# Rashik Shrestha

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Morgantown, West Virginia, USA

More about me: rashik.info.np

## About Me

My research interest lies in the intersection of **Robotics** and **Spatial Intelligence**. I am fascinated by how human brains can perceive the 3D environment and act accordingly. My long-term research goal is to develop a robotic system that can accurately perceive, reason about, and interact with its surrounding 3D environment.

#### I have worked on

Computer Vision

Photogrammetry, Multi View Geometry 3D reconstruction NeRF, Gaussian Splatting Visual SLAM

Robotics
ROS
Probablistic Robotics
Kinematics
Embedded Programming
Circuit design and fabrication

Artificial Intelligence
Transformers

Diffusion Models etc..

### Publications

• Rashik Shrestha, Madhav Rijal, Trevor Smith, Yu Gu, FloPE: Flower Pose Estimation for Precision Pollination, IROS 2025 Under review

**Abstract**: A real-time flower pose estimation framework for computationally constrained robotic pollination systems. Leverages 3D Gaussian Splatting to generate photorealistic synthetic datasets with precise pose annotations, enabling effective knowledge distillation from a high-capacity teacher model to a lightweight student model for efficient inference. (https://wvu-irl.github.io/flope-irl/) (https://arxiv.org/abs/2503.11692)

• Rashik Shrestha, Bishad Koju, Abhigyan Bhusal, Danda Pani Paudel, François Rameau, CaLDiff: Camera Localization in NeRF via Pose Diffusion, Pre-Print

**Abstract**: Traditional feature-based hierarchical localization works really great until the environment lacks textures for point feature extraction. This project leverages the power of NeRFs and diffusion models for robust pose estimation in low textured environment.

 $(\rm https://rashik.info.np/2023/11/07/caldiff/) \quad (\rm https://arxiv.org/abs/2312.15242)$ 

• Rashik Shrestha, Ajad Chhatkuli, Menelaos Kanakis, Luc Van Gool, Residual Learning for Image Point Descriptors, Pre-Print Abstract: Handcrafted point features like SIFT, SURF still work good for most of the tasks (3D reconstruction, localization) with a properly tuned pipeline. This project focuses on enhancing the existing handcrafted features by learning only what they already don't know. This creates a lightweight model that is fast and robust.

 $(https://rashik.info.np/2022/10/07/residual-feature-learning/) \quad (https://arxiv.org/abs/2312.15471)$ 

## Academics

West Virginia University

Ph.D. in Computer Science

Pulchowk Campus, Tribhuwan University

Bachelor in Electronics and Communication engineering (79.27%)

Morgantown, West Virginia Sep 2024 - Now

Lalitpur, Nepal

Nov 2016 - Mar 2021

### Projects

- Visual SLAM for Mobile Robot in a dynamic environment: Used a monocular camera as its only sensor to build a 3D map of indoor environment and localized the camera in the built map using Visual SLAM algorithm. Masked out dynamic content of the environment like moving person for better accuracy.
- ABU Robocon 2019: Designed, fabricated and tested the robots to take part in ABU Robocon 2019 competition held at Ulaanbaatar, Mongolia.
- Precision Livestock Farming: Designed and tested an automated system for poultry farming that monitors various environmental factors and regulates them accordingly. Used images to estimate the weight and distribution behavior. Used sound analysis to estimate the feeding behavior.
- Streetfood Vending Machine: Designed, built and launched fully automated vending machine for a popular Nepali street food
- Low Cost Spin Coater: Designed and fabricated low cost spin coating device to use on molecular labs.

etc ..

# Work Experiences

## Interactive Robotics Laboratory (IRL) (yugu.faculty.wvu.edu)

(on-site) WVU, Morgantown

Graduate Research Assistant

August 2024 - Now

• Working on accurate pose estimation of flowers for precision pollination. Under the supervision of Prof. Yu Gu

#### NAAMII (naamii.org.np)

(on-site) Kathmandu, Nepal

Research Assistant

May 2021 - July 2024

- o Worked on project CaLDiff: Camera Localization in NeRF via Pose Diffusion under the supervision of Dr. Danda Pani Paudel and Prof. Francois Rameau
- Worked on project Residual Learning for Image Point Descriptors under the supervision of Dr. Ajad Chhatkuli

#### GeoAutomation (geoautomation.com)

(remote) Montréal (QC), Canada

Computer Vision Engineer

June 2021 - July 2024

- o Develop softwares for Structure from motion (SFM), Panorama Stitching and image retrieval algorithms
- Worked with various GenICam standard machine vision cameras for the data acquisition system for mobile mapping
- Experienced developing the highly efficient systems in C++ to handle huge amount of real-time data (3GBps) for image data acquisition
- o Develop and Deploy programs for AWS Lambda, Batch and EC2 instances

## NAAMII (naamii.org.np)

(on-site) Kathmandu, Nepal

Jun 2020 - Nov 2020

o Worked on Visual SLAM, Feature Matching, Indoor navigation, ROS

# Robotics Club, Pulchowk Campus (robotics.pcampus.edu.np)

(on-site) Lalitpur, Nepal Nov 2016 - March 2019

Robotics Engineer

Research Intern

- o Embedded Programming for AVR and ARM processors
- o Circuit design, fabrication
- o Control Systems, forward/reverse kinematics, 3D modeling

# Teaching Experiences

## Fourth Annual Nepal AI School (nepalschool)

(on-site) Kathmandu, Nepal

May 2023

o Assisted in teaching following topics: Mobile robotics, Photogrammetry, SLAM, NeRF, Image retrieval techniques, Hierarchical localization

#### Third Annual Nepal AI School (nepalschool)

(on-site) Bhaktapur, Nepal

Teaching Assistant

Teaching Assistant

Dec 2021

o Conducted lab sessions, assisted in Lab exercises and lecture assignments, prepared teaching materials for lab sessions in 10 days-long school in AI

## Hardware Fellowship, LOCUS (locus)

(on-site) Lalitpur, Nepal

Trainer/Mentor

• Worked as trainer/mentor for 10 days hardware fellowship program. I got to share my knowledge about basic electronics, sensors, actuators, Arduino programming, soldering, and many more.

# Leadership and Volunteering Experiences

## Cohere For AI - The Aya Project (aya.for.ai)

(remote)

Nepali Language Ambassador

Sep 2023 - Jan 2024

o Aya is an Open Science Initiative to Accelerate Multilingual AI Progress. I volunteer to represent Nepali Language by helping in data collection.

#### IEEE Pulchowk (ieee-pulchowk)

(on-site) Lalitpur, Nepal

Events Supervisor

Feb 2020 - Feb 2021

• Conducted and supervised events such as talk shows, blood donations, reading sessions, training programs, etc.

# Engineering Students Group of Bhaktapur (esqb)

(on-site) Bhaktapur, Nepal

President

Nov 2019 - May 2021

o Successfully organized and executed a variety of programs and initiatives to support and engage the engineering student community

Provided assistance with study materials and transportation services

## **Trainings**

#### Nepal AI School

(nepalschool)

Pokhara, Nepal Dec 2019

• Topics covered: Geometric Deep Learning, NLP, 3D Vision, VAEs and GANs, Computational Neuroscience, Robotic Vision (SLAM)

#### First Nepal winter school in AI

Kathmandu, Nepal

(firstwinterschool)

Dec 2018

• Participated in a 10 days long winter school about machine learning and AI. Topics covered: Probability and Statistics, Linear Algebra, Computer Vision, AI and Society, Bioinformatics, Reinforcement Learning, Graphical Modeling, Deep learning

# Certifications

- Machine Learning with Python-From Linear Models to Deep Learning
- Code Foundation for ROS
- ROS For Beginners
- Neural Networks and Deep Learning

#### Honors and Awards

- Rohm Award (Team): 2019 ABU Robocon 2019
- LOCUS Best Thematic Hardware: 2019 Winner of National Level Competition held by LOCUS, Pulchowk
- Institute of engineering (IOE) full scholarship: 2016 Full scholarship for studying Bachelor degree in one of the most reputed engineering college of Nepal

## References

## **Prof. Yu Gu** (Ph.D. Supervisor)

Professor - Department of Mechanical, Materials and Aerospace Engineering Adjunct Associate Professor - Lane Department of Computer Science and Electrical Engineering West Virginia University yu.gu@mail.wvu.edu Homepage

# Dr. Danda Pani Poudel

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#### Prof. François Rameau

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