

# A Minimum Ionospheric Model (MIM) for LOFAR

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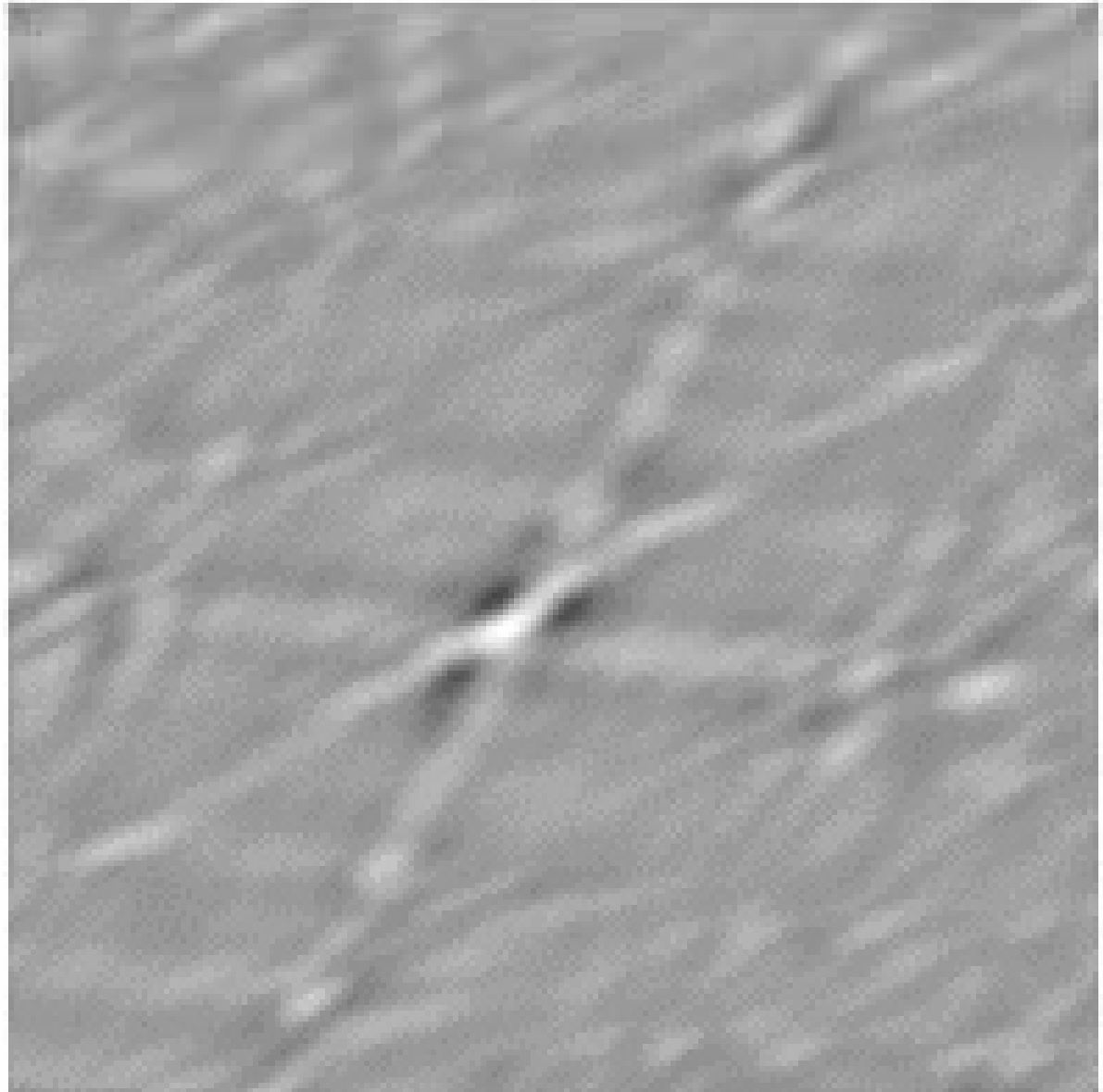


# The LOFAR challenge

- Pathological Ionosphere (1 rad / 10 sec)
  - Affects source subtraction and imaging
- (Very) crowded fields
  - Source confusion
  - PSF sidelobe confusion: increases noise
- Unstable station beam shapes
  - Affects source subtraction and imaging
- High station side-lobes
  - Bright sources (incl galactic plane and Sun)

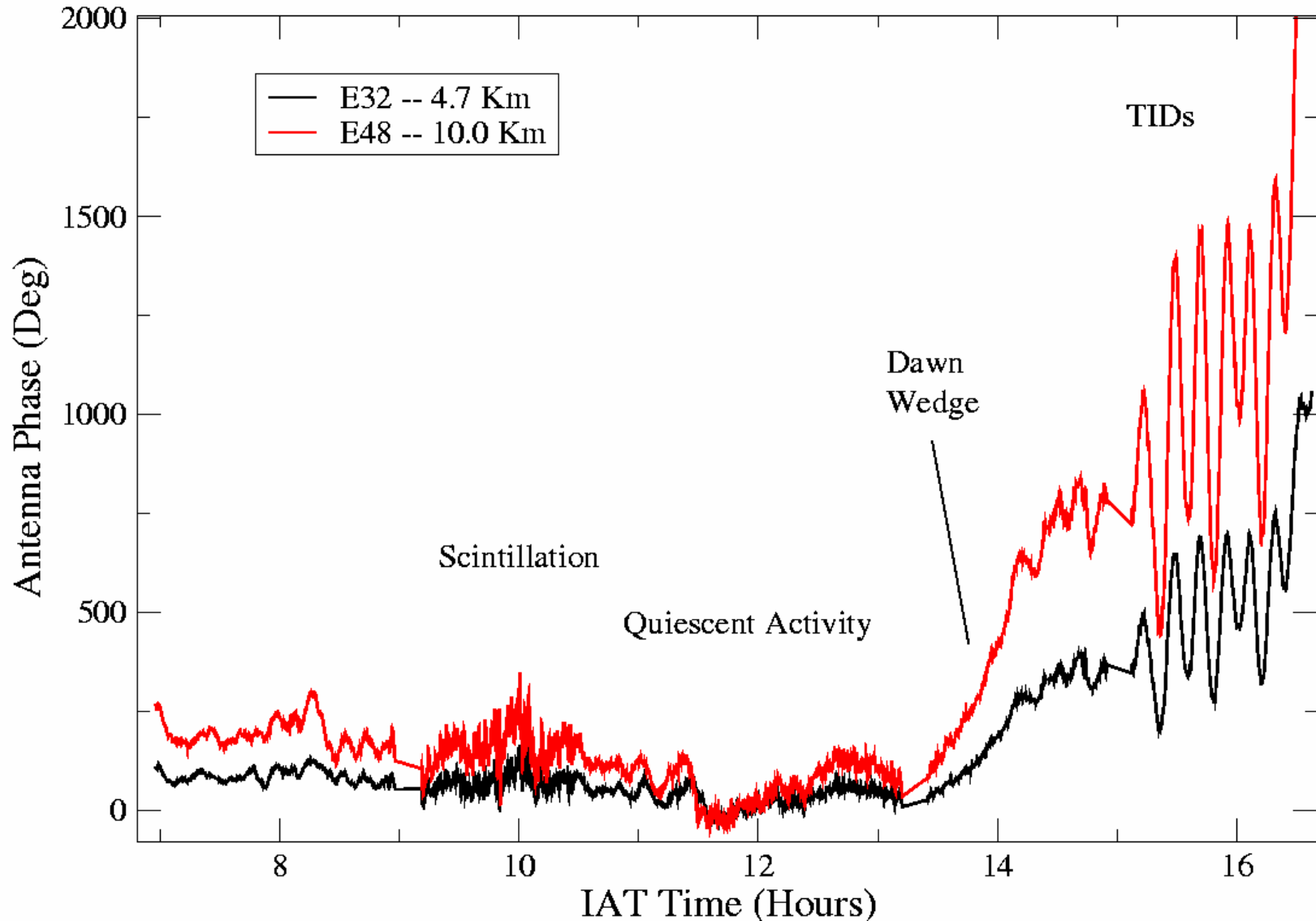
# Virgo A, VLA 74 MHz

~1 degr



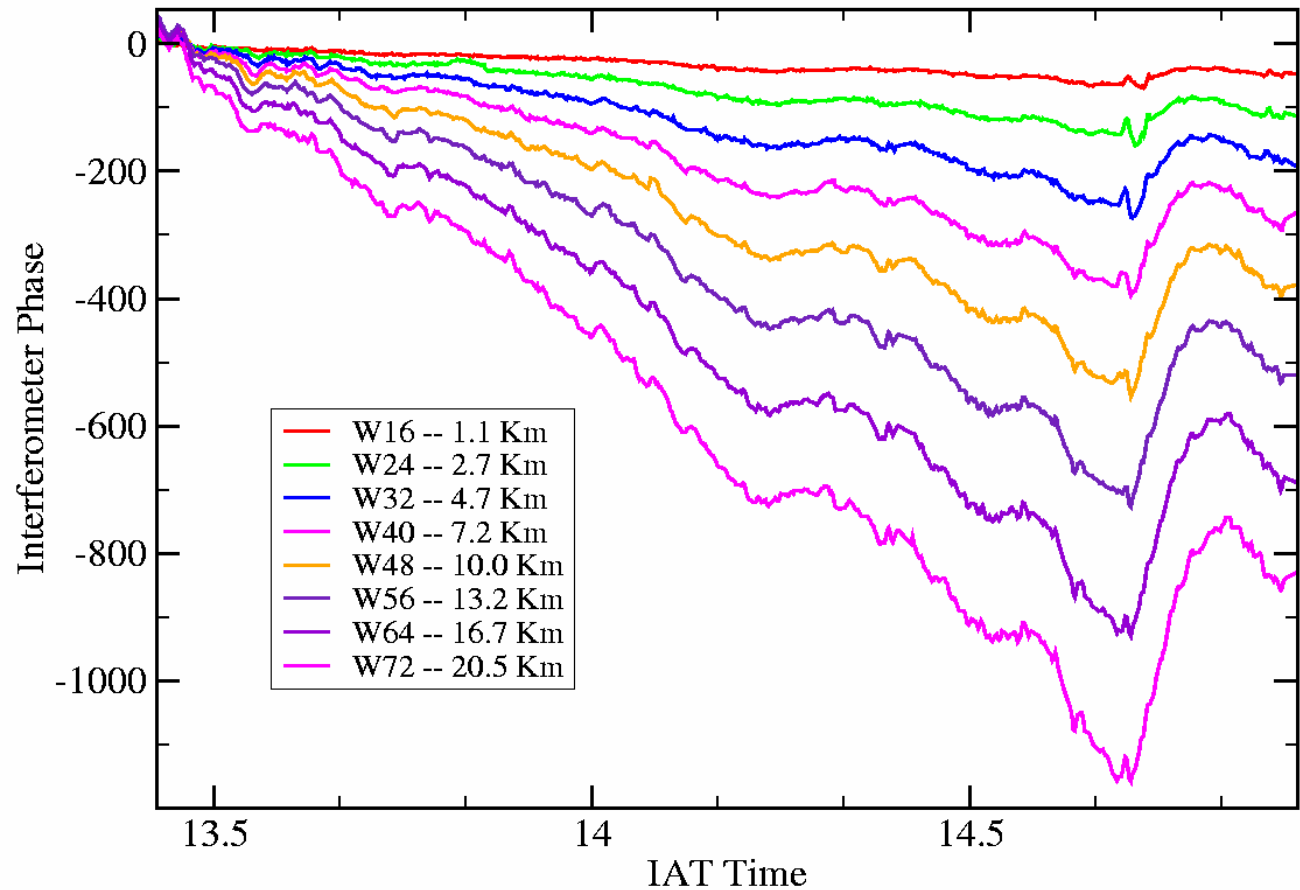
Courtesy Rick Perley (NRAO), Gary Bust (ARL, U.TX)

# Virgo A: ionospheric phase



# Virgo A: Dawn Wedge Phase

All antennas on West Arm during 'Dawn Wedge' period.



This shows a thickening wedge over the array which started about 1 hour before dawn, and was terminated by the onset of a large wave event.

# Comparable to, but easier than, adaptive optics

- Mostly large-scale motion
  - ‘Seeing-cell’ larger than field-of-view
  - Source images do not ‘break up’ so much
- More reference sources available
  - 10-50 bright sources per field
  - $\text{SNR} > 3$  in 10 sec
- But: we can learn from each other

# Evolutionary path to MIM

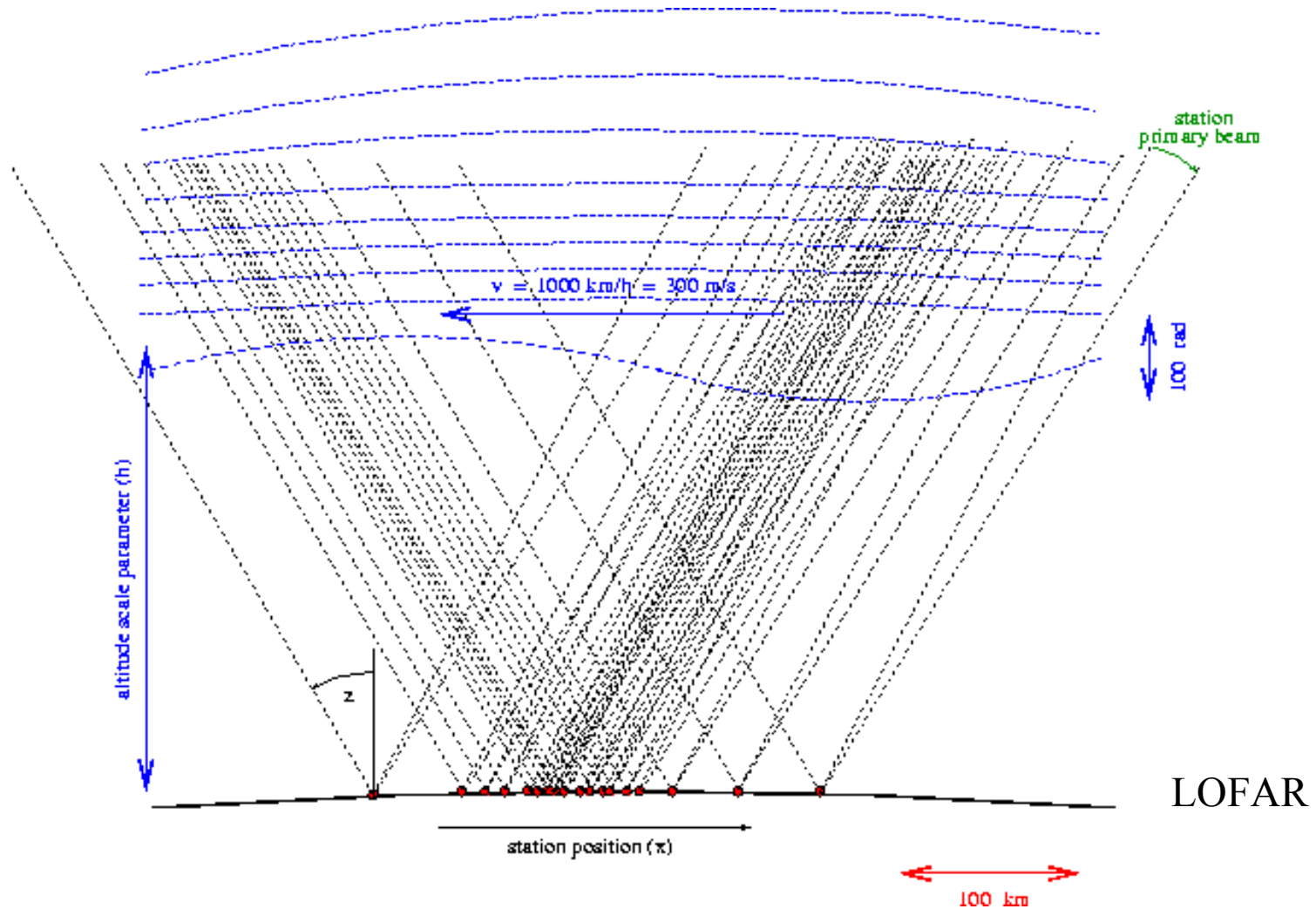
- 2001: Independent 2D phase-screen for each station beam ( $\sim 10$ -20 parameters each): Barely enough bright calibrators.
- 2003: *Peeling* brings the realisation that fainter sources may be used too, provided their phase excursions are limited by tracking
- WSRT LFFE: solving for phase gradients only
- Global MIM drastically reduces the nr of parameters, and thus the nr of calibrators

# Minimum Ionospheric Model (MIM)

- Minimum nr of parameters (few bright sources available, sometimes none)
- Only deal with observables (not interested in internal structure of ionosphere)
- Assume large-scale ( $>100$  km) structure and go progressively smaller, until ....



# Ionospheric blanket with many piercing points



# Step 1: zenith model

**Excess path** in zenith direction ( $z=0$ ):

$$L_0(f) = -40.3 \times (100/f)^2 \times \text{TEC} \quad \text{m}$$

$$\text{Typical: } \text{TEC}=5 \rightarrow L_0(100\text{MHz}) = -200 \text{ m}$$

As a function of station position ( $x$ ):

$$L_1(x) = L_0 (1 + p_1 x + p_2 x^2 + p_3 x^3 + \dots)$$

$$p_k = p_k(t)$$

## Step 2: zenith angle

$$L_2(x,z) = L_1(x) (x - h \tan(z)) S(z)$$

$$S(z) = 1/\cos(\arcsin(R\sin(z)/(R+h)))$$

Earth radius  $R$  and ionospheric ‘altitude’  $h$

NB: The altitude parameter  $h$  ( $\sim 300$  km) is just a coupling constant that introduces  $z$ -dependency. An incorrect value will be absorbed in the estimated values of the coefficients  $p_k$ .

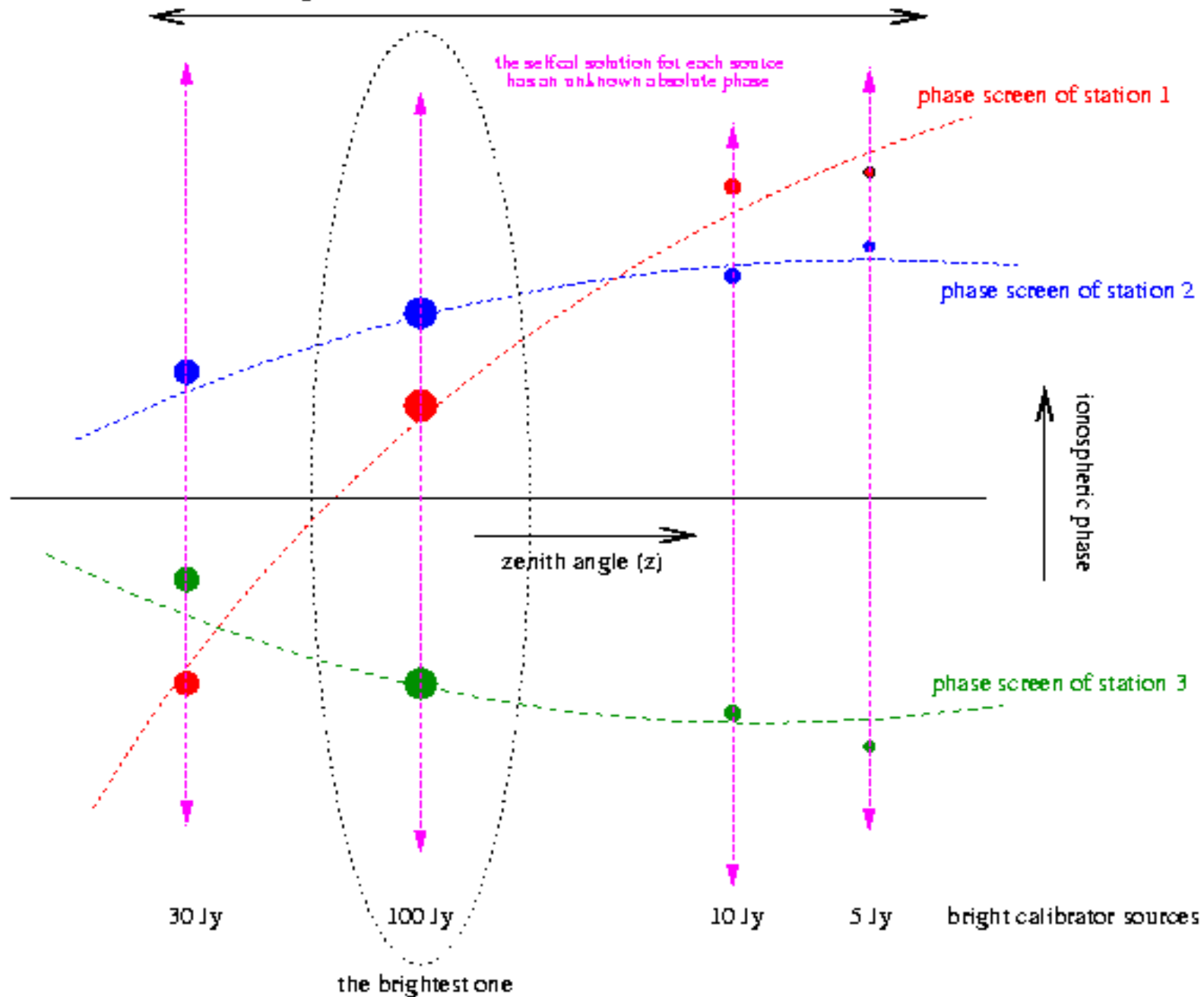
## Step 3: 2D sky frame

$$\begin{aligned} L_1(x, z) &\longrightarrow L_1(x, y, z_{\text{North}}, z_{\text{East}}) \\ &\longrightarrow L_1(x, y, \text{RA}, \text{DEC}) \end{aligned}$$

So, given the MIM parameters  $(p_k(t), h)$  we can calculate the *absolute* ionospheric phase from an arbitrary station  $(x, y)$ , in the direction  $(\text{RA}, \text{DEC})$  of an arbitrary point in the sky.

Note the tiny nr of parameters: typically  $< 20$

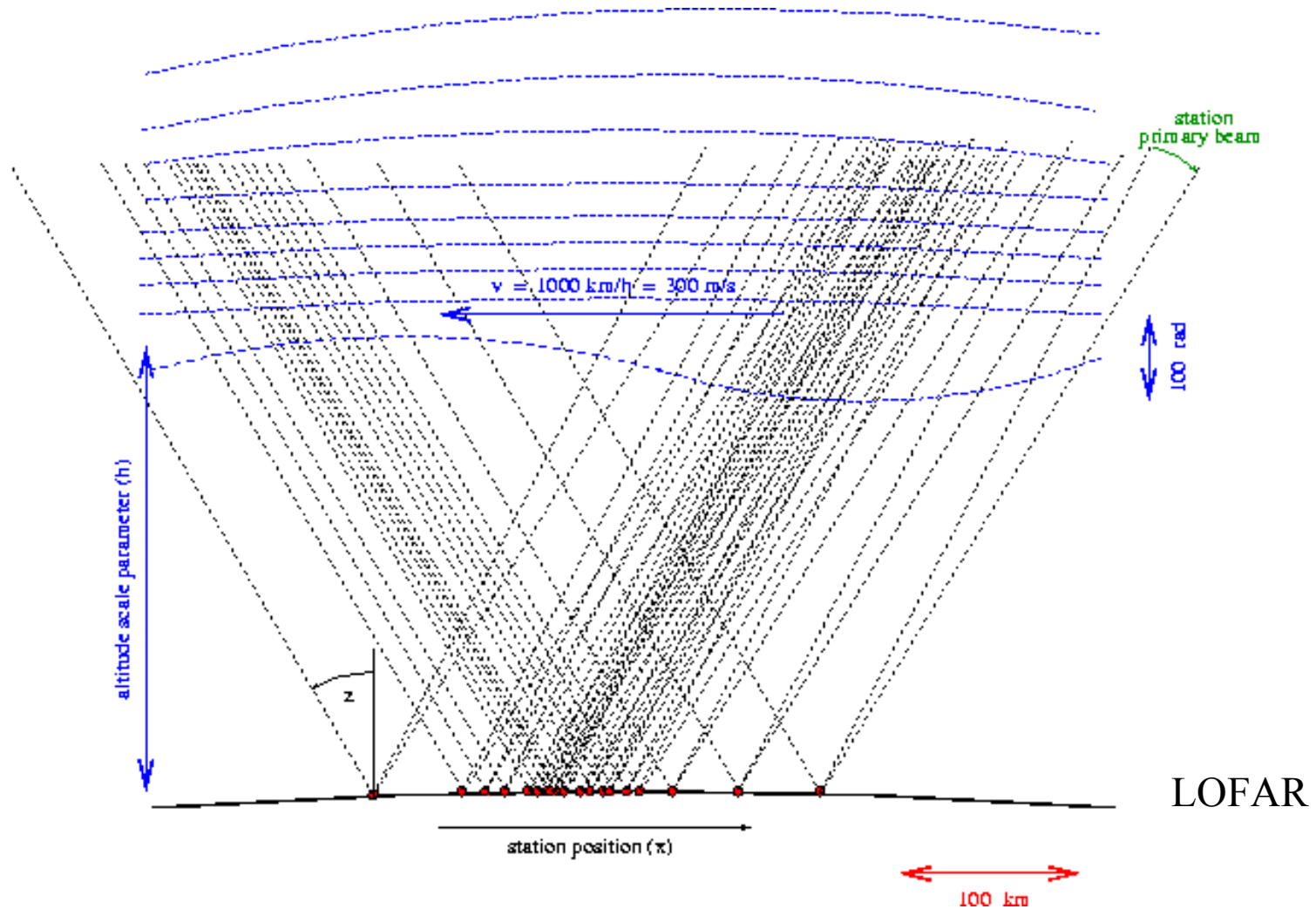
5 deg = 0.1 rad = 30 km @ 300 km altitude (z=0)



# Procedure

- Do phase selfcal on the brightest source in the main lobe of the station beam
- Estimate 10-20 MIM parameters ( $h, p_k$ ) from  $N_{\text{station}}$  phases. Remove  $2\pi$  ambiguities by minimising the internal inconsistency.
- Use the remaining inconsistency to determine whether to add or remove MIM parameters.

# Ionospheric blanket with many piercing points



# A plethora of possibilities...

- Include other calibrators in the field (main lobe)
- Include calibrators in different LOFAR beams to get greater sky coverage
- Include calibrators in the side-lobes
- Use MIM to track the ionosphere during the observation (within a radian, or better)



# Main lobe and side-lobes

- How to separate phases due to the voltage beam and the ionospheric?
- Main lobe: differential (except for beam shape differences): negligible?
- Far side-lobes: Calibrator may be in different sidelobes:  $\pi$  jumps
- Zeroes...

# Use of moving 'frozen' pattern?

- Does not seem very useful...

# Gain effects (scintillation)

- Focussing effect (10 km blobs). Rare.
- Distinguish from sidelobe gain
- Straightforward MIM extension...

# Faraday rotation

$$\text{TEC} = \int N_e \, dl \quad \text{m}^{-2}$$

$$\text{RM} = \int N_e \, B \cdot dl \quad \text{rad/m}^{-2}$$

- More complicated than phase:
  - Angle with Earth magnetic field
  - Integral along (curved) path
- Do we need 3D ionosphere model?
- Or can we use large-scale MIM approach?
- We need some polarised ‘anchor’ points...

# Conclusions

- MIM looks like a useful concept
- The ionosphere is a problem, but it might also be an opportunity...
- **Let's try it !**



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