

Arduino Coding:

```
#include <Wire.h>

#include <LiquidCrystal_I2C.h> //I2C pins declaration
LiquidCrystal_I2C lcd(0x27, 16, 2);

#include <SoftwareSerial.h>

SoftwareSerial gprsSerial(7, 8); //7-->Tx, 8-->Rx

#include "dht.h"

dht DHT;

#include <DS3231.h>

DS3231 rtc(SDA, SCL);

Time t;

int LDR = A0;    //analog pin for LDR sensor

int IR = 3;      //digital pin for IR sensor

#define DHT11_PIN 2 //digital pin for DHT11 sensor

int smokeA0 = A1;    //analog pin for mq sensor

int trigPin = 9;    // water Ultrasonic

int echoPin = 10;

int Relay1 = 4; //light

int Relay2 = 5; //relay for water pump

int Relay3 = 6; //relay for cooling fan

int Relay4 = 11; //relay for exhaust fan for Humidity control

//int Relay4 = 7; //relay for exhaust fan for Ammonia gas control

int Relay5 = 12; //relay for feeder control

int Relay6 = 13; //relay for Cleanliness DC Moter control

const int OnHour1 = 19; //light time 1

const int OnHour2 = 20;

const int OnHour3 = 4; //light time 2

const int OnHour4 = 5;

void setup() {

    lcd.begin();           //Defining 16 columns and 2 rows of lcd display

    lcd.backlight();       //To Power ON the back light

    lcd.setCursor(0,0);    //Defining positon to write from first row,first column .
```

```
lcd.print(" Smart Poultry ");    //You can write 16 Characters per line .
delay(1000);

lcd.setCursor(0,1);            //Defining position to write from second row,first column .
lcd.print(" SSPM's COE ");
delay(1000);

gprsSerial.begin(19200);
Serial.begin(19200);
Serial.println("Config SIM900...");
delay(2000);

gprsSerial.flush();
Serial.flush();

gprsSerial.println("AT+CGATT?");
delay(100);
toSerial();

gprsSerial.println("AT+SAPBR=3,1,\"CONTYPE\",\"GPRS\"");
delay(2000);
toSerial();

lcd.clear();
lcd.setCursor(0,0);
lcd.print("Connect Network");
delay(1000);
lcd.setCursor(0,1);
lcd.print("Connect GPRS");
delay(1000);

gprsSerial.println("AT+SAPBR=3,1,\"APN\",\"bsnlNet\"");
delay(2000);
toSerial();

gprsSerial.println("AT+SAPBR=1,1");
delay(2000);

gprsSerial.println("AT+SAPBR=2,1");
delay(2000);
toSerial();
```

```
rtc.begin();

pinMode(Relay1, OUTPUT);
digitalWrite(Relay1, LOW);
pinMode(Relay2, OUTPUT);
pinMode(trigPin, OUTPUT);
pinMode(echoPin, INPUT);
pinMode(3,INPUT); //DHT11 input
pinMode(Relay3, OUTPUT);
pinMode(Relay4, OUTPUT);
pinMode(Relay5, OUTPUT);
pinMode(Relay6, OUTPUT);
pinMode(smokeA0, INPUT);
pinMode(LDR, INPUT);
pinMode(IR, INPUT);
}

void loop() {
    t = rtc.getTime();
    lcd.clear();//Clean the screen
    lcd.setCursor(0,0);
    lcd.print("Time:");
    lcd.setCursor(6,0); //clm,row
    lcd.print(t.hour);
    lcd.setCursor(8,0);
    lcd.print(":");
    lcd.setCursor(9,0);
    lcd.print(t.min);
    lcd.setCursor(11,0);
    lcd.print(":");
    lcd.setCursor(12,0);
    lcd.print(t.sec);
    lcd.setCursor(0,1); //date
    lcd.print("Date:");
```

```
lcd.setCursor(6,1); //clm,row
lcd.print(t.date);
lcd.setCursor(8,1);
lcd.print(":");
lcd.setCursor(9,1);
lcd.print(t.mon);
lcd.setCursor(11,1);
lcd.print(":");
lcd.setCursor(12,1);
lcd.print(t.year);
delay(2000);
lcd.clear();//Clean the screen
lcd.setCursor(0,0);
lcd.print("collecting");
lcd.setCursor(4,1);
lcd.print("Data...");
delay(2000);
/*humadity and temperature & MQ gas sensor*/
int d = DHT.read11(DHT11_PIN); //humadity and temperature
Serial.print("Temperatur=");
Serial.println(DHT.temperature);
Serial.print("Humidity = ");
Serial.println(DHT.humidity);
int dt1=DHT.temperature;
int dt2=DHT.humidity;
String Act1;
    Act1="FanOff";
String Act2;
    Act2="ExhFanOFF";
if(dt1>=41)
{
    digitalWrite(Relay3, HIGH); //cooling fan relay on
    Serial.println("cooling fan on");
```

```

    Act1="FanOn";
}
else
{
    digitalWrite(Relay3, LOW); //cooling fan relay off
    Act1="FanOff";
}
Serial.println(Act1);

int sensorThres = 400; //mq sensor 100
int analogSensor = analogRead(smokeA0);
int dt3=analogSensor-50;
Serial.println(dt3);
if (dt3 > sensorThres || dt2>=75) // if (analogSensor-50 > sensorThres)
{
    digitalWrite(Relay4,HIGH);
    Serial.println("Exhaust fan on"); //exhaust fan relay on
    Act2="ExhFanON";
}
else
{
    digitalWrite(Relay4, LOW); //exhaust fan relay off
    Act2="ExhFanOFF";
}
Serial.println(Act2);

/*Light */
int dt4 = analogRead(LDR);
String Act3;
Serial.println("Luminicity=");
Serial.print(dt4);

if(t.hour==8 || t.hour==9 || t.hour==10 || t.hour==11 || t.hour==12 || t.hour==13 || t.hour==14 || t.hour==15
|| t.hour==16 || t.hour==17 || t.hour==18)

```

```
{  
  if (dt4>=400)  
  {  
    digitalWrite(Relay1, HIGH);  
    Serial.println("LIGHT ON");  
    Act3="LightOn";  
  }  
  else  
  {  
    digitalWrite(Relay1,LOW);  
    Serial.println(" LIGHT OFF");  
    Act3="LightOFF";  
  }  
}  
else  
{  
  if(t.hour == OnHour1 || t.hour == OnHour2 || t.hour == OnHour3 || t.hour == OnHour4)  
  {  
    digitalWrite(Relay1,HIGH);  
    Serial.println(" LIGHT ON");  
    Act3="LightOn";  
    lcd.clear();//Clean the screen  
    lcd.setCursor(0,0);  
    lcd.print(" LIGHT ON");  
    lcd.setCursor(0,1);  
    lcd.print(t.hour);  
    lcd.setCursor(4,1);  
    lcd.print(Act3);  
    delay(60000); //1 min  
  }  
  else  
  {  
    digitalWrite(Relay1,LOW);
```

```
Serial.println(" LIGHT OFF");
    Act3="LightOFF";
}
}

Serial.println(Act3);

/*Water level */
long duration, distance;    //Ultrasonic code
int dt5;
String Act4;

digitalWrite(trigPin,HIGH);
delayMicroseconds(1000);
digitalWrite(trigPin, LOW);
duration=pulseIn(echoPin, HIGH);
distance =(duration/2)/29.1;
Serial.print(distance);
Serial.println("CM");
delay(2000);
if(distance<=5)
{
    digitalWrite(Relay2, LOW);
    Act4="PumpOff";
    Serial.println(Act4);
    dt5=100;
    Serial.println(dt5);
}
if(distance>=6&&distance<=10)
{
    dt5=75;
    Serial.println(dt5);
    Act4="PumpOff";
}
if(distance>10&&distance<=13)
{
```

```

    dt5=60;
    Serial.println(dt5);
    Act4="PumpOff";
}
if(distance>13&&distance<=16)
{
    dt5=45;
    Serial.println(dt5);
    Act4="PumpOff";
}
if(distance>=17)
{
    digitalWrite(Relay2, HIGH);
    dt5=40;
    Serial.println(dt5);
    Serial.println("MOTER ON");
    Act4="PumpOn";
    lcd.clear();//Clean the screen
    lcd.setCursor(0,0);
    lcd.print(" PumpOn");
    lcd.setCursor(0,1);
    lcd.print(dt5);
    lcd.setCursor(4,1);
    lcd.print(Act4);
    delay(75000);          //give delay for fill up the water tank
    digitalWrite(Relay2, LOW);
}
    Serial.println(Act4);
/* Cleanliness System */
String Act5="ProcessOFF";
if(t.hour == 1&& t.min==1 || t.hour == 6&& t.min==1 || t.hour == 7&& t.min==1 || t.hour == 13&&
t.min==1 || t.hour == 19&& t.min==1 )
{

```



```
    digitalWrite(Relay6,HIGH);

    Act5="ProcessON";
    lcd.clear();//Clean the screen
    lcd.setCursor(0,0);
    lcd.print(" Cleaning ");
    lcd.setCursor(2,1);
    lcd.print(Act5);

    delay(120000);

    digitalWrite(Relay6,LOW);
}

else
{
    digitalWrite(Relay5,HIGH);
    // Serial.println(" Cleanliness Moter Off");

    Act5="ProcessOFF";
}

    Serial.println(Act5);
/* IR sensor */

int detect = digitalRead(IR); // read obstacle status and store it into "detect"

    String Act6="FeederEmpty";
    if(detect == LOW){
        Act6="FeederFull";
        digitalWrite(Relay5,LOW);
        Serial.println("Feeder is Full");
    }else{
        Act6="FeederEmpty";
        digitalWrite(Relay5,HIGH);
    }
    lcd.clear();//Clean the screen
    lcd.setCursor(0,0);
    lcd.print(Act6);
    lcd.setCursor(1,1);
    lcd.print(ProcessOff);

    delay(120000);
```

```
Serial.println("Feeder Getting full");
}

gprsSerial.println("AT+HTTPINIT\r");

delay(2000);

toSerial();

String str="AT+HTTTPARA=\"URL\", "
"http://anajiprojects.000webhostapp.com/project/wdata.php?dt1=";

String url = str + dt1+"&Act1="+ Act1+ "&dt2="+ dt2+ "&dt3="+ dt3+ "&Act2="+ Act2+ "&dt4="+
dt4+"&Act3="+ Act3+ "&Act2="+ Act2+ "&dt5="+ dt5+ "&Act4="+ Act4+ "&Act5="+ Act5;

Serial.println(url);

gprsSerial.println(url);

delay(2000);

Serial.println("SEND DATA.....");

lcd.clear();//Clean the screen

lcd.setCursor(0,0);

lcd.print("GPRS sent Data...");

delay(2000);

toSerial();

gprsSerial.println("");

// set http action type 0 = GET, 1 = POST, 2 = HEAD

gprsSerial.println("AT+HTTPACTION=0\r");

delay(6000);

toSerial();

gprsSerial.println("");

gprsSerial.println("AT+HTTPTERM\r");

toSerial();

delay(300);

gprsSerial.println("");

delay(2000);

lcd.clear();//Clean the screen

lcd.setCursor(0,0);

lcd.print("Temperature(C)");

lcd.setCursor(0,1);
```

```
lcd.print(dt1);  
lcd.setCursor(4,1);  
lcd.print(Act1);  
delay(2000);  
lcd.clear();//Clean the screen  
lcd.setCursor(0,0);  
lcd.print("Humidity(%)");  
lcd.setCursor(0,1);  
lcd.print(dt2);  
lcd.setCursor(4,1);  
lcd.print(Act2);  
delay(2000);  
lcd.clear();//Clean the screen  
lcd.setCursor(0,0);  
lcd.print("Gas Level(PPM)");  
lcd.setCursor(0,1);  
lcd.print(dt3);  
lcd.setCursor(4,1);  
lcd.print(Act2);  
delay(2000);  
lcd.clear();//Clean the screen  
lcd.setCursor(0,0);  
lcd.print("water level(%)");  
lcd.setCursor(0,1);  
lcd.print(dt5);  
lcd.setCursor(4,1);  
lcd.print(Act4);  
delay(1000);  
lcd.clear();//Clean the screen  
lcd.setCursor(0,0);  
lcd.print("Feeder is ");  
lcd.setCursor(0,1);  
lcd.print(Act6);
```

```

delay(2000);

lcd.clear();//Clean the screen

lcd.setCursor(0,0);

lcd.print("Light is ");

lcd.setCursor(0,1);

lcd.print(dt4);

lcd.setCursor(4,1);

lcd.print(Act3);

delay(2000);

lcd.clear();//Clean the screen

lcd.setCursor(0,0);

lcd.print("Cleanning ");

lcd.setCursor(0,1);

lcd.print(Act5);

delay(2000);

lcd.clear();

lcd.setCursor(0,0);

lcd.print(" Smart Poultry ");

lcd.setCursor(0,1);

lcd.print("SSPM Dairy Clg");

delay(5000); //1min wait*/

}

void toSerial()

{

  while(gprsSerial.available()!=0)

  {

    Serial.write(gprsSerial.read());

  }

}

```

Fetch Data from Database:

checklogin.php:

```
<?php
function check_login()
{
    if(strlen($_SESSION['login'])==0)
    {
        $host=$_SERVER['HTTP_HOST'];
        $uri = rtrim(dirname($_SERVER['PHP_SELF']), '/\');
        $extra="index.php";
        $_SESSION["login"]="";
        header("Location: http://$host$uri/$extra");
    }
}
?>
```

data1.php:

```
<?php
session_start();
include("checklogin.php");
check_login();
?>
<!DOCTYPE html>
<html lang="en">
<head>
    <meta charset="utf-8">
    <meta http-equiv="X-UA-Compatible" content="IE=edge">
    <meta name="viewport" content="width=device-width, initial-scale=1">
    <meta name="description" content="">
    <meta name="author" content="">
    <title>Project || LIVE status </title>
    <link href="assets/css/bootstrap.min.css" rel="stylesheet">
    <link href="assets/css/heroic-features.css" rel="stylesheet">
```

```
<style>
table {
    font-family: arial, sans-serif;
    border-collapse: collapse;
    width: 100%;
}
th {
    border: 1px solid #dddddd;
    text-align: center;
    padding: 10px;
}
td{
    border: 1px solid #dddddd;
    text-align: center;
    padding: 8px;
}
tr:nth-child(even) {
    background-color: #dddddd;
}
</style>
</head>
<body>
    <nav class="navbar navbar-inverse navbar-fixed-top" role="navigation">
        <div class="container">
            <div class="navbar-header">
                <button type="button" class="navbar-toggle" data-toggle="collapse" data-target="#bs-example-navbar-collapse-1">
                    <span class="sr-only">Toggle navigation</span>
                    <span class="icon-bar"></span>
                    <span class="icon-bar"></span>
                    <span class="icon-bar"></span>
                </button>
                <a class="navbar-brand" href="index1.php">Welcome</a>
```

```

</div>

<div class="collapse navbar-collapse" id="bs-example-navbar-collapse-1">
    <ul class="nav navbar-nav">
        <li>
            <a href="#"><?php echo $_SESSION['login'];?></a>
        </li>
        <li>
            <a href="logout.php">Logout</a>
        </li>
    </ul>
</div>
</div>
</nav>
<div class="container">
    <header class="jumbotron hero-spacer">
        <h3>Live Environment Status of Poultry Farm</h3>
    <?php
include("dbconnection.php");
if (!$con)
{
    die("Connection error: " . $con->connect_error);
}
$result= mysqli_query($con,"SELECT * FROM data ORDER BY Date_Time DESC");

        echo "<table>";
        echo "<tr>";
        echo "<th>Date & Time</th>";
        echo "<th>Temperature</th>";
        echo "<th>Action</th>";
        echo "<th>Humidity</th>";
        echo "<th>Ammonia Gas Level</th>";
        echo "<th>Action</th>";
        echo "<th>Light</th>";
        echo "<th>Action</th>";

```

```

        echo "<th>Water Level</th>";

        echo "<th>Action</th>";

        echo "<th>Cleaning</th>";

        echo "</tr>";

while ($row = mysqli_fetch_array($result))
{
    echo "<tr>";

    echo "<td>".$row['Date_Time']. "</td>";

    echo "<td>".$row['dt1']. "</td>";

    echo "<td>".$row['act1']. "</td>";

    echo "<td>".$row['dt2']. "</td>";

    echo "<td>".$row['dt3']. "</td>";

    echo "<td>".$row['act2']. "</td>";

    echo "<td>".$row['dt4']. "</td>";

    echo "<td>".$row['act3']. "</td>";

    echo "<td>".$row['dt5']. "</td>";

    echo "<td>".$row['act4']. "</td>";

    echo "<td>".$row['act5']. "</td>";

    echo "</tr>";

}

echo "</table>";

?>

    </header>

    </div>

</body>

<script src="assets/js/jquery.js"></script>

    <script src="assets/js/bootstrap.min.js"></script>

</html>

```

```

*****

```


Upload data to database:

```
<?php

define('DB_SERVER','localhost');

define('DB_USER','id8498692_project');

define('DB_PASS','project@123');

define('DB_NAME','id8498692_project');

$con = mysqli_connect(DB_SERVER,DB_USER,DB_PASS,DB_NAME);

if (mysqli_connect_errno($con))

{

    echo "Failed to connect to MySQL: " . mysqli_connect_error();

}

date_default_timezone_set('Asia/Kolkata');

$date = date('d/m/Y h:i A');

$sql = "INSERT INTO data (Date_Time, dt1, act1, dt2, dt3, act2, dt4, act3, dt5, act4, act5) VALUES
('$date','" . $_GET['dt1'] . "','" . $_GET['Act1'] . "','" . $_GET['dt2'] . "','" . $_GET['dt3'] . "','" . $_GET['Act2'] . "','" . $_GET['dt4'] . "','" . $_GET['Act3'] . "','" . $_GET['dt5'] . "','" . $_GET['Act4'] . "','" . $_GET['Act5'] . "')"; // Execute SQL
statement

    if (!mysqli_query($con,$sql))

    {

        die('Error: ' . mysqli_error($con));

    }

    mysqli_close($con);

?>
```
