

$$Y(j\omega) = \mathcal{F}\{y(t)\} = \mathcal{F}\{x(t) * h(t)\} = \quad -r$$

$$\mathcal{F}\{x(t)\} \cdot \mathcal{F}\{h(t)\} = X(j\omega) \cdot H(j\omega)$$

$$G(j\omega) = \mathcal{F}\{g(t)\} = \mathcal{F}\{x(r t) * h(r t)\} =$$

$$\mathcal{F}\{x(r t)\} \cdot \mathcal{F}\{h(r t)\} = \frac{X\left(\frac{j\omega}{r}\right)}{r} \cdot \frac{H\left(\frac{j\omega}{r}\right)}{r}$$

$$G(j\omega) = \frac{Y\left(\frac{j\omega}{r}\right)}{r} \longleftrightarrow g(t) = \frac{y(r t)}{r}$$

$$A = \frac{1}{r} \quad B = r$$

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$$e^{-r|t|} \sin(rt) = e^{-rt} \sin(rt) u(t) + e^{rt} \sin(rt) u(-t) =$$

$$u_1(t) + u_r(t) = u_1(t) - u_1(-t)$$

$$X_1(j\omega) = \mathcal{F}\{e^{-rt} \sin(rt) u(t)\} = \frac{1}{r\pi} \mathcal{F}\{e^{-rt} u(t)\} *$$

$$\mathcal{F}\{\sin(rt)\} = \frac{1}{r\pi} \left(\frac{1}{r + j\omega} * \left(\frac{\pi}{j} [\delta(\omega - r) - \delta(\omega + r)] \right) \right)$$

$$= \frac{1}{rj} \left(\frac{1}{r + j(\omega - r)} - \frac{1}{r + j(\omega + r)} \right) = \frac{r}{-r^2 + \omega(\omega + 4i)}$$

$$X(j\omega) = X_1(j\omega) + X_r(j\omega) = X_1(j\omega) - X_1(-j\omega)$$

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$$X(j\omega) = \int_{-\infty}^{+\infty} \sum_{k=0}^{\infty} a^k \delta(t - kT) e^{-j\omega t} dt \quad (-1)$$

$$= \sum_{k=0}^{\infty} a^k \int_{-\infty}^{+\infty} \delta(t - kT) e^{-j\omega t} dt =$$

$$\sum_{k=0}^{\infty} a^k e^{-j\omega kT} = \frac{1}{1 - a e^{-j\omega T}}$$

$$G(j\omega) = F\{g(t)\} = F\{u(t)\cos(t)\} = (1 - \omega^2)$$

$$\frac{1}{2\pi} (F\{u(t)\} * F\{\cos(t)\}) =$$

$$\frac{1}{2\pi} * (X(j\omega) * \pi(\delta(\omega-1) + \delta(\omega+1))) =$$

$$\frac{X(j(\omega-1)) + X(j(\omega+1))}{2} = \begin{cases} 1 & |\omega| \leq 1 \\ 0 & \text{o.w} \end{cases} \Rightarrow$$

$$X(j\omega) = \begin{cases} 1 & |\omega| \leq 1 \\ 0 & \text{o.w} \end{cases} \Leftrightarrow u(t) = \frac{\sin(t)}{\pi t}$$

$$G(j\omega) = \mathcal{F}\{x(t)\} = \mathcal{F}\left\{u(t) \cos\left(\frac{r}{r}t\right)\right\} = \quad (5-15)$$

$$\frac{1}{r\pi} \left(\mathcal{F}\{u(t)\} * \mathcal{F}\left\{\cos\left(\frac{r}{r}t\right)\right\} \right) =$$

$$\frac{1}{r\pi} * \left(X(j\omega) * \pi \left(\delta\left(\omega - \frac{r}{r}\right) + \delta\left(\omega + \frac{r}{r}\right) \right) \right) =$$

$$\frac{X(j(\omega - \frac{r}{r})) + X(j(\omega + \frac{r}{r}))}{r} = \begin{cases} 1 & |\omega| \leq r \\ 0 & \text{o.w.} \end{cases}$$

$$H_1(j\omega) = \frac{j\omega}{r} \mathcal{F} \left\{ \frac{\sin(\omega_c t)}{\pi t} \right\} = \begin{cases} \frac{j\omega}{r} & |\omega| < \omega_c \\ 0 & \text{o.w} \end{cases} \quad \checkmark$$

$$H_r(j\omega) = \mathcal{F} \left\{ \frac{\sin(r\omega_c b)}{\pi t} \right\} = \begin{cases} 1 & |\omega| < r\omega_c \\ 0 & \text{o.w} \end{cases}$$

$$H_p(j\omega) = \mathcal{F} \{ u(t) \} = \frac{1}{j\omega} + \pi \delta(\omega)$$

$$h(t) = (h_1(t) + (h_1(t) * h_r(t))) * h_p(t) * h_r(t)$$

$$H(j\omega) = (H_1(j\omega) + H_1(j\omega)H_r(j\omega)) H_p(j\omega) H_r(j\omega)$$

$$(j\omega)^r Y(j\omega) + \gamma(j\omega) Y(j\omega) + \lambda Y(j\omega) = r X(j\omega) \quad (1)$$

$$H(j\omega) = \frac{Y(j\omega)}{X(j\omega)} = \frac{r}{(j\omega)^r + \gamma(j\omega) + \lambda} = \frac{1}{(j\omega + r)} - \frac{1}{(j\omega + r)}$$

$$h(t) = \mathcal{F}^{-1}\{H(j\omega)\} = e^{-rt} u(t) - e^{-rt} u(t)$$