

Chapter 6: Green's Function

Observation:

$$\frac{d}{dx}(x^2) = 2x.$$

$$\text{and } x^2 = \int 2x dx$$

be the differential operator

Thus if $D \equiv \frac{d}{dx}$ and I be the integral operator,

$$\text{then, } Dx^2 = 2x$$

$$\Rightarrow x^2 = I(2x), \text{ neglecting constant.}$$

Now, ^{take} any differential equation.

$$\frac{d^2 y}{dx^2} - 4 \frac{dy}{dx} + 3y = \sin x; \quad a \leq x \leq b.$$

$$\text{or, } D^2 y - 4Dy + 3y = \sin x.$$

$$\text{or, } (D^2 - 4D + 3I)y = \sin x$$

$$\text{or, } Ly = \sin x$$

$$\text{where, } L \equiv D^2 - 4D + 3I.$$

i.e. L is some differential operator.

Thus $y(x)$ can be obtained by operating L^{-1} on $\sin x$, where it is expected that L^{-1} will be some integral operator.

Thus, any linear diff. equation can be expressed as $Ly = f(x) \rightarrow (1)$

where $f(x)$ is known function.

Then $y(x)$ can be obtained as,

$$y(x) = L^{-1} f(x) \rightarrow (2)$$

and it can be shown that,

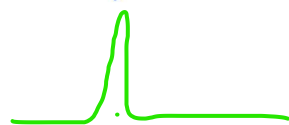
$$y(x) = \int_a^b g(x, t) f(t) dt. \rightarrow (3)$$

Here $g(x, t)$ is the Green's function for the operator L , with the understanding that,

$$Lg(x, t) = \delta(x - t). \rightarrow (4)$$

where $\delta(x - t)$ is the Dirac Delta function

$$\delta(x - t) = \begin{cases} 0, & x \neq t \\ \infty, & x = t. \end{cases}$$



Also, $\int_{-\infty}^{\infty} \delta(x - t) dt = 1, \int_{-\infty}^{\infty} \delta(x - t) f(t) dt = f(x),$

$\int_{-\infty}^{\infty} \delta(x - t) f(x) dx = f(t);$ $f(t)$ is a smooth function in $(-\infty, \infty)$

Note: $y(x) = \int_a^b g(x, t) f(t) dt.$

$$\begin{aligned} \therefore Ly &= L \int_a^b g(x, t) f(t) dt = \int_a^b L g(x, t) f(t) dt \\ &= \int_a^b \delta(x - t) f(t) dt \end{aligned}$$

let $F(t) = \begin{cases} f(t); & a \leq t \leq b. \\ 0 & ; \text{otherwise,} \end{cases}$

Then, $Ly = \int_{-\infty}^{\infty} \delta(x - t) F(t) dt = F(x) = f(x); a \leq x \leq b.$

Example. Find the Green's function for the BVP

$$\frac{d^2 u}{dx^2} = f(x); \quad 0 \leq x \leq 1; \quad u(0) = 0, u(1) = 0.$$

($f(x)$ is known).

Solution: Here $Lu = f(x)$; $L \equiv \frac{d^2}{dx^2}$.

$$u(x) = \int_0^1 g(x, t) f(t) dt.$$

To find $g(x, t)$.

We should have, $Lg(x, t) = \delta(x - t)$.

$$\text{or, } \frac{d^2}{dx^2} g(x, t) = \delta(x - t).$$

Integrating w.r. to x , we get

$$\frac{d}{dx} g(x, t) = \int \delta(x - t) dx + \alpha(t) \longrightarrow (5).$$

~~Again, integrate w.r. to x~~

Now, we use the property

$$\frac{d}{dx} H(x - t) = \delta(x - t)$$

where $H(x)$ is the Heaviside's fu. given by,

$$H(x) = \begin{cases} 1, & x > 0 \\ 0, & x < 0. \end{cases}$$

Thus, from (5),

$$\frac{d}{dx} g(x, t) = \int H'(x - t) dx + \alpha(t)$$

$$\therefore \frac{d}{dx} g(x, t) = H(x - t) + \alpha(t).$$

Integrate again w.r.to. x and get

$$g(x, t) = \int H(x-t) dx + \int \alpha(t) dx + \beta(t).$$

\downarrow
 $d(x-t)$

$$= \{H(x-t)\} (x-t) - \int H'(x-t) (x-t) dx + x\alpha(t) + \beta(t).$$

$$\text{or, } g(x, t) = (x-t)H(x-t) - \int \delta(x-t) (x-t) dx + x\alpha(t) + \beta(t).$$

$$\text{Now, } \int_{-\infty}^{\infty} \delta(x-t) \phi(x) dx = \phi(t).$$

Here $\phi(x) = x-t$ so that $\phi(t) = t-t=0$.

$$\therefore g(x, t) = (x-t)H(x-t) + x\alpha(t) + \beta(t) \longrightarrow (6)$$

$\alpha(t)$, $\beta(t)$ are unknown functions. These are to be determined with the help of the boundary conditions.

The solution to $Lu = f$ is,

$$u = \int_0^1 g(x, t) f(t) dt.$$

$$\text{or, } u(x) = \int_0^1 \{ (x-t)H(x-t) + x\alpha(t) + \beta(t) \} f(t) dt.$$

$$\text{Since } H(x-t) = \begin{cases} 1, & x > t \\ 0, & x < t \end{cases}$$

So, $u(x)$ becomes

$$u(x) = \int_0^x (x-t) f(t) dt + \int_0^1 \{ x\alpha(t) + \beta(t) \} f(t) dt.$$

Now, the b.c. $u(0) = 0$ gives,

$$0 = \int_0^1 \beta(t) f(t) dt.$$

Since $f(t) \neq 0$ in $[0, 1]$, $\beta(t) \equiv 0$ in $[0, 1]$

Also, $u(1) = 0$

$$\Rightarrow \int_0^1 (1-t) f(t) dt + \int_0^1 f(t) \alpha(t) dt = 0.$$

$$\text{or, } \int_0^1 \{ (1-t) + \alpha(t) \} f(t) dt = 0.$$

Since $(1-t) + \alpha(t) = 0$,

$$\alpha(t) = t-1$$

Thus, from (6),

$$\begin{aligned} g(x, t) &= (x-t) H(x-t) + x(t-1) \\ &= \begin{cases} (x-t) \cdot 1 + x(t-1) & ; x > t \\ (x-t) \cdot 0 + x(t-1) & ; x < t. \end{cases} \\ &= \begin{cases} x-t + xt-x & ; x > t \\ x(t-1) & ; x < t \end{cases} \end{aligned}$$

$$\therefore g(x, t) = \begin{cases} t(x-1) & ; x > t \\ x(t-1) & ; x < t. \end{cases} \longrightarrow (7)$$

From (7),

$$\begin{aligned} g(x, x^+) &= x(x-1) = x^2 - x \\ g(x, x^-) &= x(x-1) = x^2 - x \end{aligned}$$

Thus, $g(x, t)$ is continuous at $t=x$.

Note, (7) can be re-written as,

$$g(x, t) = \begin{cases} x(t-1); & 0 \leq x \leq t \\ t(x-1); & t < x \leq 1. \end{cases} \rightarrow (8)$$

$$g(t, x) = \begin{cases} t(x-1) & t < x \\ x(t-1) & t > x \end{cases} \quad \left[\begin{array}{l} \text{changing roles of} \\ x \text{ \& } t \end{array} \right].$$

$\rightarrow (9)$

From (8) & (9), $g(x, t) = g(t, x)$

Thus, $g(x, t)$ is symmetric in x & t .

Also, $g(0, t) = 0, t-0 = 0$, from (8a)

$g(1, t) = t-(1-1) = 0$, from (8b)

Thus, $g(x, t)$ satisfies the boundary conditions.

Note that the given diff. equation

$$\frac{d^2 u}{dx^2} = f(x)$$

can be expressed as, $- \left(- \frac{du}{dx} \right)' + 0 \cdot y = f(x)$.

which is of the form $- \left(p(x) \frac{du}{dx} \right)' + q(x) \cdot y = f(x)$

with $p(x) = -1$, $q(x) = 0$.

Next let us compute $\frac{\partial g}{\partial x}(t+0, t)$ & $\frac{\partial g}{\partial x}(t-0, t)$.

For this we compute $\frac{\partial g}{\partial x}(x, t)$.

$$\frac{\partial g}{\partial x}(x, t) = \begin{cases} t-1, & 0 \leq x < t \\ t, & t < x \leq 1. \end{cases}$$

$$\therefore \frac{\partial q}{\partial x}(t+0, t) - \frac{\partial q}{\partial x}(t-0, t)$$

$$= t - (t-1) = t - t + 1 = 1.$$

This can be expressed as,

$$\frac{\partial q}{\partial x}(t+0, t) - \frac{\partial q}{\partial x}(t-0, t) = -\frac{1}{p(t)}.$$