

P346 (Computational Physics Lab)  
Assignment 3  
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```
[1]: import mylibrary
```

#### Question 1

```
[2]: X = []
Y = []

mat_a = open("a.txt", "r+")
#calling matrix from txt file

for row in mat_a:
    #matrix structure is applied
    y = row.split()
    x = []
    for i in range(len(y)-1):
        x.append(float(y[i]))
    X.append(x)
    z = row.split()
    Y.append(float(z[len(y)-1]))

print("The solution to the system of linear equations is:")
soln = mylibrary.applyGJ(X, Y)
print("x = " + str(mylibrary.integerRound(soln[0])))
print("y = " + str(mylibrary.integerRound(soln[1])))
print("z = " + str(mylibrary.integerRound(soln[2])))
print("w = " + str(mylibrary.integerRound(soln[3])))
```

The solution to the system of linear equations is:

x = 2  
y = 0  
z = 6  
w = 5

#### Question 2

```
[3]: M = []
N = []

mat_b = open("b.txt", "r+")
#calling matrix from txt file

for row in mat_b:
    #matrix structure is applied
```

```

y = row.split()
x = []
for i in range(len(y)-1):
    x.append(float(y[i]))
M.append(x)
z = row.split()
N.append(float(z[len(y)-1]))

print("The solution to the system of linear equations is:")
soln_2 = mylibrary.applyGJ(M, N)
print("x = " + str(mylibrary.integerRound(soln_2[0])))
print("y = " + str(mylibrary.integerRound(soln_2[1])))
print("z = " + str(mylibrary.integerRound(soln_2[2])))

```

The solution to the system of linear equations is:

```

x = 1
y = -2
z = -1

```

### Question 3

```

[4]: Q = []

mat_c = open("c.txt", "r+")
#calling matrix from txt file

for row in mat_c:
    x = row.split()
    y = []
    for i in range(len(x)):
        y.append(float(x[i]))
    Q.append(y)

print("Inverse of the matrix is: ")
Q_inv = mylibrary.inverseMatrix(Q)
mylibrary.displayMatrix(Q_inv)

```

Inverse of the matrix is:

```

[-0.33, 0.33, 0.33]
[-0.17, 0.17, 0.67]
[1.33, -0.33, -1.33]

```

```

[5]: #we check the product of Q and Q_inv
Q_orig = []
mat_c_new = open("c.txt", "r+")

for row in mat_c_new:
    x = row.split()

```

```

y = []
for i in range(len(x)):
    y.append(float(x[i]))
Q_orig.append(y)

mylibrary.displayMatrix(Q_orig)
mylibrary.displayMatrix(Q_inv)

mylibrary.productMatrix(Q_orig, Q_inv)
#this should return the identity matrix
#since we know that  $Q \cdot Q^{-1}$  should be I

```

```

[0.0, 2.0, 1.0]
[4.0, 0.0, 1.0]
[-1.0, 2.0, 0.0]
[-0.33, 0.33, 0.33]
[-0.17, 0.17, 0.67]
[1.33, -0.33, -1.33]
[1.0, 0.0, 0.0]
[0.0, 1.0, 0.0]
[0.0, 0.0, 1.0]

```

#### Question 4

```

[7]: S = []
mat_d = open("d.txt", "r+") #opening the matrix m_4.

for value in mat_d:
    x = value.split() #splitting/seperating the matrix.
    y = []
    for i in range(len(x)):
        y.append(float(x[i])) #float allows decimal values.
    S.append(y)

print("Determinant of given matrix is:")
mylibrary.findDeterminant(S)

```

```

Determinant of given matrix is:
65.0

```