

# CS 561 Artificial Intelligence

## Lecture # 4 Inference in Bayesian Networks

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# Outline

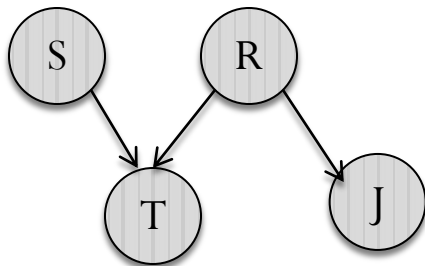
- Inference in Bayesian Network
  - Exact Inference
  - Approximate Inference
- Exact Inference
  - Inference by Enumeration
  - Variable Elimination
- Approximate inference: Sampling
- Sampling
  - Direct Sampling methods
    - Forward sampling
    - Rejection sampling
    - Likelihood sampling
  - Markov chain sampling

# Conditional Independence

- **Example:** One morning Tracey leaves her house and realise that her grass is wet. Is it due to overnight rain or did she forget to turn off the sprinkler last night?
- Next she notices that the grass of her neighbour, Jack, is also wet.
- This **explains away** to some extent the possibility that her sprinkler was left on, and she concludes therefore that it is probably been raining (it decreases her belief that the sprinkler is on).
- Using the following four propositional random variables, construct the BN and determine if S is d-separated from J when T is known.
  - R: Rain  $\in \{0,1\}$  (Rain = 1 means that it has been raining, and 0 otherwise)
  - S: Sprinkler  $\in \{0,1\}$
  - J: Jack's grass wet  $\in \{0,1\}$
  - T: Tracy's Grass wet

# Conditional Independence

- Four propositional random variables are:
  - R: Rain  $\in \{0,1\}$  (Rain = 1 means that it has been raining, and 0 otherwise)
  - S: Sprinkler  $\in \{0,1\}$
  - J: Jack's grass wet  $\in \{0,1\}$
  - T: Tracy's Grass wet

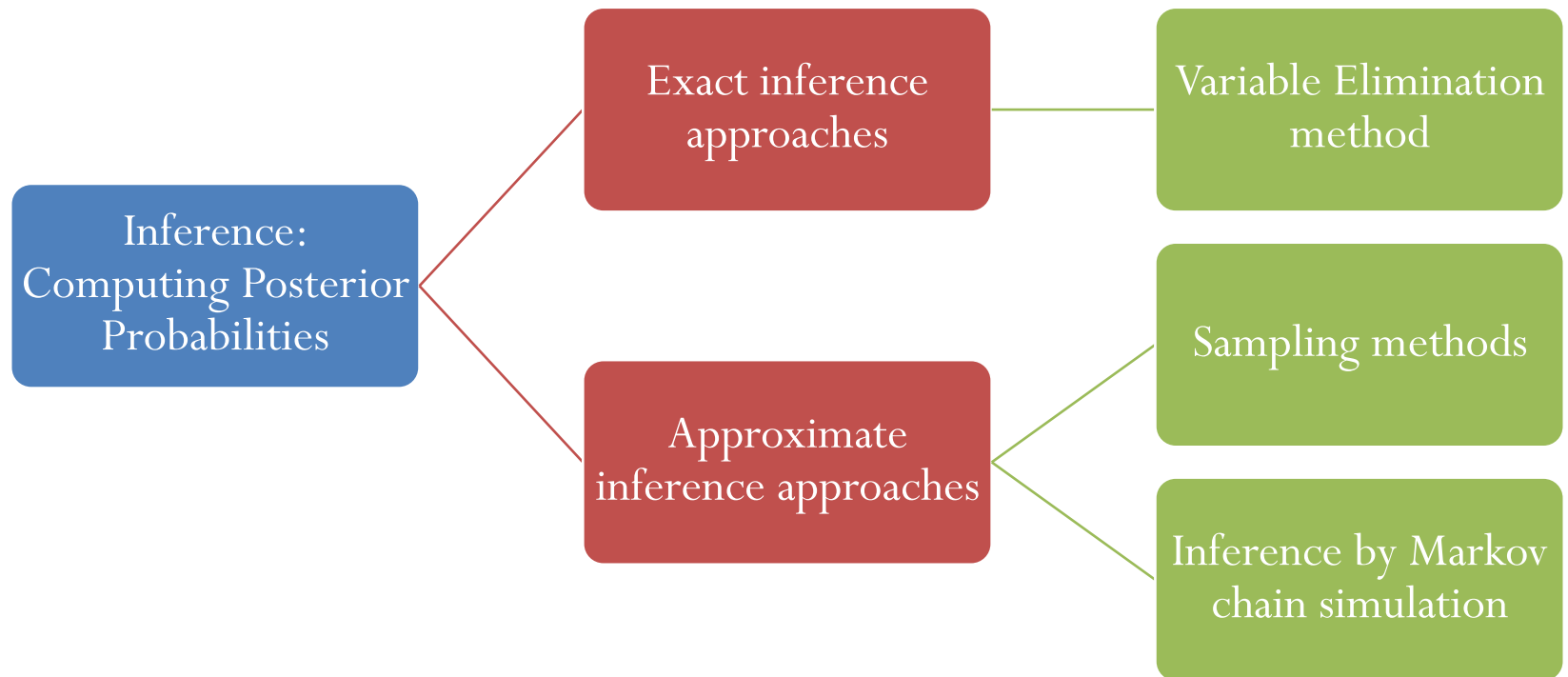


- The trail between S and J: S-T-R-J
- S-T-R converging connection and T is known so influence flows from S to R.
- T-R-J diverging connection and R is not known so influence flows from T to J.
- So, S and J are not d-separated given T

# Inference in Bayesian Networks

- Given a Bayesian network, what queries one might ask?
  - Simple query: compute posterior probability i.e.  $P(X_i | E=e)$
- $X$  denotes query variable,  $E$  is set of evidence variables,  $E_1, \dots, E_m$ , and  $e$  is particular observed event,  $Y$  denotes non-query, non-evidence variables (called **hidden variables**).
- Example:  $P(\text{Burglary} | \text{JohnCalls} = \text{true}, \text{MaryCalls} = \text{true})$ 
  - $X = \text{Burglary}, E = \{\text{JohnCalls}, \text{MaryCalls}\}, Y = \{\text{Alarm}, \text{Earthquake}\}$

# Inference in Bayesian Networks



# Inference by Enumeration

- $P(X | e) = \alpha P(X, e) = \alpha \sum_y P(X, e, y)$  : Sum over the variables not involved in the query.

$$P(B | j, m) = \alpha P(B, j, m) = \alpha \sum \sum P(B, j, m, e, a)$$

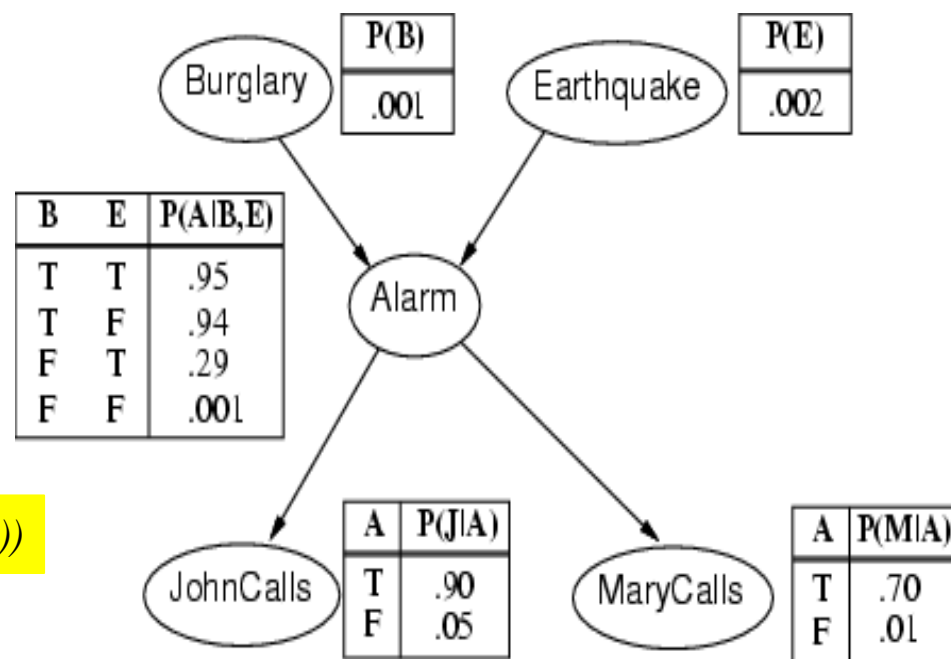
Using Bayesian network semantics we can get the expression in terms of CPTs.

Let us write this for *Burglary* = true

$$P(b | j, m) =$$

$$\alpha \sum_e \sum_a P(b) P(e) P(a | b, e) P(j | a) P(m | a)$$

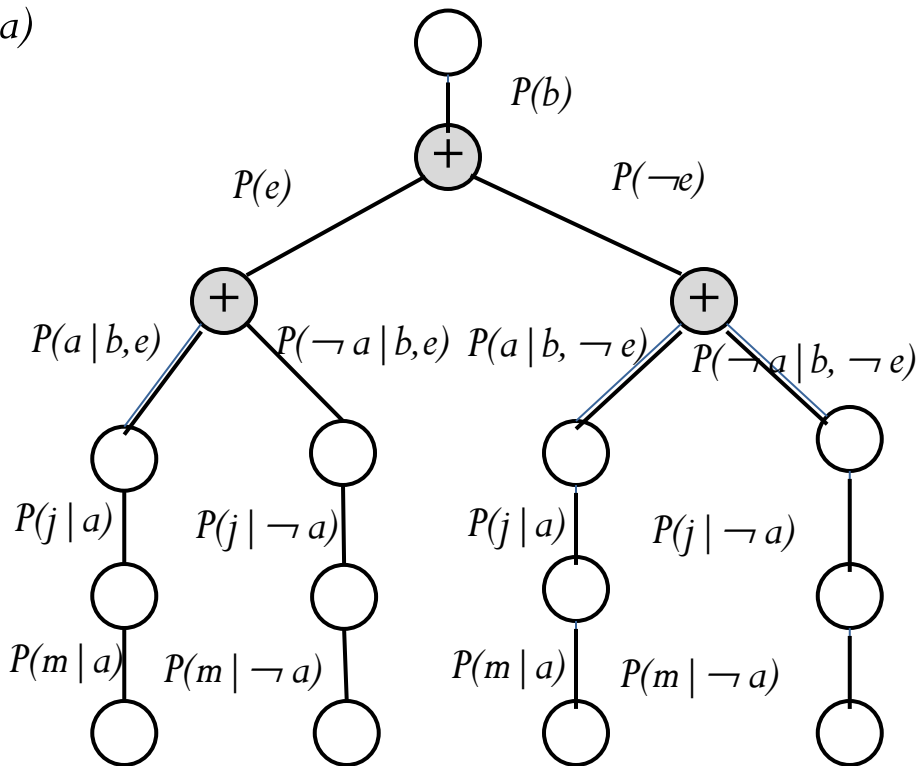
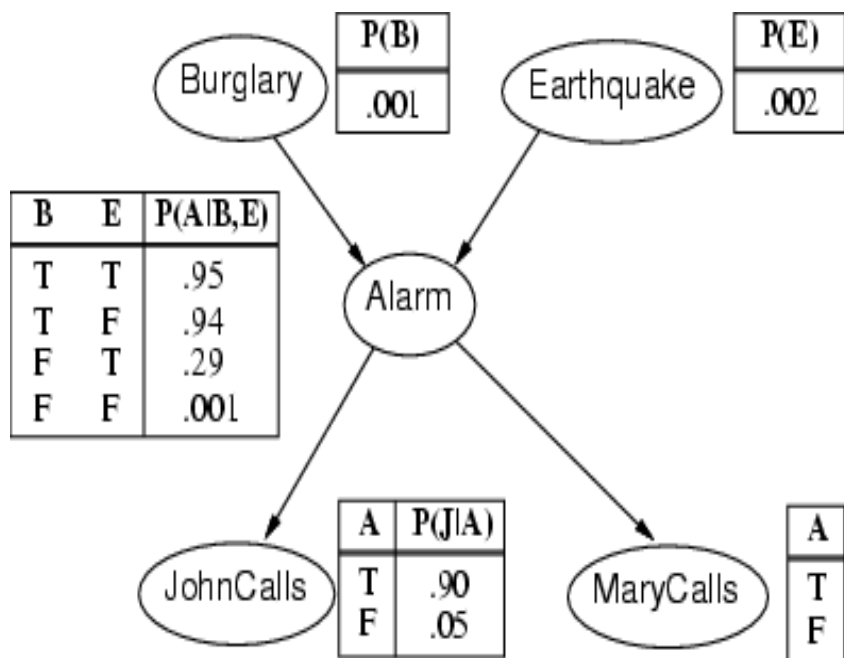
$$= \alpha P(b) \sum_e P(e) \sum_a P(a | b, e) P(j | a) P(m | a)$$



**We know:**  $P(X_1, \dots, X_n) = \prod_{i=1}^n P(X_i | \text{Parents}(X_i))$

# Inference by Enumeration

$$P(b | j, m) = \alpha P(b) \sum_e P(e) \sum_a P(a | b, e) P(j | a) P(m | a)$$



Proceed top down, multiplying values along each path and summing at the “+” nodes. Note repetition of the paths for  $j$  and  $m$  (repeated computation). For large networks takes long time.



# Inference by Variable elimination

- Eliminates repeated calculations
- **Variable elimination:**
  - expression is evaluated from right-to-left order
  - intermediate results are stored
  - summations over each variable are done only for those portions of the expression that depend on the variable.

$$\begin{aligned}
 P(B | j, m) &= \alpha P(B) \sum_e P(e) \sum_a P(a | B, e) P(j | a) P(m | a) \\
 &\quad f_1(B) \quad f_2(E) \quad f_3(A, B, E) \quad f_4(A) \quad f_5(A) \leftarrow \text{factor} \\
 &= \alpha f_1(B) \times \sum_e f_2(E) \times \sum_a f_3(A, B, E) \times f_4(A) \times f_5(A)
 \end{aligned}$$

$$\text{Eg. } f_4(A) = \begin{pmatrix} P(j|a) \\ P(j|\sim a) \end{pmatrix} = \begin{pmatrix} 0.90 \\ 0.05 \end{pmatrix}$$

Matrix

Point-wise  
product  
operation

# Inference by variable elimination

- Sum out variables (right-to-left) from point-wise products of factors to produce new factors, eventually yielding a factor that is the solution.

- sum out  $A$  from the product  $f_3, f_4$ , and  $f_5$  giving  $f_6$

$$\begin{aligned} f_6(B, E) &= \sum_a f_3(A, B, E) \times f_4(A) \times f_5(A) \\ &= (f_3(a, B, E) \times f_4(a) \times f_5(a)) + (f_3(\sim a, B, E) \times f_4(\sim a) \times f_5(\sim a)) \end{aligned}$$

Now we are left with expression

$$P(B | j, m) = \alpha f_1(B) \times \sum_e f_2(E) \times f_6(B, E)$$

- sum out  $E$  from the product of  $f_2$  and  $f_6$

$$f_7(B) = \sum_e f_2(E) \times f_6(B, E) = f_2(e) \times f_6(B, e) + f_2(\sim e) \times f_6(B, \sim e)$$

Now the expression becomes

$$P(B | j, m) = \alpha f_1(B) \times f_7(B)$$

# Inference by variable elimination

- Basic operations
  - Point-wise product
    - two factors  $f_1$  and  $f_2$  yields a new factor  $f$  whose variables are the union of the variables in  $f_1$  and  $f_2$
    - $f$ 's elements are given by product of the corresponding elements in the two factors
    - Example:
      - given two factors  $f_1(A,B)$  and  $f_2(B,C)$ , the pointwise product  $f_1 \times f_2 = f_3$  (A,B,C) has  $2^{1+1+1}$  entries (table in next slide)
  - Summing out variable
    - It is done by adding up the submatrices formed by fixing the variable to each of its value in turn.

# Inference by variable elimination

A	B	$f_1(A,B)$	B	C	$f_2(B,C)$	A	B	C	$f_3(A,B,C)$
T	T	0.3	T	T	0.2	T	T	T	$0.3 \times 0.2 = 0.06$
T	F	0.7	T	F	0.8	T	T	F	$0.3 \times 0.8 = 0.24$
F	T	0.9	F	T	0.6	T	F	T	$0.7 \times 0.6 = 0.42$
F	F	0.1	F	F	0.4	T	F	F	$0.7 \times 0.4 = 0.28$
						F	T	T	$0.9 \times 0.2 = 0.18$
						F	T	F	$0.9 \times 0.8 = 0.72$
						F	F	T	$0.1 \times 0.6 = 0.06$
						F	F	F	$0.1 \times 0.4 = 0.04$

- To sum out A from  $f_3(A,B,C)$ , we write
- $f(B,C) = \sum_a f_3(A,B,C) = f_3(a,B,C) + f_3(\sim a,B,C)$   

$$= \begin{pmatrix} .06 & .24 \\ .42 & .28 \end{pmatrix} + \begin{pmatrix} .18 & .72 \\ .06 & .04 \end{pmatrix} = \begin{pmatrix} .24 & .96 \\ .48 & .32 \end{pmatrix}$$

# Summary Exact Inference

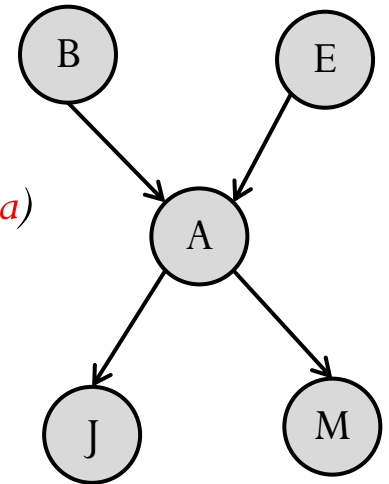
- **Inference** – compute posterior probability distribution for a set of query variables given a set of evidence variables that are observed.
- Exact methods :

- **Inference by enumeration**

- **Simple query:**  $P(B | j, m) = \alpha P(B, j, m) = \alpha \sum \sum P(B, j, m, e, a)$

$$P(B | j, m) = \alpha \sum_e \sum_a P(B) P(E) P(a | B, e) P(j | a) P(m | a)$$

Worst case time complexity: for  $n$  Boolean variable  $O(n2^n)$ , can be improved by moving the summation outside but still will be  $O(2^n)$



- **Variable elimination**

- $d^k$  entries computed for a factor over  $k$  variables with domain sizes  $d$
- ordering of elimination of hidden variables does matter- bad elimination order can generate large factors
- Worst case running time exponential in the size of the Bayes' net (large multiply connected networks)

# Approximate Inference

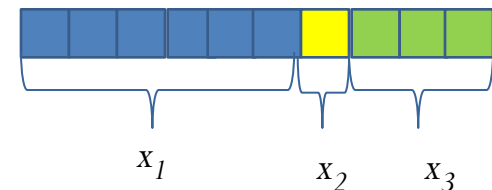
- Sampling based inference
- **Basic idea:** Generate random samples and compute required probabilities from samples.
  - Draw  $N$  samples from distribution
  - Estimate  $P(X | E)$  from samples
- What do we need to know?
  - How to generate a new sample ?
  - How many samples do we need ?
  - How to estimate  $P(X | E)$  ?

# Sampling

- Known distribution, single variable
- Consider a random variable  $X$  with  $dom(X) = \{x_1, x_2, x_3\}$
- To generate a random sample for  $X$ 
  - Select a random number  $y$  in the range  $[0,1)$   
(we select  $y$  from a uniform distribution to ensure that each number between 0 and 1 has same chance of being chosen)
  - Convert this value of  $y$  to a sample from given distribution by associating each outcome  $\{x_1, x_2, x_3\}$  to a given sub-interval with size proportional to  $P(X)$ .
  - Example: suppose  $random()$  returns  $y = 0.3, 0.25, 0.45, 0.65 \dots$  corresponding samples will be  $x_1, x_1, x_1, x_2, \dots$

$X$	$P(X)$
$x_1$	0.6
$x_2$	0.1
$x_3$	0.3

$0 \leq y < 0.6 \rightarrow X = x_1$   
 $0.6 \leq y < 0.7 \rightarrow X = x_2$   
 $0.7 \leq y < 1 \rightarrow X = x_3$



# Sampling Methods

- Forward sampling
- Rejection sampling
- Likelihood weighting
- Gibbs Sampling (MCMC)



# Sampling Methods

- **Forward sampling** / Prior sampling (**without evidence**)
  - Sample each variable in topological order
  - probability distribution from which the value is sampled is conditioned on the values already assigned to the variable's parents

Input: Bayesian network

$X = \{X_1, \dots, X_n\}$ ,  $n$  - #nodes,  $N$  - # samples

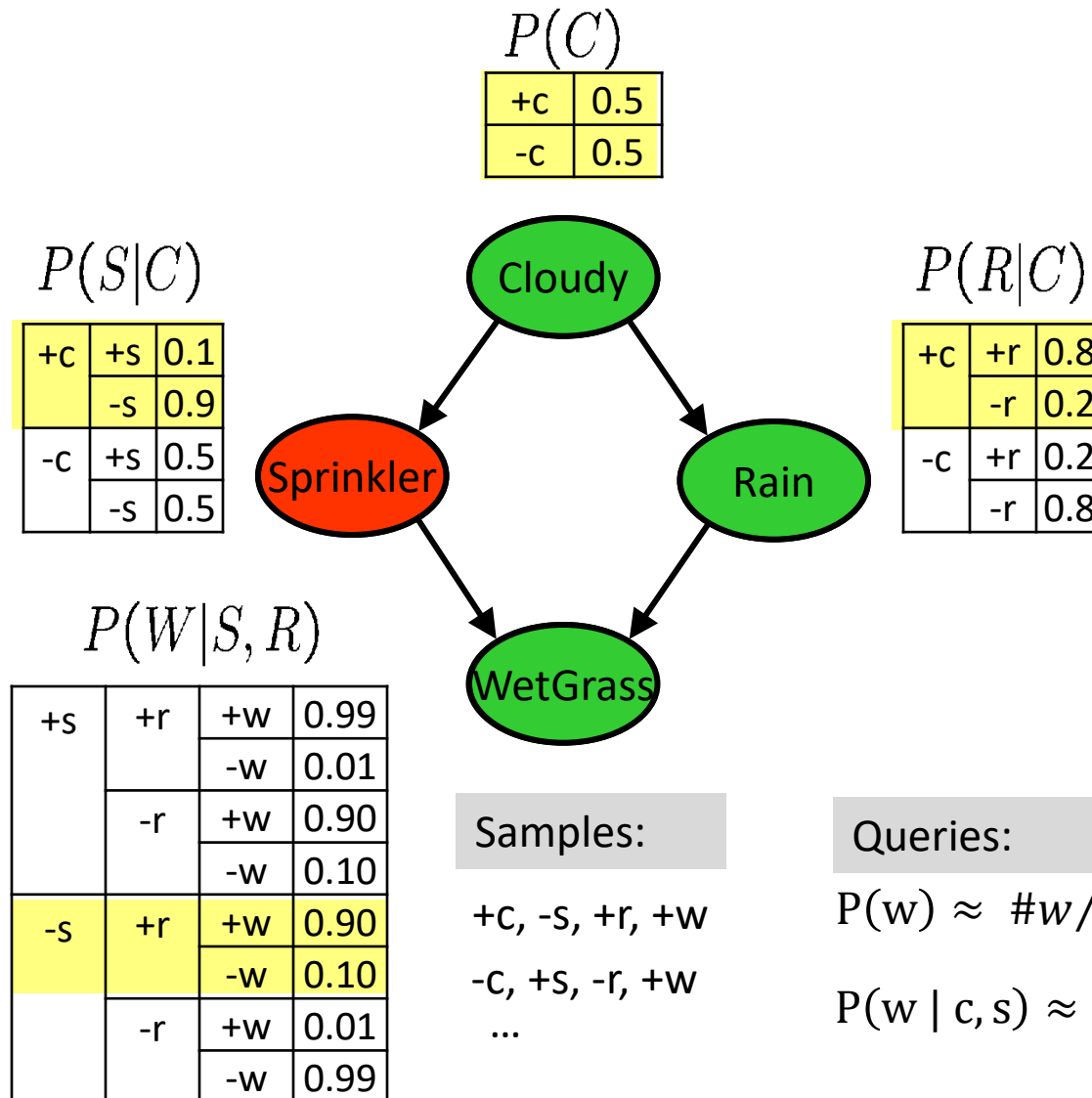
Output:  $N$  samples

*Process nodes in topological order - first process the ancestors of a node, then the node itself*

1. For  $t = 1$  to  $N$
2.     For  $i = 1$  to  $n$
3.          $X_i \leftarrow \text{sample } x_i^t \text{ from } P(x_i | \text{parents}(X_i))$

Assume ordering: Cloudy, Sprinkler, Rain, WetGrass

## Forward Sampling



# Sampling methods

- Rejection Sampling (evidence available)
  - generate samples from the prior distribution specified by the network, reject all those samples that do not match the evidence.

Input: Bayesian network

$X = \{X_1, \dots, X_n\}$ ,  $n$  - #nodes

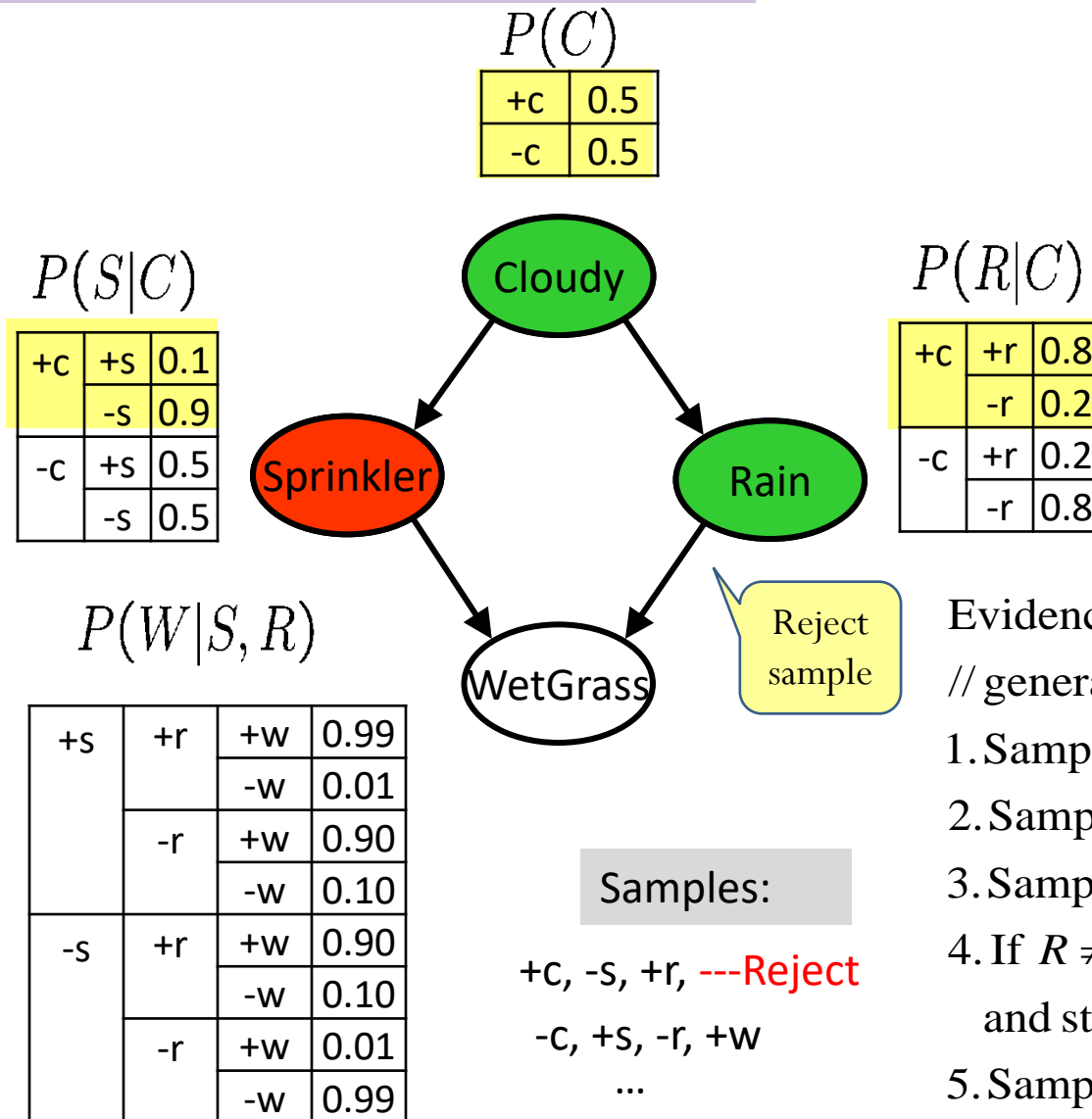
$E$  - evidence,  $N$  - # samples

Output:  $N$  samples consistent with  $E$

1. For  $t=1$  to  $N$
2.     For  $i=1$  to  $n$
3.          $X_i \leftarrow \text{sample } x_i^t \text{ from } P(x_i \mid \text{parent}(X_i))$
4.         If  $X_i$  in  $E$  and  $X_i \neq x_i$ , reject sample:
5.             set  $i = 1$  and go to step 2

Assume ordering: Cloudy, Sprinkler, Rain, WetGrass

## Rejection Sampling



Evidence :  $R = -r$

// generate sample  $k$

1. Sample  $C$  from  $P(C)$
2. Sample  $S$  from  $P(S | C)$
3. Sample  $R$  from  $P(R | C)$
4. If  $R \neq -r$ , reject sample and start from 1, otherwise
5. Sample  $W$  from  $P(W | S, R)$

# Sampling Method

**Problem of Rejection Sampling:** for unlikely evidence, lots of samples rejected

- **Likelihood Weighting**
  - fix the values for evidence variables, and sample only non-evidence variable (not sampling from right distribution anymore)
  - Now weight the samples by evidence likelihood (probability of evidence given parents).

**For**  $k = 1$  to  $N$

For each  $X_i$  in topological order  $o = (X_1, \dots, X_n)$ :

$w_k = 1$

**if**  $X_i \notin E$

$X_i \leftarrow$  sample  $x_i$  from  $P(x_i \mid \text{parents}(X_i))$

**else**

assign  $X_i = e_i$

$w_k = w_k \bullet P(e_i \mid \text{parents}(X_i))$

Assume ordering: Cloudy, Sprinkler, Rain, WetGrass

## Likelihood Weighting

Query:  $P(\_ | W)$

Evidence:  $W = +w$

$$P(S|C)$$

+c	+s	0.1
	-s	0.9
-c	+s	0.5
	-s	0.5

$$P(C)$$

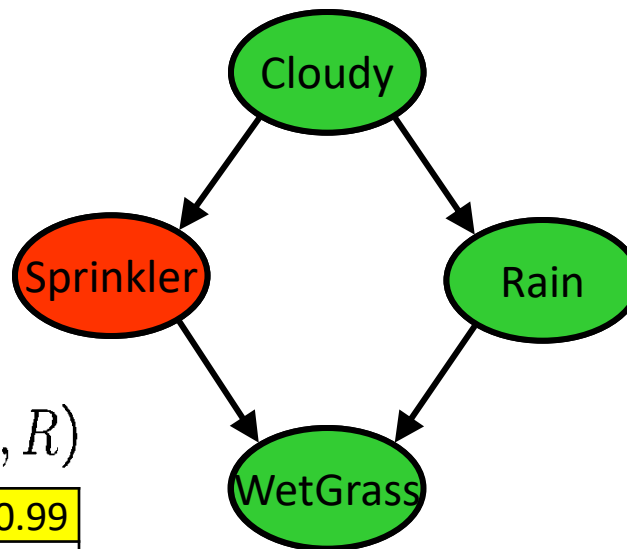
+c	0.5
-c	0.5

$$P(R|C)$$

+c	+r	0.8
	-r	0.2
-c	+r	0.2
	-r	0.8

$$P(W|S, R)$$

+s	+r	+w	0.99
		-w	0.01
	-r	+w	0.90
		-w	0.10
-s	+r	+w	0.90
		-w	0.10
	-r	+w	0.01
		-w	0.99



Samples:

+c, -s, +r, +w 0.90 (weight)

-c, +s, -r, +w 0.90

...