M}}$



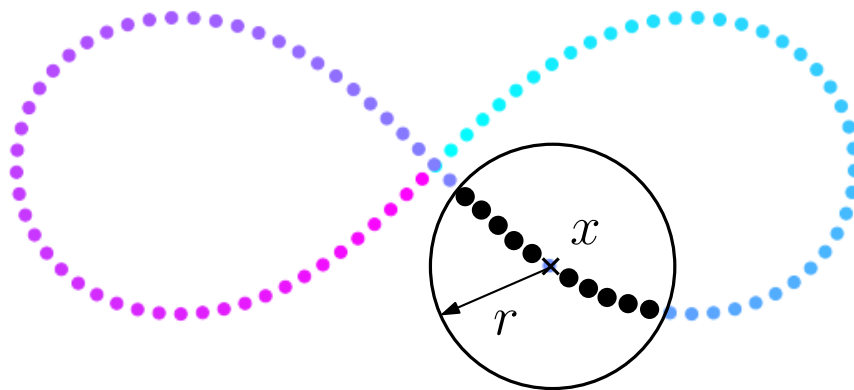
(PCA dimension reduction)

## Recipe in practice

- We observe a point cloud  $X \subset \mathbb{R}^n$  close to  $\mathcal{M}$ .
- Let  $r > 0$  be a parameter.  
For every  $x \in X$ , compute a *local covariance matrix*

$$\Sigma_X(x, r) = \frac{1}{|A|} \sum_{y \in A} (x - y)^{\otimes 2} \in M(\mathbb{R}^n)$$

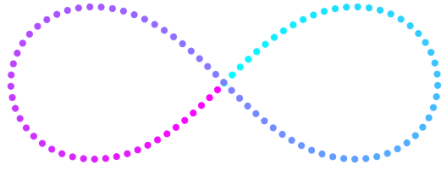
where  $A = \{y \in X, \|x - y\| \leq r\}$ .



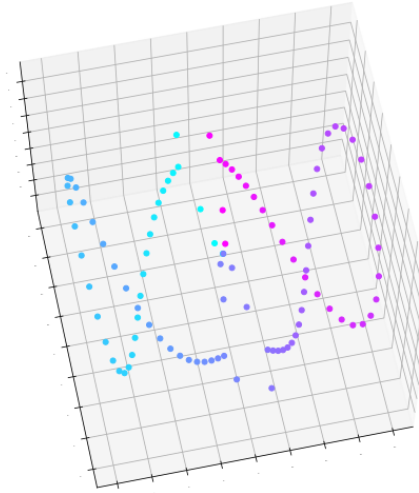
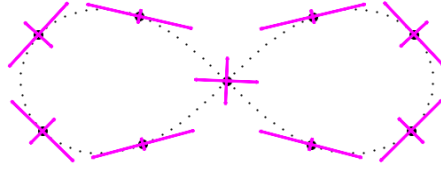
- Consider the set

$$\check{X} = \{(x, \Sigma_X(x, r)), x \in X\} \subset \mathbb{R}^n \times M(\mathbb{R}^n).$$

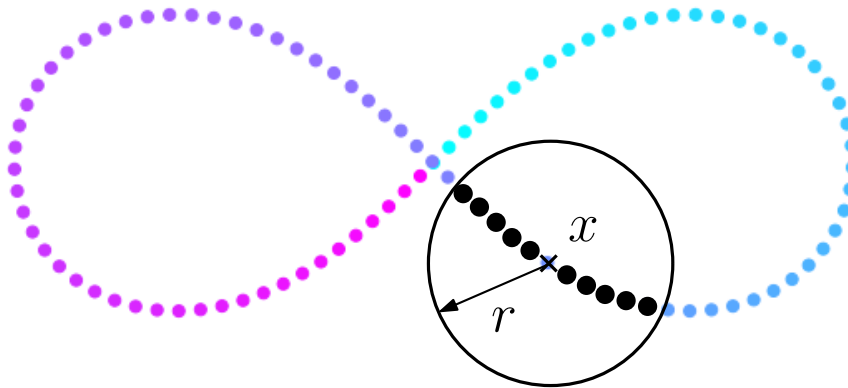
# Recipe in practice



$X$



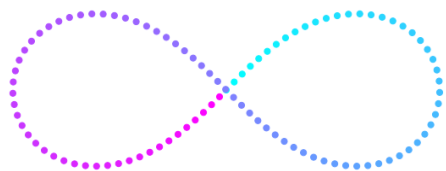
$\check{X}$



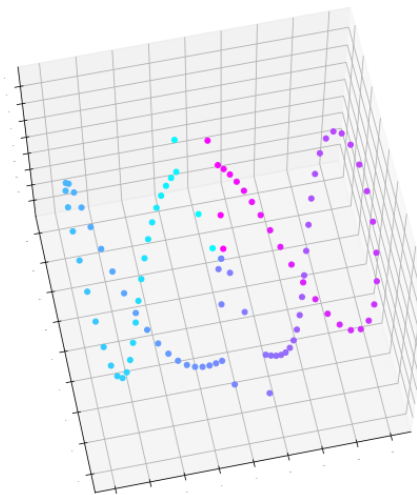
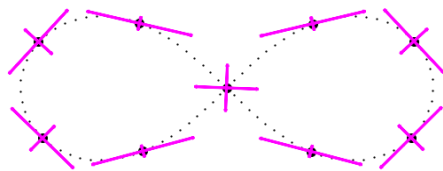
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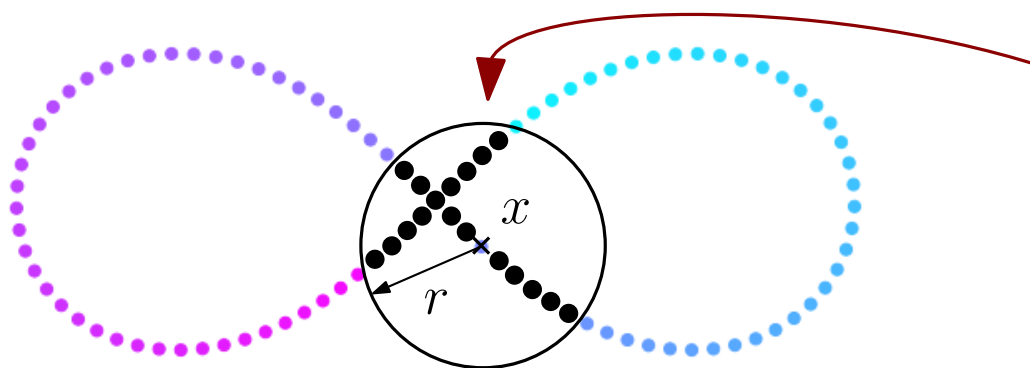
# Recipe in practice



$X$



$\check{X}$

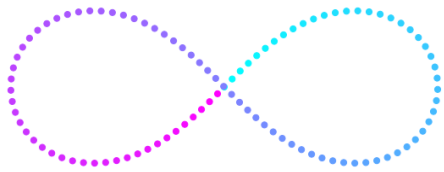


bad estimation of  
tangent space

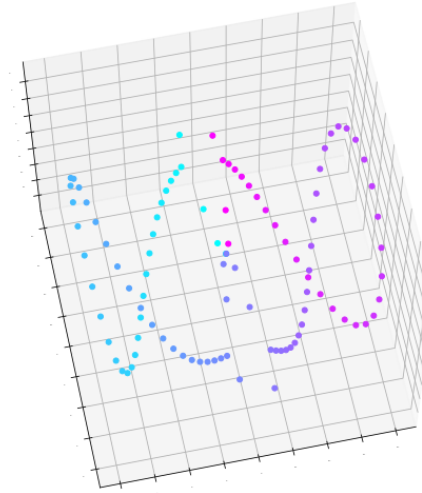
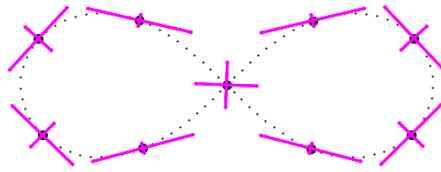
- Consider the set

$$\check{X} = \{(x, \Sigma_X(x, r)), x \in X\} \subset \mathbb{R}^n \times M(\mathbb{R}^n).$$

# Recipe (that does not work) in practice



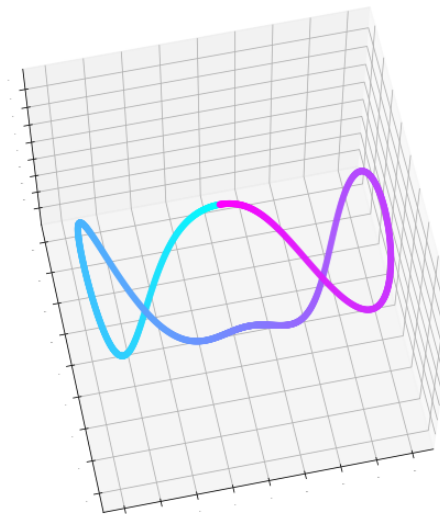
$X$



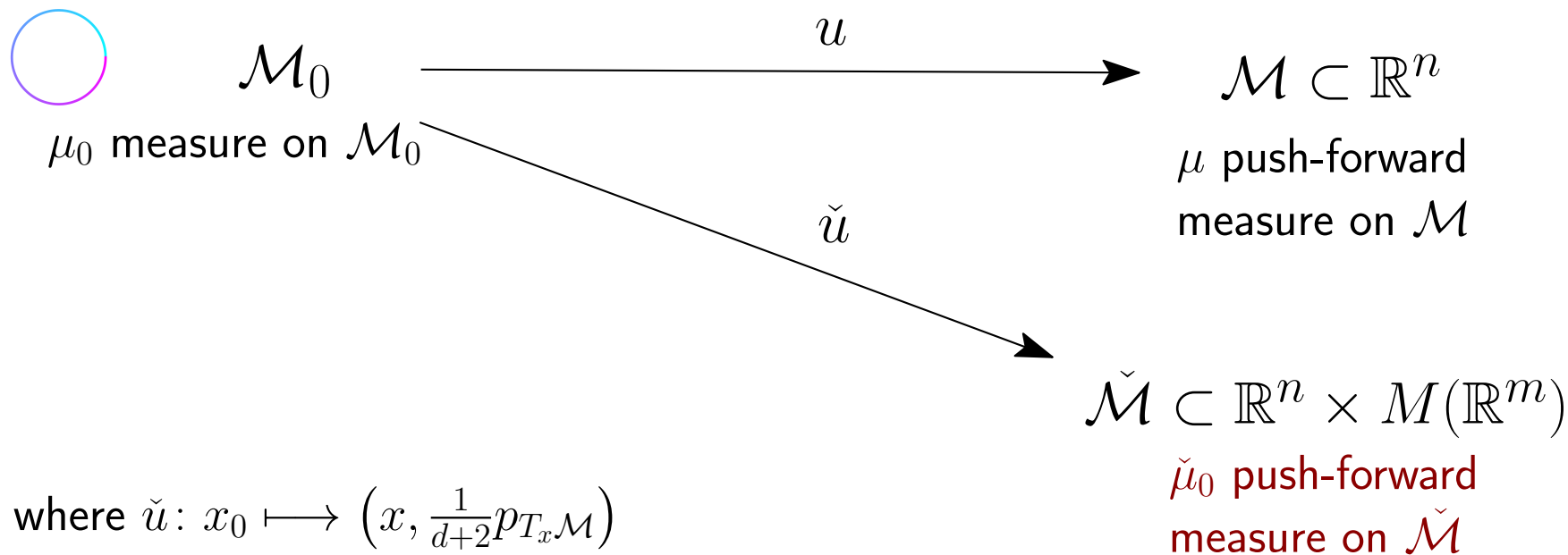
$$\check{X} = \{(x, \Sigma_X(x, r)), x \in \mathcal{M}\}$$

$$\check{\mathcal{M}} = \{(x, p_{T_x \mathcal{M}}), x_0 \in \mathcal{M}_0\}$$

$\check{\mathcal{M}}$  and  $\check{X}$  are not close in Hausdorff distance :(



# A measure-theoretic setting

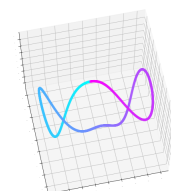
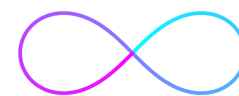
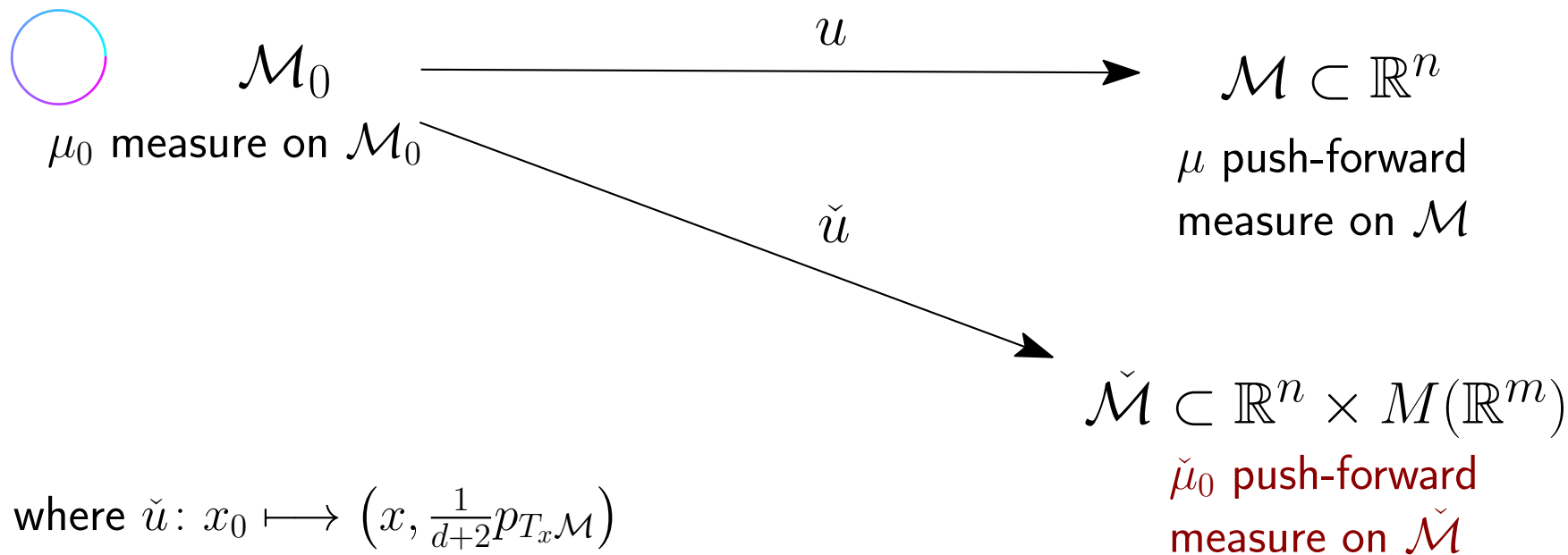


$\check{\mu}_0$  can be defined as follows: for every test function  $\phi: \mathbb{R}^n \times M(\mathbb{R}^n) \rightarrow \mathbb{R}$ ,

$$\int \phi(x, A) \cdot d\check{\mu}_0(x, A) = \int \phi\left(x, \frac{1}{d+2} p_{T_x \mathcal{M}}\right) \cdot d\mu_0(x_0).$$



# A measure-theoretic setting



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Now, we are observing a measure  $\nu$  close to  $\mu$

Define  $\check{\nu}$  as follows: for every test function  $\phi: \mathbb{R}^n \times M(\mathbb{R}^n) \rightarrow \mathbb{R}$ ,

$$\int \phi(x, A) \cdot d\check{\nu}(x, A) = \int \phi\left(x, \frac{1}{r^2}\Sigma_\nu(x, r)\right) \cdot d\nu(x),$$

where  $\Sigma_\nu(x, r)$  is the local covariance matrix.

# A measure-theoretic setting

## Theorem:

Let  $r > 0$ . Suppose that  $W_1(\mu, \nu)$  is small enough. Under several assumptions on  $\mathcal{M}_0$  and  $\mu_0$ , we have

$$W_p(\check{\nu}, \check{\mu}_0) \leq \text{constant} \cdot r^{\frac{1}{p}}$$

where  $W_p$  denote the  $p$ -Wasserstein distance.

$\check{\mu}_0$  can be defined as follows: for every test function  $\phi: \mathbb{R}^n \times M(\mathbb{R}^n) \rightarrow \mathbb{R}$ ,

$$\int \phi(x, A) \cdot d\check{\mu}_0(x, A) = \int \phi\left(x, \frac{1}{d+2} p_{T_x \mathcal{M}}\right) \cdot d\mu_0(x_0).$$

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Define  $\check{\nu}$  as follows: for every test function  $\phi: \mathbb{R}^n \times M(\mathbb{R}^n) \rightarrow \mathbb{R}$ ,

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where  $\Sigma_\nu(x, r)$  is the local covariance matrix.

# Persistent homology for measures

[Anai, Chazal, Glisse, Ike, Inakoshi, T., Umeda. DTM-based filtrations]

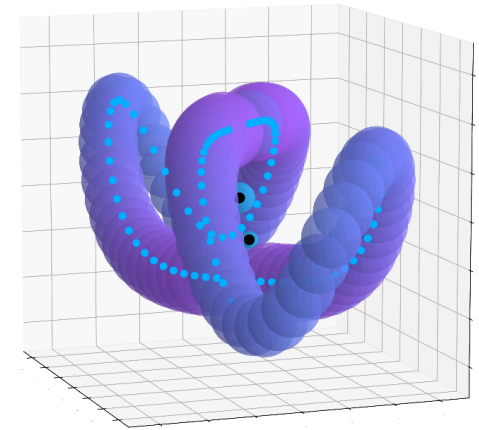
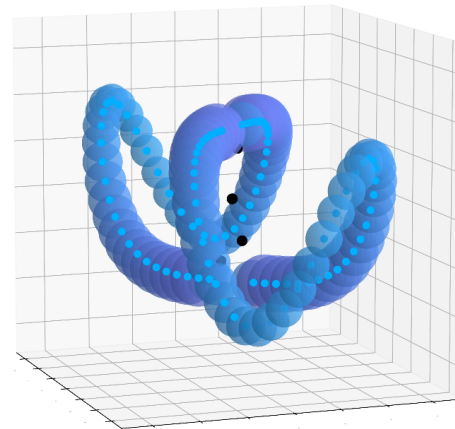
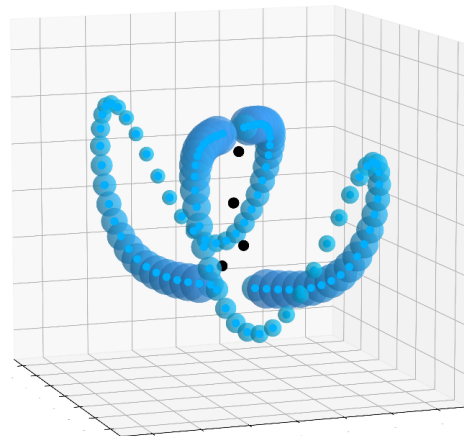
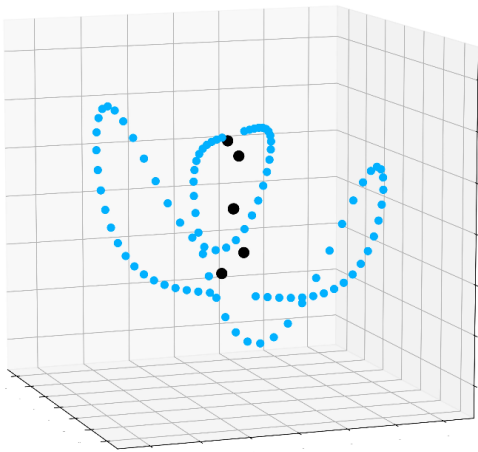
- Usual Čech filtration: with  $X \subset \mathbb{R}^k$ ,

$$X^t = \bigcup_{x \in X} \overline{B}(x, t)$$

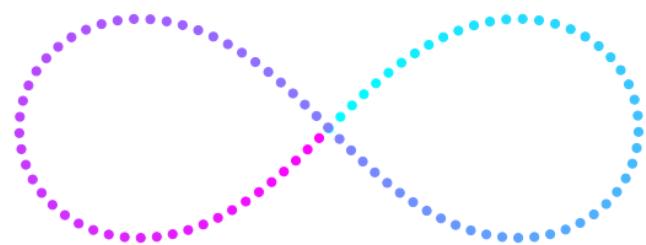
- DTM-filtration: with  $\mu$  measure on  $\mathbb{R}^k$ ,

$$V^t = \bigcup_{x \in \text{supp}(\mu)} \overline{B}(x, t - d_\mu(x))$$

where  $d_\mu$  is the distance-to-measure (DTM) associated to  $\mu$

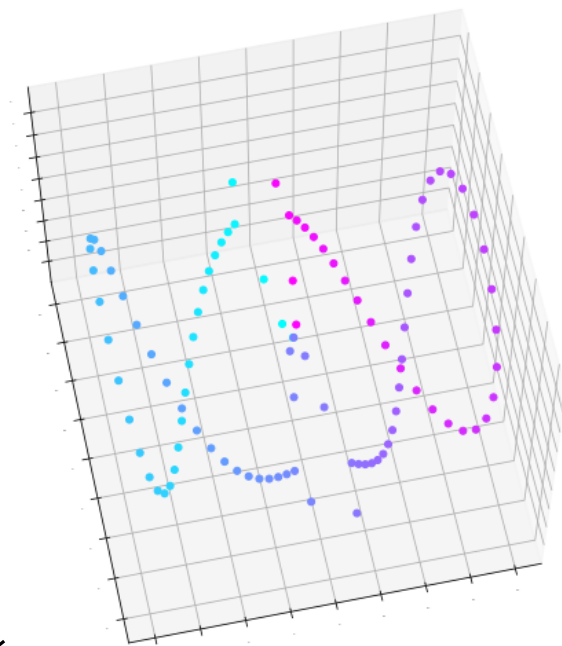


# Persistent homology for measures

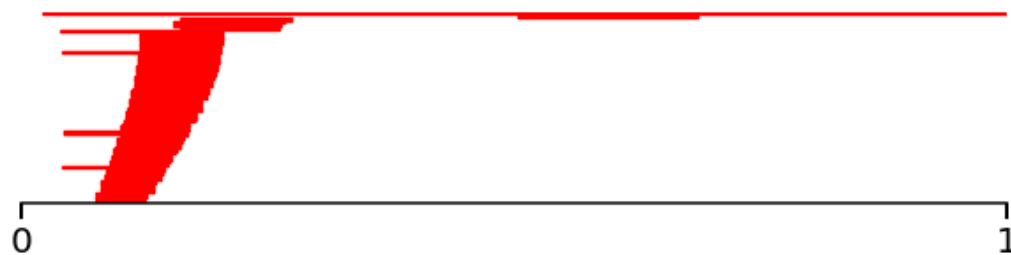


observation  $X \subset \mathbb{R}^2$

lift in  $\mathbb{R}^2 \times M(\mathbb{R}^2)$



$H_0$

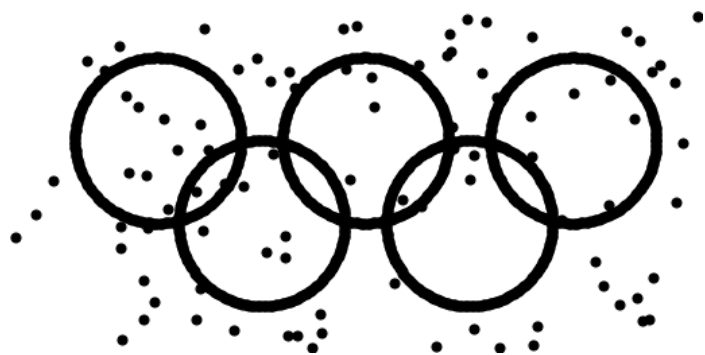


$H_1$



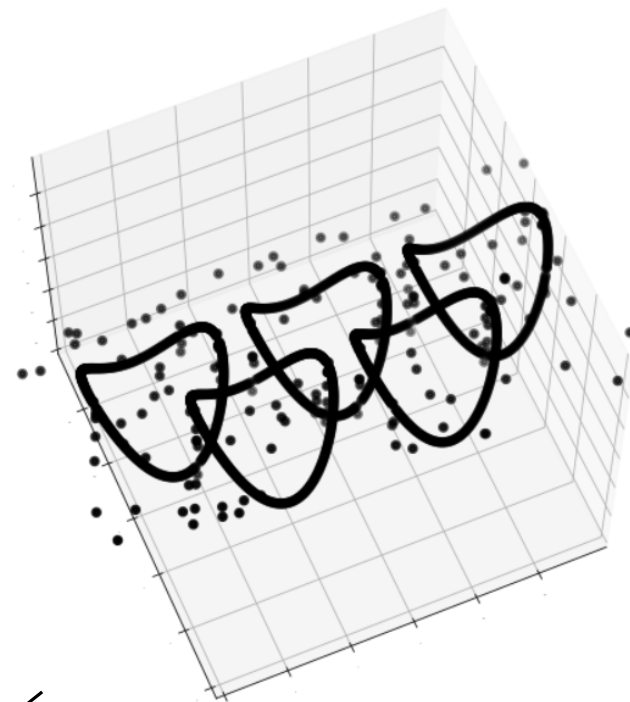
DTM-filtration

# A last illustration



observation  $X \subset \mathbb{R}^2$

lift in  $\mathbb{R}^6$



$H_0$



$H_1$



measure-based  
filtrations