## Incremental Data Flow analysis using PRISM

Rashmi Rekha Mech (*Project Guide: Prof. Uday Khedker*)



Department of Computer Science and Engineering, Indian Institute of Technology, Bombay

June 2015

#### Outline of the talk

- Incremental Data Flow Analysis
  - Bit-vector Frameworks
  - General Frameworks
- Method to Reduce the Size of Affected Region
- Overview of PRISM
- Incremental Solver for PRISM
  - Architecture
  - Testing
- Conclusion

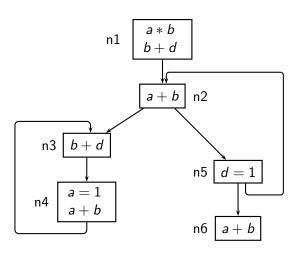
## Part I

Incremental Data Flow Analysis

## Why Incremental Analysis?

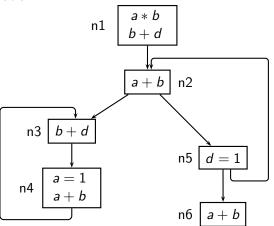
When program undergoes changes:

- Some or all computed data flow information becomes invalid
- Re-computation is required

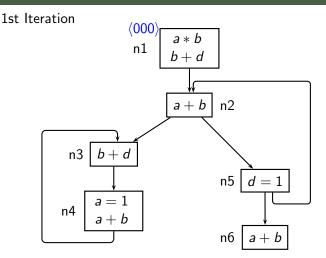


Bit Vector 
$$a * b \mid b + d \mid a + b$$

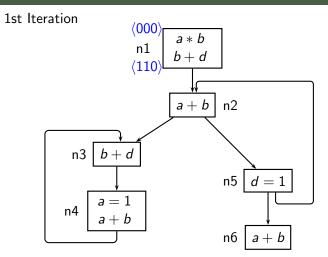
#### 1st Iteration



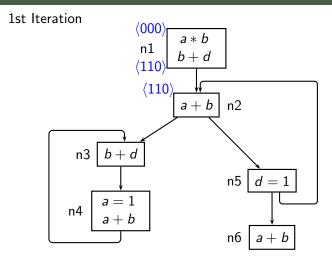
Bit Vector 
$$a * b \mid b + d \mid a + b$$



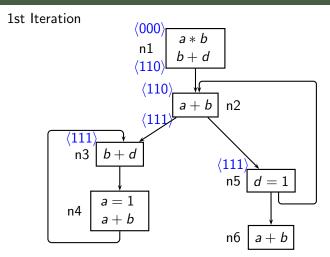
Bit Vector 
$$a * b \mid b + d \mid a + b$$



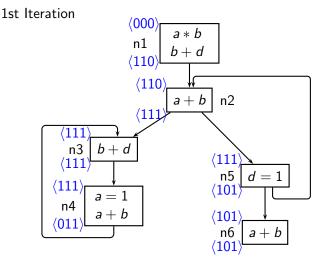
Bit Vector 
$$a*b b+d a+b$$



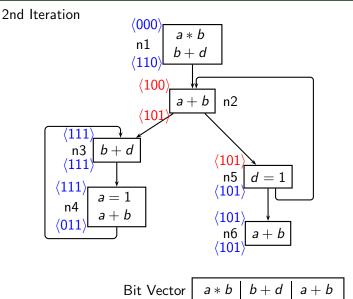
Bit Vector 
$$a*b b+d a+b$$

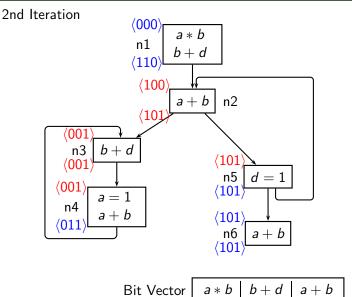


Bit Vector 
$$a*b \mid b+d \mid a+b$$



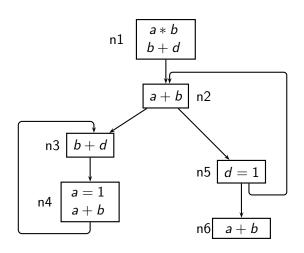
Bit Vector 
$$a*b \mid b+d \mid a+b$$



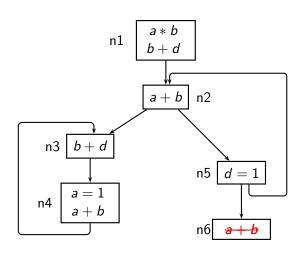


Bit vector  $\begin{bmatrix} a*b & b+a & a+b \end{bmatrix}$ 

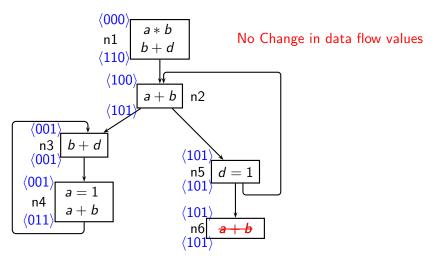
It requires 3 iterations to converge



Bit Vector 
$$a*b b+d a+b$$



Bit Vector 
$$a*b b+d a+b$$



Bit Vector a\*b b+d a+b

- May unnecessarily analyze unaffected program behaviours which leads to redundant computation of old values which is very inefficient.
- Need an incremental analysis:
  - modifies only affected data flow information
  - more cost effective than exhaustive analysis

#### Part II

Incremental Analysis for Bit-vector Frameworks

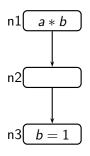
## Possible changes

- Due to program change, the following changes are possible<sup>1</sup>:
  - Change in flow functions
  - Change in control flow graph
  - Change in lattice

#### Flow Functions in Bit-vector Frameworks

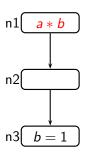
- Possible flow functions:
  - Raise : Result is always top
  - Lower : Result is always bottom
  - Propagate : Propagates the value from one program point to another

#### **Available Expression Analysis**





#### **Available Expression Analysis**



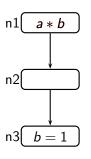
#### **Raise Function**

$$\begin{aligned} &\mathsf{Gen}_1 = 1 \\ &\mathsf{Kill}_1 = 0 \\ &\mathsf{IN}_1 = 0 \\ &\mathsf{OUT}_1 = &\mathsf{Gen}_1 \cup \left(\mathsf{IN}_1\text{-}\mathsf{Kill}_1\right) = 1 \end{aligned}$$

## Lattice



#### **Available Expression Analysis**



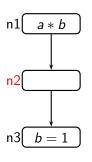
#### Raise Function

$$\begin{aligned} &\mathsf{Gen}_1 = 1 \\ &\mathsf{Kill}_1 = 0 \\ &\mathsf{IN}_1 = 0 \\ &\mathsf{OUT}_1 = &\mathsf{Gen}_1 \cup \left(\mathsf{IN}_1\text{-}\mathsf{Kill}_1\right) = 1 \end{aligned}$$

#### Result is always top



#### **Available Expression Analysis**

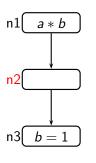


#### **Propagate Function**

$$\begin{split} \mathsf{Gen}_2 &= 0 \\ \mathsf{Kill}_2 &= 0 \\ \mathsf{IN}_2 &= 1 \\ \mathsf{OUT}_2 &= \mathsf{Gen}_2 \cup \left( \mathsf{IN}_2\text{-}\mathsf{Kill}_2 \right) = \mathsf{IN}_2 = 1 \end{split}$$

# **Lattice** (⊤) 1 |

#### **Available Expression Analysis**



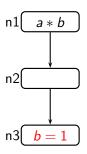
## **Propagate Function**

$$\begin{aligned} &\mathsf{Gen}_2 = 0 \\ &\mathsf{Kill}_2 = 0 \\ &\mathsf{IN}_2 = 1 \\ &\mathsf{OUT}_2 = &\mathsf{Gen}_2 \cup \left(\mathsf{IN}_2\text{-}\mathsf{Kill}_2\right) = \mathsf{IN}_2 = 1 \end{aligned}$$

Propagates the value at IN to OUT

Lattice

#### **Available Expression Analysis**



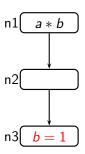
#### **Lower Function**

$$\begin{aligned} &\mathsf{Gen}_3 = 0 \\ &\mathsf{Kill}_3 = 1 \\ &\mathsf{IN}_3 = 1 \\ &\mathsf{OUT}_3 = &\mathsf{Gen}_3 \cup \left(\mathsf{IN}_3\text{-}\mathsf{Kill}_3\right) = 0 \end{aligned}$$

## Lattice (⊤) 1



#### **Available Expression Analysis**



#### **Lower Function**

$$\begin{aligned} &\mathsf{Gen}_3 = 0 \\ &\mathsf{Kill}_3 = 1 \\ &\mathsf{IN}_3 = 1 \\ &\mathsf{OUT}_3 = &\mathsf{Gen}_3 \cup \left(\mathsf{IN}_3 \text{-}\mathsf{Kill}_3\right) = 0 \end{aligned}$$

Result is always bottom

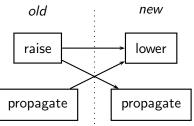


## Possible Changes in Data Flow Values

- As a consequence of some change in a node, some data flow values may:
  - change from top to bottom
  - change from bottom to top
  - remain same

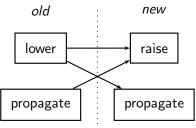
## Top to Bottom Change

Possible changes in flow functions.



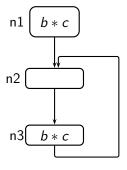
## Bottom to Top Change

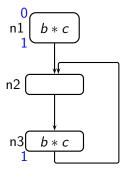
Possible changes in flow functions.

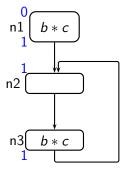


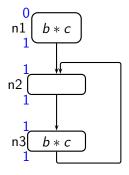
## Handling Top to Bottom Change

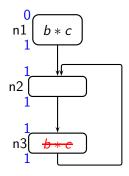
- Bottom value is a final value even during analysis
- Whenever there is top to bottom change, the changes can be propagated directly to its neighbouring nodes



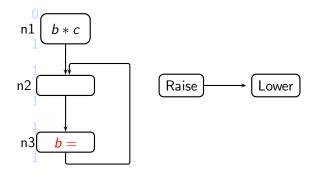




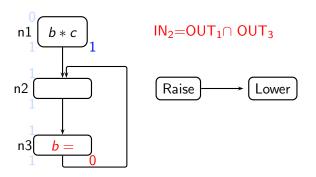




### Top to Bottom change

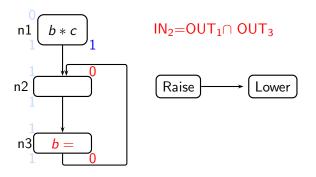


#### Top to Bottom change



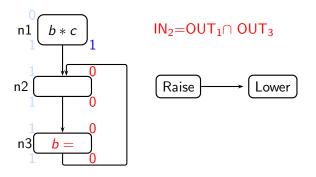
Directly Propagate the change to its neighbour

#### Top to Bottom change



Directly Propagate the change to its neighbour

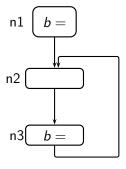
#### Top to Bottom change

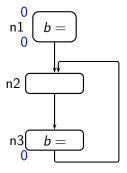


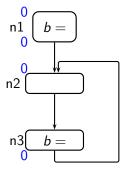
Directly Propagate the change to its neighbour

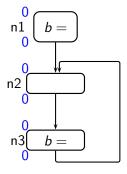
## Handling Bottom to Top Change

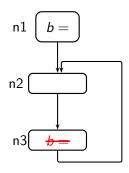
- Top value is an intermediate value until data flow analysis is completed
- Whenever there is bottom to top change, we cannot directly propagate the changes to its neighbouring nodes
- Need some more processing



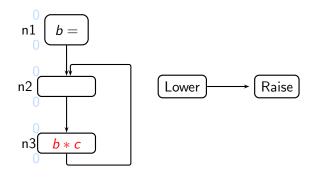




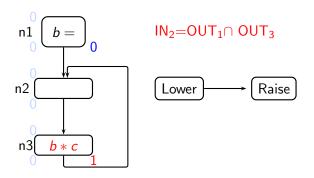




### Bottom to Top change

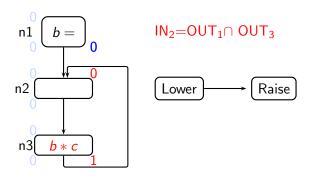


#### Bottom to Top change



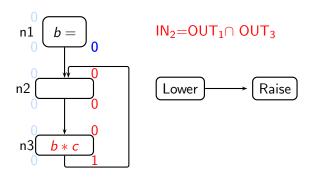
Cannot propagate the change to its neighbouring nodes

#### Bottom to Top change



Cannot propagate the change to its neighbouring nodes

### Bottom to Top change



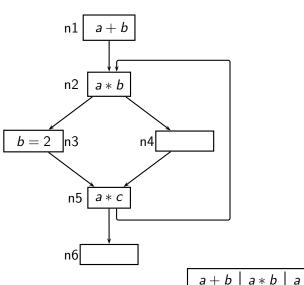
Cannot propagate the change to its neighbouring nodes

Need some more processing

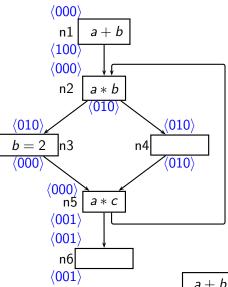
• Steps to incorporate bottom to top change:

- Steps to incorporate bottom to top change:
  - Identify data flow values which may become top

- Steps to incorporate bottom to top change:
  - Identify data flow values which may become top
  - Find out the data flow values which must remain bottom due to the effect of some other property



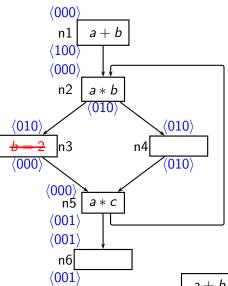
a\*b



## Initial Available Expression Analysis

	a + b		a*b		a * c	
Node	In	Out	In	Out	In	Out
1.	0	1	0	0	0	0
2.	0	0	0	1	0	0
3.	0	0	1	0	0	0
4.	0	0	1	1	0	0
5.	0	0	0	0	0	1
6.	0	0	0	0	1	1

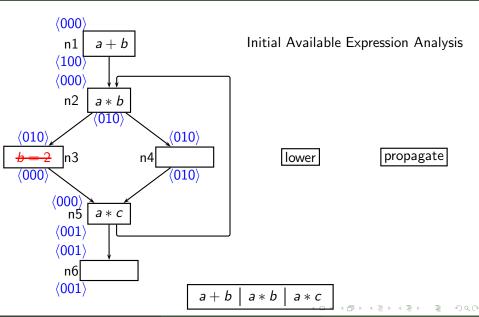
 $a+b \mid a*b \mid a*c$ 

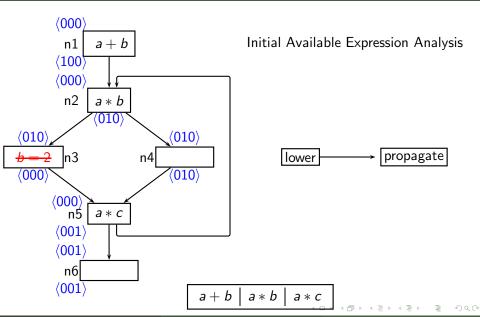


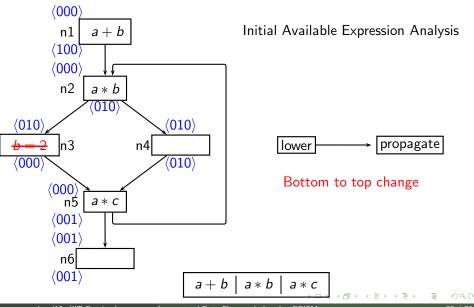
## Initial Available Expression Analysis

	a + b		a*b		a * c	
Node	In	Out	In	Out	In	Out
1.	0	1	0	0	0	0
2.	0	0	0	1	0	0
3.	0	0	1	0	0	0
4.	0	0	1	1	0	0
5.	0	0	0	0	0	1
6.	0	0	0	0	1	1

 $a+b \mid a*b \mid a*c$ 

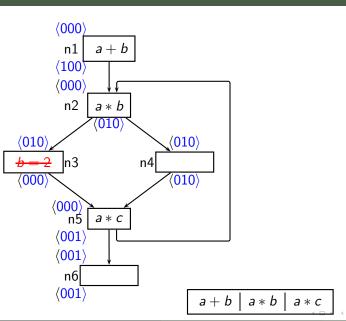


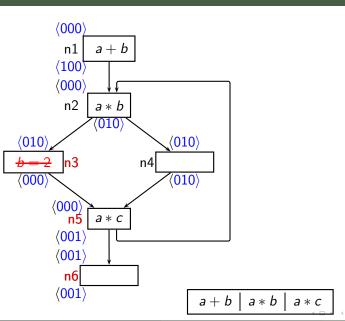


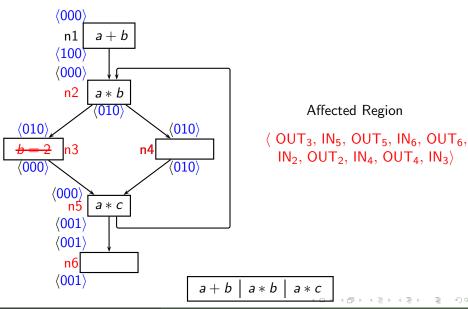


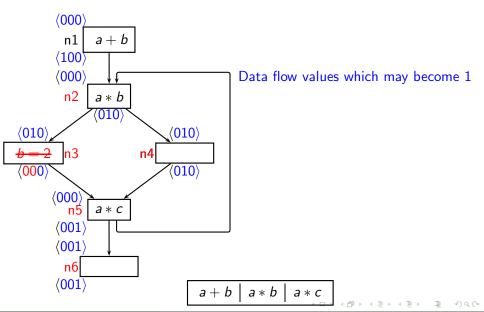
 To identify data flow values which were 0 and may become 1 due to this change

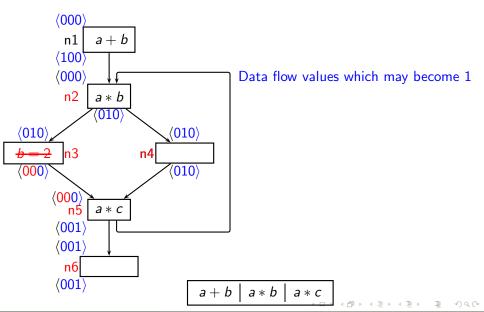
- To identify data flow values which were 0 and may become 1 due to this change
  - Affected region

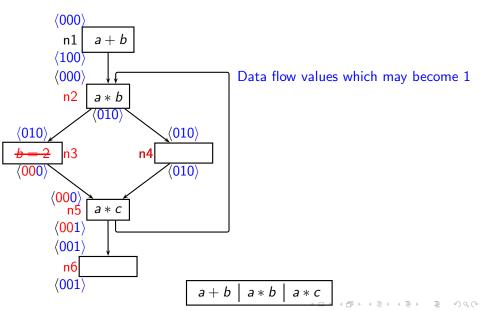


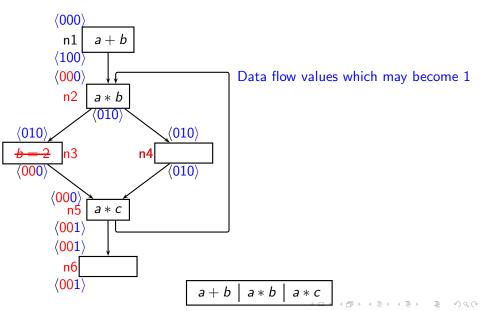


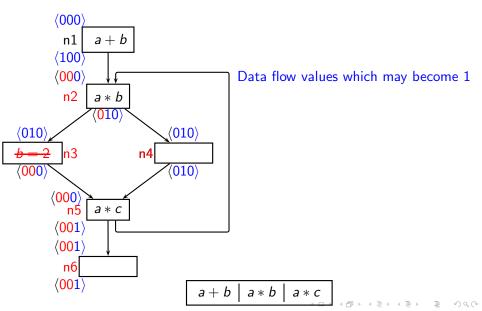


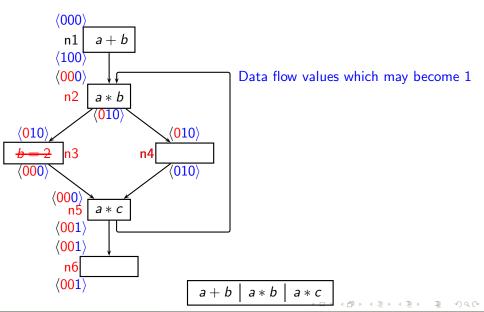


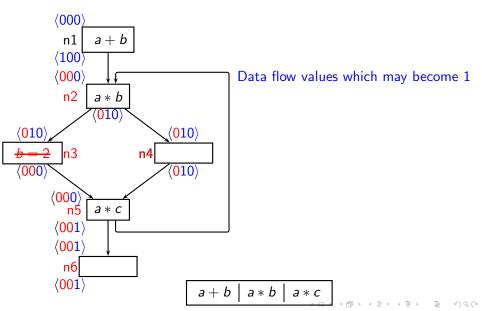


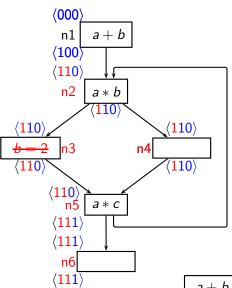












#### Data flow values which may become 1

	a + b		a*b		a * c	
Node	In	Out	In	Out	In	Out
1.						
2.	1	1	1			
3.	1	1		1		
4.	1	1				
5.	1	1	1	1		
6.	1	1	1	1		

a \* b

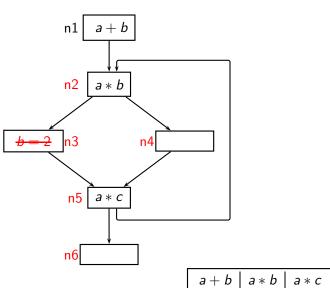
a \* c

 To identify data flow values which must remain bottom due to the effect of some other properties

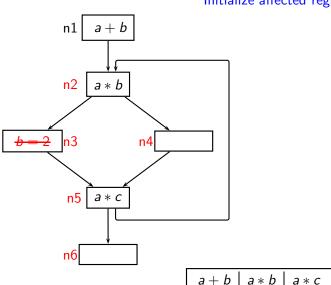
- To identify data flow values which must remain bottom due to the effect of some other properties
  - Initialize affected region to top.

- To identify data flow values which must remain bottom due to the effect of some other properties
  - Initialize affected region to top.
  - Identify boundary nodes.

- To identify data flow values which must remain bottom due to the effect of some other properties
  - Initialize affected region to top.
  - Identify boundary nodes.
  - Compute values at boundary nodes and propagate them.

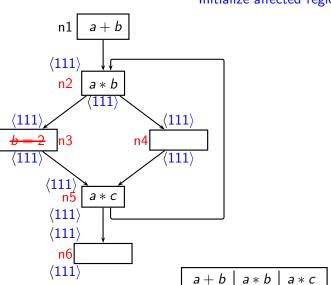


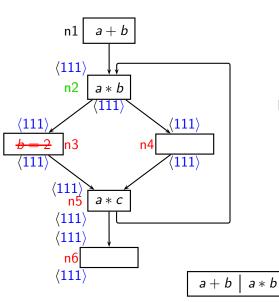
#### Initialize affected region to top



a \* b

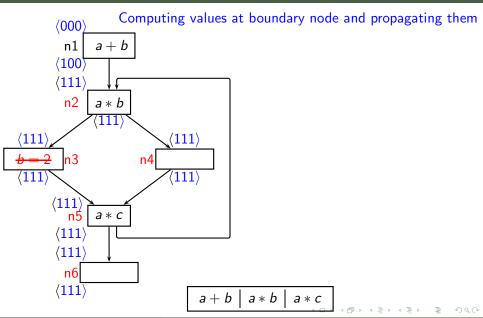
#### Initialize affected region to top

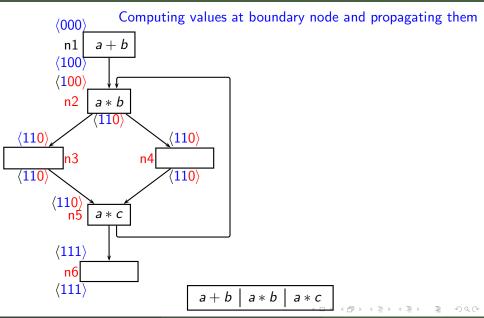


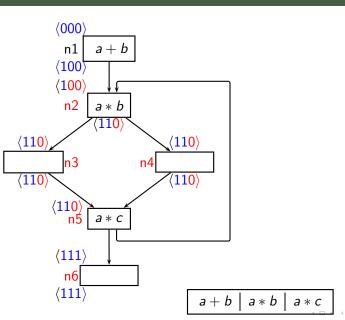


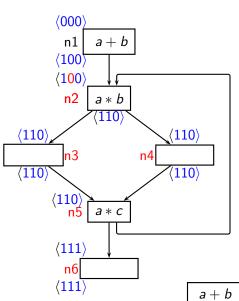
Node 2 is Boundary node

a \* c







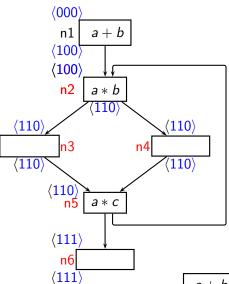


#### Values which must remain 0

	a+b		a * b		a * c	
Node	In	Out	In	Out	In	Out
1.						
2.			0			
3.						
4.						
5.						
6.						

a \* b

a \* c



#### Final values

	a + b		a * b		a * c	
Node	In	Out	In	Out	In	Out
1.	0	1	0	0	0	0
2.	1	1	0	1	0	0
3.	1	1	1	1	0	0
4.	1	1	1	1	0	0
5.	1	1	1	1	0	1
6.	1	1	1	1	1	1

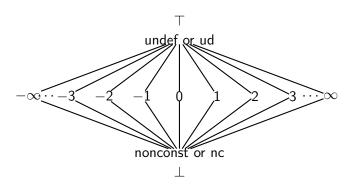
 $a+b \mid a*b \mid a*c$ 

### Part III

Incremental Analysis for General Frameworks

### Incremental Analysis for General Frameworks

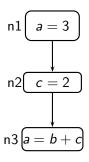
- Consider constant propagation analysis
- Component Lattice for Constant Propagation:



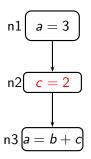
#### Flow Functions

- Possible flow functions
  - Top : Similar to raise function
  - Bottom : Similar to lower function
  - Constant : Always produce a constant value
  - Side level : Result depends on the operands of the expression

### Constant Functions

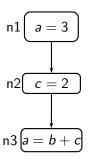


### Constant Functions

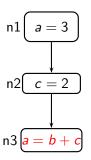


Produce constant value

### Side Level Functions

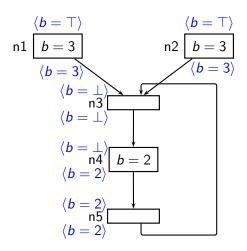


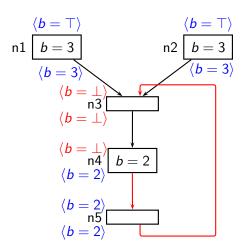
### Side Level Functions

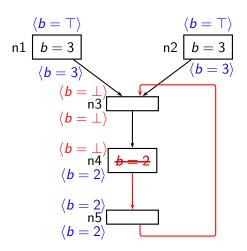


Result depends on the operands

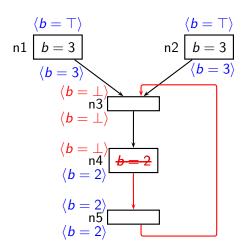
- Unlike bit-vector frameworks, when there is a change to bottom:
  - we cannot propagate the change to its neighbouring nodes







#### Change to bottom



We cannot propagate the change

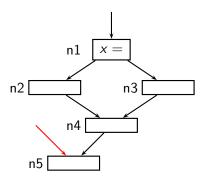
- Unlike bit-vector frameworks, we may need to create an affected region even if there is a change to bottom.
- Solution is to create affected region for all kind of changes.

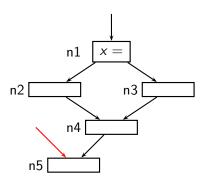
### Part IV

- Based on the observation that some boundary nodes can be characterized by the concept of **Dominance Frontier**.
- Eliminate some boundary nodes from being included in the affected region.

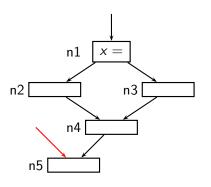
- Let n and m be nodes in CFG. The node n is said to dominate m  $(n \ge m)$ , if every path from **Start** to m passes through n.
- If  $n \neq m$ , then n strictly dominates m, denoted as n > m
- Dominance Frontier:

$$df(n) = \{ m \mid \exists p \in pred(m), (n \ge p \text{ and } n \not> m) \}$$
 (1)





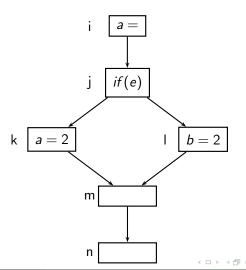
n1 dominates n4



n5 is a dominance frontier of n1

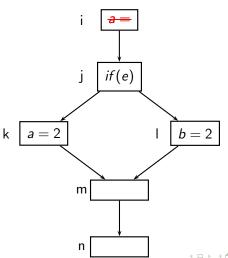
• All Dominance frontier nodes are boundary nodes (but not vice versa).

• All Dominance frontier nodes are boundary nodes (but not vice versa).



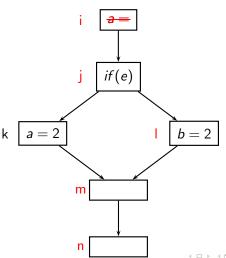
• All Dominance frontier nodes are boundary nodes (but not vice versa).

Affected region:  $\langle i, j, l, m, n \rangle$ 



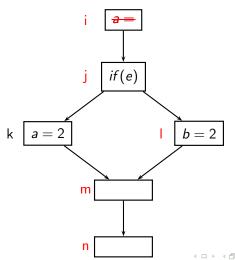
All Dominance frontier nodes are boundary nodes (but not vice versa).

Affected region:  $\langle i, j, l, m, n \rangle$ 

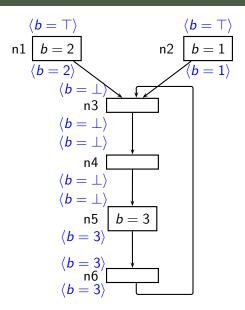


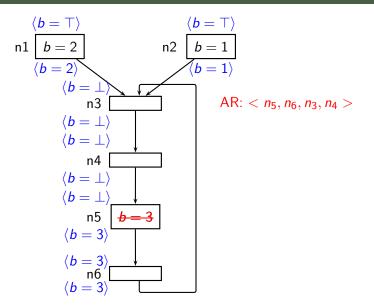
• All Dominance frontier nodes are boundary nodes (but not vice versa).

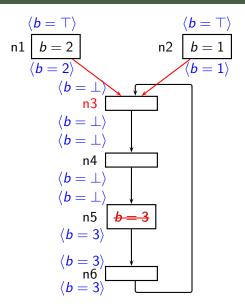
m is a boundary node and is dominated by i

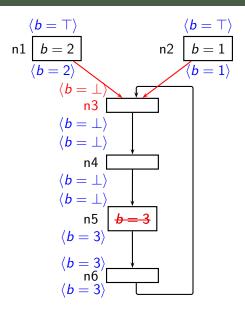


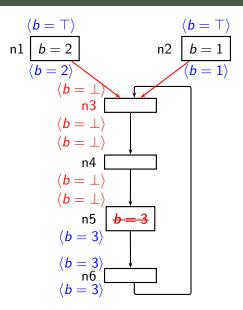
 Possible removal candidates must be dominance frontier of changed node.

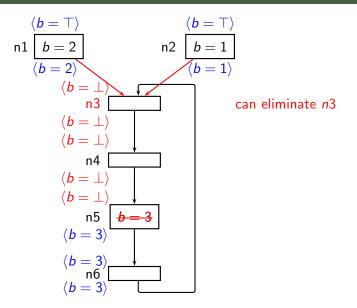












Also applicable for bit-vector frameworks.

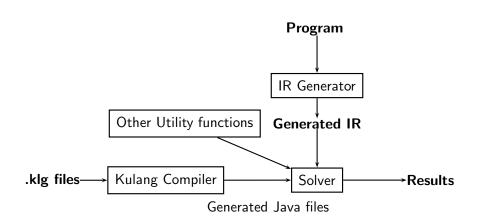
### Part V

# Overview of PRISM

#### **PRISM**

 PRISM is a program analyzer generator developed by TATA Research Development and Design Center (TRDDC)

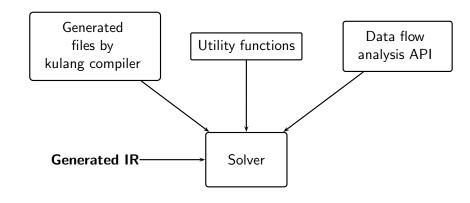
#### Old Architecture of PRISM



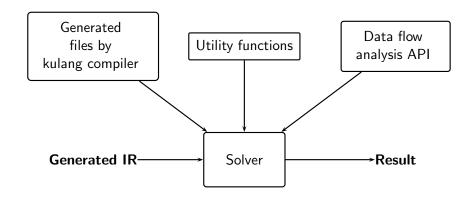
## Architecture of Analyzer Generator

Solver

## Architecture of Analyzer Generator



### Architecture of Analyzer Generator



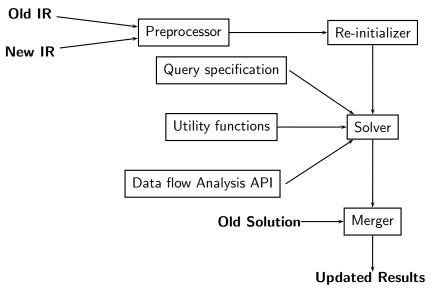
#### Part VI

Incremental Solver for PRISM

#### Architecture of Incremental Solver for PRISM

- Architecture of incremental solver for PRISM is divided into following parts:
  - Preprocessing: reads two IRs and find the difference between them.
  - Data Flow Computation:
    - Re-initialization: constructs affected region.
    - $\bullet\,$  Re-computation: identify boundary nodes and compute the information.
  - Update: merge the information.

#### Architecture of Incremental Solver for PRISM



### Assumptions

- Pointer information will remain same.
- No change in the context information.
- Declaration of variable hasn't change.
- The result of old solver is stored in non-standard format. So the following assumptions are made:
  - No structural change in the graph.
  - A name can refer to a single variable in a program at any given program point.
  - Past information is stored flow sensitively.

#### Limitations

- Following are current limitations:
  - Code for affected region has to be written manually.
  - Result is stored in a non-standard format by the Solver.
  - Non inclusion of global and local declarations.
- These can be overcome.

# Part VII

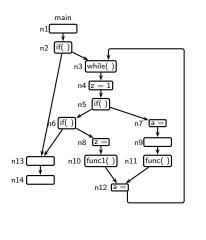
Testing

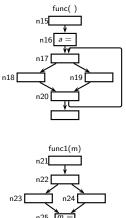
### **Testing**

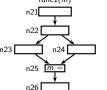
- In the absence of serialization of IR, it was not possible to test the code in real world applications.
- Artificially added the changes to check the performance of the incremental solver.

### Test Case 1 : a is a global variable

#### n7 is a changed node

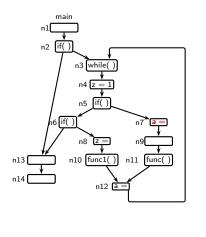


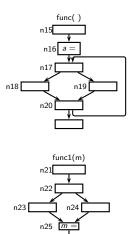




### Test Case 1 : a is a global variable

#### n7 is a changed node

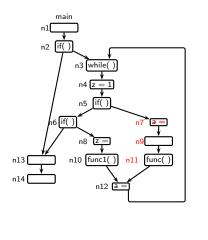


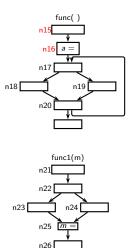


n26

### Test Case 1 : a is a global variable

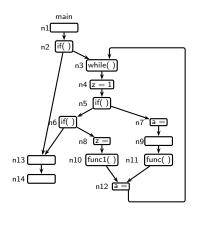
#### n7 is a changed node

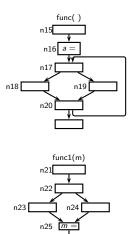




#### Test Case 2 : a is a local variable

#### n7 is a changed node

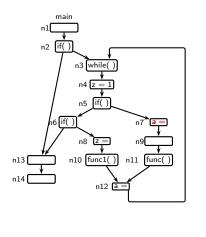


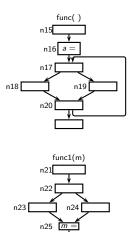


n26

#### Test Case 2 : a is a local variable

#### n7 is a changed node

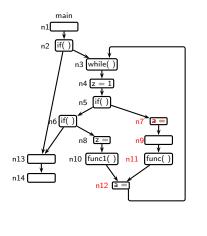


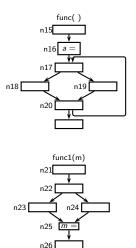


n26

#### Test Case 2 : a is a local variable

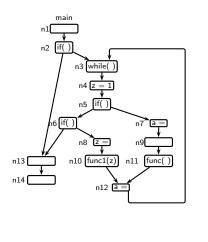
#### n7 is a changed node

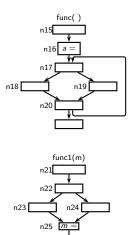




# Test Case 3: passed as a parameter

#### n8 is a changed node

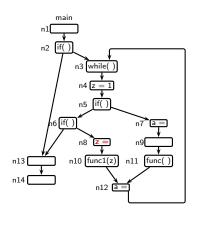


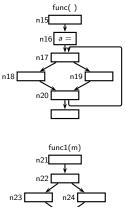


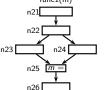
n26

# Test Case 3: passed as a parameter

#### n8 is a changed node

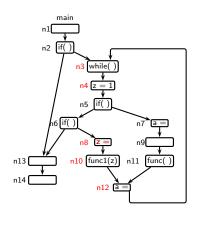


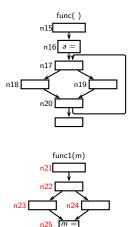




#### Test Case 3: passed as a parameter

#### n8 is a changed node





n26

### Part VIII

Future Work

#### Future Work

- Change the Kulang compiler to generate the code to compute affected region from the flow function.
- Extending the method of reducing the size of affected region for multiple changes.
- Persist the result of the solver.

### Part IX

Thank You!