

# Lecture 20

Last time

- ▷ Preconditioning
- ▷ PDHG
- ▷ Primal-dual guarantee

Today

- ▷ P-D guarantee continued
- ▷ Fenchel subdifferential

Primal-dual guarantee continued

Theorem: Suppose that  $f, g$  are closed, convex and proper. Further, assume (P)-(D) exhibit strong duality with at least one primal dual solution. Let  $z_k = (x_k, y_k)$  be a sequence defined via positive definite.

$$\hookrightarrow H(z_k - z_{k+1}) \in \left[ \begin{array}{l} \partial_x L(x_{k+1}, y_{k+1}) \\ \partial_y l - L(x_{k+1}, y_{k+1}) \end{array} \right]$$

$\underbrace{\hspace{10em}}_{\mathcal{F}(z_{k+1})}$

Denote  $\bar{z}_k = (\bar{x}_k, \bar{y}_k) = \frac{1}{k} \sum_{i=1}^k z_i$ ,

then for any  $k \geq 1$  and any primal-dual solution  $(x^*, y^*)$

$$L(\bar{x}_k, y^*) - L(x^*, \bar{y}_k) \leq \frac{\|z^* - z_0\|_H^2}{2k}$$

$\|z\|_H^2 = \langle z, Hz \rangle$

Proof: Denote  $\begin{bmatrix} u_k \\ v_k \end{bmatrix} \stackrel{w_k}{=} H(z_k - z_{k+1})$   $\in \mathcal{F}(z_{k+1})$ . Then by definition of the subdifferential

$$\begin{aligned} & L(x_{k+1}, y^*) - L(x^*, y_{k+1}) \\ &= (L(x_{k+1}, y^*) - L(x_{k+1}, y_{k+1})) \\ &\quad + (L(x_{k+1}, y_{k+1}) - L(x^*, y_{k+1})) \\ &\leq \langle v_k, y_{k+1} - y^* \rangle + \langle u_k, x_{k+1} - x^* \rangle \\ &= \langle w_k, z_{k+1} - z^* \rangle \\ &= \langle z_k - z_{k+1}, z_{k+1} - z^* \rangle_H \\ &= \frac{1}{2} \|z_k - z^*\|_H^2 - \frac{1}{2} \|z_{k+1} - z^*\|_H^2 \\ &\quad - \frac{1}{2} \|z_k - z_{k+1}\|_H^2. \end{aligned}$$

$$\leq \frac{1}{2} \| z_k - z^* \|_H^2 - \frac{1}{2} \| z_{k+1} - z^* \|_H^2.$$

Using convexity and concavity of  $L(\cdot, y^*)$  and  $L(x^*, \cdot)$  yield

$$\begin{aligned} & L(\bar{x}_k, y^*) - L(x^*, \bar{y}_k) \\ & \leq \frac{1}{k} \sum_{i=0}^{k-1} L(x_{i+1}, y^*) - L(x^*, y_{i+1}) \\ & \leq \frac{1}{2k} \left( \| z_0 - z^* \|_H^2 - \frac{1}{2} \| z_k - z^* \|_H^2 \right) \\ & \leq \frac{\| z_0 - z^* \|_H^2}{2k}. \end{aligned}$$
□

## New topic: Variational Analysis

Next, we move away from algorithms and go back to understanding sets and functions (as we did at the start of class). Our goal is to generalize some of the ideas we consider for

convex data.

## Frechet subdifferential

For smooth functions we defined gradients via linear approximations. For non-smooth convex functions we used minorizing functions. Here we combined these two for general functions.

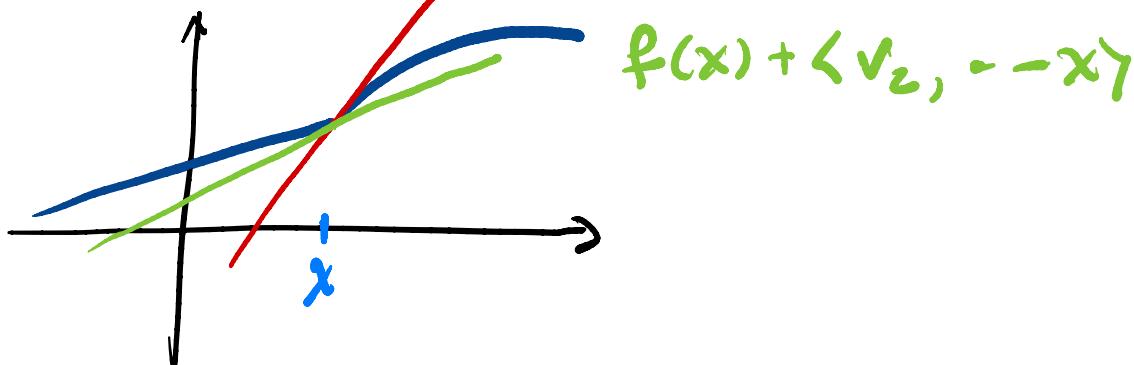
Def: For  $f: E \rightarrow \mathbb{R} \cup \{-\infty\}$  finite at  $x$ , we say that  $y \in \partial f(x)$  is a Frechet subgradient if and only if

$$f(x+z) \geq f(x) + \langle y, z \rangle + o(\|z\|) \text{ as } z \rightarrow 0$$

where  $o(z)$  is a term such that

$$\frac{o(\|z\|)}{\|z\|} \rightarrow 0 \text{ when } z \rightarrow 0. \quad \dashv$$

### Intuition



Arguably, there were three things

we liked about convex subdifferentials  
 (1) optimality conditions, (2) they exist  
 in  $\text{int dom } f$ , and (3) very nice  
 calculus rules. Next we aim to explore  
 equivalent properties for the Fréchet  
 subdifferential.

**Lemma (0)** Let  $x$  be a local minimizer  
 of  $f: E \rightarrow \mathbb{R} \cup \{+\infty\}$  and suppose  $x \in \text{dom } f$ .  
 Then,  $0 \in \partial f(x)$  holds.

Note that from now on we will only  
 be able to distinguish local properties  
 since  $\partial f$  is defined locally. We  
 have been abusing notation since  
 we used the symbol “ $\partial f$ ” for  
 convex subdifferentials. But it is  
 for a good reason:

**Lemma (+):** Suppose  $h: E \rightarrow \mathbb{R} \cup \{+\infty\}$  and  
 $g: E \rightarrow \mathbb{R}$  differentiable. Then,

$$\partial(h+g) = \partial h(x) + \nabla g(x) \quad \forall x \in \text{dom } h.$$

↑ Fréchet sub.      ↑ convex sub.

Moreover the equality still holds when  $h$  is merely proper with the Fréchet subdifferential on the right. +

The next question is about existence. General nonsmooth functions can be pretty nasty (Weierstrass function). So we can only establish that the domain of the subdifferential is dense in  $\text{dom } f$ .

**Lemma (Density of the subdifferential)**

Consider a proper, closed function  $f: E \rightarrow \mathbb{R} \cup \{-\infty\}$ . Then, the set  $\text{dom } f$  is dense in  $\text{dom } f$ .

**Proof:** Fix a point in  $\text{dom } f$ . We show the existence of a sequence  $x_i \in \text{dom } f$  with  $x_i \rightarrow x$ . Since  $f$  is closed there is a closed ball  $\Omega = \overline{B_\epsilon(x)}$  s.t  $f(y) \geq f(x) - 1 \quad \forall y \in \Omega$  (Why?)

Consider the sequence of potentials given by  $f_n(y) = f(y) + z_\Omega(y) + \frac{n}{2} \|y - x\|^2$ .

**Fact from Nonlinear 1:** If a closed function  $h: E \rightarrow \mathbb{R} \cup \{\infty\}$  is such that  $h(z) \rightarrow \infty$  when  $\|z\| \rightarrow \infty$ . (coercivity)

Then,  $h$  attains a minimizer.  $\dashv$

Clearly  $f_n$  is coercive so  $\exists x_n \in \text{argmin}_n$ .  
Note that

$$f(x_n) + \frac{n}{2} \|x_i - x\|^2 \leq f(x)$$

$$\Rightarrow \|x_i - x\|^2 \leq \frac{2}{n}(f(x) - f(x_n)) \leq \frac{2}{n}.$$

Thus,  $x_n \rightarrow x$ . Thus for large  $n$ , we have  $x_n \in \text{int } \mathcal{A}$ , and so  $x_n$  minimizes  $f(y) + \frac{n}{2} \|y - x\|^2$  without the indicator. By Lemmas (0) and (+) we conclude that

$$0 \in \partial f(x_n) + n(x_n - x)$$

and so  $\partial f(x_n) \neq \emptyset$ .  $\square$