

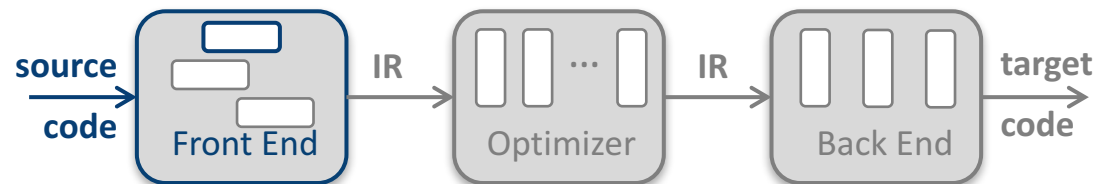


COMP 412  
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## Syntax Analysis, VII

### *The Canonical LR(1) Table Construction*

Comp 412



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Chapter 3 in EaC2e

## Review

# LR(1) Items

The *intermediate representation* of the LR(1) table construction algorithm



An **LR(1)** item is a pair  $[P, \delta]$ , where

$P$  is a production  $A \rightarrow \beta$  with a  $\bullet$  at some position in the **RHS**

$\delta$  is a single symbol lookahead (*symbol*  $\equiv$  *word* or **EOF**)

The  $\bullet$  in an item indicates the position of the top of the stack

$[A \rightarrow \bullet \beta \gamma, \underline{a}]$  means that the input seen so far is consistent with the use of  $A \rightarrow \beta \gamma$  immediately after the symbol on top of the stack.

We call an item like this a possibility.

$[A \rightarrow \beta \bullet \gamma, \underline{a}]$  means that the input seen so far is consistent with the use of  $A \rightarrow \beta \gamma$  at this point in the parse, *and* that the parser has already recognized  $\beta$  (that is,  $\beta$  is on top of the stack).

We call an item like this a partially complete item.

$[A \rightarrow \beta \gamma \bullet, \underline{a}]$  means that the parser has seen  $\beta \gamma$ , *and* that a lookahead symbol of  $\underline{a}$  is consistent with reducing to  $A$ .

This item is complete.

## Review

# LR(1) Items



The production  $A \rightarrow \beta$ , where  $\beta = B_1 B_2 B_3$  with lookahead  $\underline{a}$ , can give rise to 4 items

$[A \rightarrow \bullet B_1 B_2 B_3, \underline{a}]$ ,  $[A \rightarrow B_1 \bullet B_2 B_3, \underline{a}]$ ,  $[A \rightarrow B_1 B_2 \bullet B_3, \underline{a}]$ , &  $[A \rightarrow B_1 B_2 B_3 \bullet, \underline{a}]$

The set of LR(1) items for a grammar is *finite*.

## What's the point of all these lookahead symbols?

- Carry them along to help choose the correct reduction
- Lookaheads are bookkeeping, unless item has  $\bullet$  at right end
  - Has no direct use in  $[A \rightarrow \beta \bullet \gamma, \underline{a}]$
  - In  $[A \rightarrow \beta \bullet, \underline{a}]$ , a lookahead of  $\underline{a}$  implies a reduction by  $A \rightarrow \beta$
  - For  $\{ [A \rightarrow \beta \bullet, \underline{a}], [B \rightarrow \gamma \bullet \delta, \underline{b}] \}$ ,  $\underline{a} \Rightarrow \text{reduce to } A$ ;  $\text{FIRST}(\delta) \Rightarrow \text{shift}$

$\Rightarrow$  Limited right context is enough to pick the actions

$\underline{a} \in \text{FIRST}(\delta) \Rightarrow a$   
conflict, not LR(1)

# LR(1) Table Construction



## High-level overview

### 1 Build the Canonical Collection of Sets of **LR(1)** Items, /

#### a Begin in an appropriate state, $s_0$

- ◆  $[S' \rightarrow \bullet S, \underline{\text{EOF}}]$ , along with any equivalent items
- ◆ Derive equivalent items as  $\text{closure}(s_0)$

#### b Repeatedly compute, for each $s_k$ , and each $X$ , $\text{goto}(s_k, X)$

- ◆ If the set is not already in the collection, add it
- ◆ Record all the transitions created by  $\text{goto}()$

This eventually reaches a fixed point

$S$  is the start symbol. To simplify things, we add  $S' \rightarrow S$  to create a unique goal production.

$\text{goto}(s_i, X)$  contains the set of LR(1) items that represent possible parser configurations if the parser recognizes an  $X$  while in state  $s_i$

### 2 Fill in the table from the Canonical Collection of Sets of **LR(1)** items

The sets in the canonical collection form the states of the Control **DFA**.

The construction traces the **DFA's** transitions

# LR(1) Table Construction



## High-level overview

### 1 Build the Canonical Collection of Sets of **LR(1)** Items, $I$

- a Begin in an appropriate state,  $s_0$ 
  - ◆  $[S' \rightarrow \bullet S, \underline{\text{EOF}}]$ , along with any equivalent items
  - ◆ Derive equivalent items as **closure**(  $s_0$  )
- b Repeatedly compute, for each  $s_k$ , and each  $X$ , **goto**( $s_k, X$ )
  - ◆ If the set is not already in the collection, add it
  - ◆ Record all the transitions created by **goto**( )

This eventually reaches a fixed point

### 2 Fill in the table from the Canonical Collection of Sets of **LR(1)** items

Let's build the tables for the left-recursive *SheepNoise* grammar ( $S'$  is *Goal*)

0	<i>Goal</i>	$\rightarrow$	<i>SheepNoise</i>
1	<i>SheepNoise</i>	$\rightarrow$	<i>SheepNoise</i> <u>baa</u>
2			<u>baa</u>

# Computing Closures



***Closure(s)*** adds all the possibilities for the items already in  $s$

- Any item  $[A \rightarrow \beta \bullet B \delta, \underline{a}]$  where  $B \in NT$  implies  $[B \rightarrow \bullet \tau, x]$  for each production that has  $B$  on the *lhs*, and each  $x \in \text{FIRST}(\delta \underline{a})$
- Since  $\beta B \delta$  is valid, any way to derive  $\beta B \delta$  is valid, too

## The Algorithm

***Closure( s )***

*while ( s is still changing )*

$\forall$  items  $[A \rightarrow \beta \bullet B \delta, \underline{a}] \in s$

*lookahead*  $\leftarrow \text{FIRST}(\delta \underline{a})$  //  $\delta$  might be  $\varepsilon$

$\forall$  productions  $B \rightarrow \tau \in P$

$\forall \underline{b} \in \text{lookahead}$

*if*  $[B \rightarrow \bullet \tau, \underline{b}] \notin s$

*then*  $s \leftarrow s \cup \{ [B \rightarrow \bullet \tau, \underline{b}] \}$

- Classic fixed-point method
- Halts because  $s \subset I$ , the set of all items (*finite*)
- Worklist version is faster
- ***Closure*** “fills out” a state  $s$

Generate new lookaheads.  
See note on p. 128

This is the left-recursive SheepNoise; EaC2e shows the right-recursive version.



## Example From SheepNoise

Initial step builds the item [*Goal* → • *SheepNoise*, EOF] and takes its *Closure*( )

*Closure*( [*Goal* → • *SheepNoise*, EOF] )

Item	Source
[ <i>Goal</i> → • <i>SheepNoise</i> , EOF]	Original item
[ <i>SheepNoise</i> → • <i>SheepNoise</i> <u>baa</u> , EOF]	Iter 1, $\delta_a$ is EOF
[ <i>SheepNoise</i> → • <u>baa</u> , EOF]	Iter 1, $\delta_a$ is EOF
[ <i>SheepNoise</i> → • <i>SheepNoise</i> <u>baa</u> , <u>baa</u> ]	Iter 2, $\delta_a$ is <u>baa</u> EOF
[ <i>SheepNoise</i> → • <u>baa</u> , <u>baa</u> ]	Iter 2, $\delta_a$ is <u>baa</u> EOF

Symbol	FIRST
<i>Goal</i>	{ <u>baa</u> }
<i>SheepNoise</i>	{ <u>baa</u> }
<u>baa</u>	{ <u>baa</u> }
EOF	{ EOF }

So,  $S_0$  is

{ [*Goal* → • *SheepNoise*, EOF], [*SheepNoise* → • *SheepNoise* baa, EOF],  
 [*SheepNoise* → • baa, EOF], [*SheepNoise* → • *SheepNoise* baa, baa],  
 [*SheepNoise* → • baa, baa] }

0	<i>Goal</i>	→	<i>SheepNoise</i>
1	<i>SheepNoise</i>	→	<i>SheepNoise</i> <u>baa</u>
2			<u>baa</u>

# Computing Gotos



***Goto(s,x)*** computes the state that the parser would reach if it recognized an *x* while in state *s*

- ***Goto***( {  $[A \rightarrow \beta \bullet X \delta, \underline{a}]$  }, *X* ) produces {  $[A \rightarrow \beta X \bullet \delta, \underline{a}]$  } *(obviously)*
- It finds all such items & uses *Closure()* to fill out the state

## The Algorithm

```
Goto( s, X )  
  new  $\leftarrow \emptyset$   
   $\forall \text{ items } [A \rightarrow \beta \bullet X \delta, \underline{a}] \in s$   
    new  $\leftarrow \text{new} \cup \{ [A \rightarrow \beta X \bullet \delta, \underline{a}] \}$   
  return Closure( new )
```

- ***Goto***( ) models a transition in the automaton
- Straightforward computation
- ***Goto***( ) is not a fixed-point method (but it calls ***Closure***( ))

***Goto*** in this construction is analogous to ***Move*** in the subset construction.



# Example from SheepNoise



Assume that  $S_0$  is

{ [Goal → • SheepNoise, EOF], [SheepNoise → • SheepNoise baa, EOF],  
 [SheepNoise → • baa, EOF], [SheepNoise → • SheepNoise baa, baa],  
 [SheepNoise → • baa, baa] }

From earlier slide

**Goto**(  $S_0$ , baa )

- Loop produces

Item	Source
[SheepNoise → <u>baa</u> •, <u>EOF</u> ]	Item 3 in $s_0$
[SheepNoise → <u>baa</u> •, <u>baa</u> ]	Item 5 in $s_0$

- **Closure** adds nothing since • is at end of *rhs* in each item

In the construction, this produces  $s_2$   
 { [SheepNoise → baa •, { EOF, baa } ] }

New, but *obvious*, notation for two distinct items  
 [SheepNoise → baa •, EOF] & [SheepNoise → baa •, baa]

0	Goal	→	SheepNoise	
1	SheepNoise	→	SheepNoise <u>baa</u>	
2			<u>baa</u>	8



# Building the Canonical Collection

Start from  $s_0 = \text{Closure}([S' \rightarrow \bullet S, \underline{\text{EOF}}])$

Repeatedly construct new states, until all are found

## The Algorithm

```
 $s_0 \leftarrow \text{Closure}(\{[S' \rightarrow \bullet S, \underline{\text{EOF}}]\})$   
 $S \leftarrow \{s_0\}$   
 $k \leftarrow 1$   
while ( $S$  is still changing)  
   $\forall s_j \in S \text{ and } \forall x \in (T \cup NT)$   
     $s_k \leftarrow \text{Goto}(s_j, x)$   
    record  $s_j \rightarrow s_k$  on  $x$   
  if  $s_k \notin S$  then  
     $S \leftarrow S \cup \{s_k\}$   
     $k \leftarrow k + 1$ 
```

- Fixed-point computation
- Loop adds to  $S$  (*monotone*)
- $S \subseteq 2^{\text{ITEMS}}$ , so  $S$  is finite
- *Worklist version is faster because it avoids duplicated effort*

This membership / equality test requires careful and/or clever implementation.

# Example from SheepNoise



## Starts with $S_0$

$S_0 : \{ [Goal \rightarrow \bullet \text{ SheepNoise}, \underline{EOF}], [SheepNoise \rightarrow \bullet \text{ SheepNoise } \underline{baa}, \underline{EOF}],$   
 $[SheepNoise \rightarrow \bullet \underline{baa}, \underline{EOF}], [SheepNoise \rightarrow \bullet \text{ SheepNoise } \underline{baa}, \underline{baa}],$   
 $[SheepNoise \rightarrow \bullet \underline{baa}, \underline{baa}] \}$

## Iteration 1 computes

$S_1 = \mathbf{Goto}(S_0, \text{SheepNoise}) =$   
 $\{ [Goal \rightarrow \text{SheepNoise } \bullet, \underline{EOF}], [SheepNoise \rightarrow \text{SheepNoise } \bullet \underline{baa}, \underline{EOF}],$   
 $[SheepNoise \rightarrow \text{SheepNoise } \bullet \underline{baa}, \underline{baa}] \}$

$S_2 = \mathbf{Goto}(S_0, \underline{baa}) = \{ [SheepNoise \rightarrow \underline{baa} \bullet, \underline{EOF}],$   
 $[SheepNoise \rightarrow \underline{baa} \bullet, \underline{baa}] \}$

Nothing more to compute,  
since  $\bullet$  is at the end of every  
item in  $S_3$ .

## Iteration 2 computes

$S_3 = \mathbf{Goto}(S_1, \underline{baa}) = \{ [SheepNoise \rightarrow \text{SheepNoise } \underline{baa} \bullet, \underline{EOF}],$   
 $[SheepNoise \rightarrow \text{SheepNoise } \underline{baa} \bullet, \underline{baa}] \}$

0	Goal	→	SheepNoise	
1	SheepNoise	→	SheepNoise <u>baa</u>	
2			<u>baa</u>	10

# Example from SheepNoise



$S_0 : \{ [Goal \rightarrow \bullet SheepNoise, \underline{EOF}], [SheepNoise \rightarrow \bullet SheepNoise \underline{baa}, \underline{EOF}], [SheepNoise \rightarrow \bullet \underline{baa}, \underline{EOF}], [SheepNoise \rightarrow \bullet SheepNoise \underline{baa}, \underline{baa}], [SheepNoise \rightarrow \bullet \underline{baa}, \underline{baa}] \}$

$S_1 = \mathbf{Goto}(S_0, SheepNoise) = \{ [Goal \rightarrow SheepNoise \bullet, \underline{EOF}], [SheepNoise \rightarrow SheepNoise \bullet \underline{baa}, \underline{EOF}], [SheepNoise \rightarrow SheepNoise \bullet \underline{baa}, \underline{baa}] \}$

$S_2 = \mathbf{Goto}(S_0, \underline{baa}) = \{ [SheepNoise \rightarrow \underline{baa} \bullet, \underline{EOF}], [SheepNoise \rightarrow \underline{baa} \bullet, \underline{baa}] \}$

$S_3 = \mathbf{Goto}(S_1, \underline{baa}) = \{ [SheepNoise \rightarrow SheepNoise \underline{baa} \bullet, \underline{EOF}], [SheepNoise \rightarrow SheepNoise \underline{baa} \bullet, \underline{baa}] \}$

0	Goal	→	SheepNoise
1	SheepNoise	→	SheepNoise <u>baa</u>
2			<u>baa</u>

State	SN	<u>baa</u>
$s_0$	$s_1$	$s_2$
$s_1$	—	$s_3$
$s_2$	—	—
$s_3$	—	—

**Goto Relationships**

# Filling in the ACTION and GOTO Tables



## The Table Construction Algorithm

$x$  is the state number

```

 $\forall$  set  $S_x \in S$ 
   $\forall$  item  $i \in S_x$ 
    if  $i$  is  $[A \rightarrow \beta \bullet \underline{a} \delta, \underline{b}]$  and  $\text{goto}(S_x, \underline{a}) = S_k, \underline{a} \in T$ 
      then  $\text{ACTION}[x, \underline{a}] \leftarrow \text{"shift } k\text{"}$ 
    else if  $i$  is  $[S' \rightarrow S \bullet, \underline{\text{EOF}}]$ 
      then  $\text{ACTION}[x, \underline{\text{EOF}}] \leftarrow \text{"accept"}$ 
    else if  $i$  is  $[A \rightarrow \beta \bullet, \underline{a}]$ 
      then  $\text{ACTION}[x, \underline{a}] \leftarrow \text{"reduce } A \rightarrow \beta\text{"}$ 
   $\forall n \in NT$ 
    if  $\text{goto}(S_x, n) = S_k$ 
      then  $\text{GOTO}[x, n] \leftarrow k$ 
```

• before  $T \Rightarrow$  shift

have Goal  $\Rightarrow$  accept

• at end  $\Rightarrow$  reduce

### Many items generate no table entry

- Placeholder before a  $NT$  does not generate an **ACTION** table entry
- **Closure**( ) instantiates  $\text{FIRST}(X)$  directly for  $[A \rightarrow \beta \bullet X \delta, \underline{a}]$

# Example from SheepNoise



$S_0 : \{ [Goal \rightarrow \bullet SheepNoise, \underline{EOF}], [SheepNoise \rightarrow \bullet SheepNoise \underline{baa}, \underline{EOF}],$   
 $[SheepNoise \rightarrow \bullet \underline{baa}, \underline{EOF}], [SheepNoise \rightarrow \bullet SheepNoise \underline{baa}, \underline{baa}],$   
 $[SheepNoise \rightarrow \bullet \underline{baa}, \underline{baa}] \}$

$S_1 = Goto(S_0, SheepNoise) =$

$\{ [Goal \rightarrow SheepNoise \bullet, \underline{EOF}], [SheepNoise \rightarrow SheepNoise \bullet \underline{baa}, \underline{EOF}],$   
 $[SheepNoise \rightarrow SheepNoise \bullet \underline{baa}, \underline{baa}] \}$

$S_2 = Goto(S_0, \underline{baa}) \leftarrow \{ [\cancel{SheepNoise \rightarrow \underline{baa} \bullet, \underline{EOF}}],$   
 $[SheepNoise \rightarrow \underline{baa} \bullet, \underline{baa}] \}$

$S_3 = Goto(S_1, \underline{baa}) = \{ [SheepNoise \rightarrow SheepNoise \underline{baa} \bullet, \underline{EOF}],$   
 $[SheepNoise \rightarrow SheepNoise \underline{baa} \bullet, \underline{baa}] \}$

• before  $T \Rightarrow shift$   $k$

so, ACTION[ $s_0, \underline{baa}$ ] is  
 “shift  $S_2$ ” (clause 1)  
 (items define same entry)

# Example from SheepNoise



$S_0 : \{ [Goal \rightarrow \bullet SheepNoise, \underline{EOF}], [SheepNoise \rightarrow \bullet SheepNoise \underline{baa}, \underline{EOF}],$   
 $[SheepNoise \rightarrow \bullet \underline{baa}, \underline{EOF}], [SheepNoise \rightarrow \bullet SheepNoise \underline{baa}, \underline{baa}],$   
 $[SheepNoise \rightarrow \bullet \underline{baa}, \underline{baa}] \}$

$S_1 = Goto(S_0, SheepNoise) =$

$\{ [Goal \rightarrow SheepNoise \bullet, \underline{EOF}], [SheepNoise \rightarrow SheepNoise \bullet \underline{baa}, \underline{EOF}],$   
 $[SheepNoise \rightarrow SheepNoise \bullet \underline{baa}, \underline{baa}] \}$

$S_2 = Goto(S_0, \underline{baa}) = \{ [SheepNoise \rightarrow \underline{baa} \bullet, \underline{EOF}],$   
 $[SheepNoise \rightarrow \underline{baa} \bullet, \underline{baa}] \}$

so, ACTION[ $S_1, \underline{baa}$ ] is  
“shift  $S_3$ ” (clause 1)

$S_3 = Goto(S_1, \underline{baa}) = \{ [SheepNoise \rightarrow SheepNoise \underline{baa} \bullet, \underline{EOF}],$   
 $[SheepNoise \rightarrow SheepNoise \underline{baa} \bullet, \underline{baa}] \}$

# Example from SheepNoise



$S_0 : \{ [Goal \rightarrow \bullet SheepNoise, \underline{EOF}], [SheepNoise \rightarrow \bullet SheepNoise \underline{baa}, \underline{EOF}],$   
 $[SheepNoise \rightarrow \bullet \underline{baa}, \underline{EOF}], [SheepNoise \rightarrow \bullet SheepNoise \underline{baa}, \underline{baa}],$   
 $[SheepNoise \rightarrow \bullet \underline{baa}, \underline{baa}] \}$

$S_1 = Goto(S_0, SheepNoise) =$   
 $\{ [Goal \rightarrow SheepNoise \bullet, \underline{EOF}], [SheepNoise \rightarrow SheepNoise \bullet \underline{baa}, \underline{EOF}],$   
 $[SheepNoise \rightarrow SheepNoise \bullet \underline{baa}, \underline{baa}] \}$

$S_2 = Goto(S_0, \underline{baa}) = \{ [SheepNoise \rightarrow \underline{baa} \bullet, \underline{EOF}],$   
 $[SheepNoise \rightarrow \underline{baa} \bullet, \underline{baa}] \}$

so, ACTION[ $S_1, EOF$ ] is  
“accept” (clause 2)

$S_3 = Goto(S_1, \underline{baa}) = \{ [SheepNoise \rightarrow SheepNoise \underline{baa} \bullet, \underline{EOF}],$   
 $[SheepNoise \rightarrow SheepNoise \underline{baa} \bullet, \underline{baa}] \}$



# Example from SheepNoise



$S_0 : \{ [Goal \rightarrow \bullet SheepNoise, \underline{EOF}], [SheepNoise \rightarrow \bullet SheepNoise \underline{baa}, \underline{EOF}],$   
 $[SheepNoise \rightarrow \bullet \underline{baa}, \underline{EOF}], [SheepNoise \rightarrow \bullet SheepNoise \underline{baa}, \underline{baa}],$   
 $[SheepNoise \rightarrow \bullet \underline{baa}, \underline{baa}] \}$

$S_1 = Goto(S_0, SheepNoise) =$   
 $\{ [Goal \rightarrow SheepNoise \bullet, \underline{EOF}], [SheepNoise \rightarrow SheepNoise \bullet \underline{baa}, \underline{EOF}],$   
 $[SheepNoise \rightarrow SheepNoise \bullet \underline{baa}, \underline{baa}] \}$

$S_2 = Goto(S_0, \underline{baa}) = \{ [SheepNoise \rightarrow \underline{baa} \bullet, \underline{EOF}],$   
 $[SheepNoise \rightarrow \underline{baa} \bullet, \underline{baa}] \}$

so, ACTION[ $S_2, EOF$ ] is “reduce 2”  
 (clause 3) (baa, too)

$S_3 = Goto(S_1, \underline{baa}) = \{ [SheepNoise \rightarrow SheepNoise \underline{baa} \bullet, \underline{EOF}],$   
 $[SheepNoise \rightarrow SheepNoise \underline{baa} \bullet, \underline{baa}] \}$

ACTION[ $S_3, \underline{EOF}$ ] is “reduce 1”  
 (clause 3) (baa, too)

# Building the Goto Table



$S_0 : \{ [Goal \rightarrow \bullet SheepNoise, \underline{EOF}], [SheepNoise \rightarrow \bullet SheepNoise \underline{baa}, \underline{EOF}], [SheepNoise \rightarrow \bullet \underline{baa}, \underline{EOF}], [SheepNoise \rightarrow \bullet SheepNoise \underline{baa}, \underline{baa}], [SheepNoise \rightarrow \bullet \underline{baa}, \underline{baa}] \}$

$S_1 = \mathbf{Goto}(S_0, SheepNoise) =$

$\{ [Goal \rightarrow SheepNoise \bullet, \underline{EOF}], [SheepNoise \rightarrow SheepNoise \bullet \underline{baa}, \underline{EOF}], [SheepNoise \rightarrow SheepNoise \bullet \underline{baa}, \underline{baa}] \}$

$S_2 = \mathbf{Goto}(S_0, \underline{baa}) = \{ [SheepNoise \rightarrow \underline{baa} \bullet, \underline{EOF}], [SheepNoise \rightarrow \underline{baa} \bullet, \underline{baa}] \}$

$S_3 = \mathbf{Goto}(S_1, \underline{baa}) = \{ [SheepNoise \rightarrow SheepNoise \underline{baa} \bullet, \underline{EOF}], [SheepNoise \rightarrow SheepNoise \underline{baa} \bullet, \underline{baa}] \}$

**The Goto table holds just the entries for nonterminal symbols.**  
(ignore the column for baa)

State	SN	<u>baa</u>
$S_0$	$S_1$	$S_2$
$S_1$	—	$S_3$
$S_2$	—	—
$S_3$	—	—

***Goto Relationships***



## ACTION & GOTO Tables

Here are the tables for the left-recursive *SheepNoise* grammar

The tables

ACTION TABLE		
State	EOF	<u>baa</u>
0	—	<i>shift 2</i>
1	<i>accept</i>	<i>shift 3</i>
2	<i>reduce 2</i>	<i>reduce 2</i>
3	<i>reduce 1</i>	<i>reduce 1</i>

GOTO TABLE	
State	<i>SheepNoise</i>
0	1
1	0
2	0
3	0

The grammar

0	<i>Goal</i>	→	<i>SheepNoise</i>
1	<i>SheepNoise</i>	→	<i>SheepNoise</i> <u><i>baa</i></u>
2			<u><i>baa</i></u>

Remember, this is the left-recursive *SheepNoise*; EaC2e shows the right-recursive version.

# What can go wrong?

The **if-then-else** grammar is worked as an example in EaC2e



## What if a set $s$ contains $[A \rightarrow \beta \bullet \underline{a} \gamma, \underline{b}]$ and $[B \rightarrow \beta \bullet, \underline{a}]$ ?

- First item generates “shift”, second generates “reduce”
- Both define  $\text{ACTION}[s, \underline{a}]$  — cannot do both actions
- This is a fundamental ambiguity, called a *shift/reduce error*
- Modify the grammar to eliminate it (if-then-else)
- Shifting will often resolve it correctly

## What if a set $s$ contains $[A \rightarrow \gamma \bullet, \underline{a}]$ and $[B \rightarrow \gamma \bullet, \underline{a}]$ ?

- Each generates “reduce”, but with a different production
- Both define  $\text{ACTION}[s, \underline{a}]$  — cannot do both reductions
- This is a fundamental ambiguity, called a *reduce/reduce conflict*
- Modify the grammar to eliminate it (PL/I's overloading of (...))

***In either case, the grammar is not LR(1)***

# Implementing the Construction

## Building the Canonical Collection



Start from  $s_0 = \text{closure}([S' \rightarrow \bullet S, \underline{\text{EOF}}])$

Repeatedly construct new states, until

### The algorithm

```
 $s_0 \leftarrow \text{closure}([S' \rightarrow \bullet S, \underline{\text{EOF}}])$   
 $S \leftarrow \{s_0\}$   
 $k \leftarrow 1$   
while ( $S$  is still changing)  
   $\forall s_j \in S \text{ and } \forall x \in (T \cup NT)$   
     $s_k \leftarrow \text{goto}(s_j, x)$   
    record  $s_j \rightarrow s_k$  on  $x$   
  if  $s_k \notin S$  then  
     $S \leftarrow S \cup \{s_k\}$   
     $k \leftarrow k + 1$ 
```

Remember this comment about implementing the equality test at the bottom of the algorithm to build the Canonical Collection of Sets of LR(1) Items?

- Only need to compare core items — the rest will follow
- Represent items as a triple  $(R, P, L)$ 
  - $R$  is the rule or production
  - $P$  is the position of the placeholder
  - $L$  is the lookahead symbol
- Order items, then
  1. Compare set cardinalities
  2. Compare (in order) by  $R, P, L$

This membership / equality test requires careful and/or clever implementation.

STOP