

CS 561 Artificial Intelligence

Lecture # 3 Bayesian Networks

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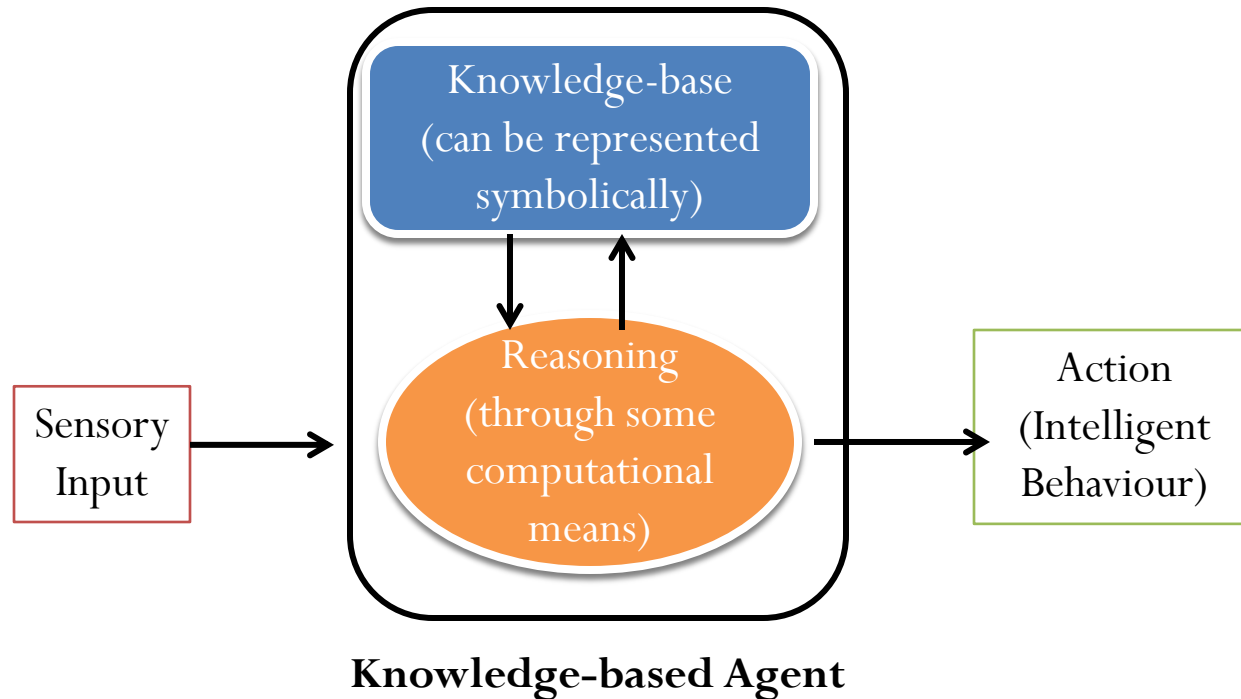
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Outline

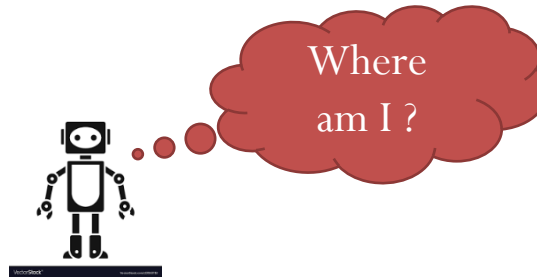
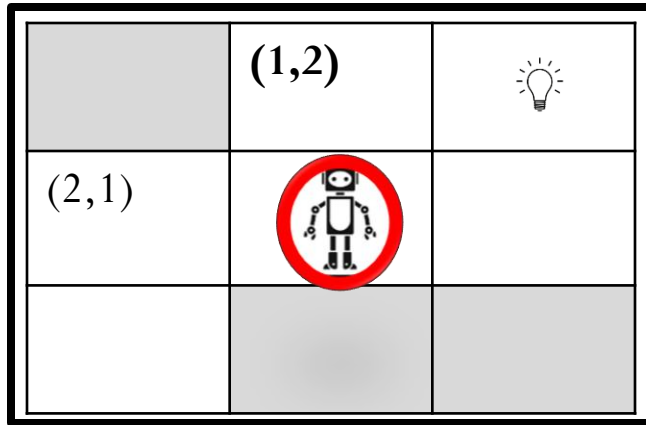
- Background
 - Knowledge, Representation, Reasoning
 - Uncertainty
 - What is uncertainty?
 - Reasons of Uncertainty
- Reasoning under uncertainty: How probability theory can be used?
- Belief Networks
 - Structure
 - Notion of d-separation

Background



- How an agent uses what it knows in deciding what to do?

Background



- Propositional Logic
 - $S_1: \neg O_{1,2}, S_2: O_{3,2}$
 - $S_3: B_{2,2} \Leftrightarrow L_{1,2} \vee L_{2,1} \dots$

- **Robot Localization:** robot needs to determine its current location
 - given a map of the world
 - four sonar sensors (NSWE) and one light sensor (L)
 - tells whether there is an obstacle (the outer wall or gray square in the figure), and also if a room is bright.
 - Current sensor value : [N S W E L] : [False True False False False]

Background

- **Uncertainty**
 - the state of being unsure of something (from dictionary)
- **Uncertainty in data (facts)**
 - Imprecise, inaccurate and unreliable data
 - Missing data
 - Example: Medical domain
 - Patient's weight is 45 kg vs. 45.25 kg
 - Patient's weight is 43.444 kg vs. 45 kg (former is more precise not accurate if a person's actual weight is 44.9 kg)
 - Patient's weight is 45.25 kg, measured again – it is 44.95 kg.
 - Medication requires two tests, however results of only one test is available

Background

- **Uncertainty in knowledge (rules)**
 - Vagueness in rules
 - Example: If the person is overweight then they usually have large waistline.
 - Not enough rules to cover the problem space (theoretical or practical ignorance, lack of available theory to describe a situation)
 - Rules may be contradictory (different evidences suggesting same diagnosis)
- **Issues:**
 - How to represent uncertain data and knowledge?
 - How to draw inference using uncertain data and knowledge?

Background

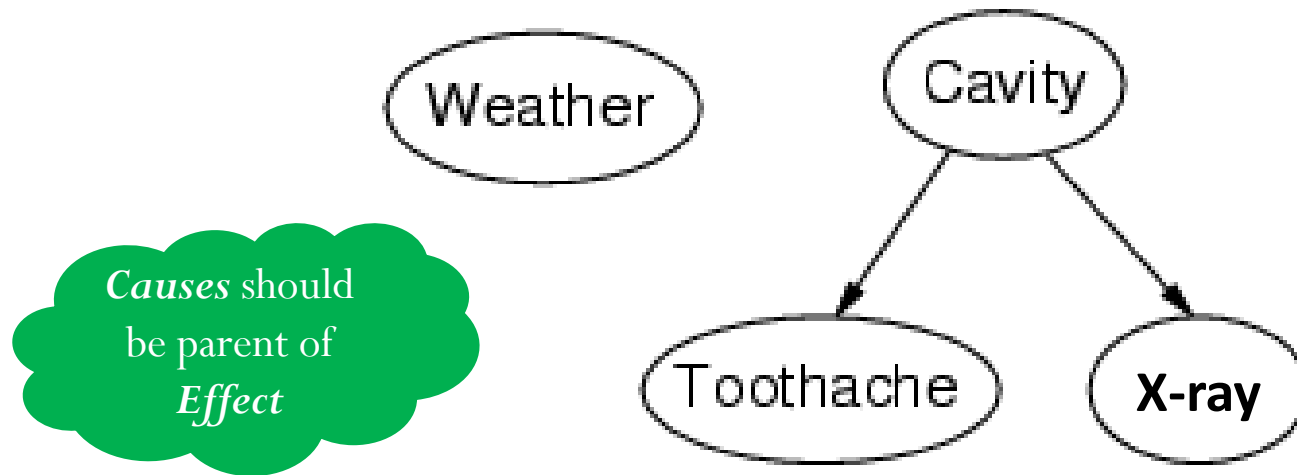
- **Probability theory**- deals with incompleteness (ignorance about the world)
- Probability provides a way of summarizing the uncertainty that comes from ignorance, quantifies the *degree of belief*
- **Probability** : a measure of belief (as opposed to being a frequency) – **Bayesian Probability** or Subjective Probability

Bayesian networks

- Representing knowledge in uncertain domain
- A simple, graphical notation for conditional independence assertions and hence for compact specification of full joint distributions.
- Syntax:
 - a set of nodes, one node per random variable
 - a directed, acyclic graph (link \approx "directly influences")
 - a conditional distribution for each node given its parents:
$$\mathbf{P}(X_i \mid \text{Parents}(X_i))$$
- In the simplest case, conditional distribution represented as a **conditional probability table** (CPT) giving the distribution over X_i for each combination of parent values

Example

- Topology of network encodes conditional independence assertions:

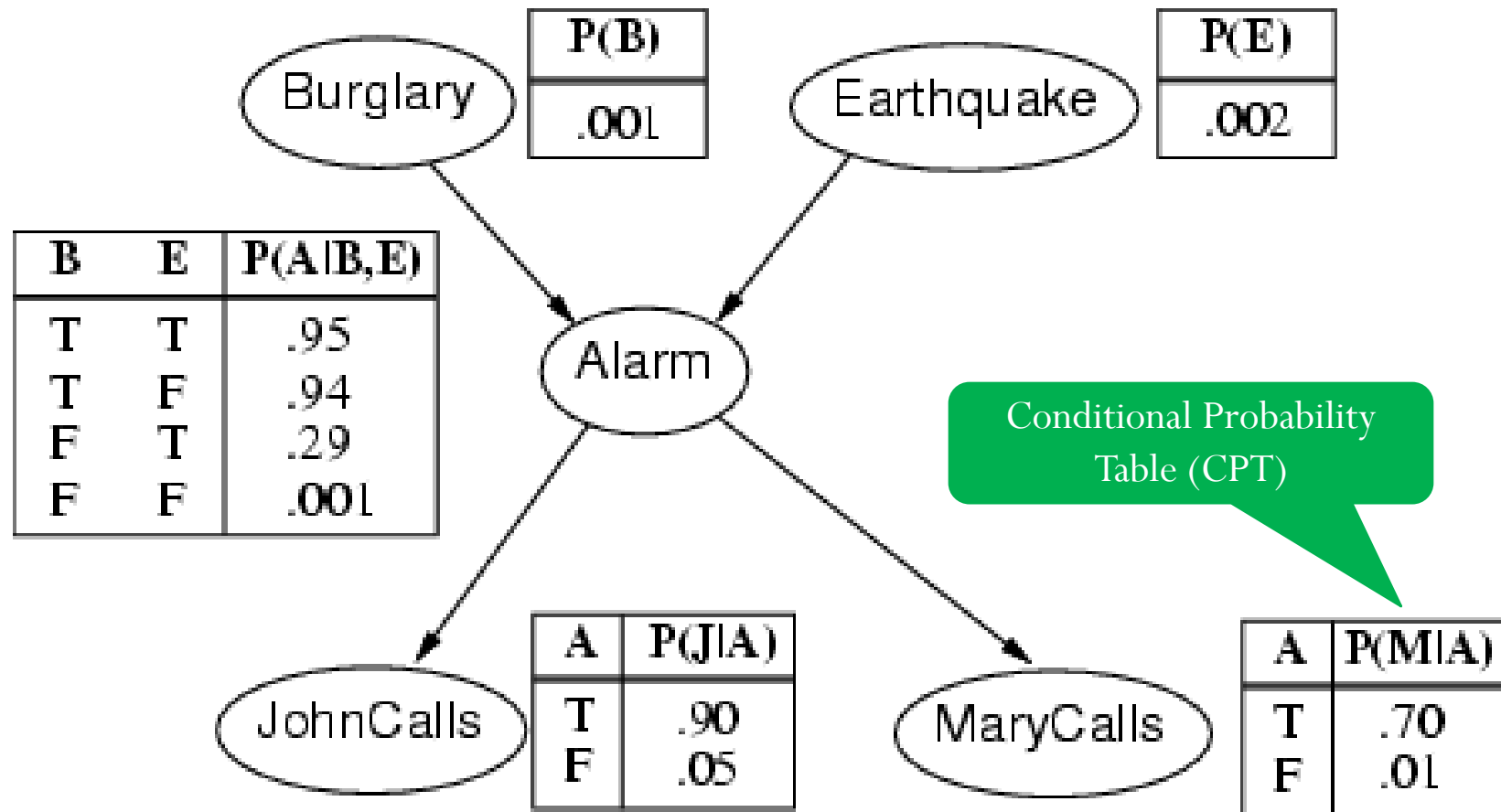


- *Weather* is independent of the other variables
- *Toothache* and *X-raySpot* are conditionally independent given *Cavity*

Example

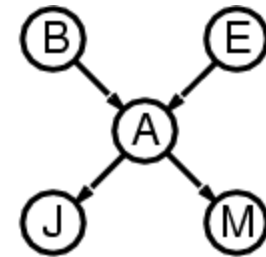
- I'm at work, neighbor John calls to say my alarm is ringing, but neighbor Mary doesn't call. Sometimes it's set off by minor earthquakes. Is there a burglar?
- Variables: *Burglary, Earthquake, Alarm, JohnCalls, MaryCalls*
- Network topology reflects "causal" knowledge:
 - A burglar can set the alarm off
 - An earthquake can set the alarm off
 - The alarm can cause Mary to call
 - The alarm can cause John to call

Example contd.



Compactness

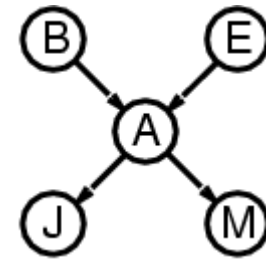
- A CPT for Boolean X_i with k Boolean parents has 2^k rows for the combinations of parent values
- Each row requires one number p for $X_i = \text{true}$ (the number for $X_i = \text{false}$ is just $1-p$)
- If each variable has no more than k parents, the complete network requires $O(n \cdot 2^k)$ numbers
- i.e., grows linearly with n , vs. $O(2^n)$ for the full joint distribution
- For burglary net, $1 + 1 + 4 + 2 + 2 = 10$ numbers (vs. $2^5 - 1 = 31$)



Semantics

The full joint distribution is defined as the product of the local conditional distributions that are associated with the nodes of the network:

$$\mathbf{P}(X_1, \dots, X_n) = \prod_{i=1}^n \mathbf{P}(X_i \mid \text{Parents}(X_i))$$



$$\begin{aligned} \text{e.g., } & \mathbf{P}(j \wedge m \wedge a \wedge \neg b \wedge \neg e) \\ &= \mathbf{P}(j \mid a) \mathbf{P}(m \mid a) \mathbf{P}(a \mid \neg b, \neg e) \mathbf{P}(\neg b) \mathbf{P}(\neg e) \\ &= 0.9 \times 0.7 \times 0.001 \times 0.999 \times 0.998 \\ &\approx 0.00063 \end{aligned}$$

Constructing Bayesian networks

- The joint distribution $P(X_1=x_1, \dots, X_n=x_n)$ can be given in terms of conditional probability using **product rule**:

$$P(x_1, \dots, x_n) = P(x_n | x_{n-1}, \dots, x_1) P(x_{n-1}, \dots, x_1)$$

repeating the process, reducing each conjunctive probability to a conditional probability and a smaller conjunction

$$P(x_1, \dots, x_n) = P(x_n | x_{n-1}, \dots, x_1) P(x_{n-1} | x_{n-2}, \dots, x_1) \dots P(x_2 | x_1) P(x_1)$$

$$P(x_1, \dots, x_n) = \pi_{i=1}^n P(x_i | x_{i-1}, \dots, x_1)$$

Chain Rule

This specification of joint distribution is equivalent to

$$P(X_1, \dots, X_n) = \pi_{i=1}^n P(X_i | \text{Parents}(X_i))$$

provided $\text{Parents}(X_i) \subseteq \{X_1, \dots, X_{i-1}\}$

Take care of the node ordering while constructing the network.

Constructing Bayesian networks

- Determine the set of variables, choose an ordering of variables X_1, \dots, X_n (if causes precede effects, this will result in compact network)
- For $i = 1$ to n
 - add X_i to the network
 - select parents from X_1, \dots, X_{i-1} such that

$$\mathbf{P}(X_i \mid \text{Parents}(X_i)) = \mathbf{P}(X_i \mid X_1, \dots, X_{i-1})$$

this choice of parents guarantees:

$$\begin{aligned}\mathbf{P}(X_1, \dots, X_n) &= \pi_{i=1} \mathbf{P}(X_i \mid X_1, \dots, X_{i-1}) \text{ (chain rule)} \\ &= \pi_{i=1} \mathbf{P}(X_i \mid \text{Parents}(X_i)) \text{ (by construction)}\end{aligned}$$

- for each parent insert a link from parent to X_i
- CPTs: write down the conditional probability table, $\pi \mathbf{P}(X_i \mid \text{Parents}(X_i))$

Example

- Suppose we choose the ordering M, J, A, B, E

Wrong
ordering??

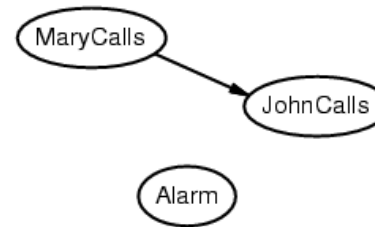
MaryCalls

JohnCalls

$$P(J \mid M) = P(J)?$$

Example

- Suppose we choose the ordering M, J, A, B, E



$$P(J \mid M) = P(J)?$$

No

$$P(A \mid J, M) = P(A)?$$

Example

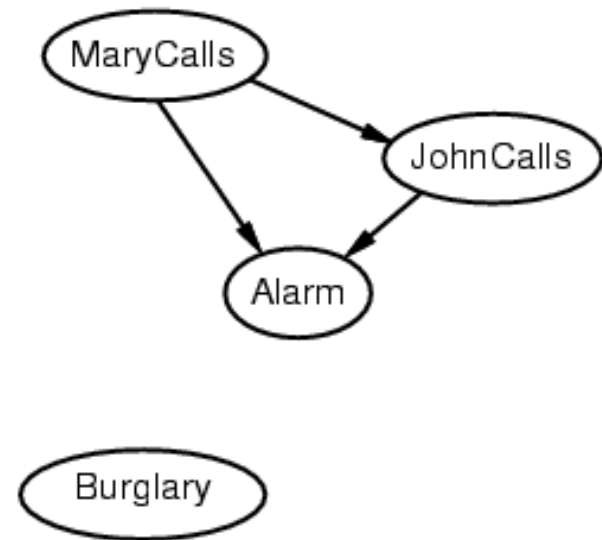
- Suppose we choose the ordering M, J, A, B, E

$P(J \mid M) = P(J)$? **No**

$P(A \mid J, M) = P(A)$? **No**

$P(B \mid A, J, M) = P(B \mid A)$?

$P(B \mid A, J, M) = P(B)$?



Example

- Suppose we choose the ordering M, J, A, B, E

$$P(J \mid M) = P(J)?$$

No

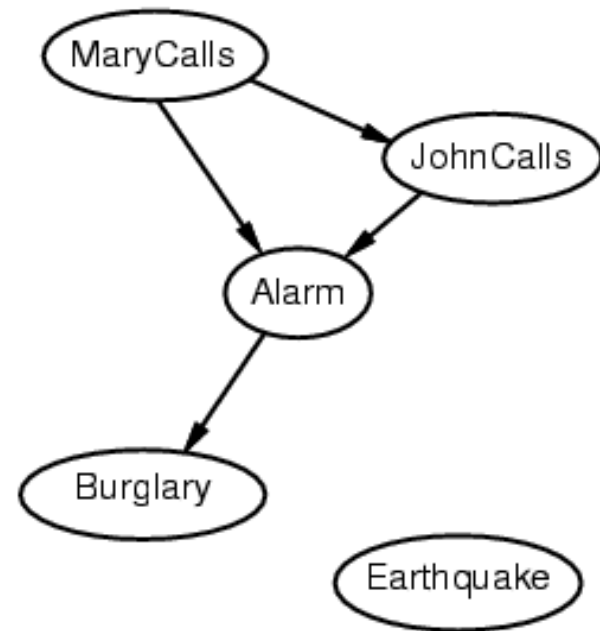
$$P(A \mid J, M) = P(A)?$$
 No

$$P(B \mid A, J, M) = P(B \mid A)?$$
 Yes

$$P(B \mid A, J, M) = P(B)?$$
 No

$$P(E \mid B, A, J, M) = P(E \mid A)?$$

$$P(E \mid B, A, J, M) = P(E \mid A, B)?$$



Example

- Suppose we choose the ordering M, J, A, B, E

$$P(J \mid M) = P(J)?$$

No

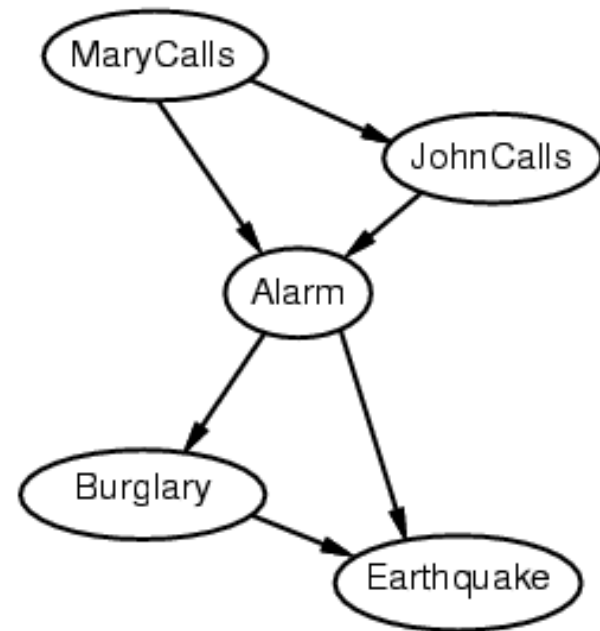
$$P(A \mid J, M) = P(A)? \text{ No}$$

$$P(B \mid A, J, M) = P(B \mid A)? \text{ Yes}$$

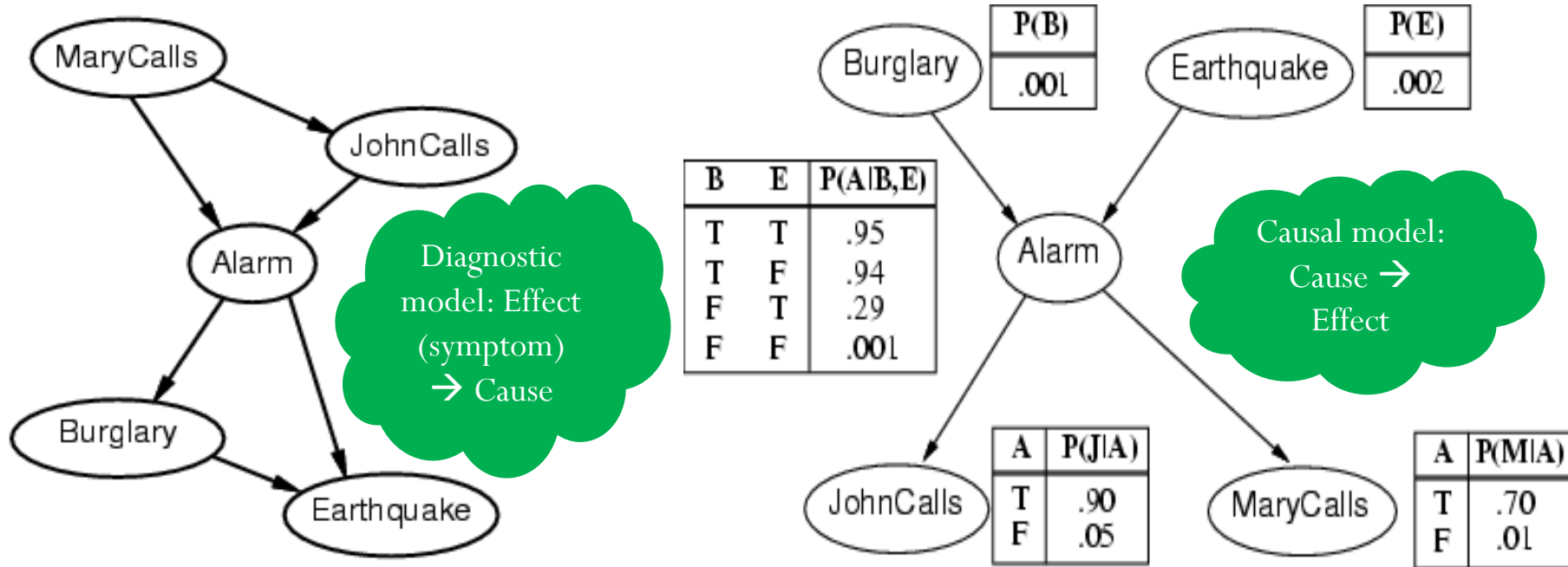
$$P(B \mid A, J, M) = P(B)? \text{ No}$$

$$P(E \mid B, A, J, M) = P(E \mid A)? \text{ No}$$

$$P(E \mid B, A, J, M) = P(E \mid A, B)? \text{ Yes}$$



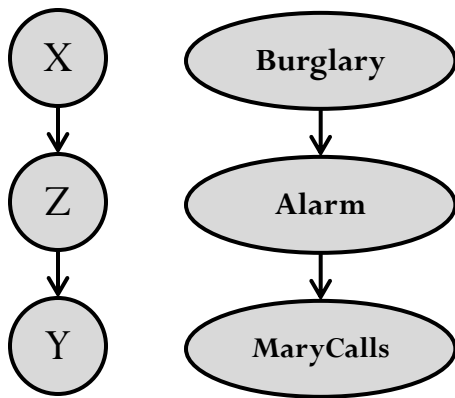
Example contd.



- Resulting network has two more links, requires three more probabilities to be specified: Network is less compact: $1 + 2 + 4 + 2 + 4 = 13$ numbers needed
- Deciding conditional independence is hard in noncausal directions

Conditional Independence

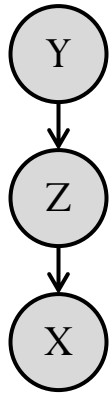
- Can we find all the independences of a BN by inspecting its structure (from the graph)?
- Let us first see a three-node network where variables X and Y are connected via third variable Z in four different ways and we will try to understand when an observation regarding a variable X can possibly change our beliefs about Y, in the presence of evidence variable Z.
- Forward serial connection (Causal trail - active iff Z is not observed)



- When Z is not instantiated (its truth value is not known variable is not observed) X can influence Y via Z (having observed X will tell something about Y).
- When Z is instantiated then X cannot influence Y (if we observe Z then knowing about X will not tell anything new about Y).

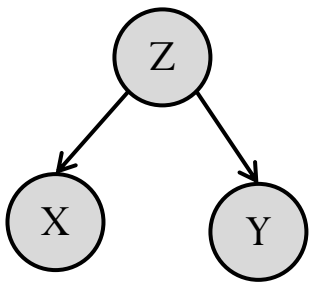
Conditional Independence

- Backward serial connection (evidential trail- active iff Z is not observed)

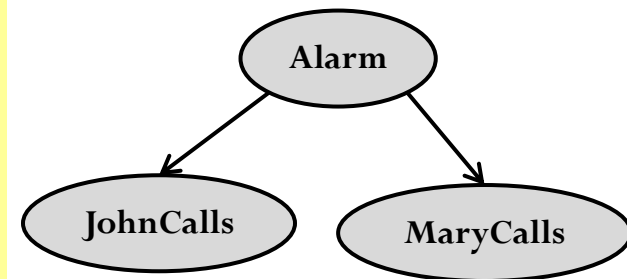


- When Z is not instantiated Y can influence X via Z (knowing about Y will tell something about X).
- When Z is instantiated then Y cannot influence X (if we observe Z then knowing about Y will not tell anything new about X).

- Diverging connection (Common cause- active iff Z is not observed)

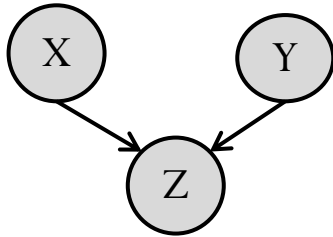


- Similar to previous two cases: X can influence Y via Z if and only if Z is not observed.
- In other words, if we know Z (or observe Z), then knowing about X will not give us any additional information about

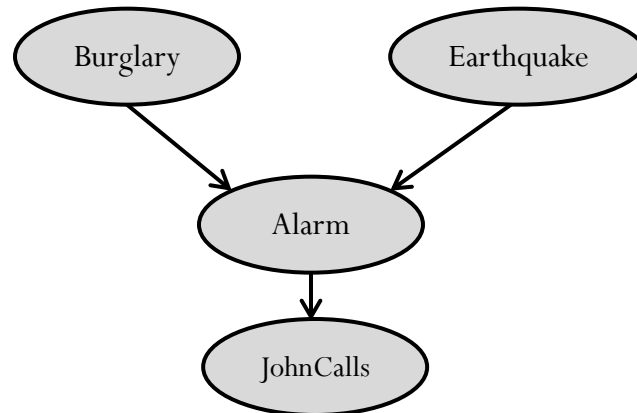
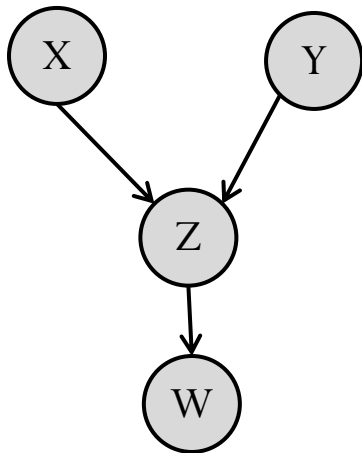


Conditional Independence

- **Converging connection** (Common effect- active iff either Z or one of Z's descendants is observed)

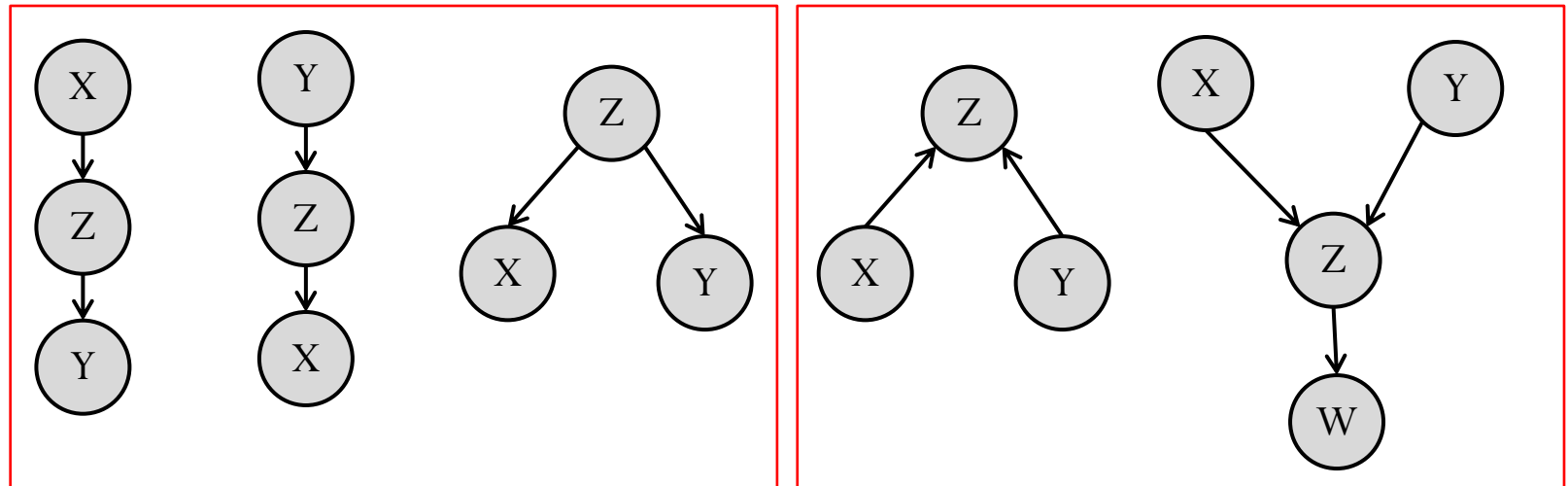


- X can influence Y only if Z or descendant of Z is instantiated.
- Without observing Z, knowing X does not tell anything about Y.
- When either node Z is instantiated, or one of its descendants is, then we know something about whether Z, and in that case information does propagate through from X to Y.



Conditional Independence

- Serial connections and diverging connections are essentially the same.



- General case:** Considering longer trail $X_1 \Rightarrow \dots \Rightarrow X_n$, for influence to “flow” from X_1 to X_n , it needs to flow through every single node on the trail.
- When multiple trails are there between two nodes then one node can influence another if there is any trail along which influence can flow.

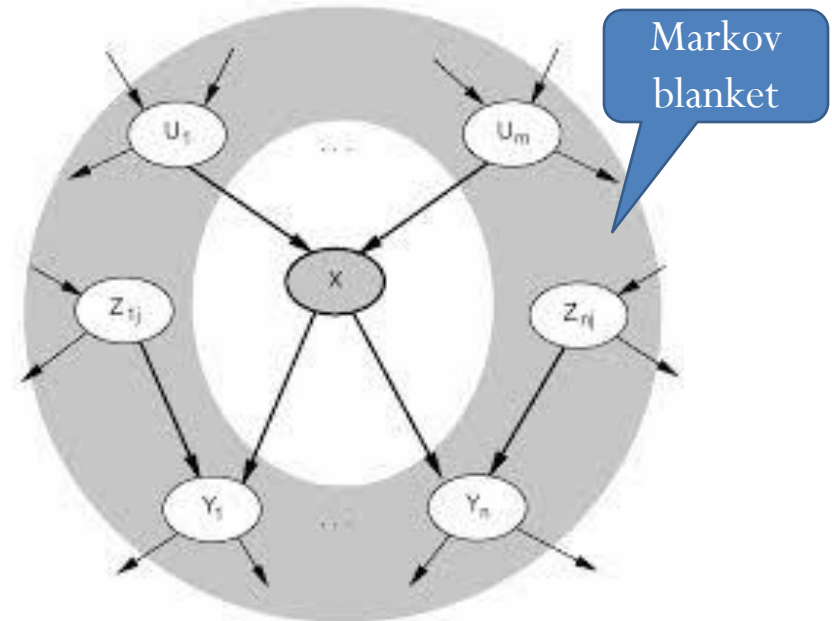
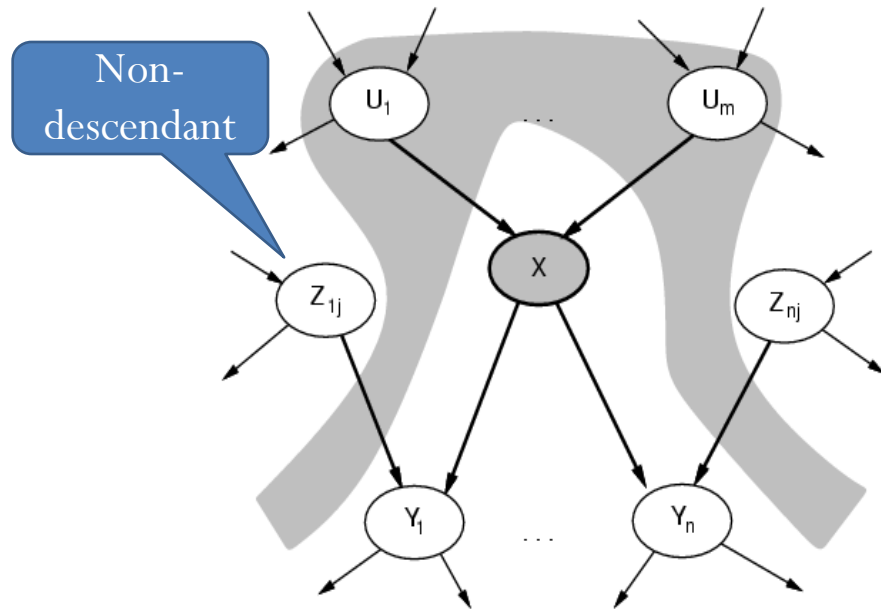
Conditional Independence

- **d-separation (directed separation)**: provides a notion of separation between nodes in a directed graph.
 - Variables X and Y are d-separated iff for every trail between them, there is an intermediate variable Z such that either
 - Z is in a serial or diverging connection and Z is known (observed).
 - Z is in converging connection and neither Z nor any of Z 's descendants are known.
 - Two variables X and Y are d-connected if they are not d-separated.
 - If variables X and Y are d-separated by Z then, X and Y are **conditionally independent** given Z .
- **Definition:** Let X, Y, Z be three sets of nodes in G (BN structure). We say that X and Y are d-separated given Z , denoted **$dsep(X; Y|Z)$** , if there is no active trail between any node $X \in X$ and $Y \in Y$ given Z .
 - Let $I(G)$ denote the set of independencies that correspond to d-separation:

$$I(G) = \{X \perp Y|Z : dsep(X; Y|Z)\}$$

This set is also called the set of global **Markov independencies**.

Conditional Independence relations



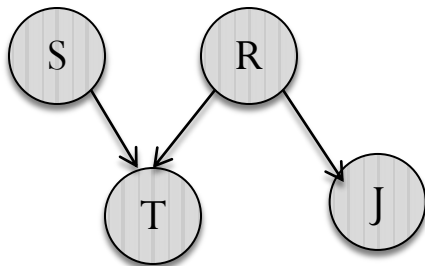
- Each node is conditionally independent of its non-descendants, given its parents.
- Each node is conditionally independent of all others given its Markov blanket: parents+children+children's parents

Conditional Independence

- **Example:** One morning Tracey leaves her house and realise that her grass is wet. Is it due to overnight rain or did she forget to turn off the sprinkler last night?
- Next she notices that the grass of her neighbour, Jack, is also wet.
- This **explains away** to some extent the possibility that her sprinkler was left on, and she concludes therefore that it is probably been raining (it decreases her belief that the sprinkler is on).
- Using the following four propositional random variables, construct the BN and determine if S is d-separated from J when T is known.
 - R: Rain $\in \{0,1\}$ (Rain = 1 means that it has been raining, and 0 otherwise)
 - S: Sprinkler $\in \{0,1\}$
 - J: Jack's grass wet $\in \{0,1\}$
 - T: Tracy's Grass wet

Conditional Independence

- Four propositional random variables are:
 - R: Rain $\in \{0,1\}$ (Rain = 1 means that it has been raining, and 0 otherwise)
 - S: Sprinkler $\in \{0,1\}$
 - J: Jack's grass wet $\in \{0,1\}$
 - T: Tracy's Grass wet



- The trail between S and J: S-T-R-J
- S-T-R converging connection and T is known so influence flows from S to R.
- T-R-J diverging connection and R is not known so influence flows from T to J.
- So, S and J are not d-separated given T

What did we discuss in L3?

- What is knowledge, representation, and reasoning?
- What is uncertainty and reasoning under uncertainty?
- Under what situations does logic fail and how Probability theory can be useful in such situations?
- What kind of uncertainty is handled by Bayesian Probability?
- How Bayesian Networks can be used to represent knowledge under uncertainty?
- How to construct a Bayesian network?
- How to identify conditional independence relations from the structure of BNs?