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#include <Servo.h>
#include <Wire.h>
#include <ESP8266WiFi.h>
#include "ThingSpeak.h"

#include <LiquidCrystal_I2C.h>
WiFiClient client;

Servo servol;
Servo servo2;
LiquidCrystal_I2C lcd(0x27, 16, 2);
int inputPin1 = D0; // choose input pin (for Infrared sensor)
int inputPin2 = D1;
int inputPin3 = D2;
int inputPin4 = D3;

int val1 = 0; // variable for reading the pin status
int val2 = 0;
int val3 = 0;
int val4 = 0;
const char* ssid = "IOT LAB";
const char* password = "iotlab@507";
int slot=2;
unsigned long myChannelNumber = 1;
const char * myWriteAPIKey = "7MQA95ZCS0QMCRG9";

void setup()
{
    servol.attach(D4);
    servol.write(0);

    WiFi.mode(WIFI_STA);
    ThingSpeak.begin(client); // Initialize ThingSpeak

    servo2.attach(D5);
    servo2.write(0);

    pinMode(inputPin1, INPUT); // declare Infrared sensor as input
    pinMode(inputPin2, INPUT);
    pinMode(inputPin3, INPUT);
    pinMode(inputPin4, INPUT);

    lcd.init(); // Initialize the display

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    lcd.backlight(); // Turn on the backlight
    lcd.print("Smart Parking"); // Display the message on the first
line
    lcd.setCursor(0, 1); // Move cursor to the second line
    lcd.print("Initializing...");

    Serial.begin(9600);
}

void loop()
{

    // Connect or reconnect to WiFi
    if(WiFi.status() != WL_CONNECTED){
        Serial.print("Attempting to connect");
        while(WiFi.status() != WL_CONNECTED){
            WiFi.begin(ssid, password);
            delay(5000);
        }
        Serial.println("\nConnected.");
    }

    val4 = digitalRead(inputPin4); // read input value
    //Serial.print(val1);

    if (val4 == 0)
    {

        servo1.write(90);
        delay(3000);
        servo1.write(0);
    }

    val1 = digitalRead(inputPin1);
    if (val1 == 0)
    {
        servo2.write(90);
        delay(3000);
        servo2.write(0);
    }

    val2 = digitalRead(inputPin2);
    val3 = digitalRead(inputPin3);
    if(val2==0 && val3==0){
        slot=0;
    }
    else if(val2==1 && val3==1){

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        slot=2;
    }
    else{
        slot=1;
    }
    Serial.print("Slot Free:");
    Serial.print(slot);
    Serial.print("\n");
    lcd.setCursor(0, 1); // Move cursor to the second line
    lcd.print("Slot Free: ");
    lcd.print(slot);      // Display the slot status on the LCD
    Serial.print(slot);
    //Serial.print("\n");

    int x = ThingSpeak.writeField(myChannelNumber, 1, slot, myWriteAPIKey);
    if(x == 200){
        Serial.println("Channel update successful.");
    }
    else{
        Serial.println("Problem updating channel. HTTP error code " +
String(x));
    }

    delay(1000);
}
```