# Bidirectional Context Sensitive data flow analysis in PRISM

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#### Outline of the talk

- Overview of PRISM data flow analyzer generator
- Background on Value context method.
- Our extensions to PRISM
- Building a scalable data flow solver
- Performance measurements
- Conclusion and future work

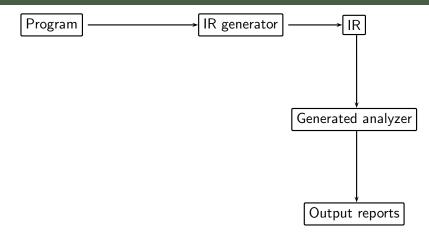
#### Part I

Overview of PRISM data flow analyzer generator

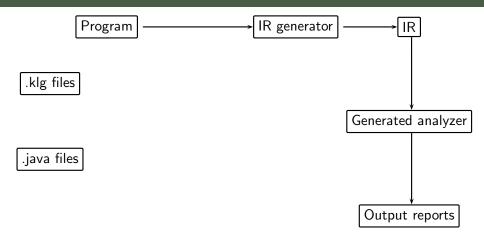
#### **PRISM**

 PRISM is an program analyzer generator developed by TATA Research Development and Design Center (TRDDC)

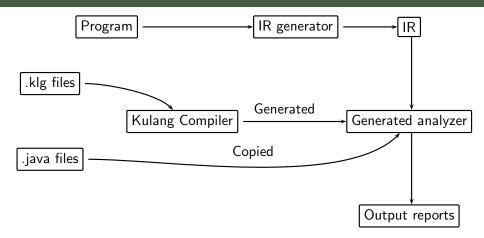
#### Architecture of PRISM



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#### Kulang specifications

```
lattice L :: set NamedEntity;
top : (set NamedEntity){};
A meet B : A+B;
BoundaryValue : (set NamedEntity){};
BackwardNodeflow(n: Call, S: L)
let
  useincall = getNEsFromCall( n )
in
  S + useincall;
```

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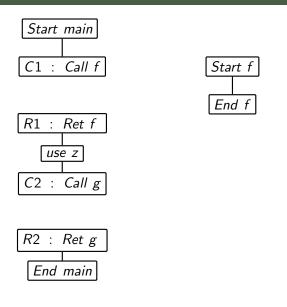
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- The current kulang specifications does not have support for specifying lattices of data flow problems.
- Meet function needs to be explicitly defined in kulang specifications.
   The meet function can be inferred from the lattice of the data flow problem.
- There is no proper way to debug the kulang specifications.

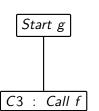
#### Part II

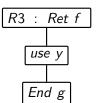
Value Context method of data flow analysis

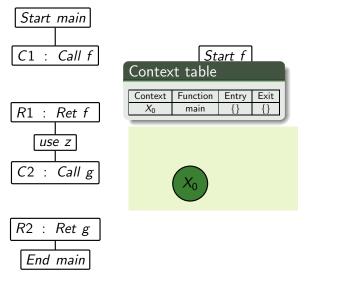
#### Context Sensitive analysis using value contexts

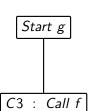
- Based on paper Interprocedural data flow analysis in Soot using value contexts by Padhye, Rohan and Khedker, Uday presented in SOAP 13
- New context created for a unique (function, entry value) combination
- Uses a context transition graph for expressing relation between contexts

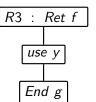


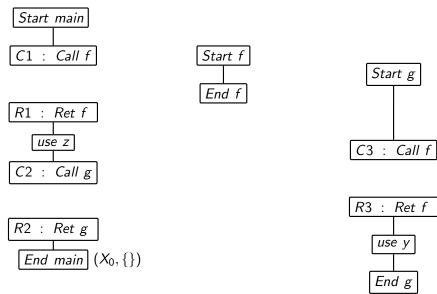




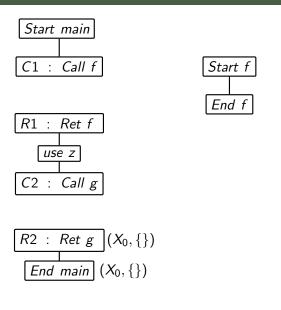


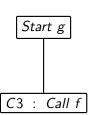


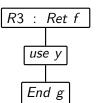


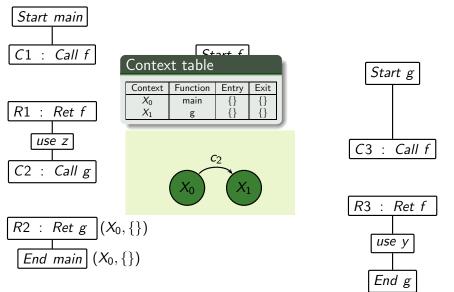


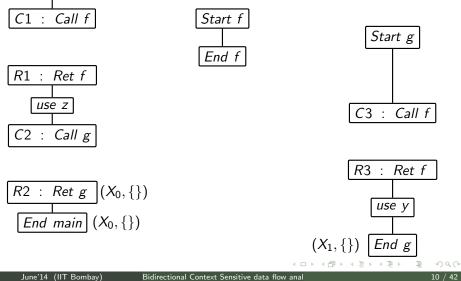
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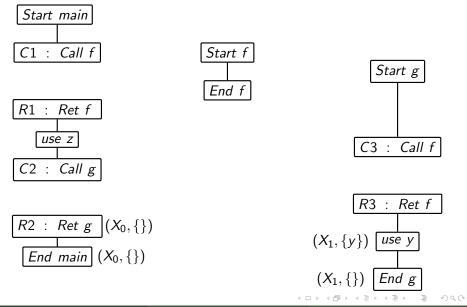


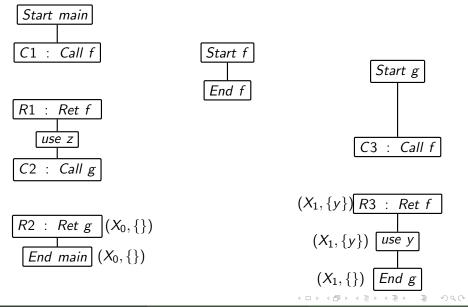


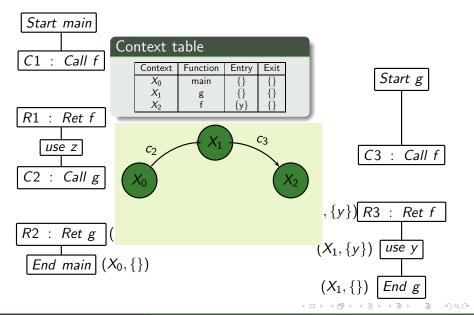


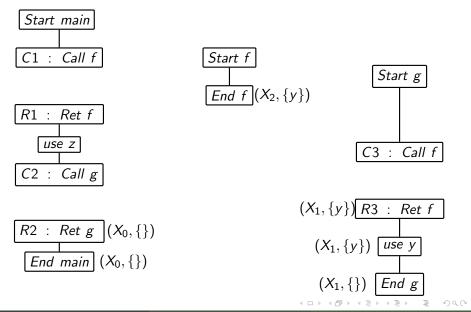


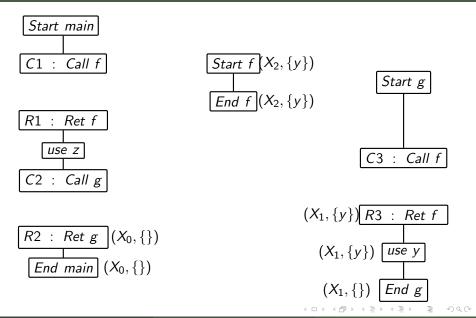
Start main

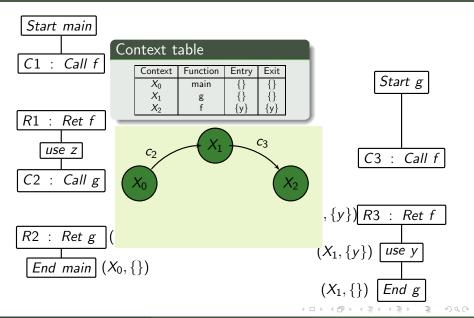


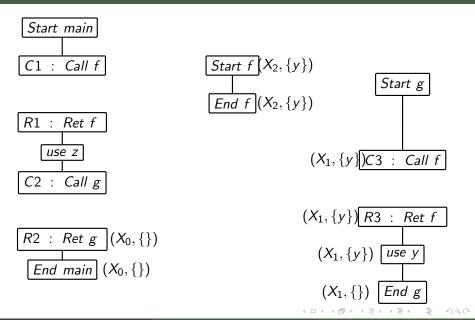


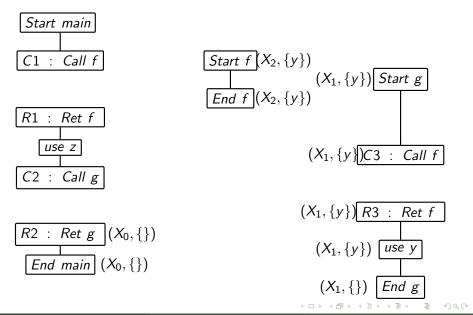


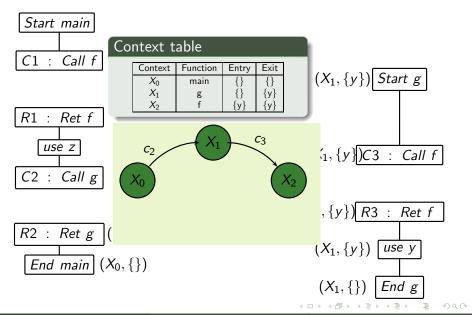


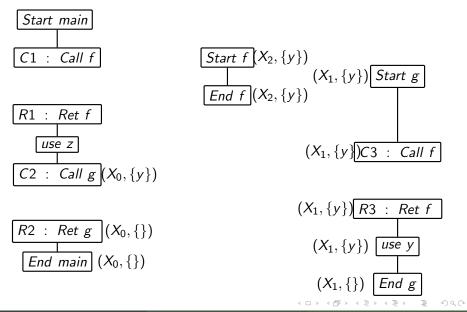


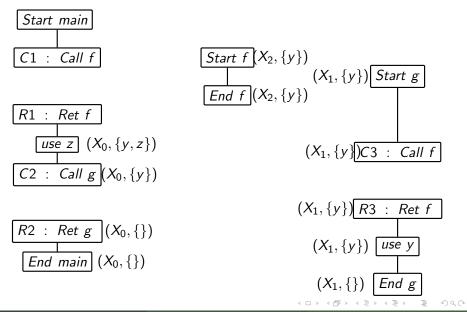


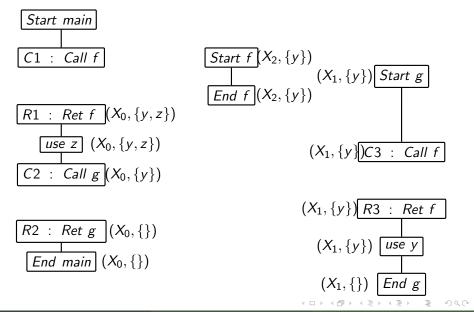


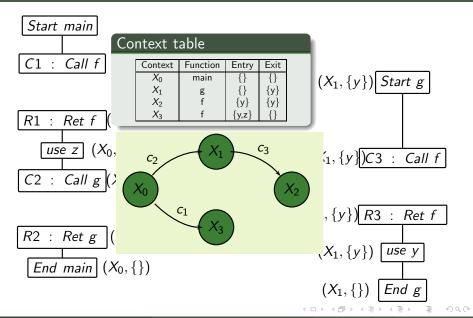


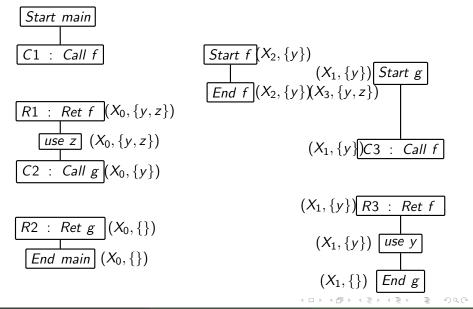


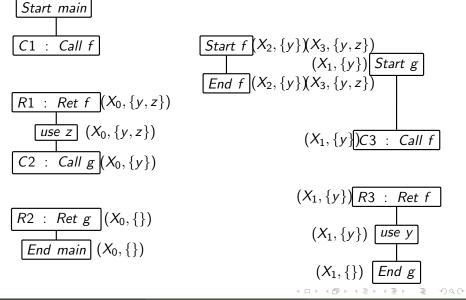


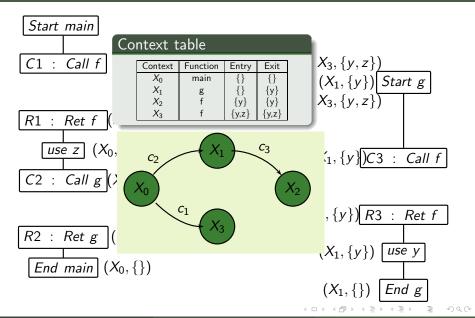


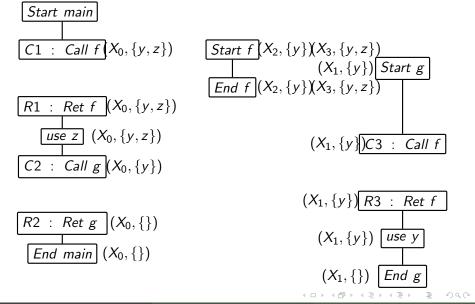










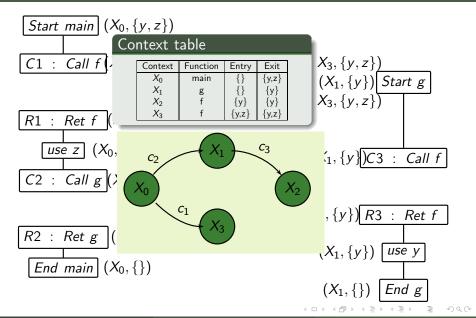


Start main 
$$(X_0, \{y, z\})$$

C1 : Call  $f(X_0, \{y, z\})$ 

Start  $f(X_2, \{y\})(X_3, \{y, z\})$ 
 $(X_1, \{y\})(X_3, \{y, z\})$ 

End  $f(X_2, \{y\})(X_3, \{y, z\})$ 
 $(X_1, \{y\})(X_3, \{y, z\})$ 



## Part III

# Our extensions to PRISM

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 Extended the kulang specification language to accept bidirectional data flow problems

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- Extended the kulang specification language to accept bidirectional data flow problems
- Extended the core solver to efficiently solve a bidirectional data flow problem.

## Extensions to kulang

We extended the specifications so that they can accept

• Forward and backward flow functions and meet functions

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- Forward and backward lattice types
- Forward and backward boundary values and top values

#### Role of the solver

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- The solver is a driver which uses the generated flow and meet functions to solve the data flow problem.
- The solver maintains work list, context information and the intermediate results.

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- The solver makes use of the code generated from bidirectional specifications
- The solver solves the bidirectional problem in the context sensitive manner
- The solver maintains the results of the analysis for different contexts.

## Example of Bidirectional specifications

```
livenesslattice = set NamedEntity pointstolattice = set tuple(NamedEntity,NamedEntity)
```

```
A ForwardMeet B = Meet(A,B)
A BackwardMeet B = A + B
```

 $BackwardFlowFunction (n:Unary,\ S:livenesslattice\ ,\ T:pointstolattice)$  where S is liveness at the OUT and T is pointsto at the IN

BackardFlowFunction (n:Binary, S:liveness lattice, T:pointstolattice)

## Part IV

Building a scalable solver

## Major factors affecting the running time of a solver

- Complexity of input program
- Complexity of flow functions
- Amount of data flow information maintained
- Path followed to achieve the fixed point

## Complexity of input program

- Identify statements where gen will be constant
- Example where gen will not be constant

$$p = **q$$

• Example where gen will be constant

$$p = q$$

## Complexity of flow functions

• Optimizations that can be handled by java compiler

int a = c + b; // This assignment is dead if a is not used further

Optimizations that cannot be handled by java compiler

$$(\mathsf{a} - \mathsf{a} \cap \mathsf{b} \ ) \cup (\mathsf{b} - \mathsf{a} \cap \mathsf{b} \ )$$

code produced by kulang translator :

t1 = a.intersection(b)

t2 = a.diff(t1)

t3 = a.intersection(b)

t4 = b.diff(t3)

t5 = t2.union(t4)

 $a \cup b$  -  $a \cap b$  (Simplified expression for the above expression)

- Separating accessible and non accessible information
- Bypassing global variables
- Techniques specific to data flow analysis

Separating accessible and non accessible information

A variable is accessible inside a function if :

- It is local to the function
- It is global
- It is accessible through a pointer which is accessible inside the function

$$\begin{cases} p->&a \rbrace \\ f() \ //No \ information \ will \ be \ passed \ to \ f \\ \{p,a,b \} \\ \end{cases}$$

```
\{p->a\}
f(p)\{p,a\} will be passed to f
\{p,a,b\}
```

Bypassing global variables

- Let G be set of global variables in the program
- For every function, compute G1 which is set of global variables accessed from that function
- At the function call, transfer G1 in the function and copy G-G1 directly across the function call

```
 \begin{cases} \mathsf{G1} \,\cup\, (\mathsf{G}\,\text{-}\,\,\mathsf{G1}) \rbrace \\ \mathsf{f()} \,\,//\,\,\mathsf{transfer}\,\,\mathsf{G1}\,\,\mathsf{in}\,\,\mathsf{the}\,\,\mathsf{called}\,\,\mathsf{function} \\ \mathsf{G2} \,\cup\, (\mathsf{G}\,\text{-}\,\,\mathsf{G1}) \rbrace \,\,//\,\,\mathsf{G2}\,\,\mathsf{is}\,\,\mathsf{at}\,\,\mathsf{exit}\,\,\mathsf{of}\,\,\mathsf{the}\,\,\mathsf{called}\,\,\mathsf{function} \\ \end{cases}
```

```
int a,b,c,d
use a
use b
access set of f = \{a\}
access set of g = \{a, b\}
```

- Techniques specific to data flow analysis
  - Do not explicitly maintain information of undef pointers

## Do not explicitly maintain information of undef pointers

```
x = \&b

b = 1;

c = 2;

if(c==1)

y = \&c;

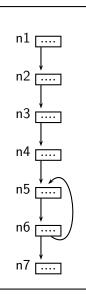
// Insert y- > undef here

z = x
```

## Path followed to achieve the fixed point

- Solve the cfg in postorder in a backward analysis and preorder in a forward analysis
- Solve inner function calls first.

## Path followed to achieve the fixedpoint



A possible processing order for a FIFO work list: n7, n6, n5, n4, n6, n3, n5, n2, n4, n1, n3, n2, n1

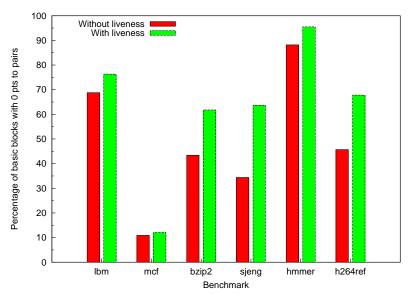
Optimal processing order:

n7, n6, n5, n6, n5, n4, n3, n2, n1

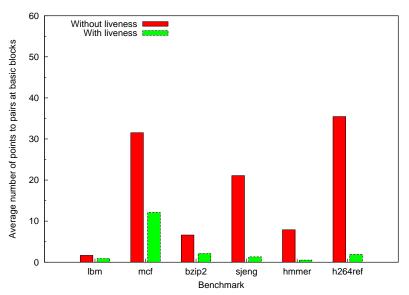
## Part V

# Performance measurements

## Percentage of basic blocks having 0 pointsto pairs



## Average pointsto pairs per basic blocks



# Separating accessible and non accessible information vs non separation

Program	Without sepa- rating accessible and non accessible variables		Separating accessible and non accessible variables	
	Avg DF	Execution	Avg DF	Execution
	values	time	values	time
		(ms)		(ms)
mcf	7.46	488	2.51	312
lbm	10.01	434	0.58	258
bzip2	14.56	6815	1.2	1699
sjeng	-	-	0.62	6050
hmmer	-	-	0.4	3358
h264ref	-	-	1.01	33046

Table: Separating accessible and non accessible information vs non separation

# Bypassing global variables

Program	Bypassing global variables			Not by-
				passing
	Execution	Total	Avg	Execution
	time	global	number	time
		variables	of global	
			variables	
			accessed	
			per	
			context	
mcf	4280	26	5.86	4703
Ibm	1639	4	0.7	1788
bzip2	21784	38	3.6	51445
sjeng	27116	25	1.85	92415
hmmer	27900	232	6.05	31268
h264ref	311021	464	43.95	1023911
cfe	4038702	1449	62.20	-

## Measuring Scalability: Major operations

Operation	Percentage of time	Percentage of
	(<20kloc)	time (>20kloc)
Flow functions	59.35 %	72.11 %
Meet function	4.97 %	3.32 %
CTD add/retrive	12.18%	9.43 %
Worklist	10.12%	7.81 %
add/retrive		
Store/load data	5.24 %	3.27 %
flow information		
Others	8.14 %	4.06 %

Table: Percentage of time required for individual operations

## Measuring Scalability

- The flow functions are a bottleneck as size of the program grows
- The amount of time taken by flow function depends upon the size of set of data flow values processed by the flow function

## Proposed method to remove the bottleneck

- Implement globals bypassing inside a function.
- Identify accessible information more precisely

## Implement globals bypassing inside a function

```
use x
\{x, y, z\}
use y
```

## Identify accessible information more precisely

```
f(int** x)
printf(x)
main()
\{x->y, y->z, z->a\}
Only x is actually used inside f
```

## Part VI

Future work

#### Future work

- The current specifications allow specification of one forward and one backward analysis
- Current specifications do not support specification of lattices of data flow problems. Hence meet function cannot be inferred but explicitly defined.

#### Future work

#### DATAFLOW\_VAR dv1,dv2

## Part VII

Thank You!