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KIM-1 USER MANUAL

KIM-1
MICROCOMPUTER MODULE
USER MANUAL

AUGUST 1976

The information in this manual has been reviewed and is believed to be entirely reliable. However,
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CHAPTER 1

YOUR KIM-1 MICROCOMPUTER MODULE

Congratulations and welcome to the exciting new world of micro-computers! As the owner of a KIM-1 Microcomputer Module, you now have at your disposal a completely operational, fully tested, and very capable digital computer which incorporates the latest in microprocessor technology offered by MOS Technology, Inc. By selecting the KIM-1 module, you have eliminated all of the problems of constructing and debugging a microcomputer system. Your time is now available for learning the operation of the system and beginning immediately to apply it to your specific areas of interest. In fact, if you will follow a few simple procedures

outlined in this manual, you should be able to achieve initial operation of your KIM-1 module within a few minutes after unpacking the shipping container.

Your KIM-1 module has been designed to provide you with a choice of operating features. You may choose to operate the system using only the keyboard and display included as part of the module. Next, you may add a low cost audio cassette tape recorder to allow storage and retrieval of your programs. Also, you may add a serial interfaced teleprinter to the system to provide keyboard commands, hard-copy printing, and paper tape read or punch capability.

At the heart of your KIM-1 system is an MCS 6502 Microprocessor Array operating in conjunction with two MCS 6530 arrays. Each MCS 6530 provides a total of 1024 bytes of Read-only Memory (ROM) , 64 bytes of Random Access Memory (RAM), 15 Input/Output pins, and an Interval Timer. Stored permanently in the ROM's of the MCS 6530 arrays are the monitor and executive programs devised by NOS Technology, Inc. to control the various operating modes of the KIM-1 system.

The KIM-1 system is intended to provide you with a capable micro-computer for use in your "real-world" application. Accordingly, the system includes a full 1024 bytes of RAM to provide data and program storage for your application program. In addition, you are provided with 15 bidirectional input/output pins to allow interface control of your specific application. Finally, one of the interval timers included in the system is available for generation of time base signals required by your application.

Your KIM-1 system comes to you complete with all components mounted and tested as a system. You need not worry about timing signals (we've included a 1MHz crystal oscillator on the module), interface logic or levels between system components, or interface circuitry to peripheral devices. In fact, you need only apply the indicated power supply voltages to the designated pins to achieve full operation of your KIM-1 system.

We recommend that you read all of this manual before applying power to or attempting to operate your KIM-1 module. In the order presented, you will find:

- [Chapter 2](#) - "hints and kinks" to help you achieve initial system operation
- [Chapter 3](#) - a more detailed description of the KIM-1 system hardware and software
- [Chapter 4](#) - operating procedures for all system modes
- [Chapter 5](#) - an example of a typical application program using all of the features of the KIM-1 system.

At some future time, you may find it desirable to expand the KIM-1 system to incorporate more memory, different types of memory, or additional input/output capability. Again, we have tried to make system expansion as simple as possible with all required interface signals brought out to a special connector on the module. Watch for:

[Chapter 6](#) - a guide to system expansion for increasing both memory and input/output capability

Despite our best efforts to provide you with a fully operable and reliable system, you might encounter some difficulties with your KIM-1 module. If so, refer to:

[Chapter 7](#) - some guidance on warranty and service procedures for your KIM-1 module

Following the basic text of this manual, you will find a series of Appendices intended to provide you with detailed information on certain specialized subjects of interest to you in understanding the operation of the KIM-1 system.

Lastly, since this manual cannot presume to provide all of the technical information on the hardware or programming aspects of the MCS 6502 microprocessor array, we are including with your KIM-1 system two additional manuals for your reference. The Hardware Manual defines the various elements of the system, their electrical and interface characteristics, and the basic system architecture and timing. The Programming Manual provides the detailed information required to write effective programs using the MCS 6502 instruction program set.

So much for introductory comments! Now lets get started and see if we can get your KIM-1 Microcomputer Module doing some real work for you.

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CHAPTER 2

GETTING STARTED

This chapter is intended to guide you through the first important steps in achieving initial operation of your KIM-1 Microcomputer Module. We will ask you to perform certain operations without explanation at this time as to why they are being done. In later sections of this manual, full explanations will be offered for every operating procedure.

2.1 PARTS COMPLEMENT

After unpacking the shipping container for your KIM-1, you should

have located the following items:

- 3 Books - KIM-1 Users Manual
Hardware Manual
Programming Manual
- 1 Programming Card
- 1 System Schematic
- 1 KIM-1 Module
- 1 Connector (Already mounted on the Module)
- 1 Hardware Packet
- 1 Warranty Card

You may wish to save the shipping container and packing material should you need to return your KIM-1 module to us at some future date.

2.2 A FEW WORDS OF CAUTION

WARNING

Your KIM-1 module includes a number of MOS integrated circuits. All such circuits include protective devices to prevent damage resulting from inadvertant application of high voltage potentials to the pins of the device. However, normal precautions should be taken to prevent the application of high voltage static discharges to the pins of an MOS device. Immediately before removal of the packing material from your KIM-1 module, you should develop the following precautionary habits:

1. Discharge any static charge build up on your body by touching a ground connection before touching any part of your KIM-1 module. (This precaution is especially important if you are working in a carpeted area)
2. Be certain that soldering irons or test equipment used on the KIM-1 module are properly grounded and not the source of dangerously high voltage levels.

On a different subject, after unpacking your KIM-1 module, you will note the presence of a potentiometer. This adjustment has been set at the factory to insure correct operation of the audio cassette interface circuits. It should never be necessary for you to change the position of this potentiometer. -----

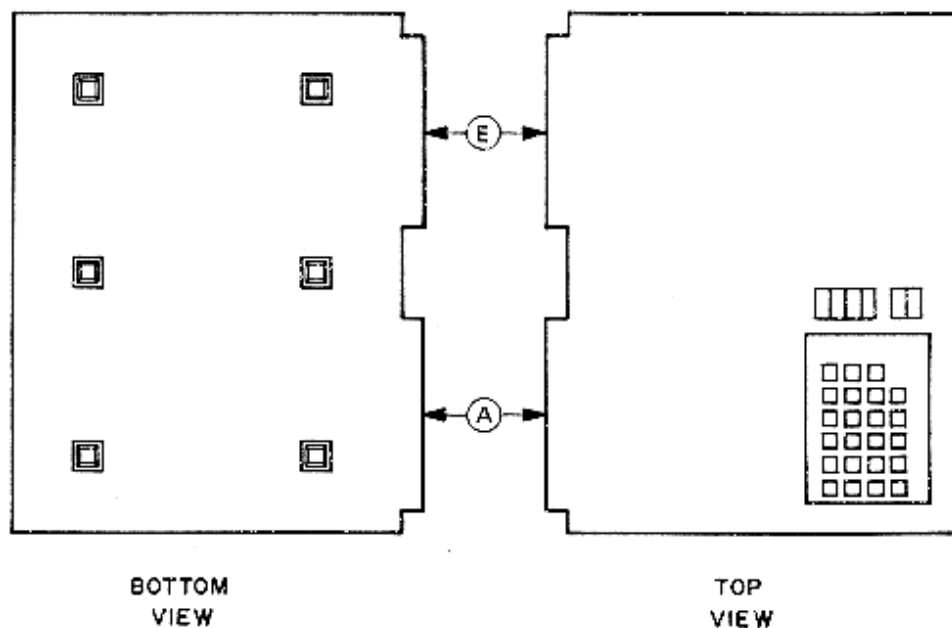
2.3 FIRST STEPS

After unpacking the KIM-1 module, locate the small hardware packet and install the rubber pads provided. The rubber pads are located at the bottom of the module (see attached sketch) and act both to lift the card off your work surface and to provide mechanical support for the module

while you depress keys.

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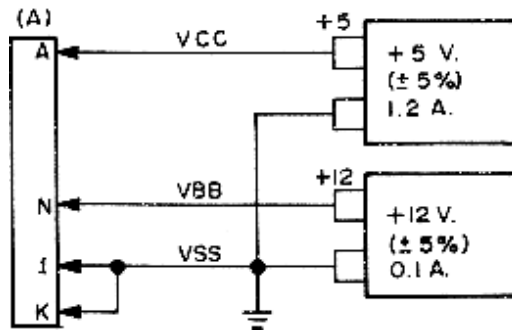
Place the module such that the keyboard is to your lower right and observe that two connector locations extend from the module to your left. The connector area on the lower left is referred to as the Application connector (A). You will note that a 44 pin board edge connector is already installed at this location. The connector area to the upper left is for use by you for future system expansion and is referred to as the Expansion connector (E).



*KIM-1 Module
FIGURE 2.1*

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Remove the (A) connector from the module and connect the pins as shown in the sketch.



Power Supply Connections
FIGURE 2.2

Reinstall the (A) connector making certain that the orientation is correct.

Note 1: The +12 volt power supply is required only if you will be using an audio cassette recorder in your system.

Note 2: The jumper from pin A-K to Vss (Pin A-1) is essential for system operation. If you expand your system later, this jumper will be removed and we'll tell you what to do to pin A-K.

Note 3. If you don't have the proper power supplies already available, you may wish to construct the low cost version shown with schematic and parts list in Appendix D. In any event, your power supply must be regulated to insure correct system operation and must be capable of supplying the required current levels indicated in the sketch.

Now, recheck your connections, turn on your power supplies, and depress [RS] (reset). You should see the LED display digits light as your first check that the system is operational. If not, recheck your hookup or refer to Appendix C (In Case of Trouble).

2.4 LETS TRY A SIMPLE PROGRAM

Assuming that you have completed successfully all of the steps thus far, a simple program now can be tried to demonstrate the operation of the system and increase your confidence that everything works properly. We'll be using only the keyboard and display on the module for this example. (In the next two sections we'll worry about the teleprinter and the audio cassette).

For our first example, we will add two 8 bit binary numbers together and display the result. We presume that you are familiar with the hexadecimal representation of numbers and the general rules for binary arithmetic.

First check and be sure that the slide switch in the upper right

corner of the keyboard is pushed to the left (SST Mode is OFF). Now proceed with the following key sequence:

<u>Press Keys</u>	<u>See On Display</u>	<u>Step #</u>
[AD]	xxxx xx	1
[0] [0] [0] [2]	0002 xx	2
[DA]	0002 xx	3
[1] [8]	0002 18	4
[+] [A] [5]	0003 A5	5
[+] [0] [0]	0004 00	6
[+] [6] [5]	0005 65	7
[+] [0] [1]	0006 01	8
[+] [8] [5]	0007 85	9
[+] [F] [A]	0008 FA	10
[+] [A] [9]	0009 A9	11
[+] [0] [0]	000A 00	12
[+] [8] [5]	000B 85	13
[+] [F] [B]	000C FB	14
[+] [4] [C]	000D 4C	15
[+] [4] [F]	000E 4F	16
[+] [1] [C]	000F 1C	17

What you have just done is entered a program and stored it in the RAM at locations 0002 through 000F. You should have noticed the purpose of several special keys on your keyboard:

- [AD] - selects the address entry mode
- [DA] - selects the data entry mode
- [+] - increments the address without changing the entry mode
- [0] to [F] - 16 entry keys defining the hex code for address or data entry

You've noticed as well that your display contains 6 digits. The four on the left are used to display the hex code for an address. The two on the right show the hex code for the data stored at the address shown. Therefore, when you pressed [AD] (step 1) and [0] [0] [0] [2] (step 2), you defined the address entry mode, selected the address 0002, and displayed the address 0002 in the four left-most display digits. Incidentally, when we show an "x" in the display chart, we mean that we don't know what will be displayed and we "don't care."

Next you pressed [DA] (step 3) followed by [1] [8] (step 4). Here, you have defined the data entry mode and entered the value 18 to be stored at your selected address 0002. Of course, the 18 then was displayed in the two right-most digits of your display.

You remained in the data entry mode but began to press [+] followed by a two digit number (steps 5 to 17). Note that each depression of the [+] key caused the address displayed to increase by one. The hex keys following the [+] key continued to enter the data field of the display. This procedure is merely a convenience when a number of successive address locations are to be filled.

If you made any mistakes in pressing the keys, you should have noticed that correcting an error is simply a matter of reentering the data until the correct numbers show on the display.

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The program you have entered is a simple loop to add two 8 bit binary numbers together and present the result on the display. For a programmer, the listing of the program entered might appear as follows:

```

POINTL          = $FA
POINTH          = $FB
START           = $1C4F
0000            VAL1
0001            VAL2
0002            18      PROG   CLC
0003            A5 00      LDA  VAL1
0005            65 01      ADC  VAL2
0007            85 FA      STA  POINTL
0009            A9 00      LDA  #00
000B            85 FB      STA  POINTH
000D            4C 4F 1C    JMP  START

```

Stated in simple terms, the program will clear the carry flag (CLC) load VAL1 into the accumulator (LDA VAL1), add with carry VAL2 to the accumulator (ADC VAL2), and store the result in a location POINTL (STA POINTL). A zero value is stored in a location POINTH (LDA #00 and STA POINTH) and the program jumps to a point labelled START (JMP START). This pre-stored program will cause the display to be activated and will cause the address field of your display to show the numbers stored in locations POINTH and POINTL. Note that the result of the addition has already been stored in location POINTL.

The hex codes appearing next to the address field of the listing are exactly the numbers you entered to store the program. We refer to these as machine language codes. For example, 4C is the hex code for the JMP instruction of the microprocessor. The next two bytes of the program define 1C4F (START) as the jump address.

As yet, you are not able to run the program because you have not yet entered the two variables (VAL1 and VAL2). Lets try an actual example:

<u>Press Keys</u>	<u>See On Display</u>	<u>Step #</u>
[AD]	000F 1C	17A
[0] [0] [F] [1]	00F1 xx	17B
[DA] [0] [0]	00F1 00	18
[AD]	00F1 00	19
[0] [0] [0] [0]	0000 xx	20
[DA]	0000 02	21
[+] [0] [3]	0001 03	22
[+] [G0]	0002 18	23

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Steps 17A, 17B, and 18 insure that the binary arithmetic mode is selected.

Steps 19 to 21 store the hex value 02 in location 0000 (VAL1). Step 22 stores the hex value 03 in location 0001 (VAL2). Now we are ready to run the program. In step 23, the [GO] key causes the program to execute and the result, 05, appears in the right two digits of the address display. Although the problem appears trivial, it illustrates the basic principles of entering and executing any program as well as providing a fairly high assurance level that your KIM-1 module is operating properly.

You should try one more example using your stored program. Repeat steps 17A to 23 but substitute the value FF for VAL1 and VAL2 at locations 0000 and 0001. Now when you press the GO key, your display should read:

00FE xx

The answer is correct because:

$$\begin{array}{r} \text{FF} = 1111\ 1111 \\ + \text{FF} = \underline{1111\ 1111} \\ \text{FE} \quad 1111\ 1110 \end{array}$$

Try some more examples if you wish and then let's move on to the rest of the system.

2.5 ADDING A TAPERECORDER

In the previous section, you entered and executed a program. If you turn off the power supplies to the system, your program is lost since the memory into which you stored your program is volatile. If you require the same program again, you would have to repower the system and reenter the program as in the previous example.

The KIM-1 system is designed to work with an audio cassette tape recorder/player to provide you with a medium for permanent storage of your programs or data. The cassette with recorded data may be reread by the system as often as you wish. In this section, you will connect the audio cassette unit to the system and verify its operation.

The recording technique used by the KIM-1 system and the interface circuits provided have been selected to insure trouble-free operation with virtually any type and any quality level audio cassette unit. (We have demonstrated correct operation with a tape unit purchased for less than \$20.00 from a local discount outlet). In addition, tapes recorded on one unit may be played back to the system on a different unit if desired. We recommend, of course, that you make use of the best equipment and best quality tapes you have available.

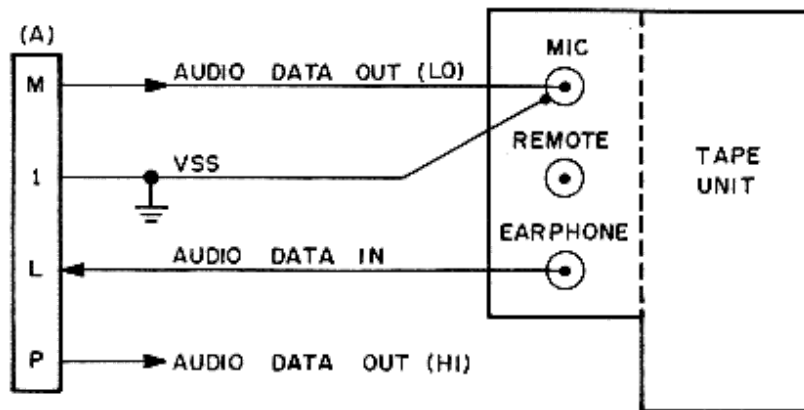
In selecting a tape unit for use with your KIM-1 system, you should verify that it comes equipped with the following features:

1. An earphone jack to provide a source of recorded tape data to the KIM-1 system.
2. A microphone jack to allow recording of data from the KIM-1 system on the tape.

3. Standard controls for Play, Record, Rewind, and Stop.

Note: You should avoid certain miniaturized tape equipment intended for dictating applications where the microphone and speaker are enclosed within the unit and no connections are provided to external jacks. If such equipment is used, you will have to make internal modifications to reach the desired connection points.

To connect your tape unit to the KIM-1 module, turn off the power supplies and remove the connector (A) from the module. Add the wires shown in the sketch:



Audio Tape Unit Connections
FIGURE 2.3

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Keep the leads as short as possible and avoid running the leads near sources of electrical interference. The connections shown are for typical, portable type units. The Audio Data Out (LO) signal has a level of approximately 15 mv. (peak) at pin M. Should you desire to use more expensive and elaborate audio tape equipment, you may prefer to connect the high level (1 volt peak) audio signal available at pin P to the "LINE" input of your equipment.

Return the connector (A) to its correct position on the KIM-1 module and turn on the power supplies. To verify the operation of your audio cassette equipment, try the following procedures:

1. Reenter the sample program following the procedures outlined in the previous section (2.4). Try the sample problem again to be sure the system is working correctly.
2. Install a cassette in your tape equipment and REWIND to the limit position.
3. Define the starting and ending address of the program to be stored and assign an identification number (ID) to the program.

Press Keys

See On Display

Step #

[AD]

xxxx xx

1

[0]	[0]	[F]	[1]	00F1 xx	2
[DA]		[0]	[0]	00F1 00	3
[AD]				00F1 00	4
[1]	[7]	[F]	[5]	17F5 xx	5
[DA]		[0]	[0]	17F5 00	6
[+]		[0]	[0]	17F6 00	7
[+]		[1]	[0]	17F7 10	8
[+]		[0]	[0]	17F8 00	9
[+]		[0]	[1]	17F9 01	10
[AD]				17F9 01	11
[1]	[8]	[0]	[0]	1800 xx	12

You will recall that the program we wish to store on tape was loaded into locations 0000 to 000F of the memory. Therefore, we define a starting address for recording as 0000 and store this in locations 17F5 and 17F6 (Steps 4 to 7). We define an ending address for recording as one more than the last step of our program and stored the value 0010 (= 000F + 1) in locations 17F7 and 17F8 (Steps 8,9). Finally we pick an arbitrary ID as 01 and store this value at location 17F9 (Step 10).

Note that before we use the audio cassette unit for recording or playing back, we must put 00 in location 00F1 (Steps 1,2 and 3).

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The starting address of the tape recording program is 1800. In Steps 11 and 12 we set this address value into the system. If we were to press [GO], the system would proceed to load data on to the magnetic tape. But first, we'd better start the tape!

4. Select the Record/Play mode of the tape recorder. Wait a few seconds for the tape to start moving and now:

Press [GO]

5. The display will go dark for a short time and then will relight showing:

0000 xx

6. As soon as the display relights, the recording is finished and you should STOP the tape recorder.

Now, you should verify that the recording has taken place correctly. This can be proven by reading the tape you have just recorded. Proceed as follows:

1. Rewind the tape cassette to its starting position.
2. Turn off the system power supplies and then later, turn them back on.

This has the effect of destroying your previously stored program which you already have recorded on tape.

3. Prepare the system for reading the tape as follows:

Press Keys	See On Display	Step #
------------	----------------	--------

[RS]					
[AD]				xxxx xx	1
[0]	[0]	[F]	[1]	00F1 xx	2
[DA]		[0]	[0]	00F1 00	3
[AD]				00F1 00	4
[1]	[7]	[F]	[9]	17F9 xx	5
[DA]				17F9 xx	6
		[0]	[1]	17F9 01	7
[AD]				17F9 01	8
[1]	[8]	[7]	[3]	1873 xx	9
[GO]				(Dark)	10

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The KIM-1 system is now looking for tape input data with the ID label 01. Recall that this is the same ID label we assigned when we recorded the program.

4. If your tape unit has a volume control, set the control at approximately the half way point.
5. If your tape unit has a tone control, set the control for maximum treble.
6. Now, turn on the tape using the PLAY mode. The tape will move forward and the system will accept the recorded data. As soon as the data record (ID=01) has been read, the display should relight showing:

0000 xx

You may now stop the tape unit. If the display relights and shows;

FFFF xx

this means that the selected record has been located and read but that an error has occurred during the reading of the data. In this case, press the [RS] key and repeat the read tape procedures from the beginning. If the FFFF still shows on the display, repeat the entire recording and playback procedures checking each step carefully. If the problem persists, refer to Appendix C, (In Case of Trouble).

If the tape continues to run and the display does not relight, this means that the system has been unsuccessful in reading any data back from the tape. In this case, repeat the entire recording and playback procedures checking each step carefully. If the problem persists, refer to Appendix C, (In Case of Trouble).

7. Assuming that you have read the tape successfully, you now may verify that the program has been restored to memory by trying a sample problem. (02 + 03 = 05)

NOTE: The KIM-1 interface circuits for the audio tape system are designed so that you do not require special test equipment to set up correct operating levels. If you have followed the procedures indicated, the tape system should work without the need of any adjustments by you.

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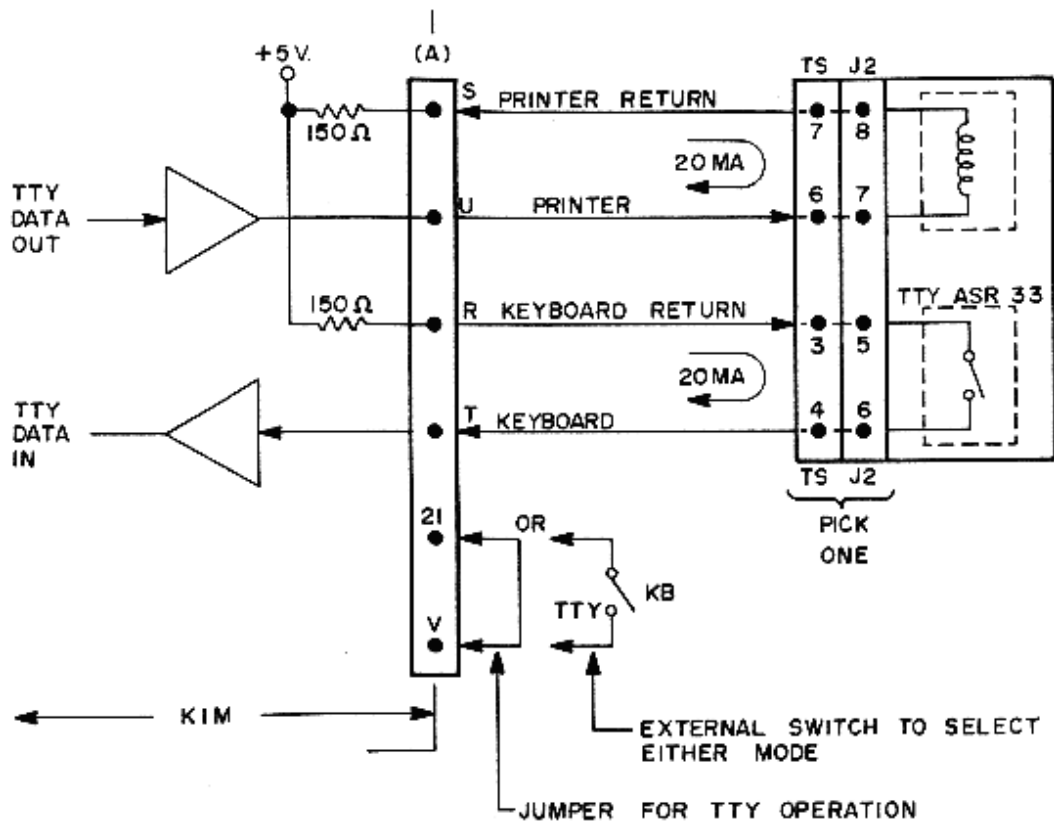
2.6 ADDING A TELEPRINTER

If you have access to a serial teleprinter, you may add such a unit to the KIM-1 system with very little effort. One of the more commonly available units of this type is the Teletype Model 33ASR which we will use for the purposes of illustration in this section. However, if you have available different equipment, you may use the information presented here as a guide to connecting your specific unit. In any case, we recommend you follow the directions offered by the equipment manufacturer in his instruction manual to effect the desired wiring and connection options.

The KIM-1 provides for a 4 wire interface to the TTY. Specifically, the "20 mA loop" configuration should be used and you should check that your TTY has been wired for this configuration. If not, you may easily change from "60 mA loop" to "20 mA loop" configurations following the manufacturers directions. The KIM-1 has been designed to work properly only with a teleprinter operating in full duplex mode. Check the literature supplied with your teleprinter if you are unsure if your unit is properly configured. You are not restricted to units with specific bit rates (10 CPS for TTY) since the KIM-1 system automatically adjusts for a wide variety of data rates (10CPS, 15CPS, 30CPS, etc.).

To connect the TTY to the system, proceed as follows:

1. Turn off system power and remove connector (A) from the module.
2. Add the wires shown in the sketch to connector (A) and to the appropriate connector on the TTY unit.



TTY Connections
FIGURE 2.4

3. The jumper wire from A-21 to A-V is used to define for the KIM-1 system that a teleprinter will be used as the only input/display device for the system. If you expect to use both TTY and the KIM-1 keyboard/display, you should install the switch shown instead of the jumper. Now, the switch, when open, will allow use of the keyboard and display on the KIM-1 module and, when closed, will select the teleprinter as the input/display device. (of course, you may use a clip-lead instead of the switch if you desire).
4. Be sure pins A-21 and A-V are connected. Reinstall connector (A) and return power to the system. Turn-on the TTY.
5. Press the [RS] key on the KIM-1 module then press the [RUB OUT] key on the TTY. This step is most important since the KIM-1 system adjusts automatically to the bit rate of the serial teleprinter and requires this first key depression to establish this rate.

If everything is working properly you should immediately observe a message being typed as follows:

KIM

This is a prompting message telling you that the TTY is on-line and the

KIM-1 system is ready to accept commands from the TTY keyboard.

Should the prompting message not be typed press the [RS] key on the KIM-1 keyboard and then the [RUB OUT] key on the TTY. If the "KIM" message still is not typed, recheck all connections and the TTY itself and try again. If the problem persists, refer to Appendix C, (In Case of Trouble).

6. Assuming that the TTY is operable, you may now try a simple group of operations to verify correct system operation:

Press Keys	See On Display	Step #
	KIM	
	xxxx xx	1
0002	0002	2
[SPACE]	0002 xx	3
18.	18.	4
	0003 xx	5
A5.	A5.	6
	0004 xx	7
[LF]	0003 A5	8
[RUB OUT]	KIM	
	xxxx xx	9

Step 1 shows the "KIM" prompting message. In Step 2, an address (0002) is selected followed by a space key in Step 3. The address cell 0002 together with the data stored at that location (xx) is printed. Step 4 shows the "modify cell" operation using the [.] key and the hex data keys preceding. Step 5 shows the incrementing to the next address cell (0003) after the [.] key. Note that the modification of cell 0002 also occurs. Steps 6 and 7 show the modification of data in cell 0003 and the incrementing to cell 0004. Step 8 shows the action of the [LF] key in backing up one cell to 0003 where we can see from the printout that the correct data (A5) has been stored at that location. Step 9 shows the reaction to the [RUB OUT] key in resetting the system and producing a new "KIM" prompting message. Note, by the way, that in this example you have repeated a portion of the program entry exactly as you did in Section 2.4 but this time using the TTY.

So much for now! If all of the operations have occurred properly, you may be certain that your TTY and KIM-1 module are working together correctly. We will describe in detail all of the other operations possible with the TTY in a later section of the manual.

If you have reached this point without problems, you now have completed all of the required system tests and may be confident that the KIM-1 module and your peripheral units are all working correctly. Our next task is to learn more about the KIM-1 system and its operating programs.

Up to this point you have been engaged in bringing up your KIM-1 system and verifying its correct operation. Now it's time to learn more about the various parts of the KIM-1, how the parts work together as a system, and how the operating programs control the various activities of the system. The diagrams included in this section together with your full sized system schematic will be helpful in understanding the elements of your KIM-1 module.

3.1 KIM-1 SYSTEM DESCRIPTION

[Figure 3-1](#) shows a complete block diagram of the KIM-1 system. You should note first the presence of the MCS 6502 Microprocessor Array which acts as the central control element for the system. This unit is an 8 bit microprocessor which communicates with other system elements on three separate buses. First, a 16 bit address bus permits the 6502 to address directly up to 65,536 memory locations in the system. Next, an 8 bit, bidirectional data bus carries data from the 6502 array to any memory location or from any memory location back to the 6502 array. Lastly, a control bus carries various timing and control signals between the 6502 array and other system elements.

Associated with the 6502 array is a 1 MHz crystal which operates with an oscillator circuit contained on the 6502 array. This crystal controlled oscillator is the basic timing source from which all other system timing signals are derived. In particular, the $\phi 2$ signal generated by the 6502 array and used either alone, or gated with other control signals, is used as the system time base by all other system elements.

The 6502 microprocessor is structured to work in conjunction with various types of memory. In the KIM-1 system, all memory may be considered to be of the Read-only (ROM) or Read/Write (RAM) variety. The ROM portion of the memory provides permanent storage for the operating programs essential to the control of the KIM-1 system. You will note the inclusion of two devices, labelled 6530-002 and 6530-003. Each of these devices include a 1024 byte (8 bits per byte) ROM with different portions of the operating program stored permanently in each ROM.

RAM type memory is available at three locations in the system. Again, each of the 6530 arrays include 64 bytes of RAM primarily used for temporary data storage in support of the operating program. In addition, a separate 1024 byte RAM is included in the KIM-1 system and provides memory storage for user defined application programs and data.

Input/output controls for the system also are included within the 6530 arrays. Each 6530 array provides 15 I/O pins with the microprocessor and operating program defining whether each pin is an input pin or output pin, what data is to appear on the output pins, and reading the data appearing on input pins. The I/O pins provided on the 6530-002 are dedicated to interfacing with specific elements of the KIM-1 system including the keyboard, display, TTY interface circuit, and audio tape interface circuit. The 15 I/O pins on the 6530-003 are brought to a connector and are avail-

able for the user to control a specific application.

Finally, each 6530 array includes an interval timer capable of counting a specific number of system clocks to generate precise timing gates. The exact time interval is preset under program control. The interval timer on the 6530-003 array is available for a user defined application program and is not required by the operating programs.

[Figure 3-1](#) shows a major block labelled Control Logic. Included under this category are an address decoder used for generation of chip select signals for the 6530 arrays and the static RAM. Also included is the logic required to debounce the keys for system reset (RS key) and program stop (ST key). Lastly, special logic is included to allow operation of the system in a "single instruction" mode to facilitate program debugging.

[Figure 3-1](#) shows the keyboard/display logic interfacing with the I/O pins of the 6530-002. Also shown are the interface circuits for transmission of data to and reception of data from the TTY and audio tape units.

[Figure 3-2](#) shows the detailed interconnections between the MCS 6502 and the two NCS 6530 arrays.

[Figure 3-3](#) shows detailed logic and schematics for the control logic.

[Figure 3-4](#) shows a detailed schematic of the static RAM.

[Figure 3-5](#) and [3-6](#) show the detailed schematic of the keyboard and display logic and circuits.

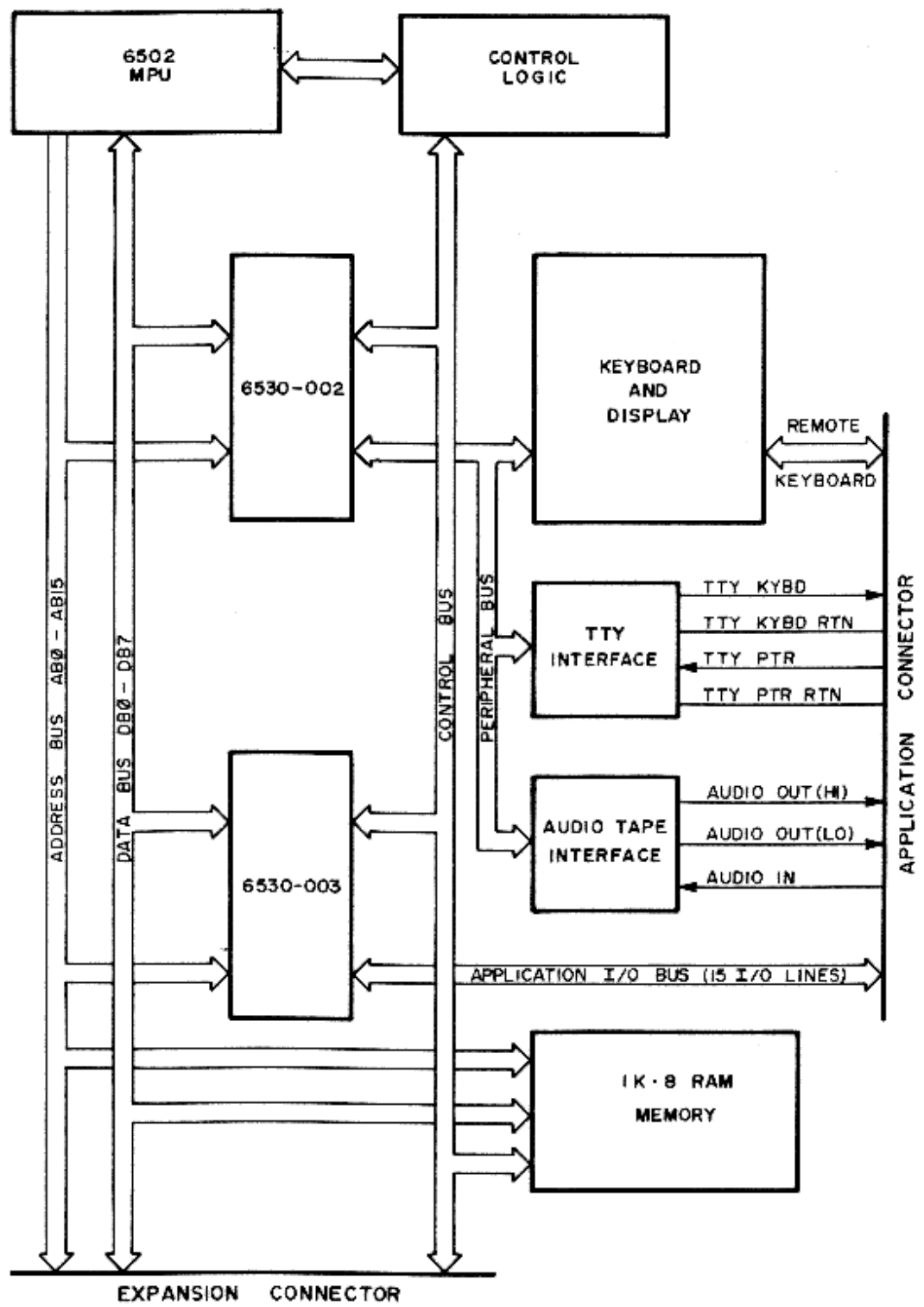
[Figure 3-7](#) details the schematic of the TTY interface circuits.

[Figure 3-8](#) details the schematic of the audio tape cassette interface circuits.

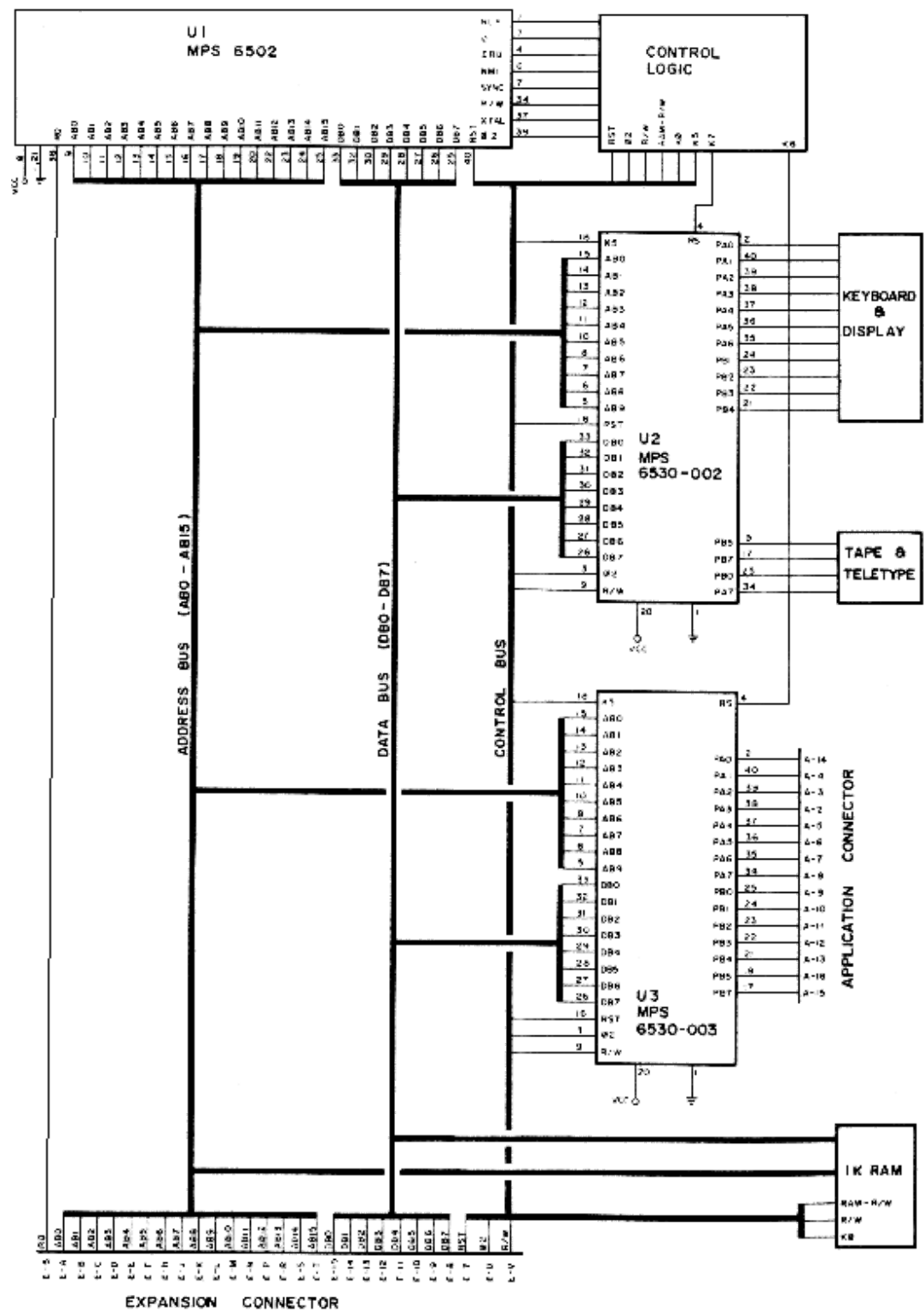
[Figures 3-9](#) and [3-10](#) provide a summary of all signals available on either the Application connector or the Expansion Connector.

The fold-out system schematic shows all of the elements of the system connected together and all signals appearing on the module connectors.

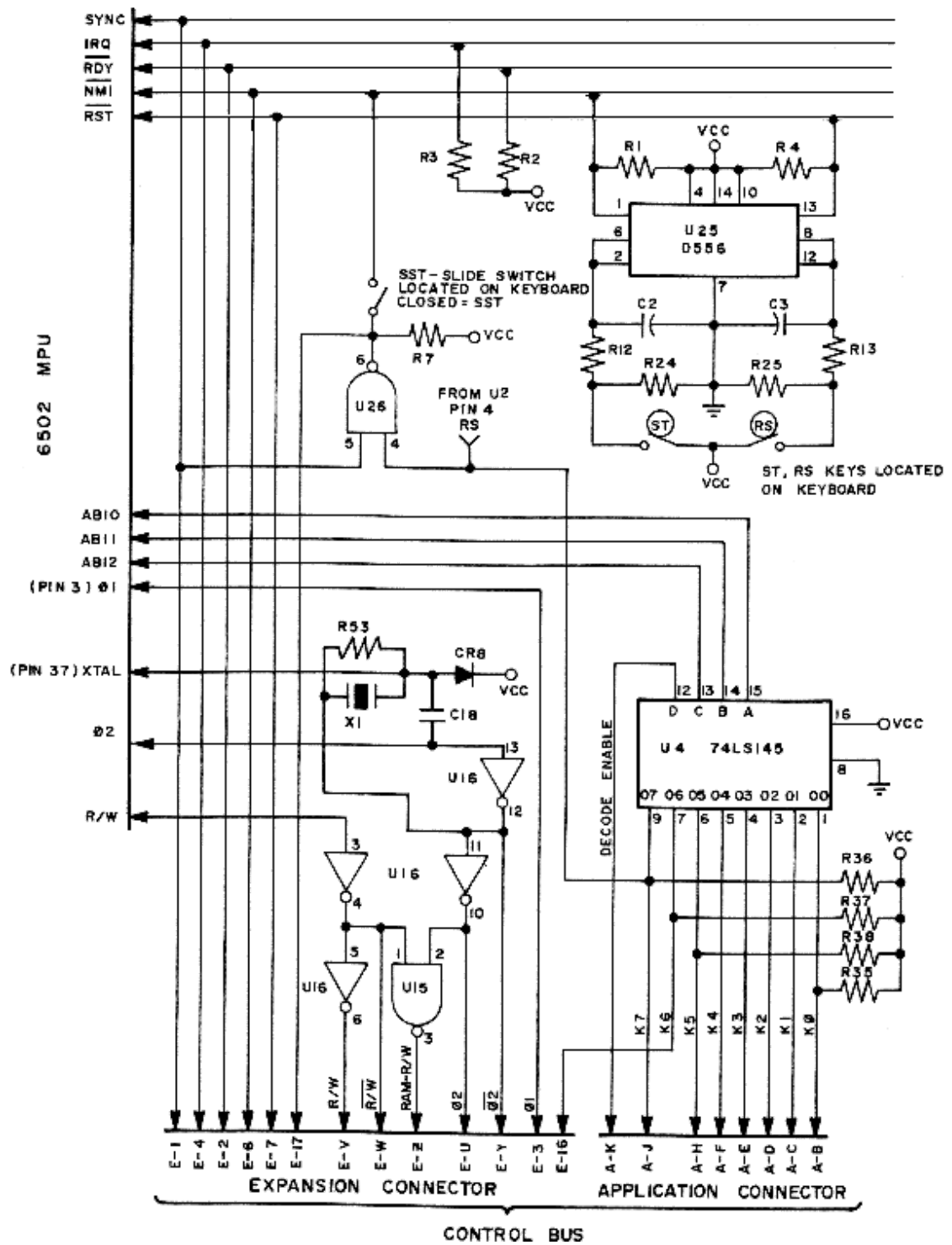
You may refer to the Hardware Manual included with your KIM-1 module for additional details on the operating characteristics of the 6502 and 6530 arrays as well as detailed information on system timing.



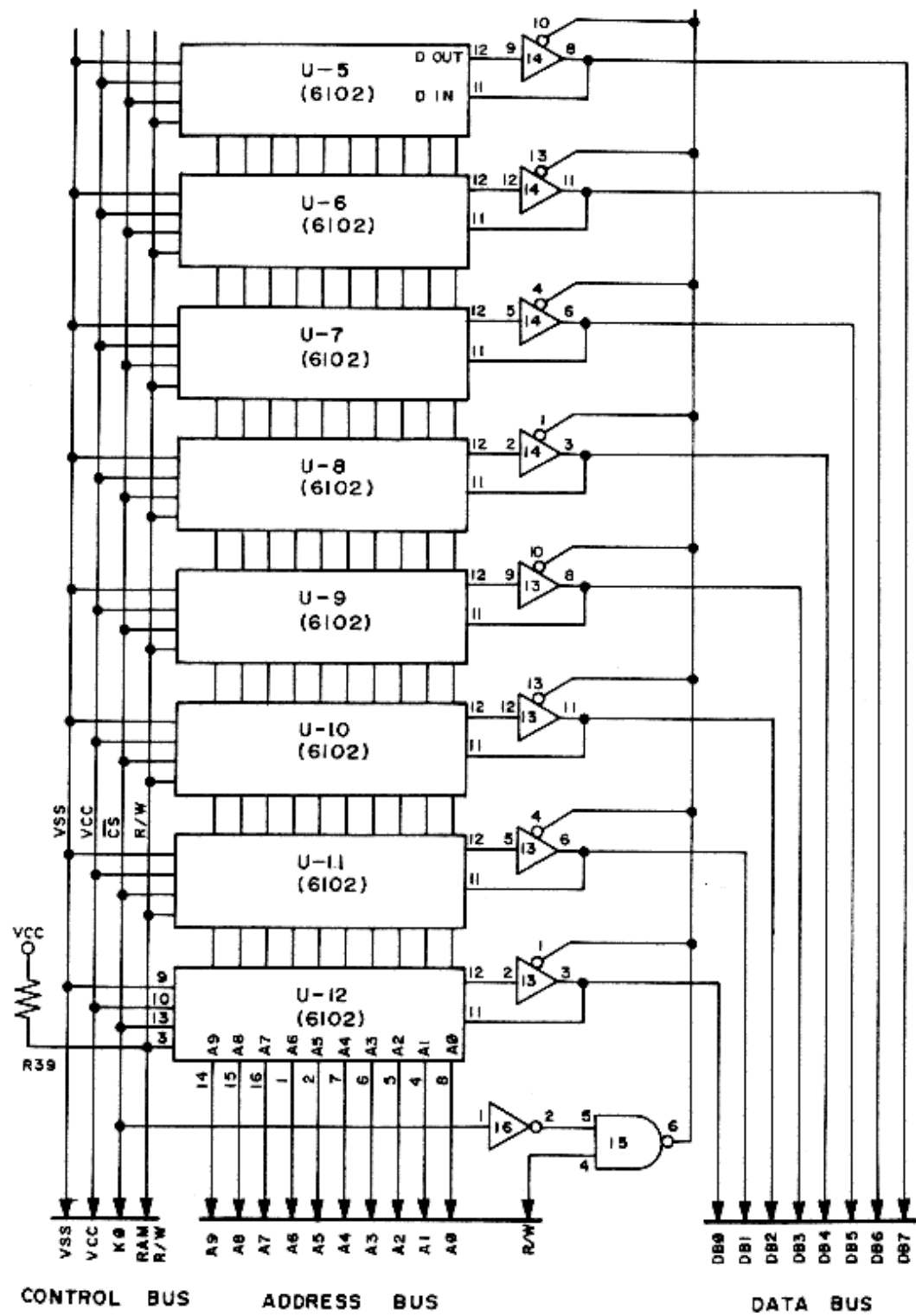
KIM-1 Block Diagram
FIGURE 3.1



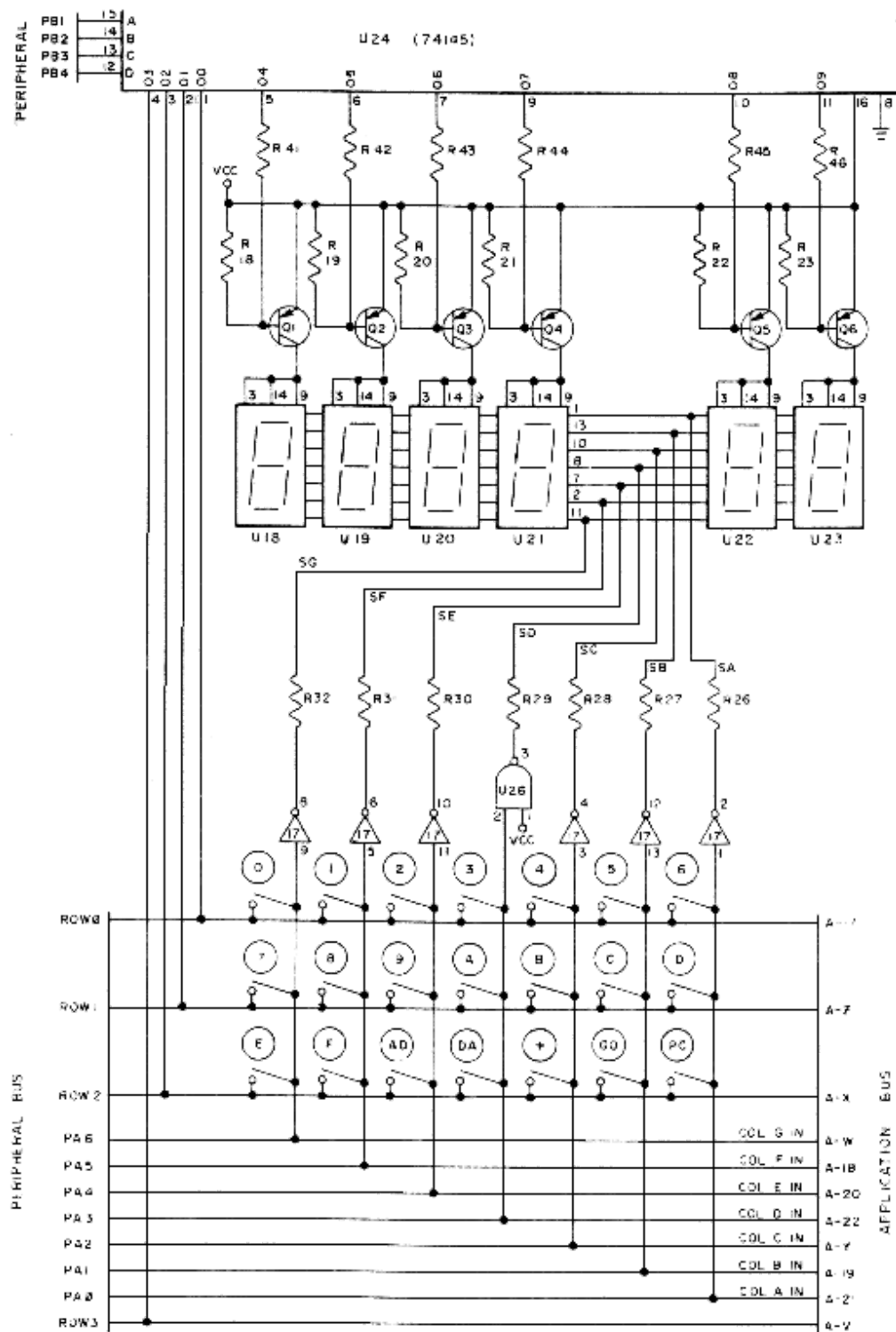
Detailed Block Diagram
FIGURE 3.2



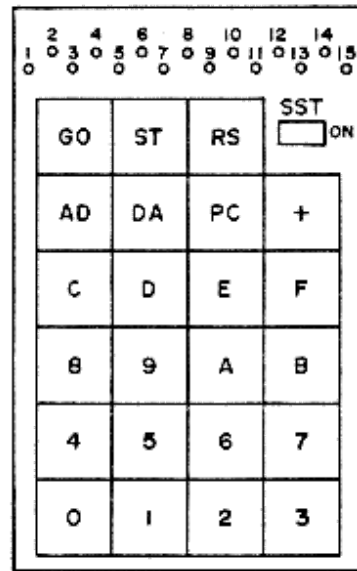
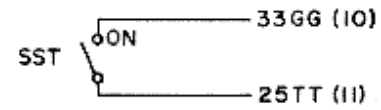
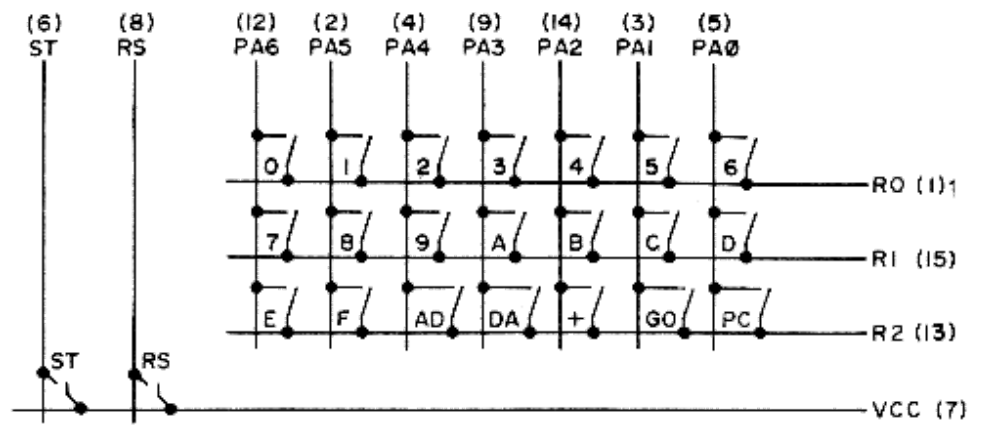
Control and Timing
FIGURE 3.3



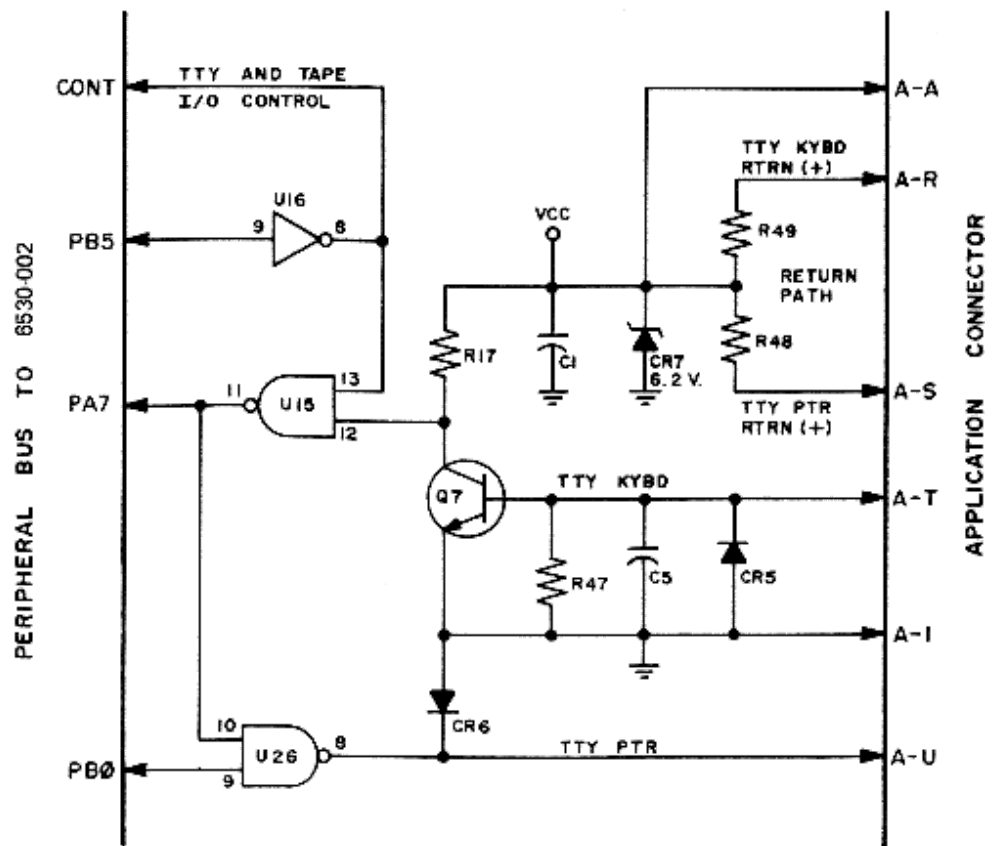
1Kx8 RAM Memory
FIGURE 3.4



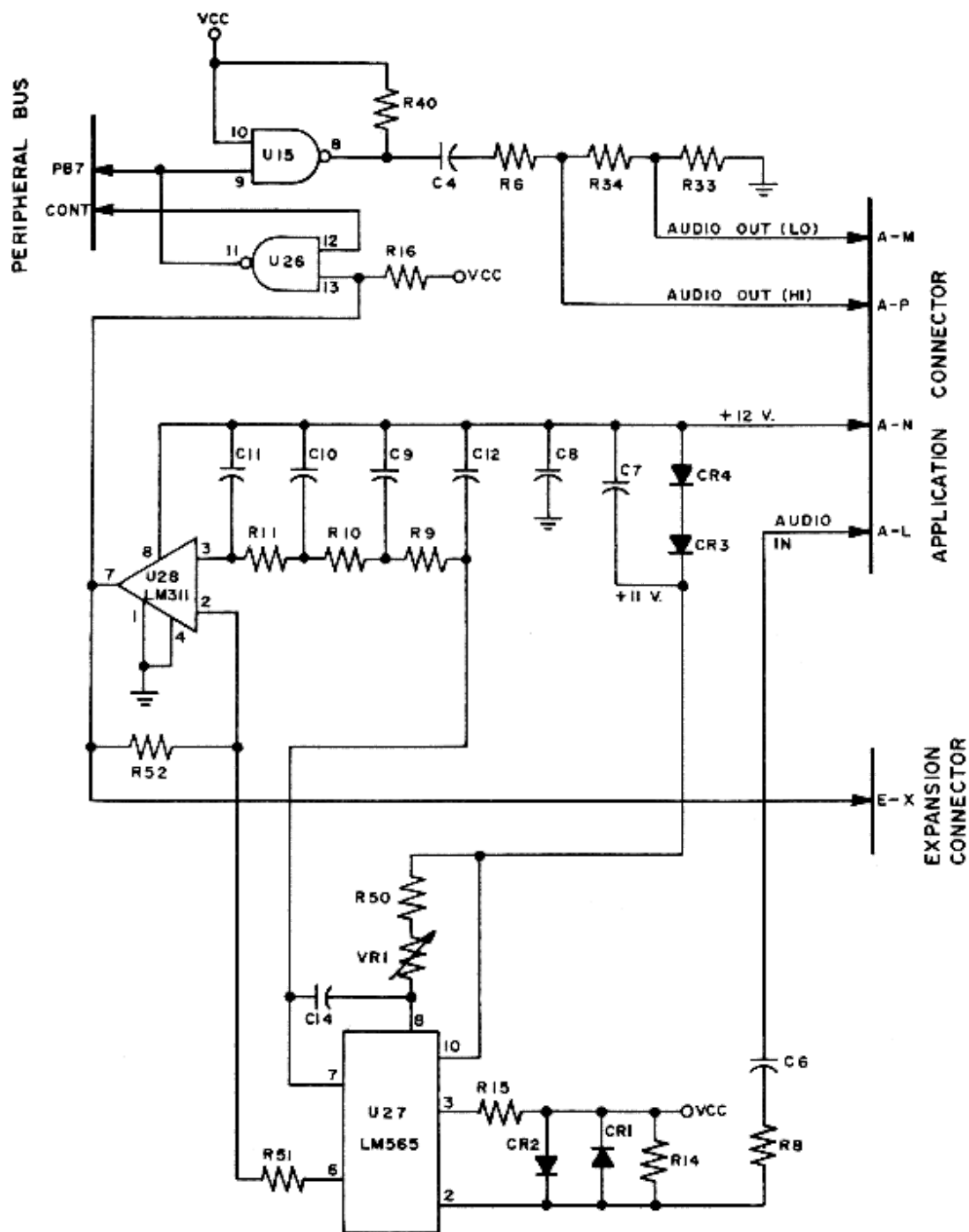
Keyboard and Display
FIGURE 3.5



Keyboard Detail
FIGURE 3.6



TTY Interface
FIGURE 3.7



Audio Tape Interface
FIGURE 3.8

22	KB Col D	0	KB Row 1
21	KB Col A	Y	KB Col C
20	KB Col E	X	KB Row 2
19	KB Col B	W	KB Col G
18	KB Col F	V	KB Row 3
17	KB Row 0	U	TTY PTR
16	PB5	T	TTY KYBD

15	PB7	S	TTY PTR RTRN(+)
14	PA0	R	TTY KYBD RTRN(+)
13	PB4	p	AUDIO OUT HI
12	PB3	N	+12v
11	PB2	M	AUDIO OUT LO
10	PB1	L	AUDIO IN
9	PB0	K	DECODE ENAB
8	PA7	J	K7
7	PA6	H	K5
6	PA5	F	K4
5	PA4	E	K3
4	PA1	D	K2
3	PA2	C	K1
2	PA3	B	K0
1	VSS CND	A	VCC +5v

Application Connector
FIGURE 3.9

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22	VSS GND	Z	RAM/R/W
21	VCC +5	Y	/p2
20		X	PLL TEST
19		W	/R/W
18		V	R/W
17	SST OUT	U	p2
16	K6	T	AB15
15	DB0	S	AB14
14	DB1	R	AB13
13	DB2	P	AB12
12	DB3	N	AB11
11	DB4	N	AB10
10	DB5	L	AB9
9	DB6	K	AB8
8	DB7	J	AB7
7	RST	H	AB6
6	NMI	F	AB5
5	R0	E	AB4
4	IRQ	D	AB3
3	p1	C	AB2
2	RDY	B	AB1
1	SYNC	A	AB0

Expansion Connector
FIGURE 3.10

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3.2 KIM-1 MEMORY ALLOCATION

It has been stated that the 6502 microprocessor array included in the KIM-1 system is capable of addressing any of 65,536 memory locations. Obviously, we have not included that much memory in your KIM-1 system and

this section is intended to detail for you exactly what memory locations are included in the system and where they are located (their exact addresses).

Each byte of memory in the system is understood to include 8 bits. Also, you should note that any addressable location in the system may be performing any one of four functions:

1. A ROM byte - read-only memory in which we have stored the operating program.
2. A RAM byte - read/write memory for storage of variable data.
3. An I/O location - these locations include both direction registers which define the I/O pins to be either input pins or output pins, and the actual data buffer locations containing the data to be transmitted on output pins or the data read from input pins. Any I/O location may be viewed as a read/write memory location with a specific address.
4. An Interval Timer location - a series of addresses are reserved for each interval timer in the system. Again, you may write to the timer to define its counting period or read from the timer to determine its exact state.

[Figure 3-11](#) shows a block diagram detailing all memory blocks in the KIM-1 system. [Figure 3-12](#) provides a memory map showing all addressable locations included in the system and their relationship to each other. Note also the areas in the memory map indicated as available for expansion. (Section 6 of the manual provides more detail on the subject of memory expansion). Finally, [Figure 3-13](#) provides a complete listing of all important memory locations and will be referenced frequently by you when writing your application programs.

Referring to [Figure 3-12](#), note that the memory map shows a block of 8192 address locations all existing in the lowest address space within the possible 65,536 address locations. This address space is further divided into eight blocks of 1024 locations each. Each 1024 block is further divided into four pages of 256 locations each. The "K" reference defines a specific block of 1024 locations and refers to the "K" number of the address decoder included within the system control logic. The "page" reference defines a specific group of 256 addresses. A total of 32 pages (0 to 31) are included in the 8192 address locations. The hex codes for certain addresses are shown at strategic locations in the memory map.

Beginning from the highest address location of the 8192, note that the first 1024 block (K7) is assigned to the ROM of the 6530-002 and the second 1024 block (K6) is assigned to the ROM of the 6530-003. The entire operating program of the KIM-1 system is included in these two blocks.

Next in order, a portion of the K5 block is dedicated to the RAM, I/O, and Timer locations of the two 6530 arrays. An expanded view of this address space is shown in [Figure 3-12](#). Note that the RAM addresses for the 6530-002 (Hex 17EC to 17FF) are reserved for use by the operating program and should not appear in a user generated application program. The same is true for the I/O and Timer locations of the 6530-002 which also are reserved for use by the operating programs.

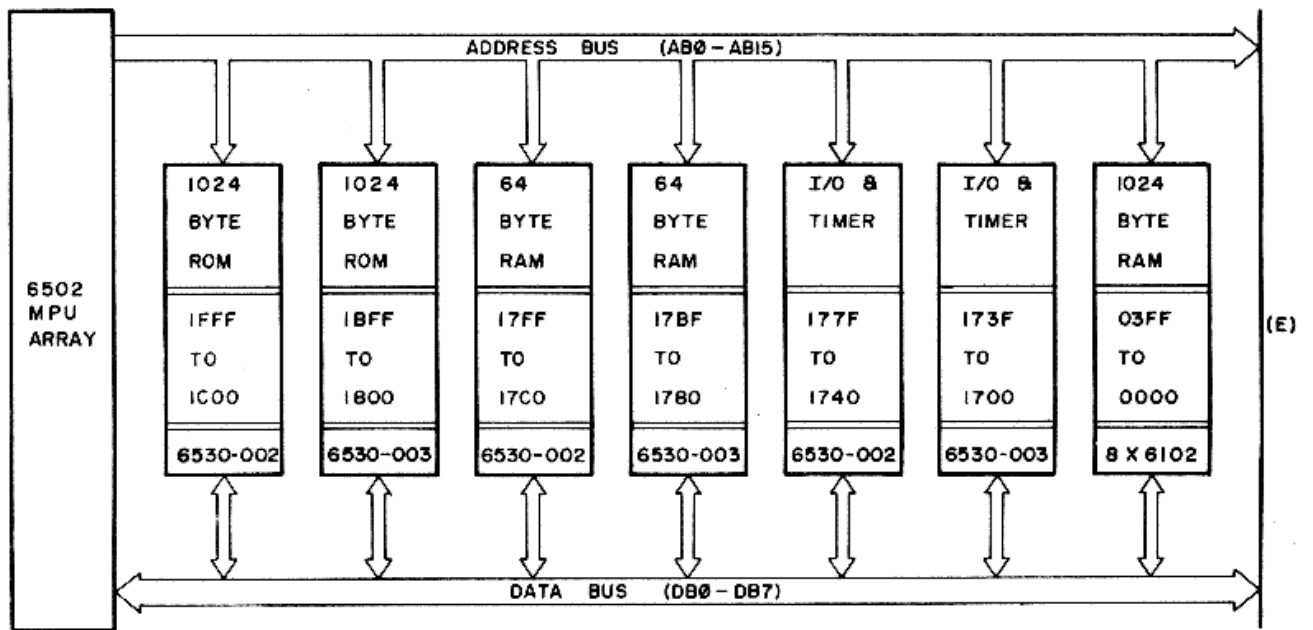
The next four blocks in order (K4, K3, K2, K1) are reserved for additional memory in an expanded system. In Section 6, the methods for adding memory will be discussed.

Finally, the lowest 1024 address locations (K0) are assigned to the static RAM included within the KIM-1 system. You should note that within this block, Page 0 and Page 1 have special significance. Page 1 is used as the system stack onto which return addresses and machine status words are pushed as the system responds to interrupts and subroutine commands. Page 0 has significance for certain of the special addressing modes available when programming for the 6502 microprocessor array.

[Figure 3-12](#) shows an expanded view of Page 0 and Page 1. Note that 17 addresses (00EF to 00FF) are reserved for use by the operating program and must never appear in the user generated application program. Also, note the comment that a maximum of eight locations may be required on the stack (Page 1) to service operating program interrupts.

In summary, the user generated application program may make use of the following areas of memory:

1. All of Page 0 except 00EF to 00FF
2. All of Page 1 (remember that the stack will extend an extra 8 bytes deep to accommodate the operating program).
3. All of Page 2 and Page 3.
4. In Page 23:
 - All I/O locations from 1700 to 173F
 - All 64 bytes of RAM from 1780 to 17BF
 - An additional 44 bytes of RAM from 17c0 to 17EB



Memory Block Diagram
FIGURE 3.11

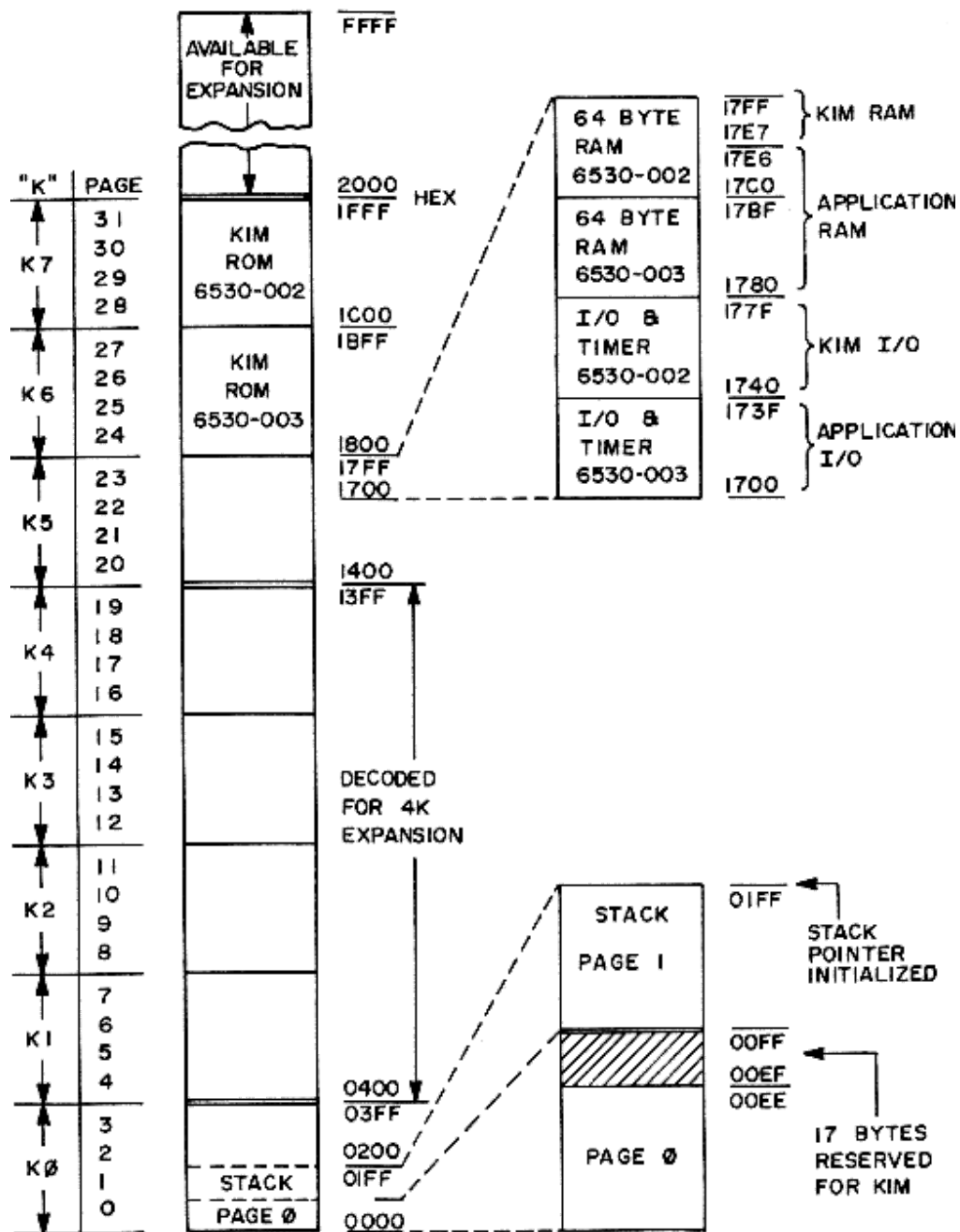


FIGURE 3.12
Memory Map

ADDRESS	AREA	LABEL	FUNCTION
00EF	Machine Register Storage Buffer	PCL	Program Counter - Low Order Byte
00F0		PGH	Program Counter - High Order Byte
00F1		P	Status Register
00F2		SF	Stack Pointer
00F3		A	Accumulator
00F4		Y	Y-Index Register
00F5		X	X-Index Register

1700	Application I/O	PAD	6530-003 A Data Register
1701		PADD	6530-003 A Data Direction Register
1702		PBD	6530-003 B Data Register
1703		PBDD	6530-003 B Data Direction Register
1704	Interval Timer		6530-003 Interval Timer
170F			(See Section 1.6 of Hardware Manual)
17F5	Audio Tape Load & Dump	SAL	Starting Address - Low Order Byte
17F6		SAH	Starting Address - High Order Byte
17F7		EAL	Ending Address - Low Order Byte
17F8		EAH	Ending Address - High Order Byte
17F9		ID	File Identification Number
17FA	Interrupt Vectors	NMIL	NMI Vector - Low Order Byte
17FB		NMIH	NMI Vector - High Order Byte
17FC		RSTL	RST Vector - Low Order Byte
17FD		RSTH	RST Vector - High Order Byte
17FE		IRQL	IRQ Vector - Low Order Byte
17FF		IRQH	IRQ Vector - High Order Byte
1800	Audio Tape	DUMPT	Start Address - Audio Tape Dump
1873		LOADT	Start Address - Audio Tape Load
1C00	STOP Key + SST		Start Address for NMI using KIM "Save Nachine" Routine (Load in 17FA & 17FB)
17F7	Paper Tape Dump (Q)	EAL	Ending Address - Low Order Byte
17F8		EAH	Ending Address - High Order Byte

Special Memory Addresses
FIGURE 3.13

3.3 KIM-1 OPERATING PROGRAMS

[Figure 3-14](#) shows a simplified flow chart of the KIM-1 operating programs. This section provides a brief explanation of these programs to assist you in understanding the various operating modes of the system.

First, you should note that when power is first applied to your KIM-1 module and the [RS] (reset) key is depressed, control of the system automatically is assumed by the operating program. This is true, as well, for any succeeding depression of the reset key.

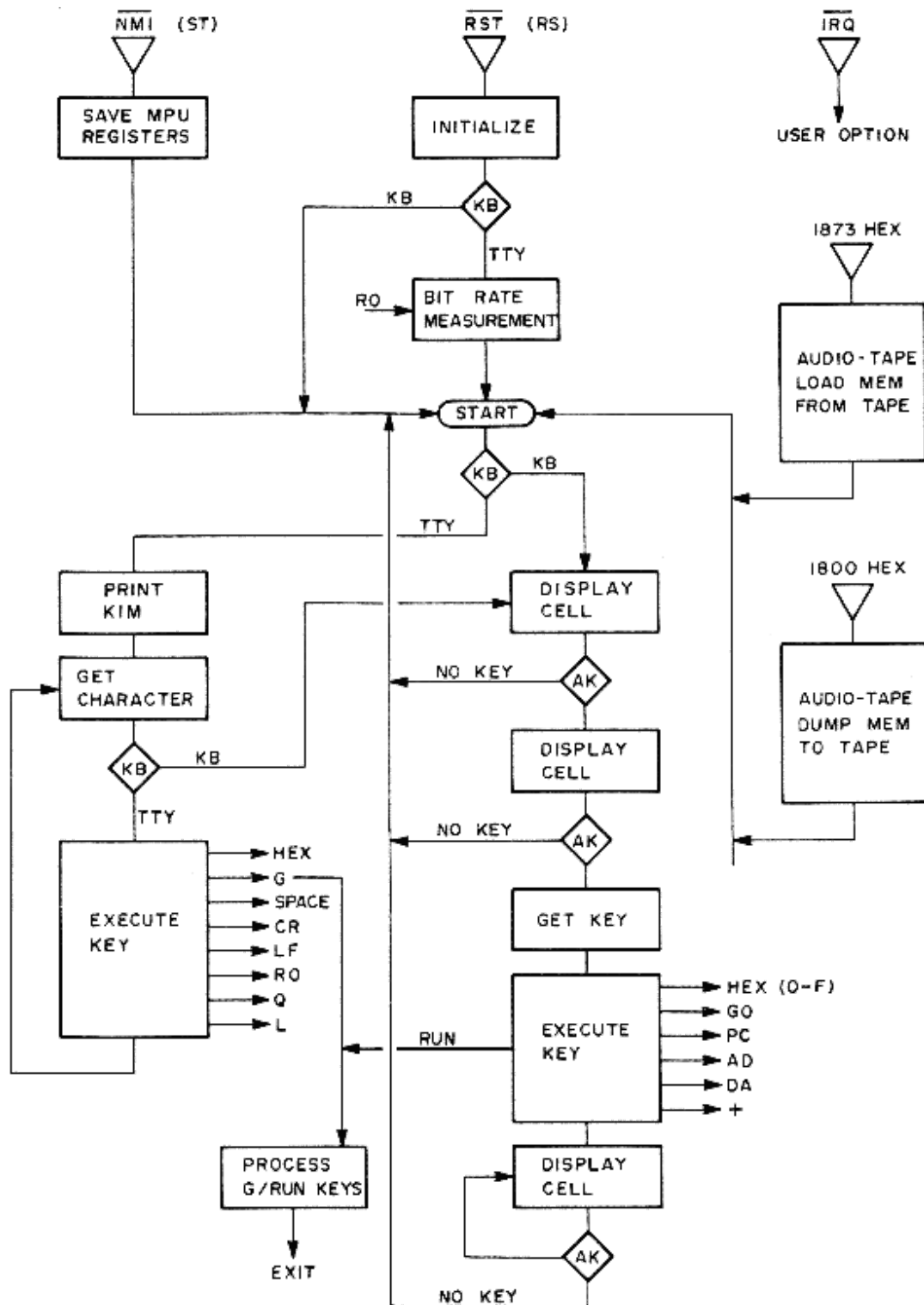
For each depression of the reset key, the system is initialized. At this time, stack pointer values are set, the I/O configuration is established, and essential status flags are conditioned. Next the program determines whether the system is to respond to TTY inputs or is to operate with the keyboard and display on the KIM-1 module.

If the TTY mode has been selected, the program halts and awaits a first key depression from the TTY (the RubOut Key). Upon receipt of this key depression, the program automatically performs a bit rate measurement and stores the correct value for use in receiving and decoding succeeding data transfers from the TTY. Note that this bit rate measurement is performed after each depression of the reset key.

The program will proceed immediately to a routine causing the prompting message ("KIM") to be typed on the TTY. Now, the program halts

at the loop called "Get Character". As each key is depressed on the TTY, the coded data is accepted and analyzed in the routine called "Execute Key". The various keys depressed will cause the program to branch to the appropriate subroutines required to perform the desired operation. Upon completion of the individual key executions, the program returns to the "Get Key" loop and awaits the next key depression.

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Exit from the TTY processing loop will occur in response to:

1. A depression of the reset key,
2. A depression of the G key which initiates execution of the application program, or
3. A change in the mode from TTY to Keyboard/Display.

If, after system reset and initialization, the Keyboard/Display mode (KB) is determined to be in effect, the program will proceed directly to display, and keyboard scan routines. The program will cause the display scan to occur continuously ("Display Cell") until one of the keys on the keyboard is depressed (AK?). Key validation is performed during an additional scan cycle. If the key is truly depressed (not noise), the program proceeds to the routine called "Get Key" in which the exact key depressed is defined. Next, the program moves to the "Execute Key" routine where branches to appropriate execution routines will be performed. Finally, after key execution, the program returns to the "Display Cell" routine and waits for the key to be released. When no key is depressed, the program returns to the normal "Display Cell" routine and awaits the next key depression.

In either the TTY or KB modes, the audio tape load or dump routines may be executed using appropriate commands from the selected keyboards. In either case, completion of the tape load or dump routine allows the program to return to the "Start" position which will, as usual, activate the KIM-1 display or cause the "KIM" prompting message on the TTY.

You should note the use of the Stop key to activate the non-maskable interrupt input (NMI) of the 6502 microprocessor array. Depression of this key causes an unconditional termination of program execution, a saving of machine status registers on the stack, and a return to the control of the operating program.

A second interrupt input is available and referred to as IRQ. This interrupt may be defined by the user and will cause the program to jump to any location defined by the user in his program.

CHAPTER 4

OPERATING THE KIM-1 SYSTEM

Now that you have a better idea of what is included in your KIM-1 system and how it operates, its time to provide you with detailed procedures for all of the operations you can perform with the system. We will separate our operating procedures into three areas giving specific

direction for the use of the KIM-1 keyboard and display, the audio tape recorder, and the serial teleprinter (TTY).

4.1 USING THE KIM KEYBOARD AND DISPLAY

A brief study of your keyboard shows a total of 23 keys and one slide switch. First, let's list the purpose of each key:

- [0] to [F] - Sixteen keys used to define the hex code of address or data
- [AD] - selects the address entry mode
- [DA] - selects the data entry mode
- [+] - increments the address by +1 but does not change the entry mode
- [PC] - recalls the address stored in the Program Counter locations (PCH, PCL) to the display
- [RS] - causes a total system reset and a return to the control of the operating program
- [GO] - causes program execution to begin starting at the address shown on the display
- [ST] - terminates the execution of a program and causes a return to the control of the operating program

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You have seen in an earlier chapter that the six digit display includes a four digit display of an address (left four digits) and a two digit display of data (right two digits).

Using only the KIM-1 keyboard and display, you may perform any of the following operations:

1. Select an Address

Press AD followed by any four of the hex entry keys. The address selected will appear on the display. If an entry error is made, just continue to enter the correct hex keys until the desired address shows on the display. Regardless of what address is selected, the data field of the display will show the data stored at that address.

2. Modify Data

After selecting the proper address, press [DA] followed by two hex entry keys which correctly define the data to be stored at the selected address. The data entered will appear in the data field of the display to indicate that the desired code has already been entered.

Note that it is possible for you to select an address of a ROM memory cell or even the address of a memory cell that

does not exist in your system. In these cases, you will not be able to change the data display since it is clearly not possible for the system to write data to a ROM cell or a non-existent memory location.

3. Increment the Address

By pressing the [+] key the address displayed is automatically increased by +1. Of course, the data stored at the new address will appear on the display. This operation is useful when a number of successive address locations must be read or modified. Note that the use of the [+] key will not change the entry mode. If you had previously pressed the [AD] key, you remain in the address entry mode and a previous depression of the [DA] means you remain in the data entry mode.

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4. Recall Program Counter

Whenever the NMI interrupt pin of the 6502 microprocessor array is activated, the program execution in progress will halt and the internal registers of the 6502 are saved in special memory locations before the control of the system is returned to the operating program. In the KIM-1 system, the NMI interrupt may occur in response to a depression of the [ST] key (stop) or, when operating in the Single Step mode, after each program instruction is executed following the depression of the GO key.

The [PC] key allows you automatically to recall the value of the Program Counter at the time an interrupt occurred. You may have performed a variety of operations since the interrupt such as inspecting the contents of various machine registers stored at specific memory locations. However, when you press the [PC] key, the contents of the Program Counter at the time of the interrupt are recalled to the address field of the display. You now may continue program execution from that point by pressing the [GO] key.

5. Execute a Program

Select the starting address of the desired program. Now, press the [GO] key and program execution will commence starting with the address appearing on the display.

6. Terminate a Program

The [ST] key is provided to allow termination of program execution. As mentioned earlier, the [ST] key activates the NMI interrupt input of the 6502 microprocessor array.

Note: The [ST] key will operate correctly only if you store the correct interrupt vector at locations 17FA and 17FB. For most of your work with the KIM-1 system, you should store the address 1C00 in these locations as follows:

[AD]			
[1]	[7]	[F]	[A]
[DA]		[0]	[0]
[+]		[1]	[C]

45

Now, when the NMI interrupt occurs, the program will return to location 1C00 and will proceed to save all machine registers before returning control to the operating program.

You should remember to define the NMI vector each time the power to the system has been interrupted. A failure of the system to react to the [ST] key means you have forgotten to define the NMI vector.

7. Single Step Program Execution

In the process of debugging a new program, you will find the single step execution mode helpful. To operate in this mode, move the SST slide switch to the ON position (to your right). Now, depress the [GO] key for each desired execution of a program step. The display will show the address and data for the next instruction to be executed. Note that in the course of stepping through a program, certain addresses will appear to be skipped. A program instruction will occupy one, two, or three bytes of memory depending upon the type of instruction. In single instruction mode, all of the bytes involved in the execution of the instruction are accessed and the program will halt only on the first byte of each successive instruction.

Note: SST mode also makes use of the NMI interrupt of the 6502 microprocessor array. Again, the NMI vector must be defined as described in (6) above if the SST mode is to work correctly.

This covers all of the standard operations you may perform from the KIM-1 keyboard. Using combinations of the operations described, you may wish to perform certain specialized tasks as follows:

1. Define the IRQ Vector

You will recall that a separate interrupt input labelled IRQ is available as an input to the 6502 microprocessor array. If you wish to use this feature, you should enter the address to which the program will jump. The IRQ vector is stored in locations 17FE and 17FF.

2. Interrogate Machine Status

We have mentioned that after an NMI interrupt in response to the ST key or during the SST mode, the contents of various machine registers are stored in specific memory locations. If you wish to inspect these locations, their addresses are:

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```
00EF = PCL
00F0 = PCH
00F1 = Status Register (P)
00F2 = Stack Pointer (SP)
00F3 = Accumulator (A)
00F4 = Y Index Register
00F5 = X Index Register
```

4.2 USING THE AUDIO TAPE RECORDER

There are two basic operations possible when working with your audio tape system. You may transfer data from the KIM-1 memory and record it on tape. Or, you may read back a previously recorded tape, transferring the data on tape into the KIM-1 memory.

Recording on Audio Tape

The procedure for recording on audio tape requires that you perform the following steps:

1. Clear decimal mode by entering 00 in location 00F1. Define an identification number (ID) for the data block you are about to record. This two digit number is loaded into address 17F9. Don't use ID = 00 or ID = FF.

2. Define the starting address of the data block to be transferred. This address is to be loaded into locations:

```
17F5 = Starting Address Low (SAL)
17F6 = Starting Address High (SAH)
```

3. Define the ending address as one greater than the last address in the data block to be recorded. The ending address is to be loaded into locations:

```
17F7 = End Address Low (EAL)
17F8 = End Address High (EAH)
```

As an example, assume you wish to record a data block from address 0200 up to and including address 03FF. (All of Pages 2 and 3). You wish to assign an ID number of 06 to this block. Using the KIM-1 keyboard, you should load the data shown into the addresses indicated so that:

```
00F1 = 00 (Clear Decimal Mode)
17F5 = 00 (SAL)
17F6 = 02 (SAH)
17F7 = 00 (EAL) \
                        > = 03FF + 1
17F8 = 04 (EAH) /
17F9 = 06 (ID)
```


Note that the ending address must be greater than the starting address for proper operation.

4. Assuming that you are using a new cassette on which no data has been stored previously, insert the cassette in the unit and rewind the tape to its start position.
5. Select the starting address of the tape record program. This address is 1800.
6. Select the Play/Record mode of the audio unit and allow several seconds for the tape to begin to move.
7. Press the [GO] key and the recording process will begin. The display will be blanked for a period and then will relight showing 0000 xx. This means that the data block selected has been recorded.
8. You may now stop the tape or allow some additional seconds of blank tape and then stop the unit.

Loading Data From Audio Tape

The procedure for loading data from an audio tape into the KIM-1 memory requires that you perform the following steps:

1. Clear decimal mode by entering 00 in location 00F1. Define the ID number of the data block to be loaded from tape. The ID number is loaded into address 17F9.
2. Select the starting address of the Tape Load program. This address is 1873 HEX.
3. Press the [GO] key. The KIM-1 system is now waiting for the appearance of data from the tape unit.
4. Load the cassette and, presuming you do not know where on the tape the data block is recorded, rewind the tape to its starting position. Check the volume control setting.
5. Start the audio tape unit in its Play mode and observe that the tape begins to move.
6. Wait for the KIM-1 display to relight showing 0000 xx. This means the data block has been loaded successfully from the tape into the KIM-1 memory. If the display relights with FFFF xx, the correct data block has been found but there has been an error detected during the read operation. If the tape continues to run and the display never relights, the system has not been successful in finding the data block with the specific ID number you requested.

7. If in step (1), you had selected an ID = 00, the ID number recorded on the tape will be ignored and the system will read the first valid data block encountered on the tape. The data read from the tape will be loaded into memory address as specified on the tape.
8. If, in step (1), you had selected an ID = FF, the ID number recorded on the tape will be ignored and the system will read the first valid data block encountered on the tape. In addition, the data block will be loaded into successive memory locations beginning at the address specified in locations 17F5 and 17F6 (SAL, SAH) instead of the locations specified on the tape.

Special Operations with Audio Tape

The KIM-1 system causes data to be recorded on audio tape with a specific format as detailed in Appendix E. Each recorded data block is preceded by a group of synchronizing characters together with an identification code to define the specific block. Data blocks may be of arbitrary length.

With a little care, there is no reason for you not to include a number of recorded data blocks on the same tape. If you are recording blocks in sequence and have not rewound the tape between blocks, you need only specify the parameters of each new block (ID, SAL, SAH, EAH, EAL) and proceed with recording the new block.

If the tape has been rewound, you will need to know the ID number of the last recorded data block. Rewind the tape to its starting point and set up the parameters required to read the last recorded data block. After reading this block, stop the tape and you may now proceed to add a new block or blocks to the tape.

If you wish, you may add voice messages between the recorded data blocks on the tape. The KIM-1 system will ignore these audio messages when the tape is read back. Of course, you will need to install an earphone or speaker in parallel with the KIM-1 audio tape data input pin in order to hear the voice messages.

We do not recommend that you attempt to record data blocks in areas of the tape which have been used previously for recorded data. Variations in tape speed and block lengths can result in overlapping of recorded data which may be read incorrectly by the KIM-1 system.

4.3 USING A SERIAL TELEPRINTER

The addition of a serial teleprinter (such as the Teletype Model 33ASR) to work with the KIM-1 system permits a variety of special operations to be performed. In all cases, you define desired operations by depressing the proper keys while simultaneously producing a hard-copy printed record of each operation. If your teleprinter is equipped with a paper tape reader/punch, you may generate or read paper tapes using the KIM-1 system. Using the serial teleprinter, you may perform the following operations:

Select an Address

Type four hex keys (0 to F) to define the desired address. Next, press the [SPACE] bar.

The printer will respond showing the address code selected followed by a two digit hex code for data stored at the selected address location:

```
Type:          1234      [SPACE]
Printer Responds: 1234    AF
showing that the data AF is stored at location 1234.
```

Modify Data

Select an address as in the previous section. Now type two hex characters to define the data to be stored at that address. Next type the [.] key to authorize the modification of data at the selected address:

```
Type:          1234 [SPACE]
Printer Responds: 1234 AF
Type:          6D   [.]
Printer Responds: 1235 B7
Note that the selected address (1234) has been modified and the system
increments automatically to the next address (1235).
```

Note: Leading zero's need not be entered for either address or data fields: For example:

```
EF [SPACE] selects address 00EF
E [SPACE] selects address 000E
A [.] enters data 0A
[.] enters data 00 (etc.)
```

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Step to Next Address

Type [CR] to step to the next address without modifying the current address:

```
See Printed:      1234  AF
Type:             [CR]
Printer Responds: 1235  B7
Type:             [CR]
Printer Responds: 1236  C8      (etc.)
```

Step to Preceeding Address

Type [LF] to step back to the preceeding address:

```
See Printed:      1234  AF
Type:             [LF]
Printer Responds: 1233  9D
Type:             [LF]
Printer Responds: 1232  8E      (etc.)
```

Abort Current Operation

Type [RUB OUT] to terminate the current operation. The prompting message will be printed ("KIM") indicating that a new operation may proceed:

```
Type:          1264      [RUB OUT]
Printer Responds: KIM
```

	xxxx	xx	
Type:	1234		[SPACE]
Printer Responds:	1234	AF	

In the example, the [RUB OUT] key is used to correct an erroneous address selection.

Note: The [RUB OUT] key must be depressed after each depression of the KIM-1 reset key in order to allow the operating program to define the serial bit rate for the tele-printer.

Load Paper Tape

Paper Tapes suitable for use with the KIM-1 system are generated using the format shown in Appendix F. To read such a tape into the KIM-1 system, proceed as follows:

1. Load the punched paper tape on to the tape mechanism
2. Type [L]
3. Activate the paper tape reader

The paper tape will advance and data will be loaded into addresses as specified on the tape. A printed copy of the data read will be generated simultaneously with the reading of the paper tape.

Check-sums are generated during the reading of the paper tape and are compared to check-sums already contained on the tape. A check-sum error will cause an error message to appear in the printed copy.

Punch Paper Tape

The KIM-1 system can be used to punch paper tapes having the format described in Appendix F. The procedures for generating these tapes is as follows:

1. Define the starting address and ending address of the data block to be punched on the paper tape.
2. Load blank paper tape on the punch unit and activate the punch.

Type:			[1] [7] [F] [7] [SPACE]
See Printed:	17F7	xx	
Type:			[F] [F] [.]
See Printed:	17F8	xx	
Type:			[0] [3] [.]
See Printed:	17F9	xx	
Type:			[2] [0] [0] [SPACE]
See Printed:	0200	xx	

You have now loaded the ending address (03FF) into address locations 17F7 (EAL) and 17F8 (EAH). The starting address (0200) is selected as shown.

3. Now type [Q]

The paper tape will advance and punching of the data will proceed. Simultaneously, a printed record of the data will be typed.

List Program

A printed record of the contents of the KIM-1 memory may be typed. The procedure is the same as for punching paper tape except that the punch mechanism is not activated.

Execute Program

To initiate execution of a program using the TTY keyboard, the following procedures should be followed:

1. Enter the starting address of the program

2. Type [G]

For example, to begin program execution from address location 0200:

Type:	[2] [0] [0] [SPACE]
See Printed:	0200 xx
Type:	[G]

Program execution begins from location 0200 and will continue until the [ST] or [RS] keys of the KIM-1 module are depressed. The single step feature may be employed while in the TTY mode.

CHAPTER 5

LET'S TRY A REAL APPLICATION

It is not practical in this manual to describe every possible

application or Programming technique. However, now that you have become familiar with the basic elements and operating procedures of the KIM-1 system, this section will show you how to apply what you have learned in a simple but realistic application example.

Our example will involve the generation of a variable frequency square wave which will be connected to a speaker to produce an audible tone. The frequency of the tone will be selected using a set of seven toggle switches. We will proceed through the example by defining the interface, writing and entering the program, and executing the program. Finally, we will study a series of program debugging techniques which will be useful to you for any new program you may write.

5.1 DEFINING THE INTERFACE

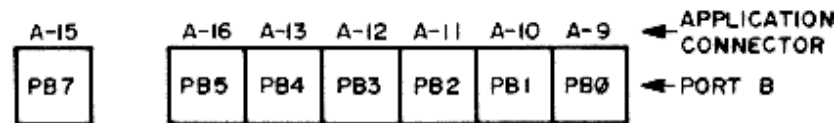
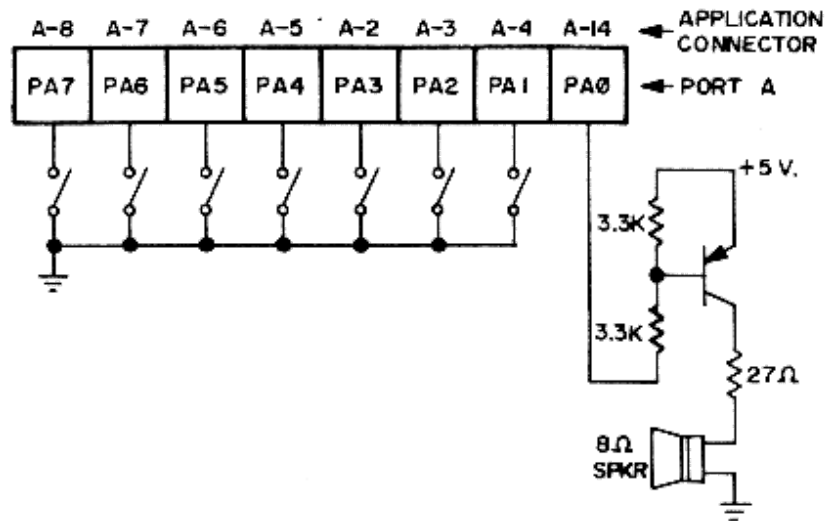
You will recall that a group of 15 I/O pins are brought to the Application connector from the 6530-003 array. The logic and circuit details concerning these I/O pins are described in Appendix H and in Section 1.6 of the Hardware Manual ("Peripheral Interface/Memory Device - - MCS 6530").

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For our application example we will use eight of these I/O pins. One pin (PA0) will be used as an output line to supply a square wave to a driver circuit and speaker. The other seven I/O pins (PA1 to PA7) are defined as input points with a SPST toggle switch connected to each. [Figure 5-1](#) shows the circuit configuration for this example. Note that the remaining seven I/O pins (the PB port) are not used for this problem.

For the switches connected to the input pins, we would like the sense of the switch to be defined as a logic "0" when open and a logic "1" when closed. By connecting the switches to ground, we are producing exactly the opposite sense and must remember to complement the switch states with software when we write our program. Also, we must define now that the switch at PA1 is to be the LSB (least significant bit) and the switch at PA7 is to be the MSB (most significant bit) of the seven bit binary word formed by all seven switches. In this way, the state of the switches can define a binary number from zero (all switches open) to 127_{DEC} (all switches closed).

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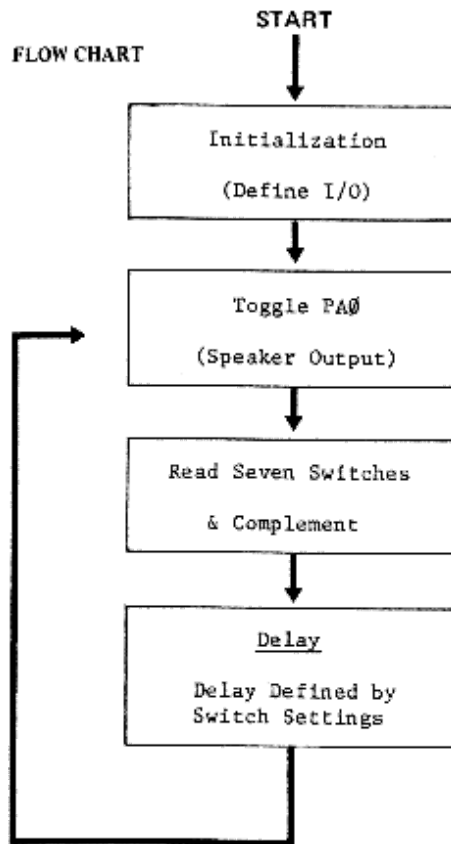
(THE B PORT IS NOT USED IN THIS EXAMPLE APPLICATION)

Speaker Application
FIGURE 5.1

5.2 WRITING THE PROGRAM

Having defined the interface for our application, we may proceed now to write our program. The effort proceeds in four stages:

1. Generate a flow chart
2. Generate assembly language code
3. Analyze the program
4. Generate machine language code



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Briefly, our flow chart shows a first step of system initialization. During this step, we must define the I/O configuration of the system in that pin PA0 becomes the output to the speaker and that pins PA1 to PA7 become inputs from the seven switches.

After initialization, a loop is set up which begins by inverting the state of PA0 (Toggle PA0). Next, the state of the switches is read and the data is complemented to produce the correct "sense" from the switches. The value so read is used to define a delay before returning to the start of the loop and again toggling the state of PA0. A little thought will show that this loop will produce a square wave with a frequency determined by the setting of the seven switches.

Assembly Language Program

Our next task is to convert the simple flow chart into a program. The program is first written in "Assembly Language". You should refer to your Programming Manual to become familiar with all of the possible 6502 instructions (especially see [Appendix B](#); Instruction Summary). [Figure 5-2](#) shows the application example programmed in assembly language.

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LABEL	OPCODE	OPERAND	MACHINE CYCLES	COMMENTS
INIT	LDA	#\$01	2	Define I/O 0=Input 1=Output
	STA	PADD	4	PADD PORT A DATA DIRECTION REG.
START	INC	PAD	6	Toggle PA0, PA1-PA7 Inputs not affected
READ	LDA	PAD	4	READ switches into accumulator
	EOR	#\$FF	2	Complement switch value
	LSR	A	2	Shift Accumulator 1 bit to right
	TAX		2	Transfer final count into X-Index
DELAY	DEX		2	Delay by an amount specified
	BPL	DELAY	3,2	By the count in the X-Index
	BMI	START	3	Go To START
PADD	=\$1701			Define absolute address of Data Direction Reg. A
PAD	=\$1700			Define absolute address of Data Reg. A

Assembly Language Listing
FIGURE 5.2

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You will note that each line of the program is broken into several fields:

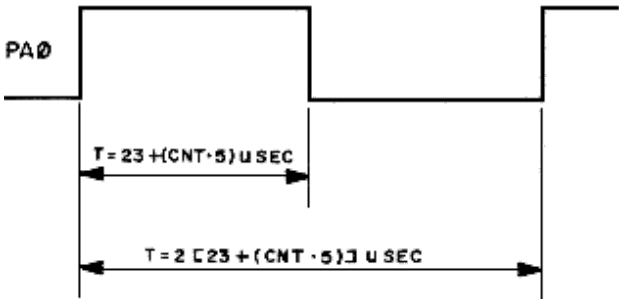
- A label field permitting you to assign a "name" to a specific location in the program.
- An Operation Code field (Op Code) in which the exact instruction to be executed is defined.
- An Operand Field where the exact data required by the instruction is defined together with certain symbols defining addressing modes or data formats. Symbols encountered generally in MOS Technology, Inc. manuals are:
 - # Immediate Addressing
 - \$ Hex Code
 - @ Octal Code
 - % Binary Code
 - ' ASCII literal
 - = Equates a label to a value
- A Machine Cycle field defining the total number of machine cycles required to execute an instruction. (This information is derived from Appendix B of the Programming Manual).
- A Comment Field where the programmer may define the intent of specific program steps.

Program Analysis

The inclusion of the "machine cycle" information of the program chart ([Figure 5-2](#)) allows us to analyze the exact timing relationships

involved in our program example. Note that the KIM-1 system operates from a fixed frequency (1 MHz) oscillator with each machine cycle being 1 μ s. Therefore, an instruction like "INC PAD" which requires 6 machine cycles will be executed in a 6 μ s period.

By counting the total machine cycles occurring between each toggle of PA0, an equation for the square wave frequency can be developed. The actual frequency is determined by the position of the seven switches, the number of machine cycles between each toggle of PA0, and the basic clock rate (1 MHz) of the KIM-1 system. [Figure 5-3](#) shows the waveform of the PA0 square wave and the derived equations for computing the exact frequency.



$$FREQ = \frac{1}{T} = \frac{10^6}{46 + 10 \cdot CNT} \text{ CPS}$$

NOTE: CNT EQUALS THE VALUE IN X-INDEX
WHICH WAS CALCULATED FROM THE
SEVEN SWITCHES $0 \leq CNT \leq 127$

Square Wave Output
FIGURE 5.3

Machine Language Coding

Our next problem is to convert our assembly language program into a program written in "machine language". The quickest and most foolproof method for accomplishing this conversion is by using the MOS Technology, Inc. Assembler (available for use on the time share services of United Computing Systems, Inc.). If you choose not to use this method, you will need to convert your source program to machine code using "paper-and-pencil" techniques.

You should proceed by constructing a table similar to that shown in [Figure 5-4](#).

	INSTRUCTION	SOURCE CODE
--	-------------	-------------

ADDRESS	BYTE 1	BYTE 2	BYTE 3	LABEL	OP CODE	OPERAND
0200	A9	01		INIT	LDA	#\$01
0202	8D	01	17		STA	PADD
0205	EE	17		START	INC	PAD
0208	AD	17		READ	LDA	PAD
020B	49	FF			EOR	\$\$FF
020D	4A				LSR	A
020E	AA				TAX	
020F	CA			DELAY	DEX	
0210	10	F0			BPL	DELAY
0212	30	F1			BMI	START
0214						

Machine Language Code Table
FIGURE 5.4

The source code contained in your assembly language program ([Figure 5-2](#)) is entered into the table first. A column is provided to allow you to define the specific address at which an instruction is located. The Instruction column provides space for defining one, two, or three byte instructions. (Please refer to Appendix B of the Programming Manual or to your Programming Card for specific Op Codes).

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As an example, the first source instruction is LDA #\$01 which, when translated, means load the accumulator with the byte stored in the next program location (hex 01). This is the "immediate" addressing mode defined by the "#" symbol. The Op Code for LDA# is A9. This value is entered in the first column under the heading, Instruction. The next column contains the hex 01 value defined by the source statement. The initial address for the program is inserted in the "Address" column as 0200 (an arbitrary selection). The total instruction LDA #\$01 now occupies address locations 0200 and 0201.

The next available address is 0202 which is inserted in the "Address" column for the next source instruction. In this manner, you will proceed through all of the source statements decoding each and entering one, two, or three bytes of machine code as required in the "Instruction" column. The "Address" column will contain the address of the first byte of machine code (the Op Code) for each source statement.

In cases where the operand of the source statement is a symbol, the address to which the symbol has been equated should be filled in as the proper machine code. For example, the source statement "INC PAD" requires the incrementing of data stored at a location "PAD" defined in our assembly programs to have the address: PAD = 1700. Therefore, the address 1700 is entered as the second and third bytes of the source statement "INC PAD". (See [Figure 5-4](#)). Note also that when entering an address, such as 1700, the low order byte (00) is entered first and immediately after the Op Code and the high order byte (17) is entered next as the third byte of the instruction.

When dealing with branch instructions (BPL, BMI, etc.), you will need to calculate the exact value of the offset which may be either positive (branch forward) or negative (branch backward). You should refer to Section 4.1.1 of the Programming Manual to explore "Basic Concept of Relative Branching." As an example, the source statement "BMI START" (See

[Figures 5-2](#) and [5-4](#)) requires a branch backward by (-15) locations to the address labelled "START" (from address 0213 backward to 0205 inclusive).

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(The 2's complement of the -15 displacement is F1 HEX which you should insert at location 0212). Had the branch been to a forward location the positive value of the offset would be inserted rather than the 2's complement value.

5.3 ENTERING THE PROGRAM

With the program now reduced to machine language code, you may enter the program address and data codes listed in [Figure 5-4](#) following the procedures detailed in Section 2.4. The procedure for entering the program is as follows:

<u>Press Keys</u>	<u>See On Display</u>
[AD] [0] [2] [0] [0]	0200 xx
[DA] [A] [9]	0200 A9
[+] [0] [1]	0201 01
[+] [8] [D]	0202 8D
[+] [0] [1]	0203 01
[+] [1] [7]	0204 17
[+] [E] [E]	0205 EE
[+] [0] [0]	0206 00
[+] [1] [7]	0207 17
[+] [A] [D]	0208 AD
[+] [0] [0]	0209 00
[+] [1] [7]	020A 17
[+] [4] [9]	020B 49
[+] [F] [F]	020C FF
[+] [4] [A]	020D 4A
[+] [A] [A]	020E AA
[+] [C] [A]	020F CA
[+] [1] [C]	0210 1C
[+] [F] [D]	0211 FD
[+] [3] [0]	0212 30
[+] [F] [1]	0213 F1

Key Sequences: Enter Program
FIGURE 5.5

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5.4 EXECUTING THE PROGRAM

With the program entered, you may proceed to program execution. First, if the NMI vector has not been defined previously, enter the vector as follows:

<u>Press Keys</u>	<u>See Displayed</u>
[AD] [1] [7] [F] [A]	17FA xx
[DA] [0] [0]	17FA 00
[+] [1] [C]	17fb 1C

This procedure insures that the [ST] key will be effective in terminating the program. Now, select the starting address of your program (0200) and begin execution as follows:

<u>Press Keys</u>	<u>See Displayed</u>
[AD] [0] [2] [0] [0]	0200 xx
[GO]	(DARK)

The program will now execute. If your seven selector switches all are open, you will probably hear no sound from the speaker because the square wave frequency is too high. If all selector switches are closed, you will hear in the speaker the lowest frequency that can be generated with the program as currently written. You may experiment with other combinations of switch settings to hear a variety of tones from the speaker.

Depression of the [ST] key will cause the program execution to stop (the tone will terminate) and the KIM-1 display will relight. The display will show the address and data for the next instruction to be executed (probably 020F or 0210 since this is the delay loop where the program spends most of its running time).

5.5 PROGRAM DEBUGGING AND MODIFICATION

If your program did not execute correctly, you would follow a debugging procedure involving the following steps:

Step 1: List the Program

First make sure you have entered the program steps correctly. Select the starting address ([AD] [0] [2] [0] [0]) and observe that the correct data (A9) is displayed. Now, using the [+] key, step through the remaining program locations checking for the correct data stored in each location.

Step 2: Single Step the Program

Follow the procedures listed in Section 5-4 for program execution but before depressing the [GO] key, place the SST slide switch in the ON position. Now, press the [GO] key and the first instruction will be executed. The display will relight indicating that the operating program is again in control of the system. The address displayed will be the address of the first byte of the next instruction to be executed. You may press the [GO] key again to execute the next instruction or you may choose to investigate changes in the contents of machine registers stored in selected memory locations (See [Figure 3-13](#)). The procedure detailed in [Figure 5-6](#) gives a good indication of the various operations you may wish

to perform in the SST mode.

Step 3: Check the I/O Operations

If program entry has been verified and program execution in the SST mode appears to be normal, you may wish to verify the correct operation of your specific I/O configuration.

You should recall that writing to or reading from any I/O port is the same as reading from or writing to any other memory location in the system. Therefore, if you select the address of an I/O port, the KIM-1 display will show you the hex code for the data being read from that address and thus, directly indicate the state of each I/O pin in the port. For example, the

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address of the I/O port used for your sample program is 1700. Press [AD] [1] [7] [0] [0] and the display will show the hex code corresponding to the settings of your selector switches. If you change the positions of your selector switches, you will see the hex code change in the data field of the display.

Now, leave the same address (1700) selected and press the [DA] key. If you press any of the hex keys [0] to [F] you will write the data to the I/O port (1700). Since seven of the pins of this I/O port are defined as inputs, only one (PA0) will act as an output and will respond to the data entered by you from the keyboard. Try alternating rapidly between the [0] and [1] keys and you should hear clicking in the speaker indicating that you are successfully toggling the PA0 pin.

This concept of using the KIM-1 keyboard and display to exercise and verify the operation of I/O ports is a generally useful technique for debugging the hardware portions of most specific applications.

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<u>Press Keys</u>	<u>See On Display</u>	<u>Comments</u>
[AD] [0] [2] [0] [0]	0200 A9	Select first instruction address
<u>SST</u> <u>X</u> ON	0200 A9	Set SST to ON; All selector switches open
[GO]	0202 8D	Accumulator now loaded with \$01
[GO]	0205 EE	PADD now loaded
[GO]	0208 AD	PA0 now toggled
[GO]	020B 49	Switch values (PA1-PA7) now loaded
[GO]	020D 4A	Accumulator now complemented

[GO]	020E AA	Accumulator now right shifted 1 Bit
[AD] [0] [0] [F] [3]	00F3 xx	Display Accu
[+]	00F4 xx	Display Y - INDEX
[+]	00F5 00	Display X - INDEX
[PC]	020E AA	Restore PC (TAX will execute next)
[GO]	020F CA	Accumulator now loaded in X-INDEX
[AD] [0] [0] [F] [3]	00F3 00	Display Accumulator
[+]	00F4 xx	Display Y-INDEX
[+]	00F5 00	Display X-INDEX (A=0->X)
[PC]	020F CA	Restore PC
[GO]	0210 10	DEX now completed
[AD] [0] [0] [F] [5]	00F5 FF	Display X-INDEX (X<0)
[PC]	0210 10	Restore PC
[GO]	0212 30	No branch (Result of DEX <u>not</u> positive)
[GO]	0205 EE	Branch (Result of DEX <u>is</u> negative).

SST Mode: Sample Operation
FIGURE 5.6

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BLANK

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CHAPTER 6

EXPANDING YOUR SYSTEM

In earlier sections you have learned that the MCS 6502 Microprocessor Array is capable of directly addressing up to 65,536 locations (bytes) of memory. (Usually abbreviated to 65K where "1K" for the remainder of this section is to mean 1024 memory locations). In this section, we will discuss first the techniques for adding memory or I/O locations to the system and next, the proper handling of interrupt vectors in an expanded system.

6.1 MEMORY AND I/O EXPANSION

In the KIM-1 system, the management of input/output data is handled exactly the same as transfers to or from any other memory location in the system. There are no instructions dealing specifically with input/output transfers. Instead, transfer of data is accomplished by reading from or writing to registers connected to the data bus and to I/O pins in specific I/O interface devices (such as the 6530 array). These registers have a

specific address in the system just as does any other memory location. Therefore, when we speak of expanding the memory of the KIM-1 system, we are defining the methods for expanding both the real memory (RAM, ROM, PROM, etc.) as well as the I/O ports since they are both treated exactly alike as far as address assignments are concerned.

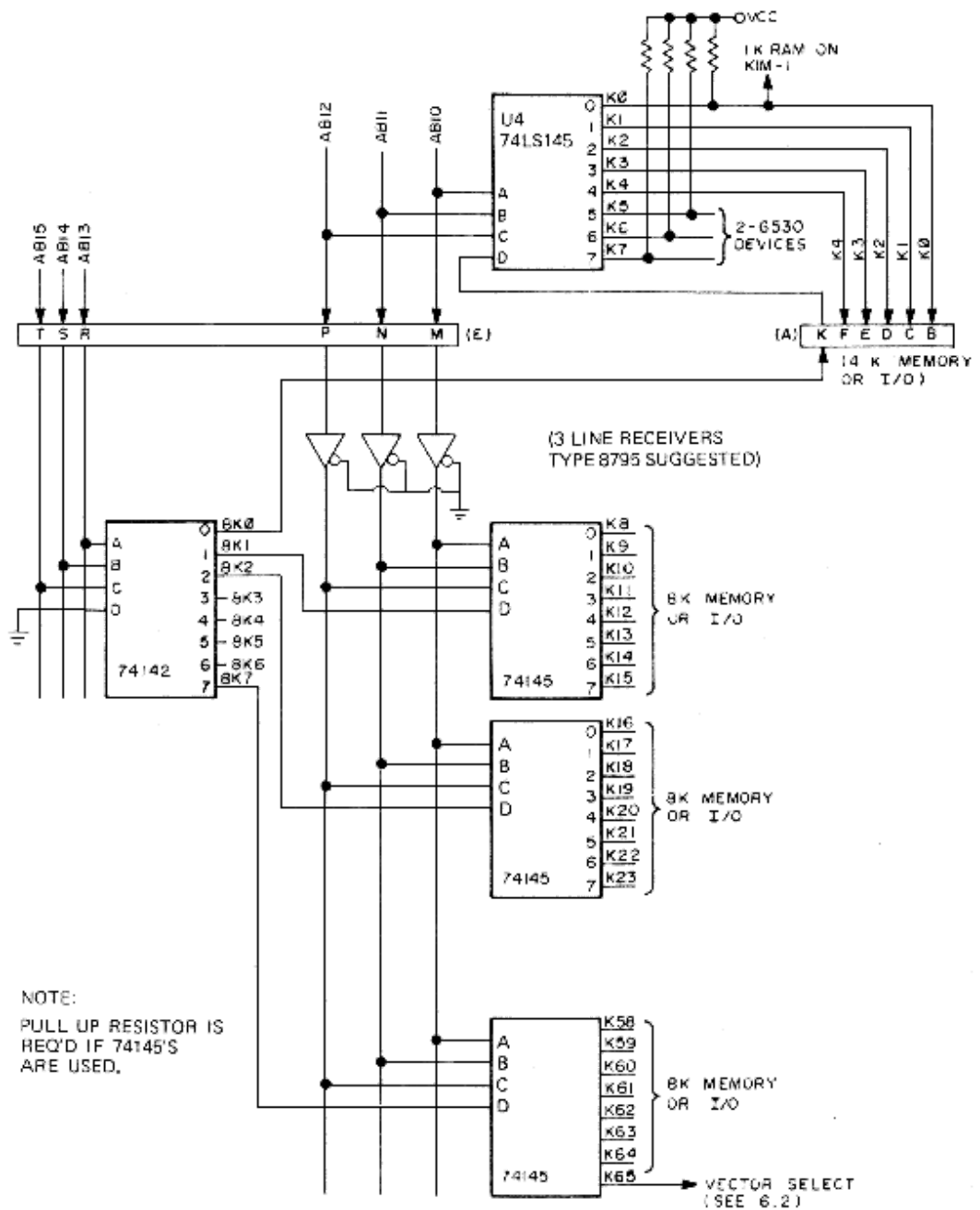
The first and most easily implemented memory expansion is the addition of up to 4K of memory space. You will recall that the lowest 8K memory locations are defined by an address decoder included on the KIM-1 module, (Device U4 on the schematic). The eight outputs of this decoder (K0 to K7) each define a 1K block of addresses in the lowest 8K of the memory map. Three of the outputs (K5, K6, K7) are used to select ROM, RAM, I/O and Timer locations on the two 6530 arrays while a fourth (K0) is used to select the 1024 locations of the static RAM memory. The remaining four outputs (K1, K2, K3, K4) are not used on the KIM-1 module but instead, are brought out to the Expansion connector for use as chip selects for memory or I/O additions.

[Figure 6-1](#) shows the proper method for deriving the four chip select signals for the additional 4K of memory. Note that one of input pins of the decoder (D) was brought out to the Application Connector. It was this pin which we asked you to connect to ground in Chapter 2 of this manual. As long as this point remains connected to ground, the decoder will always select the lowest 8K addresses of the memory field regardless of the state of AB13, AB14, and AB15.

If you wish to expand the memory and I/O address space beyond the lower 8K addresses, you must arrange to de-select the lower 8K memory block while selecting some other 8K block. One suggested method for expanding beyond the lower 8K space is shown in [Figure 6-2](#).

Note that the three high order address bits (AB13, AB14, AB15) are connected to a decoder. The eight outputs of the decoder act to divide the total 65K memory space into eight blocks of 8K each (8K0, 8K1, etc.). Now, the 8K0 output may be returned as the fourth input (D) to the decoder (U4) on the KIM-1 module causing the proper selection and de-selection of this block within the total address space. The remaining seven outputs (8K1 to 8K7) may be used to select and de-select the additional decoders shown in [Figure 6-2](#). You need add only as many decoders (one for each 8K block of memory) as you need for your desired memory expansion.

A word of caution is in order when you decide to add memory to your system. You have noticed the inclusion of the line receivers for the AB10, AB11, and AB12 signals, ([See Figure 6-2](#)). These devices are included because of loading limitations placed on the address bus lines of the 6502 array (Each such line is capable of driving one standard TTL load and 130pf of capacity. See [Appendix G](#)).



Before deciding how to expand your system, we recommend a careful study of all of the loading limitations of the KIM-1 signals since almost certainly you will require additional buffering circuits if correct operation is to be achieved.

6.2 INTERRUPT VECTOR MANAGEMENT

We have referred several times in earlier sections to the interrupt features of the 6502 Microprocessor Array. We suggest now a careful

reading of Section 9 of the Programming Manual for the subject "Reset and Interrupt Considerations".

In summary, there are three possible types of interrupt: Reset, NMI, and IRQ. Each will occur in response to an activation of one of the three pins of the 6502 array (RST, NMI, IRQ). In response to these inputs, the 6502 array will fetch the data stored at a specific pair of addresses and load the data fetched into the program counter. The addresses are hardware determined and not under the control of the programmer. The specific addresses for each type of interrupt are:

FFFA, FFFB - NMI Vector
FFFC, FFFD - RST Vector
FFFE, FFFF - IRQ Vector

You will note that these addresses define the highest six locations in the 65K memory map.

In the KIM-1 system, three address bits (AB13, AB14, AB15) are not decoded at all. Therefore, when the 6502 array generates a fetch from FFFC and FFFD in response to a RST input, these addresses will be read as 1FFC and 1FFD and the reset vector will be fetched from these locations. You now see that all interrupt vectors will be fetched from the top 6 locations of the lowest 8K block of memory which is the only memory block decoded for the unexpanded KIM-1 system.

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It is typical in any system to store the interrupt vectors in ROM so that they are immediately available after power-on. However, it is desirable that for the NMI and IRQ interrupts, the programmer be allowed to define as a variable the exact vector to which these interrupts will direct the system. Accordingly, the NMI and IRQ vector locations contain an indirect jump instruction referencing a RAM location into which the programmer will store the specific vector for the two types of interrupt. In the KIM-1 system, locations 17FA and 17FB contain the actual NMI vector and 17FE with 17FF contain the actual IRQ vector. The RST vector is not handled in this manner and always directs the system to the first step of the power-on initialization routine.

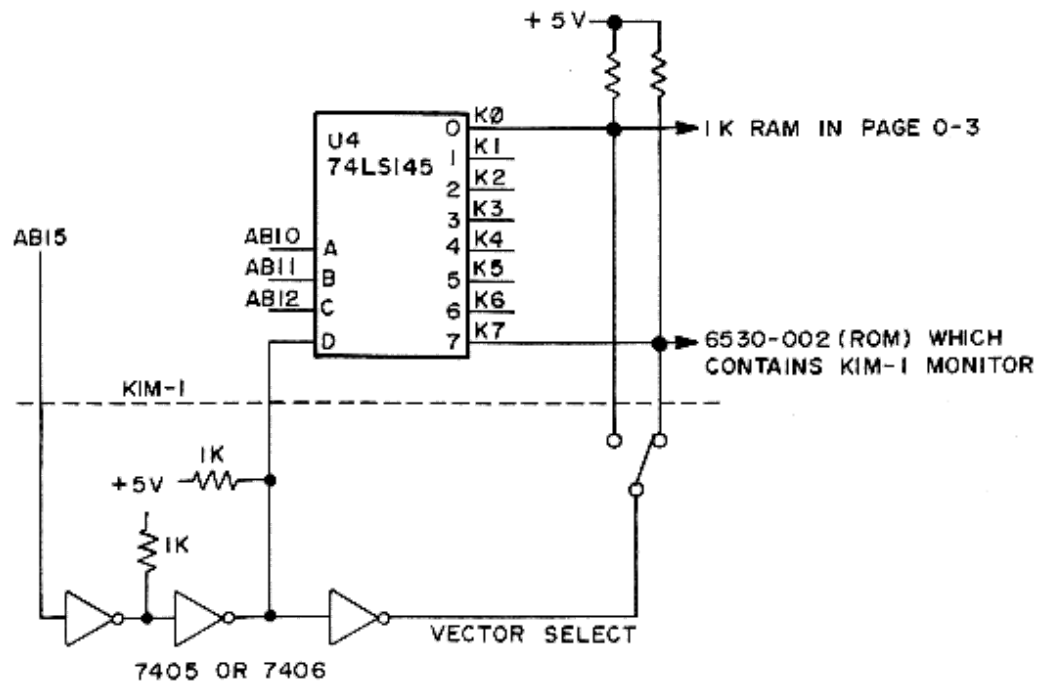
But what happens if we expand our memory above the lowest 8K block included in the KIM-1 system? Recall that we now must use AB13, AB14, and AB15 to decode the additional address locations of the memory. By so doing, the interrupt vector locations are no longer located in the K7 memory block since the decoder (U4) is de-selected in response to the addresses generated by the 6502 array in fetching the interrupt vectors (FFFA for example). We would have the same problem even in an unexpanded system if we wished to use a RST vector and initialization routine different than what the KIM-1 system provides and if the RST vector was to be located in a 1K block lower than K7 (K0 for instance).

The solution to this dilemma is to generate logically a special signal for interrupt select. Referring to [Figure 6-2](#), a special signal called "Vector Select" is created to define the highest 1K memory block (K65). The fetch of any interrupt vector will cause this signal to go low "Select". Assuming that the K65 state is not used to select RAM, this signal may be "wire-or'd" with any one of the other "K" signals (K0 to K64) to define exactly which 1K block is to contain the interrupt vectors.

As an example, assume that you have connected the K65 "Vector Select" line to the K0 line. When a RST occurs, the 6502 array generates a fetch from locations FFFC and FFFD. These addresses cause K65 to be selected which, in turn, accesses the K0 field of the memory and causes the actual fetch of the RST vector from locations 03FC and 03FD. (Had you chosen to connect K65 to K7, the fetch of the reset vectors would occur from locations 1FFC and 1FFD).

In this way, the highest six addresses of any 1K block of memory may be used to supply the interrupt vectors for the system. If desired, a switch could be installed to allow you to select different areas of memory as the source locations for the interrupt vectors. (By the way, we selected the 75145 type decoders in [Figure 6-2](#) specifically to allow the "wire-or" of K65 with any other K. This is possible because the 75145 decoder is provided with open-collector outputs which allows "wire-or" of several states using an external load resistor.)

An even simpler arrangement using the "Vector Select" approach is shown in [Figure 6-3](#). Here, the KIM-1 system is assumed to have only the lower 8K of memory in place. The address decoder (U4) is de-selected using the AB15 signal which becomes "true" whenever an interrupt vector fetch is initiated by the system. The same signal (AB15) is inverted and "wire-or'd" through a switch to the K0 or the K7 chip select lines. Now, depending upon the position of the switch, interrupt vectors will be fetched from the top 6 addresses of either block K0 or K7. K0 in the KIM-1 system is the RAM and K7 is the ROM in the 6530-002 array (the operating program). In this way, you may have two different sets of interrupt vectors in your system and may select which set is to be used with a simple switch.



Vector Selection
FIGURE 6.3

CHAPTER 7

WARRANTY AND SERVICE

Should you experience difficulty with your KIM-1 module and be unable to diagnose or correct the problem, you may return the unit to MOS Technology, Inc. for repair.

7.1 IN-WARRANTY SERVICE

All KIM-1 series Microcomputer Modules are warranted by MOS Technology, Inc. against defects in workmanship and materials for a period of ninety (90) days from date of delivery. During the warranty period, MOS Technology, Inc. will repair or, at its option, replace at no charge components that prove to be defective provided that the module is returned, shipping prepaid, to:

KIM Customer Service Department
MOS Technology, Inc.
950 Rittenhouse Road
Norristown, Pennsylvania 19401

This warranty does not apply if the module has been damaged by accident or misuse, or as a result of repairs or modifications made by other than authorized personnel at the above captioned service facility

No other warranty is expressed or implied. NOS Technology, Inc. is not liable for consequential damages.

7.2 OUT-OF-WARRANTY SERVICE

Beyond the ninety (90) day warranty period, KIM modules will be repaired for a reasonable service fee. All service work performed by MOS Technology, Inc. beyond the warranty period is warranted for an additional ninety (90) day period after shipment of the repaired module.

7.3 POLICY ON CHANGES

All KIM series modules are sold on the basis of descriptive specifications in effect at the time of sale. MOS Technology, Inc. shall have no obligation to modify or update products once sold. MOS Technology, Inc. reserves the right to make periodic changes or improvements to any KIM series module.

7.4 SHIPPING INSTRUCTIONS

It is the customer's responsibility to return the KIM series module with shipping charges prepaid to the above captioned service facility.

For in-warranty service, the KIM module will be returned to the customer, shipping prepaid, by the fastest economical carrier.

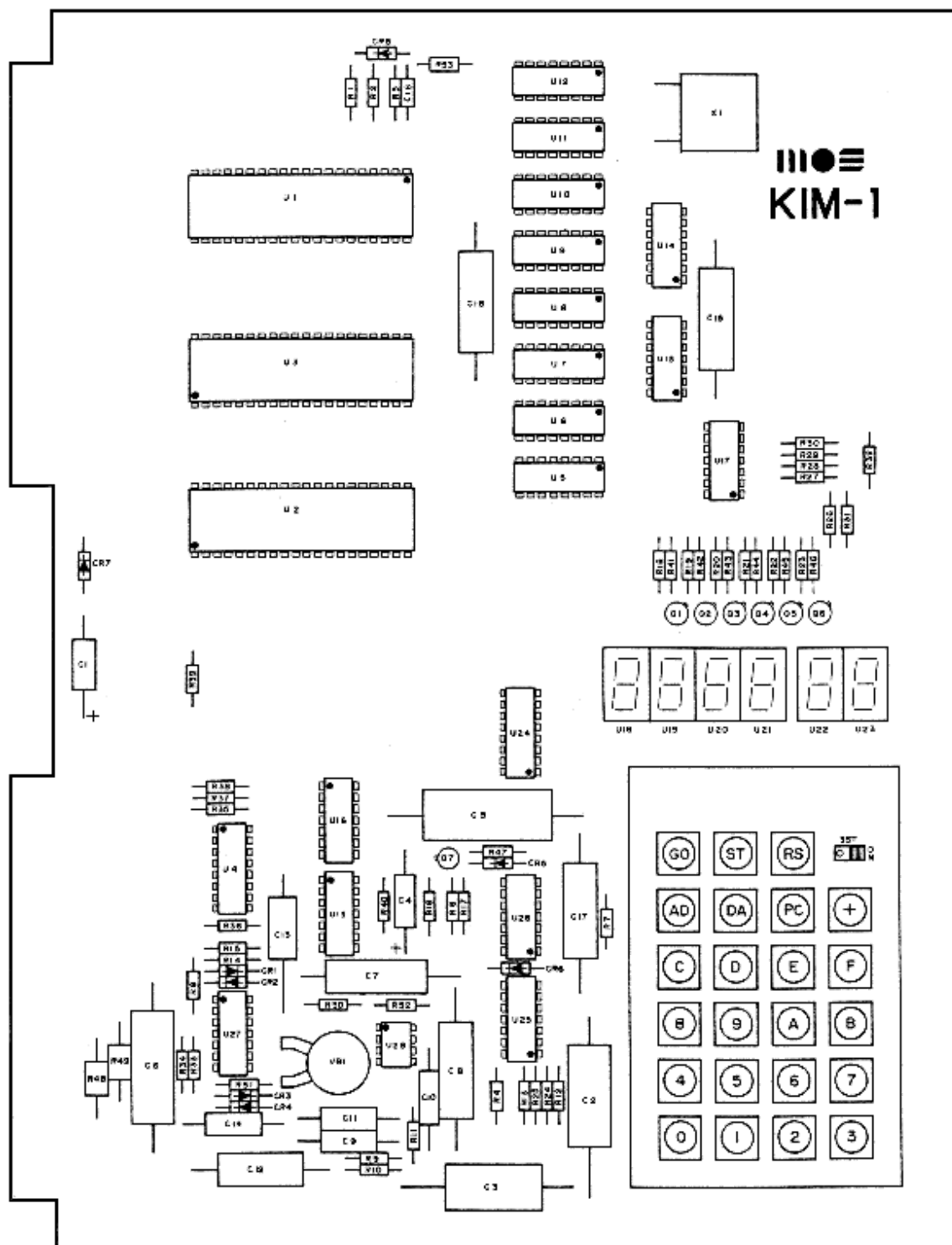
For out-of-warranty service, the customer will pay for shipping charges both ways. The repaired KIM module will be returned to the customer C.O.D. unless the repairs and shipping charges are prepaid by the customer.

Please be certain that your KIM module is safely packaged when returning it to the above captioned service facility.

APPENDIX A

ITEM	PART	QTY.	DESCRIPTION
1.	U1	1	6502 Microprocessor
2.	U2	1	6530 ROM RAM I/O Chip-02
3.	U3	1	6530 ROM RAM I/O Chip-03

4.	U5 through U12	8	6102 RAM 500ns Acc,0ns
5.	U18 through U23	6	7 SEG .3" Red Display
6.	U25	1	556 Timer IC
7.	U27	1	565 Phase Lock Loop
8.	U28	1	311 Comparator
9.	U24	1	74145 BCD Decoder IC
10.	U13 & U14	2	74125 TRI STATE Buffer
11.	u15	1	7400 Quad Nand IC
12.	U16	1	7404 Hex Inverter IC
13.	U17	1	7406 Hex Inv. O/C IC
14.	U26	1	7438 Quad Nand O/C IC
15.	CR1,2,3,4,&8	5	20 mA. 50v Diode - 1N914
16.	CR5, CR6	2	1A 50v Diode - 1N4001
17.	CR7	1	6.2v ½w Z. Diode - 1N4735
18.	Q7	1	NPN Transistor B>20, VCE>12 - 2N5371
19.	Q1 through Q6	6	PNP Transistor B>20, VCE>6 - 2N5375
20.	Ø4 & Ø5	2	47K ±10% ¼w Resistor
21.	R1,2,3,4, & 6	5	3.3K ±10% ¼w Resistor
22.	R34 & P5Ø	2	2.2K ±10% ¼w Resistor
23.	R12-R17, R41-R46	12	1.0K ±10% ¼w Resistor
24.	R35 through R4Ø	6	560Øhm ±10% ¼w Resistor
25.	R18-R23, R47	7	220Øhm ±10% ¼w Resistor
26.	R33	1	470hm ±10% ¼w Resistor
27.	R52	1	5 Meg. ±10% ¼w Resistor
28.	R51	1	30K ±5% ¼w Resistor
29.	R7,R8,R9,R1Ø&R11	5	10K ±5% 1/4w Resistor
30.	R48, R49	2	150 ±5% Ø
31.	R26 through R32	7	820hm ±Ø5%
32.	VR1	1	5K Potentiometer
33.	C2, C3, C6	3	.22±10% uf.>12 wv. cap
34.	C1, C4	2	1uf+8Ø-10%>12WV Cap
35.	CS	1	.33 uf±10%>12WV Cap
36.	C7,C8,C15,C16,C17	5	.1uf+8Ø-10%>12WV Cap
37.	C9, C1Ø, C11	3	.ØØ68uf±10%>12WV
38.	C12	1	.Ø47uf±10%>12WV
39.	C13	1	.Ø22uf±10%>12WV
40.	C14	1	.ØØ1uf±10%>12WV
41.		1	44 Pin Edge Conn. (Vector #R644)
42.	X1	1	1 MHz XTAL
43.		1	PCB.
44.		1	24 Key KBD
45.		6	Rubber Pads
46.		1	Shipping Bag (Static Free)
47.		1	Shipping Box
48.		1	Hardware Manual
49.		1	Software Manual
50.		1	KIM Manual
51.		1	Warranty Card
52.		1	Wall Chart
53.		2	#2 x ¼ SS Screws (Keyboard)
54.		1	Program Card
55.	C18	1	1Øpf CAP
56.	R53	1	330K ¼w Resistor
57.	U4	1	74L5145 BCD Decoder 1C



B-1

APPENDIX C

IN CASE OF TROUBLE

SYMPTOM: Display Not Lit

1. Test +5 volt power supply. Using a VOM check for +5 volts between Pin E-21 and E-22. Also check for +5 volts between Pin A-A and Pin A-1. KIM-1 power supply should be set at +5v \pm 5%.
2. Test KB/TTY option wiring ([Figure 2-4](#)). Pin A-21 should not be connected to Pin A-V.
3. Make sure decoder is enabled. See [Figure 2-2](#) and insure that Pin A-K is connected to ground.
4. Depress the reset key and check all other keys to insure that no key is stuck.
5. Place a VOM between Pin E-21 (+5v) and Pin E-7 (Reset). Alternately depress and release the reset key checking to see if the voltage swings from (>4v) to (<1v).
6. Test Pin E-V (è2) with an oscilloscope and insure 1 MHz operation.

SYMPTOM: Cannot Dump to Audio Tape
Cannot Load From Audio Tape

1. Test +12 volt power supply. Using a VOM check for +12 volts between Pin A-N (+12v) and Pin A-1 (GND). Set power supply to +12v \pm 5%. (See [Figure 2-2](#)).
2. Check volume control on the tape recorder (Set at half way point).

C-1

3. Make sure that you are using the proper tape output pin. See [Figure 2-3](#).
4. Check the tape interface circuit by disconnecting the tape recorder and shorting Pin A-P (Audio Out High) to Pin A-L (Audio In). Set up KIM-1 monitor to dump a section of memory. Using an oscilloscope observe data at Pin E-X (PLL TEST). See Appendix E for correct data format and calibration procedure.
5. Record voice on a section of tape and play it back to insure that the tape recorder is working. Connect another tape recorder to the system or try another cassette.
6. Make sure Status Register (Location 00F1) has been loaded with data value "00".
7. Make sure Tone Control is set to High.

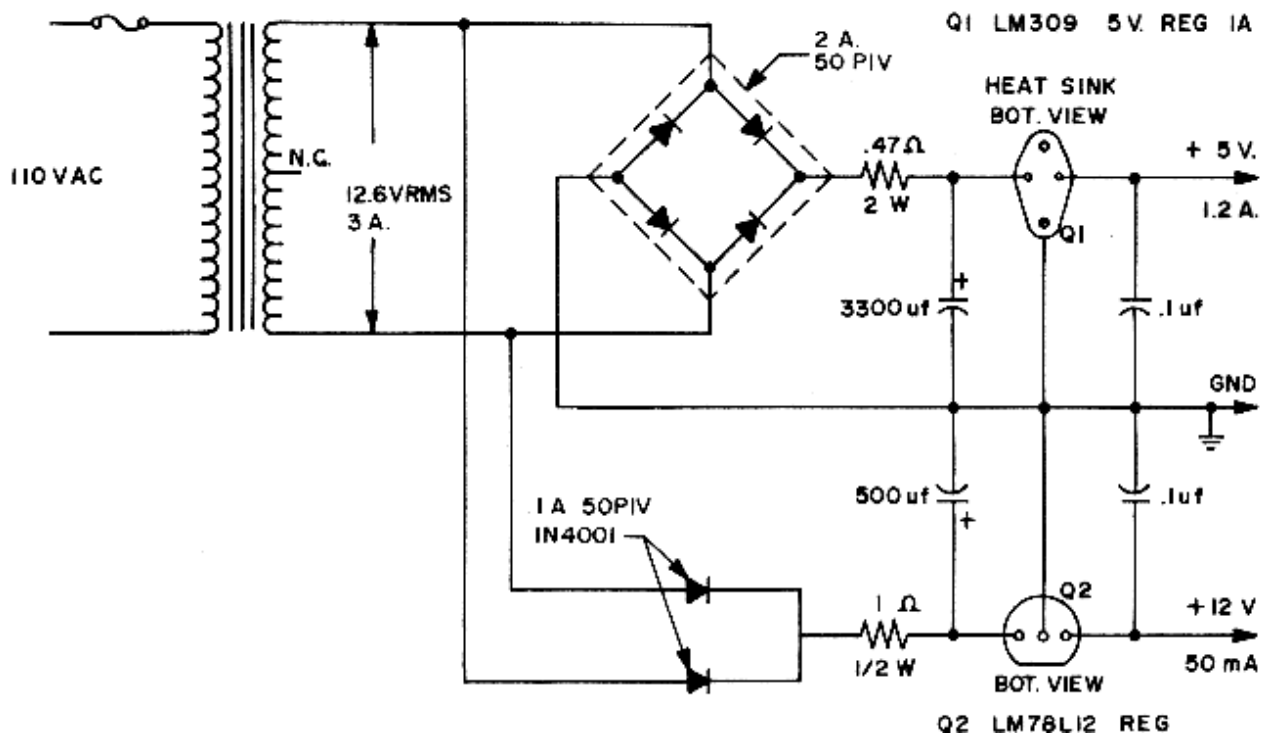
SYMPTOM: TTY Interface Problems

1. Make sure that Pin A-21 is connected to Pin A-V ([Figure 2-4](#)) to allow TTY operation.

2. Compare the connections on [Figure 2-4](#) with interface schematics in your TTY manual (or any other serial teleprinter).
3. Depress the reset key on the KIM-1 keyboard followed by a rub out character from the TTY.

C-2

APPENDIX D



Suggested Power Supply

D-1

APPENDIX E

AUDIO TAPE FORMAT

Data is stored out onto your audio cassette recorder in a specific format designed to insure an error free recovery. In the unlikely event

that a playback error does occur, several "ERROR DETECTION" methods are incorporated to warn you of this condition.

Data is transmitted to the tape recorder in the form of serial "ASCII" encoded characters (seven data bits plus Parity bit). Data retrieved from the memory is converted into this form by separating each byte into two half bytes. The half bytes are then converted into their ASCII equivalents.

Each record transmitted begins with a leader of one hundred "SYN" characters (ASCII 16) followed by a * character (ASCII 2A). During playback, this pattern allows your micro-computer to detect the start of a valid data record and synchronize to the serial data stream. Following the *, the record identification number (ID), and starting address low (SAL) and the starting address high (SAH) are transmitted. The data specified by the starting (SAL, SAH) and ending limits (EAL, EAH) is transmitted next followed by a "/" character (ASCII 2F) to indicate the end of the data portion of the record. Following the "/" two "CHECK-SUM" bytes are transmitted for comparison with a calculated check-sum number during playback to further insure that a proper data retrieval has taken place. Two "EOT" characters (ASCII 04) mark the end of record transmission.

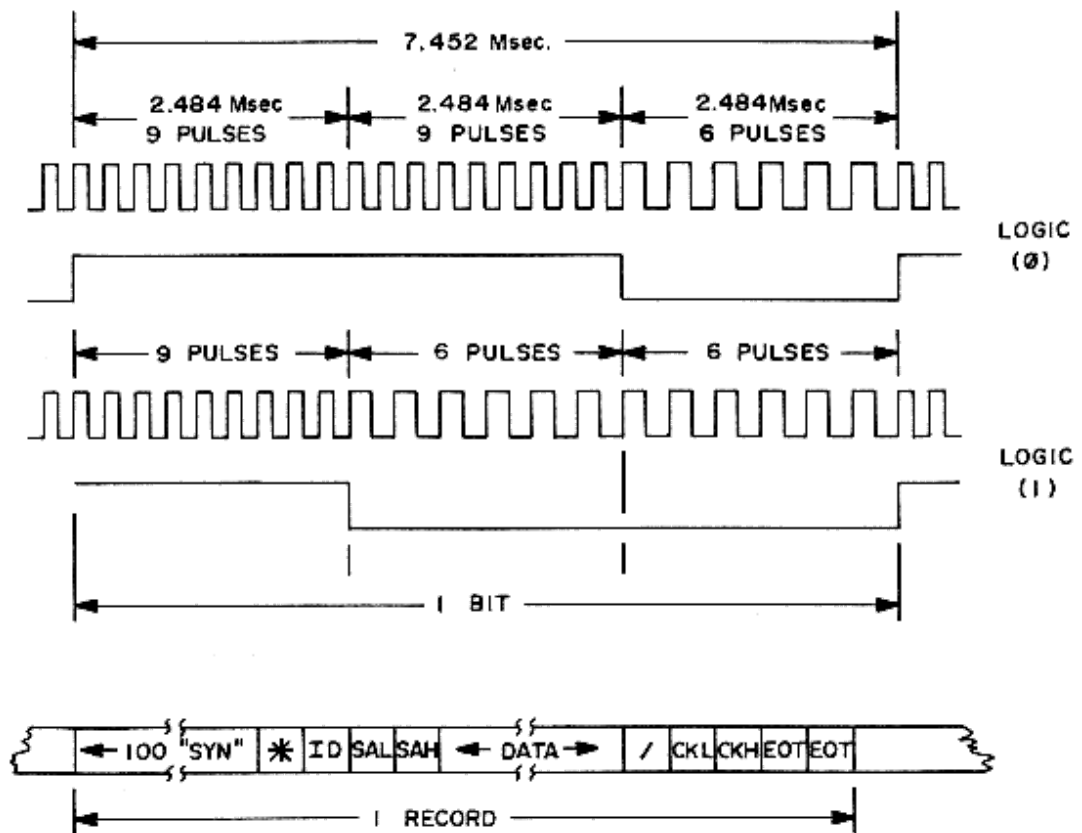
E-1

Each transmitted bit begins with a 3700 hertz tone and ends with a 2400 hertz tone. "Ones" have the high to low frequency transition at one-third of the bit period. "Zeros" have the transition at two-thirds of the period. During playback the 565 phase locked loop locks to, and tracks these two frequencies producing (through the 311 comparator) a logic "1" pulse of one-third the bit period for a "One". A pulse two thirds the bit period is likewise produced for a "Zero". Your microcomputer uses a software controlled algorithm for converting this signal into eight bit data words.

The frequency shift keyed phase lock loop method of data recovery is relatively insensitive to amplitude and phase variations. The "FREE RUNNING" frequency of the phase lock loop has been adjusted at the factory to a frequency half way between the two data frequencies (called the Center Frequency). This adjustment is accomplished by strapping Pin A-P (Audio Out High) to Pin A-L (Audio In). A program starting at address 1A6B_{HEX} provides the center frequency reference that allows the loop to be adjusted by potentiometer VR1. Pin E-X (PLL TEST) is monitored with a voltmeter while the pot is rotated until the voltmeter reading is at the transition point between a logical "1" (+5v) and "0" (GND).

THIS ADJUSTMENT HAS BEEN FACTORY PRESET AND SHOULD ONLY REQUIRE ADJUSTMENT DUE TO COMPONENT REPLACEMENT.'

E-2



Audio Tape Format
FIGURE E-1

E-3

APPENDIX F

PAPER TAPE FORMAT

The paper tape LOAD and DUMP routines store and retrieve data in a specific format designed to insure error free recovery. Each byte of data to be stored is converted to two half bytes. The half bytes (whose possible values are 0 to F_{HEX}) are translated into their ASCII equivalents and written out onto paper tape in this form.

Each record outputted begins with a ";" character (ASCII 3B) to mark the start of a valid record. The next byte transmitted (18_{HEX}) or (24₁₀) is the number of data bytes contained in the record. The record's starting address High (1 byte, 2 characters), starting address Lo (1 byte, 2 characters), and data (24 bytes, 48 characters) follow. Each record is terminated by the record's check-sum (2 bytes, 4 characters), a carriage return (ASCII 0D), line feed (ASCII 0A), and six "NULL" characters (ASCII 00).

The last record transmitted has zero data bytes (indicated by ;00). The starting address field is replaced by a four digit Hex number representing the total number of data records contained in the transmission,

followed by the records usual check-sum digits. A "XOFF" character ends the transmission.

;180000FFEEDDCCBBAA0099887766554433221122334455667788990AFC
;0000010001

F-1

During a "LOAD" all incoming data is ignored until a ";" character is received. The receipt of non ASCII data or a mismatch between a records calculated check-sum and the check-sum read from tape will cause an error condition to be recognized by KIM. The check-sum is calculated by adding all data in the record except the ";" character.

The paper tape format described is compatible with all other MOS Technology, Inc. software support programs.

F-2

APPENDIX G

6502 CHARACTERISTICS

Clocks ($\phi 1$, $\phi 2$).

The MCS 6502 is supplied with an internal clock generator. The frequency of this clock is crystal controlled.

Address Bus (A0-A15).

These outputs are TTL compatible, capable of driving one standard TTL load and 130pf.

Data Bus (D0-D7).

Eight pins are used for the data bus. This is a bi-directional bus, transferring data to and from the device and peripherals. The outputs are tri-state buffers capable of driving one standard TTL load and 130pf.

Ready (RDY).

This input signal allows the user to single cycle the microprocessor on all cycles except write cycles. A negative transition to the low state during or coincident with phase one ($\phi 1$) will halt the microprocessor with the output address lines reflecting the current

address being fetched. This condition will remain through a subsequent phase two (p2) in which the Ready signal is high. This feature allows microprocessor interfacing with low speed PROMS as well as fast (max 2 cycle) Direct Memory Access (DMA). If Ready is low during a write cycle, it is ignored until the following read operation.

G-1

Interrupt Request (IRQ).

This TTL level input requests that an interrupt sequence begin within the microprocessor. The microprocessor will complete the current instruction being executed before recognizing the request. At that time, the interrupt mask bit in the Status Code Register will be examined. If the interrupt mask flag is not set, the microprocessor will begin an interrupt sequence. The Program Counter and Processor Status Register are stored in the stack. The microprocessor will then set the interrupt mask flag high so that no further interrupts may occur. At the end of this cycle, the program counter low will be loaded from address FFFE, and program counter high from location FFFF, therefore transferring program control to the memory vector located at these addresses. The RDY signal must be in the high state (for control to the memory vector) located at these addresses. The RDY signal must be in the high state for any interrupt to be recognized. A 3K Ω external resistor should be used for proper wire-OR operation.

Non-Maskable Interrupt (NMI)

A negative going edge on this input requests that a non-maskable interrupt sequence be generated within the microprocessor.

NMI is an unconditional interrupt. Following completion of the current instruction, the sequence of operations defined for IRQ will be performed, regardless of the state of the interrupt mask flag. The vector address loaded into the program counter, low and high, are locations FFFA and FFFB respectively. The instructions loaded at these locations causes the microprocessor to branch to a non-maskable interrupt routine in memory.

NMI also requires an external 3K Ω resistor to Vcc for proper wire-OR operations.

G-2

Inputs $\overline{\text{IRQ}}$ and $\overline{\text{NMI}}$ are hardware interrupts lines that are sampled during $\phi 2$ (phase 2) and will begin the appropriate interrupt routine on the $\phi 1$ (phase 1) following the completion of the current instruction.

Set Overflow Flag (S.O.).

This TTL level input signal allows external control of the overflow bit in the Status Code Register.

SYNC

This output line is provided to identify those cycles in which the microprocessor is doing an Op Code fetch. The SYNC line goes high during $\phi 1$ of an Op Code fetch and stays high for the remainder of that cycle. If the RDY line is pulled low during the $\phi 1$ clock pulse in which SYNC went high, the processor will stop in its current state and will remain in the state until the RDY line goes high. In this manner, the SYNC signal can be used to control RDY to cause single instruction execution.

RESET

This input is used to reset or start the microprocessor from a power down condition. During the time that this line is held low, writing to or from the microprocessor is inhibited. When a positive edge is detected on the input, the microprocessor will immediately begin the reset sequence.

After a system initialization time of six clock cycles, the mask interrupt flag will be set and the microprocessor will load the program counter from the memory vector locations FFFC and FFFD. This is the start location for program control.

After Vcc reaches 4.75 volts in a power up routine, reset must be held low for at least two clock cycles.

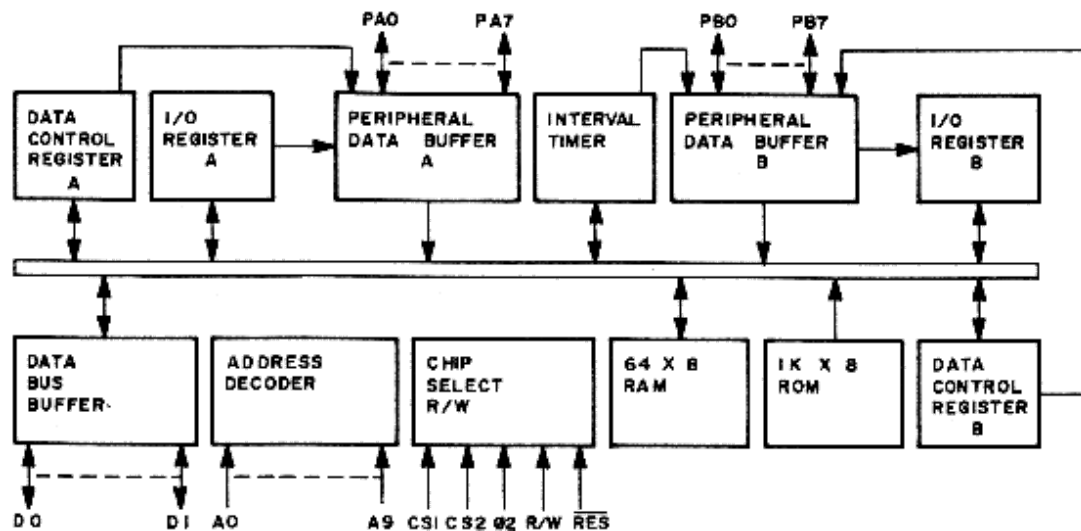
When the reset signal goes high following these two clock cycles, the microprocessor will proceed with the normal reset procedure detailed above.

G-3

APPENDIX H

6530 CHARACTERISTICS

The MCS 6530 is designed to operate in conjunction with the MCS 650X Microprocessor Family. It is comprised of a mask programmable 1024 x 8 ROM, a 64 x 8 static RAM, two software controlled 8 bit bi-directional data ports allowing direct interfacing between the microprocessor unit and peripheral devices, and a software programmable interval timer with interrupt, capable of timing in various intervals from 1 to 262,144 clock periods.



MCS 6530 Block Diagram
FIGURE H.1

H-1

Reset ($\overline{\text{RES}}$).

During system initialization a Logic "0" on the $\overline{\text{RES}}$ input will cause a zeroing of all four I/O registers. This in turn will cause all I/O buses to act as inputs thus protecting external components from possible damage and erroneous data while the system is being configured under software control. The Data Bus Buffers are put into an OFF-STATE during Reset. Interrupt capability is disabled with the RES signal. The RES signal must be held low for at least one clock period when reset is required.

Input Clock

The input clock is a system Phase Two clock which can be either a low level clock ($V_{IL} < 0.4$, $V_{IH} > 2.4$) or high level clock ($V_{IL} < 0.2$, $V_{IH} = V_{CC} \pm 0.2$).

Read/Write (R/W).

The R/W signal is supplied by the microprocessor array and is used to control the transfer of data to and from the microprocessor array and the MCS 6530. A high on the R/W pin allows the processor to read (with proper addressing) the data supplied by the MCS 6530. A low on the R/W pin allows a write (with proper addressing) to the MCS 6530.

Interrupt Request ($\overline{\text{IRQ}}$).

The $\overline{\text{IRQ}}$ pin is an interrupt pin from the interval timer. This same pin, if not used as an interrupt, can be used as a peripheral I/O pin (PB7). Then used as an interrupt, the pin should be set

up as an input by the data direction register. The pin will be normally high with a low indicating an interrupt from the MCS 6530.

H-2

Data Bus (D0-D7)

The MCS 6530 has eight bi-directional data pins (D0-D7). These pins connect to the system's data lines to allow transfer of data to and from the microprocessor array. The output buffers remain in the off state except when a Read operation occurs.

Peripheral Data Ports

The MCS 6530-002, MCS 6530-003 both have 15 pins available for peripheral I/O operations. Each pin is individually software programmable to act as either an input or an output. The 15 pins are divided into 2 8-bit ports, PA0-PA7 and PB0-PB7. PB6 was used as a chip select and is not available to the user. The pins are set up as an input by writing a "0" into the corresponding bit of the data direction register. A "1" into the data direction register will cause its corresponding bit to be an output. When in the input mode, the peripheral output buffers are in the "1" state and a pull-up device acts as less than one TTL load to the peripheral data lines. On a Read operation, the microprocessor unit reads the peripheral pin. When the peripheral device gets information from the MCS 6530 it receives data stored in the data register. The microprocessor will read correct information if the peripheral lines are greater than 2.0 volts for a "1" and less than 0.8 volts for a "0" as the peripheral pins are all TTL compatible. Pins PA0 and PB0 are also capable of sourcing 3 ma at 1.5v, thus making them capable of Darlington drive. Pin PB7 has no internal pull-up (to allow collector-oring with other devices).

Address Lines (A0-A9)

There are 10 address pins. In addition to these 10, there is the ROM SELECT pin. The above pins, A0-A9 and ROM SELECT, are always used as addressing pins. There are 2 additional pins which are mask programmable and can be used either individually or together as CHIP SELECTS. They are pins PB5 and PB6. When used as peripheral data pins they cannot be used as chip selects. PB5 was used as a data pin while PB6 was used as a chip select and is not available to the user.

H-3

A block diagram of the internal architecture is shown in [Figure H-1](#). The MCS 6530 is divided into four basic sections, RAM, ROM, I/O and TIMER. The RAM and ROM interface directly with the microprocessor through the system data bus and address lines. The I/O section consists of 2 8-bit halves. Each half contains a Data Direction Register (DDR) and an I/O

Register.

ROM 1K Byte (8K Bits)

The 8K ROM is in a 1024 x 8 configuration. Address lines A0-A9, as well as RS0 are needed to address the entire ROM. With the addition of CS1 and CS2, seven MCS 6530's may be addressed, giving 7168 x 8 bits of contiguous ROM.

RAM 64 Bytes (512 Bits)

A 64 x 8 static RAM is contained on the MCS 6530. It is addressed by A0-A5 (Byte Select), RS0, A6, A7, A8, A9 and CS1.

Internal Peripheral Registers

There are four internal registers, two data direction registers and two peripheral I/O data registers. The two data direction registers (A side and B side) control the direction of the data into and out of the peripheral pins. A "1" written into the Data Direction Register sets up the corresponding peripheral buffer pin as an output. Therefore, anything then written into the I/O Register will appear on that corresponding peripheral pin. A "0" written into the DDR inhibits the output buffer from transmitting data to or from the I/O Register. For example, a "1" loaded into data direction register A, position 3, sets up peripheral pin PA3 as an output. If a "0" had been loaded, PA3 would be configured as an input and remain in the high state. The two data I/O registers are used to latch data from the Data Bus during a Write operation until the peripheral device can read the data supplied by the microprocessor array.

H-4

During a read operation the microprocessor is not reading the I/O Registers but in fact is reading the peripheral data pins. For the peripheral data pins which are programmed as outputs the microprocessor will read the corresponding data bits of the I/O Register. The only way the I/O Register data can be changed is by a microprocessor Write operation. The I/O Register is not affected by a Read of the data on the peripheral pins.

Interval Timer

1. Capabilities

The KIM-1 Interval Timer allows the user to specify a preset count of up to 256₁₀ and a clock divide rate of 1, 8, 64 or 1024 by writing to a memory location. As soon as the write occurs, counting at the specified rate begins. The timer counts down at the clock frequency divided by the divide rate. The current timer count may be read at any time. At the user's option, the timer may be programmed to generate an interrupt when the counter counts down past zero. When a count of zero is passed, the divide rate is automatically set to 1 and the counter continues to count down at the clock rate starting at a count of FF (-1 in two's complement arithmetic). This allows the user to

determine how many clock cycles have passed since the timer reached a count of zero. Since the counter never stops, continued counting down will reach 00 again, then FF, and the count will continue.

2. Operation

a. Loading the timer

The divide rate and interrupt option enable/disable are programmed by decoding the least significant address bits. The starting count for the timer is determined by the value written to that address.

H-5

<u>Writing to Address</u>	<u>Sets Divide Ratio To</u>	<u>Interrupt Capability Is</u>
1704	1	Disabled
1705	8	Disabled
1706	64	Disabled
1707	1024	Disabled
170C	1	Enabled
170D	8	Enabled
170E	64	Enabled
170F	1024	Enabled

b. Determining the timer status

After timing has begun, reading address location 1707 will provide the timer status. If the counter has passed the count of zero, bit 7 will be set to 1, otherwise, bit 7 (and all other bits in location 1707) will be zero. This allows a program to "watch" location 1707 and determine when the timer has timed out.

c. Reading the count in the timer

If the timer has not counted past zero, reading location 1706 will provide the current timer count and disable the interrupt option; reading location 170E will provide the current timer count and enable the interrupt option. Thus the interrupt option can be changed while the timer is counting down.

If the timer has counted past zero, reading either memory location 1706 or 170E will restore the divide ratio to its previously programmed value, disable the interrupt option and leave the timer with its current count (not the count originally written to the timer). Because the timer never stops counting, the timer will continue to decrement, pass zero, set the divide rate to 1, and continue to count down at the clock frequency, unless new information is written to the timer.

H-6

d. Using the interrupt option

In order to use the interrupt option described above, line PB7

(application connector, pin 15) should be connected to either the IRQ (Expansion Connector, pin 4) or NMI (Expansion Connector, pin 6) pin depending on the desired interrupt function. PB7 should be programmed as in input line (it's normal state after a RESET).

NOTE: If the programmer desires to use PB7 as a normal I/O line, the programmer is responsible for disabling the timer interrupt option (by writing or reading address 1706) so that it does not interfere with normal operation of PB7. Also, PB7 was designed to be wire-ORed with other possible interrupt sources; if this is not desired, a 5.1K resistor should be used as a pull-up from PB7 to +5v. (The pull-up should NOT be used if PB7 is connected to NMI or IRQ.)

H-7

APPENDIX I

KIM-1 PROGRAM LISTINGS

PAGE 2

CARD #	LOC	CODE	CARD
3		;	666666 555555 333333 000000
4		;	6 5 3 0 0
5		;	6 5 3 0 0
6		;	666666 555555 333333 0 0
7		;	6 6 5 3 0 0
8		;	6 6 5 3 0 0
9		;	666666 666666 666666 000000
10		;	
11		;	
12		;	
13		;	000000 000000 333333
14		;	0 0 0 0 3
15		;	----- 0 0 0 0 3
16		;	----- 0 0 0 0 333333
17		;	----- 0 0 0 0 3
18		;	0 0 0 0 3
19		;	000000 000000 333333
20		;	
21		;	
22		;	
23		;	
24		;	
25		;	COPYRIGHT
26		;	MOS TECHNOLOGY, INC
27		;	DATE: OCT 18, 1975 REV-D
28		;	
29		;	

```

30      ;
31      ;      6530-003 I.C. IS AN AUDIO CASSETT TAPE
32      ;      RECORDER EXTENSION OF THE BASIC
33      ;      KIM MONITOR
34      ;
35      ;      IT FEATURES TWO BASIC ROUTINES
36      ;      LOADT-LOAD MEM FROM AUDIO TAPE
37      ;      DUMPT-STOR MEM ONTO AUDIO TAPE
38      ;
39      ;      LOADT
40      ;      ID=00      IGNORE ID
41      ;      ID=FF      IGN. ID USE SA FOR START ADDR
42      ;      ID=01-FE   IGN.ID USE ADDRESS ON TAPE
43      ;
44      ;      DUMPT
45      ;      ID=00      SHOULD NOT BE USED
46      ;      ID=FF      SHOULD NOT BE USED
47      ;      ID=01-FE   NORMAL ID RANGE
48      ;      SAL        LSB STARTING ADDRESS OF PROGRAM
49      ;      SAH        MSB
50      ;      EAL        ENDING ADDRESS OF PROGRAM
51      ;      EAH        MSB
52      ;

```

PAGE 3

CARD #	LOC	CODE	CARD
54			;
55			;
56			EQUATES
57			;
58			SET UP FOR 6530-002 I/O
59			;
60			SAD = \$1740 6530 A DATA
61			PADD = \$1741 6530 A DATA DIRECTION
62			SBD = \$1742 6530 B DATA
63			PBDD = \$1743 6530 B DATA DIRECTION
64			CLK1T = \$1744 DIV BY 1 TIME
65			CLK8T = \$1745 DIV BY 8 TIME
66			CLK64T = \$1746 DIV BY 64 TIME
67			CLKKT = \$1747 DIV BY 1024 TIME
68			CLKRDI = \$1747 READ TIME OUT BIT
69			CLKRDT = \$1746 READ TIME
70			;
71			*= \$00EF
72			;
73			MPU REG. SAVX AREA IN PAGE 0
74			;
75			PCL *= *+1 PROGRAM CNT LOW
76			PCH *= *+1 PROGRAM CNT HI
77			PREG *= *+1 CURRENT STATUS REG
78			SPUSER *= *+1 CURRENT STACK POINTER
79			ACC *= *+1 ACCUMULATOR
80			YREG *= *+1 Y INDEX
81			XREG *= *+1 X INDEX
82			;
83			;
84			KIM FIXED AREA IN PAGE 0
85			;
86			CHKHI *= *+1
87			CHKSUM *= *+1
88			INL *= *+1 INPUT BUFFER
89			INH *= *+1 INPUT BUFFER
90			POINTL *= *+1 LSB OF OPEN CELL
91			POINTH *= *+1 MSB OF OPEN CELL
92			TEMP *= *+1
93			TMPX *= *+1

90	00FE	CHAR	*=+1	
91	00FF	MODE	*=+1	
92		;		
93		;		KIM FIXED AREA IN PAGE 23
94		;		
95	0100		*=\$17E7	
96	17E7	CHKL	*=+1	
97	17E8	CHKH	*=+1	CHKSUM
98	17E9	SAVX	*=+3	
99	17EC	VEB	*=+6	VOLATILE EXECUTION BLOCK
100	17F2	CNTL30	*=+1	TTY DELAY
101	17F3	CNTH30	*=+1	TTY DELAY
102	17F4	TIMH	*=+1	
103	17F5	SAL	*=+1	LOW STARTING ADDRESS
104	17F6	SAH	*=+1	HI STARTING ADDRESS
105	17F7	EAL	*=+1	LOW ENDING ADDRESS

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CARD #	LOC	CODE	CARD	
106	17F8		EAH	*=+1
107	17F9		ID	*=+1
108			;	
109			;	INTERRUPT VECTORS
110			;	
111	17FA		NMIV	*=+2
112	17FC		RSTV	*=+2
113	17FE		IRQV	*=+2
114			;	

				HI ENDING ADDRESS
				TAPE PROGRAM ID NUMBER
				STOP VECTOR (STOP=1C00)
				RST VECTOR
				IRQ VECTOR (BRK= 1C00)

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CARD #	LOC	CODE	CARD	
116	1800			*=\$1800
117			;	
118			;	INIT VOLATILE EXECUTION BLOCK
119			;	DUMP MEM TO TAPE
120			;	
121	1800	A9 AD	DUMPT	LDA #\$AD
122	1802	8D EC 17		STA VEB
123	1805	20 32 19		JSR INTVEB
124			;	
125	1808	A9 27		LDA #\$27
126	180A	8D 42 17		STA SBD
127	180D	A9 BF		LDA #\$BF
128	180F	8D 43 17		STA PBDD
129			;	
130	1812	A2 64		LDX #\$64
131	1814	A9 16	DUMPT1	LDA #\$16
132	1816	20 7A 19		JSR OUTCHT
133	1819	CA		DEX
134	181A	D0 F8		BNE DUMPT1
135			;	
136				
137	181C	A9 2A		LDA #\$2A
138	181E	20 7A 19		JSR OUTCHT
139			;	
140	1821	AD F9 17		LDA ID
141	1824	20 61 19		JSR OUTBT
142			;	

				LOAD ABSOLUTE INST
				TURN OFF DATAIN PB5
				CONVERT PB7 TO OUTPUT
				100 CHARS
				SYNC CHAR'S
				START CHAR
				OUTPUT ID

143	1827	AD F5 17		LDA	SAL	OUTPUT STARTING
144	182A	20 5E 19		JSR	OUTBTC	ADDRESS
145	182D	AD F6 17		LDA	SAH	
146	1830	20 5E 19		JSR	OUTBTC	
147						
148	1833	AD ED 17	DUMPT2	LDA	VEB+1	CHECK FOR LAST
149	1836	CD F7 17		CMP	EAL	DATA BYTE
150	1839	AD EE 17		LDA	VEB+2	
151	183C	ED F8 17		SBC	EAH	
152	183F	90 24		BCC	DUMPT4	
153						
154	1841	A9 2F		LDA	#'/	OUTPUT END OF DATA CHAR
155	1843	20 7A 19		JSR	OUTCHT	
156	1846	AD E7 17		LDA	CHKL	LAST BYTE HAS BEEN
157	1849	20 61 19		JSR	OUTBT	OUTPUT NOW OUTPUT
158	184C	AD E8 17		LDA	CHKH	CHKSUM
159	184F	20 61 19		JSR	OUTBT	
160						
161						
162	1852	A2 02		LDX	#\$02	2 CHAR'S
163	1854	A9 04	DUMPT3	LDA	#\$04	EOT CHAR
164	1856	20 7A 19		JSR	OUTCHT	
165	1859	CA		DEX		
166	185A	D0 F8		BNE	DUMPT3	
167						

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CARD #	LOC	CODE	CARD		
168	185C	A9 00	LDA	#\$00	DISPLAY 0000
169	185E	85 FA	STA	POINTL	FOR NORMAL EXIT
170	1860	85 FB	STA	POINTH	
171	1862	4C 4F 1C	JMP	START	
172					
173	1865	20 EC 17	DUMPT4	JSR	VEB
174	1868	20 5E 19		JSR	OUTBTC
175					
176	186B	20 EA 19		JSR	INCVEB
177	186E	4C 33 18		JMP	DUMPT2
178					
179					LOAD MEMORY FROM TAPE
180					
181					
182	1871	0F 19	TAB	.WORD	LOAD12
183	1873	A9 8D	LOADT	LDA	#\$8D
184	1875	8D EC 17		STA	VEB
185	1878	20 32 19		JSR	INTVEB
186					
187	187B	A9 4C		LDA	#\$4C
188	187D	8D EF 17		STA	VEB+3
189	1880	AD 71 18		LDA	TAB
190	1883	8D F0 17		STA	VEB+4
191	1886	AD 72 18		LDA	TAB+1
192	1889	8D F1 17		STA	VEB+5
193					
194	188C	A9 07		LDA	#\$07
195	188E	8D 42 17		STA	SBD
196					
197	1891	A9 FF	SYNC	LDA	#\$FF
198	1893	8D E9 17		STA	SAVX
199					
200	1896	20 41 1A	SYNC1	JSR	RDBIT
201	1899	4E E9 17		LSR	SAVX

202	189C	0D E9 17		ORA	SAVX	
203	189F	8D E9 17		STA	SAVX	
204	18A2	AD E9 17		LDA	SAVX	GET NEW CHAR
205	18A5	C9 16		CMP	#\$16	SYNC CHAR
206	18A7	D0 ED		BNE	SYNC1	
207			;			
208	18A9	A2 0A		LDX	#\$0A	TEST FOR 10 SYNC CHARS
209	18AB	20 24 1A	SYNC2	JSR	RDCHT	
210	18AE	C9 16		CMP	#\$16	
211	18B0	D0 DF		BNE	SYNC	IF NOT 10 CHAR, RE-SYNC
212	18B2	CA		DEX		
213	18B3	D0 F6		BNE	SYNC2	
214			;			
215			;			
216	18B5	20 24 1A	LOADT4	JSR	RDCHT	LOOK FOR START OF
217	18B8	C9 2A		CMP	#\$2A	DATA CHAR
218	18BA	F0 06		BEQ	LOAD11	
219	18BC	C9 16		CMP	#\$16	IF NOT , SHOULD BE SYN

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CARD #	LOC	CODE	CARD			
220	18BE	D0 D1		BNE	SYNC	
221	18C0	F0 F3		BEQ	LOADT4	
222			;			
223	18C2	20 F3 19	LOAD11	JSR	RDBYT	READ ID FROM TAPE
224	18C5	CD F9 17		CMP	ID	COMPARE WITH REQUESTED ID
225	18C8	F0 0D		BEQ	LOADT5	
226	18CA	AD F9 17		LDA	ID	DEFAULT 00, READ RECORD
227	18CD	C9 00		CMP	#\$00	ANYWAY
228	18CF	F0 06		BEQ	LOADT5	
229	18D1	C9 FF		CMP	#\$FF	DEFAULT FF, IGNORE SA ON
230	18D3	F0 17		BEQ	LOADT6	TAPE
231	18D5	D0 9C		BNE	LOADT	
232			;			
233	18D7	20 F3 19	LOADT5	JSR	RDBYT	GET SA FROM TAPE
234	18DA	20 4C 19		JSR	CHKT	
235	18DD	8D ED 17		STA	VEB+1	SAVX IN VEB+1,2
236	18E0	20 F3 19		JSR	RDBYT	
237	18E3	20 4C 19		JSR	CHKT	
238	18E6	8D EE 17		STA	VEB+2	
239	18E9	4C F8 18		JMP	LOADT7	
240			;			
241	18EC	20 F3 19	LOADT6	JSR	RDBYT	GET SA BUT IGNORE
242	18EF	20 4C 19		JSR	CHKT	
243	18F2	20 F3 19		JSR	RDBYT	
244	18F5	20 4C 19		JSR	CHKT	
245			;			
246			;			
247	18F8	A2 02	LOADT7	LDX	#\$02	GET 2 CHARS
248	18FA	20 24 1A	LOAD13	JSR	RDCHT	GET CHAR (X)
249	18FD	C9 2F		CMP	#\$2F	LOOK FOR LAST CHAR
250	18FF	F0 14		BEQ	LOADT8	
251	1901	20 00 1A		JSR	PACKT	CONVERT TO HEX
252	1904	D0 23		BNE	LOADT9	Y=1 NON-HEX CHAR
253	1906	CA		DEX		
254	1907	D0 F1		BNE	LOAD13	
255			;			
256	1909	20 4C 19		JSR	CHKT	COMPUTE CHECKSUM
257	190C	4C EC 17		JMP	VEB	SAVX DATA IN MEMORY
258	190F	20 EA 19	LOAD12	JSR	INCVEB	INCREMENT DATA POINTER
259	1912	4C F8 18		JMP	LOADT7	
260			;			

261	1915	20 F3 19	LOADT8	JSR	RDBYT	END OF DATA, COMPARE CHKSUM
262	1918	CD E7 17		CMP	CHKL	
263	191B	D0 0C		BNE	LOADT9	
264	191D	20 F3 19		JSR	RDBYT	
265	1920	CD E8 17		CMP	CHKH	
266	1923	D0 04		BNE	LOADT9	
267	1925	A9 00		LDA	#\$00	NORMAL EXIT
268	1927	F0 02		BEQ	LOAD10	
269			;			
270	1929	A9 FF	LOADT9	LDA	#\$FF	ERROR EXIT
271	192B	85 FA	LOAD10	STA	POINTL	

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CARD #	LOC	CODE	CARD		
272	192D	85 FB		STA	POINTH
273	192F	4C 4F 1C		JMP	START
274				;	

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CARD #	LOC	CODE	CARD		
276				;	
277				;	SUBROUTINES FOLLOW
278				;	
279				;	SUB TO MOVE SA TO VEB+1,2
280				;	
281	1932	AD F5 17	INTVEB	LDA	SAL MOVE SA TO VEB+1,2
282	1935	8D ED 17		STA	VEB+1
283	1938	AD F6 17		LDA	SAH
284	193B	8D EE 17		STA	VEB+2
285	193E	A9 60		LDA	#\$60 RTS INST
286	1940	8D EF 17		STA	VEB+3
287	1943	A9 00		LDA	#\$00 CLEAR CHKSUM AREA
288	1945	8D E7 17		STA	CHKL
289	1948	8D E8 17		STA	CHKH
290	194B	60		RTS	
291				;	
292				;	COMPUTE CHKSUM FOR TAPE LOAD
293				;	RTN USES Y TO SAVEX A
294				;	
295	194C	A8	CHKT	TAY	
296	194D	18		CLC	
297	194E	6D E7 17		ADC	CHKL
298	1951	8D E7 17		STA	CHKL
299	1954	AD E8 17		LDA	CHKH
300	1957	69 00		ADC	#\$00
301	1959	8D E8 17		STA	CHKH
302	195C	98		TYA	
303	195D	60		RTS	
304				;	
305				;	OUTPUT ONE BYTE USE Y
306				;	TO SAVX BYTE
307				;	
308	195E	20 4C 19	OUTBTC	JSR	CHKT COMPARE CHKSUM
309	1961	A8	OUTBT	TAY	SAVX DATA BYTE
310	1962	4A		LSR	A SHIFT OFF LSD
311	1963	4A		LSR	A
312	1964	4A		LSR	A
313	1965	4A		LSR	A
314	1966	20 6F 19		JSR	HEXOUT OUTPUT MSD
315	1969	98		TYA	

316	196A	20 6F 19		JSR	HEXOUT	OUTPUT LSD
317	196D	98		TYA		
318	196E	60		RTS		
319			;			
320			;		CONVERT LSD OF A TO ASCII	
321			;		OUTPUT TO TAPE	
322			;			
323	196F	29 0F	HEXOUT	AND	#\$0F	
324	1971	C9 0A		CMP	#\$0A	
325	1973	18		CLC		
326	1974	30 02		BMI	HEX1	
327	1976	69 07		ADC	#\$07	

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CARD #	LOC	CODE	CARD			
328	1978	69 30	HEX1	ADC	#\$30	
329			;			
330			;		OUTPUT TO TAPE ONE ASCII	
331			;		CHAR USE SUB'S ONE + ZRO	
332			;			
333	197A	8E E9 17	OUTCHT	STX	SAVX	
334	197D	8C EA 17		STY	SAVX+1	
335	1980	A0 08		LDY	#\$08	START BIT
336	1982	20 9E 19	CHT1	JSR	ONE	
337	1985	4A		LSR	A	GET DATA BIT
338	1986	B0 06		BCS	CHT2	
339	1988	20 9E 19		JSR	ONE	DATA BIT=1
340	198B	4C 91 19		JMP	CHT3	
341	198E	20 C4 19	CHT2	JSR	ZRO	DATA BIT=0
342	1991	20 C4 19	CHT3	JSR	ZRO	
343	1994	88		DEY		
344	1995	D0 EB		BNE	CHT1	
345	1997	AE E9 17		LDX	SAVX	
346	199A	AC EA 17		LDY	SAVX+1	
347	199D	60		RTS		
348			;			
349			;			
340			;		OUTPUT 1 TO TAPE	
351			;		9 PULSES, 138 MICROSEC EACH	
352			;			
353	199E	A2 09	ONE	LDX	#\$09	
354	19A0	48		PHA		SAVX A
355	19A1	2C 47 17	ONE1	BIT	CLKRDI	WAIT FOR TIME OUT
356	19A4	10 FB		BPL	ONE1	
357	19A6	A9 7E		LDA	#126	
358	19A8	8D 44 17		STA	CLK1T	
359	19AB	A9 A7		LDA	#\$A7	
360	19AD	8D 42 17		STA	SBD	SET PB7=1
361	19B0	2C 47 17	ONE2	BIT	CLKRDI	
362	19B3	10 FB		BPL	ONE2	
363	19B5	A9 7E		LDA	#126	
364	19B7	8D 44 17		STA	CLK1T	
365	19BA	A9 27		LDA	#\$27	
366	19BC	8D 42 17		STA	SBD	RESET PB7=0
367	19BF	CA		DEX		
368	19C0	D0 DF		BNE	ONE1	
369	19C2	68		PLA		
370	19C3	60		RTS		
371			;			
372			;			
373			;		OUTPUT 0 TO TAPE	
374			;		6 PULSES, 207 MICROSEC EACH	

```

375                               ;
376 19C4 A2 06      ZR0      LDX  #$06
377 19C6 48                PHA                SAVX A
378 19C7 2C 47 17  ZR01     BIT  CLKRDI
379 19CA 10 FB                BPL  ZR01

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CARD # LOC      CODE      CARD
380 19CC A9 C3      LDA  #$C3
381 19CE 8D 44 17      STA  CLK1T
382 19D1 A9 A7      LDA  #$A7
383 19D3 8D 42 17      STA  SBD      SET PB7=1
384 19D6 2C 47 17  ZR02  BIT  CLKRDI
385 19D9 10 FB      BPL  ZR02
386 19DB A9 C3      LDA  #195
387 19DD 8D 44 17      STA  CLK1T
388 19E0 A9 27      LDA  #$27
389 19E2 8D 42 17      STA  SBD      RESET PB7=0
390 19E5 CA      DEX
391 19E6 D0 DF      BNE  ZR01
392 19E8 68      PLA      RESTORE A
393 19E9 60      RTS
394                               ;
395                               ;      SUB TO INC VEB+1,2
396                               ;
397 19EA EE ED 17  INCVEB  INC  VEB+1
398 19ED D0 03      BNE  INCVE1
399 19EF EE EE 17      INC  VEB+2
400 19F2 60      INCVE1  RTS
401                               ;
402                               ;      SUB TO READ BYTE FROM TAPE
403                               ;
404 19F3 20 24 1A  RDBYT  JSR  RDCHT
405 19F6 20 00 1A      JSR  PACKT
406 19F9 20 24 1A      JSR  RDCHT
407 19FC 20 00 1A      JSR  PACKT
408 19FF 60      RTS
409                               ;
410                               ;      PACK A=ASCII INTO SAVX
411                               ;      AS HEX DATA
412                               ;
413 1A00 C9 30      PACKT  CMP  #$30
414 1A02 30 1E      BMI  PACKT3
415 1A04 C9 47      CMP  #$47
416 1A06 10 1A      BPL  PACKT3
417 1A08 C9 40      CMP  #$40
418 1A0A 30 03      BMI  PACKT1
419 1A0C 18      CLC
420 1A0D 69 09      ADC  #$09
421 1A0F 2A      PACKT1  ROL  A
422 1A10 2A      ROL  A
423 1A11 2A      ROL  A
424 1A12 2A      ROL  A
425 1A13 A0 04      LDY  #$04
426 1A15 2A      PACKT2  ROL  A
427 1A16 2E E9 17      ROL  SAVX
428 1A19 88      DEY
429 1A1A D0 F9      BNE  PACKT2
430 1A1C AD E9 17      LDA  SAVX
431 1A1F A0 00      LDY  #$00      Y=0 VALID HEX CHAR

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CARD #	LOC	CODE	CARD		
432	1A21	60	RTS		
433	1A22	C8	PACKT3	INY	Y=1 NOT HEX
434	1A23	60	RTS		
435			;		
436			;	GET 1 CHAR FROM	TAPE AND RETURN
437			;	WITH CHAR IN A	USE SAVX+1 TO ASM CHAR
438			;		
439	1A24	8E EB 17	RDCHT	STX	SAVX+2
440	1A27	A2 08		LDX	#\$08 READ 8 BITS
441	1A29	20 41 1A	RDCHT1	JSR	RDBIT GET NEXT DATA BIT
442	1A2C	4E EA 17		LSR	SAVX+1 RIGHT SHIFT CHAR
443	1A2F	0D EA 17		ORA	SAVX+1 OR IN SIGN BIT
444	1A32	8D EA 17		STA	SAVX+1 REPLACE CHAR
445	1A35	CA		DEX	
446	1A36	D0 F1		BNE	RDCHT1
447			;		
448	1A38	AD EA 17		LDA	SAVX+1 MOVE CHAR INTO A
449	1A3B	2A		ROL	A SHIFT OFF PARITY
450	1A3C	4A		LSR	A
451	1A3D	AE EB 17		LDX	SAVX+2
452	1A40	60		RTS	
453			;		
454			;	THIS SUB GETS ONE BIT FROM	
455			;	TAPE AND RETURNS IT IN SIGN OF A	
456			;		
457	1A41	2C 42 17	RDBIT	BIT	SBD WAIT FOR END OF START BIT
458	1A44	10 FB		BPL	RDBIT
459	1A46	AD 46 17		LDA	CLKRDT GET START BIT TIME
460	1A49	A0 FF		LDY	#\$FF A=256-T1
461	1A4B	8C 46 17		STY	CLK64T SET UP TIMER
462			;		
463	1A4E	A0 14		LDY	#\$14
464	1A50	88	RDBIT3	DEY	DELAY 100 MICROSEC
465	1A51	D0 FD		BNE	RDBIT3
466			;		
467	1A53	2C 42 17	RDBIT2	BIT	SBD
468	1A56	30 FB		BMI	RDBIT2 WAIT FOR NEXT START BIT
469					
470	1A58	38		SEC	
471	1A59	ED 46 17		SBC	CLKRDT (256-T1)-(256-T2)=T2-T1
472	1A5C	A0 FF		LDY	#\$FF
473	1A5E	8C 46 17		STY	CLK64T SET UP TIMER FOR NEXT BIT
474					
475	1A61	A0 07		LDY	#\$07
476	1A63	88	RDBIT4	DEY	DELAY 50 MICROSEC
477	1A64	D0 FD		BNE	RDBIT4
478			;		
479	1A66	49 FF		EOR	#\$FF COMPLEMENT SIGN OF A
480	1A68	29 80		AND	#\$80 MASK ALL EXCEPT SIGN
481	1A6A	60		RTS	

CARD #	LOC	CODE	CARD
483			;
484			;
485			DIAGNOSTICS
486			;
			MEMORY
			PLLCAL

```

487      ;
488      ;
489      ;
490      ;      PLLCAL OUTPUT 166 MICROSEC
491      ;      PULSE STRING
492      ;
493 1A6B A9 27 PLLCAL LDA #$27
494 1A6D 8D 42 17 STA SBD      TURN OFF DATIN PB5=1
495 1A70 A9 BF LDA #$BF      CONVERT PB7 TO OUTPUT
496 1A72 8D 43 17 STA PBDD
497      ;
498 1A75 2C 47 17 PLL1 BIT CLKRDI
499 1A78 10 FB BPL PLL1
500 1A7A A9 9A LDA #154      WAIT 166 MICROSEC
501 1A7C 8D 44 17 STA CLK1T
502 1A7F A9 A7 LDA #$A7      OUTPUT PB7=1
503 1A81 8D 42 17 STA SBD
504      ;
505 1A84 2C 47 17 PLL2 BIT CLKRDI
506 1A87 10 FB BPL PLL2
507 1A89 A9 9A LDA #154
508 1A8B 8D 44 17 STA CLK1T
509 1A8E A9 27 LDA #$27      PB7=0
510 1A90 8D 42 17 STA SBD
511 1A93 4C 75 1A JMP PLL1
512      ;
513      ;
514      ;      INTERRUPTS PAGE 27
515      ;
516      ;      *=*+$164      RESERVED FOR TEST
517 1BFA 6B 1A NMIP27 .WORD PLLCAL
518 1BFC 6B 1A RSTP27 .WORD PLLCAL
519 1BFE 6B 1A IRQP27 .WORD PLLCAL
520      ;

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CARD #	LOC	CODE	CARD
522			;
523			;
524			;
525			;
526			;
527			666666 555555 333333 000000
528			6 5 3 0 0
529			6 5 3 0 0
530			666666 555555 333333 0 0
531			6 6 5 3 0 0
532			6 6 5 3 0 0
533			666666 666666 666666 000000
534			;
535			;
536			;
537			000000 000000 222222
538			0 0 0 0 2
539			----- 0 0 0 0 2
540			----- 0 0 0 0 222222
541			----- 0 0 0 0 2
542			0 0 0 0 2
543			000000 000000 222222

CARD #	LOC	CODE	CARD
545			;
546			;
547			;
548			;
549			COPYRIGHT
550			MOS TECHNOLOGY INC.
551			DATE OCT 13 1975 REV E
552			;
553			KIM :TTY INTERFACE
554			:KEYBOARD INTERFACE
555			:7 SEG 6 DIGIT DISPLAY
556			;
557			TTY CMDS:
558			G GOEXEC
559			CR OPEN NEXT CELL
560			LF OPEN PREV. CELL
561			. MODIFY OPEN CELL
562			SP OPEN NEW CELL
563			L LOAD (OBJECT FORMAT)
564			Q DUMP FROM OPEN CELL ADDR TO HI LIMIT
565			RO RUB OUT - RETURN TO START (KIM)
566			((ALL ILLEGAL CHARS ARE IGNORED))
567			;
568			KEYBOARD COMMANDS:
569			ADDR SETS MODE TO MODIFY CELL ADDRESS
570			DATA SETS MODE TO MODIFY DATA IN OPEN CELL
571			STEP INCREMENTS TO NEXT CELL
572			RST SYSTEM RESET
573			RUN GOEXEC
574			STOP \$1C00 CAN BE LOADED INTO NMIV TO
575			USE STOP FEATURE
576			PC DISPLAY PC
577			;
578			CLOCK IS NOT DISABLED IN SIGMA 1
579			;
580			;
581			;
582			;

CARD #	LOC	CODE	CARD
584			*=\$1C00
585			;
586			;
587	1C00	85 F3	SAVE STA ACC KIM ENTRY VIA STOP (NMI)
588	1C02	68	PLA OR BRK (IRQ)
589	1C03	85 F1	STA PREG
590	1C05	68	PLA KIM ENTRY VIA JSR (A LOST)
591	1C06	85 EF	STA PCL
592	1C08	85 FA	STA POINTL
593	1C0A	68	PLA
594	1C0B	85 F0	STA PCH
595	1C0D	85 FB	STA POINTH
596	1C0F	84 F4	STY YREG
597	1C11	86 F5	STX XREG
598	1C13	BA	TSX
599	1C14	86 F2	STX SPUSER
600	1C16	20 88 1E	JSR INITS

601	1C19	4C 4F 1C		JMP	START	
602			;			
603	1C1C	6C FA 17	NMIT	JMP	(NMIV)	NON-MASKABLE INTERRUPT TRAP
604	1C1F	6C FE 17	IRQT	JMP	(IRQV)	INTERRUPT TRAP
605			;			
606	1C22	A2 FF	RST	LDX	#\$FF	KIM ENTRY VIA RST
607	1C24	9A		TXS		
608	1C25	86 F2		STX	SPUSER	
609	1C27	20 88 1E		JSR	INITS	
610			;			
611			;			
612	1C2A	A9 FF		LDA	#\$FF	COUNT START BIT
613	1C2C	8D F3 17		STA	CNTH30	ZERO CNTH30
614	1C2F	A9 01		LDA	#\$01	MASK HI ORDER BITS
615	1C31	2C 40 17	DET1	BIT	SAD	TEST
616	1C34	D0 19		BNE	START	KEYBD SSW TEST
617	1C36	30 F9		BMI	DET1	START BIT TEST
618	1C38	A9 FC		LDA	#\$FC	
619	1C3A	18	DET3	CLC		THIS LOOP COUNTS
620	1C3B	69 01		ADC	#\$01	THE START BIT TIME
621	1C3D	90 03		BCC	DET2	
622	1C3F	EE F3 17		INC	CNTH30	
623	1C42	AC 40 17	DET2	LDY	SAD	CHECK FOR END OF START BIT
624	1C45	10 F3		BPL	DET3	
625	1C47	8D F2 17		STA	CNTH30	
626	1C4A	A2 08		LDX	#\$08	
627	1C4C	20 6A 1E		JSR	GET5	GET REST OF THE CHAR, TEST CHAR
628			;			
629			;			
630			;			
631			;			
632			;			
633			;			
634			;			
635			;			
					MAKE TTY/KB SELECTION	

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CARD #	LOC	CODE	CARD			
636	1C4F	20 8C 1E	START	JSR	INIT1	
637	1C52	A9 01		LDA	#\$01	
638	1C54	2C 40 17		BIT	SAD	
639	1C57	D0 1E		BNE	TTYKB	
640	1C59	20 2F 1E		JSR	CRLF	PRT CR LF
641	1C5C	A2 0A		LDX	#\$0A	TYPE OUT KIM
642	1C5E	20 31 1E		JSR	PRTST	
643	1C61	4C AF 1D		JMP	SHOW1	
644			;			
645	1C64	A9 00	CLEAR	LDA	#\$00	
646	1C66	85 F8		STA	INL	CLEAR INPUT BUFFER
647	1C68	85 F9		STA	INH	
648	1C6A	20 5A 1E	READ	JSR	GETCH	GET CHAR
649	1C6D	C9 01		CMP	#\$01	
650	1C6F	F0 06		BEQ	TTYKB	
651	1C71	20 AC 1F		JSR	PACK	
652	1C74	4C DB 1D		JMP	SCAN	
653			;			
654			;			
655			;			
656			;			
657	1C77	20 19 1F	TTYKB	JSR	SCAND	IF A=0 NO KEY
658	1C7A	D0 D3		BNE	START	
659	1C7C	A9 01	TTYKB1	LDA	#\$01	

660	1C7E	2C 40 17		BIT	SAD	
661	1C81	F0 CC		BEQ	START	
662	1C83	20 19 1F		JSR	SCAND	
663	1C86	F0 F4		BEQ	TTYKB1	
664	1C88	20 19 1F		JSR	SCAND	
665	1C8B	F0 EF		BEQ	TTYKB1	
666			;			
667	1C8D	20 6A 1F	GETK	JSR	GETKEY	
668	1C90	C9 15		CMP	#\$15	
669	1C92	10 BB		BPL	START	
670	1C94	C9 14		CMP	#\$14	
671	1C96	F0 44		BEQ	PCCMD	DISPLAY PC
672	1C98	C9 10		CMP	#\$10	ADDR MODE=1
673	1C9A	F0 2C		BEQ	ADDRM	
674	1C9C	C9 11		CMP	#\$11	DATA MODE=1
675	1C9E	F0 2C		BEQ	DATAM	
676	1CA0	C9 12		CMP	#\$12	STEP
677	1CA2	F0 2F		BEQ	STEP	
678	1CA4	C9 13		CMP	#\$13	RUN
679	1CA6	F0 31		BEQ	GOV	
680	1CA8	0A	DATA	ASL	A	SHIFT CHAR INTO HIGH
681	1CA9	0A		ASL	A	ORDER NIBBLE
682	1CAA	0A		ASL	A	
683	1CAB	0A		ASL	A	
684	1CAC	85 FC		STA	TEMP	STORE IN TEMP
685	1CAE	A2 04		LDX	#\$04	
686	1CB0	A4 FF	DATA1	LDY	MODE	TEST MODE 1=ADDR
687	1CB2	D0 0A		BNE	ADDR	MODE=0 DATA

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CARD #	LOC	CODE	CARD			
688	1CB4	B1 FA		LDA	(POINTL),Y	GET DATA
689	1CB6	06 FC		ASL	TEMP	SHIFT CHAR
690	1CB8	2A		ROL	A	SHIFT DATA
691	1CB9	91 FA		STA	(POINTL),Y	STORE OUT DATA
692	1CBB	4C C3 1C		JMP	DATA2	
693			;			
694	1CBE	0A	ADDR	ASL	A	SHIFT CHAR
695	1CBF	26 FA		ROL	POINTL	SHIFT ADDR
696	1CC1	26 FB		ROL	POINTH	SHIFT ADDR HI
697	1CC3	CA	DATA2	DEX		
698	1CC4	D0 EA		BNE	DATA1	DO 4 TIMES
699	1CC6	F0 08		BEQ	DATAM2	EXIT HERE
700			;			
701	1CC8	A9 01	ADDRM	LDA	#\$01	
702	1CCA	D0 02		BNE	DATAM1	
703			;			
704	1CCC	A9 00	DATAM	LDA	#\$00	
705	1CCE	85 FF	DATAM1	STA	MODE	
706	1CD0	4C 4F 1C	DATAM2	JMP	START	
707			;			
708	1CD3	20 63 1F	STEP	JSR	INCPT	
709	1CD6	4C 4F 1C		JMP	START	
710			;			
711	1CD9	4C C8 1D	GOV	JMP	GOEXEC	
712			;			
713			;			
714			;		DISPLAY PC BY MOVING	
715			;		PC TO POINT	
716			;			
717	1CDC	A5 EF	PCCMD	LDA	PCL	
718	1CDE	85 FA		STA	POINTL	

719	1CE0	A5 F0		LDA	PCH	
720	1CE2	85 FB		STA	POINTH	
721	1CE4	4C 4F 1C		JMP	START	
722			;			
723			;	LOAD	PAPER TAPE FROM TTY	
724			;			
725	1CE7	20 5A 1E	LOAD	JSR	GETCH	LOOK FOR FIRST CHAR
726	1CEA	C9 3B		CMP	#\$3B	SMICOLON
727	1CEC	D0 F9		BNE	LOAD	
728	1CEE	A9 00		LDA	#\$00	
729	1CF0	85 F7		STA	CHKSUM	
730	1CF2	85 F6		STA	CHKHI	
731			;			
732	1CF4	20 9D 1F		JSR	GETBYT	GET BYTE CNT
733	1CF7	AA		TAX		SAVE IN X INDEX
734	1CF8	20 91 1F		JSR	CHK	COMPUTE CHKSUM
735			;			
736	1CFB	20 9D 1F		JSR	GETBYT	GET ADDRESS HI
737	1CFE	85 FB		STA	POINTH	
738	1D00	20 91 1F		JSR	CHK	
739	1D03	20 9D 1F		JSR	GETBYT	GET ADDRESS LO

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CARD #	LOC	CODE	CARD			
740	1D06	85 FA		STA	POINTL	
741	1D08	20 91 1F		JSR	CHK	
742			;			
743	1D0B	8A		TXA		IF CNT=0 DONT
744	1D0C	F0 0F		BEQ	LOAD3	GET ANY DATA
745			;			
746	1D0E	20 9D 1F	LOAD2	JSR	GETBYT	GET DATA
747	1D11	91 FA		STA	(POINTL),Y	STORE DATA
748	1D13	20 91 1F		JSR	CHK	
749	1D16	20 63 1F		JSR	INCPT	NEXT ADDRESS
750	1D19	CA		DEX		
751	1D1A	D0 F2		BNE	LOAD2	
752	1D1C	E8		INX		X=1 DATA RECORD
753			;			X=0 LAST RECORD
754	1D1D	20 9D 1F	LOAD3	JSR	GETBYT	COMPARE CHKSUM
755	1D20	C5 F6		CMP	CHKHI	
756	1D22	D0 17		BNE	LOADE1	
757	1D24	20 9D 1F		JSR	GETBYT	
758	1D27	C5 F7		CMP	CHKSUM	
759	1D29	D0 13		BNE	LOADER	
760			;			
761	1D2B	8A		TXA		X=0 LAST RECORD
762	1D2C	D0 B9		BNE	LOAD	
763			;			
764	1D2E	A2 0C	LOAD7	LDX	#\$0C	X-OFF KIM
765	1D30	A9 27	LOAD8	LDA	#\$27	
766	1D32	8D 42 17		STA	SBD	DISABLE DATA IN
767	1D35	20 31 1E		JSR	PRTST	
768	1D38	4C 4F 1C		JMP	START	
769			;			
770	1D3B	20 9D 1F	LOADE1	JSR	GETBYT	DUMMY
771	1D3E	A2 11	LOADER	LDX	#\$11	X-OFF ERR KIM
772	1D40	D0 EE		BNE	LOAD8	
773			;			
774			;	DUMP	TO TTY	
775			;	FROM	OPEN CELL ADDRESS	
776			;	TO	LIMHL,LIMHH	
777			;			

778	1D42	A9 00	DUMP	LDA	#\$00	
779	1D44	85 F8		STA	INL	
780	1D46	85 F9		STA	INH	CLEAR RECORD COUNT
781	1D48	A9 00	DUMP0	LDA	#\$00	
782	1D4A	85 F6		STA	CHKHI	CLEAR CHKSUM
783	1D4C	85 F7		STA	CHKSUM	
784			;			
785	1D4E	20 2F 1E		JSR	CRLF	PRINT CR LF
786	1D51	A9 3B		LDA	#\$3B	PRINT SEMICOLON
787	1D53	20 A0 1E		JSR	OUTCH	
788	1D56	A5 FA		LDA	POINTL	TEST POINT GT OR ET
789	1D58	CD F7 17		CMP	EAL	HI LIMIT GOTO EXIT
790	1D5B	A5 FB		LDA	POINTH	
791	1D5D	ED F8 17		SBC	EAH	

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CARD #	LOC	CODE		CARD		
792	1D60	90 18		BCC	DUMP4	
793			;			
794	1D62	A9 00		LDA	#\$00	PRINT LAST RECORD
795	1D64	20 3B 1E		JSR	PRTBYT	0 BYTES
796	1D67	20 CC 1F		JSR	OPEN	
797	1D6A	20 1E 1E		JSR	PRTPNT	
798			;			
799	1D6D	A5 F6		LDA	CHKHI	PRINT CHKSUM
800	1D6F	20 3B 1E		JSR	PRTBYT	FOR LAST RECORD
801	1D72	A5 F7		LDA	CHKSUM	
802	1D74	20 3B 1E		JSR	PRTBYT	
803	1D77	4C 64 1C		JMP	CLEAR	
804			;			
805	1D7A	A9 18	DUMP4	LDA	#\$18	PRINT 24 BYTE COUNT
806	1D7C	AA		TAX		SAVE AS INDEX
807	1D7D	20 3B 1E		JSR	PRTBYT	
808	1D80	20 91 1F		JSR	CHK	
809	1D83	20 1E 1E		JSR	PRTPNT	
810			;			
811	1D86	A0 00	DUMP2	LDY	#\$00	PRINT 24 BYTES
812	1D88	B1 FA		LDA	(POINTL),Y	GET DATA
813	1D8A	20 3B 1E		JSR	PRTBYT	PRINT DATA
814	1D8D	20 91 1F		JSR	CHK	COMPUTE CHKSUM
815	1D90	20 63 1F		JSR	INCPT	INCREMENT POINT
816	1D93	CA		DEX		
817	1D94	D0 F0		BNE	DUMP2	
818			;			
819	1D96	A5 F6		LDA	CHKHI	PRINT CHKSUM
820	1D98	20 3B 1E		JSR	PRTBYT	
821	1D9B	A5 F7		LDA	CHKSUM	
822	1D9D	20 3B 1E		JSR	PRTBYT	
823	1DA0	E6 F8		INC	INL	INCR RECORD COUNT
824	1DA2	D0 02		BNE	DUMP3	
825	1DA4	E6 F9		INC	INH	
826	1DA6	4C 48 1D	DUMP3	JMP	DUMP0	
827			;			
828	1DA9	20 CC 1F	SPACE	JSR	OPEN	OPEN NEW CELL
829	1DAC	20 2F 1E	SHOW	JSR	CRLF	PRINT CR LF
830	1DAF	20 1E 1E	SHOW1	JSR	PRTPNT	
831	1DB2	20 9E 1E		JSR	OUTSP	PRINT SPACE
832	1DB5	A0 00		LDY	#\$00	PRINT DATA SPECIFIED
833	1DB7	B1 FA		LDA	(POINTL),Y	BY POINT AD=LDA EXT
834	1DB9	20 3B 1E		JSR	PRTBYT	
835	1DBC	20 9E 1E		JSR	OUTSP	PRINT SPACE
836	1DBF	4C 64 1C		JMP	CLEAR	

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837
838 1DC2 20 63 1F ; RTRN JSR INCPT OPEN NEXT CELL
839 1DC5 4C AC 1D JMP SHOW
840
841 1DC8 A6 F2 ; GOEXEC LDX SPUSER
842 1DCA 9A TXS
843 1DCB A5 FB LDA POINTH PROGRAM RUNS FROM

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CARD #	LOC	CODE	CARD		
844	1DCD	48	PHA		OPEN CELL ADDRESS
845	1DCE	A5 FA	LDA	POINTL	
846	1DD0	48	PHA		
847	1DD1	A5 F1	LDA	PREG	
848	1DD3	48	PHA		
849	1DD4	A6 F5	LDX	XREG	RESTORE REGS
850	1DD6	A4 F4	LDY	YREG	
851	1DD8	A5 F3	LDA	ACC	
852	1DDA	40	RTI		
853					
854	1ddb	C9 20	SCAN	CMP	#\$20 OPEN CELL
855	1DDD	F0 CA		BEQ	SPACE
856	1DDF	C9 7F		CMP	#\$7F RUB OUT (KIM)
857	1DE1	F0 1B		BEQ	STV
858	1DE3	C9 0D		CMP	#\$0D NEXT CELL
859	1DE5	F0 DB		BEQ	RTRN
860	1DE7	C9 0A		CMP	#\$0A PREV CELL
861	1DE9	F0 1C		BEQ	FEED
862	1DEB	C9 2E		CMP	#' . MODIFY CELL
863	1DED	F0 26		BEQ	MODIFY
864	1DEF	C9 47		CMP	#' G GO EXEC
865	1DF1	F0 D5		BEQ	GOEXEC
866	1DF3	C9 51		CMP	#' Q DUMP FROM OPEN CELL TO HI LIMIT
867	1DF5	F0 0A		BEQ	DUMPV
868	1DF7	C9 4C		CMP	#' L LOAD TAPE
869	1DF9	F0 09		BEQ	LOADV
870	1DFB	4C 6A 1C		JMP	READ IGNORE ILLEGAL CHAR
871					
872	1DFE	4C 4F 1C	STV	JMP	START
873	1E01	4C 42 1D	DUMPV	JMP	DUMP
874	1E04	4C E7 1C	LOADV	JMP	LOAD
875					
876	1E07	38	FEED	SEC	
877	1E08	A5 FA		LDA	POINTL DEC DOUBLE BYTE
878	1E0A	E9 01		SBC	#\$01 AT POINTL AND POINTH
879	1E0C	85 FA		STA	POINTL
880	1E0E	B0 02		BCS	FEED1
881	1E10	C6 FB		DEC	POINTH
882	1E12	4C AC 1D	FEED1	JMP	SHOW
883					
884	1E15	A0 00	MODIFY	LDY	#\$00 GET CONTENTS OF INPUT BUFF
885	1E17	A5 F8		LDA	INL INL AND STORE IN LOC
886	1E19	91 FA		STA	(POINTL),Y SPECIFIED BY POINT
887	1E1B	4C C2 1D		JMP	RTRN
888					
889					END OF MAIN LINE

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CARD #	LOC	CODE	CARD
891			; SUBROUTINES FOLLOW
892			;
893			;
894			;
895			; SUB TO PRINT POINTL,POINTH
896			;
897	1E1E	A5 FB	PRTPNT LDA POINTH
898	1E20	20 3B 1E	JSR PRTBYT
899	1E23	20 91 1F	JSR CHK
900	1E26	A5 FA	LDA POINTL
901	1E28	20 3B 1E	JSR PRTBYT
902	1E2B	20 91 1F	JSR CHK
903	1E2E	60	RTS
904			;
905			; PRINT STRING OF ASCII CHARS FROM
906			; TOP+X TO TOP
907			;
908	1E2F	A2 07	CRLF LDX #\$07
909	1E31	BD D5 1F	PRTST LDA TOP,X
910	1E34	20 A0 1E	JSR OUTCH
911	1E37	CA	DEX
912	1E38	10 F7	BPL PRTST STOP ON INDEX ZERO
913	1E3A	60	RTS
914			;
915			; PRINT 1 HEX BYTE AS TWO ASCII CHAR'S
916			;
917	1E3B	85 FC	PRTBYT STA TEMP
918	1E3D	4A	LSR A SHIFT CHAR RIGHT 4 BITS
919	1E3E	4A	LSR A
920	1E3F	4A	LSR A
921	1E40	4A	LSR A
922	1E41	20 4C 1E	JSR HEXTA CONVERT TO HEX AND PRINT
923	1E44	A5 FC	LDA TEMP GET OTHER HALF
924	1E46	20 4C 1E	JSR HEXTA CONVERT TO HEX AND PRINT
925	1E49	A5 FC	LDA TEMP RESTORE BYTE IN A AND RETURN
926	1E4B	60	RTS
927			;
928	1E4C	29 0F	HEXTA AND #\$0F MASK HI 4 BITS
929	1E4E	C9 0A	CMP #\$0A
930	1E50	18	CLC
931	1E51	30 02	BMI HEXTA1
932	1E53	69 07	ADC #\$07 ALPHA HEX
933	1E55	69 30	HEXTA1 ADC #\$30 DEC HEX
934	1E57	4C A0 1E	JMP OUTCH PRINT CHAR
935			;
936			; GET 1 CHAR FROM TTY
937			; CHAR IN A
938			; X IS PRESERVED AND Y RETURNED = FF
939			;
940	1E5A	86 FD	GETCH STX TMPX SAVE X REG
941	1E5C	A2 08	LDX #\$08 SET UP 8-BIT CNT
942	1E5E	A9 01	LDA #\$01

CARD #	LOC	CODE	CARD
943	1E60	2C 40 17	GET1 BIT SAD
944	1E63	D0 22	BNE GET6
945	1E65	30 F9	BMI GET1 WAIT FOR START BIT
946	1E67	20 D4 1E	JSR DELAY DELAY 1 BIT
947	1E6A	20 EB 1E	GET5 JSR DEHALF DELAY 1/2 BIT TIME
948	1E6D	AD 40 17	GET2 LDA SAD GET 8 BITS

949	1E70	29 80		AND	#\$80	MASK OFF LOW ORDER BITS
950	1E72	46 FE		LSR	CHAR	SHIFT RIGHT CHAR
951	1E74	05 FE		ORA	CHAR	
952	1E76	85 FE		STA	CHAR	
953	1E78	20 D4 1E		JSR	DELAY	DELAY 1 BIT TIME
954	1E7B	CA		DEX		
955	1E7C	D0 EF		BNE	GET2	GET NEXT CHAR
956	1E7E	20 EB 1E		JSR	DEHALF	EXIT THIS RTN
957			;			
958	1E81	A6 FD		LDX	TMPX	
959	1E83	A5 FE		LDA	CHAR	
960	1E85	2A		ROL	A	SHIFT OFF PARITY
961	1E86	4A		LSR	A	
962	1E87	60	GET6	RTS		
963			;			
964			;			INITIALIZATION FOR SIGMA
965			;			
966	1E88	A2 01	INITS	LDX	#\$01	SET KB MODE TO ADDR
967	1E8A	86 FF		STX	MODE	
968			;			
969	1E8C	A2 00	INIT1	LDX	#\$00	
970	1E8E	8E 41 17		STX	PADD	FOR SIGMA USE SADD
971	1E91	A2 3F		LDX	#\$3F	
972	1E93	8E 43 17		STX	PBDD	FOR SIGMA USE SBDD
973	1E96	A2 07		LDX	#\$07	ENABLE DATA IN
974	1E98	8E 42 17		STX	SBD	OUTPUT
975	1E9B	D8		CLD		
976	1E9C	78		SEI		
977	1E9D	60		RTS		
978			;			
979			;			PRINT 1 CHAR CHAR IN A
980			;			X IS PRESERVED Y RETURNED = FF
981			;			OUTSP PRINTS 1 SPACE
982			;			
983	1E9E	A9 20	OUTSP	LDA	#\$20	
984	1EA0	85 FE	OUTCH	STA	CHAR	
985	1EA2	86 FD		STX	TMPX	
986	1EA4	20 D4 1E		JSR	DELAY	10/11 BIT CODE SYNC
987	1EA7	AD 42 17		LDA	SBD	START BIT
988	1EAA	29 FE		AND	#\$FE	
989	1EAC	8D 42 17		STA	SBD	
990	1EAF	20 D4 1E		JSR	DELAY	
991	1EB2	A2 08		LDX	#\$08	
992	1EB4	AD 42 17	OUT1	LDA	SBD	DATA BIT
993	1EB7	29 FE		AND	#\$FE	
994	1EB9	46 FE		LSR	CHAR	

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CARD #	LOC	CODE	CARD		
995	1EBB	69 00	ADC	#\$00	
996	1EBD	8D 42 17	STA	SBD	
997	1EC0	20 D4 1E	JSR	DELAY	
998	1EC3	CA	DEX		
999	1EC4	D0 EE	BNE	OUT1	
1000	1EC6	AD 42 17	LDA	SBD	STOP BIT
1001	1EC9	09 01	ORA	#\$01	
1002	1ECB	8D 42 17	STA	SBD	
1003	1ECE	20 D4 1E	JSR	DELAY	STOP BIT
1004	1ED1	A6 FD	LDX	TMPX	RESTORE INDEX
1005	1ED3	60	RTS		
1006			;		
1007			;		DELAY 1 BIT TIME

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1008                ;      AS DETERMEND BY DETCPS
1009                ;
1010 1ED4 AD F3 17 DELAY LDA CNTH30 THIS LOOP SIMULATES
1011 1ED7 8D F4 17 STA TIMH DETCPS SECTION AND WILL DELAY
1012 1EDA AD F2 17 LDA CNTL30 1 BIT TIME
1013 1EDD 38 DE2 SEC
1014 1EDE E9 01 DE4 SBC #$01
1015 1EE0 B0 03 BCS DE3
1016 1EE2 CE F4 17 DEC TIMH
1017 1EE5 AC F4 17 DE3 LDY TIMH
1018 1EE8 10 F3 BPL DE2
1019 1EEA 60 RTS
1020                ;
1021                ;      DELAY 1/2 BIT TIME
1022 1EEB AD F3 17 DEHALF LDA CNTH30 DOUBLE RIGHT SHIFT OF DELAY
1023 1EEE 8D F4 17 STA TIMH CONSTANT FOR A DIV BY 2
1024 1EF1 AD F2 17 LDA CNTL30
1025 1EF4 4A LSR A
1026 1EF5 4E F4 17 LSR TIMH
1027 1EF8 90 E3 BCC DE2
1028 1EFA 09 80 ORA #$80
1029 1EFC B0 E0 BCS DE4
1030                ;
1031                ;      SUB TO DETERMINE IF KEY IS
1032                ;      DEPRESSED OR CONDITION OF SSW
1033                ;      KEY NOT DEP OR TTY MODE      A=0
1034                ;      KEY DEP OR KB MODE          A NOT ZERO
1035                ;
1036                ;
1037 1EFE A0 03 AK LDY #$03 3 ROWS
1038 1F00 A2 01 LDX #$01 DIGIT 0
1039                ;
1040 1F02 A9 FF ONEKEY LDA #$FF
1041 1F04 8E 42 17 AK1 STX SBD OUTPUT DIGIT
1042 1F07 E8 INX GET NEXT DIGIT
1043 1F08 E8 INX
1044 1F09 2D 40 17 AND SAD INPUT SEGMENTS
1045 1F0C 88 DEY
1046 1F0D D0 F5 BNE AK1

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CARD # LOC      CODE      CARD
1047                ;
1048 1F0F A0 07 LDY #$07
1049 1F11 8C 42 17 STY SBD
1050                ;
1051 1F14 09 80 ORA #$80
1052 1F16 49 FF EOR #$FF
1053 1F18 60 RTS
1054                ;
1055                ;      SUB OUTPUT TO 7-SEGMENT DISPLAY
1056                ;
1057 1F19 A0 00 SCAND LDY #$00 GET DATA SPECIFIED
1058 1F1B B1 FA LDA (POINTL),Y BY POINT
1059 1F1D 85 F9 STA INH SET UP DISPLAY BUFFER
1060 1F1F A9 7F SCANDS LDA #$7F CHANGE SEG
1061 1F21 8D 41 17 STA PADD TO OUTPUT
1062                ;
1063 1F24 A2 09 LDX #$09 INIT DIGIT NUMBER
1064 1F26 A0 03 LDY #$03 OUTPUT 3 BYTES
1065                ;
1066 1F28 B9 F8 00 SCAND1 LDA INL,Y GET BYTE

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1067	1F2B	4A		LSR	A	GET MSD
1068	1F2C	4A		LSR	A	
1069	1F2D	4A		LSR	A	
1070	1F2E	4A		LSR	A	
1071	1F2F	20 48 1F		JSR	CONVD	OUTPUT CHAR
1072	1F32	B9 F8 00		LDA	INL,Y	GET BYTE AGAIN
1073	1F35	29 0F		AND	#\$0F	GET LSD
1074	1F37	20 48 1F		JSR	CONVD	OUTPUT CHAR
1075	1F3A	88		DEY		SET UP FOR NXT BYTE
1076	1F3B	D0 EB		BNE	SCAND1	
1077	1F3D	8E 42 17		STX	SBD	ALL DIGITS OFF
1078	1F40	A9 00		LDA	#\$00	CHANGE SEGMENT
1079	1F42	8D 41 17		STA	PADD	TO INPUTS
1080	1F45	4C FE 1E		JMP	AK	GET ANY KEY
1081			;			
1082			;			CONVERT AND DISPLAY HEX
1083			;			USED BY SCAND ONLY
1084			;			
1085	1F48	84 FC	CONVD	STY	TEMP	SAVE Y
1086	1F4A	A8		TAY		USE CHAR AS INDEX
1087	1F4B	B9 E7 1F		LDA	TABLE,Y	LOOKUP CONVERSION
1088	1F4E	A0 00		LDY	#\$00	TURN OFF SEGMENTS
1089	1F50	8C 40 17		STY	SAD	
1090	1F53	8E 42 17		STX	SBD	OUTPUT DIGIT ENABLE
1091	1F56	8D 40 17		STA	SAD	OUT PUT SEGMENTS
1092			;			
1093	1F59	A0 7F		LDY	#\$7F	DELAY 500 CYCLES APPROX.
1094	1F5B	88	CONVD1	DEY		
1095	1F5C	D0 FD		BNE	CONVD1	
1096			;			
1097	1F5E	E8		INX		GET NEXT DIGIT NUMBER
1098	1F5F	E8		INX		ADD 2

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CARD #	LOC	CODE	CARD			
1099	1F60	A4 FC		LDY	TEMP	RESTORE Y
1100	1F62	60		RTS		
1101			;			
1102			;			SUB TO INCREMENT POINT
1103			;			
1104	1F63	E6 FA	INCPT	INC	POINTL	
1105	1F65	D0 02		BNE	INCPT2	
1106	1F67	E6 FB		INC	POINTH	
1107	1F69	60	INCPT2	RTS		
1108			;			
1109			;			GET KEY FROM KEY BOARD
1110			;			RETURN WITH A=KEY VALUE
1111			;			GT. 15 THEN ILLEGAL OR NO KEY
1112			;			
1113			;			
1114	1F6A	A2 21	GETKEY	LDX	#\$21	START AT DIGIT 0
1115	1F6C	A0 01	GETKE5	LDY	#\$01	GET 1 ROW
1116	1F6E	20 02 1F		JSR	ONEKEY	
1117	1F71	D0 07		BNE	KEYIN	A=0 NO KEY
1118	1F73	E0 27		CPX	#\$27	TEST FOR DIGIT 2
1119	1F75	D0 F5		BNE	GETKE5	
1120	1F77	A9 15		LDA	#\$15	15=NOKEY
1121	1F79	60		RTS		
1122	1F7A	A0 FF	KEYIN	LDY	#\$FF	
1123	1F7C	0A	KEYIN1	ASL	A	SHIFT LEFT
1124	1F7D	B0 03		BCS	KEYIN2	UNTIL Y=KEY NUM
1125	1F7F	C8		INY		

1126	1F80	10 FA		BPL	KEYIN1	
1127	1F82	8A	KEYIN2	TXA		
1128	1F83	29 0F		AND	#\$0F	MASK MSD
1129	1F85	4A		LSR	A	DIVIDE BY 2
1130	1F86	AA		TAX		
1131	1F87	98		TYA		
1132	1F88	10 03		BPL	KEYIN4	
1133	1F8A	18	KEYIN3	CLC		
1134	1F8B	69 07		ADC	#\$07	MULT (X-1) TIMES A
1135	1F8D	CA	KEYIN4	DEX		
1136	1F8E	D0 FA		BNE	KEYIN3	
1137	1F90	60		RTS		
1138				;		
1139				;	SUB TO COMPUTE CHECK SUM	
1140				;		
1141	1F91	18	CHK	CLC		
1142	1F92	65 F7		ADC	CHKSUM	
1143	1F94	85 F7		STA	CHKSUM	
1144	1F96	A5 F6		LDA	CHKHI	
1145	1F98	69 00		ADC	#\$00	
1146	1F9A	85 F6		STA	CHKHI	
1147	1F9C	60		RTS		
1148				;		
1149				;	GET 2 HEX CHAR'S AND PACK	
1150				;	INTO INL AND INH	

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CARD #	LOC	CODE	CARD			
1151			;	X PRESERVED	Y RETURNED = 0	
1152			;	NON HEX CHAR WILL BE LOADED AS NEAREST HEX EQU		
1153			;			
1154	1F9D	20 5A 1E	GETBYT	JSR	GETCH	
1155	1FA0	20 AC 1F		JSR	PACK	
1156	1FA3	20 5A 1E		JSR	GETCH	
1157	1FA6	20 AC 1F		JSR	PACK	
1158	1FA9	A5 F8		LDA	INL	
1159	1FAB	60		RTS		
1160			;			
1161			;	SHIFT CHAR IN A INTO		
1162			;	INL AND INH		
1163			;			
1164	1FAC	C9 30	PACK	CMP	#\$30	CHECK FOR HEX
1165	1FAE	30 1B		BMI	UPDAT2	
1166	1FB0	C9 47		CMP	#\$47	NOT HEX EXIT
1167	1FB2	10 17		BPL	UPDAT2	
1168	1FB4	C9 40		CMP	#\$40	CONVERT TO HEX
1169	1FB6	30 03		BMI	UPDATE	
1170	1FB8	18		CLC		
1171	1FB9	69 09		ADC	#\$09	
1172	1FBB	2A	UPDATE	ROL	A	
1173	1FBC	2A		ROL	A	
1174	1FBD	2A		ROL	A	
1175	1FBE	2A		ROL	A	
1176	1FBF	A0 04		LDY	#\$04	SHIFT INTO I/O BUFFER
1177	1FC1	2A	UPDAT1	ROL	A	
1178	1FC2	26 F8		ROL	INL	
1179	1FC4	26 F9		ROL	INH	
1180	1FC6	88		DEY		
1181	1FC7	D0 F8		BNE	UPDAT1	
1182	1FC9	A9 00		LDA	#\$00	A=0 IF HEX NUM
1183	1FCB	60	UPDAT2	RTS		
1184			;			
1185	1FCC	A5 F8	OPEN	LDA	INL	MOVE I/O BUFFER TO POINT

1186	1FCE	85 FA		STA	POINTL	
1187	1FD0	A5 F9		LDA	INH	TRANSFER INH- POINTH
1188	1FD2	85 FB		STA	POINTH	
1189	1FD4	60		RTS		
1190			;			
1191			;			
1192			;		END OF SUBROUTINES	

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CARD #	LOC	CODE		CARD
1194			;	
1195			;	TABLES
1196			;	
1197	1FD5	00	TOP	.BYTE \$00,\$00,\$00,\$00,\$00,\$00,\$0A,\$0D,'MIK'
1197	1FD6	00		
1197	1FD7	00		
1197	1FD8	00		
1197	1FD9	00		
1197	1FDA	00		
1197	1FDB	0A		
1197	1FDC	0D		
1197	1FDD	4D 49 4B		
1198	1FE0	20		.BYTE ' ', \$13, 'RRE', ' ', \$13
1198	1FE1	13		
1198	1FE2	52 52 45		
1198	1FE5	20		
1198	1FE6	13		
1199			;	
1200			;	TABLE HEX TO 7 SEGMENT
1201			;	0 1 2 3 4 5 6 7
1202	1FE7	BF	TABLE	.BYTE \$BF,\$86,\$DB,\$CF,\$E6,\$ED,\$FD,\$87
1202	1FE8	86		
1202	1FE9	DB		
1202	1FEA	CF		
1202	1FEB	E6		
1202	1FEC	ED		
1202	1FED	FD		
1202	1FEE	87		
1203			;	8 9 A B C D E F
1204	1FEF	FF		.BYTE \$FF,\$EF,\$F7,\$FC,\$B9,\$DE,\$F9,\$F1
1204	1FF0	EF		
1204	1FF1	F7		
1204	1FF2	FC		
1204	1FF2	B9		
1204	1FF4	DE		
1204	1FF5	F9		
1204	1FF6	F1		

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CARD #	LOC	CODE		CARD
1206			;	
1207			;	
1208			;	
1209			;	
1210			;	INTERRUPT VECTORS
1211			;	
1212	1FF7			*=\$1FFA
1213	1FFA	1C 1C	NMIENT	.WORD NMIT
1214	1FFC	22 1C	RSTENT	.WORD RST
1215	1FFE	1F 1C	IRQENT	.WORD IRQT

END OF MOS/TECHNOLOGY 650X ASSEMBLY VERSION 4

NUMBER OF ERRORS = 0, NUMBER OF WARNINGS = 0

SYMBOL TABLE DUMP

SYMBOL	VALUE	LINE	DEFINED	CROSS REFERENCES						
ACC	00F3	76	587	851						
ADDR	1CBE	694	687							
ADDRM	1CC8	701	673							
AK	1EFE	1037	1080							
AK1	1F04	1041	1046							
CHAR	00FE	90	950	951	952	959	984	994		
CHK	1F91	1141	734	738	741	748	808	814	899	902
CHKH	17E8	97	158	265	289	299	301			
CHKHI	00F6	82	730	755	782	799	819	1144	1146	
CHKL	17E7	96	156	262	288	297	298			
CHKSUM	00F7	83	729	758	783	801	821	1142	1143	
CHKT	194C	295	234	237	242	244	256	308		
CHT1	1982	336	344							
CHT2	198E	341	338							
CHT3	1991	342	340							
CLEAR	1C64	645	803	836						
CLKKT	1747	65	****							
CLKRDI	1747	66	355	361	378	384	498	505		
CLKRDT	1746	67	459	471						
CLK1T	1744	62	358	364	381	387	501	508		
CLK64T	1746	64	461	473						
CLK8T	1745	63	****							
CNTH30	17F3	101	613	622	1010	1022				
CNTL30	17F2	100	625	1012	1024					
CONVD	1F48	1085	1071	1074						
CONVD1	1F5B	1094	1095							
CRLF	1E2F	908	640	785	829					
DATA	1CA8	680	****							
DATAM	1CCC	704	675							
DATAM1	1CCE	705	702							
DATAM2	1CD0	706	699							
DATA1	1CB0	686	698							
DATA2	1CC3	697	692							
DEHALF	1EEB	1022	947	956						
DELAY	1ED4	1010	946	953	986	990	997	1003		
DETCPS	1C2A	612	****							
DET1	1C31	615	617							
DET2	1C42	623	621							
DET3	1C3A	619	624							
DE2	1EDD	1013	1018	1027						
DE3	1EE5	1017	1015							
DE4	1EDE	1014	1029							
DUMP	1D42	778	873							
DUMPT	1800	121	****							
DUMPT1	1814	131	134							
DUMPT2	1833	148	177							
DUMPT3	1854	163	166							
DUMPT4	1865	173	152							
DUMPV	1E01	873	867							
DUMP0	1D48	781	826							
DUMP1	1D4E	785	****							

DUMP2	1D86	811	817						
DUMP3	1DA6	926	824						
DUMP4	1D7A	805	792						
EAH	17F8	106	151	791					
EAL	17F7	105	149	789					
FEED	1E07	987	861						
FEED1	1E12	882	880						
GETBYT	1F9D	1154	732	736	739	746	754	757	770
GETCH	1E5A	940	648	725	1154	1156			
GETK	1C8D	667	****						
GETKEY	1F6A	1114	667						
GETKE5	1F6C	1115	1119						
GET1	1E60	943	945						
GET2	1E6D	948	955						
GET5	1E6A	947	627						
GET6	1E87	962	944						
GOEXEC	1DC8	841	711	865					
GOV	1CD9	711	679						
HEXALP	1FB9	1170	****						
HEXNUM	1FB4	1168	****						
HEXOUT	196F	323	314	316					
HEXTA	1E4C	928	922	924					
HEXTA1	1E55	933	931						
HEX1	1978	928	326						
ID	17F9	107	140	224	226				
INCPT	1F63	1104	708	749	815	838			
INCPT2	1F69	1107	1105						
INCVEB	19EA	397	176	258					
INCVE1	19F2	400	398						
INH	00F9	85	647	760	625	1059	1179	1187	
INITS	1E88	966	600	609					
INIT1	1E8C	969	636						
INL	00F8	84	646	779	823	885	1066	1072	1158 1178 1185
INTVEB	1932	281	123	185					
IRQENT	1FFE	1215	****						
IRQP27	1BFE	519	****						
IRQT	1C1F	904	1215						
IRQV	17FE	113	604						
KEYIN	1F7A	1122	1117						
KEYIN1	1F7C	1123	1126						
KEYIN2	1F82	1127	1124						
KEYIN3	1F8A	1133	1136						
KEYIN4	1F8D	1135	1132						
LOAD	1CE7	725	727	762	874				
LOADER	1D3E	771	759						
LOADE1	1D3B	770	756						
LOADS	1CEE	728	****						
LOADT	1873	183	231						
LOADT4	18B5	216	221						
LOADT5	18D7	233	225	228					
LOADT6	18EC	241	230						
LOADT7	18F8	247	239	259					
LOADT8	1915	261	250						
LOADT9	1929	270	252	263	266				

LOADV	1E04	874	869
LOAD10	192B	271	268
LOAD11	18C2	223	218
LOAD12	190F	258	182
LOAD13	18FA	248	254
LOAD2	1D0E	764	751
LOAD3	1D1D	754	744

SAVE2	1C0F	596	****								
SAVX	17E9	98	198	201	202	203	204	233	324	345	346
			427	430	439	442	443	444	448	451	
SBD	1742	60	126	195	360	366	383	389	457	467	494
			503	510	766	974	987	989	992	996	1000
			1002	1041							
			1049	1077	1090						
SCAN	1DDB	854	652								
SCAND	1F19	1057	657	662	664						
SCAND1	1F28	1060	****								
SCAND1	1F28	1066	1076								
SHOW	1DAC	829	839	882							
SHOW1	1DAF	930	643								
SPACE	1DA9	828	855								
SPUSER	00F2	75	599	608	841						
START	1C4F	636	171	273	601	616	658	661	669	706	709
			721	768	872						
STEP	1CD3	708	677								
STV	1DFE	872	857								
SYNC	1891	197	211	220							
SYNC1	1896	200	206								
SYNC2	18AB	209	213								
TAB	1871	182	189	191							
TABLE	1FE7	1202	1087								
TEMP	00FC	88	684	689	917	923	925	1085	1099		
TIMH	17F4	102	1011	1016	1017	1023	1026				
TMPX	00FD	89	940	958	985	1004					
TOP	1FD5	1197	909								
TTYKB	1C77	657	639	650							
TTYKB1	1C7C	659	663	665							
UPDATE	1FBB	1172	1169								
UPDAT1	1FC1	1177	1181								
UPDAT2	1FCB	1183	1165	1167							
VEB	17EC	99	122	148	150	173	184	188	190	192	235
			238	257	282	284	286	397	399		
XREG	00F5	77	597	849							
YREG	00F4	78	596	850							
ZR0	19C4	367	341	342							
ZR01	19C7	378	379	391							
ZR02	19D6	384	385								

INSTRUCTION COUNT

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ADC 13
AND 9
ASL 7
BCC 4
BCS 5
BEQ 26
BIT 12
BMI 9
BNE 44
BPL 15
BRK 0
BVC 0
BVS 0
CLC 8
CLD 1
CLI 0
CLV 0
CMP 38
CPX 1
CPY 0

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DEC 2
DEX 14
DEY 8
EOR 2
INC 7
INX 5
INY 2
JMP 31
JSR 115
LDA 108
LDX 29
LDY 25
LSR 22
NOP 0
ORA 6
PHA 5
PHP 0
PLA 5
PLP 0
ROL 18
RTI 1
RTS 28
SBC 5
SEC 3
SED 0
SEI 1
STA 81
STX 14
STY 7
TAX 3
TAY 3
TSX 1
TXA 3
TXS 2
TYA 4

SYMBOLS = 204 (LIMIT = 400)
LINES = 1242 (LIMIT = 1500)
TOP 0

BYTES = 1690 (LIMIT = 4096)
XREFS = 646 (LIMIT = 900)
