Assoc.professor Naila Allahverdiyeva

NUMERICAL METHODS in ENGINEERING

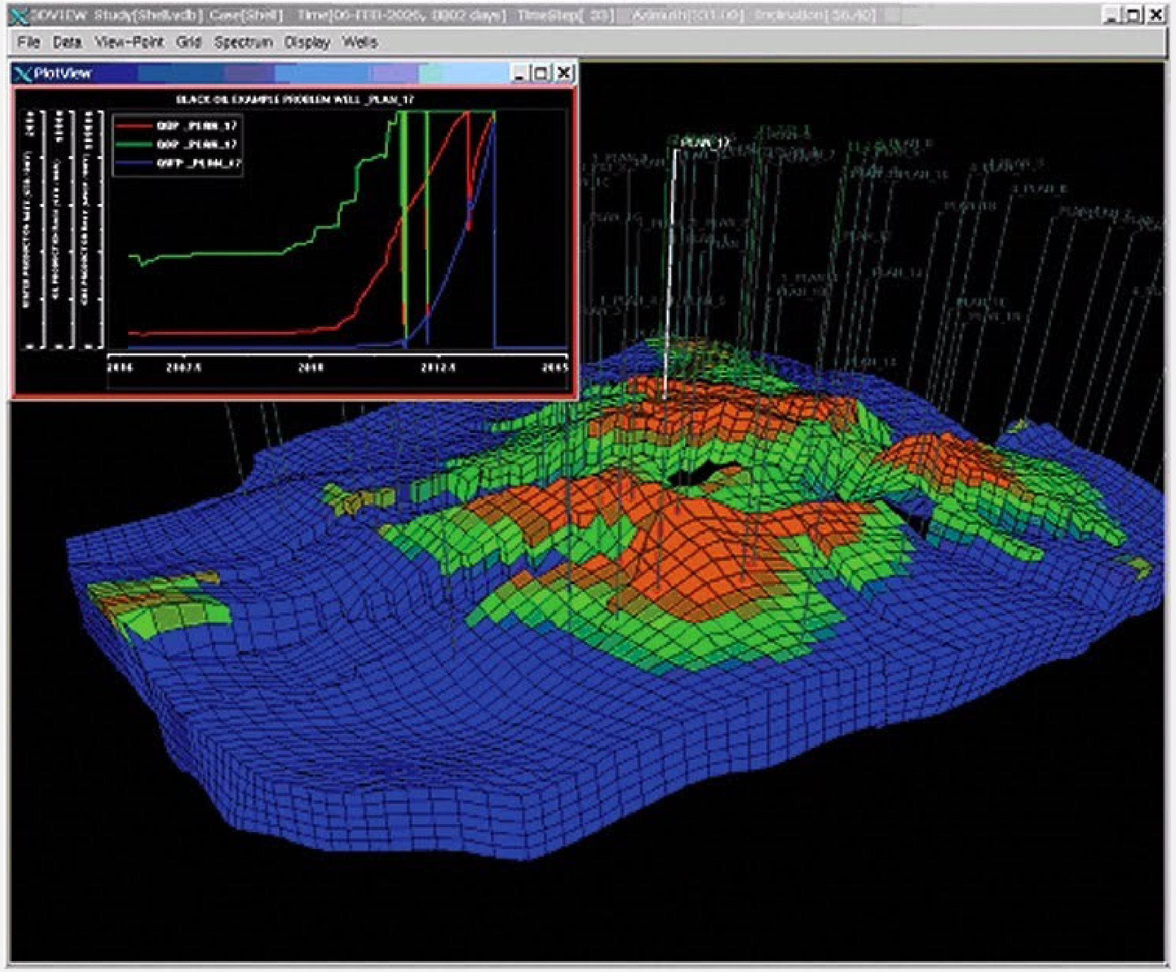
Lecture1: Introduction to Numerical Methods

Requirements for this course

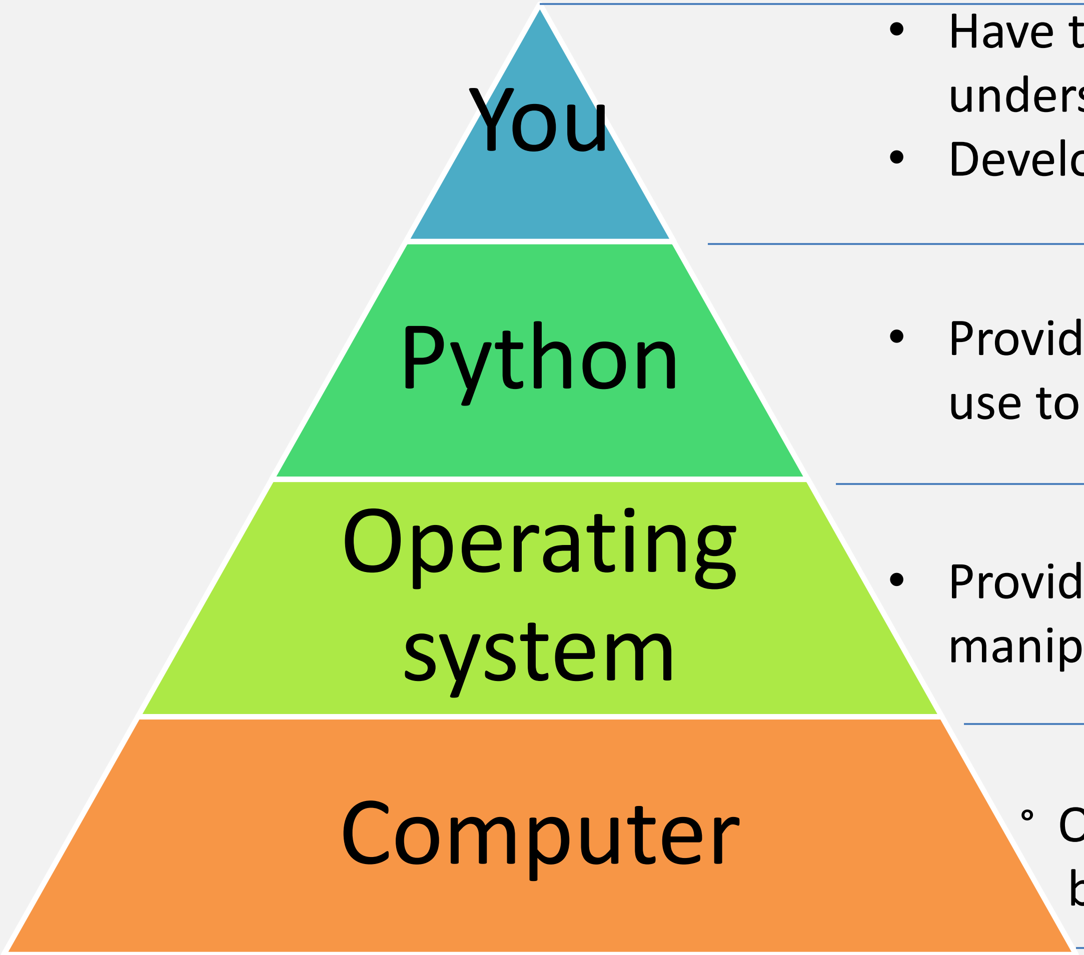
- **Prerequisite**:
- Math, Programming in Python
- **Textbook**:
- Steven C.Chapra, Raymond P. Canale. Numerical Methods for Engineers;
- Jaan Kiusalaas. Numerical Methods in Engineering with Python 3.
- **Software**:
- Python 3 (+Matplotlib, +Numpy, +Scipy)

What are numerical methods?

Numerical methods develop **accurate and fast approximations** to problems whose exact solutions are difficult to find because of their complexity



Why do we need to learn math when we have computers?



- Have the creativity and knowledge to understand a specific problem
- Develop the method to solve it

- Provides the programming language you use to describe how to solve a problem

- Provides ways to represent and manipulate different types of data

- Only knows how to add numbers, but does it quickly

Numerical Methods

Numerical Methods:

Algorithms that are used to obtain numerical solutions of a mathematical problem.

Why do we need them?

1. No analytical solution exists,
2. An analytical solution is difficult to obtain or not practical.

What do we need?

Basic Needs in the Numerical Methods:

- Practical:

  Can be computed in a reasonable amount of time.

- Accurate:
  - Good approximate to the true value,
  - Information about the approximation error (Bounds, error order,…).

Outlines of the Course

- Taylor Theorem
- Number Representation
- Solution of nonlinear Equations
- Interpolation
- Numerical Differentiation
- Numerical Integration

- Solution of linear Equations
- Least Squares curve fitting
- Solution of ordinary differential equations
- Solution of Partial differential equations

Solution of Nonlinear Equations

- Some simple equations can be solved analytically:

$$x^2 + 4x + 3 = 0$$

$$\text{Analytic solution } roots = \frac{-4 \pm \sqrt{4^2 - 4(1)(3)}}{2(1)}$$

$$x = -1 \ and \ \ x = -3$$

- Many other equations have no analytical solution:

$$\left.\begin{array}{c} x^9 - 2x^2 + 5 = 0 \\ x = e^{-x} \end{array}\right\} \text{No analytic solution}$$

Methods for Solving Nonlinear Equations

- Bisection Method
- Newton-Raphson Method
- Secant Method

Solution of Systems of Linear Equations

$$x_1 + x_2 = 3$$

$$x_1 + 2x_2 = 5$$

We can solve it as:

$$x_1 = 3 - x_2 , \qquad 3 - x_2 + 2x_2 = 5$$

$$\Rightarrow x_2 = 2,\ x_1 = 3 - 2 = 1$$

What to do if we have

1000 equations in 1000 unknowns.

Cramer's Rule is Not Practical

Cramer's Rule can be used to solve the system :

$$x_1 = \frac{\begin{vmatrix} 3 & 1 \\ 5 & 2 \end{vmatrix}}{\begin{vmatrix} 1 & 1 \\ 1 & 2 \end{vmatrix}} = 1, \quad x_2 = \frac{\begin{vmatrix} 1 & 3 \\ 1 & 5 \end{vmatrix}}{\begin{vmatrix} 1 & 1 \\ 1 & 2 \end{vmatrix}} = 2$$

But Cramer's Rule is not practical for large problems.

To solve N equations with N unknowns, we need $(N+1)(N-1)N!$ multiplica tions.

To solve a 30 by 30 system, 2.3×10^{35} multiplica tions are needed.

A super computer needs more than 10^{20} years to compute this.

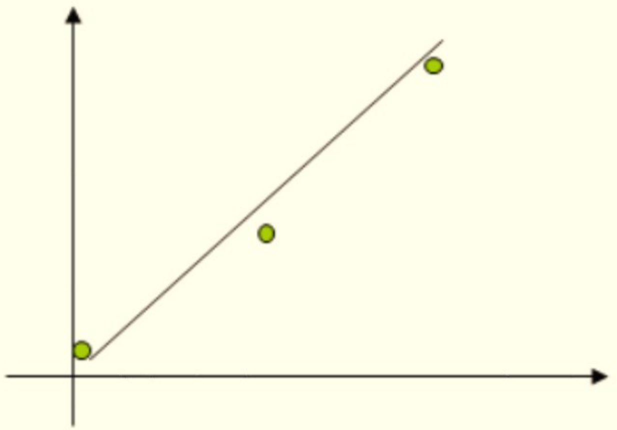
Methods for Solving Systems of Linear Equations

- Naive Gaussian Elimination
- Gaussian Elimination with Scaled Partial Pivoting
- Algorithm for Tri-diagonal Equations

Curve Fitting

- Given a set of data:

x	0	1	2
y	0.5	10.3	21.3

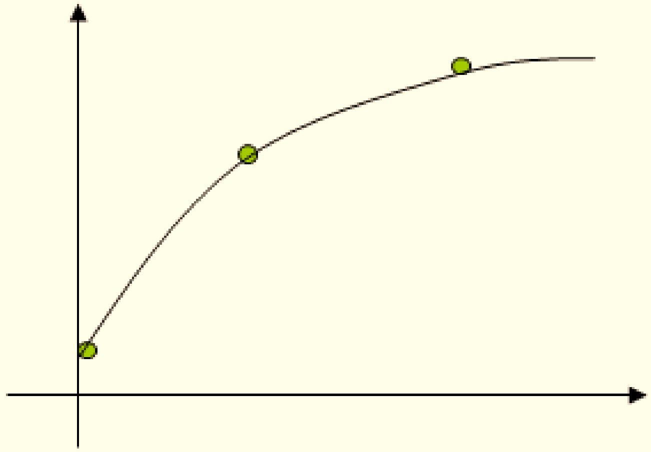


- Select a curve that best fits the data. One choice is to find the curve so that the sum of the square of the error is minimized.

Interpolation

- Given a set of data:

x_i	0	1	2
y_i	0.5	10.3	15.3



- Find a polynomial *P(x)* whose graph passes through all tabulated points.

$$y_i = P(x_i) \quad \textit{if } x_i \text{ is in the table}$$

Methods for Curve Fitting

- Least Squares
  - Linear Regression
  - Nonlinear Least Squares Problems

- Interpolation
  - Newton Polynomial Interpolation
  - Lagrange Interpolation

Integration

Some functions can be integrated analytically:

$$\int_1^3 x dx = \frac{1}{2}x^2\Big|_1^3 = \frac{9}{2} - \frac{1}{2} = 4$$

But many functions have no analytical solutions:

$$\int_0^a e^{-x^2} dx = ?$$

Methods for Numerical Integration

- **Upper and Lower Sums**
- **Trapezoid Method**
- **Romberg Method**
- **Gauss Quadrature**

Solution of Ordinary Differential Equations

A solution to the differential equation :

$$\ddot{x}(t)+3\dot{x}(t)+3x(t)=0$$

$$\dot{x}(0)=1; x(0)=0$$

is a function *x(t)* that satisfies the equations.

* Analytical solutions are available for special cases only.

Solution of Partial Differential Equations

Partial Differential Equations are more difficult to solve than ordinary differential equations:

$$\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial t^2} + 2 = 0$$

$$u(0,t) = u(1,t) = 0, \; u(x,0) = \sin(\pi x)$$

Summary

- **Numerical Methods:** Algorithms that are used to obtain numerical solution of a mathematical problem.
- **We need them when** No analytical solution exists or it is difficult to obtain it.

Topics Covered in the Course

- Solution of Nonlinear Equations
- Solution of Linear Equations
- Curve Fitting
  - Least Squares
  - Interpolation
- Numerical Integration
- Numerical Differentiation
- Solution of Ordinary Differential Equations
- Solution of Partial Differential Equations

NUMERICAL METHODS in ENGINEERING

Lecture2: Number Representation and Accuracy

Representing Real Numbers

- You are familiar with the decimal system:

$$312.45 = 3\times10^{2} + 1\times10^{1} + 2\times10^{0} + 4\times10^{-1} + 5\times10^{-2}$$

- Decimal System: Base = 10 , Digits (0,1,...,9)

- Standard Representations:

$$\underset{\text{sign}}{\pm}\quad \underset{\text{integral part}}{3\ 1\ 2}\ .\ \underset{\text{fraction part}}{4\ 5}$$

Normalized Floating Point Representation

- Normalized Floating Point Representation:

$$\underset{\text{sign}}{\pm} \quad \underbrace{d.\, f_1\ f_2\ f_3\ f_4}_{\text{mantissa}} \times 10^{\pm n}$$

exponent

$$d \neq 0, \qquad \pm n : \text{signed exponent}$$

- Scientific Notation: Exactly one non-zero digit appears before decimal point.
- Advantage: Efficient in representing very small or very large numbers.

Binary System

- Binary System: Base = 2, Digits {0,1}

$$\underbrace{\pm}_{\text{sign}} \quad \underbrace{1.\, f_1 \; f_2 \; f_3 \; f_4}_{\text{mantissa}} \times \underbrace{2^{\pm n}}_{\text{signed exponent}}$$

$$(1.101)_2 = (1 + 1 \times 2^{-1} + 0 \times 2^{-2} + 1 \times 2^{-3})_{10} = (1.625)_{10}$$

Fact

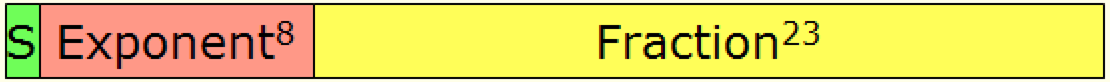
- Numbers that have a finite expansion in one numbering system may have an infinite expansion in another numbering system:

$$(1.1)_{10} = (1.0001100110\ 01100\ldots)_2$$

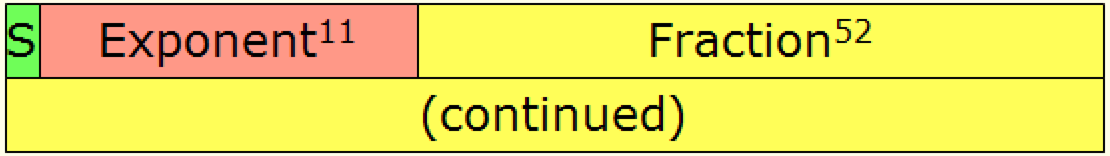
- You can never represent 1.1 exactly in binary system.

IEEE 754 Floating-Point Standard

- Single Precision (32-bit representation)
  - 1-bit Sign + 8-bit Exponent + 23-bit Fraction



- Double Precision (64-bit representation)
  - 1-bit Sign + 11-bit Exponent + 52-bit Fraction



Significant Digits

- Significant digits are those digits that can be used with confidence.
- Single-Precision: 7 Significant Digits

  $1.175494\ldots \times 10^{-38}$ to $3.402823\ldots \times 10^{38}$

- Double-Precision: 15 Significant Digits

  $2.2250738\ldots \times 10^{-308}$ to $1.7976931\ldots \times 10^{308}$

Calculator Example

- Suppose you want to compute:

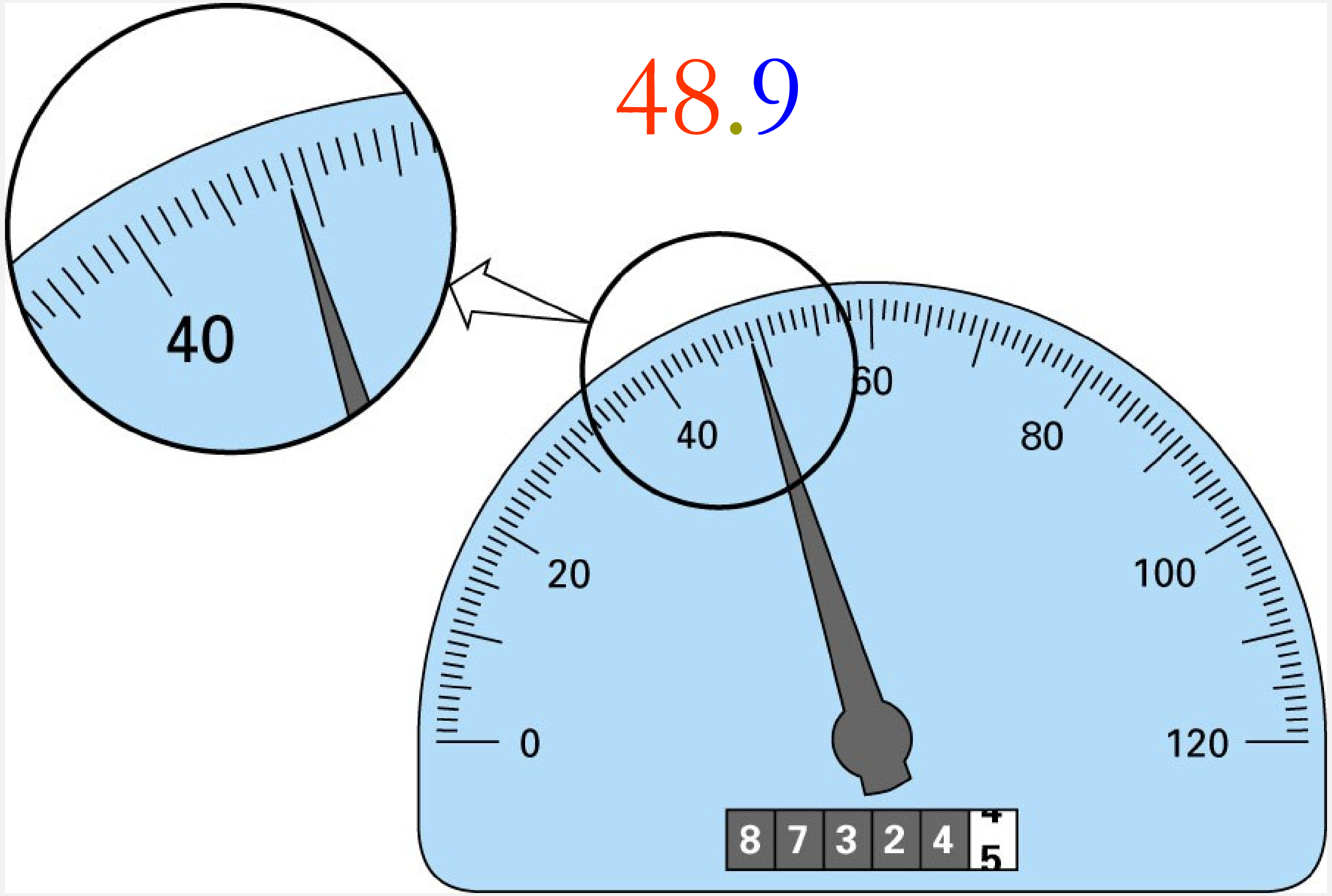
  3.578 * 2.139

  using a calculator with two-digit fractions

3.57 * 2.13 = 7.60

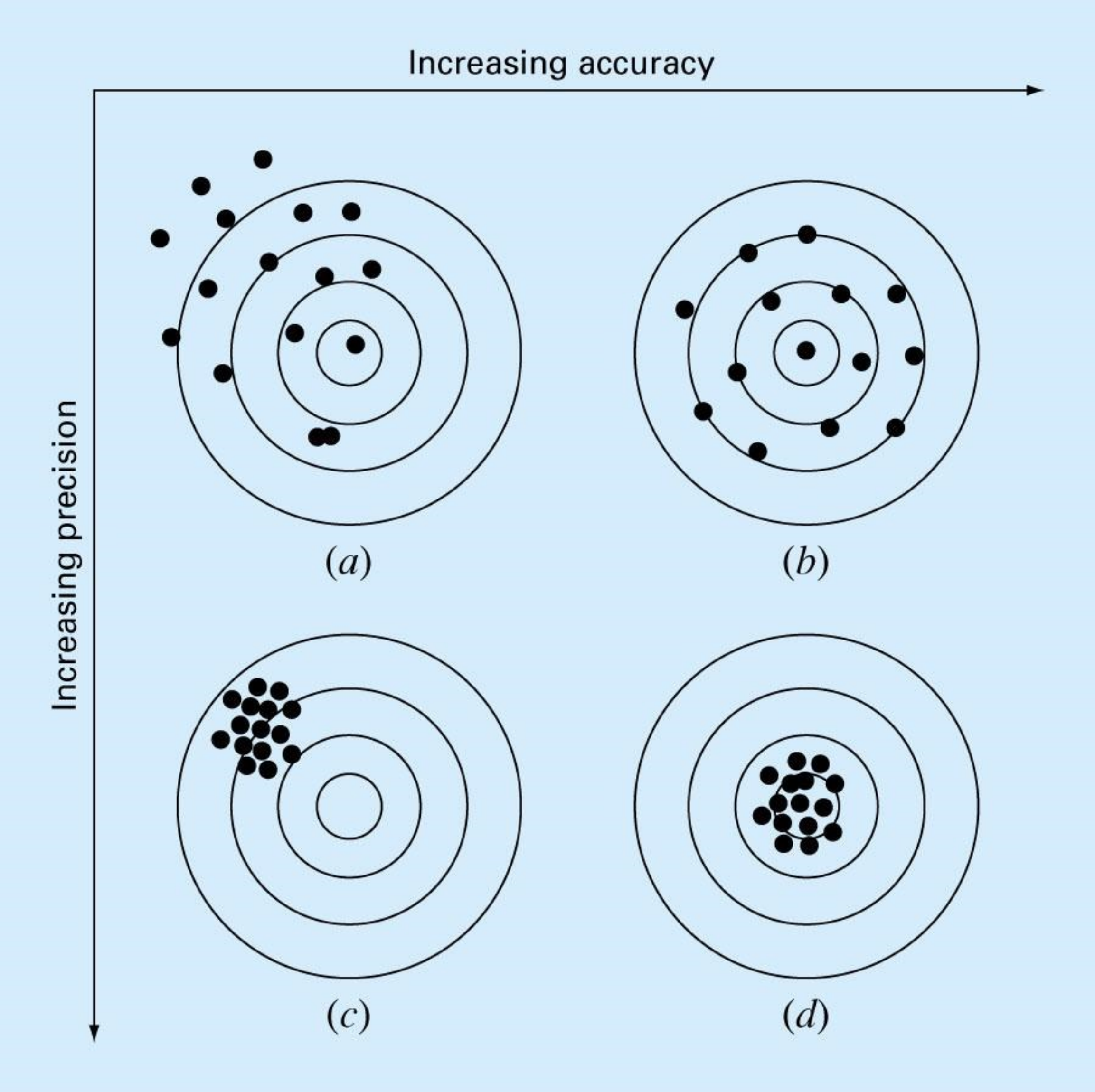
True answer: 7.653342

Significant Digits - Example



Accuracy and Precision

- Accuracy is related to the closeness to the true value.
- Precision is related to the closeness to other estimated values.


Increasing accuracy
Increasing precision
(a)
(b)
(c)
(d)

Rounding and Chopping

- Rounding: Replace the number by the nearest machine number.

- Chopping: Throw all extra digits.

Error Definitions – True Error

Can be computed if the true value is known:

Absolute True Error

$$E_t = |\text{true value} - \text{approximation}|$$

Absolute Percent Relative Error

$$\varepsilon_t = \left|\frac{\text{true value} - \text{approximation}}{\text{true value}}\right| * 100$$

Error Definitions – Estimated Error

When the true value is not known:

Estimated Absolute Error

$$E_a = \left| \text{current estimate} - \text{previous estimate} \right|$$

Estimated Absolute Percent Relative Error

$$\varepsilon_a = \left| \frac{\text{current estimate} - \text{previous estimate}}{\text{current estimate}} \right| * 100$$

Notation

We say that the estimate is correct to *n* decimal digits if:

$$|\,\text{Error}\,| \le 10^{-n}$$

We say that the estimate is correct to *n* decimal digits **rounded** if:

$$|\,\text{Error}\,| \le \frac{1}{2} \times 10^{-n}$$

NUMERICAL METHODS in ENGINEERING

Lectures 3-4: Taylor Theorem

Motivation

- We can easily compute expressions like:

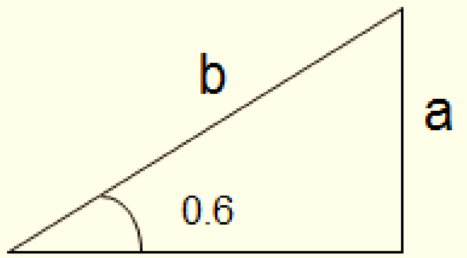
$$\frac{3 \times 10^{2}}{2(x+4)}$$

But, How do you compute $\sqrt{4.1}$, $\sin(0.6)$?

Can we use the definition

to compute $\sin(0.6)$?

Is this a practical way?



Taylor Series

The Taylor series expansion of $f(x)$ about a:

$$f(a)+f^{'}(a)(x-a)+\frac{f^{(2)}(a)}{2!}(x-a)^2+\frac{f^{(3)}(a)}{3!}(x-a)^3+\ldots$$

or

$$Taylor\ \ Series=\sum_{k=0}^{\infty}\frac{1}{k!}f^{(k)}(a)\,(x-a)^k$$

If the series converge, we can write :

$$f(x)=\sum_{k=0}^{\infty}\frac{1}{k!}f^{(k)}(a)\,(x-a)^k$$

Maclaurin Series

- Maclaurin series is a special case of Taylor series with the center of expansion *a* = 0.

The Maclaurin series expansion of $f(x)$:

$$f(0)+f^{'}(0)x+\frac{f^{(2)}(0)}{2!}x^2+\frac{f^{(3)}(0)}{3!}x^3+\ldots$$

If the series converge, we can write:

$$f(x)=\sum_{k=0}^{\infty}\frac{1}{k!}f^{(k)}(0)\,x^k$$

Maclaurin Series – Example 1

Obtain Maclaurin series expansion of $f(x) = e^x$

$$f(x) = e^x \qquad f(0) = 1$$

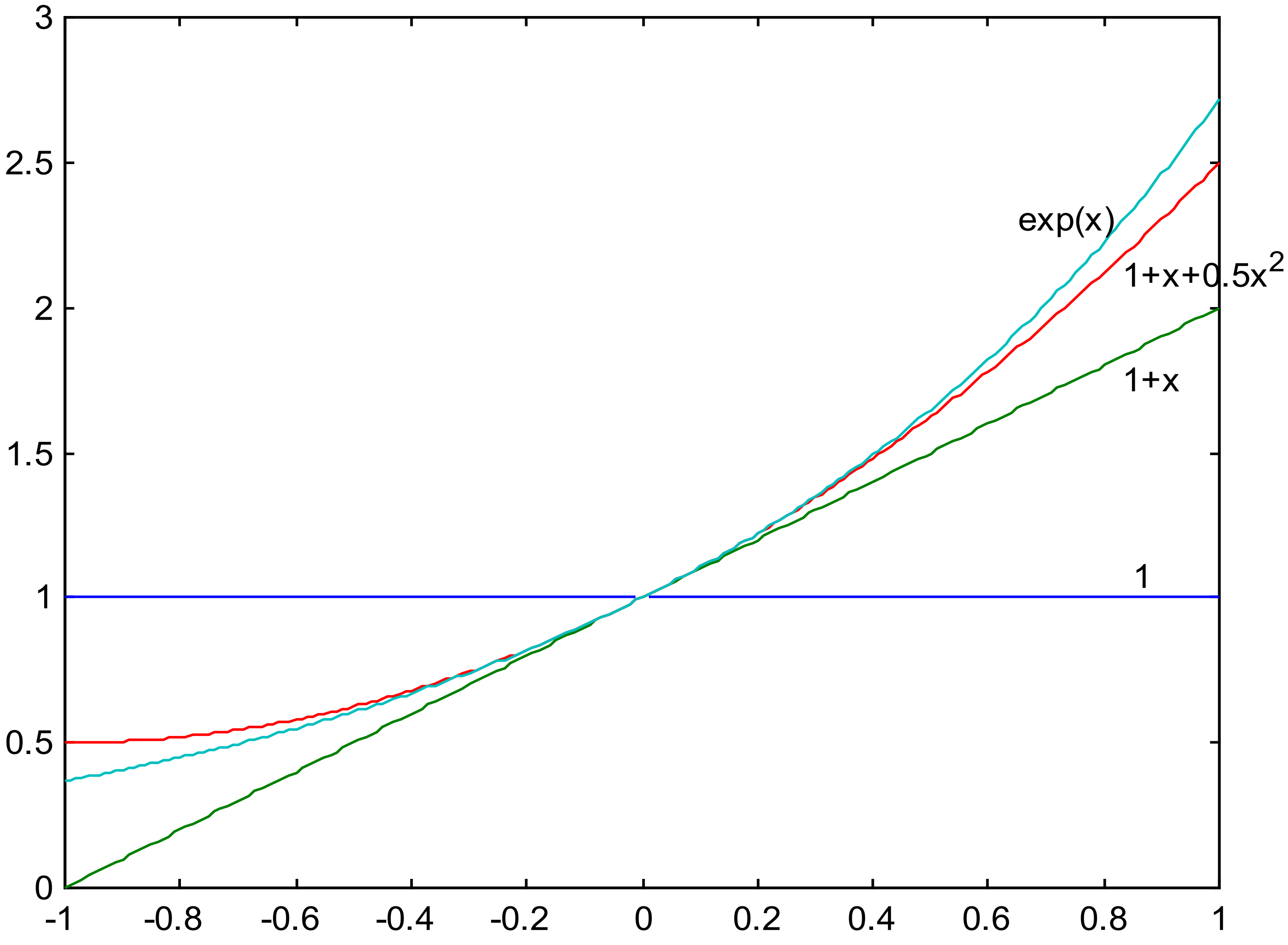
$$f'(x) = e^x \qquad f'(0) = 1$$

$$f^{(2)}(x) = e^x \qquad f^{(2)}(0) = 1$$

$$f^{(k)}(x) = e^x \qquad f^{(k)}(0) = 1 \quad for\, k \geq 1$$

$$e^x = \sum_{k=0}^{\infty} \frac{1}{k!} f^{(k)}(0)\, x^k = \sum_{k=0}^{\infty} \frac{x^k}{k!} = 1 + x + \frac{x^2}{2!} + \frac{x^3}{3!} + \ldots$$

The series converges for $|\mathrm{x}| < \infty$.



exp(x)
1+x+0.5x2
1+x
1
3
2.5
2
1.5
1
0.5
0
-1
-0.8
-0.6
-0.4
-0.2
0
0.2
0.4
0.6
0.8
1

Maclaurin Series – Example 2

Obtain Maclaurin series expansion of $f(x)=\sin(x)$:

$$f(x)=\sin(x) \qquad f(0)=0$$

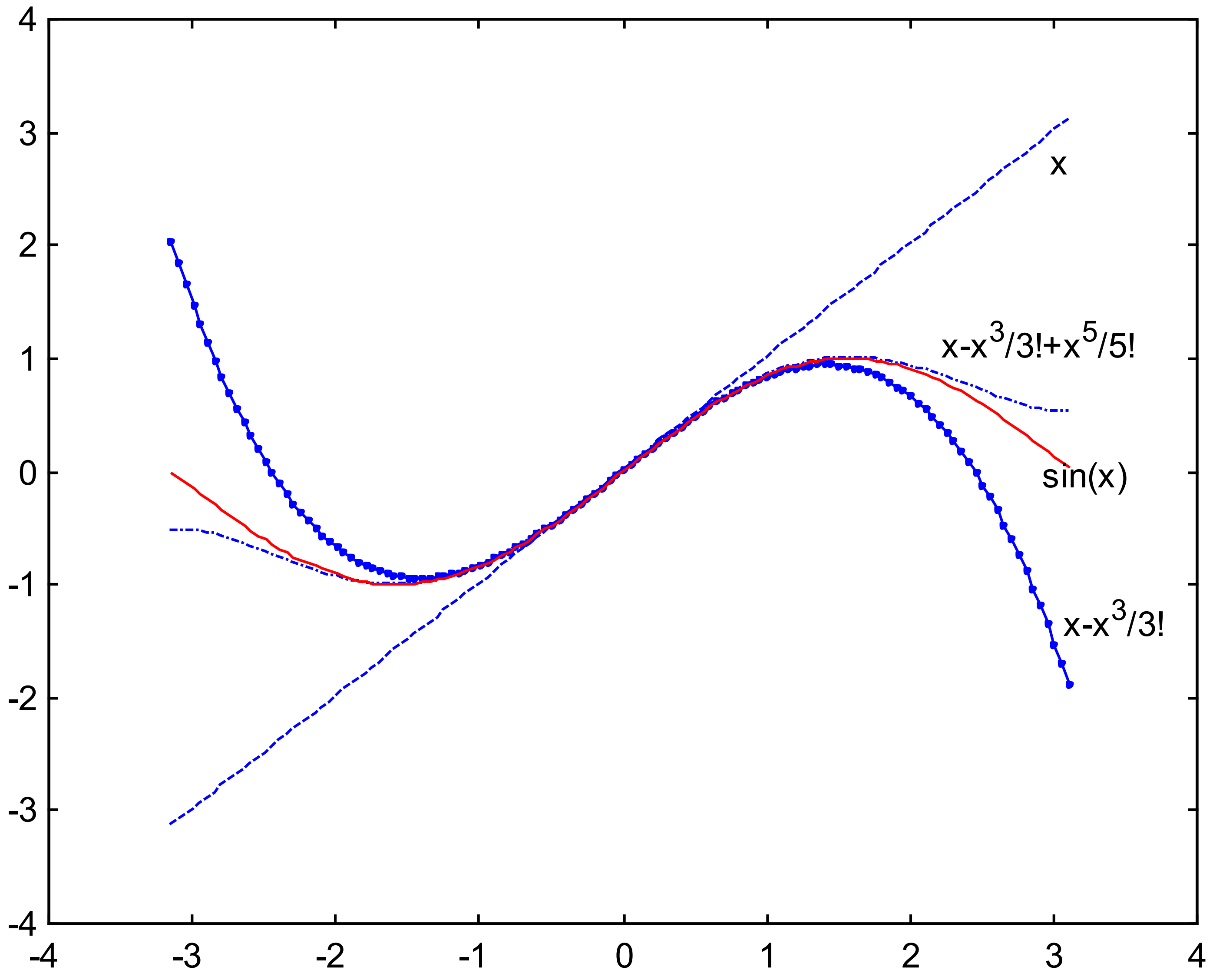
$$f'(x)=\cos(x) \qquad f'(0)=1$$

$$f^{(2)}(x)=-\sin(x) \qquad f^{(2)}(0)=0$$

$$f^{(3)}(x)=-\cos(x) \qquad f^{(3)}(0)=-1$$

$$\sin(x)=\sum_{k=0}^{\infty}\frac{f^{(k)}(0)}{k!}x^k = x-\frac{x^3}{3!}+\frac{x^5}{5!}-\frac{x^7}{7!}+\dots$$

The series converges for $|x|<\infty$.



4
3
2
1
0
-1
-2
-3
-4
-4
-3
-2
-1
0
1
2
3
4
x
x-x^3/3!+x^5/5!
sin(x)
x-x^3/3!

Maclaurin Series – Example 3

Obtain Maclaurin series expansion of : $f(x) = \cos(x)$

$$f(x) = \cos(x) \qquad f(0) = 1$$

$$f'(x) = -\sin(x) \qquad f'(0) = 0$$

$$f^{(2)}(x) = -\cos(x) \qquad f^{(2)}(0) = -1$$

$$f^{(3)}(x) = \sin(x) \qquad f^{(3)}(0) = 0$$

$$\cos(x) = \sum_{k=0}^{\infty} \frac{f^{(k)}(0)}{k!}(x)^k = 1 - \frac{x^2}{2!} + \frac{x^4}{4!} - \frac{x^6}{6!} + \ldots.$$

The series converges for $|x| < \infty$.

Maclaurin Series – Example 4

Obtain Maclaurin series expansion of $f(x) = \dfrac{1}{1-x}$

$$f(x) = \frac{1}{1-x} \qquad\qquad f(0) = 1$$

$$f'(x) = \frac{1}{(1-x)^2} \qquad\qquad f'(0) = 1$$

$$f^{(2)}(x) = \frac{2}{(1-x)^3} \qquad\qquad f^{(2)}(0) = 2$$

$$f^{(3)}(x) = \frac{6}{(1-x)^4} \qquad\qquad f^{(3)}(0) = 6$$

Maclaurin Series Expansion of: $\dfrac{1}{1-\mathrm{x}} = 1 + \mathrm{x} + \mathrm{x}^2 + \mathrm{x}^3 + \ldots$

Series converges for $|x| < 1$

Taylor Series – Example 5

Obtain Taylor series expansion of $f(x) = \frac{1}{x}$ at $a = 1$

$$f(x) = \frac{1}{x} \qquad f(1) = 1$$

$$f'(x) = \frac{-1}{x^2} \qquad f'(1) = -1$$

$$f^{(2)}(x) = \frac{2}{x^3} \qquad f^{(2)}(1) = 2$$

$$f^{(3)}(x) = \frac{-6}{x^4} \qquad f^{(3)}(1) = -6$$

Taylor Series Expansion $(a = 1)$: $1 - (x-1) + (x-1)^2 - (x-1)^3 + \ldots$

Taylor Series – Example 6

Obtain Taylor series expansion of $f(x) = \ln(x)$ at $(a = 1)$

$$f(x) = \ln(x)\ ,\ f'(x) = \frac{1}{x},\quad f^{(2)}(x) = \frac{-1}{x^2},\quad f^{(3)}(x) = \frac{2}{x^3}$$

$$f(1) = 0,\qquad f'(1) = 1,\qquad f^{(2)}(1) = -1\qquad f^{(3)}(1) = 2$$

$$\text{Taylor Series Expansion}: (x-1) - \frac{1}{2}(x-1)^2 + \frac{1}{3}(x-1)^3 - \ldots$$

Convergence of Taylor Series

- The Taylor series converges **fast** (few terms are needed) when ***x*** is near the point of expansion. If **|*x-a*|** is large then more terms are needed to get a good approximation.

Taylor's Theorem

If a function $f(x)$ possesses derivatives of orders $1, 2, ..., (n+1)$ on an interval containing a and x then the value of $f(x)$ is given by :

$$f(x) = \sum_{k=0}^{n} \frac{f^{(k)}(a)}{k!}(x-a)^k + R_n$$

(n+1) terms Truncated Taylor Series

Remainder

where :

$$R_n = \frac{f^{(n+1)}(\xi)}{(n+1)!}(x-a)^{n+1} \quad and \ \xi \text{ is between } a \text{ and } x.$$

Taylor's Theorem

We can apply Taylor's theorem for:

$$f(x) = \frac{1}{1-x} \quad \text{with the point of expansion } a = 0 \text{ if } |x| < 1.$$

If $x = 1$, then the function and its derivatives are not defined.

$\Rightarrow$ Taylor Theorem is not applicable.

Error Term

To get an idea about the approximation error, we can derive an upper bound on:

$$R_n = \frac{f^{(n+1)}(\xi)}{(n+1)!}(x-a)^{n+1}$$

for all *values of* ξ between a and x.

Alternative form of Taylor's Theorem

$Let\ f(x)$ have derivatives of orders $1, 2, \ldots, (n+1)$ on an interval containing x and $x+h$ then :

$$f(x+h) = \sum_{k=0}^{n} \frac{f^{(k)}(x)}{k!} h^k + R_n \qquad (h = \text{step size})$$

$$R_n = \frac{f^{(n+1)}(\xi)}{(n+1)!} h^{n+1} \ \ where\ \xi \text{ is between } x \text{ and } x+h$$

Taylor's Theorem – Alternative forms

$$f(x) = \sum_{k=0}^{n} \frac{f^{(k)}(a)}{k!}(x-a)^k + \frac{f^{(n+1)}(\xi)}{(n+1)!}(x-a)^{n+1}$$

where ξ is between a and x.

$$a \rightarrow x, \quad x \rightarrow x+h$$

$$f(x+h) = \sum_{k=0}^{n} \frac{f^{(k)}(x)}{k!}h^k + \frac{f^{(n+1)}(\xi)}{(n+1)!}h^{n+1}$$

where ξ is between x and $x+h$.

Mean Value Theorem

If $f(x)$ is a continuous function on a closed interval $[a,b]$ and its derivative is defined on the open interval (a,b) then there exists $\xi \in (a,b)$

$$f'(\xi) = \frac{f(b) - f(a)}{b - a}$$

Proof : Use Taylor's Theorem for $n = 0, x = a, \; x + h = b$

$$f(b) = f(a) + f'(\xi)(b - a)$$

Alternating Series Theorem

Consider the alternating series:

$$S = a_1 - a_2 + a_3 - a_4 + \cdots$$

$$\text{If } \boxed{\begin{cases} a_1 \geq a_2 \geq a_3 \geq a_4 \geq \cdots \\ \quad \textit{and} \\ \lim\limits_{n \to \infty} a_n = 0 \end{cases}} \quad \text{then } \boxed{\begin{cases} \text{The series converges} \\ \qquad \textit{and} \\ \left| S - S_n \right| \leq a_{n+1} \end{cases}}$$

S_n : Partial sum (sum of the first n terms)

a_{n+1} : First omitted term

Alternating Series – Example

$$\sin(1) \text{ can be computed using : } \quad sin(1) = 1 - \frac{1}{3!} + \frac{1}{5!} - \frac{1}{7!} + \cdots$$

This is a convergent alternating series since :

$$a_1 \geq a_2 \geq a_3 \geq a_4 \geq \cdots \quad and \quad \lim_{n \to \infty} a_n = 0$$

Then :

$$\left| sin(1) - \left(1 - \frac{1}{3!} \right) \right| \leq \frac{1}{5!}$$

$$\left| sin(1) - \left(1 - \frac{1}{3!} + \frac{1}{5!} \right) \right| \leq \frac{1}{7!}$$

Example 7

Obtain the Taylor series expansion

of $f(x) = e^{2x+1}$ at $a = 0.5$ (the center of expansion)

How large can the error be when $(n+1)$ terms are used

to approximate e^{2x+1} with $x = 1$?

Example 7 – Taylor Series

Obtain Taylor series expansion of $f(x) = e^{2x+1}$, $a = 0.5$

$$f(x) = e^{2x+1} \qquad f(0.5) = e^2$$

$$f'(x) = 2e^{2x+1} \qquad f'(0.5) = 2e^2$$

$$f^{(2)}(x) = 4e^{2x+1} \qquad f^{(2)}(0.5) = 4e^2$$

$$f^{(k)}(x) = 2^k\ e^{2x+1} \qquad f^{(k)}(0.5) = 2^k e^2$$

$$e^{2x+1} = \sum_{k=0}^{\infty} \frac{f^{(k)}(0.5)}{k!} (x-0.5)^k$$

$$= e^2 + 2e^2(x-0.5) + 4e^2 \frac{(x-0.5)^2}{2!} + \ldots + 2^k e^2 \frac{(x-0.5)^k}{k!} + \ldots$$