Bandit Problems

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- Best Arm identification in Multi Arm Bandits: When the final payoff does not include the reward from the exploration stage
 - Channel selection for cell phones: Test a number of channels, then use one to transmit
 - Clinical trials: Sequentially test a number of formulae. Choose the best for commercialization
- Best Arm identification in Multi-Bandit Multi-Arm settings
 - Clinical Trials with M subpopulations, and K_m options for treating the m^{th} population
 - Online advertising with M subpopulations, and K_m options for advertising to the m^{th} population

Problem definition

- Known Parameters: Number of arms k and number of rounds n
- **Unknown Parameters**: Reward distributions ν_1, \ldots, ν_k and unique arm i^* with maximal mean
- For each round:
 - The forecaster chooses an arm $I_t \in 1, \dots, K$
 - ullet The arm draws a reward from u_{I_t}

Finally, the forecaster outputs a recommendation J_n

- Assumptions Each arm has a finite first moment
- Goal Find the arm with maximal mean
- Evaluation
 - Regret: $r_n = \mu^* \mu_{J_n}$
 - Gap: $\Delta_i = \mu^* \mu_i$
 - Minimum Gap: $\Delta_{i^*} = \min_{i \neq i^*} \Delta_i$
 - Probability of error: $e_n = P(J_n \neq i^*)$



Lower Bound

Lower Bound

Let $\{\nu_1,\ldots,\nu_K\}$ be Bernoulli distributions with parameters in $[\frac{1}{3},\frac{2}{3}]$. For any forecaster, $\exists c>0$ such that, up to a permutation of the arms,

$$e_n \ge \exp\left(-c\frac{n\log(K)}{H}\right)$$

Here,
$$H = \sum_{i \neq i^*} \left(\frac{1}{\Delta_i}\right)^2$$

Informally, we say, the algorithm required $O(H/\log K)$ rounds to find the best arm

Also, let $H'=\max_i \frac{i}{\Delta_{(i)}^2}$, where $\Delta_{(i)}$ is the gap for the i^{th} best arm.

Notice that $H' \leq H \leq \log(2K)H'$.



Uniform Strategy

Select each arm $k \in \{1, \dots, K\}$ $\lceil \frac{n}{K} \rceil$ times

Output $J_n = \operatorname{argmax}_{i \in K} \hat{X}_i$

Probability of Error Bound

$$\exists c>0$$
 such that $e_n\leq \exp\left(-crac{n\min_i\Delta_i^2}{K}
ight)$

Proof: (Union Bound and Hoeffdings inequality)

$$P(J_n \neq i^*) \leq \sum_{i \neq i^*} P(\hat{X}_i \geq \hat{X}_{i^*})$$

$$\leq \sum_{i \neq i^*} P(\hat{X}_i - \mu_i + \mu_{i^*} - \hat{X}_{i^*} \geq \Delta_i)$$

$$\leq K \exp(-\frac{cn \min \Delta_i^2}{k})$$

Successive Rejects

Let
$$\overline{\log}(K) = \frac{1}{2} + \sum_{i=2}^K \frac{1}{i}$$

Let $n_0 = 0, n_k = \lceil \frac{1}{\overline{\log}(K)} \frac{n-K}{k+1-K} \rceil$ for $1 \le k \le K-1$
Let $A_1 = 1, \dots, K$. For $k = 1 \dots K$:

- $\forall i \in A_k$, select arm $i \ n_k n_{k-1}$ times.
- $A_{k+1} = A_k \backslash \operatorname{argmin}_{i \in A_k} \hat{X}_{i,n_k}$, where \hat{X}_{i,n_k} is the emperical value of the mean of arm i

Output the unique element in A_K as J_n

Probability of Error Bound

 $\exists c > 0$ such that

$$e_n \le \exp\left(-c \frac{n}{H'\overline{\log}(K)}\right)$$



Upper Confidence Bound - Exploration

Let
$$B_{i,t} = \hat{X}_{i,T_i(t)} + \sqrt{\frac{cn/H}{T_i(t)}}$$
,

where $T_i(t) = \text{No. of times arm } i \text{ is pulled till stage } t$

For each round t,

Draw $I_t \in \operatorname{argmax}_{i \in 1, ..., K} B_{i, t-1}$

Finally, $J_n = \operatorname{argmax}_{i,...,K} \hat{X}_{i,T_i(t)}$

Probability of Error Bound

For c small enough, $\exists c' > 0$ such that

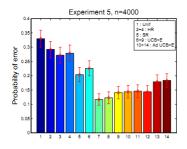
$$e_n \leq \exp(-c'n/H)$$

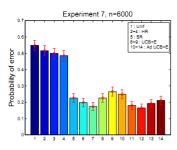
Here, c is an exploration parameter.

Note that H is unknown, thus effectively a parameter, which must be tuned.



Experiments





Multi-Bandit Multi-Arm Problem

Multi-Bandit Best Arm Identification - Gabillon, Ghavamzadeh, Lazaric, Bubeck (NIPS 2011)

Setup similar to before.

M bandits. The m^{th} bandit has K_m arms

Evaluation

Regret

$$r(n) = \frac{1}{M} \sum_{m=1}^{M} r_m(n) = \frac{1}{M} \sum_{m=1}^{M} (\mu_m^* - \mu_{J_m(n)})$$

Average probability of error

$$e(n) = \frac{1}{M} \sum_{m=1}^{M} r_m(n) = \frac{1}{M} \sum_{m=1}^{M} (P(J_m(n) \neq k_{m^*}))$$

Global max error

$$I(n) = \max_{m} I_m(n) = \max_{m} P(J_m(n) \neq k_{m^*})$$



Gap Exploration

Similar to UCB-E

Parameters: Number of rounds n, exploration parameter a, maximum range b

Let
$$T_{mk}(0) = 0$$
, $\hat{\Delta}_{mk}(0) = 0$, $\forall m, k$

For t = 1, ..., n:

$$\bullet \ \ B_{mk}(t) = -\hat{\Delta}_{mk}(t-1) + b\sqrt{\frac{a}{T_{mk}(t-1)}}$$

- Draw $I_t \in \operatorname{argmax}_{m,k} B_m k(t)$
- \bullet Pull arm I_t and update the selected bandit and arm

Probability of Error Bound

 $\exists c_1, c_2 > 0$ such that

$$I(n) \leq P(\exists m: J_m(n) \neq k_{m^*}) \leq c_1 M K n \exp\left(-c_2 \frac{n - MK}{H}\right)$$

Here,
$$H = \sum_{m,k} \frac{b^2}{\Delta_{mk}^2}$$



Further remarks and Summary

- For the algorithms which have parameters, corresponding adaptive versions also exist, and perform well in practice
- $H=1/\Delta_i^2$ measures the complexity of the problem
- We need at least $H/\log(K)$ rounds to find the best arm
- SR is parameterless and find the best arms in $H \log(K)$ rounds
- UCB E require H rounds, but needs the value of H
- Gap-E generalizes UCB-E to the multi bandit case

Linear Optimization for Bandit Problems

The Price of Bandit Information for Online Optimization - Dani, Hayes, Kakade (NIPS 2008)

We are given a set $D \subset \mathbb{R}^n$ - the decision space

D could be possibly infinite

Each vector in D is a possible decision or action

For
$$t = 1, 2, ..., T$$

- Adversary chooses $L_t \in \mathbb{R}^n$
- Learner chooses $x_t \in D$
- A loss of $I_t = L_t^T x_t$ is incurred Learner only sees this

Possible Applications

- Path planning
- Network Routing



Assumptions

- Learner has a randomized strategy. Chooses x_t probabilistically
- L_t must be admissible i.e. $0 \le L_t^T x \le 1, \ \forall x \in D$
- D contains a barycentric spanner i.e. there are n l.i. vectors $\{v_1, \ldots, v_n\}$ in D and any vector $x \in D$ is s.t. $x = \sum_i \lambda_i v_i$ with $\lambda_i \in [-1, 1]$.
- Such a barycentric spanner can be obtained for any n-dimensional compact set in \mathbb{R}^n (Awerbuch and Kleinberg, STOC 2004)
- WLOG, $\{e_1, e_2, \dots, e_n\} \subset D$ and $D \subset [-1, 1]^n$



Define regret for a particular choice of actions $\{x_1, \ldots, x_T\}$ as,

$$R = \sum_{t} L_{t}^{T} x_{t} - \min_{x \in D} \sum_{t} L_{t}^{T} x$$

AIM: Minimize the regret

Since we have a randomized strategy, we want to bound E[R]

Previous Bounds

- Use general K-arm bandit strategy by Auer et. al. Gives, $E[R] = O(\sqrt{TK \log K})$. K = |D| in this setting. Does not exploit linearity of loss. Moreover, |D| can be very high.
- Approaches prior to this Bound of $O(poly(n)T^{\frac{2}{3}})$ (Dani and Hayes, SODA 2006) or worse.

Making D finite

$\mathsf{Theorem}$

For any
$$D \subset [-1,1]^n$$
, $\exists \tilde{D}$ s.t. $|\tilde{D}| \leq (nT)^{\frac{n}{2}}$ and $|\mathit{OPT}\ \mathit{REGRET}(D) - \mathit{OPT}\ \mathit{REGRET}(\tilde{D})| \leq \sqrt{nT}$ Also, \tilde{D} forms a $1/\sqrt{T}$ -net for D .

• How ? - For every $x \in D$, truncate each coordinate to the first $\frac{1}{2}\log(nT)$ bits. Keep this vector in \tilde{D} .

Thus, only concerned with finite decision sets for obtaining sharp regret bounds



Proposed Solution

Input:
$$\gamma$$
, η

$$\forall x \in D, \ p_1(x) \leftarrow \frac{1}{|D|}$$
for $t \leftarrow 1$ to T do
$$\forall x \in D, \ \hat{p}_t(x) = (1 - \gamma)p_t(x) + \frac{\gamma}{n}\mathbf{1}\{x \in \text{ spanner }\}$$
Sample x_t from \hat{p}_t
Observe the loss $I_t = L_t^T x_t$
Compute the covariance for \hat{p}_t , $C_t := E[xx^T]$
Estimate the loss vector as $\hat{L}_t := I_t C_t^{-1} x_t$

$$\forall x \in D, \ p_{t+1}(x) \propto p_t(x) e^{-\eta \hat{L}_t^T x}$$
end for

- Inspired from the multiplicative weight approach of *Auer et.* al.
- A probability distribution, p_t is defined over the decision space D at any stage t
- This is mixed with a uniform distribution on the spanner set to get \hat{p}_t
- Action x_t for stage t is chosen from this distribution
- $p_t(x)$ is modified based on the *estimated* loss
- Obtain a bound of $O(n \log n \sqrt{nT})$

Theorem (Main Result)

Choose $\gamma = \frac{n^{3/2}}{\sqrt{T}}$ and $\eta = \frac{1}{\sqrt{nT}}$. For any sequence of loss vectors L_1, \ldots, L_T , the algorithm satisfies :

$$E[R] \le \log |D| \sqrt{nT} + 2n^{3/2} \sqrt{T}$$

Since, $|D| \leq (nT)^{\frac{n}{2}}$, we have the bound.



Proof Roadmap for Bound on Regret

- ullet Observe that $\hat{\mathcal{L}}_t$ is a meaningful estimate i.e. $E[\hat{\mathcal{L}}_t] = \mathcal{L}_t$
- The estimated loss vectors are also bounded

$$|\hat{L}_t^T x| \le \frac{n^2}{\gamma}, \, \forall \, x \in D$$

$$\sum_{t} \sum_{x} p_{t}(x) \left(\hat{L}_{t}^{T} x \right) \leq \sum_{t} \hat{L}_{t}^{T} x^{*} + \frac{\log |D|}{\eta} + \frac{\phi_{M}(\eta)}{\eta} \sum_{t} \sum_{x} p_{t}(x) \left(\hat{L}_{t}^{T} x \right)^{2}$$

- Here, $\phi_M(\eta):=\frac{e^{M\eta}-1-M\eta}{M^2}$ and M is the upper bound on $|\hat{L}_t^Tx|$ i.e. $M=\frac{n^2}{\gamma}$
- Some technical lemmas

$$E[(\hat{L}_t^T x)^2] \le x^T C_t^{-1} x$$

$$\sum_{x} \hat{p}_t(x) x^T C_t^{-1} x = n$$

- Use those to give a bound for $\sum_{t,x} \hat{p}_t(x) \left(\hat{L}_t(x)^T x_t\right)$
- The expectation of above is same as $E[\sum_t L_t^T x_t]$

Lower Bound for the Problem $=\Omega\left(n\sqrt{T}\right)$

