

1 1-D STOCHASTIC FUNCTIONS – NOISE

- “noise” = function whose amplitude is derived from a random or a *stochastic* process (i.e., not deterministic)
- Deterministic: f at x specified completely by some parameters (width, amplitude, etc.)
- Stochastic function n at x selected from distribution that describes the probability of occurrence
 - Only statistical averages of signal amplitude are specified
- Example of “discrete” process: number of individual photons measured by detector in time interval Δt
 - must be integer
 - number counted during disjoint intervals of equal length exhibit a degree of “scatter” about some mean value.
- Example of “continuous” stochastic process
 - spatial distribution of photon arrivals from an optical system; the location $[x_n, y_n]$
- Notation: $n[x]$ instead of $f[x]$; “ n ” is used to indicate its “noisy” character.
 - potential confusion because n also specifies an integer coordinate, *e.g.*, $f[n]$
- Complex-valued noise constructed by adding two random variables at each coordinate after weighting one by i :

$$n[x] = n_1[x] + i n_2[x]$$

1.1 PROBABILITY DISTRIBUTION

- P_n = probability of the integer value n for a discrete distribution
- $p[n]$ = probability density of a real-valued amplitude n derived from a continuous distribution
 - probability that continuous variable n lies within a specific interval is the integral of $p[n]$ over that interval, *e.g.*

$$P(a \leq n \leq b) = \int_a^b p[n] \, dn$$

1.2 THE MOMENTS of a PROBABILITY DISTRIBUTION

- “distribution” of probability about origin of coordinates determined by moments of $p[n]$
- k^{th} moment is area of product of $p[n]$ and a weight factor n^k :

$$m_k \{p[n]\} \equiv \int_{-\infty}^{+\infty} n^k p[n] \, dn$$

- “Zeroth moment” evaluated by setting $k = 0$; is projection of unit constant onto $p[n]$, which must be the unit area of $p[n]$:

$$m_0 \{p[n]\} = \int_{-\infty}^{+\infty} n^0 p[n] \, dn = \int_{-\infty}^{+\infty} p[n] \, dn = \langle n^0 \rangle = 1$$

- First moment is projection of n^1 onto $p[n]$
 - “amplifies” contributions from large values of n .
 - Mean value of amplitude n selected from probability distribution $p[n]$
 - Notations: $\langle n \rangle$, \hat{n} , and μ

$$m_1 \{p[n]\} = \int_{-\infty}^{+\infty} n^1 p[n] \, dn = \langle n^1 \rangle = \langle n \rangle$$

- $\langle n \rangle$ is value of n that divides $p[n]$ into two equal parts

1.3 Central Moments

- expected values of $(n - \langle n \rangle)^k$
- measure weighted variation of $p[n]$ about mean:

$$\mu_k \{p[n]\} \equiv \int_{-\infty}^{+\infty} (n - \langle n \rangle)^k p[n] \, dn$$

- first central moment $\mu_1 = 0$.
- second moment is projection of n^2 onto $p[n]$:

$$m_2 \{p[n]\} = \int_{-\infty}^{+\infty} n^2 p[n] \, dn \equiv \langle n^2 \rangle$$

- second central moment of $p[n]$ is variance σ^2
 - measures “spread” of noise probability about mean value:

$$\mu_2 \{p[n]\} \equiv \int_{-\infty}^{+\infty} (n - \langle n \rangle)^2 p[n] \, dn \equiv \sigma^2$$

- Expand $(n - \langle n \rangle)^2$ and evaluating three resulting integrals to obtain important relationship among the mean, variance, and $\langle n^2 \rangle$

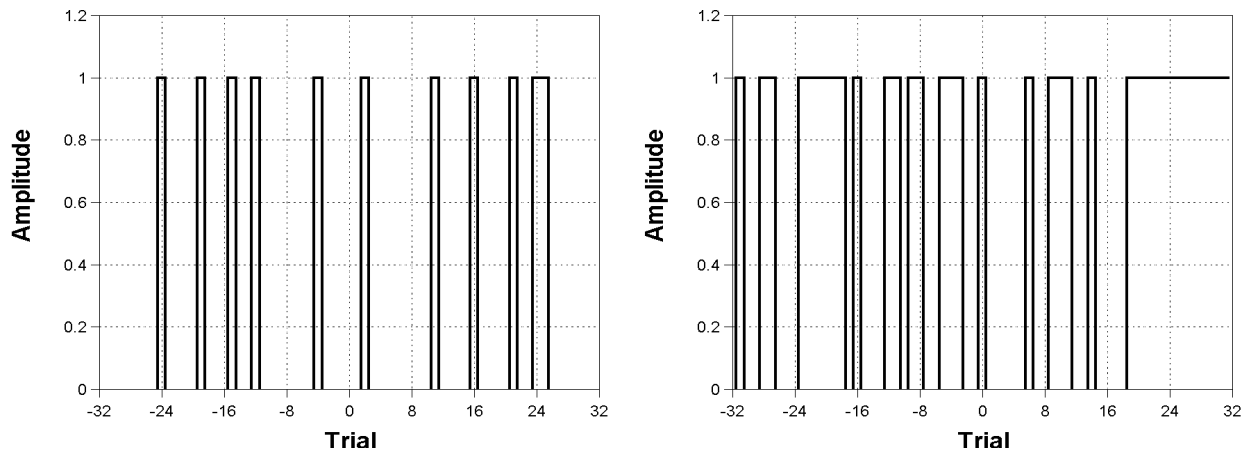
$$\sigma^2 = \langle n^2 \rangle - \langle n \rangle^2$$

1.4 DISCRETE PROBABILITY LAWS

- model processes that have discrete (and often binary) outcomes
- particularly useful when constructing models of such imaging processes as photon absorption by sensor.
- Simplest type of discrete probability law applies to events that have only two possible outcomes
 - success or failure
 - true or false
 - on or off
 - head or tail.
- Individual implementation of binary event is “Bernoulli trial”
- Collective realizations of many such events described by binomial and Poisson distributions.

1.4.1 BERNOULLI TRIALS

- Consider flux of photons onto “imperfect” absorbing material
 - Individual photons may be absorbed or not
 - Testing of absorption of a photon is a Bernoulli trial
 - “successful” absorption indicated by 1, and “failure” by 0
 - Statistics of string of Bernoulli trials specified by probability of “success” (outcome “1”, denoted by “ p ”)
 - * $0 \leq p \leq 1$
 - Probability of “failure” (outcome “0”) is $1 - p$, often denoted by “ q ”.
- Relative probabilities for particular absorber determined from physical model of interaction or from observed results of large number of Bernoulli trials
- “Images” of independent Bernoulli trials for different values of p :



Examples of 64 Bernoulli trials: (a) $p = 0.2$, (b) $p = 0.5$.

1.4.2 MULTIPLE BERNOULLI TRIALS – THE BINOMIAL PROBABILITY LAW

- N Bernoulli trials where probability of outcome “1” is p and the probability of outcome “0” is $1 - p$
- Number of possible distinct outcomes is 2^N
- Relative likelihood of outcomes is determined by p .

- Probability of specific sequence 101010 \dots 10 (alternating “1” and “0”, assuming N is even)

$$p(10101010 \dots 101010) = p \cdot q \cdot p \cdot q \cdot \dots \cdot p \cdot q = p^{\frac{N}{2}} \cdot q^{\frac{N}{2}}$$

- Equal numbers of “successes” and “failures”.
- Probability of a different sequence where the first $\frac{N}{2}$ outcomes are “1” and the remaining $\frac{N}{2}$ outcomes are “0” is same:

$$p(11111111 \dots 00000000) = p \cdot p \cdot p \cdot p \cdot \dots \cdot q \cdot q \cdot q \cdot q \cdot q = p^{\frac{N}{2}} \cdot q^{\frac{N}{2}}$$

- Two distinct outcomes have same number of “successes” and “failures”, and therefore have identical histograms.
- Outcome of N trials with exactly n “successes”. The probability of a specific such outcome is:

$$p_1 \cdot p_2 \cdot p_3 \cdot \dots \cdot p_n \cdot q_1 \cdot q_2 \cdot q_3 \cdot \dots \cdot q_{N-n} = p^n \cdot q^{N-n}$$

- In many applications, order of arrangement is not significant; only total number of successes n matters.
- Compute number of possible combinations of n successes in N trials.
- It is straightforward to show that this number is the “binomial coefficient”:

$$\frac{N!}{(N-n)! n!} \equiv \binom{N}{n}$$

- probability of n “successes” in N trials is:

$$P_n = \frac{N!}{n! (N-n)!} p^n (1-p)^{N-n} = \binom{N}{n} p^n [1-p]^{[N-n]}$$

- Consider a coin flip with two outcomes, H and T .

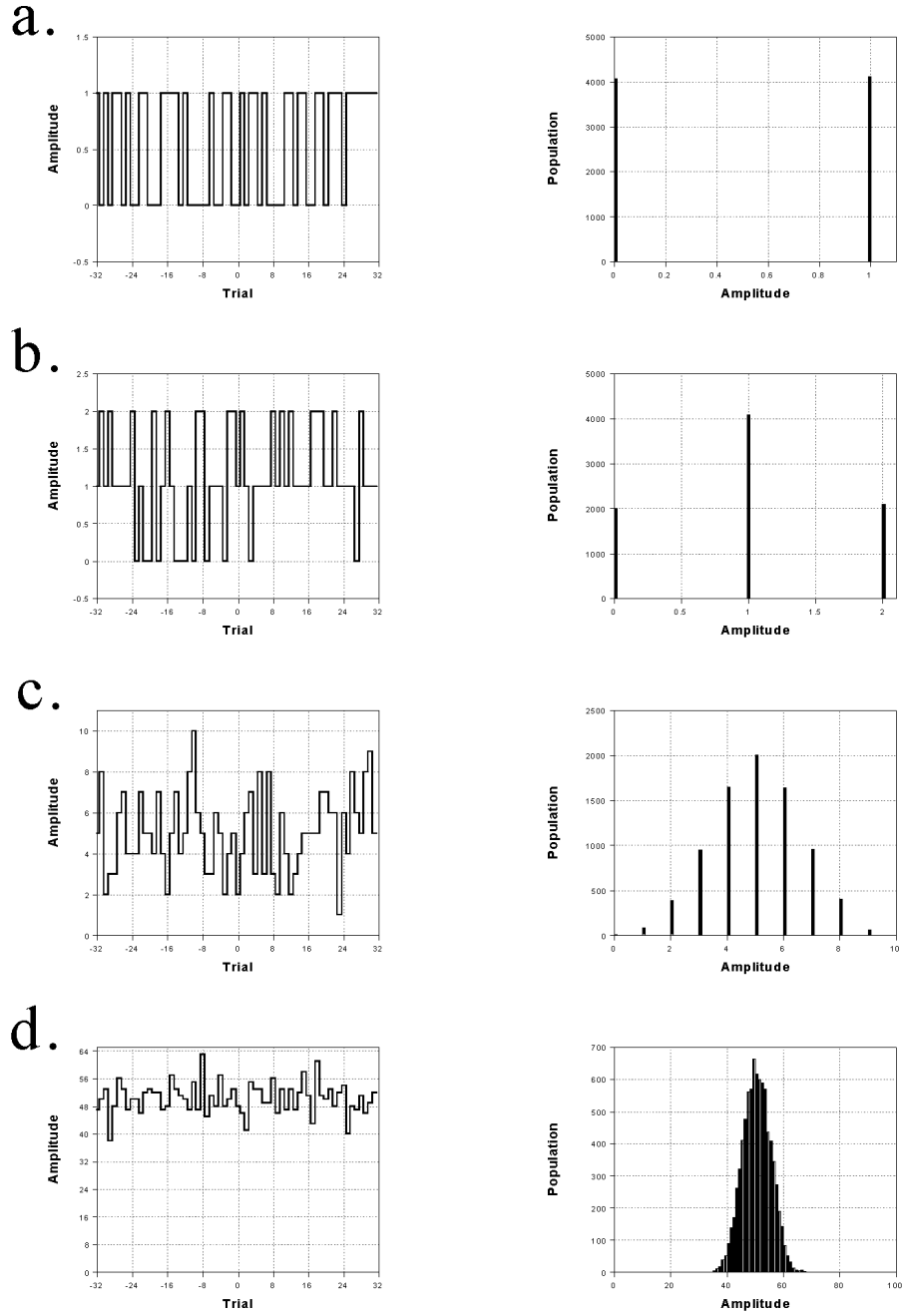
- $N = 4 \implies$ number combinations with $n = 2$ heads is $\frac{4!}{2!2!} = 6$
- $HHTT, HTHT, THHT, THTH, HTTH, \text{ and } TTHH$

- If H and T equally likely ($p = q = 0.5$) \implies probability of two heads in four flips is $P_2 = 6(0.5)^2(0.5)^2 = 0.375$.
- Number of realizations of no heads in four flips is $\frac{4!}{0!4!} = 1$, Probability of no heads in four flips is $P_0 = 1(0.5)^0(0.5)^4 = 0.0625$.
- Binomial law also applies to cases where $p \neq q$
 - Flipping “unfair” coin
 - $p = 0.75 \implies$ probability that four flips would produce two heads is $P_2 = 6(0.75)^2(0.25)^2 \simeq 0.211$

- less than probability of two heads in four flips of fair coin.
- Mean and variance of number of outcomes with individual probability p in experiments obtained by substitution

$$\begin{aligned}\langle n \rangle &= Np \\ \sigma^2 &= N p [1 - p]\end{aligned}$$

- “Shape” of histogram is approximately Gaussian.
 - Gaussian distribution is continuous
 - Binomial distribution is discrete
 - Observation suggests that samples obtained from large number of independent Bernoulli trials with probability p may be approximately generated by thresholding values generated by a Gaussian distribution.



Realizations of N Bernoulli trials at 8192 samples with $p = 0.5$ and the resulting histograms: (a) $N = 1$ trial per sample, two (nearly) equally likely outcomes; (b) $N = 2$; (c) $N = 10$; and (d) $N = 100$. The histogram approaches a Gaussian function for large N .

1.4.3 POISSON PROBABILITY LAW

- Approximation to binomial law for large numbers of rarely occurring events, i.e., $N \gg 1$ and $p \rightarrow 0$
- Mean number of events is $\langle n \rangle = Np$, denoted by λ
- Form of Poisson law obtained by substituting into the binomial law in limit $N \rightarrow \infty$:

$$p_n = \lim_{N \rightarrow \infty} \left\{ \binom{N}{n} \left[\frac{\lambda}{N} \right]^n \left[1 - \frac{\lambda}{N} \right]^{N-n} \right\}$$

- Take the natural logarithm of both sides to obtain:

$$\begin{aligned} \log_e [p_n] &= \lim_{N \rightarrow \infty} \left\{ \log_e \left[\binom{N}{n} \left[\frac{\lambda}{N} \right]^n \left[1 - \frac{\lambda}{N} \right]^{N-n} \right] \right\} \\ &= \lim_{N \rightarrow \infty} \left\{ \log_e \left[\binom{N}{n} \left[\frac{\lambda}{N} \right]^n \right] \right\} + \lim_{N \rightarrow \infty} \left\{ [N-n] \log_e \left[1 - \frac{\lambda}{N} \right] \right\} \\ &= \lim_{N \rightarrow \infty} \left\{ \log_e \left[\left(\frac{N!}{[N-n]! n!} \right) \left[\frac{\lambda}{N} \right]^n \right] \right\} + \lim_{N \rightarrow \infty} \left\{ \frac{\log_e \left[1 - \frac{\lambda}{N} \right]}{[N-n]^{-1}} \right\} \end{aligned}$$

- Use fact that n is small to evaluate first additive term:

$$\lim_{N \rightarrow \infty} \left\{ \log_e \left[\frac{N(N-1)(N-2) \cdots (N-n+1)}{n!} \left(\frac{\lambda}{N} \right)^n \right] \right\} \simeq \log_e \left\{ \frac{N^n}{n!} \left(\frac{\lambda}{N} \right)^n \right\}$$

- Second term evaluated by recognizing as ratio of two terms that both approach zero in the limit
- Apply l'Hôpital's rule:

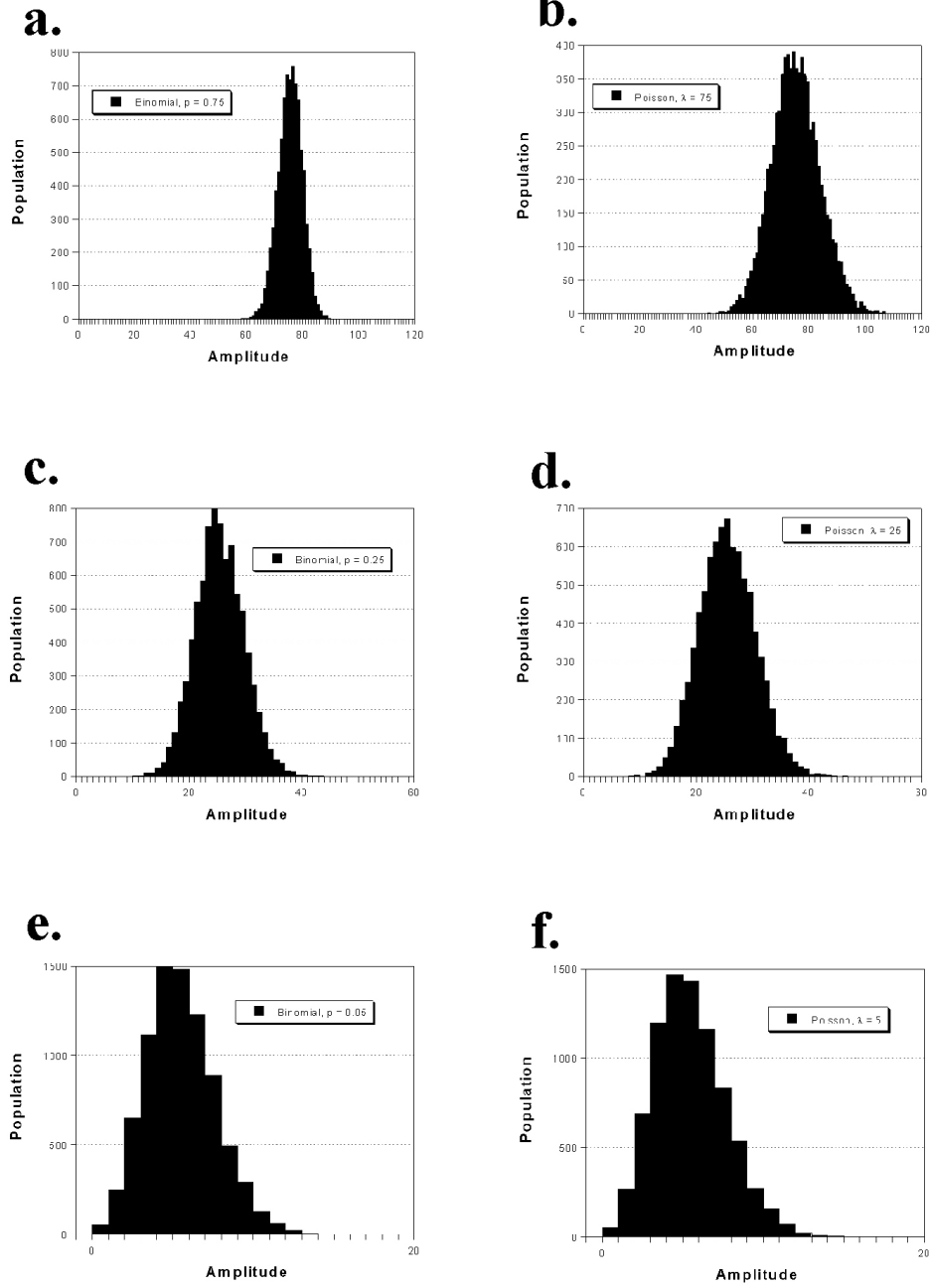
$$\begin{aligned} \lim_{N \rightarrow \infty} \left\{ \frac{\log_e \left(1 - \frac{\lambda}{N} \right)}{(N-n)^{-1}} \right\} &= \lim_{N \rightarrow \infty} \left\{ \frac{\frac{d}{dN} (\log_e (1 - \frac{\lambda}{N}))}{\frac{d}{dN} (N-n)^{-1}} \right\} \\ &= \lim_{N \rightarrow \infty} \left\{ \frac{\left(1 - \frac{\lambda}{N} \right)^{-1} \left(\frac{\lambda}{N^2} \right)}{-(N-n)^{-2}} \right\} \\ &= \lim_{N \rightarrow \infty} \left\{ -\lambda \left(\frac{N-n}{N} \right)^2 \left(1 - \frac{\lambda}{N} \right)^{-1} \right\} \end{aligned}$$

- Collect terms:

$$\log_e [p_n] = \log_e \left[\frac{\lambda^n}{n!} \right] - \lambda \implies p_n = \left[\frac{\lambda^n}{n!} \right] e^{-\lambda}$$

- Poisson distribution is particular limiting case of binomial distribution

- Mean, variance, and third central moment of Poisson distribution are identically λ



Comparison of binomial and Poisson random variables, $N = 100$: (a) binomial, $p = 0.75$, $\langle n \rangle = 75.05$, $\sigma^2 = 18.68$; (b) Poisson, $\lambda = 75$, $\langle n \rangle = 74.86$, $\sigma^2 = 74.05$; (c) binomial, $p = 0.25$, $\langle n \rangle = 24.93$, $\sigma^2 = 18.77$; (d) Poisson, $\lambda = 25$, $\langle n \rangle = 25.01$, $\sigma^2 = 24.85$; (e) binomial, $p = 0.05$, $\langle n \rangle = 5.00$, $\sigma^2 = 4.71$; (f) Poisson, $\lambda = 5$, $\langle n \rangle = 4.97$, $\sigma^2 = 4.97$.

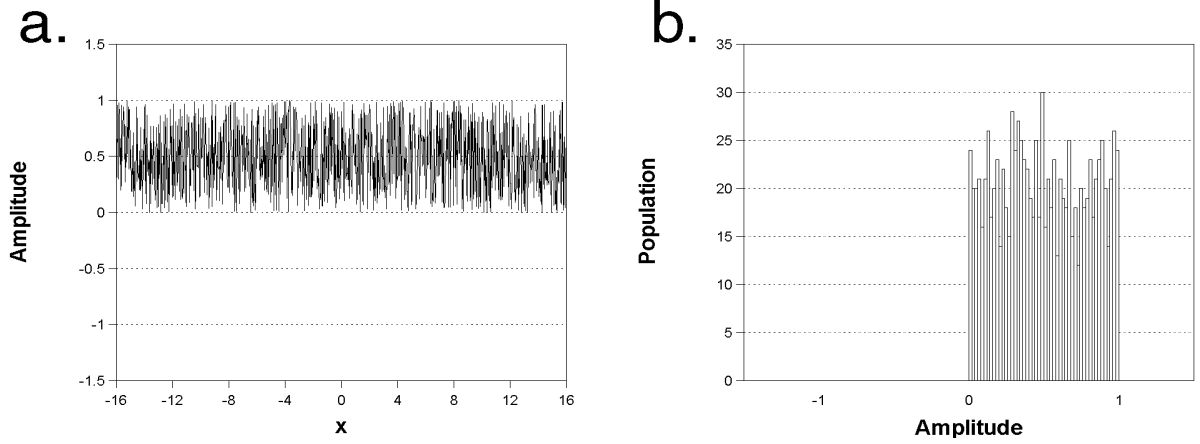
1.5 CONTINUOUS PROBABILITY DISTRIBUTIONS

1.5.1 UNIFORM DISTRIBUTION

- generates most intuitive type of noise
 - amplitude n equally likely to occur within any finite interval of equal size.

$$p_{Uniform}[n] = \frac{1}{|b|} RECT \left[\frac{n - \langle n \rangle}{b} \right]$$

- b is width of allowed values of n
- $\langle n \rangle$ is mean value
- Multiplicative scale factor b^{-1} ensures unit area
- Variance of uniform distribution is $\sigma^2 = \frac{b^2}{12}$.



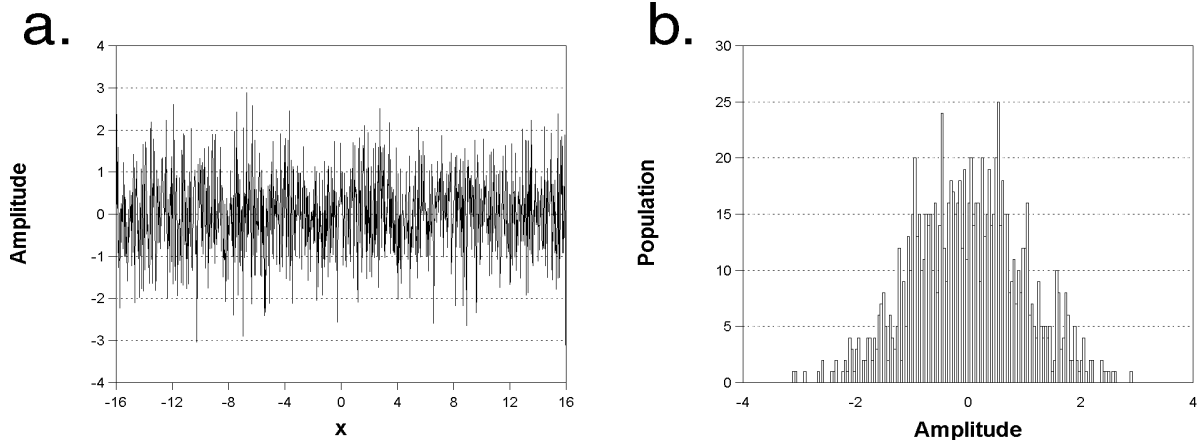
Uniformly distributed random variable on interval $[0, 1)$ with $\mu = 0.5$ and $\sigma^2 = \frac{1}{12}$: (a) sample, (b) histogram.

1.5.2 NORMAL DISTRIBUTION

- Familiar symmetric “bell curve” of probability
- Most applicable of all probability laws
- $\langle n \rangle$ = most likely amplitude (peak of the probability density)
- Probability that amplitude will differ from mean progressively decreases as the value moves away from $\langle n \rangle$
- Probability density function is Gaussian function with width parameter b proportional to standard deviation σ of probability distribution

$$p_{Normal}[n] = \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(n-\langle n \rangle)^2}{2\sigma^2}}$$

- Leading factor $(\sqrt{2\pi})^{-1}$ ensures that area of the probability density function is unity



Samples of a random variable generated by a normal distribution with $\langle n \rangle = 0, \sigma^2 = 1$: (a) samples, (b) histogram.

Central-Limit Theorem:

- Cascade of stochastic processes derived from (nearly) arbitrary set of probability density functions generates a normal distribution
- Central-limit theorem ensures that probability law of outputs is generally Gaussian, to good approximation.

1.5.3 RAYLEIGH DISTRIBUTION

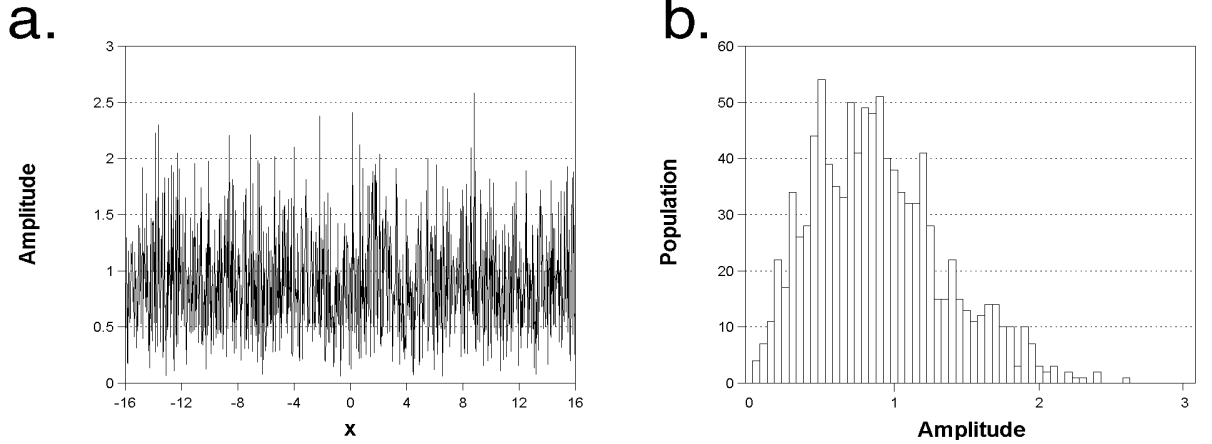
- Imaging applications that involve Fourier transforms of distributions of complex-valued random variables
 - description of Fraunhofer diffraction from a random scatterer
 - computer-generated holography.
- Distribution of magnitude where where real and imaginary parts are random variables selected from same Gaussian distribution.
- probability density function characterized by single parameter a :

$$p_{Rayleigh}[n] = \frac{n}{a^2} e^{-\left(\frac{n^2}{2a^2}\right)} STEP[n]$$

- $STEP$ function ensures that allowed amplitudes n must be nonnegative
- Mean $\langle n \rangle$ and variance σ^2 of the Rayleigh distribution must be functions of the parameter a :

$$\langle n \rangle = \sqrt{\frac{\pi}{2}} a \simeq 1.25a$$

$$\sigma^2 = \left(2 - \frac{\pi}{2}\right) a^2 \simeq 0.429a^2, \quad \sigma \simeq 0.655a$$



Rayleigh-distributed random variable generated from Gaussian-distributed random variables in quadrature, each with $\langle n \rangle = 0, \sigma^2 = 1$: (a) sample, (b) histogram. Resulting mean and variance are $\langle n \rangle = 1.270, \sigma^2 = 0.424$.