

```
from google.colab import drive
drive.mount('/content/drive')
```

Mounted at /content/drive

```
import sys, os, distutils.core
# Note: This is a faster way to install detectron2 in Colab, but it does not include all functionalities (e.g. compiled operators).
# See https://detectron2.readthedocs.io/tutorials/install.html for full installation instructions
!git clone 'https://github.com/facebookresearch/detectron2'
dist = distutils.core.run_setup("./detectron2/setup.py")
!python -m pip install {' '.join([f'{x}' for x in dist.install_requires])}
sys.path.insert(0, os.path.abspath('./detectron2'))
```

Downloading black-23.12.1-cp310-cp310-manylinux_2_17_x86_64.manylinux2014_x86_64.whl (1.7 MB)

1.7/1.7 MB 21.0 MB/s eta 0:00:00

Requirement already satisfied: packaging in /usr/local/lib/python3.10/dist-packages (23.2)
Requirement already satisfied: contourpy>=1.0.1 in /usr/local/lib/python3.10/dist-packages (from matplotlib) (1.2.0)
Requirement already satisfied: cycler>=0.10 in /usr/local/lib/python3.10/dist-packages (from matplotlib) (0.12.1)
Requirement already satisfied: fonttools>=4.22.0 in /usr/local/lib/python3.10/dist-packages (from matplotlib) (4.47.2)
Requirement already satisfied: kiwisolver>=1.0.1 in /usr/local/lib/python3.10/dist-packages (from matplotlib) (1.4.5)

```

Requirement already satisfied: pyasn1-modules<=0.2.1 in /usr/local/lib/python3.10/dist-packages (from google-auth<3,>=1.6.3->tensorboard)
Requirement already satisfied: rsa<5,>=3.1.4 in /usr/local/lib/python3.10/dist-packages (from google-auth<3,>=1.6.3->tensorboard) (4.9)
Requirement already satisfied: requests-oauthlib<=0.7.0 in /usr/local/lib/python3.10/dist-packages (from google-auth-oauthlib<2,>=0.5->ten
Requirement already satisfied: charset-normalizer<4,>=2 in /usr/local/lib/python3.10/dist-packages (from requests<3,>=2.21.0->tensorboard)
Requirement already satisfied: idna<4,>=2.5 in /usr/local/lib/python3.10/dist-packages (from requests<3,>=2.21.0->tensorboard) (3.6)
Requirement already satisfied: urllib3<3,>=1.21.1 in /usr/local/lib/python3.10/dist-packages (from requests<3,>=2.21.0->tensorboard) (2.0.
Requirement already satisfied: certifi<=2017.4.17 in /usr/local/lib/python3.10/dist-packages (from requests<3,>=2.21.0->tensorboard) (2023
Requirement already satisfied: MarkupSafe<=2.1.1 in /usr/local/lib/python3.10/dist-packages (from werkzeug<=1.0.1->tensorboard) (2.1.3)
Requirement already satisfied: pyasn1<0.6.0,>=0.4.6 in /usr/local/lib/python3.10/dist-packages (from pyasn1-modules<=0.2.1->google-auth<3,
Requirement already satisfied: oauthlib<=3.0.0 in /usr/local/lib/python3.10/dist-packages (from requests-oauthlib<=0.7.0->google-auth-oaut
Building wheels for collected packages: fvcare, antlr4-python3-runtime
  Building wheel for fvcare (setup.py) ... done
  Created wheel for fvcare: filename=fvcare-0.1.5.post20221221-py3-none-any.whl size=61400 sha256=7285d9663b781f1a860629af009c322e3163b1a9
  Stored in directory: /root/.cache/pip/wheels/01/c0/af/77c1cf53a1be9e42a52b48e5af2169d40ec2e89f7362489dd0
  Building wheel for antlr4-python3-runtime (setup.py) ... done
  Created wheel for antlr4-python3-runtime: filename=antlr4_python3_runtime-4.9.3-py3-none-any.whl size=144554 sha256=5fa95887f4c202698155
  Stored in directory: /root/.cache/pip/wheels/12/93/dd/1f6a127edc45659556564c5730f6d4e300888f4bca2d4c5a88
Successfully built fvcare antlr4-python3-runtime
Installing collected packages: antlr4-python3-runtime, yacs, portalocker, pathspec, omegaconf, mypy-extensions, iopath, hydra-core, black,
Successfully installed antlr4-python3-runtime-4.9.3 black-23.12.1 fvcare-0.1.5.post20221221 hydra-core-1.3.2 iopath-0.1.9 mypy-extensions-

```

```

import torch, detectron2
!nvcc --version
TORCH_VERSION = ".".join(torch.__version__.split(".")[:2])
CUDA_VERSION = torch.__version__.split("+")[-1]
print("torch: ", TORCH_VERSION, "; cuda: ", CUDA_VERSION)
print("detectron2:", detectron2.__version__)

```

```

nvcc: NVIDIA (R) Cuda compiler driver
Copyright (c) 2005-2023 NVIDIA Corporation
Built on Tue_Aug_15_22:02:13_PDT_2023
Cuda compilation tools, release 12.2, V12.2.140
Build cuda_12.2.r12.2/compiler.33191640_0
torch: 2.1 ; cuda: cu121
detectron2: 0.6

```

```
# Some basic setup:
# Setup detectron2 logger
import detectron2
from detectron2.utils.logger import setup_logger
setup_logger()
# import some common libraries
import numpy as np
import os, json, cv2, random
from google.colab.patches import cv2_imshow
# import some common detectron2 utilities
from detectron2 import model_zoo
from detectron2.engine import DefaultPredictor
from detectron2.config import get_cfg
from detectron2.utils.visualizer import Visualizer
from detectron2.data import MetadataCatalog, DatasetCatalog

im = cv2.imread("/content/drive/MyDrive/Train 1/20240120_090416.jpg")
cv2_imshow(im)
```





```
cfg = get_cfg()
cfg.merge_from_file(model_zoo.get_config_file("COCO-InstanceSegmentation/mask_rcnn_R_50_FPN_3x.yaml"))
cfg.MODEL.ROI_HEADS.SCORE_THRESH_TEST = 0.5 # set threshold for this model
# Find a model from detectron2's model zoo. https://github.com/facebookresearch/detectron2/blob/main/MODEL_ZOO.md
cfg.MODEL.WEIGHTS = model_zoo.get_checkpoint_url("COCO-InstanceSegmentation/mask_rcnn_R_50_FPN_3x.yaml")
predictor = DefaultPredictor(cfg)
outputs = predictor(im)
```

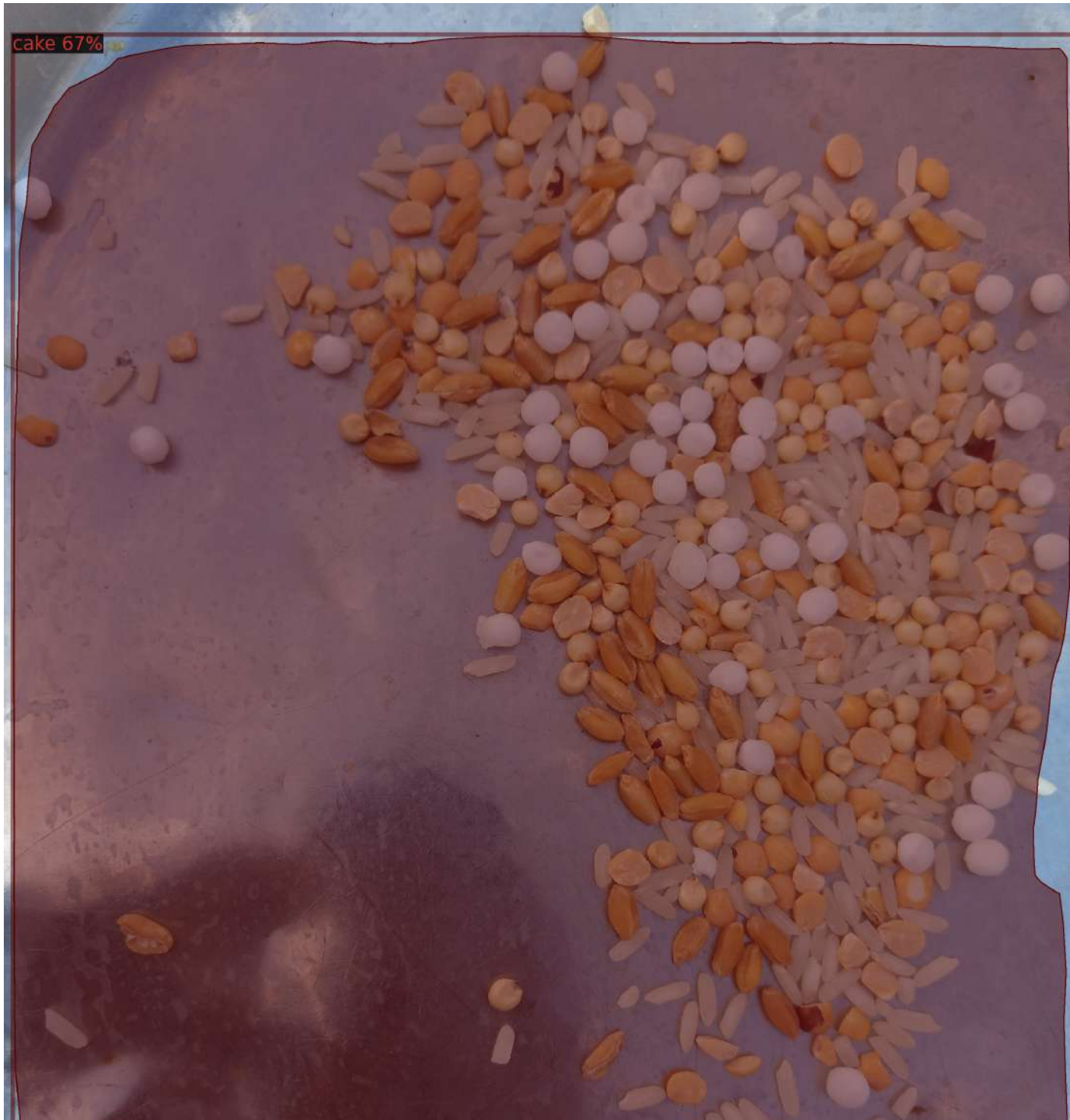
```
[01/21 07:48:27 d2.checkpoint.detection_checkpoint]: [DetectionCheckpointer] Loading from https://dl.fbaipublicfiles.com/detectron2/COCO-Insta
model_final_f10217.pkl: 178MB [00:00, 209MB/s]
```

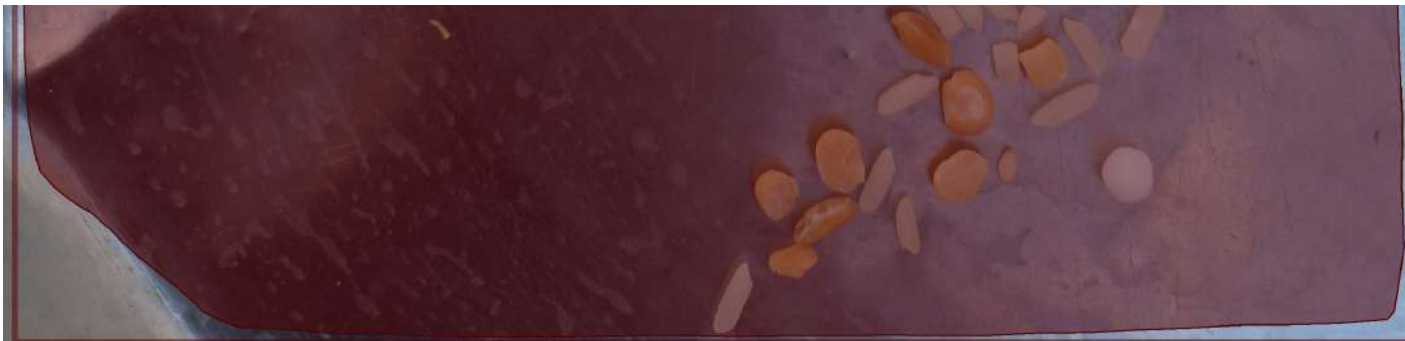
```
/usr/local/lib/python3.10/dist-packages/torch/functional.py:504: UserWarning: torch.meshgrid: in an upcoming release, it will be required to
return _VF.meshgrid(tensors, **kwargs) # type: ignore[attr-defined]
```

```
# look at the outputs - tensors and bounding boxes.
print(outputs["instances"].pred_classes)
print(outputs["instances"].pred_boxes)

    tensor([55], device='cuda:0')
Boxes(tensor([[ 21.5279,  77.5454, 2649.1726, 3398.6694]], device='cuda:0'))

# We can use `Visualizer` to draw the predictions on the image.
v = Visualizer(im[:, :, :-1], MetadataCatalog.get(cfg.DATASETS.TRAIN[0]), scale=0.8)
out = v.draw_instance_predictions(outputs["instances"].to("cpu"))
cv2_imshow(out.get_image()[:, :, :-1])
```



```
from detectron2.data.datasets import register_coco_instances
register_coco_instances("dataset_train", {}, "/content/drive/MyDrive/Train 1/labels_my-project-name_2024-01-20-01-51-10.json", "/content/drive/MyDrive/Train 1/images_my-project-name_2024-01-20-01-51-10")
register_coco_instances("dataset_val", {}, "/content/drive/MyDrive/Test/labels_my-project-name_2024-01-20-10-00-25-1.json", "/content/drive/MyDrive/Test/images_my-project-name_2024-01-20-10-00-25-1")
```

```
train_metadata = MetadataCatalog.get("dataset_train")
train_dataset_dicts = DatasetCatalog.get("dataset_train")
```

```
[01/21 07:51:04 d2.data.datasets.coco]: Loaded 5 images in COCO format from /content/drive/MyDrive/Train 1/labels_my-project-name_2024-01-20-01-51-10.json
```

```
val_metadata = MetadataCatalog.get("dataset_val")
val_dataset_dicts = DatasetCatalog.get("dataset_val")
```


[01/21 07:51:08 d2.data.datasets.coco]: Loaded 3 images in COCO format from /content/drive/MyDrive/Test/labels_my-project-name_2024-01-20-16

```
from detectron2.engine import DefaultTrainer

cfg = get_cfg()
cfg.OUTPUT_DIR = "/content/drive/MyDrive/Train 1"
cfg.merge_from_file(model_zoo.get_config_file("COCO-InstanceSegmentation/mask_rcnn_R_50_FPN_3x.yaml"))
cfg.DATASETS.TRAIN = ("dataset_train",)
cfg.DATASETS.TEST = ()
cfg.DATALOADER.NUM_WORKERS = 2
cfg.MODEL.WEIGHTS = model_zoo.get_checkpoint_url("COCO-InstanceSegmentation/mask_rcnn_R_50_FPN_3x.yaml") # Let training initialize from model :
cfg.SOLVER.IMS_PER_BATCH = 2 # This is the real "batch size" commonly known to deep learning people
cfg.SOLVER.BASE_LR = 0.00025 # pick a good LR
cfg.SOLVER.MAX_ITER = 1000 # 1000 iterations seems good enough for this dataset
cfg.SOLVER.STEPS = [] # do not decay learning rate
cfg.MODEL.ROI_HEADS.BATCH_SIZE_PER_IMAGE = 256 # Default is 512, using 256 for this dataset.
cfg.MODEL.ROI_HEADS.NUM_CLASSES = 5 # We have 5 classes.
# NOTE: this config means the number of classes, without the background. Do not use num_classes+1 here.

os.makedirs(cfg.OUTPUT_DIR, exist_ok=True)
trainer = DefaultTrainer(cfg) #Create an instance of of DefaultTrainer with the given congiguration
trainer.resume_or_load(resume=False) #Load a pretrained model if available (resume training) or start training from scratch if no pretrained moc
```

```
(deconv): ConvTranspose2d(256, 256, kernel_size=(2, 2), stride=(2, 2))
(deconv_relu): ReLU()
(predictor): Conv2d(256, 5, kernel_size=(1, 1), stride=(1, 1))
)
)
[01/21 07:51:27 d2.data.datasets.coco]: Loaded 5 images in COCO format from /content/drive/MyDrive/Train 1/labels_my-project-name_2024-01-
[01/21 07:51:27 d2.data.build]: Removed 0 images with no usable annotations. 5 images left.
[01/21 07:51:27 d2.data.build]: Distribution of instances among all 5 categories:
| category | #instances | category | #instances | category | #instances |
|:-----:|:-----:|:-----:|:-----:|:-----:|:-----:|
| Shabu    | 25         | wheat    | 25         | jowar    | 24         |
| Dal      | 25         | Rise     | 25         |          |           |
| total    | 124        |          |           |          |           |
[01/21 07:51:27 d2.data.dataset_mapper]: [DatasetMapper] Augmentations used in training: [ResizeShortestEdge(short_edge_length=(640, 672,
[01/21 07:51:27 d2.data.build]: Using training sampler TrainingSampler
[01/21 07:51:27 d2.data.common]: Serializing the dataset using: <class 'detectron2.data.common._TorchSerializedList'>
[01/21 07:51:27 d2.data.common]: Serializing 5 elements to byte tensors and concatenating them all ...
[01/21 07:51:27 d2.data.common]: Serialized dataset takes 0.03 MiB
[01/21 07:51:27 d2.data.build]: Making batched data loader with batch_size=2
[01/21 07:51:27 d2.checkpoint.detection_checkpoint]: [DetectionCheckpointer] Loading from https://dl.fbaipublicfiles.com/detectron2/COCO-Insta
WARNING:fvcore.common.checkpoint:Skip loading parameter 'roi_heads.box_predictor.cls_score.weight' to the model due to incompatible shapes
WARNING:fvcore.common.checkpoint:Skip loading parameter 'roi_heads.box_predictor.cls_score.bias' to the model due to incompatible shapes:
WARNING:fvcore.common.checkpoint:Skip loading parameter 'roi_heads.box_predictor.bbox_pred.weight' to the model due to incompatible shapes
WARNING:fvcore.common.checkpoint:Skip loading parameter 'roi_heads.box_predictor.bbox_pred.bias' to the model due to incompatible shapes:
WARNING:fvcore.common.checkpoint:Skip loading parameter 'roi_heads.mask_head.predictor.weight' to the model due to incompatible shapes: (8
WARNING:fvcore.common.checkpoint:Skip loading parameter 'roi_heads.mask_head.predictor.bias' to the model due to incompatible shapes: (80,
WARNING:fvcore.common.checkpoint:Some model parameters or buffers are not found in the checkpoint:
roi_heads.box_predictor.bbox_pred.{bias, weight}
roi_heads.box_predictor.cls_score.{bias, weight}
roi_heads.mask_head.predictor.{bias, weight}
```

trainer.train() #Start the training process

```
[01/21 07:51:42 d2.engine.train_loop]: Starting training from iteration 0
[01/21 07:52:03 d2.utils.events]: eta: 0:12:05 iter: 19 total_loss: 4.861 loss_cls: 2.004 loss_box_reg: 0.1805 loss_mask: 0.6973 loss
[01/21 07:52:21 d2.utils.events]: eta: 0:11:32 iter: 39 total_loss: 3.213 loss_cls: 1.776 loss_box_reg: 0.221 loss_mask: 0.6924 loss
[01/21 07:52:36 d2.utils.events]: eta: 0:11:18 iter: 59 total_loss: 2.779 loss_cls: 1.538 loss_box_reg: 0.2212 loss_mask: 0.6824 loss
[01/21 07:52:51 d2.utils.events]: eta: 0:10:44 iter: 79 total_loss: 2.477 loss_cls: 1.275 loss_box_reg: 0.2214 loss_mask: 0.6677 loss
[01/21 07:53:07 d2.utils.events]: eta: 0:10:30 iter: 99 total_loss: 2.191 loss_cls: 0.9907 loss_box_reg: 0.2292 loss_mask: 0.6481 los
[01/21 07:53:22 d2.utils.events]: eta: 0:10:16 iter: 119 total_loss: 1.955 loss_cls: 0.8549 loss_box_reg: 0.2098 loss_mask: 0.6252 lc
[01/21 07:53:38 d2.utils.events]: eta: 0:10:02 iter: 139 total_loss: 1.903 loss_cls: 0.8119 loss_box_reg: 0.2323 loss_mask: 0.6019 lc
[01/21 07:53:54 d2.utils.events]: eta: 0:09:56 iter: 159 total_loss: 1.873 loss_cls: 0.8139 loss_box_reg: 0.2586 loss_mask: 0.5739 lc
[01/21 07:54:09 d2.utils.events]: eta: 0:09:38 iter: 179 total_loss: 1.845 loss_cls: 0.802 loss_box_reg: 0.2433 loss_mask: 0.5451 los
[01/21 07:54:25 d2.utils.events]: eta: 0:09:28 iter: 199 total_loss: 1.783 loss_cls: 0.7934 loss_box_reg: 0.269 loss_mask: 0.5186 los
[01/21 07:54:42 d2.utils.events]: eta: 0:09:11 iter: 219 total_loss: 1.787 loss_cls: 0.7808 loss_box_reg: 0.2764 loss_mask: 0.4888 lc
[01/21 07:54:57 d2.utils.events]: eta: 0:09:00 iter: 239 total_loss: 1.737 loss_cls: 0.7811 loss_box_reg: 0.2765 loss_mask: 0.4605 lc
[01/21 07:55:13 d2.utils.events]: eta: 0:08:51 iter: 259 total_loss: 1.725 loss_cls: 0.7766 loss_box_reg: 0.2873 loss_mask: 0.4333 lc
[01/21 07:55:29 d2.utils.events]: eta: 0:08:38 iter: 279 total_loss: 1.697 loss_cls: 0.7629 loss_box_reg: 0.3119 loss_mask: 0.4193 lc
[01/21 07:55:50 d2.utils.events]: eta: 0:08:33 iter: 299 total_loss: 1.653 loss_cls: 0.7603 loss_box_reg: 0.3051 loss_mask: 0.3987 lc
[01/21 07:56:05 d2.utils.events]: eta: 0:08:13 iter: 319 total_loss: 1.67 loss_cls: 0.7643 loss_box_reg: 0.3368 loss_mask: 0.3876 los
[01/21 07:56:21 d2.utils.events]: eta: 0:08:00 iter: 339 total_loss: 1.665 loss_cls: 0.7546 loss_box_reg: 0.3584 loss_mask: 0.3702 lc
```

```

[01/21 07:56:36 d2.utils.events]: eta: 0:07:45 iter: 359 total_loss: 1.589 loss_cls: 0.7219 loss_box_reg: 0.3326 loss_mask: 0.3563 lc
[01/21 07:56:51 d2.utils.events]: eta: 0:07:31 iter: 379 total_loss: 1.577 loss_cls: 0.7217 loss_box_reg: 0.3581 loss_mask: 0.3418 lc
[01/21 07:57:07 d2.utils.events]: eta: 0:07:16 iter: 399 total_loss: 1.526 loss_cls: 0.6992 loss_box_reg: 0.3541 loss_mask: 0.326 los
[01/21 07:57:22 d2.utils.events]: eta: 0:06:59 iter: 419 total_loss: 1.508 loss_cls: 0.6751 loss_box_reg: 0.3671 loss_mask: 0.3076 lc
[01/21 07:57:37 d2.utils.events]: eta: 0:06:46 iter: 439 total_loss: 1.467 loss_cls: 0.6459 loss_box_reg: 0.3833 loss_mask: 0.2852 lc
[01/21 07:57:52 d2.utils.events]: eta: 0:06:30 iter: 459 total_loss: 1.39 loss_cls: 0.621 loss_box_reg: 0.3636 loss_mask: 0.2686 loss
[01/21 07:58:08 d2.utils.events]: eta: 0:06:19 iter: 479 total_loss: 1.379 loss_cls: 0.6084 loss_box_reg: 0.3836 loss_mask: 0.2465 lc
[01/21 07:58:24 d2.utils.events]: eta: 0:06:04 iter: 499 total_loss: 1.357 loss_cls: 0.5713 loss_box_reg: 0.3852 loss_mask: 0.2407 lc
[01/21 07:58:39 d2.utils.events]: eta: 0:05:49 iter: 519 total_loss: 1.286 loss_cls: 0.5526 loss_box_reg: 0.3806 loss_mask: 0.2291 lc
[01/21 07:58:54 d2.utils.events]: eta: 0:05:35 iter: 539 total_loss: 1.257 loss_cls: 0.5274 loss_box_reg: 0.3726 loss_mask: 0.2227 lc
[01/21 07:59:10 d2.utils.events]: eta: 0:05:21 iter: 559 total_loss: 1.219 loss_cls: 0.5142 loss_box_reg: 0.3823 loss_mask: 0.2201 lc
[01/21 07:59:25 d2.utils.events]: eta: 0:05:05 iter: 579 total_loss: 1.199 loss_cls: 0.4881 loss_box_reg: 0.3788 loss_mask: 0.2128 lc
[01/21 07:59:41 d2.utils.events]: eta: 0:04:51 iter: 599 total_loss: 1.14 loss_cls: 0.464 loss_box_reg: 0.3596 loss_mask: 0.2085 loss
[01/21 07:59:57 d2.utils.events]: eta: 0:04:36 iter: 619 total_loss: 1.109 loss_cls: 0.4489 loss_box_reg: 0.3523 loss_mask: 0.2075 lc
[01/21 08:00:12 d2.utils.events]: eta: 0:04:21 iter: 639 total_loss: 1.078 loss_cls: 0.4362 loss_box_reg: 0.3395 loss_mask: 0.2034 lc
[01/21 08:00:27 d2.utils.events]: eta: 0:04:07 iter: 659 total_loss: 1.083 loss_cls: 0.4187 loss_box_reg: 0.3491 loss_mask: 0.2045 lc
[01/21 08:00:43 d2.utils.events]: eta: 0:03:53 iter: 679 total_loss: 1.023 loss_cls: 0.3993 loss_box_reg: 0.3235 loss_mask: 0.2018 lc
[01/21 08:00:58 d2.utils.events]: eta: 0:03:38 iter: 699 total_loss: 0.9916 loss_cls: 0.3891 loss_box_reg: 0.3193 loss_mask: 0.1989 l
[01/21 08:01:13 d2.utils.events]: eta: 0:03:24 iter: 719 total_loss: 0.9541 loss_cls: 0.3613 loss_box_reg: 0.3065 loss_mask: 0.1891 l
[01/21 08:01:29 d2.utils.events]: eta: 0:03:09 iter: 739 total_loss: 0.9566 loss_cls: 0.358 loss_box_reg: 0.3021 loss_mask: 0.1972 lc
[01/21 08:01:44 d2.utils.events]: eta: 0:02:55 iter: 759 total_loss: 0.9427 loss_cls: 0.3315 loss_box_reg: 0.3029 loss_mask: 0.1947 l
[01/21 08:01:59 d2.utils.events]: eta: 0:02:40 iter: 779 total_loss: 0.8965 loss_cls: 0.3189 loss_box_reg: 0.2837 loss_mask: 0.1913 l
[01/21 08:02:14 d2.utils.events]: eta: 0:02:25 iter: 799 total_loss: 0.8515 loss_cls: 0.3044 loss_box_reg: 0.2648 loss_mask: 0.1832 l
[01/21 08:02:29 d2.utils.events]: eta: 0:02:11 iter: 819 total_loss: 0.8281 loss_cls: 0.2944 loss_box_reg: 0.2664 loss_mask: 0.1842 l
[01/21 08:02:45 d2.utils.events]: eta: 0:01:56 iter: 839 total_loss: 0.8076 loss_cls: 0.2825 loss_box_reg: 0.2624 loss_mask: 0.1821 l
[01/21 08:03:00 d2.utils.events]: eta: 0:01:41 iter: 859 total_loss: 0.8368 loss_cls: 0.306 loss_box_reg: 0.2439 loss_mask: 0.1828 lc
[01/21 08:03:15 d2.utils.events]: eta: 0:01:26 iter: 879 total_loss: 0.785 loss_cls: 0.2736 loss_box_reg: 0.2434 loss_mask: 0.1799 lc
[01/21 08:03:30 d2.utils.events]: eta: 0:01:12 iter: 899 total_loss: 0.7491 loss_cls: 0.2496 loss_box_reg: 0.2399 loss_mask: 0.177 lc
[01/21 08:03:46 d2.utils.events]: eta: 0:00:57 iter: 919 total_loss: 0.7159 loss_cls: 0.2252 loss_box_reg: 0.2345 loss_mask: 0.1789 l
[01/21 08:04:01 d2.utils.events]: eta: 0:00:43 iter: 939 total_loss: 0.6785 loss_cls: 0.2095 loss_box_reg: 0.2272 loss_mask: 0.1748 l
[01/21 08:04:16 d2.utils.events]: eta: 0:00:28 iter: 959 total_loss: 0.6898 loss_cls: 0.2067 loss_box_reg: 0.2185 loss_mask: 0.1715 l
[01/21 08:04:32 d2.utils.events]: eta: 0:00:14 iter: 979 total_loss: 0.6716 loss_cls: 0.201 loss_box_reg: 0.2281 loss_mask: 0.1733 lc
[01/21 08:04:48 d2.utils.events]: eta: 0:00:00 iter: 999 total_loss: 0.6857 loss_cls: 0.2266 loss_box_reg: 0.2044 loss_mask: 0.1698 l
[01/21 08:04:48 d2.engine.hooks]: Overall training speed: 998 iterations in 0:12:54 (0.7761 s / it)
[01/21 08:04:48 d2.engine.hooks]: Total training time: 0:13:00 (0:00:05 on hooks)

```

```

# Look at training curves in tensorboard:
%load_ext tensorboard
%tensorboard --logdir output

```

403. That's an error.

That's all we know.


```

import yaml
# Save the configuration to a config.yaml file
# Save the configuration to a config.yaml file
config_yaml_path = "/content/drive/MyDrive/Train 1/config.yaml"
with open(config_yaml_path, 'w') as file:
    yaml.dump(cfg, file)

# Inference should use the config with parameters that are used in training
# cfg now already contains everything we've set previously. We changed it a little bit for inference:
cfg.MODEL.WEIGHTS = os.path.join(cfg.OUTPUT_DIR, "model_final.pth") # path to the model we just trained
cfg.MODEL.ROI_HEADS.SCORE_THRESH_TEST = 0.5 # set a custom testing threshold
predictor = DefaultPredictor(cfg)

[01/21 08:05:37 d2.checkpoint.detection_checkpoint]: [DetectionCheckpointer] Loading from /content/drive/MyDrive/Train 1/model_final.pth ...

```

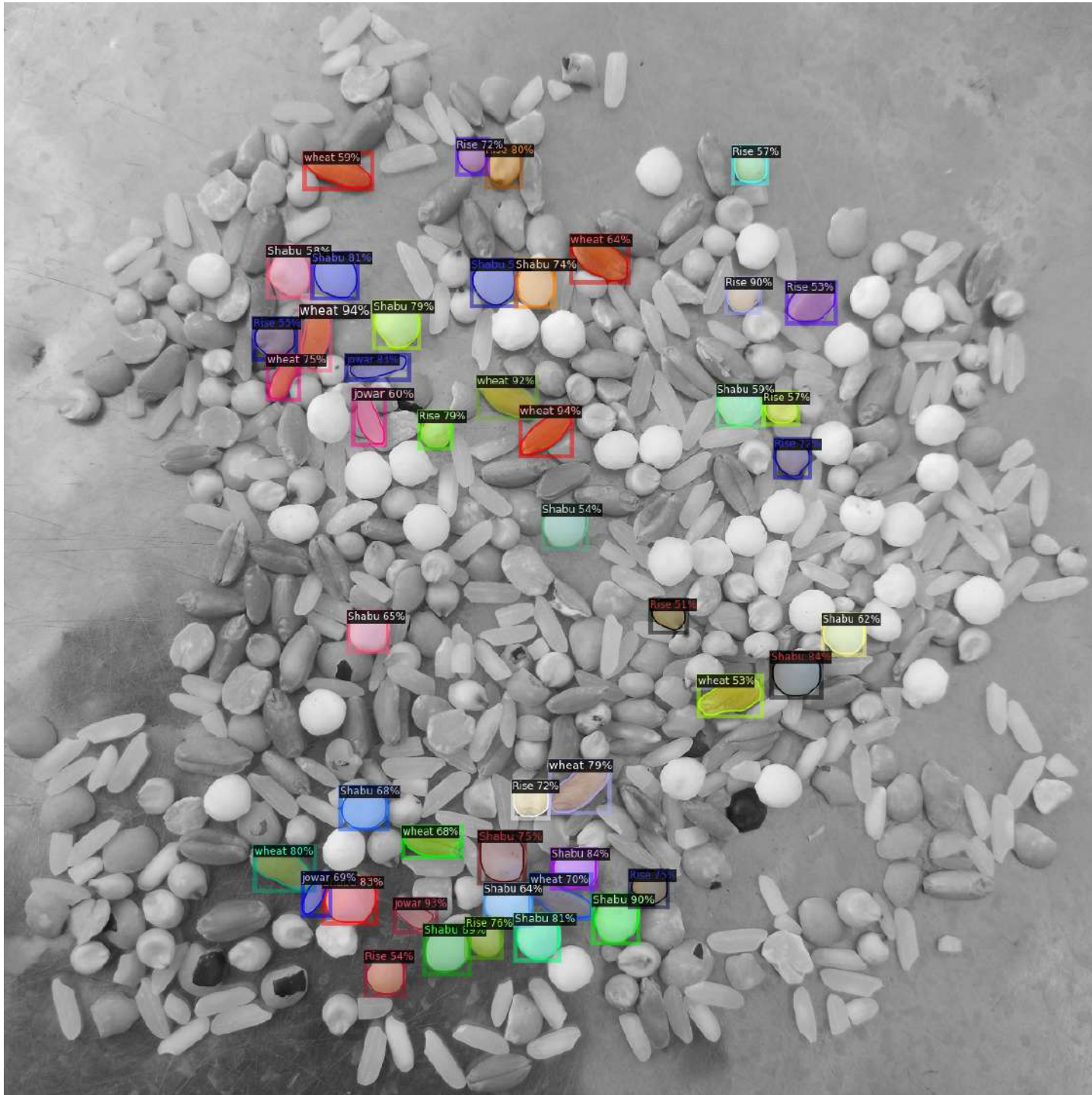


```

from detectron2.utils.visualizer import ColorMode

for d in random.sample(val_dataset_dicts, 1): #select number of images for display
    im = cv2.imread(d["file_name"])
    outputs = predictor(im)
    v = Visualizer(im[:, :, ::-1],
                    metadata=val_metadata,
                    scale=0.5,
                    instance_mode=ColorMode.IMAGE_BW # remove the colors of unsegmented pixels. This option is only available for segmentation
    )
    out = v.draw_instance_predictions(outputs["instances"].to("cpu"))
    cv2.imshow(out.get_image()[:, :, ::-1])

```




```
from detectron2.evaluation import COCOEvaluator, inference_on_dataset
from detectron2.data import build_detection_test_loader
evaluator = COCOEvaluator("dataset_val", output_dir="./output")
val_loader = build_detection_test_loader(cfg, "dataset_val")
print(inference_on_dataset(predictor.model, val_loader, evaluator))
# another equivalent way to evaluate the model is to use `trainer.test`

DONE (t=0.03s).
Accumulating evaluation results...
```

```

DONE (t=0.00s)
creating index...
index created!
Running per image evaluation...
Evaluate annotation type *segm*
DONE (t=0.03s).
Accumulating evaluation results...
DONE (t=0.02s).
Average Precision  (AP) @[ IoU=0.50:0.95 | area=   all | maxDets=100 ] = 0.042
Average Precision  (AP) @[ IoU=0.50      | area=   all | maxDets=100 ] = 0.048
Average Precision  (AP) @[ IoU=0.75      | area=   all | maxDets=100 ] = 0.048
Average Precision  (AP) @[ IoU=0.50:0.95 | area= small | maxDets=100 ] = -1.000
Average Precision  (AP) @[ IoU=0.50:0.95 | area=medium | maxDets=100 ] = 0.063
Average Precision  (AP) @[ IoU=0.50:0.95 | area= large | maxDets=100 ] = 0.015
Average Recall     (AR) @[ IoU=0.50:0.95 | area=   all | maxDets=  1 ] = 0.023
Average Recall     (AR) @[ IoU=0.50:0.95 | area=   all | maxDets= 10 ] = 0.067
Average Recall     (AR) @[ IoU=0.50:0.95 | area=   all | maxDets=100 ] = 0.118
Average Recall     (AR) @[ IoU=0.50:0.95 | area= small | maxDets=100 ] = -1.000
Average Recall     (AR) @[ IoU=0.50:0.95 | area=medium | maxDets=100 ] = 0.147
Average Recall     (AR) @[ IoU=0.50:0.95 | area= large | maxDets=100 ] = 0.113
[01/21 08:05:51 d2.evaluation.coco_evaluation]: Evaluation results for segm:
| AP   | AP50 | AP75 | APs  | APm  | APl  |
|:-----|:-----|:-----|:-----|:-----|:-----|
| 4.212 | 4.815 | 4.815 | nan  | 6.283 | 1.497 |
[01/21 08:05:51 d2.evaluation.coco_evaluation]: Some metrics cannot be computed and is shown as NaN.
[01/21 08:05:51 d2.evaluation.coco_evaluation]: Per-category segm AP:
| category | AP   | category | AP   | category | AP   |
|:-----|:-----|:-----|:-----|:-----|:-----|
| Shabu    | 12.857 | wheat    | 1.964 | Rise     | 0.000 |
| Dal      | 6.238  | jowar    | 0.000 |          |       |
OrderedDict({'bbox'. {'AP': 3.9552594253136, 'AP50': 4.814548121478814, 'AP75': 4.814548121478814, 'APs': nan, 'APm': 13.786798679867987,

```

```

new_im = cv2.imread("/content/drive/MyDrive/Test/20240120_091015.jpg")
outputs = predictor(new_im)

```

```

# We can use `Visualizer` to draw the predictions on the image.
v = Visualizer(new_im[:, :, ::-1], metadata=train_metadata)
out = v.draw_instance_predictions(outputs["instances"].to("cpu"))

```

```

cv2.imshow(out.get_image()[:, :, ::-1])

```

