

Group B:-

1. Digitize a line with end points A(11, 9) and B(29, 17)
 Using Bresenham's line drawing algorithm

$$\text{Slope } m = \frac{y_2 - y_1}{x_2 - x_1} = \frac{17 - 9}{29 - 11}$$

$$\Delta x = 18 \quad \Delta y = 8 \quad 2\Delta y = 16 \quad 2\Delta y - 2\Delta x = -20$$

$$P_0 = 16 - 18 \\ = -2$$

K	P_k	x_{k+1}	y_{k+1}
1	-2	11	9
2	14	12	9
3	-6	13	10
4	10	14	10
5	-10	15	11
6	6	16	11
7	-14	17	12
8	2	18	12
9	-18	19	13
10	-2	20	13
11	-22	21	14
12	-6	22	14
13	-26	23	15
14	-16	24	15
15	-30	25	16
16	-14	26	16
17	-34	27	17
18	-19	28	17

2) Derive recurrence relation for mid point circle algorithm.

Digitize a line with end points A(11, 9) and B(29, 17)

circle function defined as

$$f_{\text{circle}}(x, y) = x^2 + y^2 - r^2$$

at any point (x, y) satisfies following conditions.

$$f_{\text{circle}}(x, y) \begin{cases} < 0 & \text{if } f(x, y) \text{ is inside the circle boundary} \\ = 0 & \text{if } (x, y) \text{ is on the circle boundary} \\ > 0 & \text{if } (x, y) \text{ is outside the circle boundary.} \end{cases}$$

$$P_k = f_{\text{circle}}(x_{k+1}, y_{k+1/2})$$

$$= (x_{k+1})^2 + (y_{k+1/2})^2 - r^2$$

$$P_{k+1} = f_{\text{circle}}(x_{k+1} + 1, y_{k+1/2})$$

$$= [(x_{k+1} + 1)^2 + (y_{k+1/2})^2] - r^2$$

$$P_{k+1} = P_k + 2x_{k+1} + 1 - 2y_{k+1/2} - r^2$$

$$y_{k+1} = y_k \text{ if } P_k < 0$$

$$y_{k+1} = y_{k+1/2} \text{ otherwise}$$

Thus,

$$P_{k+1} = P_k + 2x_{k+1} + 1 \text{ if } P_k < 0$$

$$P_{k+1} = P_k + 2x_{k+1} + 1 - 2y_{k+1/2} - r^2 \text{ otherwise}$$

Alt incremental evaluation of $2x_{k+1}$ and

$$\Delta y_{k+1}$$

$$2x_{k+1} = 2x_k + 2$$

$$\Delta y_{k+1} = 2y_k - 2 \text{ if } P_k > 0.$$

At start position $(x_0, y_0) = (0, r)$

$$2x_0 = 0 \text{ and } 2y_0 = 2r.$$

The initial decision parameter

$$P_0 = f_{\text{circle}}(x_0, y_0 - L_{1/2})$$

$$= 1 + (r - L_{1/2})^2 - r^2$$

$$\frac{r}{2} - r$$

$$\begin{array}{ccc} -0.707 & 0.707 & 0 \\ -0.707 & -0.707 & 0 \\ 0 & 0.632 & 1 \end{array}$$

3) A triangle with vertices $A(5, 2)$, $B(4, 1)$, $C(6, 1)$ is required to be rotated in a clockwise direction by 45° degree about any arbitrary point $(4, 1)$. Find out the final clockwise position of the triangle after performing the desired transformation.

Solution

Step 1:- Translate to origin

Step 2:- Rotate about 45°

Step 3:- Again translate back to original position.

$$T_1 T_0 T_{-r} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} \cos 45^\circ & \sin 45^\circ & 0 \\ -\sin 45^\circ & \cos 45^\circ & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

+
-
+
-
+
-
+
-
+

$$= \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 4 & 4 & 1 \end{bmatrix} \begin{bmatrix} \cos 45^\circ & \sin 45^\circ & 0 \\ -\sin 45^\circ & \cos 45^\circ & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -4 & -4 & 0 \end{bmatrix}$$

$$\therefore \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 4 & 4 & 1 \end{bmatrix} \begin{bmatrix} 1/\sqrt{2} & 1/\sqrt{2} & 0 \\ -1/\sqrt{2} & 1/\sqrt{2} & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -4 & -4 & 0 \end{bmatrix}$$

$$= \begin{bmatrix} 0.7071 & 0.7071 & 1 \\ -0.7071 & -0.7071 & 0 \\ 0 & 0.632 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -4 & -4 & 0 \end{bmatrix} \begin{bmatrix} -3.2329 & -3.2329 & 1 \\ -0.7071 & 0.7071 & 0 \\ -4 & 1.6363 & 1 \end{bmatrix}$$

4) Reflect a triangle $A(1,0)$, $B(3,1)$, $C(4,2)$ about the line $y = -x + 5$ steps: → Iron lake to origin

Steps:- Rotate the line anti-clockwise direction with

Step 3: Reflect the object about x-axis

Step 4: Inverse step 2

Step 5: Inverse step 3

$\therefore M_{\text{refl}} \cdot T_{\text{R-O}} \cdot M_{\text{ROT-Y-P}}$

$$= \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 5 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} \cos 45 & -\sin 45 & 0 \\ \sin 45 & \cos 45 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} \cos 45 & \sin 45 & 0 \\ -\sin 45 & \cos 45 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & -5 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 3 & 1 \\ 0 & 1 & 2 \\ 1 & 1 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 5 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1/\sqrt{2} & -1/\sqrt{2} & 0 \\ 1/\sqrt{2} & 1/\sqrt{2} & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1/\sqrt{2} & 1/\sqrt{2} & 0 \\ -1/\sqrt{2} & 1/\sqrt{2} & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & -5 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 3 & 1 \\ 0 & 1 & 2 \\ 1 & 1 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 0 & 0 \\ 0 & -1 & 10 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1/\sqrt{2} & -1/\sqrt{2} & 0 \\ 1/\sqrt{2} & 1/\sqrt{2} & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1/\sqrt{2} & 1/\sqrt{2} & 0 \\ -1/\sqrt{2} & 1/\sqrt{2} & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 3 & 1 \\ 0 & 1 & 2 \\ 1 & 1 & 1 \end{bmatrix}$$

$$\therefore \begin{bmatrix} 1.5 & 4.5 & 1.5 \\ 11.5 & 13 & 8.5 \\ 1 & 1 & 1 \end{bmatrix}$$

5. A triangle with vertices $A(5, 2)$, $B(4, 1)$, $C(6, 4)$ is required to be reflected about an arbitrary line $y = 2x + 1$. Find out the final coordinates position of the triangle after performing the desired transformation.

Solution

1) Step 1:- Translate the point (b, c) to the origin.

2) Rotate the line clockwise with θ

3) Reflect the object about x-axis

4) Inverse of step 2

5) Inverse of step 1.

$$\therefore M_1 = T_y \cdot R_\theta \cdot m_x \cdot R_{-\theta} \cdot T_{-y} \cdot P$$

$$y = 2x + 1$$

$$m = 2, \quad C = L$$

$$\tan \theta = \frac{a}{b} = \frac{1}{2}$$

$$H = \sqrt{P^2 + b^2} = \sqrt{2^2 + 1^2} = \sqrt{5}$$

$$\sin \theta = \frac{P}{H} = \frac{2}{\sqrt{5}}, \quad \cos \theta = \frac{B}{H} = \frac{1}{\sqrt{5}}$$

n=2

$$= \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & L \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} \cos \theta & -\sin \theta & 0 \\ \sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} \cos \theta & \sin \theta & 0 \\ \sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 5 & 4 & 6 \\ 2 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 4 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1/\sqrt{5} & -2/\sqrt{5} & 0 \\ 2/\sqrt{5} & 1/\sqrt{5} & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1/\sqrt{5} & 2/\sqrt{5} & 0 \\ -2/\sqrt{5} & 1/\sqrt{5} & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & -1 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 5 & 4 & 6 \\ 2 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 1 \\ 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & -1 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 5 & 4 & 6 \\ 2 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix} = \begin{bmatrix} 5 & 4 & 6 \\ 0 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix}$$

- 6) A triangle with vertices $A(5, 2)$, $B(4, 1)$, $C(6, 1)$ is required to be rotated by 45° clockwise direction.
- about origin
 - about line $y=5$.

Sol:

(i) About origin:

Transformation matrix:

$$\begin{bmatrix} 5 & 4 & 6 \\ 2 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} \cos\theta & -\sin\theta & 0 \\ \sin\theta & \cos\theta & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\begin{bmatrix} 5 & 4 & 6 \\ 2 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} \cos 45^\circ & -\sin 45^\circ & 0 \\ \sin 45^\circ & \cos 45^\circ & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 6.3 \\ 2.1 \\ 0.4 \end{bmatrix}$$

(ii) About line $y=5$:

1) Translate the points so that line $y=5$ becomes $x=0$

$y=5$ become $x=0$

2) Rotate the point by 45° counter-clockwise

3) Translate back to origin position

$$= \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 5 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} \cos 45^\circ & -\sin 45^\circ & 0 \\ \sin 45^\circ & \cos 45^\circ & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & -5 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

$$\therefore \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 5 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} \cos 45^\circ & -\sin 45^\circ & 0 \\ \sin 45^\circ & \cos 45^\circ & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 6 \\ 0 & 1 & -5 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 0.7071 & -1.414 \\ 0.7071 & 0.7071 \\ 0 & 0 \end{bmatrix}$$

Now,

$$P' = P \cdot T_{inv} : \begin{bmatrix} 5 & 4 & 6 \\ 2 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} 0.7071 & -1.414 & 0 \\ 0.7071 & 0.7071 & 0 \\ 0 & 0 & 1 \end{bmatrix} \Rightarrow \begin{bmatrix} 6.7071 \\ 4.3457 \\ 1 \end{bmatrix}$$

(8) Rotate triangle A(0,0), B(1,1), C(1,2) about origin and about point (-1,-1) by 45 degree in counter clockwise direction.

(i) about origin

$$\text{Transformation matrix: } \begin{bmatrix} 0 & 1 & s \\ 0 & 1 & 2 \\ 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1/\sqrt{2} & -1/\sqrt{2} & 0 \\ 1/\sqrt{2} & 1/\sqrt{2} & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 0.7071 & -0.7071 & 0 \\ 0.7071 & 0.7071 & 0 \\ 1.4142 & 0 & 0 \end{bmatrix}$$

$$\text{Transformation: } \begin{bmatrix} 0 & 0 & 1 \\ 1 & 1 & 1 \\ s & 2 & 1 \end{bmatrix} \begin{bmatrix} 1/\sqrt{2} & -1/\sqrt{2} & 0 \\ 1/\sqrt{2} & 1/\sqrt{2} & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 0 & 0 & 1 \\ 0 & \sqrt{2} & 1 \\ \frac{3\sqrt{2}}{2} & \frac{\sqrt{2}}{2} & 1 \end{bmatrix}$$

About point (-1,-1)

1) translate about the origin

a) Rotate about 45°

3) translate to original position

$$\begin{bmatrix} 1 & 0 & t_x \\ 0 & 1 & t_y \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} \cos 45 & -\sin 45 & 0 \\ \sin 45 & \cos 45 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & -t_x \\ 0 & 1 & -t_y \\ 0 & 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} \frac{\sqrt{2}}{2} & -\frac{\sqrt{2}}{2} & 0 \\ \frac{\sqrt{2}}{2} & \frac{\sqrt{2}}{2} & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & -1 \\ 0 & 1 & -1 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 0.7071 & -0.7071 & 0 \\ 0.7071 & 0.7071 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

$$= \begin{bmatrix} 0 & 0 & 1 \\ 1 & 1 & 1 \\ 1.4142 & 0 & 0 \end{bmatrix} \begin{bmatrix} 0.7071 & -0.7071 & 0.999 \\ 0.7071 & 0.7071 & -0.414 \\ 0 & 0 & 1 \end{bmatrix}^{-1} \begin{bmatrix} 0 & 0 & 1 \\ 1.4142 & 0 & 1.585 \\ 4.9497 & -2.121 & 1 \end{bmatrix}$$

(11) Use Cohen Sutherland algorithm to clip two lines $(60, 10)$ and $(100, 40)$ against window $(50, 10), (80, 40)$

Solving finding region code.

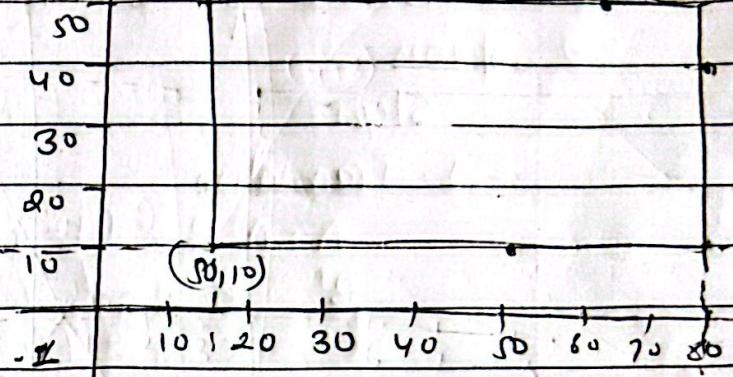
$$p_1 = 10000$$

$$p_2 = 00100$$

AND - 00000 partially
visible

Now,

$$\text{Slope} = \frac{y_2 - y_1}{x_2 - x_1} = \frac{10 - 50}{60 - 40} = \frac{-40}{20} = -2$$



$i = 10$.

$(80, 40)$

i_1

$$i_1(x_{m1x}, y_{m1y}) = (x, y_1)$$

$$x = \frac{1}{m} (y_{m1x} - y_1) + x_1$$

$$= \frac{1}{-2} (40 - 50) + 60$$

$$= -10 + 60 = 70$$

-1

$(50, 10)$

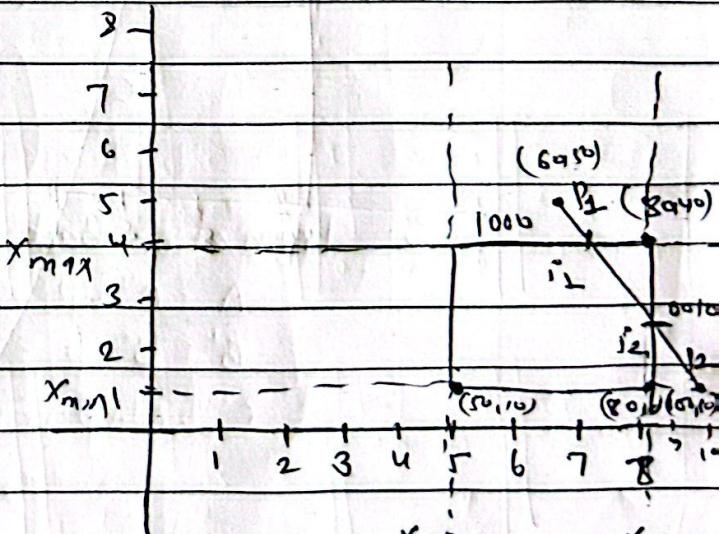
i.e. $(x_{m1x}, y) = (80, ?)$

$$Y = m(x_{m1x} - x_1) + y_1$$

$$= -2(80 - 60) + 50$$

$$= -20 + 50$$

$$= 30$$



13) prove two successive rotation are transformation commute
 We have,

$$R_2 = \begin{bmatrix} \cos\theta & \sin\theta \\ -\sin\theta & \cos\theta \end{bmatrix}$$

Also,

$$R_1 R_2 = \begin{bmatrix} \cos\theta_1 & \sin\theta_1 \\ -\sin\theta_1 & \cos\theta_1 \end{bmatrix} \begin{bmatrix} \cos\theta_2 & \sin\theta_2 \\ -\sin\theta_2 & \cos\theta_2 \end{bmatrix} \text{ and}$$

$$R_2 R_1 = \begin{bmatrix} \cos\theta_2 & \sin\theta_2 \\ -\sin\theta_2 & \cos\theta_2 \end{bmatrix} \begin{bmatrix} \cos\theta_1 & \sin\theta_1 \\ -\sin\theta_1 & \cos\theta_1 \end{bmatrix}$$

$$\therefore R_1 R_2 = \begin{bmatrix} \cos\theta_1 \cdot \cos\theta_2 & -\sin\theta_1 \cdot \sin\theta_2 \\ -\sin\theta_1 \cdot \cos\theta_2 & \cos\theta_1 \cdot \sin\theta_2 \end{bmatrix} \quad \begin{bmatrix} \cos\theta_1 \cdot \sin\theta_2 - \sin\theta_1 \cdot \cos\theta_2 \\ -\sin\theta_1 \cdot \sin\theta_2 + \cos\theta_1 \cdot \cos\theta_2 \end{bmatrix}$$

$$R_2 R_1 = \begin{bmatrix} \cos\theta_2 \cdot \cos\theta_1 & -\sin\theta_2 \cdot \sin\theta_1 \\ -\sin\theta_2 \cdot \cos\theta_1 & \cos\theta_2 \cdot \sin\theta_1 \end{bmatrix} \quad \begin{bmatrix} \cos\theta_2 \cdot \sin\theta_1 + \sin\theta_2 \cdot \cos\theta_1 \\ -\sin\theta_2 \cdot \sin\theta_1 + \cos\theta_2 \cdot \cos\theta_1 \end{bmatrix}$$

since multiplication is commutative $\cos\theta_1 \cdot \cos\theta_2 = \cos\theta_2 \cdot \cos\theta_1$

Therefore $R_1 R_2 = R_2 R_1$

14) Triangle with vertices $A(1, 1)$, $B(7, 1)$, $C(4, 3)$ is required to be rotated about any arbitrary fixed point $(4, 2)$ counter clockwise direction by 90° degree. What will be the coordinates of the triangle?

\Rightarrow Solution

Step -

1. Translation

$$A' = A - p = (1-4, 1-2) = (-3, -1)$$

$$B' = B - p = (7-4, 1-2) = (3, -1)$$

$$C' = C - p = (4-4, 3-2) = (0, 1)$$

2. Rotation

The 90° - degree counter clockwise direction matrix

$$\begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$$

$$\text{Then } A'' = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} -3 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 \\ -3 \end{pmatrix}$$

$$B'' = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 3 \\ -1 \end{pmatrix} = \begin{pmatrix} 1 \\ 3 \end{pmatrix}$$

$$C'' = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

3. Translation Back -

$$A''' = A'' + p = (1+4, -3+2) = (5, -1)$$

$$B''' = B'' + p = (1+4, 3+2) = (5, 5)$$

$$C''' = C'' + p = (-1+4, 0+2) = (3, 2)$$

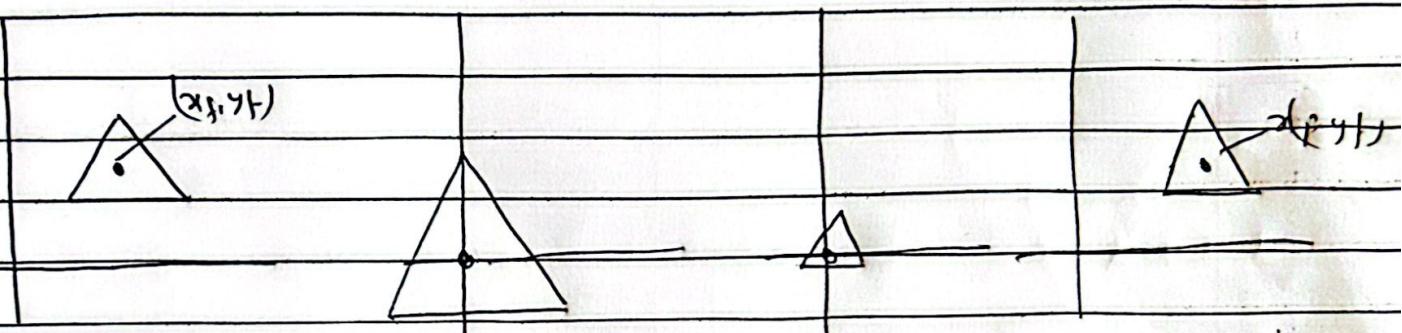
o Find Scaling transformation matrix to scale s_x, s_y, s_z units with respect to a fixed point $p(x, y, z)$.

→ Translate object so that the fixed point coincides with the coordinate origin.

→ Scale the object with respect to the coordinate origin.

→ use the inverse translation of step 2 to return the object to its original position

$$p' = [T(-x_f, -y_f) \cdot S(s_x, s_y) \cdot T(x_f, y_f)] p$$



original position of
object and pivot
point

b) translate object so
that fixed point
 (x_f, y_f) is at

c) scale object
with respect
to origin

d) translate object
back to its
original position
 (x_f, y_f)

The homogeneous matrix equation is

$$\begin{bmatrix} x' \\ y' \\ 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & x_f \\ 0 & 1 & y_f \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} s_x & 0 & 0 \\ 0 & s_y & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & -x_f \\ 0 & 1 & -y_f \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ 1 \end{bmatrix}$$

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Assignment

[Group A]

1. Raster Refresh system characteristics

1) Resolution:-

Determined by the number of pixels in a grid. Common resolutions include 1920×1080 (Full HD), 3840×2160 (4K) etc.

2) Refresh Rate:-

Refresh Rate typically ranges from 60 Hz to 240 Hz.

3) Image Rendering:-

The entire screen is refreshed multiple times per second.

2) Vector Refresh Systems Characteristics

1) Resolution

The resolution depends on the precision of the deflection system and the analog nature of the display.

2) Refresh Rate:-

Variable, typically slower than raster systems. Depends on the complexity of the image.

3) Image Rendering:-

Draws images by moving the electron beam directly to trace out shapes rather than scanning a grid.

3) Plasma Panels :-
characteristic;

1. Resolution:

High resolution available, commonly used in large displays (eg, 1080p, 4K).

2) Refresh Rate

Typically 60Hz to 120Hz

3) Image Rendering :-

Uses small cells containing electrically charged ionized gases to produce image.

4) LCDs

Characteristics:-

1. Resolution:-

Very high resolutions available, common resolution includes 1920x1080/ 2360x1440 etc.

2) Refresh Rate:-

Typically 60Hz to 144Hz.

3) Image Rendering :-

Uses liquid crystals that align to modulate light from a backlight, creating images.

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2)

Raster Scan System

- 1) They are composed of pixels
- 2) It is less expensive
- 3) modification is difficult
- 4) Resolution is low
- 5) It uses interlacing
- 6) solid pattern is easy to fill
- 7) occupy more space

Random Scan system

- 1) They are composed of paths
- 2) It is more expensive
- 3) modification is easy
- 4) Resolution is high
- 5) It does not use interlacing
- 6) solid pattern is difficult to fill
- 7) occupy less space

3) Solution

for the system with resolution 640 by 400

$$\text{Resolution (No of pixels)} = 640 \times 400 = 256000$$

Storage = 12 bits per pixel

$$\text{Size of frame buffer} = 640 \times 400 \times 12$$

$$= 3072000 \text{ bytes} \Rightarrow 3.072 \text{ MB}$$

for the system with resolution 1280 by 1024.

$$\text{Resolution (No of pixels)} = 1280 \times 1024 = 1310720 \text{ pixels}$$

Storage = 12 bits per pixel

$$\text{Size of frame buffer} = 1280 \times 1024 \times 12 = 15728640 \text{ bits}$$

$$= 1966080 \text{ bytes}$$

for the system with resolution 2160 by 2048.

$$\text{Resolution (NO of pixels)} = \frac{1280 \times 2048}{2160} = 1310720 \text{ pixels.}$$

Storage = 24 bits per pixel

$$\begin{aligned}\text{Size of frame Buffer} &= \text{Resolution} \times \text{bits per pixel} \\ &= 2160 \times 2048 \times 24 \\ &= 2160 \times 2048 \times 12 / 8 \text{ bytes.} \\ &= 1966080 \text{ bytes.}\end{aligned}$$

24 bits

for 640 by 480.

$$\text{Resolution} = 640 \times 480 = 307200$$

Storage = 24 bits per pixel

$$\begin{aligned}\text{Size of Frame Buffer} &= 640 \times 480 \times 24 \text{ bits} \\ &= 614400 \text{ bits} \\ &= 768000 \text{ bytes}\end{aligned}$$

for 1280 by 1024

$$\text{Resolution} = 1280 \times 1024 = 1310720$$

Storage = 24 bits per pixel

$$\begin{aligned}\text{Size of frame Buffer} &= 1280 \times 1024 \times 24 \\ &= 31457280 \text{ bits}\end{aligned}$$

3932160 bytes.

for 2160 by 2048

$$\text{Resolution} = 2160 \times 2048 = 5242880$$

Storage = 24 bits per pixel

$$\begin{aligned}\text{Size of frame Buffer} &= 2160 \times 2048 \times 24 \\ &= 125829120 \text{ bits}\end{aligned}$$

15718640 bytes.

4) Solution

Given,

Screen size = 8-inch by 10-inch

$$\text{Resolution} = 10 \times 100 \times 8 \times 100$$

$$= 1000 \times 800 \Rightarrow 800,000 \text{ pixels}$$

Storage = 9 bits per pixels

Size of frame buffer = Resolution * bits per pixels

$$= 800,000 \times 9$$

$$= 72,000,000 \text{ bits}$$

$$= 9,000,000 \text{ bytes}$$

5) Solution

The system of 640 by 480 frame buffer with 12 bit per pixel

$$\text{Resolution} = 640 \times 480 = 307200 \text{ pixels}$$

Storage = 12 bits per pixel

$$\text{Size of frame buffer} = 640 \times 480 \times 12 \\ = 3676400 \text{ bits}$$

Transfer Rate (Lsu) = 105 bits per su

$$105 \text{ bits} = 1 \text{ second}$$

$$3676400 \text{ bits} = 1 \times 3676400 \\ \cancel{3676400} \times 10^3$$

$$= 3676.4 \text{ sec}$$

The system of 1280 by 1024 frame buffer with 24 bits per pixel.

$$\text{Resolution} = 1280 \times 1024 = 1310720 \text{ pixels}$$

Storage = 24 bits per pixel

$$\text{Size of frame Buffer} = 1280 \times 1024 \times 24 \\ = 31457280 \text{ bits}$$

Transfer Rate (per sec) = 10^5 bits per sec.

$$10^5 \text{ bits} = 1 \text{ sec}$$

$$31457280 \text{ bits} : \frac{1}{10^5} \times 31457280$$

$$= 314.5728 \text{ sec}$$

6) Solution

Given,

for the system; 640×480

$$\text{Resolution} = 640 \times 480 \Rightarrow 307200 \text{ pixels}$$

$$\text{No of pixels, in 60 frames} = 640 \times 480 \times 60 \text{ (Resolution} \times n)$$

$\approx 18432000 \text{ pixels}$

Refresh rate = 60 frames per sec.

$$1 \text{ sec} = \frac{1}{60} \text{ frame} \Rightarrow 60 \text{ frames per sec}$$

$$60 \text{ frames} = 1 \text{ sec}$$

~~$$18432000 \text{ pixels} = \frac{1}{60} \text{ sec}$$~~

$$1 \text{ frame} = \frac{1}{60} \text{ sec}$$

$$= \frac{1}{18432000} \text{ sec} \Rightarrow 5.4 \times 10^{-9} \text{ sec}$$

The system with resolution of 1280×1024

$$\text{Resolution (2 frames)} = (1280 \times 1024) \text{ pixels} = 1310720 \text{ pixels}$$

$$\text{No of pixels in 60 frames} = 1310720 \times 60$$

$$= 78643200 \text{ pixels}$$

Refresh Rate = 60 frame per sec.

$$1 \text{ sec} = 78643200 \text{ pixels}$$

$$1 \text{ pixel} = \frac{1}{78643200} \text{ sec}$$
$$= 1.2 \times 10^{-9} \text{ sec}$$

8)

Sonic Touch Panel

- 1. Touch-sensitive interface for direct interaction with a display

2) Offers high optical quality

3) Fast Response time

4) More expensive

5) Integrated with the display screen

6) Arms, industrial control etc

Sonic tablet

- 1. Graphical input device for drawing or writing.

2) Not applicable.

3) comparatively less response time

4) more affordable

5) Separate from the display

6) Graphic design, CAD, digital art etc

(8)

Bresenham's Line Drawing Algorithm

Start from left end point (x_0, y_0) steps to calc successive column (x_{sample}) and plot the pixels whose scan line (y value) is closer to the line.

After (x_k, y_k) , the choice could be (x_{k+1}, y_k)

$$(x_{k+1}, y_{k+1})$$

$$y = m(x_{k+1}) + b$$

Then,

$$d_1 = y - y_k$$

$$= m(x_{k+1}) + b - y_k$$

and

$$d_2 = (y_{k+1}) - y$$

$$= y_{k+1} - m(x_{k+1}) - b$$

Difference between separations

$$d_1 - d_2 = 2m(x_{k+1}) - 2y_k + 2b - 1$$

Defining decision parameter

$$P_k = \Delta x(d_1 - d_2)$$

$$= 2\Delta y x_k - 2\Delta x y_k + c$$

Sign 'of' P_k is same as that of $d_1 - d_2$ if
 $x > 0$

$$P_{k+1} = 2\Delta x y_{k+1} - 2\Delta x y_k + c$$

$$P_{k+1} - P_k = 2\Delta x(x_{k+1} - x_k) - 2\Delta x(y_{k+1} - y_k)$$

$$P_{k+1}^2 = P_k + 2\Delta y - 2\Delta x(y_{k+1} - y_k)$$

for reducing calculation initially

$$P_0 = 2\Delta y - \Delta x$$

10. a) Refresh Rate:-

The refresh rate is the number of times per second that a display hardware update its buffer. It is measured in Hertz (Hz).

Importance:-

- A higher refresh rate results in smoother motion and reduces the flicker that can cause eye strain.
- Common refresh rates for monitors and TVs include 60Hz, 120Hz and 240Hz.

Application

- Essential in gaming monitors, VR headsets and high-end video displays to ensure a smooth visual output.

b) Aspect-Ratio

The aspect ratio is the proportional relationship between the width and height of a display screen or image.

It is expressed as two numbers separated by a colon (e.g. 16:9, 4:3).

Importance,

- Determines the shape of the display and how content fits on the display.

- Different aspect ratios are suited to different types of content and applications.

for example, 16:9 is common for TVs and computer monitors, while 4:3 was common for older TV monitors.

Applications

- used in video production, screen design and digital photography.

c) Resolution:

Resolution refers to the number of distinct pixels that can be displayed on a screen, typically expressed as width x height (eg 1920 x 1080)

- Importance

- Higher resolution means more pixels and sharper and clearer images. It is a critical factor in image quality.
- Important in various fields including digital display, printing and imaging.

Applications

- In monitors, TVs and mobile devices to determine the clarity and details of the displayed image.

d) Persistence

Persistence refers to the duration of a pixel on a display remains lit after being activated, often measured in milliseconds (ms).

- Importance

- High persistence can lead to motion blur and ghosting effects in fast-moving images. Low persistence is preferable for clearer, sharper images during motion.

- Critical for gaming and video applications where fast movements are common.

Applications

- Important in CRT displays, where it was a major factor in image quality. In modern devices, lower persistence rates improve the visual experience for dynamic content.