YECHEOL KIM

CONTACT INFORMATION

Email address yckim@spa.hanyang.ac.kr

Address Room #407-2, Engineering Center Main Building, Hanyang University, Seoul, Korea

Tel. +82 2 2220 4799

RESEARCH INTERESTS

Deep Learning, Computer Vision, Inteligent Vehicle, Point Clouds Detection

- Specific Research Interests:
 - Object recognition/detection with deep learning
 - Deep learning based point clouds detection algorithms
 - Sensor fusion-based 3D object detection
 - Domain Adaptation

EDUCATION

Ph.D. Cadndidate, Electrical Engineering, Hanyang University Advisor: Prof. Jun Won Choi	Mar. 2018 - Present
B.S., Electrical Engineering, Hanyang University	Mar. 2014 - Feb. 2018
International Olympiad in Informatics Training Course	Mar. 2011 - Dec. 2012

EXPERIENCE

Engineering Intern, Kakao Mobility

Mar. 2021 - Aug. 2021

- Deep Learning based 3D object detection using LiDAR point cloud

PUBLICATIONS

[International Conference]

- 1. Junho Koh*, Jaekyum Kim*, Jin Hyeok Yoo, **Yecheol Kim**, Dongsuk Kum and Jun Won Choi, "Joint 3D Object Detection and Tracking Using Spatio-Temporal Representation of Camera Image and LiDAR Point Clouds", accepted in Association for the Advancement of Artificial Intelligence (AAAI), 2022. (*: equal contribution)
- 2. Jin Hyeok Yoo*, **Yecheol Kim***, Jisong Kim and Jun Won Choi, "3D-CVF: Generating joint camera and LiDAR features using cross-view spatial feature mapping for 3D object detection", accepted in *European Conference on Computer Vision (ECCV)*, 2020. (*: equal contribution) (Ranked 4th place on KITTI 3D car detection leaderboard of March 2020)
- 3. Yecheol Kim, Jaekyum Kim, Junho Koh, and Jun Won Choi, "Enhanced object detection in bird's eye view using 3D global context inferred from Lidar point data," *IEEE Intelligent Vehicles Symposium (IV)*, 2019.
- 4. Jaekyum Kim, Junho Koh, **Yecheol Kim**, Jaehyung Choi, Youngbae Hwang and Jun Won Choi, "Robust Deep Multi-modal Learning Based on Gated Information Fusion Network," *Asian Conference on Computer Vision (ACCV)*, 2018.
- 5. Jaekyum Kim, Jaehyung Choi, **Yecheol Kim**, Junho Koh, and Jun Won Choi, "Robust camera lidar sensor fusion via deep gated fusion network," *IEEE Intelligent Vehicles Symposium (IV)*, 2018.

[Preprint]

1. Yecheol Kim, Konyul Park, Minwook Kim, Dongsuk Kum, and Jun Won Choi, "3D Dual-Fusion: Dual-Domain Dual-Query Camera-LiDAR Fusion for 3D Object Detection," arxiv, 2022.11. (Ranked 5th place on nuScenes 3D Detection leaderboard of December 2022 among single model without any test-time augmentation)

PROJECTS (SELECTED)

Supervision Organization: Kakao Mobility

Jan. 2022 - Jan. 2023

Topic: Semi-supervised domain adaptation for 3D object detection

Supervision Organization: Qualcomm

Sep. 2019 - Jan.2022

Topic: Research on 3D detection of dynamic objects based on Camera and LiDAR sensor fusion

Supervision Organization: Mando

Mar. 2021 - Dec. 2021

Topic: Development of radar only 3D object detection technology

Supervision Organization: Hyundai Motor

Mar. 2021 - Dec. 2021

Topic: Obstacle sensing algorithm using Mono camera attached to power swing doors

Supervision Organization: SK Telecom

Jul. 2019 - Jul. 2020

Topic: Development of Spatio-temporal object detection technology

Supervision Organization: Hyundai Motor

Sep. 2018 - Mar. 2019

Topic: Object detection technology using camera and LiDAR sensor

Supervision Organization: Hyundai MOBIS

Jul. 2017 - Dec. 2017

Topic: Research on Artificial Intelligence Driver System (End to end steering angle prediction on drive PX2)

HONORS AND AWARDS

3rd Place, 2017 Hanyang Computer Programming Contest.

3rd Place, 2016 Hanyang Computer Programming Contest.

Silver Medal, 2012 Korea Olympiad in Informatics.

SKILLS

Languages: Python, C++, Matlab

Deep Learning Tools: Pytorch, Tensorflow, Caffe

REFERENCES

Prof. Jun Won Choi

Department of Electrical Engineering, Hanyang University

E-mail: junwchoi@hanyang.ac.kr Web: http://spa.hanyang.ac.kr/

Relationship: M.S. and Ph.D. supervisor at Hanyang University