view\_frames Result

Recorded at time: 1374609881.640

										/world										
Broadcaster: /transform_l Average rate: 100.2 Most recent transform: 0. Buffer length: 4.84	$0.209~{ m Hz}$ Average rate $0.011~{ m sec}$ old Most recent transfo	rate: 50.212 Hz nsform: -0.491 sec old / Most r	Average rate: 50.212 Hz  ost recent transform: -0.491 sec old  Buffer length: 4.820 sec	er Broadcaster: /robot_stat Average rate: 50.2 old Most recent transform: -0 Buffer length: 4.82	$0.212~{ m Hz}$ Average ra : -0.491 sec old Most recent trans	e rate: $50.212 \text{ Hz}$ ansform: $-0.491 \text{ sec old}$ Most re	adcaster: /robot_state_publishe Average rate: 50.212 Hz recent transform: -0.491 sec of Buffer length: 4.820 sec	Average rate: 50. c old Most recent transform: -	60.212 Hz Average n: -0.491 sec old Most recent tra	/robot_state_publisher Broade e rate: 50.212 Hz A ransform: -0.491 sec old Most re	adcaster: /robot_state_public Average rate: 50.212 Hz recent transform: -0.491 se Buffer length: 4.820 sec	Average rate: 50 sec old \dagged Most recent transform:	$0.212~{ m Hz}$ Average rate: 5 : -0.491 sec old ${ m Most}$ recent transform	$00.212~{ m Hz}$ Average rat n: -0.491 sec old $\sqrt{ m Most}$ recent transf	ate: 50.212 Hz \ Assertance Assertance \ Assertance As	lcaster: /robot_state_publishe Average rate: 50.212 Hz ecent transform: -0.491 sec of Buffer length: 4.820 sec	\ Average rate: 50.2	L2 Hz Average rate 491 sec old Most recent transfo		Broadcaster: /robot_state_publisher Average rate: 50.212 Hz lost recent transform: -0.491 sec old Buffer length: 4.820 sec
/left_optical_frame	/0_link	/frame_base_suppor	ρort_L /frame_r	_base_support_R	/frame_bottom_B	/frame_bottom_F	_F	frame_bottom_L	/frame_bottom_R	/frame_top_B		/frame_top_F	/frame_top_L	/frame_top_R	/frame_vertical_L	_B /fr;	rame_vertical_LF	/frame_vertical_RB	/frame_vertical	cal_RF
//left_optical_frame	Broadcaster: /robot_ Average rate: Most recent transform	bot_state_publisher ate: 50.212 Hz aform: -0.491 sec old gth: 4.820 sec  bot_state_publisher te: 46.816 Hz aform: 0.012 sec old gth: 4.806 sec  bot_state_publisher te: 46.816 Hz aform: 0.012 sec old gth: 4.806 sec  bot_state_publisher te: 46.816 Hz aform: 0.012 sec old gth: 4.806 sec  bot_state_publisher te: 46.816 Hz aform: 0.012 sec old gth: 4.806 sec  bot_state_publisher te: 46.816 Hz aform: 0.012 sec old gth: 4.806 sec	ort_L //frame_ba	ise_support_R	/frame_bottom_B	/frame_bottom_F	F //fra	ame_bottom_L	/frame_bottom_R	/frame_top_B		/frame_top_F	/frame_top_L	/frame_top_R	/frame_vertical_L	B /fra	me_vertical_LF	/frame_vertical_RB	/frame_vertical	ıl_RF
Broadcaster: /robot_sta Average rate: 46.8 Most recent transform: 0 Buffer length: 4.8	n: 0.012 sec old Most recent transform	te: 46.816 Hz Asform: 0.012 sec old Most re	Average rate: 46.816 Hz st recent transform: 0.012 sec old Buffer length: 4.806 sec																	

Broadcaster: /robot\_state\_publisher
Average rate: 50.212 Hz

Most recent transform: -0.491 sec old Buffer length: 4.820 sec

/tool\_tip\_L

Broadcaster: /robot\_state\_publisher Average rate: 50.212 Hz

Most recent transform: -0.491 sec old Buffer length: 4.820 sec

Broadcaster: /robot\_state\_publisher Average rate: 50.212 Hz

Buffer length: 4.820 sec

/grasper2\_tip\_L

Average rate: 50.212 Hz

Buffer length: 4.820 sec

(/tool\_L