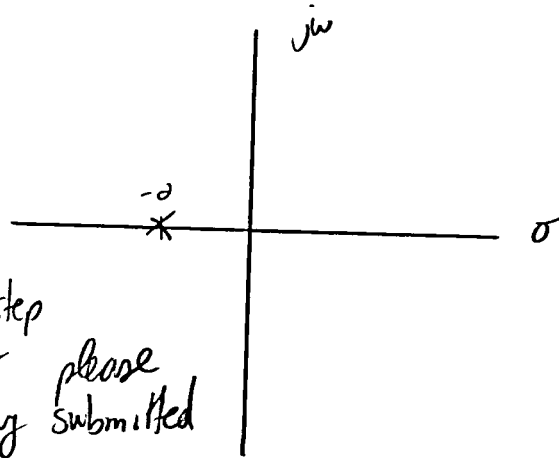


# HW #3

ras70

## Problem 1

a)  $T(s) = \frac{2}{s+2}$



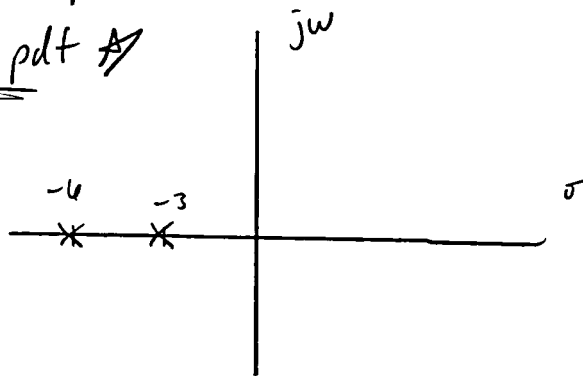
First order

For actual step responses please see my submitted Maple script

$S_R(t) = K_1 + K_2 e^{-2t}$

b)  $T(s) = \frac{5}{(s+3)(s+6)}$

Problem1.pdt



$(s+3), (s+6)$  both real  
 $s^2 + 9s + 18$

$b^2 - 4c = 81 - 72 = 9 > 0$

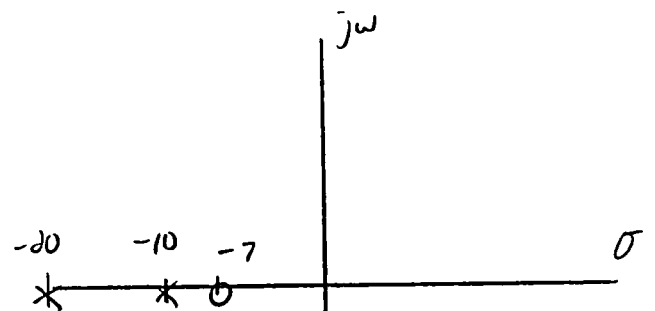
$\Rightarrow$  Overdamped

$S_R(t) = K_1 + K_2 e^{-3t} + K_3 e^{-6t}$

c)  $T(s) = \frac{10(s+7)}{(s+10)(s+20)}$

Again 2 real roots

$\Rightarrow$  Overdamped



$S_R(t) = K_1 + K_2 e^{-10t} + K_3 e^{-20t}$

## Problem 1 cont

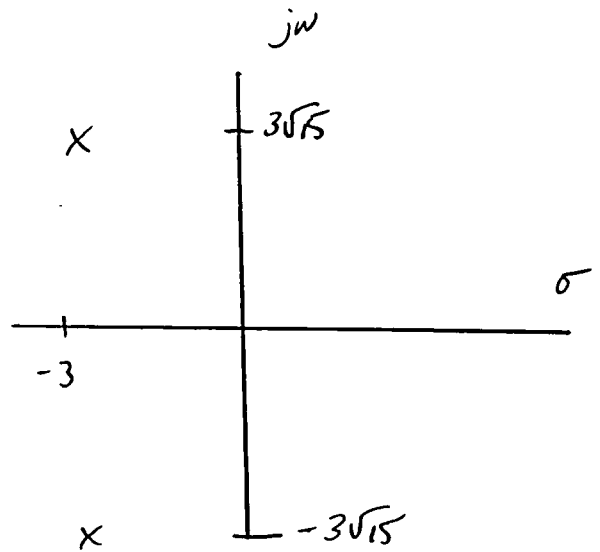
$$d) T(s) = \frac{20}{s^2 + 6s + 144}$$

$$\frac{-6 \pm \sqrt{36 - 4(144)}}{2}$$

$$\frac{-3 \pm \sqrt{540}}{2}$$

$$-3 \pm 3\sqrt{5}$$

$$b^2 < 4c \Rightarrow \text{Underdamped}$$



$$s_2(t) = K_1 + e^{-3t} (K_2 \cos(3\sqrt{5}t) + K_3 \sin(3\sqrt{5}t))$$

$$e) T(s) = \frac{s+2}{s^2+9}$$

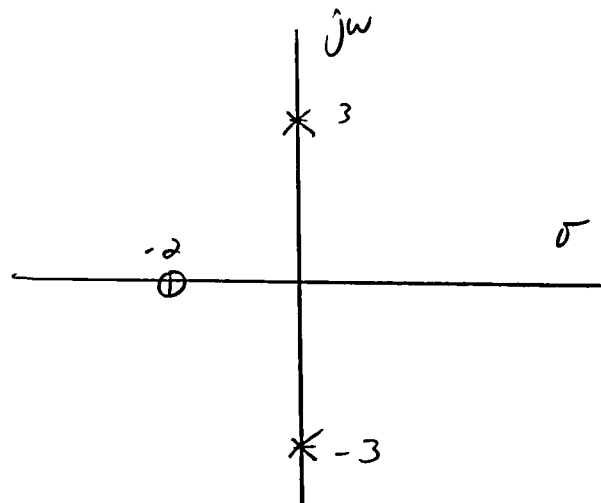
$$b=0$$

Undamped

$$(s^2 + 9) = 0$$

$$s^2 = -9$$

$$s = \pm 3i$$



$$s_2(t) = K_1 + K_2 \cos(3t) + K_3 \sin(3t)$$

## Problem 1 cont

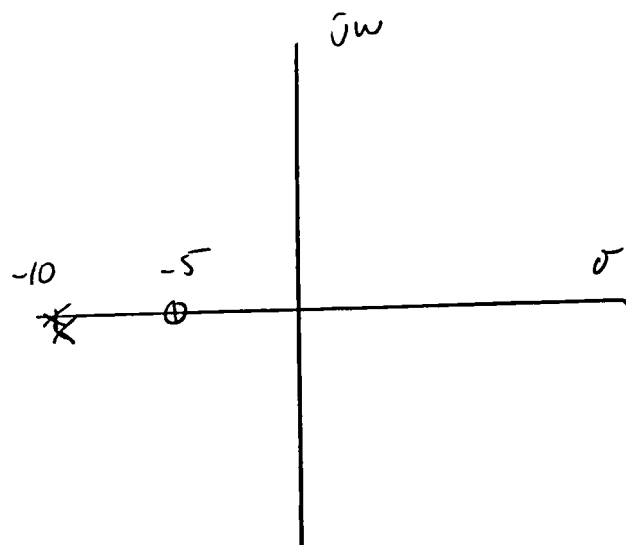
$$c) T(s) = \frac{s+5}{(s+10)^2}$$

$$b^2 = 4b$$

$$20^2 = 4(100)$$

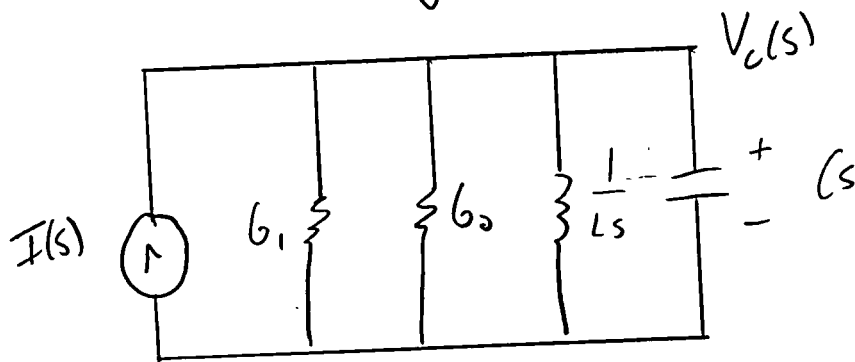
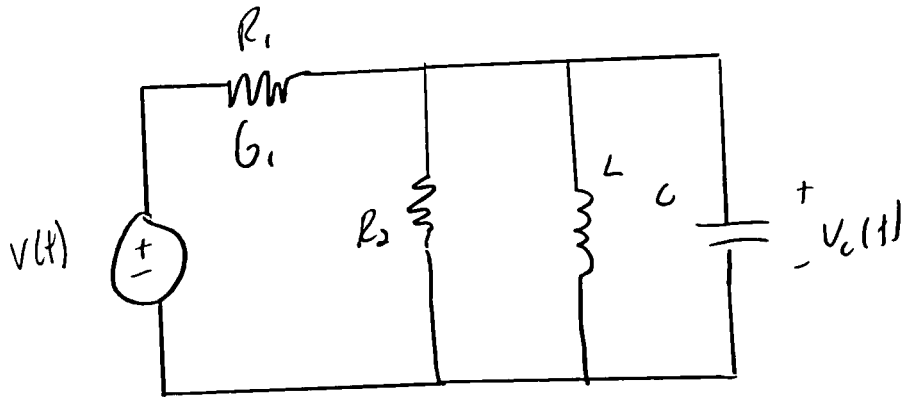
$$400 = 400$$

Critically  
Damped



$$S_R(t) = K_1 + e^{-10t}(K_2 + K_3 t)$$

## Problem 2



a)

$$I(s) = G_1 V(s)$$

$$V_c(s) : (G_1 + G_2 + \frac{1}{Ls} + Cs) V_c(s) = G_1 V(s)$$

$$\frac{V_c}{V_s} = \frac{G_1}{(G_1 + G_2 + \frac{1}{Ls} + Cs)} = \frac{1/R_1}{(1/R_1 + 1/R_2 + \frac{1}{Ls} + Cs)} = \frac{R_2 Ls}{R_2 Ls + R_1 Ls + R_1 R_2 + R_1 R_2 L C s^2}$$

$$\boxed{\frac{V_c}{V_s} = \frac{R_2 Ls}{R_2 Ls + R_1 Ls + R_1 R_2 + R_1 R_2 L C s^2}}$$

$$R_1 = 10k\Omega = R_2, L = 100H, C = 10\mu F \rightarrow \frac{2 \times 10^6 s}{2 \times 10^5 s^2 + 4 \times 10^6 s + 1 \times 10^8}$$

## Problem 2 cont

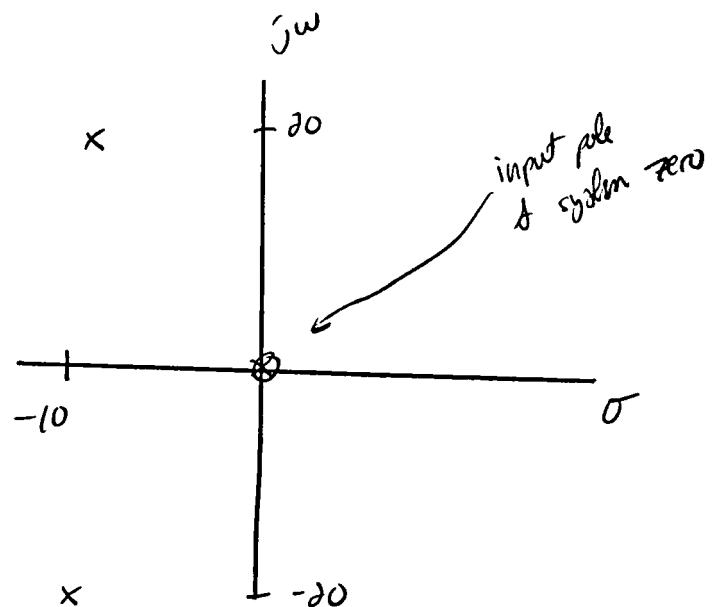
$$\frac{V_c}{V_s} = \frac{10s}{s^2 + 20s + 500}$$

b) Step input

$$\frac{-20 \pm \sqrt{20^2 - 4(500)}}{2}$$

$$-10 \pm 20i$$

↑  
roots



c) Underdamped

$$c(t) = K_1 + e^{-10t} (K_2 \cos(20t) + K_3 \sin(20t))$$

### Problem 3

Please reference Sakai for submitted script. ~~OK~~

↳ a diary

$$a) T(s) = \frac{16}{s^2 + 3s + 16}$$

$$\omega_n = 4 \text{ rad/s}$$

$$\% OS = 28.06\%$$

$$\zeta = 0.3750$$

$$T_r = 3.56 \times 10^{-1} \text{ s}$$

$$T_p = 8.47 \times 10^{-1} \text{ s}$$

$$T_s = 2.47 \text{ s}$$

$$b) T(s) = \frac{0.04}{s^2 + 0.02s + 0.04}$$

$$\omega_n = 2 \times 10^{-1} \text{ rad/s}$$

$$\zeta = 0.0500$$

$$T_r = 5.26 \text{ s}$$

$$T_p = 1.57 \times 10^1 \text{ s}$$

$$T_s = 4.00 \times 10^0 \text{ s}$$

$$\% OS = 85.45\%$$

$$c) T(s) = \frac{1.05 \times 10^7}{s^2 + 1.6 \times 10^3 s + 1.05 \times 10^7}$$

$$\omega_n = 3.87 \times 10^3 \text{ rad/s}$$

$$T_r = 3.13 \times 10^{-4} \text{ s}$$

$$T_s = 5.00 \times 10^{-3} \text{ s}$$

$$\zeta = 0.2066$$

$$T_p = 8.29 \times 10^{-4} \text{ s}$$

$$\% OS = 51.52\%$$

# Problem 4

a) Using Output 1. fig

Final value  $\rightarrow 2.5$

$T_s = 98\%$  of final value

Time to set to

98% of 2.5

$$= 0.98(2.5) = 2.45$$

$$T_s \approx 1.956 s$$

for here I graphically got these values & my justification PDI =

$$\begin{aligned} T_s &\approx 1.956 s \\ T_r &\approx 1.097 s \end{aligned}$$

$T_r =$  time 10%  $\rightarrow 20\%$  of final value

$$= 0.25 \rightarrow 2.25$$

$$\begin{aligned} &\rightarrow 1.15 s \\ &\approx 0.053 \end{aligned}$$

$$= 1.15 - 0.053 = 1.097 s$$

$$a \approx 2$$

$$T_s = \frac{3.91}{a}$$

$$a = \frac{3.91}{T_s} = \frac{3.91}{1.956} \approx 2$$

$$\lim_{s \rightarrow 0} \frac{K}{s+2} = \frac{K}{2} = 2.5$$

$$K = 5$$

$$G(s) = \frac{K}{s+a} = \frac{K}{s+2}$$

$$G(s) = \frac{K}{s+2}$$

$$G(s) = \frac{5}{s+2}$$

## Problem 4 cont

b) From the Output d. fig

$$\boxed{T_p = 1.545 \text{ s}}$$

For all graphical approximations see justification PDF

The value at  $T_p$  is  $\approx 0.3853$

The final value is  $0.361$

$$\boxed{\% OS = 6.31\%}$$

$$\% \text{ overshoot} = \frac{0.3853 - 0.361}{0.361} \cdot 100 = 6.31\%$$

$\pm 2\%$  of final value  $(0.354, 0.368)$

The second dip does not go below this value. Thus we can consider when the signal first enters this range

$$\boxed{T_s \approx 2.25 \text{ s}}$$

Rise time

$$0.361(0.2) = 0.3249 \rightarrow \approx 0.9 \text{ s}$$

$$0.361(0.1) = 0.0361 \rightarrow \approx 0.1875 \text{ s}$$

$$\boxed{T_r \approx 0.713 \text{ s}}$$

$$\% \text{ Overshoot} = e^{-\left(\frac{\zeta}{\sqrt{1-\zeta^2}}\pi\right)} \cdot 100 = 6.31$$

$$\frac{\zeta}{\sqrt{1-\zeta^2}} = \frac{-\ln\left(\frac{6.31}{100}\right)}{\pi} = 0.88$$



# Problem 4b. cont

$$\zeta = 0.661$$

$$\omega_n = 2.69$$

$$T_s = \frac{4}{\zeta \omega_n} \Rightarrow \omega_n = \frac{4}{\zeta T_s} = \frac{4}{(0.661)(2.25)} = 2.68953$$

$$G(s) = \frac{K}{s^2 + 2\zeta\omega_n s + \omega_n^2} = \frac{K}{s^2 + 3.56s + 7.24}$$

$$\lim_{s \rightarrow 0} G(s) = \frac{K}{7.24} = 0.361 = 2.61$$

$$G(s) = \frac{2.61}{s^2 + 3.56s + 7.24}$$

## Problem 4c

For output 3. fig

Final value = 0.77

Peak value  $\approx 1.36$  at 0.9 seconds

$$\% \text{ overshoot} = \frac{1.36 - 0.77}{0.77} (100) = 76.62\%$$

$\pm 2\%$  of final value = (0.755, 0.785)  $\rightarrow$  Graphically  $\approx 14.5$  s

Rise time

$$\left. \begin{array}{l} .77(1.1) = 0.77 \rightarrow 0.13 \\ .77(.9) = 0.693 \rightarrow 0.455 \end{array} \right\} \text{substant} = 0.32 \text{ s} \quad \boxed{T_r \approx 0.32 \text{ s}}$$

$$\% \text{ overshoot} = e^{-(\xi\pi / \sqrt{1-\xi^2})} \cdot 100 = 76.62$$

$$\frac{\xi}{\sqrt{1-\xi^2}} = -\ln\left(\frac{76.62}{100}\right) / \pi = 0.08477$$

$$\boxed{\xi = 0.084}$$

$$\frac{1}{s} = \frac{4}{\xi \omega_n} \Rightarrow \omega_n = \frac{4}{\xi T_s} = \frac{4}{0.084(14.5)} = 3.28$$

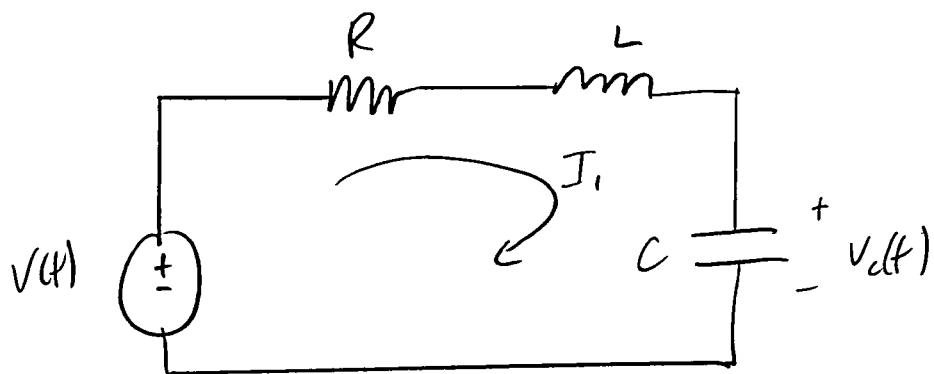
$$\boxed{\omega_n = 3.28}$$

$$|s| = \frac{K}{s^2 + 2\xi\omega_n s + \omega_n^2} = \frac{K}{s^2 + 1.8s + 10.8}$$

$$\lim_{s \rightarrow 0} |s| = \frac{K}{10.8} = 0.77 \Rightarrow K = 8.316$$

$$\boxed{G(s) \approx \frac{8.3}{s^2 + 1.8s + 10.8}}$$

# Problem 5



a)  
Mesh current

$$I_1: (R + Ls + \frac{1}{Cs}) I_1(s) = V(s)$$

Ohm's  $V_c(s) = \frac{1}{Cs} I_1(s) \Rightarrow I_1(s) = Cs V_c(s)$

$$(R + Ls + \frac{1}{Cs}) Cs V_c(s) = V(s)$$

$$(RCs + CLs^2 + 1) V_c(s) = V(s)$$

$$\left| \frac{V_c(s)}{V(s)} = \frac{1}{CLs^2 + RCs + 1} \right.$$

$$b) \frac{V_c(s)}{V(s)} = \frac{1/CL}{s^2 + \frac{RC}{CL}s + 1/CL} = \frac{1}{CL} \frac{1}{s^2 + \frac{R}{L}s + 1/LC}$$

$$\omega_n^2 = \frac{1}{LC}$$

$$\zeta = \frac{R/L}{2\omega_n} = \frac{R/L}{2 \frac{1}{\sqrt{LC}}} = \frac{R\sqrt{LC}}{2L} = \frac{R\sqrt{L}\sqrt{C}}{2\sqrt{L}\sqrt{L}} = \frac{R}{2} \sqrt{\frac{C}{L}}$$

$$\boxed{\omega_n = \frac{1}{\sqrt{LC}}}$$

$$\boxed{\zeta = \frac{R}{2} \sqrt{\frac{C}{L}}}$$

# Problem 5c

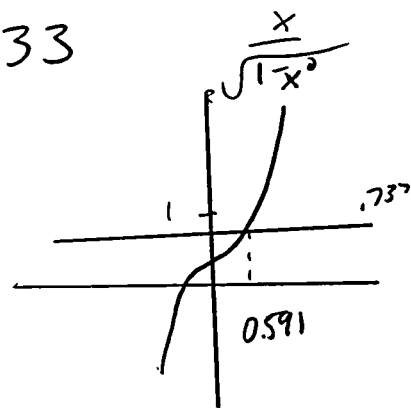
$$L = 100$$

$$\% OS = e^{-(\xi\pi/\sqrt{1-\xi^2})} \cdot 100 = 10\%$$

$$e^{-(\xi\pi/\sqrt{1-\xi^2})} = 0.1$$

$$\frac{\xi}{\sqrt{1-\xi^2}} = \frac{-\ln(0.1)}{\pi} \approx 0.733$$

$$\xi \approx 0.591 \text{ determined graphically}$$



$$T_r = 0.0321 \text{ s}$$

According to Figure 4.16,  $\xi \approx 0.6$  corresponds to a normalized rise time of  $\omega_n T_r = 1.854$ .

$$\omega_n T_r = 1.854$$

$$\omega_n = \frac{1.854}{0.0321} = 57.757 \text{ rad/s}$$

$$\xi = \frac{R}{2} \sqrt{\frac{C}{L}}$$

$$R = 2\xi \sqrt{\frac{L}{C}} = \frac{2(0.591)}{\sqrt{\frac{3 \times 10^{-4}}{100}}}$$

$$\omega_n = \frac{1}{\sqrt{LC}}$$

$$\omega_n^2 = \frac{1}{LC}$$

$$C = \frac{1}{L\omega_n^2} = \frac{1}{100(57.757)^2} = 2.99771 \text{ nF}$$

$$\left. \begin{array}{l} C \approx 3 \text{ nF} \\ R = 6824.28 \Omega \end{array} \right\}$$

$$= 6824.28 \Omega$$

# Problem 6

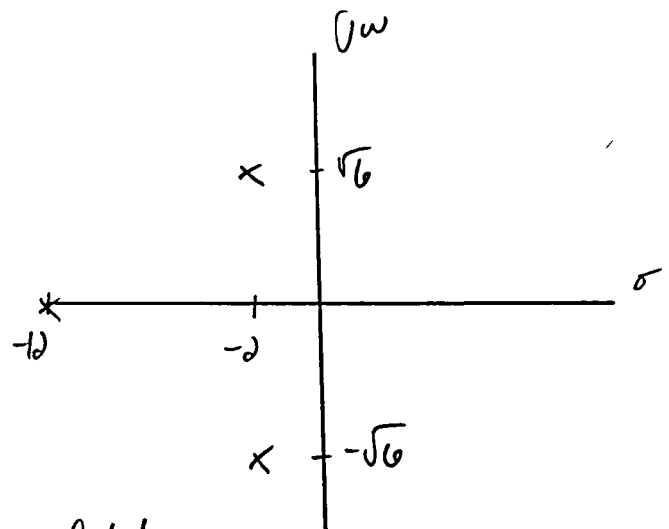
a)  $T(s) = \frac{5}{(s+2)(s^2+4s+10)}$

$$(s+2)(s^2+4s+10)$$

$$-4 \pm \frac{\sqrt{16-40}}{2} = -2 \pm \sqrt{6}i$$

$12 > 2(5) = 10$ , thus this pole can be neglected

$$T(s) \approx \frac{5}{(s^2+4s+10)}$$



b)  $T(s) = \frac{s+2.1}{(s+2)(s^2+s+5)} = \frac{A}{s+2} + \frac{Bs+C}{s^2+s+5}$

$$\begin{aligned} A &\approx 0.014 \\ B &\approx -0.014 \\ C &\approx 1.01 \end{aligned} \quad \left. \begin{array}{l} \text{About} \\ \text{same} \\ \text{magnitude} \end{array} \right\}$$

$$(s+2.1) = A(s^2+s+5) + (s+2)(Bs+C)$$

$$s = -2 \Rightarrow +0.1 = 7A$$

$$A = 0.1/7$$

cannot cancel zero & pole

$$s^2/ \quad As^2 + Bs^2 = 0$$

$$A = -B$$

$$B = -0.1/7$$

$$s^2+s+5 \text{ roots}$$

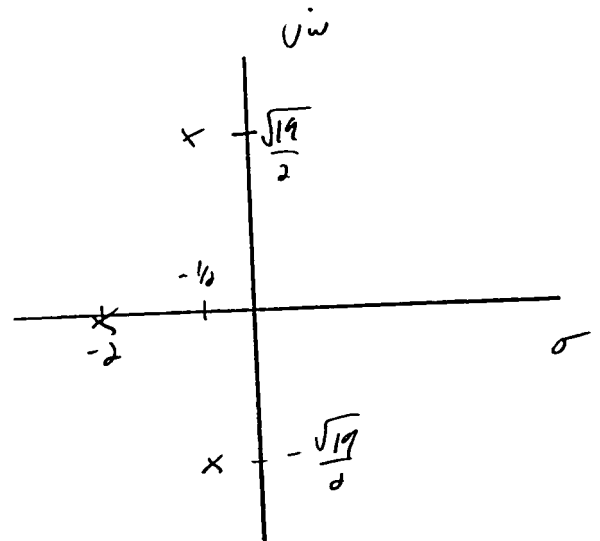
$$-1 \pm \frac{\sqrt{1-20}}{2} = -\frac{1}{2} \pm \frac{\sqrt{19}}{2}$$

1)  $5A + 2C = 2.1$

$$C = \frac{2.1 - 5A}{2} = 1.01$$

## Problem 6b cont

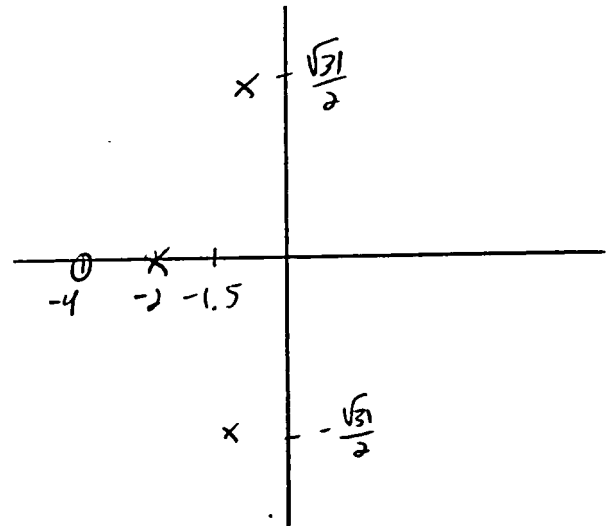
-2 pole is not 5 times left of the other two poles. Thus, the two pole approximation cannot be made



$$c) T(s) = \frac{s+4}{(s+2)(s^2+3s+10)}$$

$$\frac{-3 \pm \sqrt{9-40}}{2} = -\frac{3}{2} \pm \frac{\sqrt{31}}{2}i$$

Again, 2 is not 5 times left of the other two poles. Thus, the two pole approximation cannot be made



$$\frac{s+4}{(s+2)(s^2+3s+10)} = \frac{A}{s+2} + \frac{Bs+C}{s^2+3s+10}$$

$$s+4 = A(s^2+3s+10) + (s+2)(Bs+C)$$

$$s = -2 \Rightarrow 2 = A(8)$$

$$A = 1/4$$

A, B, & C are all of the same magnitude

∴

$$10A + C = 4$$

$$C = 4 - 10/4 = \frac{3}{2}$$

$$A + B = 0$$

$$-A = B$$

$$B = -1/4$$

↪ cannot cancel a zero + pole

## Problem 7

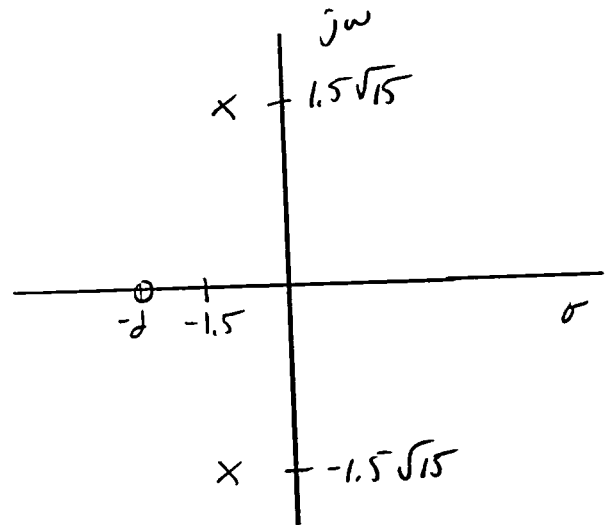
Since  $s^2 + 3s + 36$  is the denominator for  $T(s)$  in a-c let's analyze that first.

$$\frac{-b \pm \sqrt{b^2 - 4ac}}{2a} = \frac{-3 \pm \sqrt{9 - 4(36)}}{2} = \frac{-3 \pm \frac{3}{2} \sqrt{15} i}{2}$$

a)  $T(s) = \frac{s+2}{s^2 + 3s + 36}$

$2 < 5\left(\frac{3}{2}\right) = 7.5$

$\therefore$  zero approximation cannot be applied

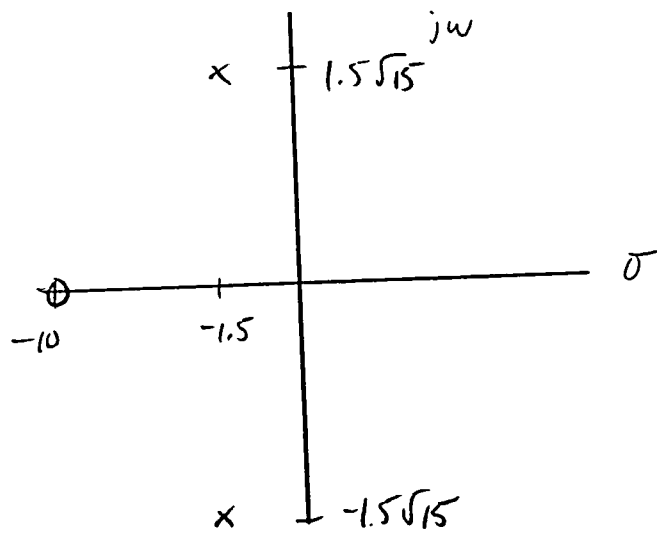


b)  $T(s) = \frac{s+10}{s^2 + 3s + 36}$

-10 is much left of the poles

$10 > 5\left(\frac{3}{2}\right) = 7.5$

$\therefore$  zero approximation can be applied



$T(s)$  can be approximated with no zeros and a gain of 10

i.e

$$\frac{10}{s^2 + 3s + 36}$$

## Problem 7 cont

$$c) T(s) = \frac{s-10}{s^2+3s+36}$$

Zero is far from poles. Therefore approximation can be applied.  $K=-10$

$$T(s) \approx \frac{-10}{s^2+3s+36}$$

This is a nonminimum phase system

I have plotted  $T(s)$  vs its approximation for b & c. Please see my attached PDF's for this discussion.

