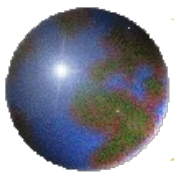


CSH2G3: Design & Analysis of Algorithm

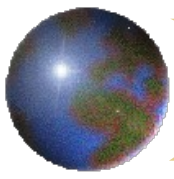
Branch and Bound

Rimba Whidiana Ciptasari



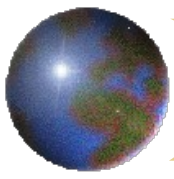
The idea behind the BnB

- ✚ Like backtracking,
 - ▣ It constructs state space tree whose solution set is exponential in size
 - ▣ The complexity, in worst case, exponential
 - ▣ Significantly decrease execution time by use of “promising” function



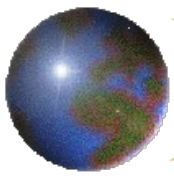
The idea behind the BnB

- ✚ The difference between BnB and Backtracking,
 - ✚ It is a method to solve **combinatorial optimization problems**
 - ✚ It is necessary to provide **a bound** on the best value of the objective function.
 - ✚ The way it traverses the state space tree → **BFS** (*Breadth First Search*)



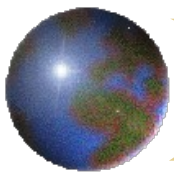
Minimization problem: lower bound

Maximization problem: upper bound



Two strategies in traversing tree

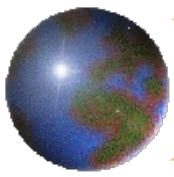
- ✚ Breadth-first branch and bound
- ✚ Best-first branch and bound



General scheme of Breadth First

```
optimumType BranchAndBoundBreadthFirst (StateSpaceTree T){
    optimumType temp, optimum;
    queue<nodeType> Q;
    nodeType u, v;

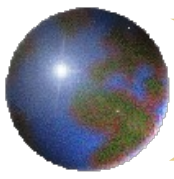
    v = T.root(); // operation root() returns T's root//
    Q.enqueue(v);
    optimum = value(v);
    while(Q.length() is not zero){
        v = Q.dequeue();
        for (each child u of v){
            temp = value(u);
            if (temp is better than optimum){
                optimum = temp;
            }
            if (bound(u) better than optimum){
                Q.enqueue(u);
            }
        }
    }
    return optimum;
}
```



General scheme of Best First

```
optimumType BranchAndBoundBestFirst (StateSpaceTree T){
    optimumType temp, optimum;
    priorityQueue<nodeType> PQ;
    nodeType u, v;

    v = T.root(); // operation root() returns T's root//
    PQ.AddInorder(v);
    optimum = value(v);
    while(PQ.length() is not zero){
        v = PQ.dequeue();
        if (bound(v) is better than optimum){
            for (each child u of v){
                temp = value(u);
                if (temp is better than optimum){
                    optimum = temp;
                }
                if (bound(u) better than optimum){
                    PQ.AddInorder(u);
                }
            }
        }
    }
    return optimum;
}
```



Case 1. Assignment Problem

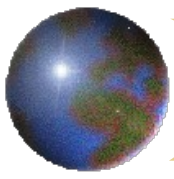
Let us consider n people who need to be assigned n jobs, one person per job (each person is assigned exactly one job and each job is assigned to exactly one person).

Suppose that the cost of assigning job j to person i is $C(i,j)$. Find an assignment with a minimal total cost.

Mathematical description.

Find (s_1, \dots, s_n) with s_i in $\{1, \dots, n\}$ denoting the job assigned to person i such that:

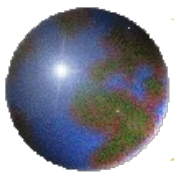
- ✚ $s_i \neq s_k$ for all $i \neq k$ (different persons have to execute different jobs)
- ✚ $C(1, s_1) + C(2, s_2) + \dots + C(n, s_n)$ is minimal



Assignment Problem

Generate only the assignments
which have the chance to be
optimal.

Estimate a **bound** of the cost of
solutions



Assignment Problem

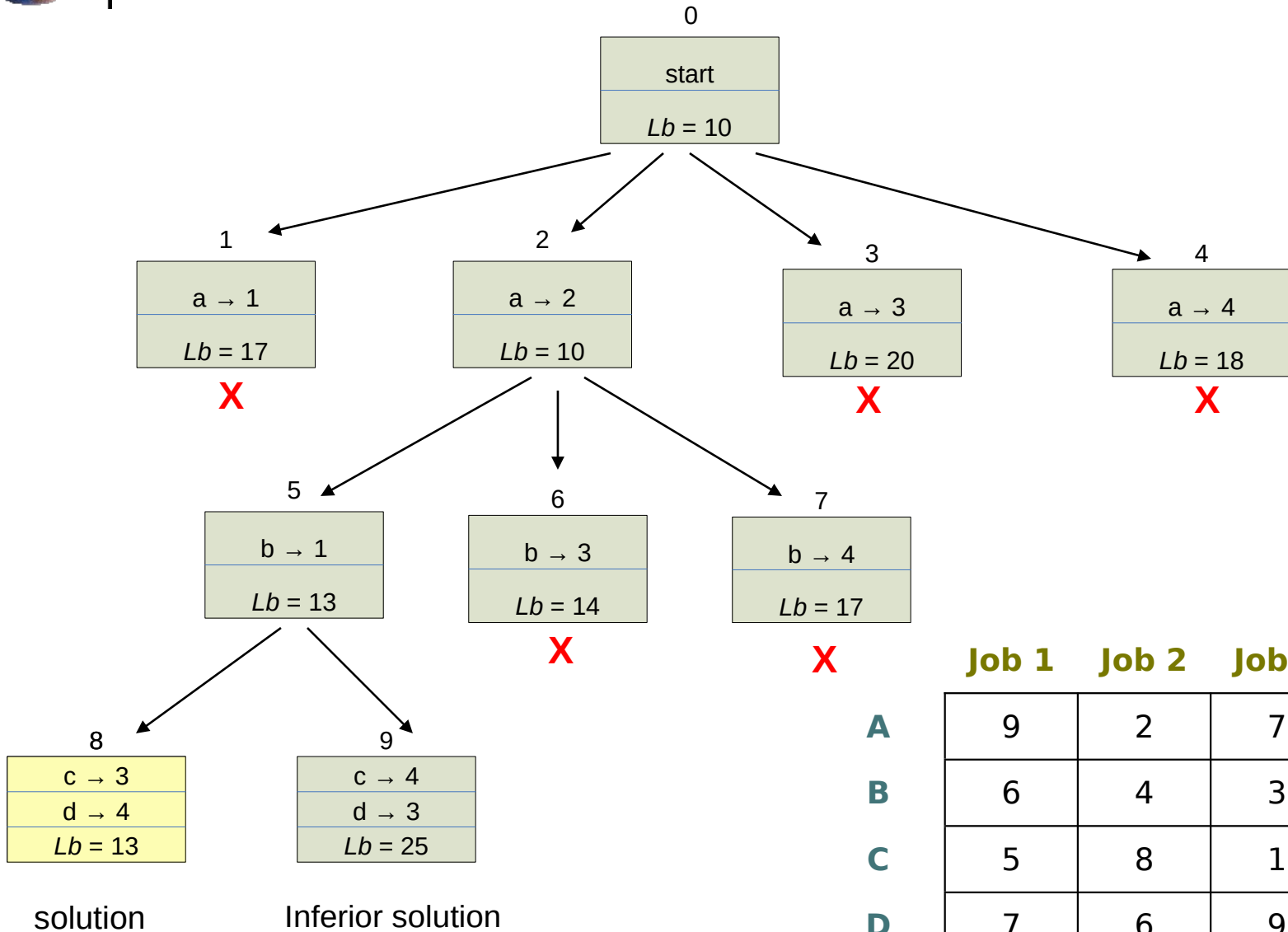
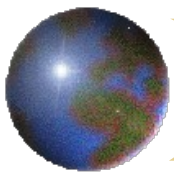
	Job 1	Job 2	Job 3	Job 4
A	9	2	7	8
B	6	4	3	7
C	5	8	1	8
D	7	6	9	4

It is just a of any
legitimate selection

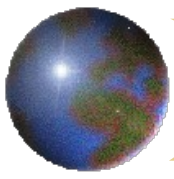
$$\text{lower bound (lb)} = 2 + 3 + 1 + 4 = 10$$

The cost function could be calculated using two approaches:

1. For each worker, we choose job with minimum cost from list of unassigned jobs (**take minimum entry from each row**) → adopted in this lecture.
2. For each job, we choose a worker with lowest cost for that job from list of unassigned workers (**take minimum entry from each column**)



	Job 1	Job 2	Job 3	Job 4
A	9	2	7	8
B	6	4	3	7
C	5	8	1	8
D	7	6	9	4



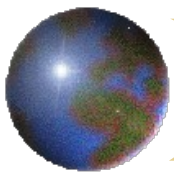
Example. 0/1 Knapsack

- ✚ Order the *value-to-weight ratios* in descending order

$$v_1/w_1 \geq v_2/w_2 \geq \dots \geq v_n/w_n$$

- ✚ Bound:

$$ub = v + (W - w)(v_{i+1}/w_{i+1})$$



0/1 Knapsack

- Consider the following instance of the 0/1 Knapsack

$$n=4, W=10$$

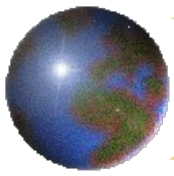
i	v_i	w_i	v_i/w_i
-----	-------	-------	-----------

1	40	4	10
---	----	---	----

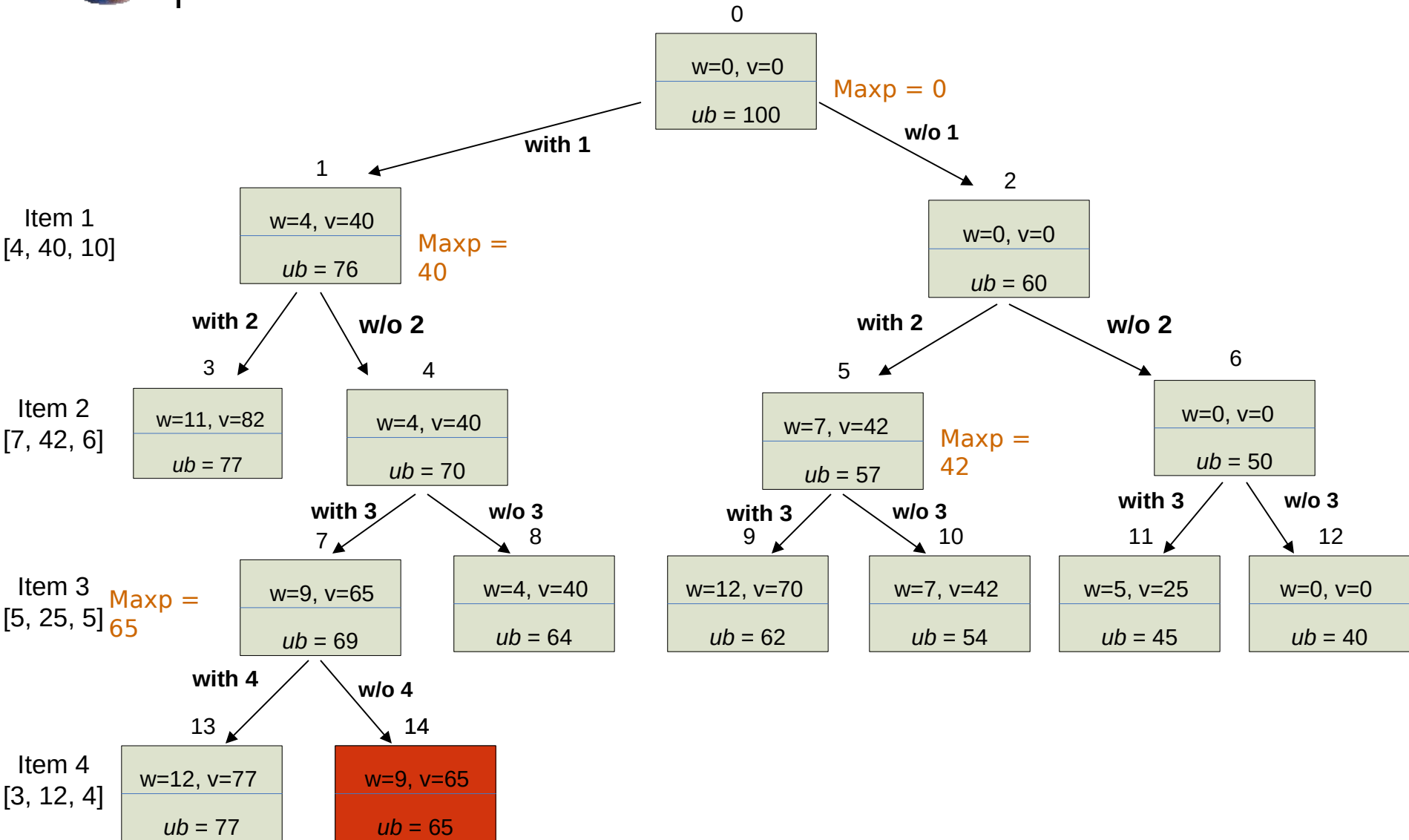
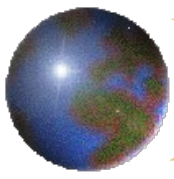
2	42	7	6
---	----	---	---

3	25	5	5
---	----	---	---

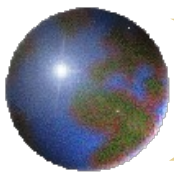
4	12	3	4
---	----	---	---



Breadth-First_0/1Knapsack



solution



Breadth-first_0/1 Knapsack algorithm

Procedure knapsack(n: integer; p,w: array[1..n] of integer; W: integer; var maxprofit: integer)

Var Q: queue of node; u,v: node;

Begin

 Initialized(Q);

 v.level:=0; v.weight:=0; v.profit:=0;

 maxprofit:=0;

 v.bound:=bound(v);

 insert(Q,v);

while not empty(Q) **do**

 remove(Q,v);

 u.level:=v.level+1;

 u.weight:=v.weight+w[u.level];

 u.profit:=v.profit + p[u.level];

if u.weight \leq W **and** u.profit > maxprofit **then**

 maxprofit:=u.profit;

end;

if u.weight \leq W **and** bound(u) > maxprofit **then**

 insert(Q,u);

end;

 u.weight:=v.weight; u.profit:=v.profit;

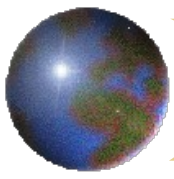
if u.weight \leq W **and** bound(u) > maxprofit **then**

 insert(Q,u);

end;

end;

End;



Function bound(u: node): real;
j,k : index; totweight: integer

Algorithm

If u.weight \geq W **then**
 bound = 0

Else

 bound = u.profit
 j = u.level + 1
 totweight = u.weight;
 k=j
 promising = true

While j \leq n **and** promising **do**

if (totweight + w[j]) \leq W **then**
 totweight = totweight + w[j]
 bound = bound + p[j]
 k=j
 j = j+1

else

 promising = false

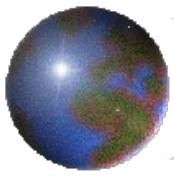
 {end while}

If k \leq n **then**

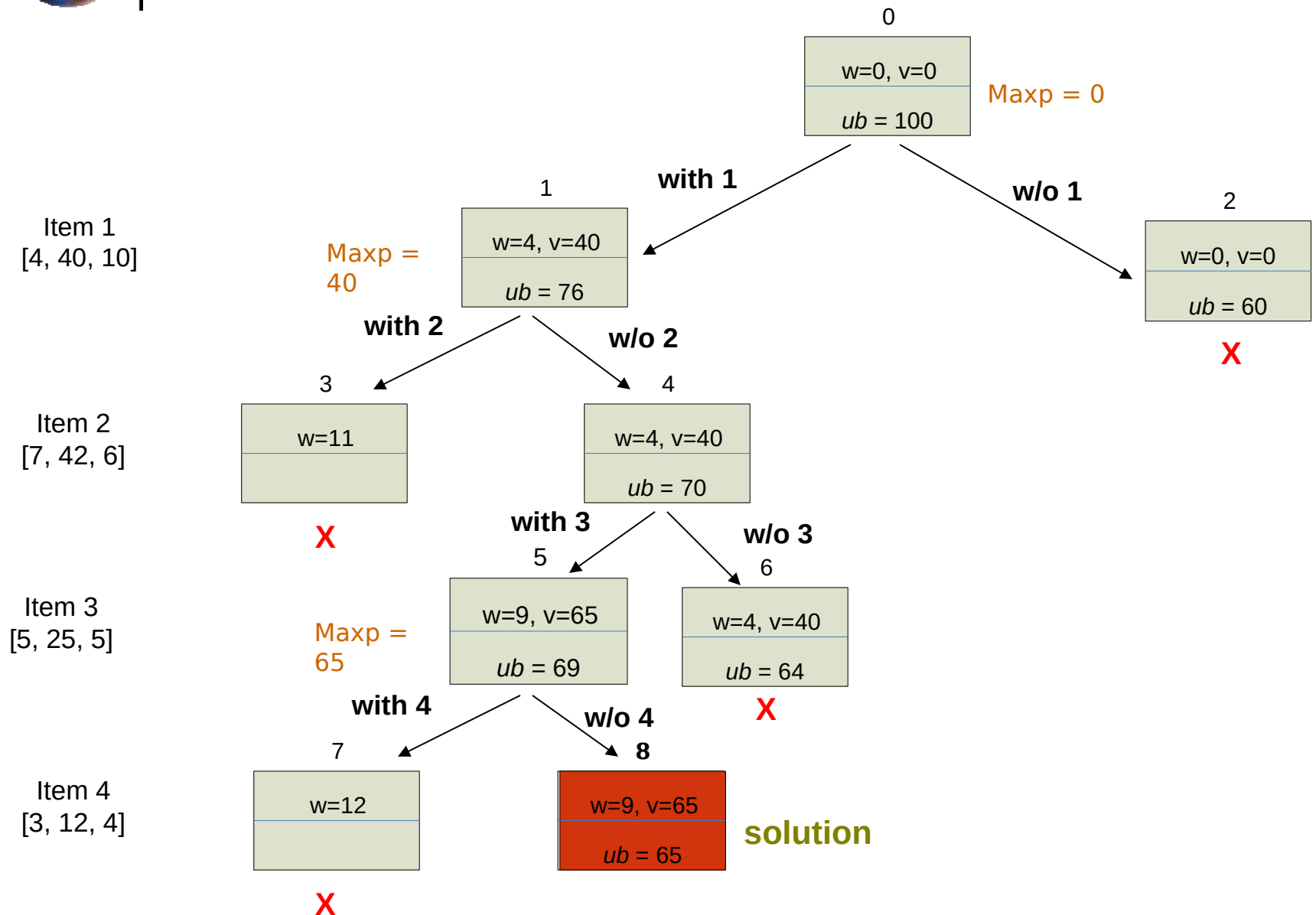
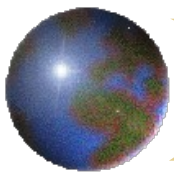
 bound = bound + (W-totweight)*p[k]/w[k]

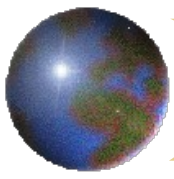
$n=4, W=10$

i	v_i	w_i	v_i/w_i
1	40	4	10
2	42	7	6
3	25	5	5
4	12	3	4



Best-First with Branch-and-Bound Pruning 0/1_Knapsack





Best-First_0/1 Knapsack Algorithm

Procedure knapsack(n: integer; p,w: array[1..n] of integer; W: integer; var maxprofit: integer)

Var PQ: priority_queue of node; u,v: node;

Begin

 Initialized(PQ);

 v.level:=0; v.weight:=0; v.profit:=0;

 maxprofit:=0;

 v.bound:=bound(v);

 insert(PQ,v);

while not empty(PQ) **do**

 remove(PQ,v);

if v.bound > maxprofit **then**

 u.level:=v.level+1;

 u.weight:=v.weight+w[u.level];

 u.profit:=v.profit + p[u.level];

if u.weight ≤ W **and** u.profit > maxprofit **then**

 maxprofit:=u.profit;

end;

if u.weight ≤ W **and** bound(u) > maxprofit **then**

 insert(PQ,u);

end;

 u.weight:=v.weight; u.profit:=v.profit;

if u.weight ≤ W **and** bound(u) > maxprofit **then**

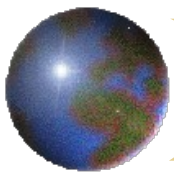
 insert(PQ,u);

end;

end;

end;

End;



Exercise

- ✚ Solve the following instance of the 0/1 knapsack problem by constructing the state-space-tree.

$$n=4, W=16$$

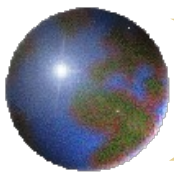
i	v_i	w_i	v_i/w_i
-----	-------	-------	-----------

1	40	2	20
---	----	---	----

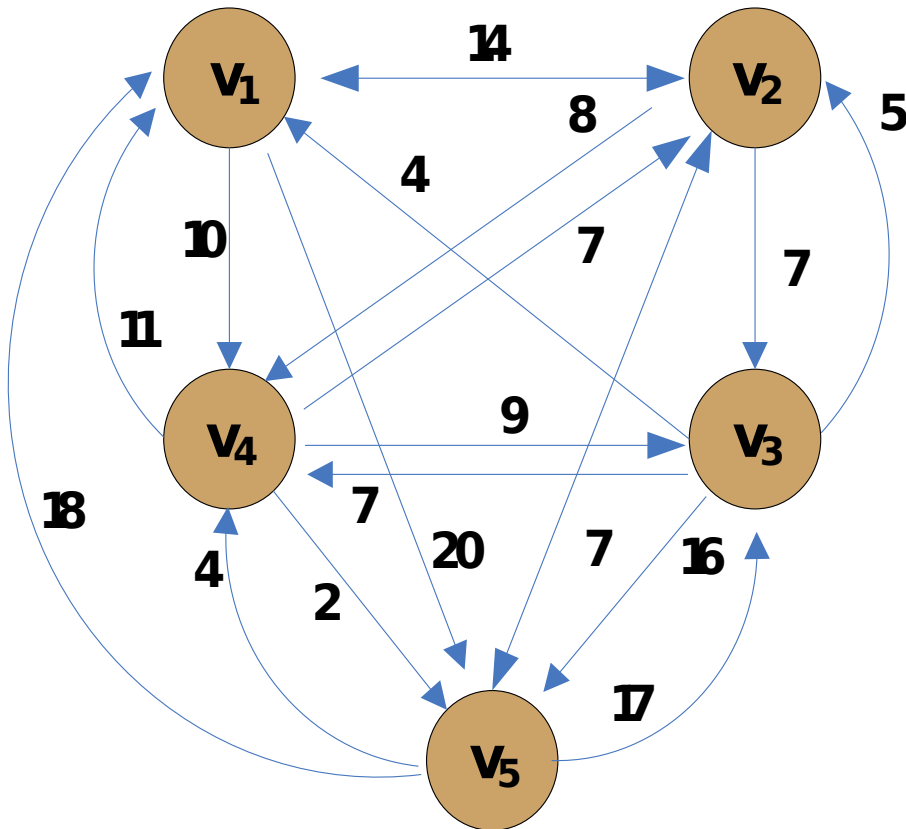
2	30	5	6
---	----	---	---

3	50	10	5
---	----	----	---

4	10	5	2
---	----	---	---

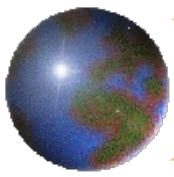


Example. Traveling Salesman Problem



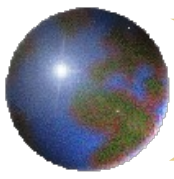
Adjacency matrix

0	14	4	10	20
14	0	7	8	7
4	5	0	7	16
11	7	9	0	2
18	7	17	4	0



Traveling Salesman Problem

- ✚ **Lower bound** on the cost of leaving vertex v_1 is given by the minimum of all nonzero entries in row 1 of the adjacency matrix,
- ✚ **Lower bound** on the cost of leaving vertex v_2 is given by the minimum of all nonzero entries in row 2 of the adjacency matrix,
- ✚ And so on..



Traveling Salesman Problem

- ✚ Lower bound on the cost of leaving the five vertices are:

$$v_1 \text{ minimum } (14, 4, 10, 20) = 4$$

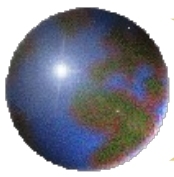
$$v_2 \text{ minimum } (14, 7, 8, 7) = 7$$

$$v_3 \text{ minimum } (4, 5, 7, 16) = 4$$

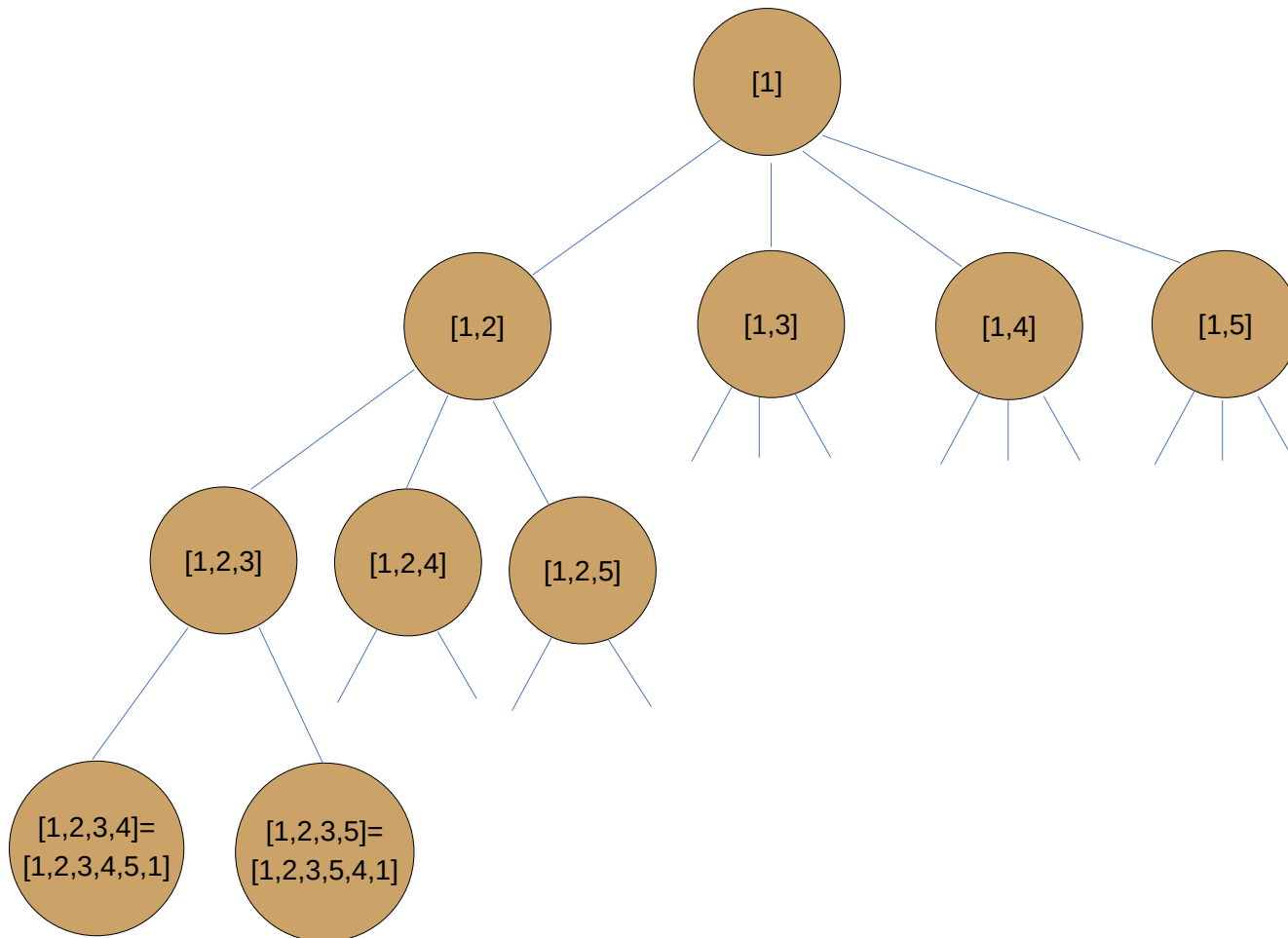
$$v_4 \text{ minimum } (11, 7, 9, 2) = 2$$

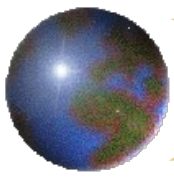
$$v_5 \text{ minimum } (18, 7, 17, 4) = 4$$

- ✚ The sum of these minimums is 21



Lower bound



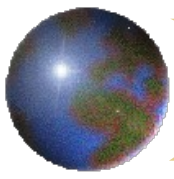


Lower bound

- ✚ Lower bound on the node containing [1,2] :
 - ✚ The cost of getting to v_2 is 14
 - ✚ Obtain the minimum for v_2 , it doesn't include the edge to v_1
 - ✚ Obtain the minimums for the other vertices it doesn't include v_2 because it's already been at v_2 .

$$\begin{aligned}v_1 &= 14 \\v_2 \text{ minimum}(7, 8, 7) &= 7 \\v_3 \text{ minimum}(4, 7, 16) &= 4 \\v_4 \text{ minimum}(11, 9, 2) &= 2 \\v_5 \text{ minimum}(18, 17, 4) &= 4\end{aligned}$$

- ✚ Lower bound obtained by expanding beyond the node containing [1,2] is $14+7+4+2+4=31$

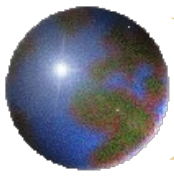


Lower bound

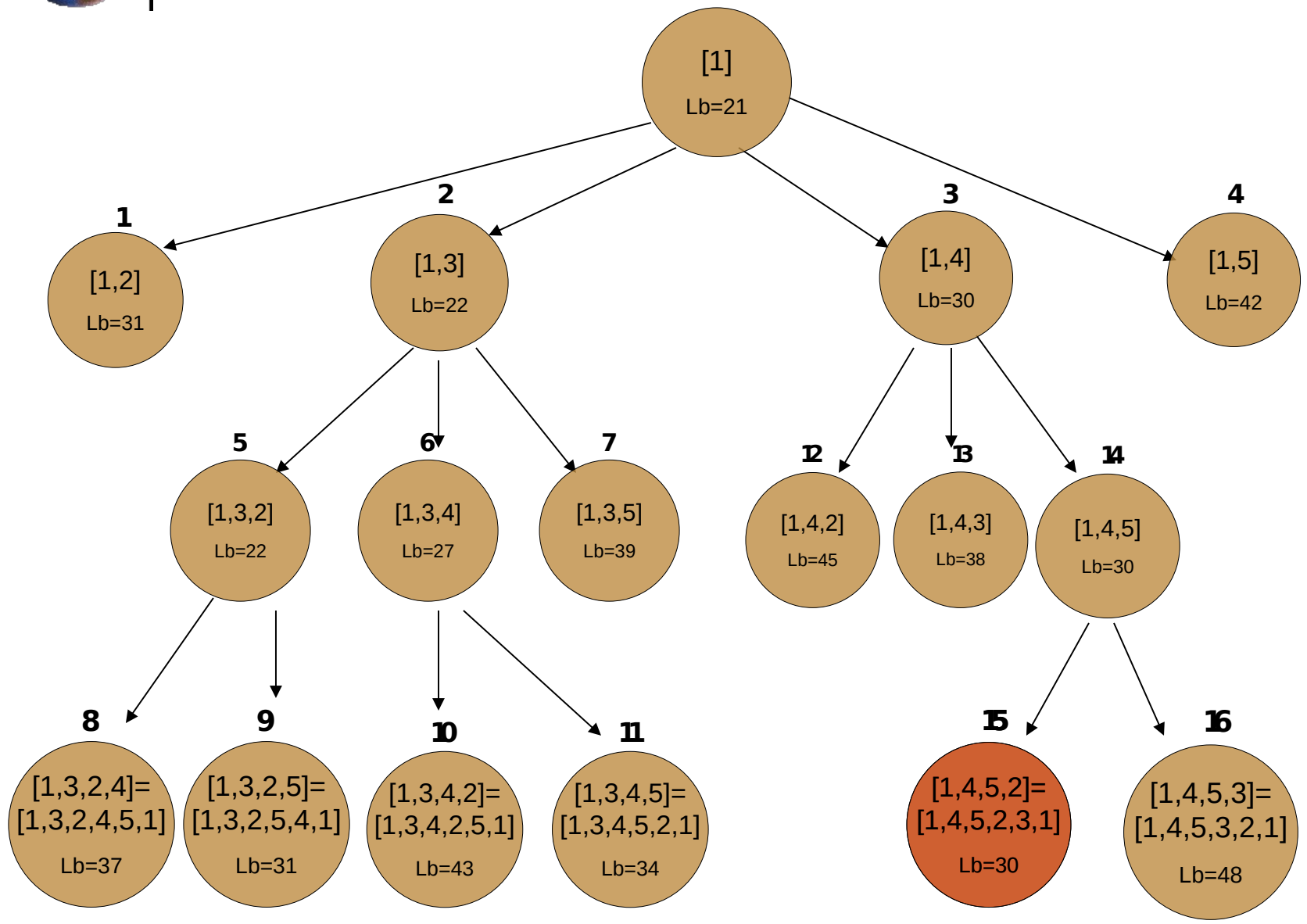
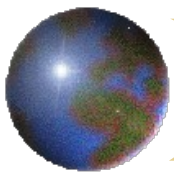
- ✚ Lower bound on the node containing [1,2,3]. Any tour obtained by expanding beyond this node has the following lower bound on the cost of leaving the vertices:

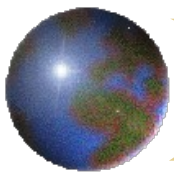
$$\begin{aligned}v_1 &= 14 \\v_2 &= 7 \\v_3 \text{ minimum}(7, 16) &= 7 \\v_4 \text{ minimum}(11, 2) &= 2 \\v_5 \text{ minimum}(18, 4) &= 4\end{aligned}$$

- ✚ The lower bound on the node [1,2,3] is $14+7+7+2+4=34$



Best-first search with branch-and-bound pruning

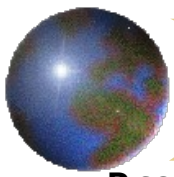




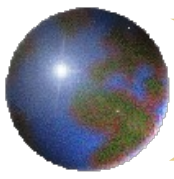
Problem: determine an optimal tour in a weighted graph. The weights are nonnegative numbers

Inputs: a weighted, directed graph W , and n the number of vertices in W . W is represented by matrix, where $W[i,j]$ is the weight on the edge from v_i to v_j

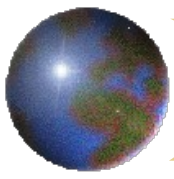
Outputs: variable *minlength*, whose value is the length of an optimal tour, and variable *optour*, whose value is an optimal tour



```
Procedure travel(n:int; W:array[1..n,1..n]of number; var
    optour:ordered_set;var minlength:number)
Var
    u,v:node;PQ:priority_queue_of_node
Begin
    initialize(PQ);
    v.level=0;v.path=[1];v.bound=bound(v);minlength=∞;
    insert(PQ,v);
    while not empty(PQ)do
        remove(PQ,v);
        if v.bound < minlength then
            u.level=v.level+1;
            if u.level=n-1 then
                u.path=v.path;
                add 1 to the end of u.path;
                if length(u) < minlength then
                    minlength=length(u);
                    optour=u.path
            else
                for i such that 2≤i≤n and i is not in v.path do
                    u.path=v.path;
                    add i to the end of u.path;
                    u.bound=bound(v);
                    if u.bound<minlength then
                        insert(PQ,u)
```



```
Type node = record  
    level:integer;  
    path :ordered_set;  
    bound:number  
End;
```

TSP: an optimal tour

