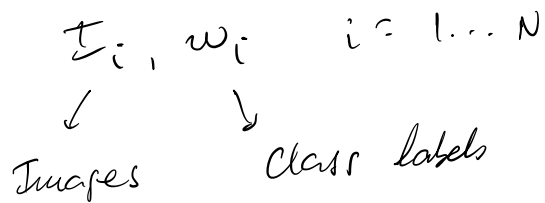
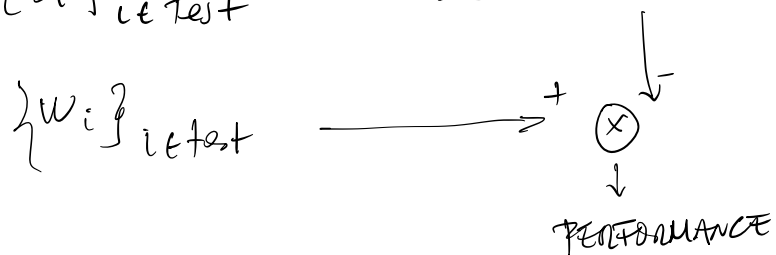
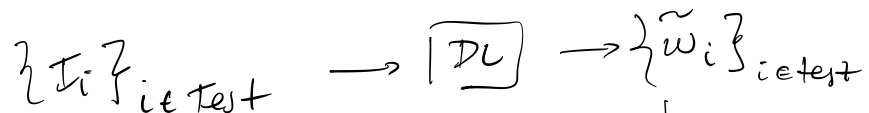


IMAGE DATASET - CLASSIFICATION



1. TRAIN A **DL CLASSIFICATION** - CNN ARCHITECTURE



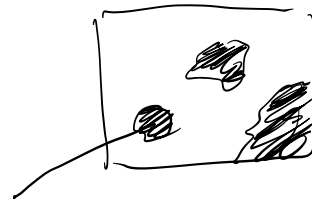
2. APPLY A **DL INTERPRETABILITY** TECHNIQUE
 $\{\text{GRAD-CAM}, \text{Activation-Maximization}, \text{Saliency maps}\}$
IN ORDER TO OBTAIN AN INTERPRETABILITY
HEATMAP



USE AN OTSU/MANUAL THRESHOLDING TO
 BINARIZE THE INTERPRETABILITY HEATMAP
 ('1' - REGIONS RELEVANT FOR THE PC CLASSIFIER
 '0' - REGIONS NOT RELEVANT)

$$H_i \rightarrow \boxed{\text{OTSU}} \rightarrow BH_i$$

BINARY HEATMAP

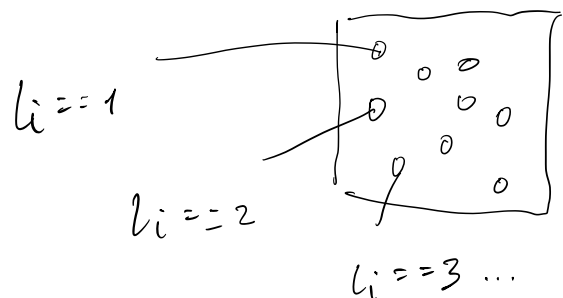


'1's: relevant regions

3. APPLY AN OBJECT SEGMENTATION METHOD TO I_i
 IN ORDER TO IDENTIFY RELEVANT STRUCTURES

$$I_i \rightarrow \boxed{\text{SEGMENTATION}} \rightarrow L_i$$

segmented/
labelled
Image



A TOTAL OF N_i OBJECTS
 ARE FOUND

4. EXTRACT REGIONAL ATTRIBUTES FROM THE SEGMENTED REGIONS:

	OBJECT	FEATURES
- SHAPE		
- AREA/PETE	→ 1	$f_{11} f_{12} \dots f_{1m}$
- TEXTURE	2	$f_{21} f_{22} \dots f_{2m}$
- ORIENTATION ...	3	
	...	
	N_i	$f_{N_i 1} \dots f_{N_i m}$

A TOTAL OF m FEATURES ARE EXTRACTED

DATA MATRIX

f_{ij}
 object \ feature
 ($N_i \times m$)

5. ASSIGN A CLASS LABEL 'H' OR 'L' TO EACH OBJECT ACCORDING TO THE LOCATION OF THE CENTROID OF THE OBJECT IN THE BINARY HEATMAP:

OBJECTS LOCATED IN $BH == 1 \rightarrow$ 'H'

OBJECTS LOCATED IN $BH == 0 \rightarrow$ 'L'

↓

INTERPRETABILITY CLASS VECTOR

$$\vec{\Phi} = \{ \Phi_1, \dots, \Phi_{N_i} \}$$

$$\Phi_i \in \{H, L\}$$

6. CONSTRUCT A CLASSIFICATION DATABASE
WITH OBJECT FEATURES & OBJECT INTERPRETABILITY
CLASS LABELS :

object	f_1	f_2	$f_3 \dots$	f_m	de interpretability class label
1	f_{11}	f_{12}	\dots	f_{1m}	ϕ_1
2	\dots				
\vdots					
N_i	$f_{N_i 1}$	\dots	\dots	$f_{N_i m}$	ϕ_{N_i}

→ X
DATABASE

7. TRAIN A **DECISION TREE** WITH THE
DATABASE X.

THE STRUCTURE OF THE TREE WILL REVEAL
WHICH FEATURES ARE MORE RELEVANT
IN ORDER TO DISTINGUISH BETWEEN
RELEVANT & NON-RELEVANT REGIONS.