

Datasets used in the paper:
 ”Benchmarking Safety Monitors for
 Image Classifiers with Machine Learning”

May 12, 2021

1 Datasets

Figure 1 gives a general illustration about the generated types of out-of-distribution (OOD) data.

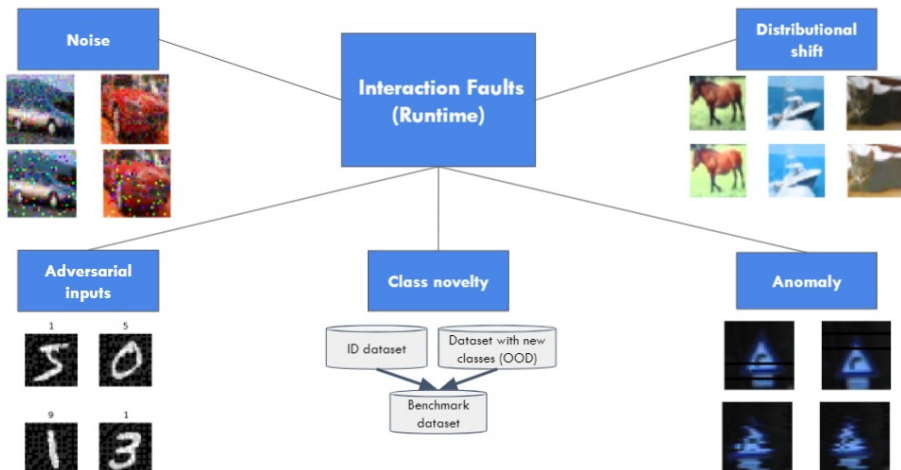


Figure 1: Example of OOD data generated by the framework.

Adversarial attack on images generated with the fast gradient sign method (FGSM). Novelty class datasets generated as ID dataset - OOD dataset. Anomalies based on common anomalies on sensors described in the report ”Evaluating Functional Safety in Automotive Image Sensors, Semiconductor Components Industries”^a. For distributional shifts, we applied simulations of weather conditions (snow, fog) and possible interference of the environment on the cameras such as brightness, contrast and saturation. We also generated rotated images, varying from -30 degrees to +30 degrees. For noise variations, we applied several types of corruptions in the pixels as can be seen in the Table 1 All the variations for distributional shift and noise (except for the rotated data) were proposed on the paper ”Benchmarking neural network robustness to common corruptions and perturbations”^b.

Table 1: Dataset details.

| Variation | OOD type | ID Instances | OOD Instances |
|-------------------|----------------------|--------------|---------------|
| FGSM | Adversarial Attack | | |
| BTSC-GTSRB | Novelty Class | | |
| GTSRB-CIFAR10 | Novelty Class | | |
| CIFAR10-GTSRB | Novelty Class | | |
| Pixel Trap | Anomaly | | |
| Row Add Logic | Anomaly | | |
| Shifted Pixel | Anomaly | | |
| Snow | Distributional shift | | |
| Fog | Distributional shift | | |
| Brightness | Distributional shift | | |
| Contrast | Distributional shift | | |
| Saturate | Distributional shift | | |
| Rotated | Distributional shift | | |
| Spatter | Noise | | |
| Gaussian | Noise | | |
| Shot | Noise | | |
| Speckle | Noise | | |
| Defocus Blur | Noise | | |
| Elastic Transform | Noise | | |
| Impulse | Noise | | |
| Glass Blur | Noise | | |
| Zoom Blur | Noise | | |
| Gaussian Blur | Noise | | |

^a<https://www.onsemi.cn/pub/Collateral/TND6233-D.PDF>

^bHendrycks, D., & Dietterich, T. (2019). Benchmarking neural network robustness to common corruptions and perturbations. arXiv preprint arXiv:1903.12261.