

Lecture 2b

Last class

(Bonus class!)

Last time

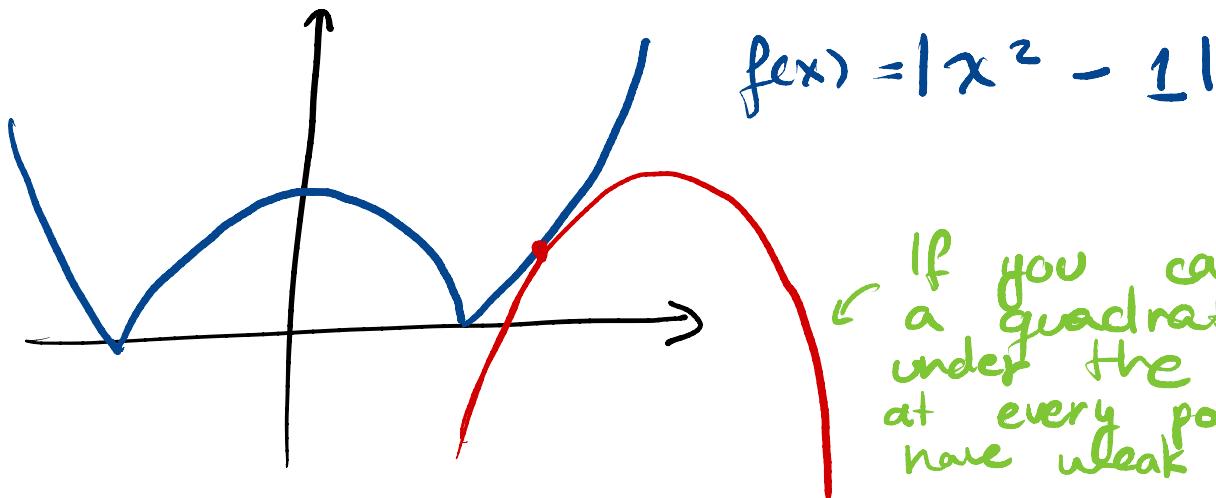
- ▷ Heuristics to solve the subproblem.
- ▷ Descent
- ▷ Full method
- ▷ Guarantees.

Today

- ▷ Weakly convex functions
- ▷ Composite optimization
- ▷ A guarantee
- ▷ Closing remarks

Weakly convex functions

A function $f: \mathbb{R}^d \rightarrow \mathbb{R} \cup \{\infty\}$ is called ρ -weakly convex if
 $x \mapsto f(x) + \frac{\rho}{2} \|x\|^2$
is a convex function.



Why is this an interesting class?

It gives a natural way to measure stationarity.

Def: A vector $g \in \mathbb{R}^d$ is a subgradient of a ρ -weakly convex function f at x ($g \in \partial f(x)$), if

$$\forall y \quad f(y) \geq f(x) + \langle g, y-x \rangle - \frac{\rho}{2} \|x-y\|^2.$$

A point x is critical if $0 \in \partial f(x)$.

Proposition : Let $f: \mathbb{R}^d \rightarrow \mathbb{R}$ ρ -weakly convex, then for any $\lambda > 0$ with $\rho < \frac{1}{\lambda}$ the following are well-defined:

$$\text{prox}_{\lambda f}(x) = \underset{y}{\operatorname{argmin}} \quad f(y) + \frac{1}{2\lambda} \|y-x\|^2.$$

$$f_\lambda(x) = \underset{y}{\min} \quad f(y) + \frac{1}{2\lambda} \|y-x\|^2.$$

Moreover, f_λ is continuously diff and if $\|\nabla f_\lambda(x)\| \leq \varepsilon$, then $x^+ = \text{prox}_{\lambda f}(x)$ satisfies:

- i) $\|x - x^+\| \leq \lambda \varepsilon$
- ii) $f(x^+) \leq f(x)$
- iii) $\inf_{\substack{g \in \partial f(x^+)} \|g\|} \leq \varepsilon$

Proof: Expanding

$$\begin{aligned}
 f(y) + \frac{1}{2\lambda} \|y - x\|^2 &= f(y) + \frac{1}{2\lambda} \|y\|^2 + \langle x, y \rangle + \frac{1}{2\lambda} \|x\|^2 \\
 &= f(y) + \underbrace{\frac{\rho}{2\lambda} \|y\|^2}_{\text{convex}} + \underbrace{\langle x, y \rangle + \frac{1}{2\lambda} \|x\|^2}_{\text{convex}} \\
 &\quad + \underbrace{\frac{1}{2} \left(\frac{1}{\lambda} - \rho \right) \|y\|^2}_{\text{strongly convex.}}
 \end{aligned}$$

Since the function is strongly, everything is well-defined.

The fact that f_λ is C^1 follows from a similar reasoning from the HW, where you proved

$$\nabla f_\lambda(x) = \frac{1}{\lambda} (x - x^+).$$

Then, ii) follows trivially. Moreover, by definition of x^+ :

$$f(x^+) \leq f(x^+) + \frac{1}{2\lambda} \|x - x^+\|^2 \leq f(x)$$

so (ii) follows.

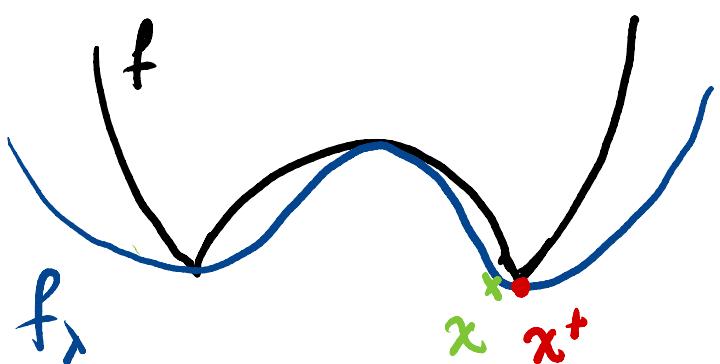
This we will not prove.

Finally, by the sum rule:

$$\begin{aligned} 0 &\in \partial f(x^+) + \frac{1}{\lambda} (x^+ - x) \\ \Rightarrow \| \nabla f_\lambda(x) = \underbrace{(x - x^+)}_{\lambda} &\in \partial f(x^+). \end{aligned}$$

□

Intuition



If we find x with $\|f_\lambda'(x)\|$ small, then there is a close point that is almost stationary.

Composite optimization

Consider

$$\min_x f(x) \quad \text{with } f(x) = h \circ G(x)$$

L -smooth map

with $f: \mathbb{R}^m \rightarrow \mathbb{R}$ and $G: \mathbb{R}^d \rightarrow \mathbb{R}^m$.
This class of problems is weakly β -Lipschitz convex function

convex and captures many data scientific tasks (phase retrieval, matrix completion, ...).

Let's consider two simple algorithms:

▷ Subgradient method

Update:

$$x_{k+1} \leftarrow x_k - \alpha_k \xi_k \quad \text{with } \xi_k \in \partial f(x_k)$$

One can show that $\partial f(x) = \nabla G(x) \partial h(x)$

▷ Gauss-Seidel method

Update:

$$x_{k+1} \leftarrow \operatorname{argmin} \left\{ h(G(x_k) + D G(x_k)(x - x_k)) + \frac{\beta}{2} \|x - x_k\|^2 \right\}$$

Linear approximation
stepsize.

Note that the subgradient method applies to weakly convex problems, while Gauss Seidel applies to composite problems only.

One can show that subgradient descent achieves a rate of

$$\|\nabla f_\lambda(\bar{x}_k)\| = O\left(\frac{1}{k^{\gamma_4}}\right)$$

Much slower than convex and smooth.

(Davis & Drusvyatskiy '18)

But local convergence might be much faster! Define $\text{dist}(x, S) = \inf_{y \in S} \|x - y\|$

Theorem: Suppose that $f: \mathbb{R}^d \rightarrow \mathbb{R}$ is ρ -weakly convex, L -Lipschitz, and μ -sharp, i.e., let $S = \operatorname{argmin} f$,

$$\mu \text{dist}(x, S) \leq f(x) - \min f.$$

If x_0 is such that $\text{dist}(x_0, S) \leq \frac{1}{2} \frac{\mu}{\rho}$, then the iterates of subgradient descent with $\alpha_k = \frac{f(x_k) - \min f}{\|\boldsymbol{\xi}_k\|^2}$ satisfy

$$\text{dist}(x_{k+1}, S)^2 \leq \left(1 - \frac{\mu^2}{2L^2}\right) \text{dist}(x_k, S)^2.$$

Proof: If x_0 lies in S there is nothing

to prove as $\alpha_k = 0$. Let's show $\xi_k \neq 0$,
 assume it was zero, then $\exists \bar{x} \in S$
 $\text{dist}(x_0, S) = \mu \|x_0 - \bar{x}\| \leq f(x_0) - f(\bar{x}) \quad \leftarrow \text{sharpness}$

Subgradient $\rightarrow \langle f(\bar{x}) + \frac{\rho}{2} \|x_0 - \bar{x}\|^2 - f(\bar{x})$
 $\xi_0 = 0 \quad = \rho \text{dist}^2(x_0, S),$

which contradicts $\text{dist}(x_0, S) \leq \frac{1}{2} \frac{\mu}{\rho}$.

Then,

$$\begin{aligned}
 & \|x_1 - \bar{x}\|^2 \\
 &= \|x_0 - \kappa_0 \xi_0 - \bar{x}\|^2 \\
 &= \|x_0 - \bar{x}\|^2 + 2\kappa_0 \langle \xi_0, \bar{x} - x_0 \rangle + \kappa_0^2 \|\xi_0\|^2 \\
 &= \|x_0 - \bar{x}\|^2 + 2 \underbrace{(\rho f(x_0) - f^*)}_{\|\xi_0\|^2} \langle \xi_0, \bar{x} - x_0 \rangle + \underbrace{(\rho f(x_0) - f^*)^2}_{\|\xi_0\|^2} \\
 &\leq \|x_0 - \bar{x}\|^2 + 2 \underbrace{(\rho f(x_0) - f^*)}_{\|\xi_0\|^2} (f^* - f(x_0)) + \frac{\rho}{2} \|x_0 - \bar{x}\|^2 \\
 &\quad + \underbrace{(\rho f(x_0) - f^*)^2}_{\|\xi_0\|^2} \\
 &= \|x_0 - \bar{x}\|^2 + \underbrace{(\rho f(x_0) - f^*)}_{\|\xi_0\|^2} (\rho \|x_0 - \bar{x}\|^2 - (\rho f(x_0) - f^*)) \\
 &\leq \|x_0 - \bar{x}\|^2 + \underbrace{(\rho f(x_0) - f^*)}_{\|\xi_0\|^2} (\rho \|x_0 - \bar{x}\|^2 - \mu \|x_0 - \bar{x}\|) \\
 &\quad \underbrace{\leq \frac{1}{2} \frac{\mu}{\rho}}
 \end{aligned}$$

$$\leq \|x_0 - \bar{x}\|^2 - \frac{\mu(\|f(x_0) - f^*\|)}{2} \|x_0 - \bar{x}\|$$

$$\leq \|x_0 - \bar{x}\|^2 - \frac{\mu^2}{2L} \|x_0 - \bar{x}\|. \quad \begin{matrix} \text{μ-sharp and} \\ \text{L-Lipschitz.} \end{matrix}$$

The proof follows by induction. \square

Closing remarks

We have built machinery to tackle

$$\min_{x \in \mathbb{R}^d} f(x)$$

in a wide variety of settings.

- ▷ Optimality conditions
- ▷ First-order methods
 - ↳ Smooth opt
 - ↳ Nonsmooth opt
 - ↳ Stochastic / coordinate methods
 - ↳ Conjugate gradient
- ▷ Second order methods
 - ↳ Newton's
 - ↳ Quasi Newton
 - ↳ Gauss-Seidel
 - ↳ Trust region

THANK YOU!