

T1.1 → Intro data analysis & ML

T1.2 → CLUSTERING ALGORITHMS

↳ k-means

↳ Hierarchical clustering

↳ Gaussian Mixture Models (GMM)

- Model selection
- Parameter estimation in probabilistic models.

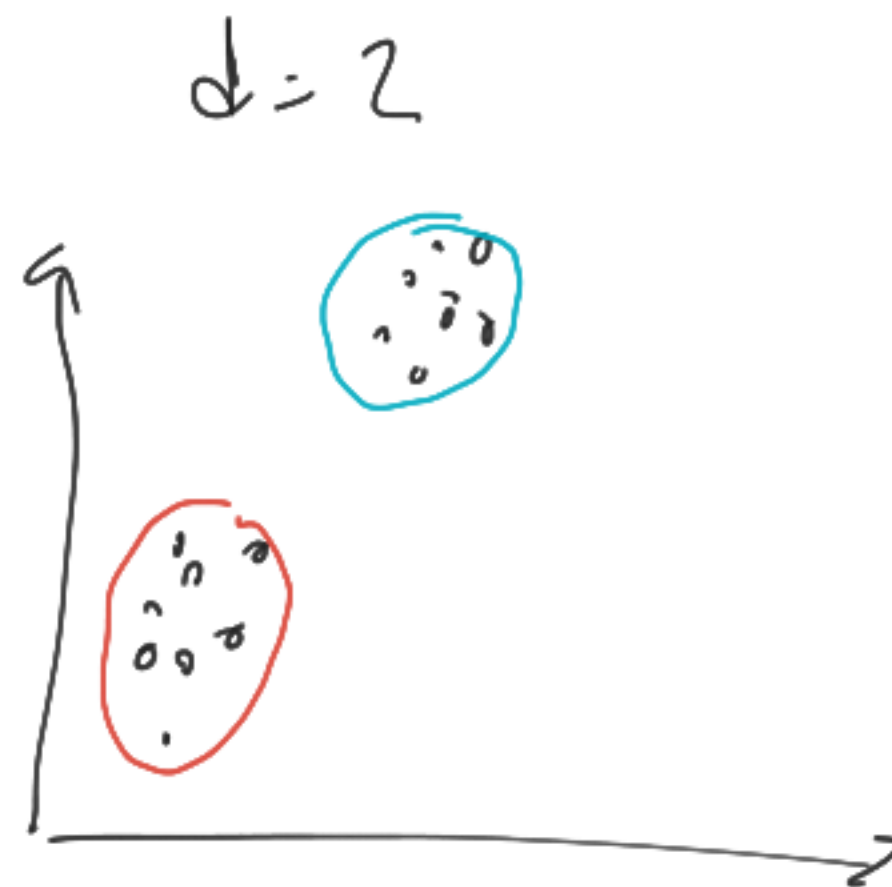
# CLUSTERING

d-dimensional feature space  $\vec{x} \in \mathbb{R}^d$

From a set of observations

$$\{\vec{x}_1, \vec{x}_2, \vec{x}_3, \dots, \vec{x}_N\}$$

UNSUPERVISED METHODS !



DATA ML



CLASS MEMBERSHIP OF  
EACH OBSERVATION

✓ data matrix  
observations  $\times$  features

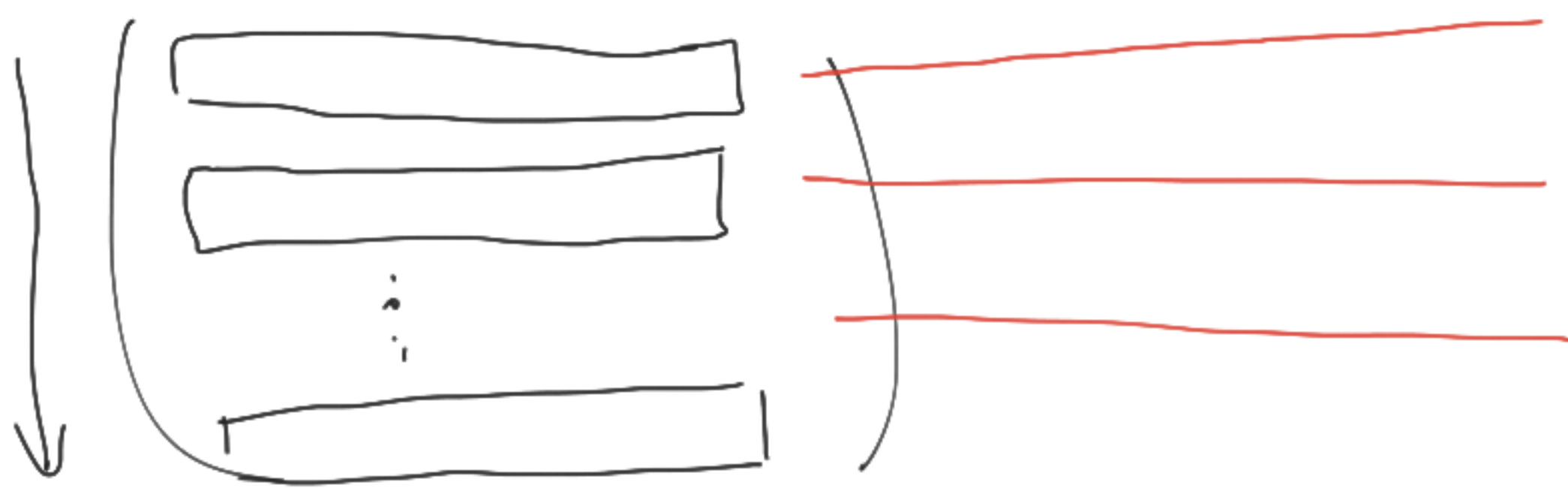
$w_j \quad j = 1 \dots \text{NOBS}$

$w_1 = \text{'FCB supporter'}$

$w_2 = \text{'other team'}$

$w_3 = \text{'other team'}$   
 $\vdots$

$w = \{ \text{'FCB supporter'}, \text{'other team'} \}$



features | variable | attributes

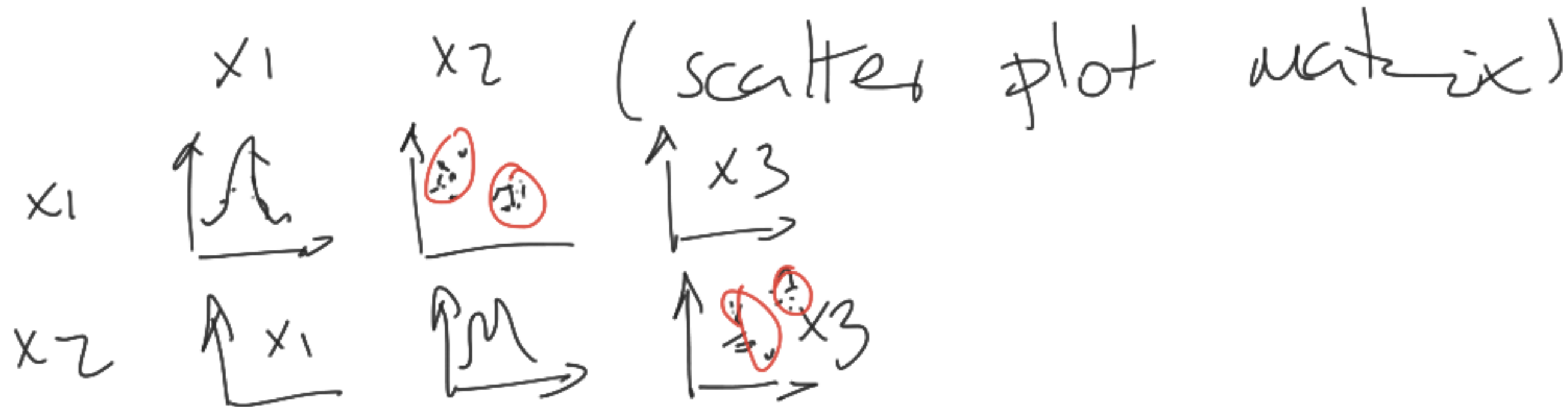
data matrix  $\longrightarrow$  unsupervised techniques

$\left\{ \begin{array}{l} \text{data matrix} \\ \text{class-label vector} \end{array} \right. \longrightarrow \text{supervised techniques}$   
 $\downarrow$   
TRAIN / FITTING / LEARNING  
(ML)

k-means  $\rightarrow$  require pre-define # clusters  
hierarchical to be found in data

2d  $\rightarrow$  easy

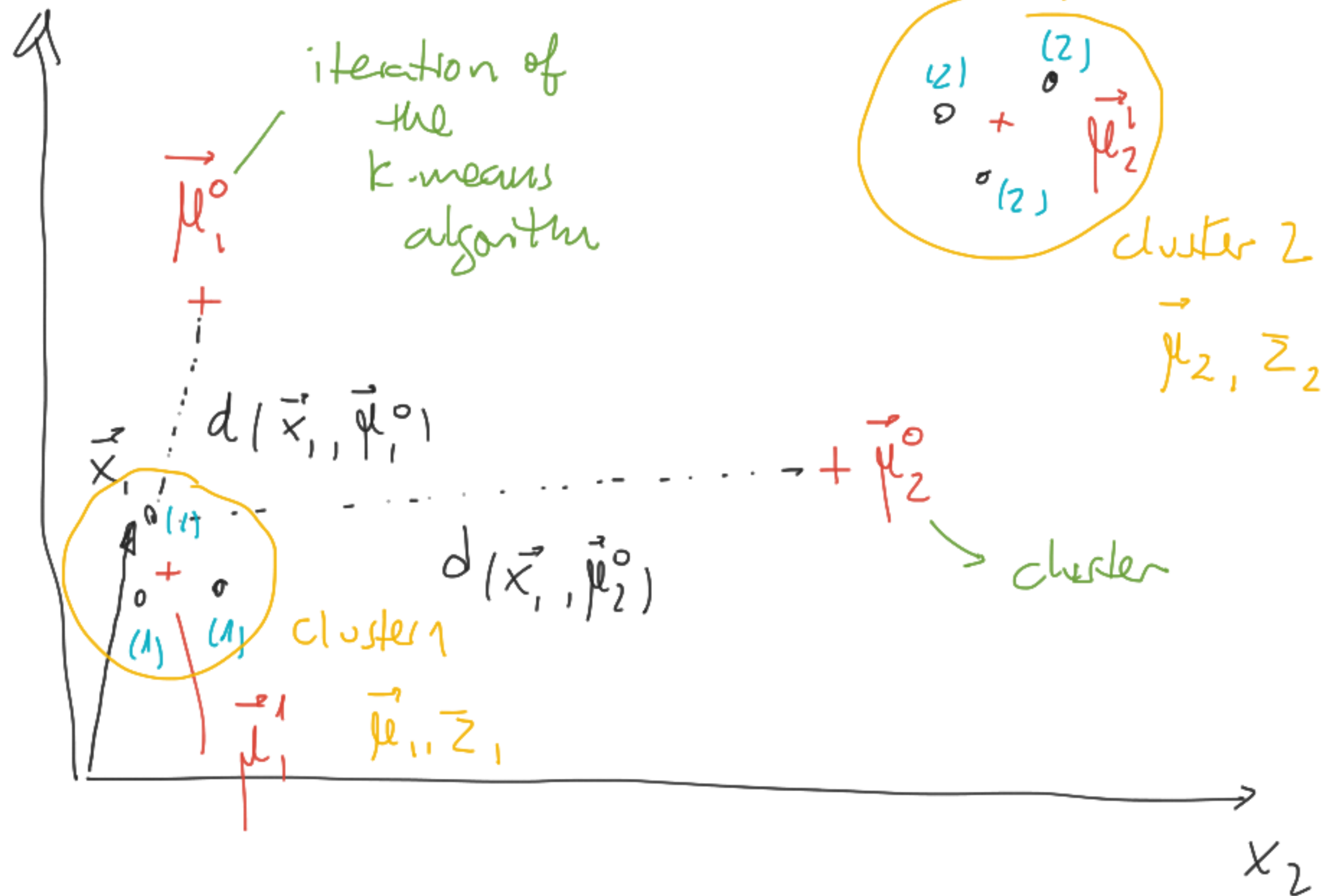
$> 2d$   $\rightarrow$  plot data using a pairplot



k-means  $x_1$

$$d = 2$$

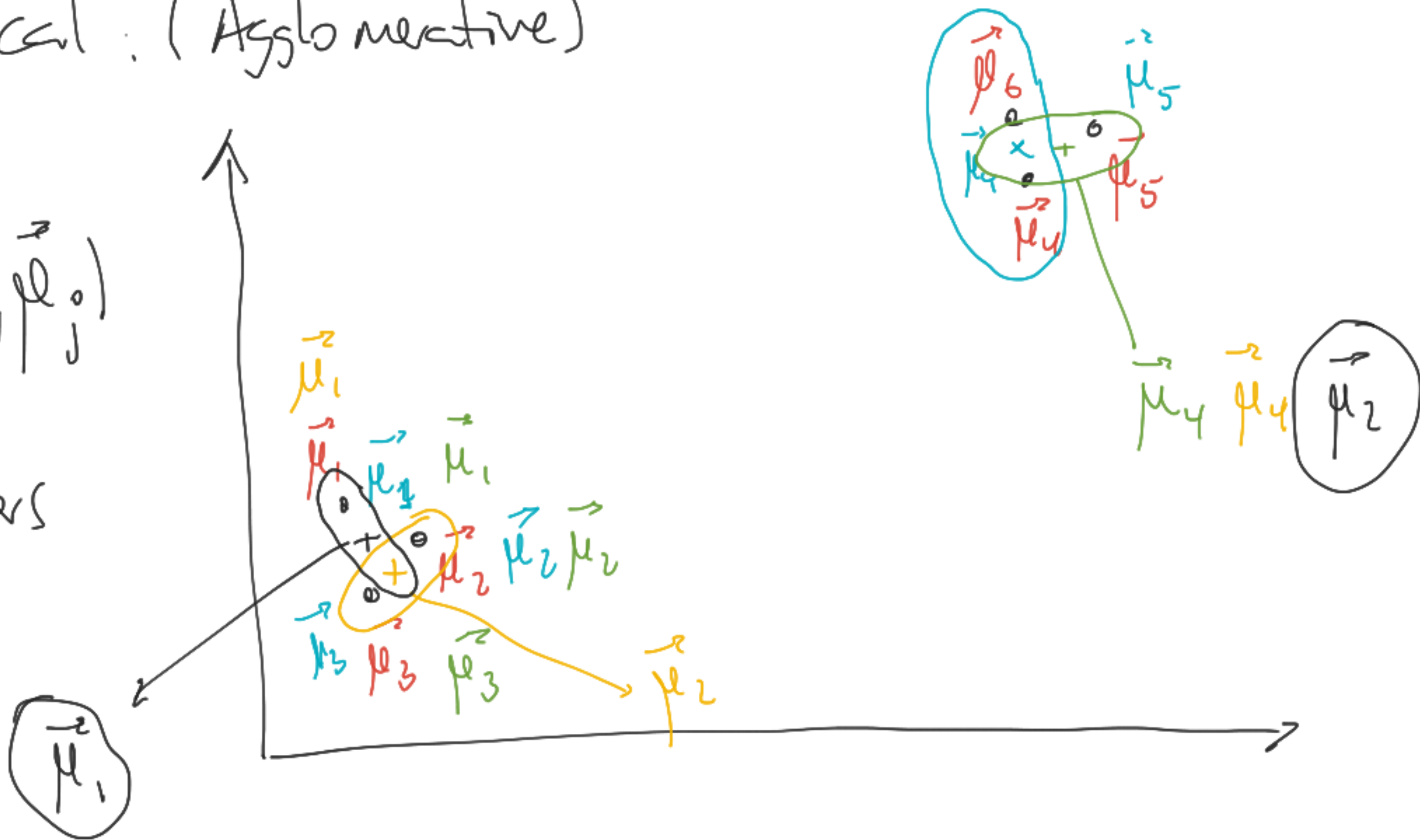
$$\vec{\mu}_1, \vec{\mu}_2^0$$

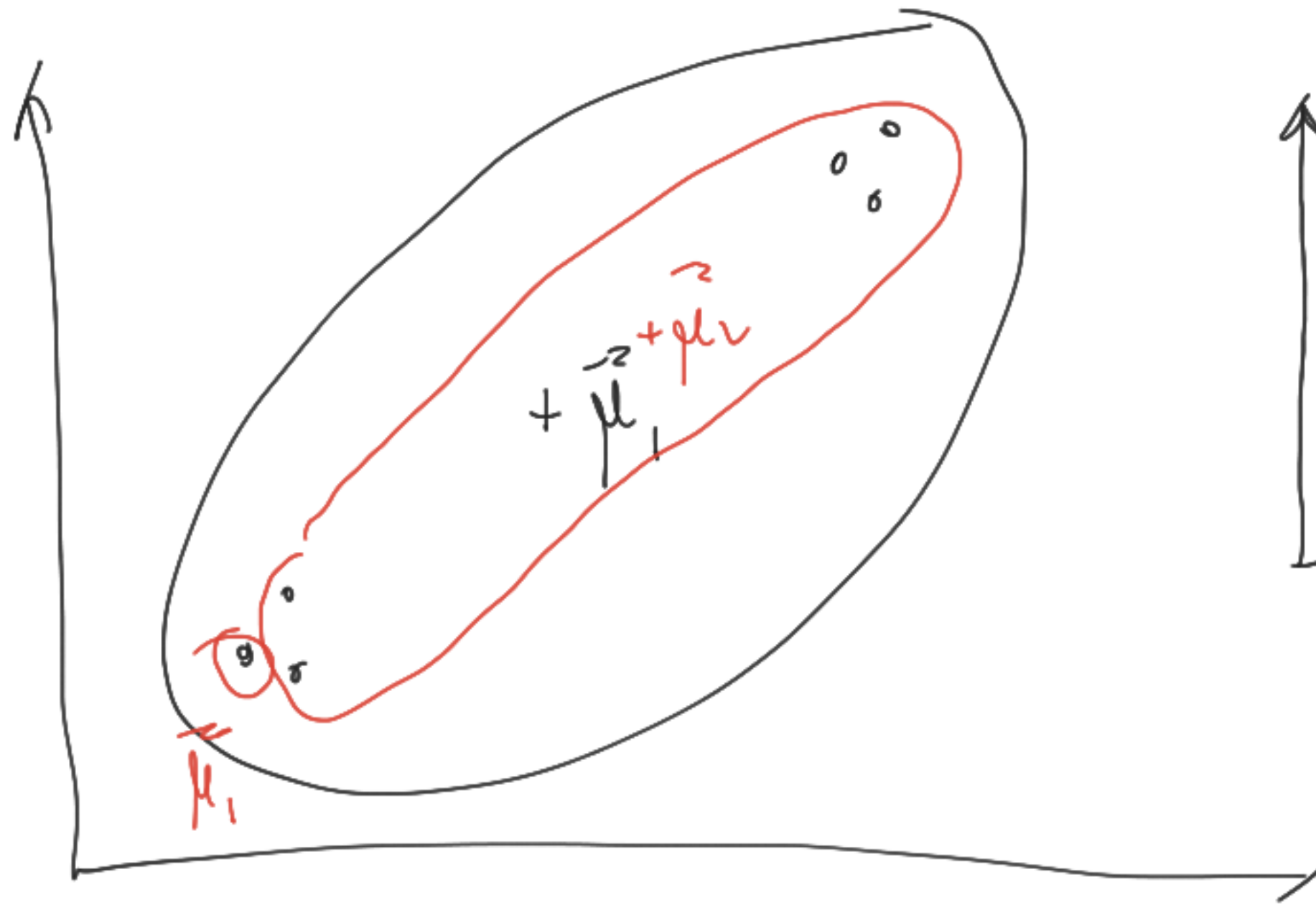


hierarchical : (Agglomerative)

$$\text{pdist}(\vec{\mu}_i, \vec{\mu}_j)$$

$K = 2$  clusters







GMM

$$\vec{x} \in \mathbb{R}^d$$

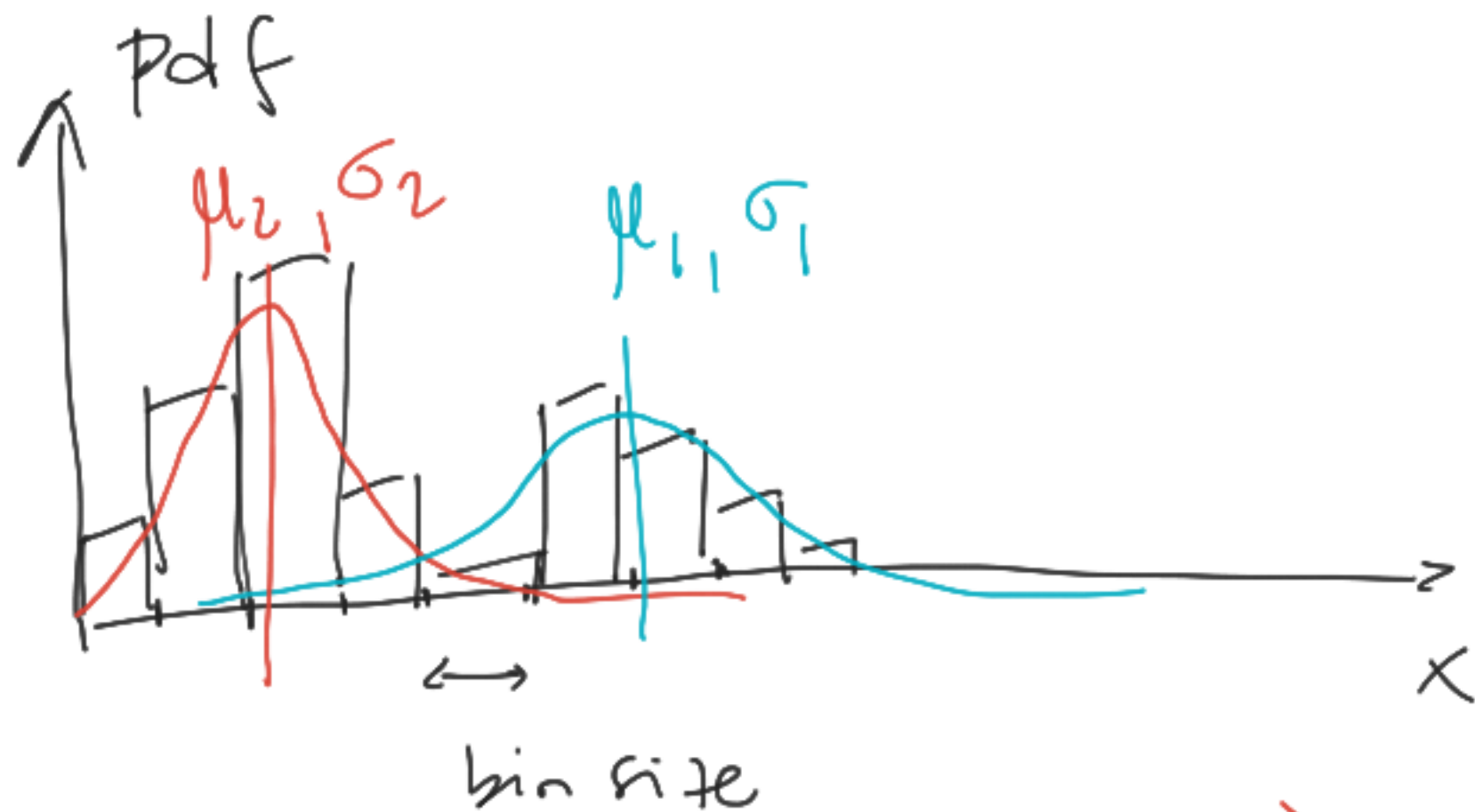
$$P(\vec{x}) = \sum_{j=1}^G \pi_j \cdot N(\vec{\mu}_j, \Sigma_j)$$

weights

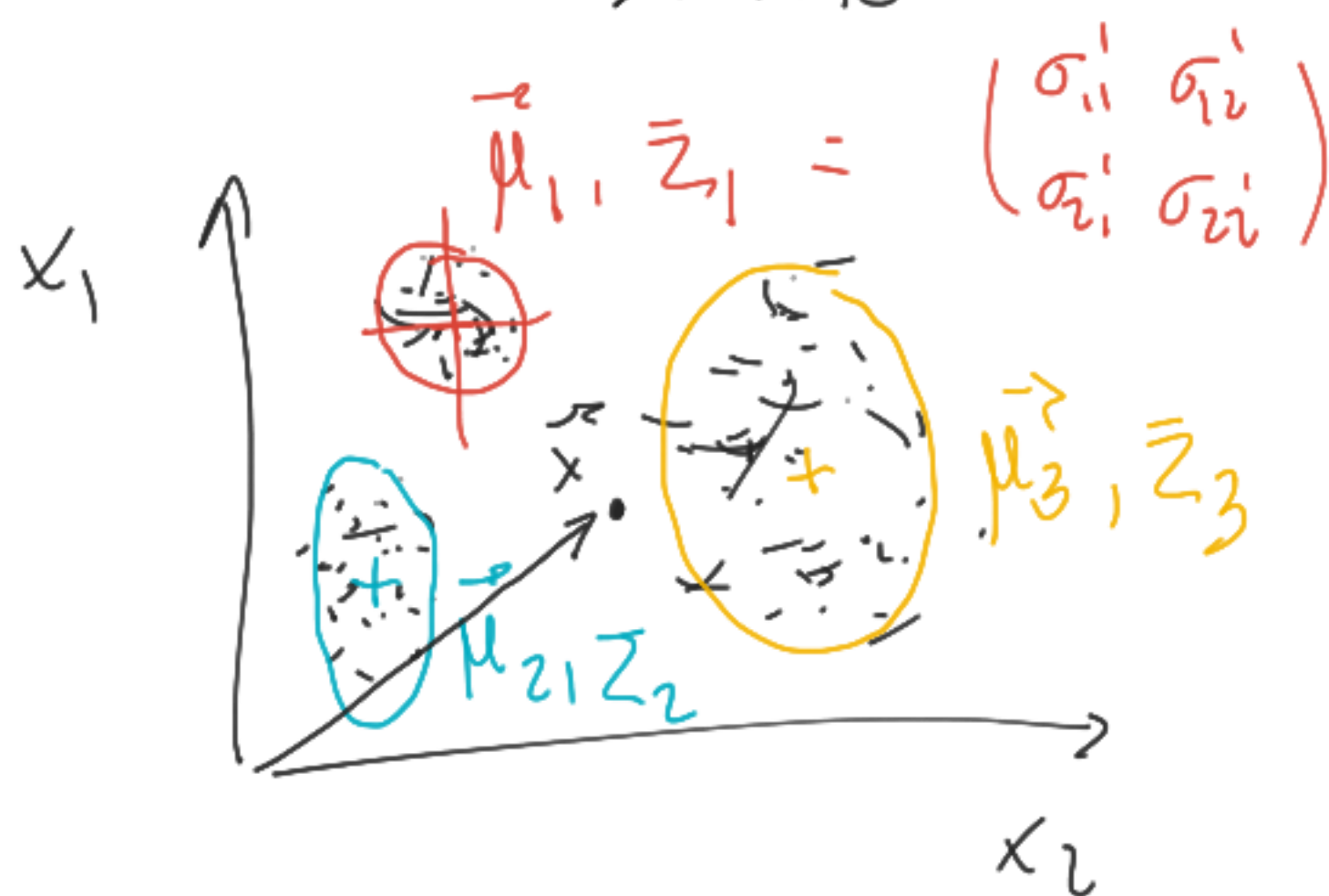
mean  
of  
gaussian  $j$   
( $1 \times d$ )

covariance matrix  
of gaussian  $j$   
( $d \times d$ )

Ex:  $d=1$   
 (univariate, <sup>#</sup>observ.)  
 $G=2$   
 gaussian



Ex:  $d=2$   
 $G=3$

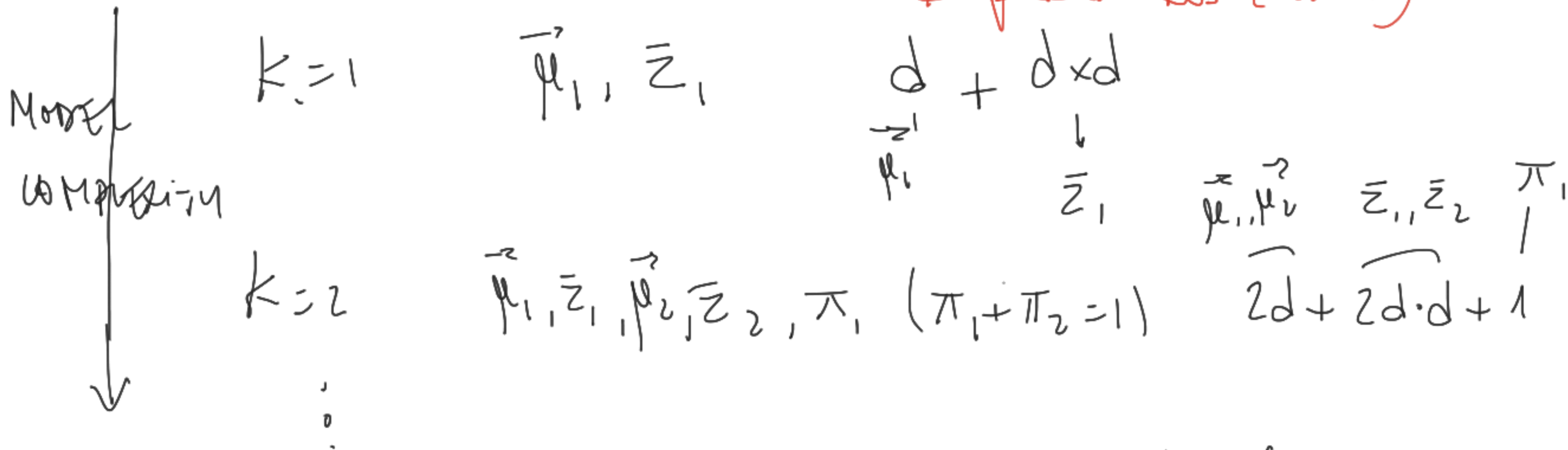


$$p(\vec{x}) = \sum_{j=1}^3 \pi_j \cdot \mathcal{N}(\vec{\mu}_j, \bar{\Sigma}_j)$$

GMM

→ pre-define # clusters → # gaussians

# parameters (GMM)



PARSIMONY INDICES

You need several observations  
to fit a GMM model

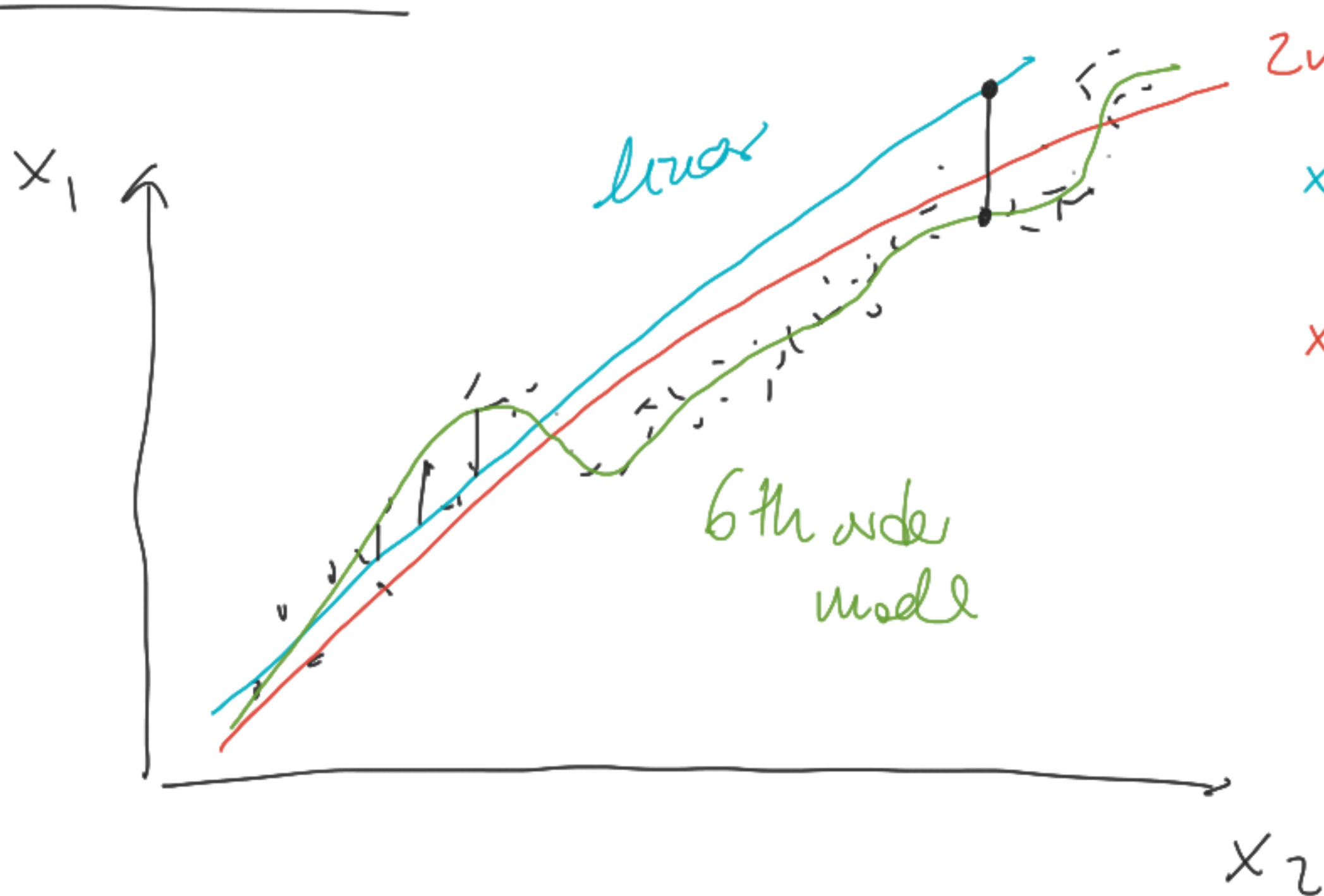
Parsimony

=

(RESIDUALS)  
MODEL (ERROR)  
MSE  
PERFORMANCE

vs

MODEL # parameters  
COMPLEXITY



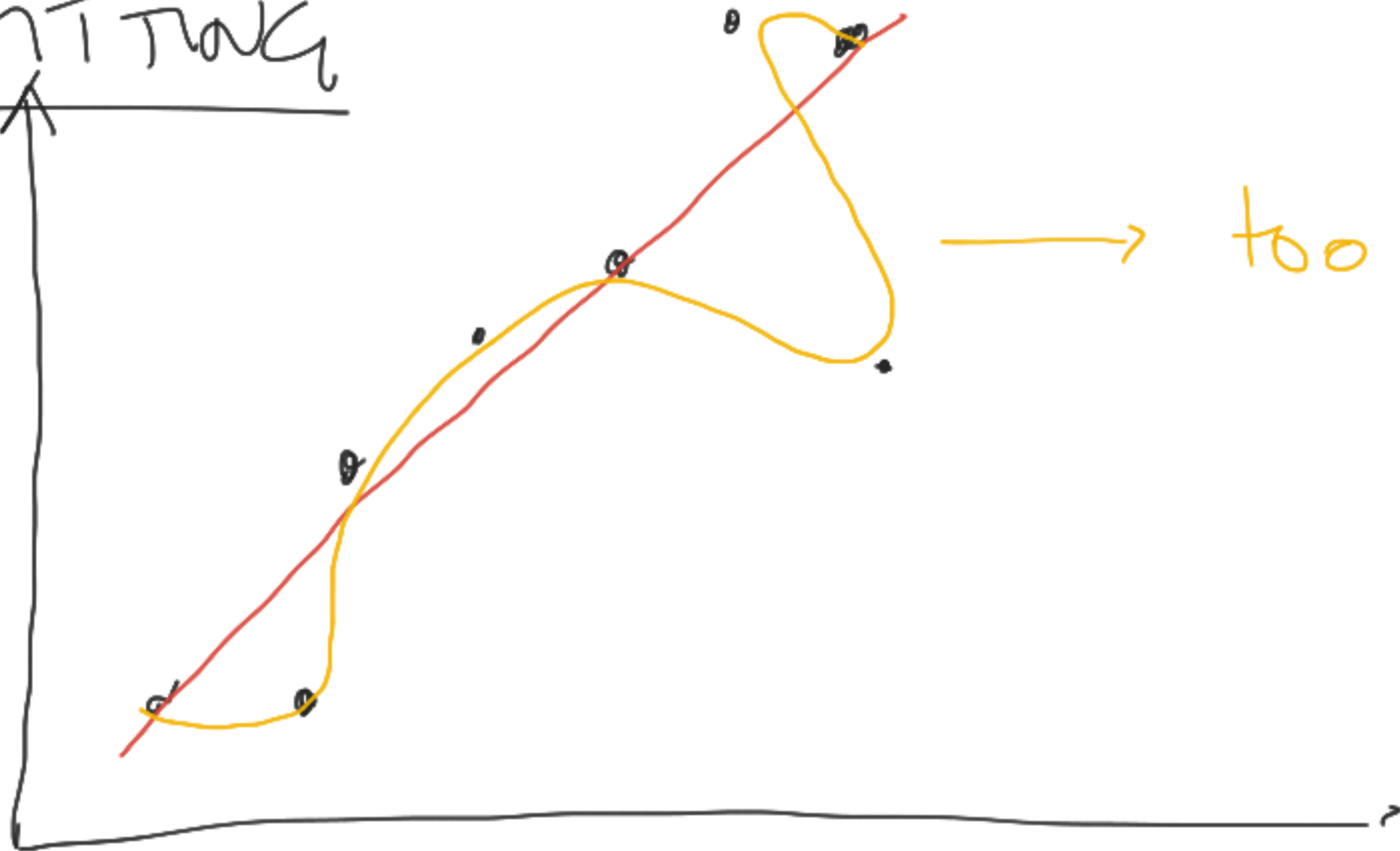
2nd order

$$x_1 = a x_2 + b \quad 2$$

$$x_2 = a x_1^2 + b x_1 + \dots \quad 3$$

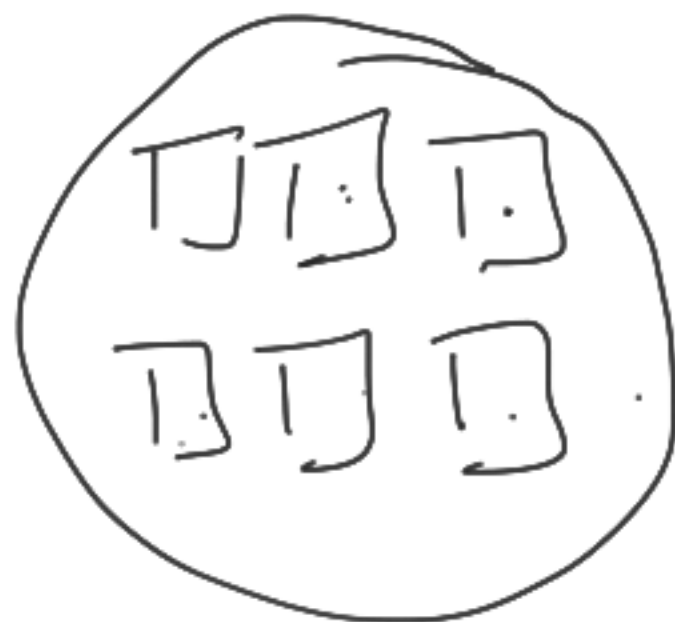
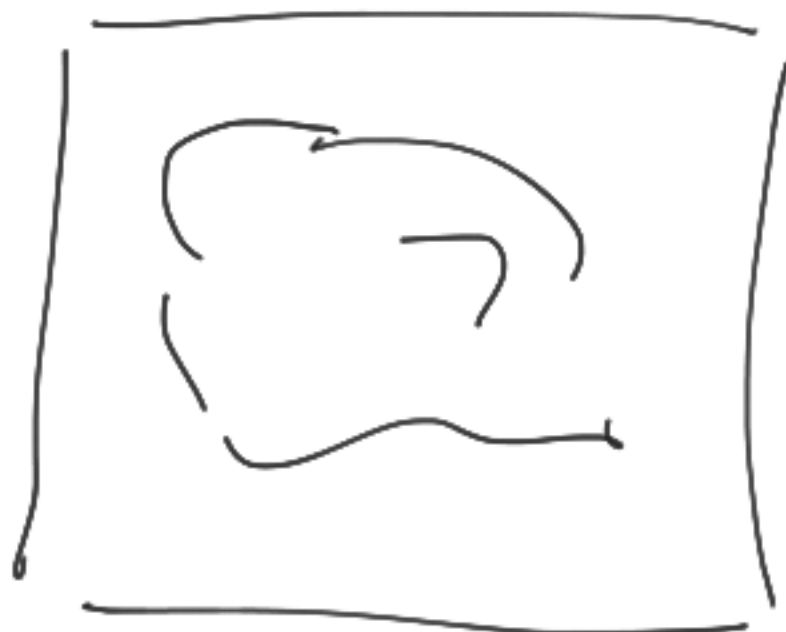
avoid data  
overfitting

OVERFITTING

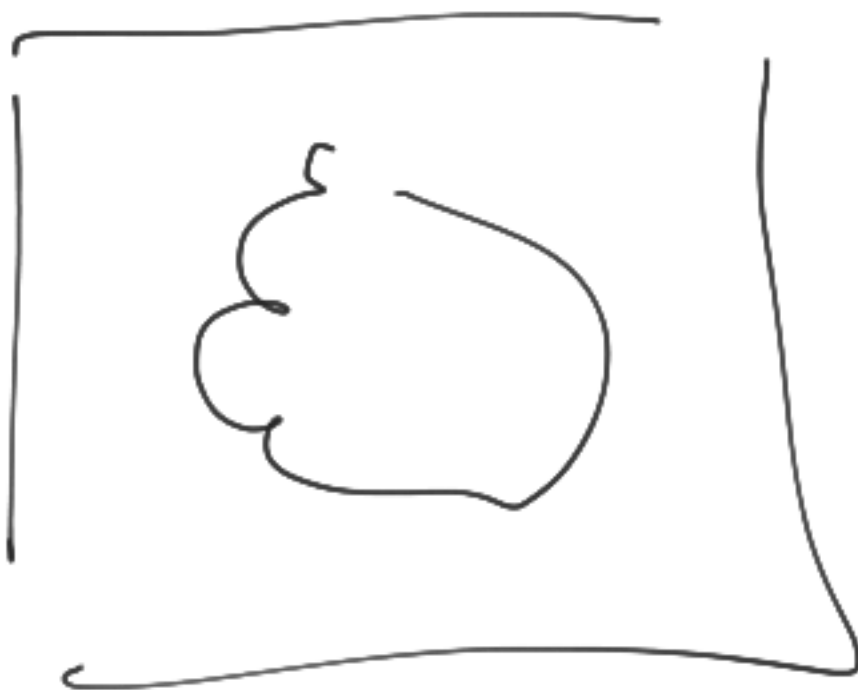


→ too complex!

R



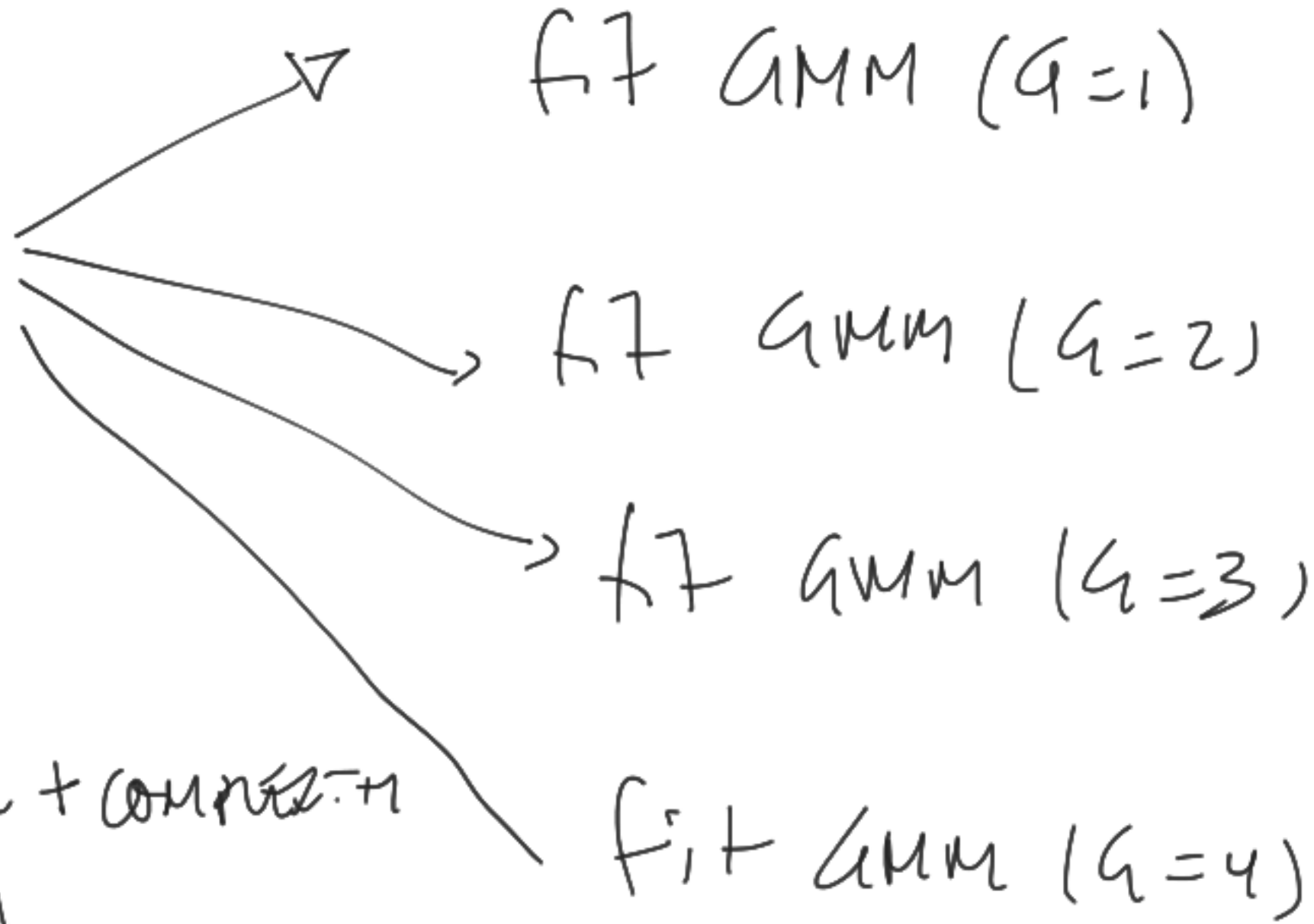
J



OVERFITTING  $\Leftrightarrow$  GENERALIZATION

# GMM + Model Selection

DATA



$$BIC = -\text{error} + \text{complexity}$$

$$= -2 \ln(\hat{\mathcal{L}}) + k \ln(n)$$

(ML) # parameters

How many clusters?

$$\arg \max_{j=1..4} \{BIC_j\} \rightarrow 2 \text{ clusters}$$

## BIC Parsimony Index

$$BIC_1 = -748$$

$$BIC_2 = -800$$

$$BIC_3 = -790$$

$$BIC_4 = -796$$



# PARAMETER ESTIMATION IN PROBABILISTIC MODELS

Probabilistic model:  $\vec{x}$ : data observation (d-dimensions)

$\theta$ : model parameters



$p(\vec{x}, \theta)$   $\rightarrow$  joint pdf

Ex:  $p(\vec{x} | \theta) = \mathcal{N}(\vec{x} | \underbrace{\vec{\mu}, \bar{\Sigma}}_{\theta})$

$\theta$ : model parameters

$$p(\vec{x} | \theta) = \sum_{j=1}^G \pi_j \cdot \mathcal{N}(\vec{x} | \vec{\mu}_j, \bar{\Sigma}_j)$$



## PARAMETER ESTIMATION :

sample of  
observations

$$\{\vec{x}_1, \vec{x}_2, \dots, \vec{x}_n\} \rightarrow \theta^*$$

SAMPLE  
ESTIMATE  
of model  
parameters

→ MAXIMUM LIKELIHOOD ESTIMATE (MLE)

Gaussian multivariate (unknown  $\vec{\mu}$ )  $\rightarrow \theta = \vec{\mu}$  ( $\vec{\Sigma}$  is known)

likelihood  
function

$$P(\vec{x} | \vec{\mu}) = N(\vec{x} | \vec{\mu}, \vec{\Sigma})$$

define log-likelihood  $\mathcal{Z} = \ln P(\vec{x} | \vec{\mu})$        $\mathcal{N}(\vec{x} | \vec{\mu}, \bar{\Sigma}) = \frac{1}{(2\pi)^d |\bar{\Sigma}|^{1/2}}$

$$\mathcal{Z} = -\frac{1}{2} \ln \left[ (2\pi)^d \cdot |\bar{\Sigma}| \right] - \underbrace{\frac{1}{2} (\vec{x} - \vec{\mu})^T \cdot \bar{\Sigma}^{-1} \cdot (\vec{x} - \vec{\mu})}_{\text{mahalanobis distance}}$$

Maximum Likelihood:

$$\partial_{\vec{\mu}} \ln P(\vec{x} | \vec{\mu}) = \partial_{\vec{\mu}} \mathcal{Z} =$$

$$= \bar{\Sigma}^{-1} \cdot (\vec{x} - \vec{\mu}) \rightarrow$$

$$\vec{\mu}_j = \frac{1}{n} \sum_{i=1}^n x_i^j$$

(quadratic weighted with  
variance in each  
directions)

# LATENT VARIABLE MODELS $\rightarrow$ hidden variable

$$\text{GMM: } p(\vec{x}) = \sum_{k=1}^K \pi_k \cdot N(\vec{x} | \vec{\mu}_k, \vec{\Sigma}_k)$$

LATENT

VARIABLE :  $\vec{z} = (z_1, z_2, \dots, z_G)$   $z_j \in \{0, 1\}$

(clustering  
variable)

one-hot encoding

$\rightarrow$   $x$  belongs to cluster 3  $\rightarrow \vec{z} = (0, 0, 1, 0, 0, \dots, 0)$

$$P(Z_k = 1) = \pi_k$$

joint distribution

$$P(\vec{x}, \vec{z}) = P(\vec{x} | \vec{z}) P(\vec{z})$$

↑  
latent

conditional probability

$$P(\vec{z} | \vec{x}) \rightarrow \text{posterior}$$

posterior

$$P(\vec{z} | \vec{x}) =$$

likelihood

$$\frac{P(\vec{x} | \vec{z}) P(\vec{z})}{P(\vec{x})}$$

prior

$$P(\vec{x})$$

→ normalizing constant

# EXPECTATION - MAXIMIZATION ALGORITHM (EM - algorithm)

Iterative procedure to get the ML estimate of parameters in probabilistic models with latent variables.

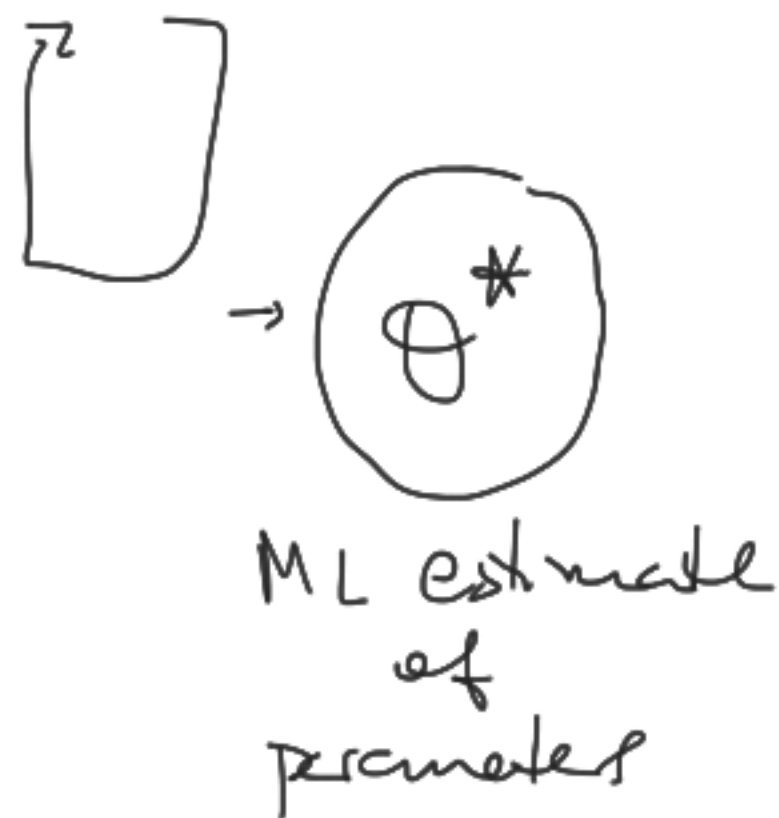
GMM + EM  $\rightarrow$  start from initial value for the parameters

$$\theta^0 = \{ \pi_j^0, \vec{\mu}_j^0, \vec{\Sigma}_j^0 \}$$

(1) E-STEP: evaluate posterior  $P(\vec{z} | \vec{x}, \theta^0)$

(2) M-STEP:  $\theta_{\text{new}} = \underset{\theta}{\operatorname{argmax}} Q(\theta, \theta_0)$

expect.  $Q(\theta, \theta_0) = \sum_{\vec{z}} \underbrace{P(\vec{z} | \vec{x}, \theta^0)} \cdot \ln P(\vec{x}, \vec{z} | \theta)$



# Fitting a GMM:

set  
of  
observations

$$\{\vec{x}_1, \vec{x}_2, \dots, \vec{x}_n\}$$



EM-algorithm



$$\pi_j^*, \mu_j^*, \Sigma_j^* \quad j=1 \dots G$$



$$p(\vec{x}) = \sum_{j=1}^G \pi_j^* N(\vec{x} | \mu_j^*, \Sigma_j^*) \rightarrow$$

assign each  
obs.  
to a cluster.



# GMM - options

→ Randomized initial values for  $\theta$

→ Choice for the structure of the covariance matrix:

$$\Sigma = \begin{pmatrix} \sigma_{11} & \sigma_{12} \\ \sigma_{21} & \sigma_{22} \end{pmatrix}$$

full-covariance



$$\Sigma = \begin{pmatrix} \sigma_1 & 0 \\ 0 & \sigma_2 \end{pmatrix}$$

diagonal



Tied

$$\begin{bmatrix} \bar{\sigma}_1 & \bar{\sigma}_2 \end{bmatrix}$$

$$\bar{\Sigma}$$

$$\bar{\Sigma} = \begin{pmatrix} \sigma & 0 \\ 0 & \sigma \end{pmatrix}$$

