Kyle Rassweiler

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Portfolio | Github | LinkedIn

Summary

I'm an **Engineering specialist** with experience in both software and hardware development with schooling focused on embedded development and robotics. I'm a self starter and quick to learn new technologies.

Skills

Software Angular, Assembly(PIC), C++, CMake, Django, Git, HTML, JavaScript,

Mongoose, Node, PHP, Python, React, Redux, SCSS, Typescript, VBA

Virtualisation Docker, Proxmox, Qemu/KVM, XCP-NG

Systems Arch, Debian, FreeBSD/OpenBSD, Windows

Databases MongoDB, MySQL, Postgresql, SQLite

Hardware Arduino, PIC, Raspberry Pi, Zigbee

PLC Mitsubishi, Toyopuc, AB

Robots Kawasaki, Nachi, Panasonic, Yaskawa

Projects

React Pagination A Hatchways assessment for React front-end work. The project required the

addition of a pagination system for a sample blog site.

(Javascript, CSS, HTML, Node, React)

Source

Random Quote Machine A FreeCodeCamp project that generates random tweetable quotes using

React.

(Javascript, SCSS, HTML, Node, React,

Bootstrap)

Source

Markdown Preview A FreeCodeCamp project that will preview markdown input into a seperate

editor window.

(Javascript, SCSS, HTML, Node, React,

Bootstrap)

Source

Krello A simple kanban web app made using Nextjs, React, tRPC, NextAuth,

Prisma, and Typescript. The app is hosted on Vercel and Planetscale.

(Typescript, React, tRPC, Nextjs,

NextAuth, Prisma, Vercel,

Planetscale)

Site | Source | Demo

Kawasaki AS Parser A Kawasaki robot backup parser library written in TypeScript. Used to

assist with analysing robot data in a seperate Toyota project.

(Typescript, SCSS, HTML, Node,

Electron)

Site | Source

Certificates

Free Code Camp

JavaScript Algorithms and Data Structures

July 2022

Certificate

Free Code Camp

Responsive Web Design

June 2022

Certificate

Experience

Engineering Specialist

2017 – Present

TEMA (Toyota)

Commissioning, HMI design, PLC programming, Robotic Vision (Robeye , Omron, Keyence), 3D Factory Design (CAD), Robot programming, Project Management, Tools Programming (VBA, Powerbi, Electron).

Highlights

- Managed project implementation during non production time, ensuring no issues affect production and quality.
- Implemented a new teach method that saved 75% of equipment recovery time, using a 4 point before-after comparison.
- Setup production lines in 7 plants across North America for: Rav4, Camery, Hilander, Lexus NX, and Lexus RX. Production earned roughly 89 billion USD in 2022 across North America.

Robotics Technician

HMI design, PLC programming, Robot programming, SCADA programing.

2014 - 2017

FIO Automotive

Highlights

- Developed a proof of concept SCADA system using Angular, MongoDB, and Node.js. The system allowed management to track downtime and target repeat issues during a 24/7 production period.
- Setup networking for all production lines in order to implement my proof of concept and collect data to a MSSQL database.

Operational Technician

PLC programming, Robot programming.

Education

2012 - 2014

Abbott Point Of Care

Electro-Mechanical Engineering Technician

Embedded development, plc programming, circuit and pcb design, motor controls, industrial robotics, microcontrollers.

Algonquin College

Computer Animation

Traditional animation, 3d animation, riging, modelling, python scripting, layout.

Algonquin College