

# **FT61F02X**

# **TIMER1 Application note**



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# FT61F02x TIMER1application

# 1.timer (TIMERS)

in total7timers, including the watchdog timer (WDT)inside.

	WDT	Timer0	Timer1	Timer2	Timer3/4/5
Prescaler (bits)	-	8 (andWDTshared)	3 (1x, 2x, 4x, 8x)	4 (1x, 4x, 16x)	7 (1x, 2x, 4x, 8x, 16x, 32x, 64x, 128x)
counter (bit)	16	8	16	8	12
Postscaler (bits)	7 (andTimer0shared)	-	-	4 (1 – 16x)	-
clock source	- <u>LIRC</u>	- instruction clock - PA2/TOCKI (transition edge count device)	- instruction clock - LP - PA7/T1CKI (rising edge count	- 2xcommand bell - 2x HIRC	- HIRC - 2xinstruction clock - PA2/TOCKI (transition edge counter) - PA7/T1CKI (rising edge counter)

#### surface1-1timer resource

Note: If the clock source of the timer is not the instruction clock, after changingTMRxBefore setting the "TMRxON = 0".

When the timer is enabled, its selected clock source is automatically turned on. When the timer selectsLPWhen the oscillator is used as the clock source, the FOSC must be configured accordingly LPmode or choice INTOSCIO mode, otherwise LPThe oscillator will be off and will not generate counts.

WDTThe postscaler (postscaler) and Timer 0 The prescaler (prescaler) Share the same hardware frequency division circuit. The hardware circuit is assigned by instruction selection to WDT or Timer 0, but both cannot be used at the same time. For timers that are not assigned a divider, the divider ratio is "1".

existPORor system reset, exceptTimer0counter of (counter)The counters, prescalers, and postscalers of all other timers will be reset except. The following events will also reset the counter and divider of the corresponding timer:

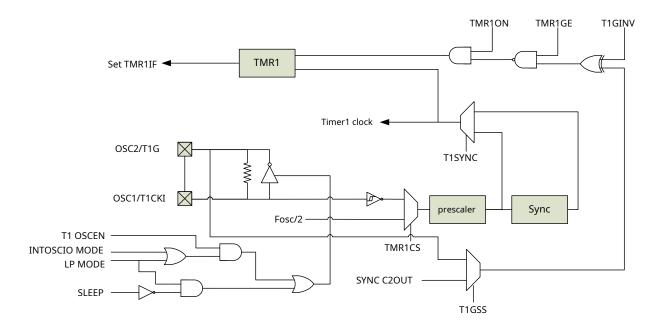
	WDT	Timer0	Timer1	Timer2	Timer3/4/5
		- WriteTMR0	- TMR1ON = 0	- LIRCandHIRC	- WriteTMRxL/H
		- PSAto switch	- WriteTMR1L/H	Cross Calibration Start	- WriteTxCKDIV
prescaler	-			- WriteT2CON,	
				TMR2L/H	
				- any reset action	
	- WDT, OSToverflow	-Timer0overflow	- TMR1 = PR1	- TMR2 = PR2	- TMRx = PRx
	- enter/exitSLEEP		(match, special	(match)	(BUZZERmode
counter	- CLRWDT		event trigger)		match)
	- WriteWDTCON		- ECCPtrigger special		
			special event		
	except writeWDTCONoutside			- WriteT2CON,	
post divider	all of the above conditions		-	TMR2L/H	-
	- PSAto switch			- any reset action	

surface1-2Timer counter and divider reset event

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# 1.1. timer1 (TIMER1)



picture1-1Timer1Structure diagram

TIMER1Is a16Bit timers and counters have the following characteristics:

- a pair16Bit Timer/Counter Register (TMR1H:TMR1L) Programmable
- internal or external clock source
- 3bit prescaler
- optionalLPoscillator
- synchronous or asynchronous operation
- via a comparator orT1GPin'sTimer1Gating (count enable) Overflow
- interrupt
- Wake-up on overflow (external clock only and in asynchronous mode)
- Time Base for Capture/Compare Functions
- Special event triggers (withECCP)
- Comparator output withTimer1Clock synchronization

Timer1module is16Bit up counter. rightTMR1HorTMR1LA write operation will directly update the counter.

When used with an internal clock source, this module is a timer. When used with an external clock source, the module can be used as a timer or counter.

Timer1A pair of registers (TMR1H:TMR1L) increments to FFFFhreturn after 0000h. Timer1When the full return, PIR1 register Timer1 interrupt flag (TMR1IF) be placed 1. Whether to trigger to interrupt and / or wake up from sleep depends on the corresponding enable / disable control bit (TMR1ON, GIE, PEIE and TMR1IE). In the interrupt service routine will TMR1IF Clearing the bit will clear the interrupt.

To wake up from sleep, set to asynchronous counter mode. In this mode, an external crystal or clock source signal can be used to increment the counter. otherwise Timer1will stop counting and maintain the count value it had before going to sleep. The required register configuration is as follows:

- must beT1CONregisterTMR1ONLocation1
- must bePIE1registerTMR1IELocation1



- must beINTCONregisterPEIELocation1
- must beT1CONregisterT1SYNCLocation1
- must beT1CONregisterTMR1CSLocation1
- Can beT1CONregisterT1 OSCENLocation1

# 1.1.1. Timer1Summary of related registers

name	state		register	address	reset value	
T1GINV	gating toggle bit	1 =Active high (starts when the gate is high $\frac{dynamic\ count}{dynamic\ count}$ $0 = \underbrace{active\ low}$	T1CON[7]		RW-0	
TMR1GE	Gate enable bit	1 = Enable (Clock source is not instruction clock) 0 = <u>no</u>	T1CON[3]		RW-0	
T1CKPS	Timer1Prescaler 00 = 1		T1CON[5:4]		RW-00	
T1 OSCEN	LPoscillator enable bit  1 = LPThe oscillator is enabled for  Timer1 0 = LPOscillator off  Note: When the clock is configured asLPorLIRCmode, this bit is valid, otherwise this bit is ignored.		T1CON[3]	0x10	RW-0	
T1SYNC	Timer1External clock input synchronization control bit  whenTMR1CS = 1:  1 =out of sync		T1CON[2]		RW-0	
TMR1CS	Timer1clock	1 = PA7/T1CKI(rising edge) <u>0 =</u> instruction clock	T1CON[1]		RW-0	
TMR1ON	enable bit	1 =Enable 0 = <u>closure</u>	T1CON[0]		RW-0	
T1GSS	gating source option bit	1 = T1Gpin (configured as a digital input) 0 =ComparatorsC2Output	CMCON1[1]		RW-1	
C2SYNC	Comparators2output sync bit  1 =output withTimer1Synchronous to the falling edge of the clock 0  =asynchronous output		CMCON1[0]	0x1A	RW-0	
TMR1L TMR1H	TMR1Timing and counting result register low8bit  TMR1Timing and counting result register high8bit		TMR1L[7:0] TMR1H[7:0]	0x0E 0x0F	- RW-0000 0000	

**surface1-3**Timer1Related User Control Registers

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name	S	register	address	reset value	
GIE	global interrupt	1 =Enable (PEIE, TMR1IEBe applicable) 0 = global shutdown (wake up is not affected)	INTCON[7]	0x0B 0x8B 0x10B	RW-0
PEIE	Total Peripheral Interrupt	1 =Enable (TMR1IEBe applicable) 0 = <u>closure</u> (no wakeup)	INTCON[6]		RW-0
TMR1IE	Timer1andPR1overflow interrupt	1 =Enable 0 = <u>closure</u> (no wakeup)	PIE1[0]	0x8C	RW-0
TMR1IF	Timer1andPR1overflow interrupt flag	1 =overflow (latch) 0 = <u>not overflow</u>	PIR1[0]	0x0C	RW-0

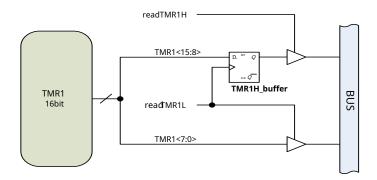
surface1-4Timer1Interrupt Enable and Status Bits

#### 1.1.2. Timer1Register read/write operations

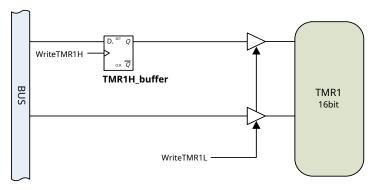
When the timer runs on an external asynchronous clock, TMR1HandTMR1LCannot read or write at the same time. passTMR1Hinternal cache of TMR1H\_buf
To resolve this issue, the following read and write sequences must be followed:

- readTMR1when, read firstTMR1L,at this timeTMR1HThe value of will be latched intoTMR1H\_buf, then readTMR1H. whenTimer1 When the clock source is not the instruction clock, you need to set "TMR1ON=0"to stop counting, then read theTMR1Executed before1stripNOP instruction.
- WriteTMR1when, first writeTMR1H,at this timeTMR1HThe value of will be stored inTMR1H\_buffermiddle. then writeTMR1L,at this time TMR1Hand

  TMR1Lwill be updated to the count value at the same time. In addition, in order to avoid the contention between write operation and count, before write operation, should set "TMR1ON = 0"to stop counting.



picture1-2TMR1Read operation block diagram



picture1-3 TMR1Write Operation Structure Box

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#### 1.1.3.Timer1clock source

T1CONregisterTMR1CSBits are used to select the clock source. whenTMR1CS=0hour, is the instruction clock (2Tmode). whenTMR1CS=1 When, the clock source is provided externally (T1CKIpins).

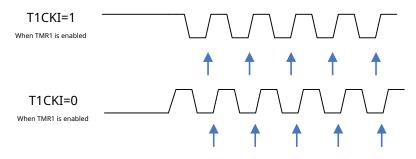
When an external clock source is selected, Timer1The module can work as a timer and counter. when counting, Timer1The external clock inputT1CKI The rising edge increments.

When the clock is configured asLPorINTOSCIOmode, Timer1be usableLPOscillator as clock source.

#### Notice:

In Counter mode, the counter must experience a falling edge before the first rising edge increments after any one or more of the following conditions:

- POREnable after resetTimer1
- to writeTMR1HorTMR1L
- Timer1Prohibited
- T1CKIwhen highTimer1Prohibited(TMR1ON=0), then inT1CKIwhen lowTimer1enabled (TMR1ON=1).



## Notice:

- 1. The edge pointed by the arrow is the counter increment;
- 2. In counter mode, a falling edge must pass before the counter increments.

picture1-4TIMER1Incremental edge indication

OSC1(input) pin withOSC2(output) pins connected between low power32.768kHzcrystal, willT1CONregisterT1 OSCEN control position1Enable the oscillator, the oscillator will continue to work during sleep.

becauseTimer1Oscillators and SystemsLPOscillator shared, theTimer1Only when the main system clock comes from the internal oscillator or the oscillator is in LPThis mode can only be used in this mode. The user must provide a software delay to ensure proper oscillator start-up.

when Timer 1 The oscillator is enabled when the PORTA[7], PORTA[6] The output drive is disabled, and the PA7 and PA6 bits read as 0. but TRISA6, TRISA6 Keep the original value.

## Notice:

1.Because the oscillator needs a certain start-up and stabilization time. So in willT1 OSCENplace1and enableTimer1An appropriate delay should be added before:

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2. When configured in Oscillator mode, the T1G fixed output1, so it cannot be used to gate TIMER1.



# 1.1.4.Timer1prescaler

Timer1There are four prescaler options for clock input1,2,4or8crossover.T1CONregisterT1CKPSbit controls the prescaler counter. The prescaler counter cannot be read and written directly;TMR1HorTMR1Lduring a write operation, orTIMER1 When closed (TMR1ONfor0), the prescaler counter is cleared.

#### 1.1.5.Timer1Works in asynchronous counter mode

whenT1CONRegister Control BitsT1SYNCplace1, the external clock input is not synchronized. The timer increments asynchronously to the internal phase clock. If an external clock source is selected, the timer will continue to run during sleep and can generate an interrupt on overflow to wake up the processor. However, special care should be taken when reading and writing timers (seechapter1.1.2).

#### Notice:

It is possible to miss an increment when switching from synchronous to asynchronous mode. When switching from asynchronous mode to synchronous mode, it is possible to generate one more increment.

## 1.1.6.Timer1gating

Timer1The gating source is software configurable asT1Gpin or comparatorC2output, the device can be used directlyT1GTime an external event, or use a comparatorC2Timing of simulated events. Timer1For gating source selection, seeCMCON1register.

useT1CONregisterT1GINVbit flippedTimer1Gating, regardless of its originT1Gpin or comparatorC2Output. This will configure Timer1to ensure that there is an active-low or active-high time between events.

#### 1.1.7.Timer1Capture/Compare Timebase

 $When operating in capture or compare mode, {\it ECCPThe module uses a pair of TMR1H:} TMR1L register as the time base.$ 

- 1.In capture mode,TMR1H:TMR1LThe values of this pair of registers are copied to theCCPR1H:CCPR1L This pair of registers.
- 2.In compare mode, when CCPR1H:CCPR1LThis pair of register values and TMR1H:TMR1LWhen the value of matches, an event will be fired. This event can be a special event trigger.

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For more information seechapterError! Reference source not found."enhanced capture/compare/PWMmodule".



#### 2.Application example

```
//**************
******* /*file name:TEST_61F02x_Timer1.c
* Features:
          FT61F02x-Timer1Demo
*IC:
          FT61F023 SOP16
* Crystal:
          16M/2T
* illustrate:
          whenDemoPortInWhen floating or high level,
           Demo Port Outoutput1kHzduty cycle50%The waveform of -Timer1achieve when
           DemoPortInWhen grounded,Demo Port OutOutput high level. Off timer interrupt
              FT61F023 SOP16
* VDD-----|1(VDD)
                        (VSS)16 | -----GND
* NC----- | 2(PA7)
                         (PA0)15|----NC
* NC-----|3(PA6)
                         (PA1)14 |----NC
* NC-----| 4(PA5)
                         (PA2)13 | -----NC
* DemoPortIn--- | 5(PC3)
                         (PA3)12 | - -- DemoPortOut
* NC-----|6(PC2)
                         (PC0)11 | -----NC
* NC-----| 7(PA4)
                         (PC1)10 | -----NC
* NC----- | 8(PC5)
                         (PC4)09|----NC
*/
//*********************************
# include "SYSCFG.h"
PA3
#define Demo Port Out
                        PC3
#define DemoPortIn
/*_______
* Function name:interrupt ISR
* Function: Timer1interrupt handling
* set upTimer1Timing duration =(1/system clock cycle)*instruction cycle*prescaler value*(65536-TMR1H:TMR1L)
                    =(1/16000000)*2*1*4000=500µs
-----
----* / void interrupt ISR(void)
{
     if(TMR1IF)
    {
        TMR1IF = 0;
        TMR1L = 0X60;
                                        //timing500µs=>TMR1=4000*0.125µs=500µs //
                                        initial value =65536-4000=61536=>0XF060 //Assign
        TMR1H = 0XF0;
                                        initial value =>TMR1H=0XF0;TMR1L=0X60 //flip level
        DemoPortOut = ~DemoPortOut;
   }
}
```

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```
/*__________
* Function name:POWER INITIAL
* Features: Power-on system initialization
* enter:
            none
* output: none
 -----
----*/ void POWER INITIAL (void)
{
     OSCCON = 0B01110001:
                                                   //IRCF=111=16MHz/2T=8MHz,0.125µs//Temporarily
     INTCON = 0;
                                                    disable all interrupts
     PORTA = 0B00000000;
     TRISA = 0B00000000;
                                                   //PAinput Output0-output1-enter //
                                                    PA3->output
     PORTC = 0B00000000;
     TRISC = 0B00001000;
                                                   //PCinput Output0-output1-enter
                                                   //PC3->enter
     WPUA = 0B00000000;
                                                   //PAPort pull-up control1-pull up0-close pull //
     WPUC = 0B00001000;
                                                   PCPort pull-up control1-pull up0-close pull
     OPTION = 0B00001000;
                                                   //Bit3=1, WDT MODE, PS=000=WDT RATE 1:1
     MSCKCON = 0B00000000;
     //Bit6->0,prohibitPA4,PC5Regulated output
     //Bit5->0,TIMER2the clock isFosc //Bit4->0,
     prohibitLVR
     CMCON0 = 0B00000111;
                                                   //turn off the comparator.Cxfor numbersIOmouth
}
* Function name:TIMER1_INITIAL
* Function: Initialize and set the timer1
* Set the timing duration =(1/system clock cycle)*instruction cycle*prescaler value*(65536-TMR1H:TMR1L)
                 =(1/16000000)*2*1*4000=500µs
----* / void TIMER1_INITIAL (void)
{
     //Need to reassign the initial value in the interrupt
     T1CON = 0B000000000;
     //Bit[5:4]=00,T2clock frequency division1:1 //
     Bit1=0,T1Clock source selection internal clock
     TMR1L = 0X60;
                                                   //TMR1Assign the initial value to the lower eight bits
     TMR1H = 0XF0;
                                                    //TMR1Assign the initial value to the upper eight bits
     TMR1IE = 1;
                                                   //EnableTMER1interruption
     TMR1ON = 1;
                                                    //EnableTMER1start up
     PEIE=1;
                                                    //Enable peripheral interrupt
```

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```
GIE = 1;
                                                       //enable global interrupt
}
* Function name:main
* Features: main function
* enter: none
* output: none
*/ void main()
{
     POWER_INITIAL();
                                                       //system initialization
     TIMER1_INITIAL();
                                                       //initializationT1
     while(1)
     {
           if(DemoPortIn == 1)
                                                       //Determine whether the input is high
                TMR1IE = 1;
                                                       //start timer1to interrupt
           }
           else
           {
                TMR1IE = 0;
                                                       //off timer1to interrupt
                DemoPortOut = 1;
          }
     }
}
```

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