

①

Time series analysis.

Time series is a collection of random variables $\{x_t | t \in T\}$ where T is an index set representing time.

Distribution of timeseries:

$$x_0 = 0 \quad x_i \stackrel{\text{iid}}{\sim} N(0, 1)$$

$$z_i = \sum_{j=0}^i x_j$$

$$\text{var}(z_i) = \text{var}\left(\sum_{j=0}^i x_j\right) = i$$

$$\Rightarrow \text{var}(z_{60}) = 60$$

and $\text{var}(z_{90}) = 90.$

$$\text{cov}(z_{60}, z_{90})$$

$$= \text{cov}(z_{60}, z_{60} + \sum_{j=61}^{90} x_j)$$

$$= \text{cov}(z_{60}, z_{60}) + \text{cov}(z_{60}, \sum_{j=61}^{90} x_j)$$

$$= \text{var}(z_{60}) + 0$$

$$= 60$$

Note { Even if $20 x_i$'s are uncorrelated then also this cov. is zero.

② The necessary condition for $\text{cov}(z_{(0)}, \sum_{j=1}^{50} x_j) = 0$ is that x_j 's are uncorrelated.

* Normally distributed random variables with correlation zero implies independence.

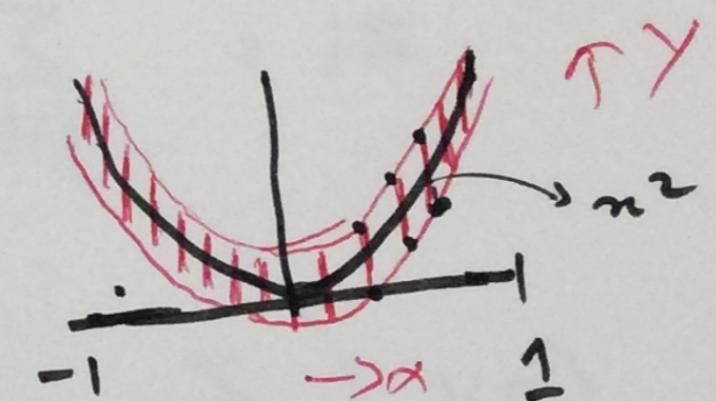
* Correlation or Covariance zero does not imply independence in general.

$$x \sim \mathcal{U}(-1, 1)$$

$$y|x \sim \mathcal{U}(x^2 - \epsilon, x^2 + \epsilon)$$

$$E(xy) = E(x^3) = 0$$

$$\text{Hence } \underline{\text{covariance}}(x, y) = 0.$$



$$E(x) E(y) = 0$$

$E(x_i) = 0$ $\vee (x_i) = 1$ and they are uncorrelated. ③

$$Z_t = \frac{1}{\sqrt{n}} \sum_{i=1}^{[nt]} x_i$$

partial sum process. $t \in [0, 1]$

What will be the distribution of Z_t when $n \uparrow \infty$??

$$Z_t = \frac{\sqrt{[nt]}}{\sqrt{n}} \left(\frac{1}{\sqrt{[nt]}} \sum_{i=1}^{[nt]} x_i \right)$$

when
 $n \uparrow \infty$
iid

independent but not identical.
uncorrelated ✓
dependent → more restricting.

Converge to $N(0, 1)$ by CLT.

Z_t will converge in distribution to

$$\sqrt{t} N(0, 1) \equiv N(0, t)$$

$Z_t \sim$ following Brownian motion.

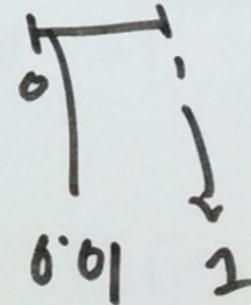
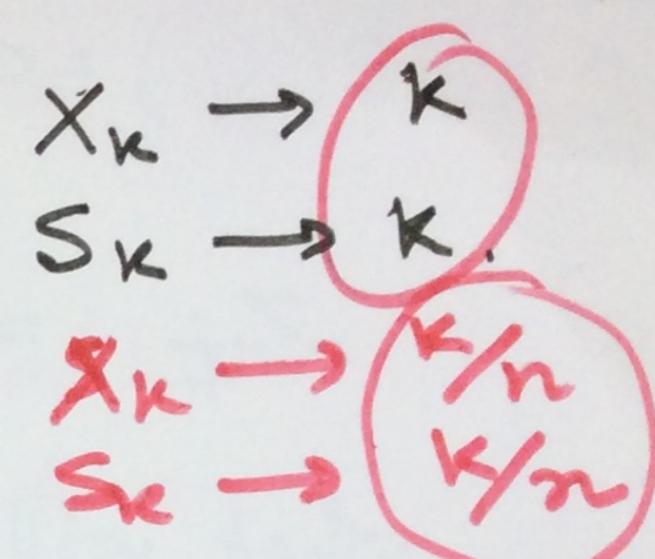
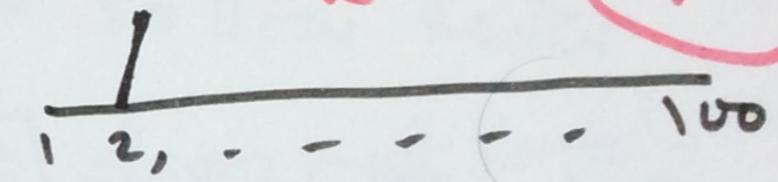
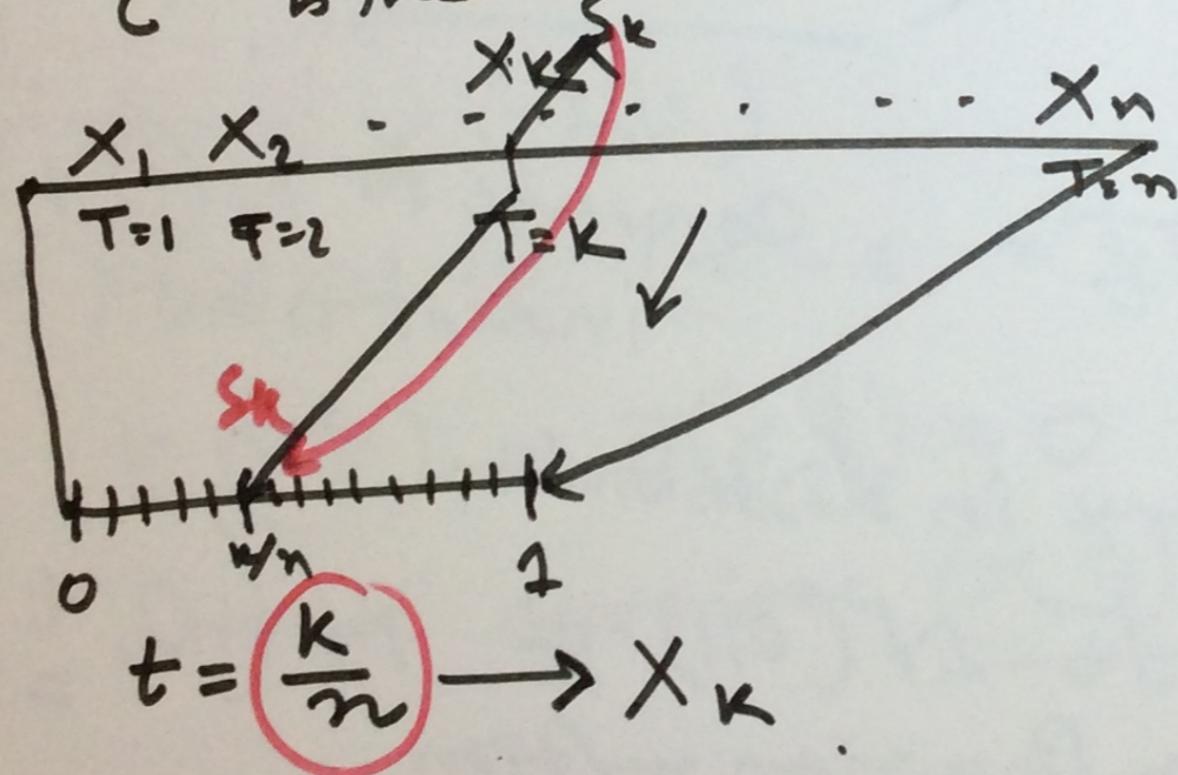
$\{x_i\}$ series of numbers.

$$S_k = \sum_{i=1}^k x_i \quad k \in \mathbb{N}.$$

partial sum.
Cumulative sum.

n = sample size.

t is the time index.



1. White noise:

A time series $\{W_t\}$ such that $E(W_t) = 0$, $V(W_t) = \sigma_w^2$
 $W_t \sim WN(0, \sigma_w^2)$.

and they are uncorrelated.

Example: (1) $X_i \stackrel{iid}{\sim} N(0, \sigma^2)$

(2) $X_i \sim \begin{cases} N(0, \sigma^2) & \text{when } i \text{ is even} \\ \exp(1) - 1 & \text{when } i \text{ is odd} \end{cases} \rightarrow \text{indepent.}$

\rightarrow (a) WN need not be normally distributed..

(b) WN need not be iid.

(c) iid sequence is always WN, with mean zero, and finite variance.

/ (d). WN is weakly stationary.

/ (e) WN with normally distributed r.v.s are strongly stationary.

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(2) Binary process:

Consider a time series $\{X_t\}$, such that.

$$X_t = \begin{cases} +1 & \text{with prob. } p. = \frac{1}{2} \\ -1 & \text{with prob. } 1-p. = \frac{1}{2} \end{cases}$$

$$E(X_t) = 0 \quad V(X_t) = 1$$

In general when $p \neq \frac{1}{2}$

$$\begin{aligned} E(X_t) &= 2p-1 & V &= 1 - (2p-1)^2 \\ && &= 4p(1-p) \end{aligned}$$

$$W \sim \text{bernoulli}(p).$$

$$X = \frac{W - 0.5}{0.5}$$

$$X = a + b W$$

$$V(X) = b^2 V(W)$$

$$= 4p(1-p)$$

(3) Random walk:

Let $\{W_t\}$ be an iid sequence of random variables.

and define $X_0 = 0$, $X_t = \sum_{i=1}^t W_i$

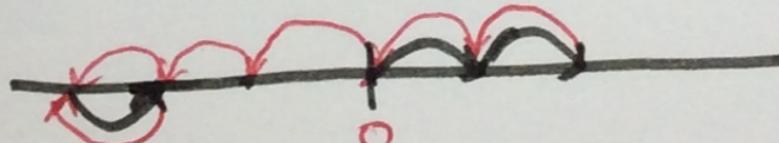
$$E(W_t) = 0 \quad \text{Var}(W_t) = \sigma_w^2$$

where.

$$\{W_t\} \sim \text{binary brown.}$$

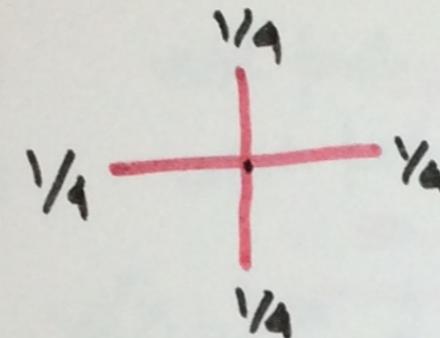
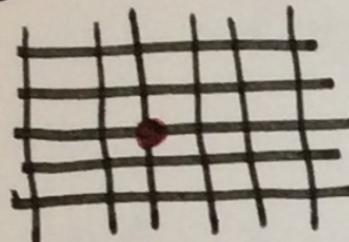
$$\sim N(0, \sigma^2)$$

$$\text{w. lawless}(0, \lambda)$$

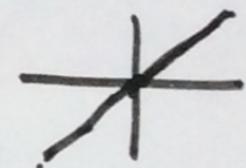


④ $w_t \sim \text{Binary borders } (\gamma_2)$. then it will eventually comeback to the place where it has started from.

⑤ $\mathbb{Z} \times \mathbb{Z}$



The random variable eventually come back to $(0,0)$.



⑥

$\mathbb{Z} \times \mathbb{Z} \times \mathbb{Z}$

with equal probability to each 6 ~~8~~ direction.
then the random variable may not come back to $(0,0,0)$.

⑦

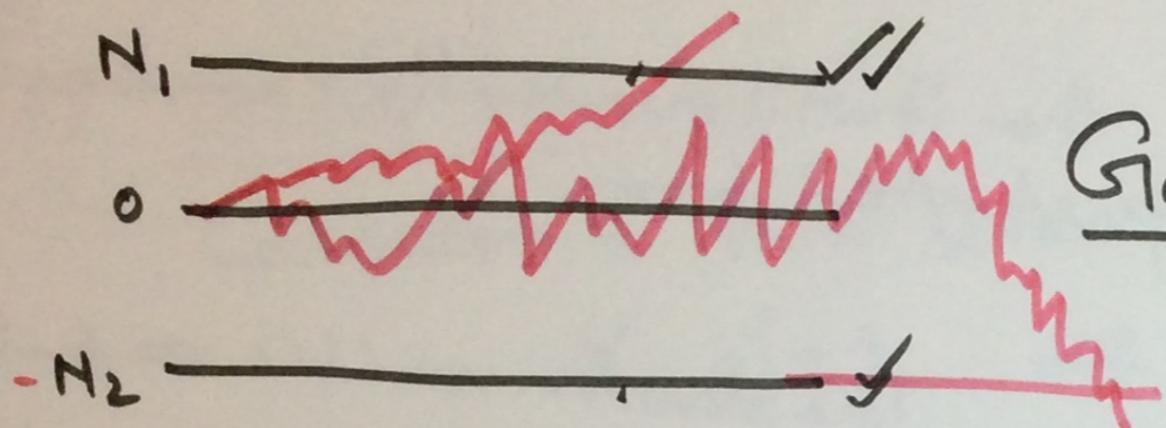
Random walk with drift:

$$\begin{cases} w_i \stackrel{\text{iid}}{\sim} E(w_i) = \delta \quad v(w) = \sigma^2 \\ x_t = \sum_{i=1}^t w_i \end{cases}$$

Mean of x_t is a function of t .

$$\begin{cases} x_t = \underline{t\delta} + \sum_{i=1}^t z_i \\ z_i \stackrel{\text{iid}}{\sim} E(z_i) = 0 \quad v(z_i) = \sigma_z^2. \end{cases}$$

(8)



Gambler's ruin problem:

⑤ Signal with noise:

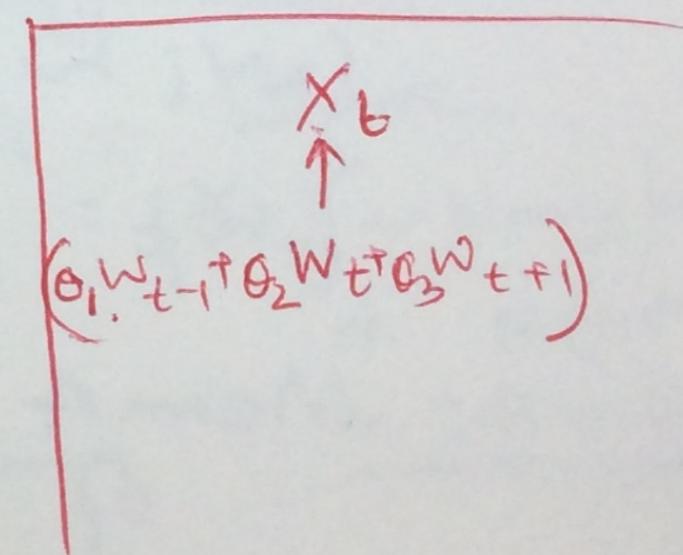
$$X_t = A \sin(2\pi f t + \varphi) + W_t.$$



⑥ Moving average process: (order one):

$$W_t \sim WN(0, \sigma_w^2).$$

$$X_t = W_t + \underbrace{\theta_1 W_{t-1} + \theta_2 W_{t-2} + \dots}_{(\theta_1 W_{t-1} + \theta_2 W_t + \theta_3 W_{t+1})}$$



(4)

⑦ Auto regressive process.: (Order one).

$$\{W_t\} \sim WN(0, \sigma_w^2)$$

$$X_t = \phi X_{t-1} + W_t. \quad |\phi| < 1, \phi \neq 0$$

$$Y = \beta X + \epsilon.$$

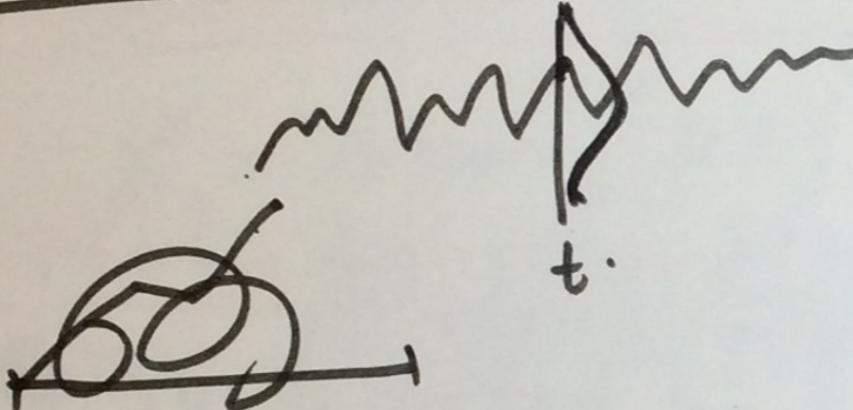
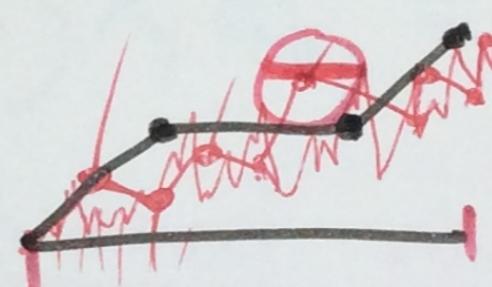
⑧ Wiener process / Brownian motion.

$\{X_t\}$ is said to follow Wiener process or BM. if.

- (i) $X_0 = a$ ($a=0 \Rightarrow$ standard BM).
- (ii) $X_{t+u} - X_t$ is independently distributed to $X_s \forall s \leq t$. $u > 0$.
- (iii) $X_{t+u} - X_t \sim N(0, u)$, $u > 0$
- (iv) $\{X_t\}$ has continuous path on $t \in \text{Time}$.
(but not differentiable)

$$\left\{ \begin{array}{l} w_k \stackrel{iid}{\sim} E(w_k) = 0 \quad \nu(w_k) = 1 \\ \text{#} \quad Y_n(t) = \frac{1}{\sqrt{n}} \sum_{i=1}^{\lfloor nt \rfloor} w_i \end{array} \right. \rightarrow \begin{array}{l} \text{For large } n \\ X_t \sim BM \\ t \in [0, 1] \end{array}$$

Continuous time process

⑤ Brownian Bridge.

Brownian motion with restriction.

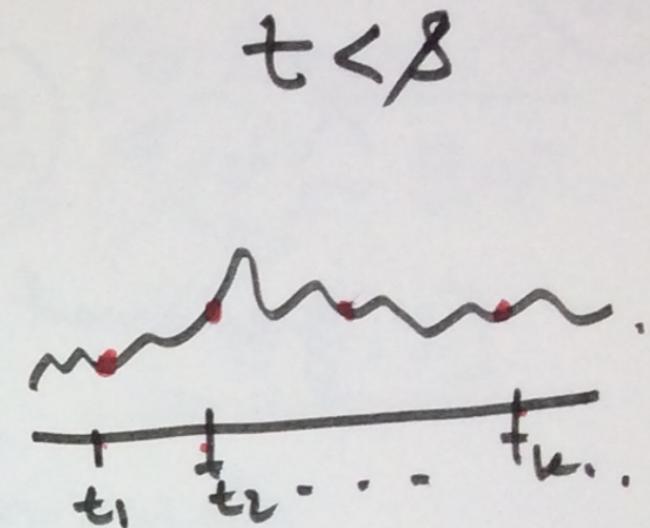
($t=0, X_t=0$) and ($t=T, X_t=b$)

If ($T=1$ and $b=0$) \Rightarrow standard Brownian bridge.

$$B_0(t) = X_t - tX_1 \quad \underbrace{X_t \sim BM \text{ on } [0, 1]}_{N(0, 1)}.$$

$X_t \sim \text{standard BN.}$

$$\begin{pmatrix} X_t \\ X_s \end{pmatrix} \sim N \left(\begin{pmatrix} 0 \\ 0 \end{pmatrix}, \begin{pmatrix} t & t \\ t & s \end{pmatrix} \right)$$



$B_0(t) \sim \text{standard BB.}$

$$\begin{pmatrix} B_0(t) \\ B_0(s) \end{pmatrix} \sim N \left(\begin{pmatrix} 0 \\ 0 \end{pmatrix}, \begin{pmatrix} t(1-t) & t(1-s) \\ t(1-s) & s(1-s) \end{pmatrix} \right)$$

~~Scat.~~

Any $K \in \mathbb{N}$. and $t_1, t_2, t_3, \dots, t_K \in \mathbb{R}$.

$$\text{As } (X_{t_1}, X_{t_2}, \dots, X_{t_K}) \sim (B_0(t_1), B_0(t_2), \dots, B_0(t_K))$$

follows multivariate Normal.

X_t and $B_0(t)$ are known as Gaussian process.

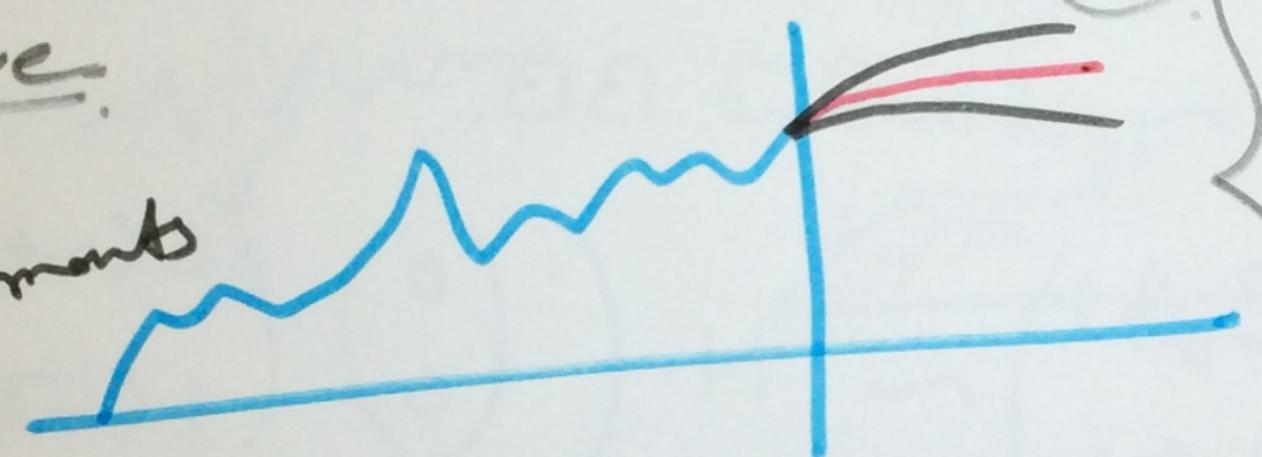
(12)

(10)

$$X_t = \underbrace{(S_0 + S_1 t + S_2 t^2)}_{\text{X}} + \underbrace{A \sin(2\pi f t)}_{\text{A sin (2πft)}} + \underbrace{\omega t}_{\text{ωt.}}$$

generat features of a time series we might observe.

where
Second order moments
are same.

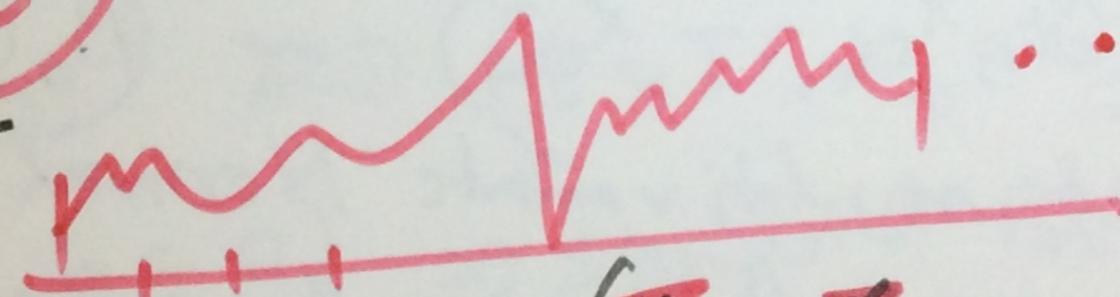


Even though all moments are same two random variables may have different distn.

For all
 $k \in \mathbb{N}$.

$t_1, t_2, \dots, t_k \in \mathbb{R}$
 $h \in \mathbb{R}$.

$\omega t.$



Stronger

Joint distribution of $(Z_{t_1}, Z_{t_2}, \dots, Z_{t_k})$
is same as $(Z_{t_1+h}, Z_{t_2+h}, \dots, Z_{t_k+h})$.