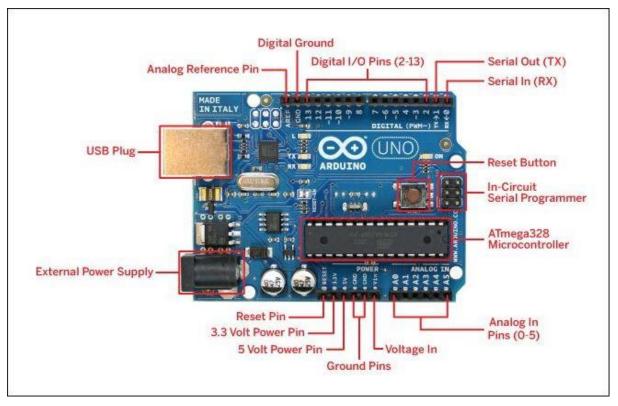


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Pin description and features



Power Supply

The power supply of the Arduino can be done with the help of an exterior power supply otherwise USB connection. The exterior power supply (6 to 20 volts) mainly includes a battery or an AC to DC adapter. The connection of an adapter can be done by plugging a center-positive plug (2.1mm) into the power jack on the board. The battery terminals can be placed in the pins of Vin as well as GND. The power pins of an **Arduino board** include the following.

Vin:

The input voltage or Vin to the Arduino while it is using an exterior power supply opposite to volts from the connection of USB or else **RPS** (**regulated power supply**). By using this pin, one can supply the voltage.

5Volts:

The RPS can be used to give the power supply to the microcontroller as well as components which are used on the Arduino board. This can approach from the input voltage through a regulator.

3V3:

A 3.3 supply voltage can be generated with the onboard regulator, and the highest draw current will be 50 mA.

GND:

GND (ground) pins

Memory

The memory of an ATmega328 microcontroller includes 32 KB and 0.5 KB memory is utilized for the Boot loader), and also it includes SRAM-2 KB as well as EEPROM-1KB.

Input and Output





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We know that an arguing Uno R3 includes 14-digital pins which can be used as an input otherwise output by using the functions like pin Mode (), digital Read(), and digital Write(). These pins can operate with 5V, and every digital pin can give or receive 20mA, & includes a 20k to 50k ohm pull up resistor. The maximum current on any pin is 40mA which cannot surpass for avoiding the microcontroller from the damage. Additionally, some of the pins of an Arduino include specific functions.

Serial Pins

The serial pins of an Arduino board are TX (1) and RX (0) pins and these pins can be used to transfer the TTL serial data. The connection of these pins can be done with the equivalent pins of the ATmega8U2 USB to TTL chip.

External Interrupt Pins

The external interrupt pins of the board are 2 & 3, and these pins can be arranged to activate an interrupt on a rising otherwise falling edge, a low-value otherwise a modify in value

PWM Pins

The PWM pins of an Arduino are 3, 5, 6, 9, 10, & 11, and gives an output of an 8-bit PWM with the function analog Write ().

SPI (Serial Peripheral Interface) Pins

The SPI pins are 10, 11, 12, 13 namely SS, MOSI, MISO, SCK, and these will maintain the **SPI communication** with the help of the SPI library.

LED Pin

An arguing board is inbuilt with a LED using digital pin-13. Whenever the digital pin is high, the LED will glow otherwise it will not glow.

TWI (2-Wire Interface) Pins

The TWI pins are SDA or A4, & SCL or A5, which can support the communication of TWI with the help of Wire library.

AREF (Analog Reference) Pin

An analog reference pin is the reference voltage to the inputs of an analog i/ps using the function like analog Reference().

Reset (RST) Pin

This pin brings a low line for resetting the microcontroller, and it is very useful for using an RST button toward shields which can block the one over the Arduino R3 board.

Communication

The communication protocols of an Arduino Uno include SPI, I2C, and UART serial communication.

UART

An Arduino Uno uses the two functions like the transmitter digital pin1 and the receiver digital pin0. These pins are mainly used in UART TTL serial communication.

I2C

An Arduino UNO board employs SDA pin otherwise A4 pin & A5 pin otherwise SCL pin is used for I2C communication with wire library. In this, both the SCL and SDA are CLK signal and data signal.

SPI Pins

The SPI communication includes MOSI, MISO, and SCK.

MOSI (Pin11)

This is the master out slave in the pin, used to transmit the data to the devices

MISO (Pin12)

This pin is a serial CLK, and the CLK pulse will synchronize the transmission of which is produced by the master.

SCK (Pin13)





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Skill AF Lean Anytime Anythere The CLK pulse synchronizes data transmission that is generated by the master. Equivalent pins with the SPI library are employed for the communication of SPI. ICSP (in-circuit serial programming) headers can be utilized for programming **ATmega microcontroller** directly with the boot loader.

