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% BME671L
% Lab #1: clear, close, plots, vectors, complex variables, real, imag,
% atan, angle

% Your name:

clear, close all
% Plotting example with  $u = 1 - 3j$ ,  $v = 2 + 4j$ 
% figure(1)
% plot([0 1],[0 -3],'k',[0 2],[0 4],'k--')
% xlabel('x-axis label goes here')
% ylabel('y-axis label goes here')
% xlim([-2 2])
% ylim([-4 4])
% grid on

% For all following problems use  $u = 2 + 3j$ ,  $v = -5 + j$ 

% Q1: Define 2 complex variables u and v.

u = ;
v = ;

% Q2: calculate the sum of u and v. Do not suppress the output.

% Q3: When an output is not assigned a variable it automatically gets
% designated as "ans". Save the results of  $u + v$  as a new variable z.
This
% time suppress the output by adding a ";" to the end of the command

% Q4: Print real and imaginary parts of z separately using the disp
% command. Use the matlab functions that return the components of z
% instead
% of hard coding the answer.

disp('real:')
disp()
disp('imag:')
disp()

% Q5: Calculate the magnitude of z using its complex conjugate either
% with a
% "" or using the conj() command. Is there any difference between
% these
% commands? What if input was a matrix?

% Your answer:
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% Q6: Find the angle of z using Matlab's "angle" command

% Q7: If you instead use the "atan" command to what result do you get?
    Why
% might these values disagree?

% Your answer:

% Q8: Plot u in red and v in blue as solid lines on the same plot. The
% vectors should originate from the origin. Label the x and y axis as
    real
% and imaginary. Set both the x and y axis to display +/- 6. Add a
    grid.
figure(1), clf

% Add z to the plot in black using the "hold on" command.

% Add an additional vector to the plot that geometrically represents
    the
% addition of u to v. Make this vector a dashed gree line. Hint:
% head-to-tail vector addition.

%
*****
%   SHOW FIGURE 1 TO THE TA TO RECIEVE CREDIT FOR THE LAB
%
*****

% Q9: Create a function cart2polar with that has an input of a complex
% number in a cartesian format, z, and outputs the corresponding
    radius
% and angle for polar coordinates. The only built-in matlab commands
    you
% are allowed to use are real(), imag(), and atan(). Use if, elseif,
    and
% else. Remember
% that in Matlab any boolean statements require the symbol to appear
    twice
% (e.g. == or && or ||).

% Q10: Convert the following values to polar coordinates by hand and
% compare the answers to output of your cart2polar function. Remeber
    that
% all angles should be between -pi and pi.
z1 = 1+1j;
z2 = -1+j;

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z3 = -3-4j;
z4 = j;

% By hand:
% z1: r =      theta =
% z2: r =      theta =
% z3: r =      theta =
% z4: r =      theta =

% Using cart2polar:

[r1, theta1] = cart2polar(z1)

% When you are done:
% * Make sure to show the indicated result/figure to the TA during the
%   lab period to receive credit
% * upload your script to Sakai
%   * upload your cart2polar function
%   * upload a pdf containing your script and outputs
%   * PRINT a copy of your pdf to turn in at the beginning of class on
%     Tuesday
return
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Error using dbstatus
Error: File: D:\OneDrive\Documents\Duke\TA Signal Processing\lab1.m
Line: 21 Column: 5
Invalid expression. Check for missing or extra characters.
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