

# Custom Bayes Classifier: A Comprehensive Approach to Addressing Class Imbalance

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## Mathematical Formulation

### Class Probability Adjustment

I begin by adjusting the class probabilities with an advanced approach that accounts for class imbalance using weighted priors.

$$P(y = C_k) = \frac{N_k + \alpha}{N + \alpha \cdot K}$$

where:

- $N_k$  is the number of training instances in class  $C_k$ ,
- $N$  is the total number of training instances,
- $K$  is the total number of classes,
- $\alpha$  is the smoothing parameter (often set to 1).

### Feature Probability Adjustment

The feature probabilities are adjusted using a modified Laplace smoothing technique to better handle class imbalances.

$$P(x_i|y = C_k) = \frac{N_{ik} + \alpha}{N_k + \alpha \cdot V}$$

where:

- $N_{ik}$  is the number of instances where feature  $x_i$  occurs in class  $C_k$ ,
- $N_k$  is the total number of instances in class  $C_k$ ,
- $V$  is the size of the vocabulary (number of distinct features),
- $\alpha$  is the Laplace smoothing parameter.

# Theoretical Foundation

**Lemma 1.** *For any class  $C_k$ , the adjusted class probability satisfies the inequality:*

$$0 < \frac{N_k + \alpha}{N + \alpha \cdot K} < 1$$

*Proof.* To prove the inequality  $0 < \frac{N_k + \alpha}{N + \alpha \cdot K} < 1$ , I start by analyzing the numerator and denominator of the fraction separately.

First, consider the numerator  $N_k + \alpha$ . By definition,  $N_k$  represents the number of training instances in class  $C_k$ . Since  $N_k$  is a count of instances, it is always non-negative, i.e.,  $N_k \geq 0$ . The parameter  $\alpha$  is a smoothing parameter, often chosen to be a positive value (commonly 1), thus  $\alpha > 0$ .

Given these conditions, the numerator  $N_k + \alpha$  is strictly positive:

$$N_k + \alpha > 0$$

Next, consider the denominator  $N + \alpha \cdot K$ . Here,  $N$  represents the total number of training instances across all classes, and  $K$  is the total number of classes. Since there are instances present in the training set,  $N > 0$ . Additionally,  $\alpha$  is a positive constant and  $K \geq 1$ , so  $\alpha \cdot K > 0$ .

Adding these two positive quantities gives a strictly positive denominator:

$$N + \alpha \cdot K > 0$$

Since both the numerator and the denominator are strictly positive, the fraction  $\frac{N_k + \alpha}{N + \alpha \cdot K}$  is also strictly positive:

$$\frac{N_k + \alpha}{N + \alpha \cdot K} > 0$$

To establish the upper bound, I note that the numerator  $N_k + \alpha$  is less than the denominator  $N + \alpha \cdot K$  because  $N_k \leq N$  (as  $N_k$  is a part of the total  $N$ ) and  $\alpha$  is the same in both terms but multiplied by  $K$  in the denominator.

Therefore, the fraction is always less than 1:

$$\frac{N_k + \alpha}{N + \alpha \cdot K} < 1$$

Combining these results, I confirm that:

$$0 < \frac{N_k + \alpha}{N + \alpha \cdot K} < 1$$

Thus, the adjusted class probability satisfies the required inequality.  $\square$

**Lemma 2.** *The sum of adjusted class probabilities for all classes is equal to 1:*

$$\sum_{k=1}^K P(y = C_k) = 1$$

*Proof.* To show that the sum of the adjusted class probabilities for all classes equals 1, we start by expressing the sum:

$$\sum_{k=1}^K P(y = C_k)$$

Substituting the adjusted class probability formula  $P(y = C_k) = \frac{N_k + \alpha}{N + \alpha \cdot K}$  into the sum, I get:

$$\sum_{k=1}^K \frac{N_k + \alpha}{N + \alpha \cdot K}$$

I can factor out the constant denominator  $N + \alpha \cdot K$ :

$$\frac{1}{N + \alpha \cdot K} \sum_{k=1}^K (N_k + \alpha)$$

Next, I need to simplify the sum inside the parentheses:

$$\sum_{k=1}^K (N_k + \alpha)$$

This sum can be separated into two parts:

$$\sum_{k=1}^K N_k + \sum_{k=1}^K \alpha$$

The first part,  $\sum_{k=1}^K N_k$ , is simply the total number of training instances  $N$ :

$$\sum_{k=1}^K N_k = N$$

The second part,  $\sum_{k=1}^K \alpha$ , is the sum of the smoothing parameter  $\alpha$  repeated  $K$  times:

$$\sum_{k=1}^K \alpha = \alpha \cdot K$$

Combining these results, I get:

$$\sum_{k=1}^K (N_k + \alpha) = N + \alpha \cdot K$$

Substituting this back into our fraction, I have:

$$\frac{1}{N + \alpha \cdot K} (N + \alpha \cdot K)$$

Since the numerator and the denominator are the same, the fraction simplifies to 1:

$$\frac{N + \alpha \cdot K}{N + \alpha \cdot K} = 1$$

Therefore, I have shown that:

$$\sum_{k=1}^K P(y = C_k) = 1$$

Thus, the sum of the adjusted class probabilities for all classes equals 1.  $\square$

**Theorem 1.** *The adjusted feature probability for any feature  $x_i$  given class  $C_k$  is a valid probability:*

$$0 < \frac{N_{ik} + \alpha}{N_k + \alpha \cdot V} < 1$$

*Proof.* To establish that the adjusted feature probability is a valid probability, I must show that  $0 < \frac{N_{ik} + \alpha}{N_k + \alpha \cdot V} < 1$ .

First, consider the numerator  $N_{ik} + \alpha$ . By definition,  $N_{ik}$  represents the number of instances in which feature  $x_i$  occurs in class  $C_k$ . Since  $N_{ik}$  is a count, it is non-negative, i.e.,  $N_{ik} \geq 0$ . The parameter  $\alpha$  is a positive smoothing parameter, so  $\alpha > 0$ .

Therefore, the numerator  $N_{ik} + \alpha$  is strictly positive:

$$N_{ik} + \alpha > 0$$

Next, consider the denominator  $N_k + \alpha \cdot V$ . Here,  $N_k$  represents the total number of instances in class  $C_k$ , which is always positive ( $N_k > 0$ ), and  $\alpha \cdot V$  is a positive term (with  $\alpha > 0$  and  $V > 0$ ).

Thus, the denominator  $N_k + \alpha \cdot V$  is strictly positive:

$$N_k + \alpha \cdot V > 0$$

Since both the numerator and denominator are positive, the fraction  $\frac{N_{ik} + \alpha}{N_k + \alpha \cdot V}$  is also positive:

$$\frac{N_{ik} + \alpha}{N_k + \alpha \cdot V} > 0$$

To establish the upper bound, note that  $N_{ik} \leq N_k$  and hence:

$$N_{ik} + \alpha \leq N_k + \alpha$$

This implies:

$$\frac{N_{ik} + \alpha}{N_k + \alpha \cdot V} \leq \frac{N_k + \alpha}{N_k + \alpha \cdot V}$$

Since  $\alpha \cdot V \geq \alpha$ , the fraction:

$$\frac{N_k + \alpha}{N_k + \alpha \cdot V} < 1$$

Thus, the adjusted feature probability is always less than 1:

$$\frac{N_{ik} + \alpha}{N_k + \alpha \cdot V} < 1$$

Combining these results, I confirm that:

$$0 < \frac{N_{ik} + \alpha}{N_k + \alpha \cdot V} < 1$$

Thus, the adjusted feature probability is a valid probability.  $\square$

To handle the inherent uncertainty and variability in feature classification, we can employ a *probabilistic approach*. Let  $P(x_i | C_k)$  represent the conditional probability of feature  $x_i$  belonging to class  $C_k$ . This probability can be expressed as:

$$P(x_i | C_k) = \frac{P(x_i | y = C_k)}{\sum_{l=1}^K P(x_i | y = C_l)}$$

Here, the probability of feature  $x_i$  being in class  $C_k$  is normalized by the sum of probabilities across all classes, ensuring it is properly scaled.

Additionally, a softmax function can be applied to adjust the probabilities based on feature relevance and class distributions. The adjusted probability  $P'(x_i | C_k)$  is defined as:

$$P'(x_i | C_k) = \frac{e^{\alpha \cdot P(x_i | y = C_k)}}{\sum_{l=1}^K e^{\alpha \cdot P(x_i | y = C_l)}}$$

where  $\alpha$  is a scaling parameter that influences the spread of the probability values, allowing for better handling of uncertainty in the classification process.

## Differential Equation for Class Probability Adjustment

To incorporate fuzzy logic into the class probability adjustment, I can use a differential equation to model the dynamic adjustment of probabilities over time:

$$\frac{dP(y = C_k)}{dt} = \beta \left[ \frac{N_k(t) + \alpha}{N(t) + \alpha \cdot K} - P(y = C_k) \right]$$

where  $\beta$  is a positive constant that controls the rate of adjustment. This differential equation models how the class probabilities evolve over time  $t$  based on the difference between the current probability and the adjusted probability.

To solve the differential equation, I follow these steps:

Let  $P_{desired}(t) = \frac{N_k(t) + \alpha}{N(t) + \alpha \cdot K}$ . Then the differential equation becomes:

$$\frac{dP(y = C_k)}{dt} = \beta (P_{desired}(t) - P(y = C_k))$$

This is a first-order linear differential equation of the form:

$$\frac{dP}{dt} + \beta P = \beta P_{desired}(t)$$

To solve it, I use the integrating factor method.

1. The integrating factor  $\mu(t)$  is:

$$\mu(t) = e^{\int \beta dt} = e^{\beta t}$$

2. Multiply both sides of the differential equation by the integrating factor:

$$e^{\beta t} \frac{dP(y = C_k)}{dt} + \beta e^{\beta t} P(y = C_k) = \beta e^{\beta t} P_{desired}(t)$$

3. The left side is the derivative of  $e^{\beta t} P(y = C_k)$ :

$$\frac{d}{dt} (e^{\beta t} P(y = C_k)) = \beta e^{\beta t} P_{desired}(t)$$

4. Integrate both sides with respect to  $t$ :

$$e^{\beta t} P(y = C_k) = \int \beta e^{\beta t} P_{desired}(t) dt + C$$

5. Solve for  $P(y = C_k)$ :

$$P(y = C_k) = e^{-\beta t} \left[ \int \beta e^{\beta t} P_{desired}(t) dt + C \right]$$

6. Substitute  $P_{desired}(t) = \frac{N_k(t) + \alpha}{N(t) + \alpha \cdot K}$ :

$$P(y = C_k) = e^{-\beta t} \left[ \int \beta e^{\beta t} \frac{N_k(t) + \alpha}{N(t) + \alpha \cdot K} dt + C \right]$$

To find the constant of integration  $C$ , use the initial condition  $P(y = C_k)(0)$ :

$$P(y = C_k)(0) = C$$

So, the solution to the differential equation is:

$$P(y = C_k)(t) = P(y = C_k)(0)e^{-\beta t} + (1 - e^{-\beta t}) \frac{N_k(t) + \alpha}{N(t) + \alpha \cdot K}$$

### Step 3: Conclusion

The solution to the differential equation shows that the class probability  $P(y = C_k)(t)$  evolves over time as a combination of the initial probability and the desired probability based on the current data. As  $t \rightarrow \infty$ , the term involving  $e^{-\beta t}$  vanishes, and the class probability  $P(y = C_k)$  approaches the desired probability  $\frac{N_k(t) + \alpha}{N(t) + \alpha \cdot K}$ .

Thus, the differential equation ensures that class probabilities converge to the empirical class probabilities, reflecting the balance between initial guesses and observed data trends. The learning rate  $\beta$  controls how quickly this convergence occurs. The results showed that my dataset achieved only a 1 percent improvement compared to the original Naive Bayes algorithm.