



Data Structures



Introduction to Data Structure

- Data is a basic unit that any computing system centers around.

- What is data structure?

Data Structure is an arrangement of data in computer's memory (or sometimes on a disk) so that we can retrieve it & manipulate it correctly and efficiently.

Definitions

■ Data type

- Information itself has no meaning because it is just sequence of bytes.
- It is interpretation of bit pattern that gives it's meaning.
- For example 00100110 can be interpreted as number 38(binary), number 26(binary coded decimal) or the character '2'.
- A method of interpreting bit pattern is called as a data type.
- So data type is a kind of data that variable may hold in a programming language. For example int, float, char, double, class, ...

Definitions

- **Data object** is a term that refers to set of elements. Such set may be finite or infinite.
- **Data structure** is a set of domains D , a set of functions F and a set of axioms A .
- A triple (D, F, A) denotes the data structure d .

Abstract Data Type

- ADT is a conceptual representation.
- ADT is a mathematical model together with various operations defined in that model.
- ADT is a way of looking at Data Structure focusing on what it does and not how it does.
- Data Structure is implementation of ADT.

Examples of Data Structure

- Arrays
- Stacks
- Queues
- Linked Lists
- Trees
- Graphs

Introduction to Arrays

- Arrays are defined as a finite ordered set of homogeneous elements.
- Finite means there is a specific number of elements in the array.
- Ordered means the elements of the array are arranged so that there is zeroth, first, second and so on elements.
- Homogeneous means all the elements in the array must be of the same type.
- E.g. An array may contain all integers or all characters but not integers and characters.
- Declaration in C++ `int a[100];`

Operations on Array

- The two basic operations that access an array are Extraction and Storing.
- The Extraction operation is a function that accepts an array a , and an index i , and returns an element of the array.
- This operation is denoted by the expression $a[i]$;
- The storing operation accepts an array a , an index i and an element x .
this operation is denoted by the expression

$$a[i] = x;$$

Arrays Continued...

- The smallest index of an array's index is called its lower bound. It is 0 in C++.
- The highest index is called its upper bound.
- If Lower bound is “lower” and Upper bound is “upper” then number of elements in the array, called its “range” is given by

$$\text{upper} - \text{lower} + 1. \rightarrow \text{arr.lengths}$$

E.g. In array a, the lower bound is 0 and the upper bound is 99, so the range is 100.

Arrays Continued..

- Arrays will always be stored in contiguous memory locations.
- You can have static as well as dynamic arrays, where the range of the array will be decided at run time.

Single Dimension Array Implementation

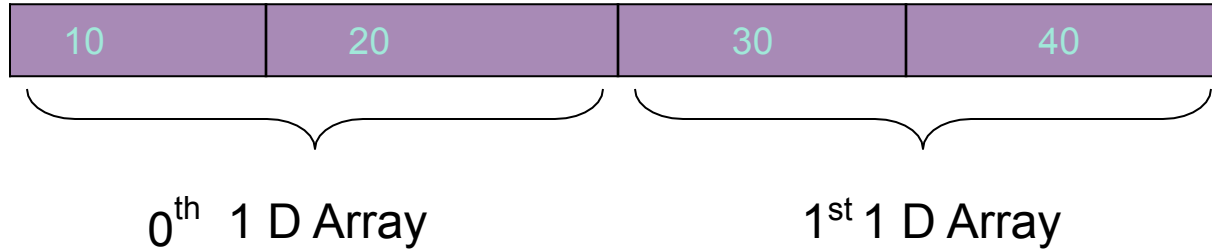
```
Int arr[], i;  
arr=new int[10]  
for( i = 0; i < 10; i++ ) arr[i] = i;  
  
for ( i = 0; i < 10; i++ )  
  
    cout<< i ;
```

Two Dimensional Array

- Two dimensional array can be considered as an array of 1-D array.
- Declaration `int arr[][]=new int[2][2];`
- This defines a new array containing two elements. Each of these elements is itself an array containing 2 integers.
- Each element of this array is accessed using two indices: row number and the column number.

2-D Array Representation

■ Physical:



□ Logical:

	C 0	C 1
R0	10	20
R1	30	40

Using 2D Array

```
Int arr[ ][ ], i , j;
```

```
For( i = 0; i < 2; i++ )
```

```
    for( j = 0; j < 2; j++ )
```

```
        arr[ i ][ j ] = i + j;
```

```
For( i = 0; i < 2; i++ )
```

```
    for( j = 0; j < 2; j++ )
```

```
        Sysout(arr[ i ][ j ]);
```

Advantages of Arrays

- Simple and easy to understand.
- Contiguous allocation.
- Fast retrieval because of indexed nature.
- No need for the user to be worried about allocation and deallocation of arrays.

Disadvantages of Array

- If you need m elements out of n locations defined. $n-m$ locations are unnecessarily wasted if $n > m$
- You can not have more than n elements. (I.e static allocation of memory.)
- large number of data movements in case of insertion & deletion, which leads to more overheads.