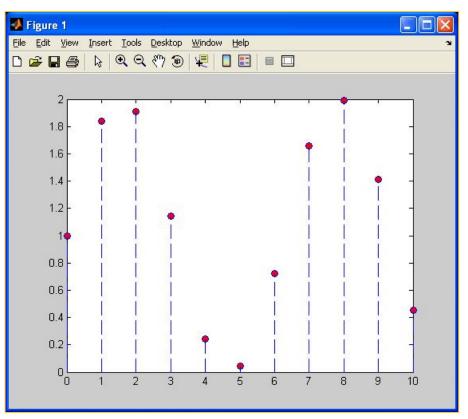
#### **Interpolation**

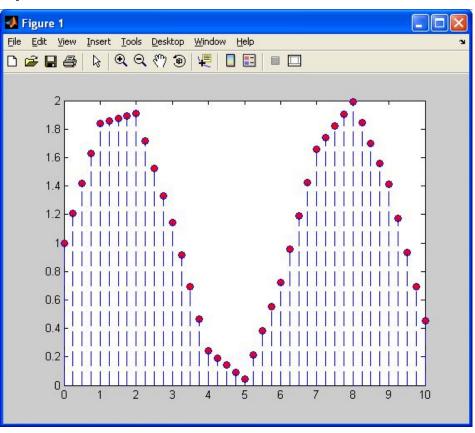
the estimation of the value of f(x), or a function of x, from certain known values of the function. If  $x_0 < ... < x_n$  and  $y_0 = f(x_0),..., y_n = f(x_n)$  are known, and if  $x_0 < x < x_n$ , then the estimated value of f(x) is said to be an interpolation. If  $x < x_0$  or  $x > x_n$ , the estimated value of f(x) is said to be an extrapolation.

1 dimension data (pixel value of 11 points are given in

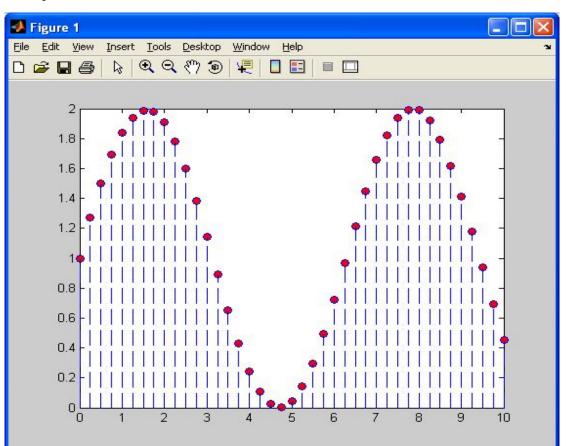
graph)



# Linear interpolation



# Cubic interpolation



#### B spline interpolation

A spline is a piecewise polynomial representation of a smooth curve which connects a set of knots. Each piece of the spline between two consecutive knots is called a patch. On each patch, the spline is represented by a polynomial function of degree d.

The polynomials on patches are written as a function of an intrinsic parameter **t** which follows the curve of the spline. Given a set of n knots ti delimiting the ends of the patches, n – 1 patches can be defined between knots t1 and tn

All patches should be continuous and derivatives at knots.

In above images x axis can be view as intrinsic parameter t .

Knots are at  $t = [0 \ 1 \ 2 \ 3 \ 4 \ 5 \ 6 \ 7 \ 8 \ 9 \ 10 \ ]$ 

We can see that at knots point pixel values are defined . patches should be defined in between the these values like between [0, 1), [1,2) ..... [9, 10)

#### B spline interpolation

Patch is built as a linear combination of basis functions (B-spline functions) whose influence is driven by a set of neighboring control points  $P_i$ 

$$c_t = \Sigma_{i=0}^n P_i B_{i,d}(t)$$

t is the intrinsic parameter of a spatial system that follows the spline curve,

**c(t)** = spline curve coordinates evaluated at t in the Cartesian coordinate system

 $P_i$  are the control point coordinates

**n** is the number of fit knots,

d is the degree of the parametric curve,

 $B_{i,d}(t)$  are the d-degree blending functions or the d-degree B-spline functions that can be defined by the Cox-de-Boor recursive algorithm.

# B spline function

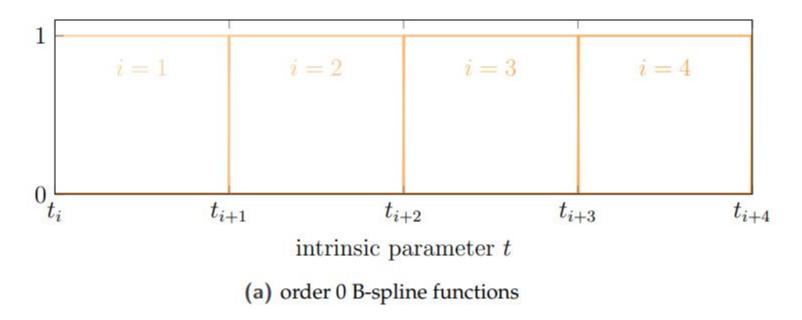
$$B_{i,0}(t) = \begin{cases} 1 \text{ if } t \in [t_i, t_{i+1}] \\ 0 \text{ if } t \notin [t_i, t_{i+1}] \end{cases}$$

$$B_{i,d}(t) = \frac{t - t_i}{t_{i+d} - t_i} B_{i,d-1}(t) + \frac{t_{i+d+1} - t}{t_{i+d+1} - t_{i+1}} B_{i+1,d-1}(t)$$

## Constant B spline function for (0-degree)

$$B_{i,0}(t) = \begin{cases} 1 \text{ if } t \in [t_i, t_{i+1}] \\ 0 \text{ if } t \notin [t_i, t_{i+1}] \end{cases}$$

## Constant B spline function for (0-degree)

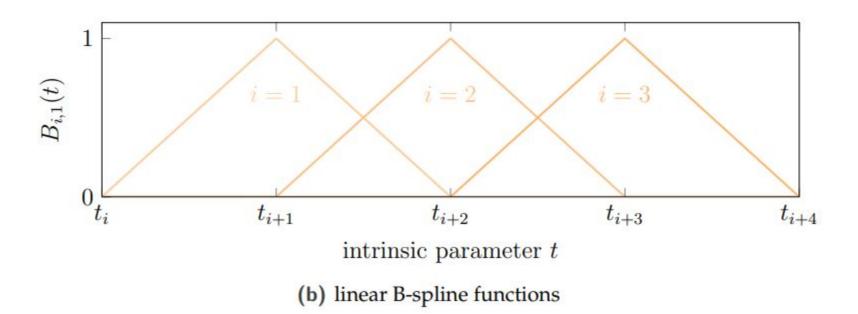


# Linear B spline function for (1-degree)

$$B_{i,1}(t) = \frac{t - t_i}{t_{i+1} - t_i} B_{i,0}(t) + \frac{t_{i+2} - t}{t_{i+2} - t_{i+1}} B_{i+1,0}(t)$$

$$B_{i,1}(t) = \begin{cases} \frac{t-t_i}{t_{i+1}-t_i} & \text{if } t \in [t_i, t_{i+1}] \\ \frac{t_{i+2}-t}{t_{i+2}-t_{i+1}} & \text{if } t \in [t_{i+1}, t_{i+2}] \\ 0 & \text{otherwise} \end{cases}$$

## Linear B spline function for (1-degree)

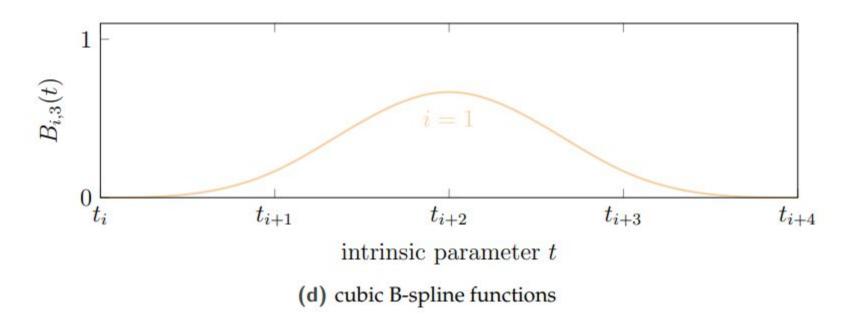


## cubic B spline function for (3-degree)

$$B_{i,3}(t) = \frac{t - t_i}{t_{i+3} - t_i} B_{i,2}(t) + \frac{t_{i+4} - t}{t_{i+4} - t_{i+1}} B_{i+1,2}(t)$$
(10)

$$B_{i,3}(t) = \begin{cases} \frac{t-t_i}{t_{i+3}-t_i} \frac{t-t_i}{t_{i+2}-t_i} \frac{t-t_i}{t_{i+1}-t_i} & \text{if } t \in [t_i, t_{i+1}] \\ \frac{t-t_i}{t_{i+3}-t_i} \left[ \frac{t-t_i}{t_{i+2}-t_i} \frac{t_{i+2}-t}{t_{i+2}-t_{i+1}} + \frac{t_{i+3}-t}{t_{i+3}-t_{i+1}} \frac{t-t_{i+1}}{t_{i+2}-t_{i+1}} \right] + \frac{t_{i+4}-t}{t_{i+4}-t_{i+1}} \frac{t-t_{i+1}}{t_{i+3}-t_{i+1}} \frac{t-t_{i+1}}{t_{i+2}-t_{i+1}} & \text{if } t \in [t_{i+1}, t_{i+2}] \\ \frac{t-t_i}{t_{i+3}-t_i} \frac{t_{i+3}-t}{t_{i+3}-t_{i+1}} \frac{t_{i+3}-t}{t_{i+3}-t_{i+2}} + \frac{t_{i+4}-t}{t_{i+4}-t_{i+1}} \left[ \frac{t-t_{i+1}}{t_{i+3}-t_{i+1}} \frac{t_{i+3}-t}{t_{i+3}-t_{i+2}} + \frac{t_{i+4}-t}{t_{i+4}-t_{i+2}} \frac{t-t_{i+2}}{t_{i+3}-t_{i+2}} \right] & \text{if } t \in [t_{i+2}, t_{i+3}] \\ \frac{t_{i+4}-t}{t_{i+4}-t_{i+1}} \frac{t_{i+4}-t}{t_{i+4}-t_{i+2}} \frac{t_{i+4}-t}{t_{i+4}-t_{i+3}} & \text{if } t \in [t_{i+3}, t_{i+4}] \\ 0 & \text{otherwise} \end{cases}$$

## cubic B spline function for (3-degree)



## Assignment 2 Q1

Find value of f(2.5) using b spline interpolation 0, 1 and 3 degree.:

$$f(0) = 2$$

$$f(1) = 3$$

$$f(2) = 4$$

$$f(3) = 2$$

$$f(4) = 5$$

#### Assignment 2 Q2

- 2. Scale the following image (1 x 10 pixel) 2 times in x-direction with the help of
- a. 0-degree b-spline function
- b. 1-degree b-spline function
- c. 3-degree b-spline function

Intensity of each pixel value is given corresponding to its index.

Pixel value	10	20	30	40	50	60	70	80	90	100
Index	0	1	2	3	4	5	6	7	8	9