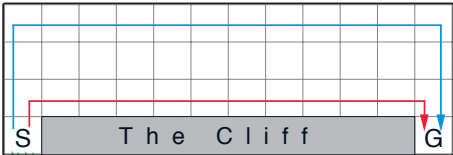


$$R = -1$$

Safer path

Optimal path



T h e C l i f f

$$R = -100$$