### Foundations of Machine Learning

Module 2: Linear Regression and Decision Tree

Part C: Learning Decision Tree

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#### **Top-Down Induction of Decision Trees ID3**

#### 1. Which node to proceed with?

- 1. A  $\leftarrow$  the "best" decision attribute for next *node*
- 2. Assign A as decision attribute for *node*
- 3. For each value of A create new descendant
- 4. Sort training examples to leaf node according to the attribute value of the branch
- 5. If all training examples are perfectly classified (same value of target attribute) stop, else iterate over new leaf nodes.2. When to stop?

#### Choices

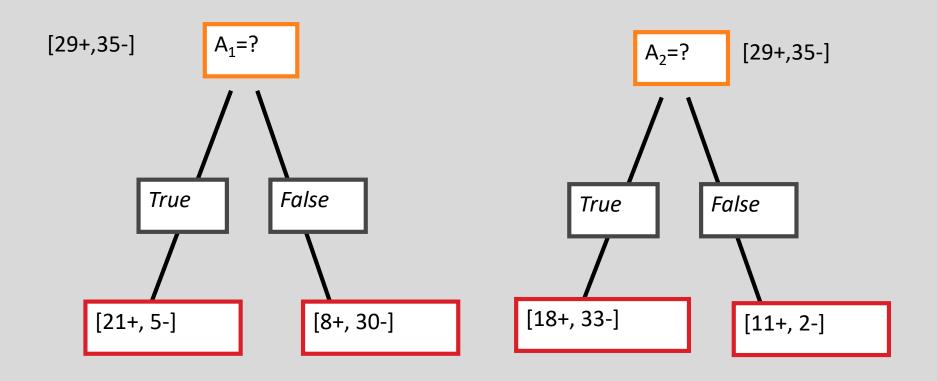
#### When to stop

- no more input features
- all examples are classified the same
- too few examples to make an informative split

#### Which test to split on

- split gives smallest error.
- With multi-valued features
  - split on all values or
  - split values into half.

### Which Attribute is "best"?



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### **Principled Criterion**

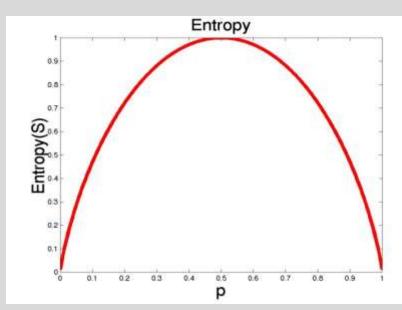
- Selection of an attribute to test at each node choosing the most useful attribute for classifying examples.
- information gain
  - measures how well a given attribute separates the training examples according to their target classification
  - This measure is used to select among the candidate attributes at each step while growing the tree
  - Gain is measure of how much we can reduce uncertainty (Value lies between 0,1)

## Entropy

- A measure for
  - uncertainty
  - purity
  - information content
- Information theory: optimal length code assigns  $(-\log_2 p)$  bits to message having probability p
- *S* is a sample of training examples
  - $-p_{+}$  is the proportion of positive examples in S
  - $-p_{-}$  is the proportion of negative examples in S
- Entropy of S: average optimal number of bits to encode information about certainty/uncertainty about S

$$Entropy(S) = p_{+}(-\log_{2}p_{+}) + p_{-}(-\log_{2}p_{-}) = -p_{+}\log_{2}p_{+} - p_{-}\log_{2}p_{-}$$

## Entropy



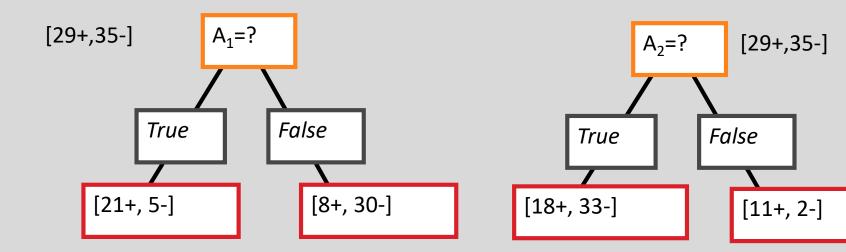
- The entropy is 0 if the outcome is ``certain".
- The entropy is maximum if we have no knowledge of the system (or any outcome is equally possible).
- S is a sample of training examples
- p<sub>+</sub> is the proportion of positive examples
- p<sub>\_</sub> is the proportion of negative examples
- Entropy measures the impurity of S Entropy(S) =  $-p_+\log_2 p_+ - p_-\log_2 p_-$

### Information Gain

Gain(S,A): expected reduction in entropy due to partitioning S on attribute A

Gain(S,A)=Entropy(S) 
$$-\sum_{v \in values(A)} |S_v|/|S|$$
 Entropy(S<sub>v</sub>)

Entropy([29+,35-]) =  $-29/64 \log_2 29/64 - 35/64 \log_2 35/64$ = 0.99



#### Information Gain

```
Entropy([21+,5-]) = 0.71

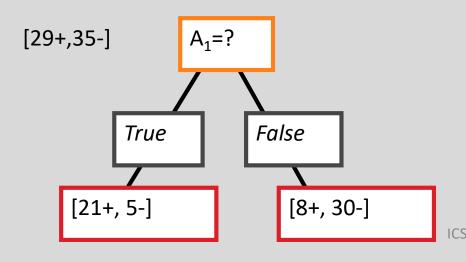
Entropy([8+,30-]) = 0.74

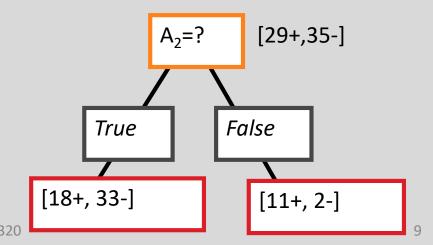
Gain(S,A<sub>1</sub>)=Entropy(S)

-26/64*Entropy([21+,5-])

-38/64*Entropy([8+,30-])

=0.27
```

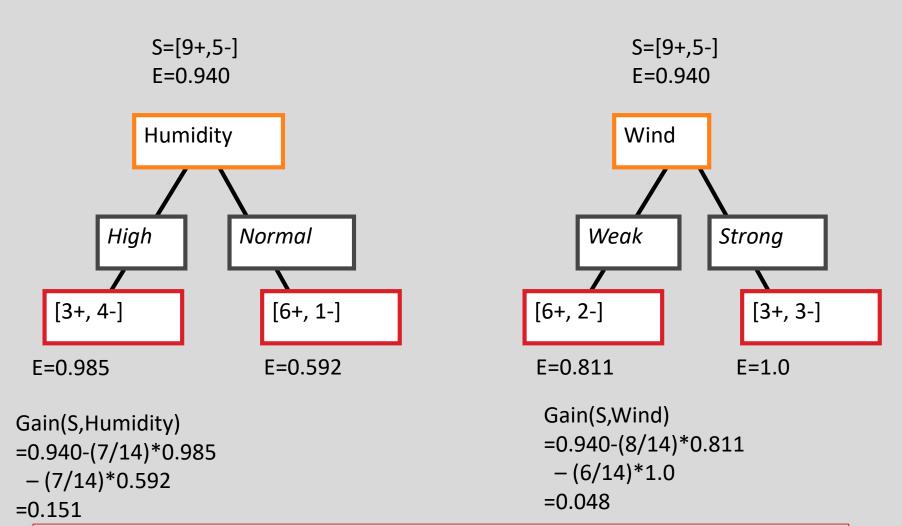




# **Training Examples**

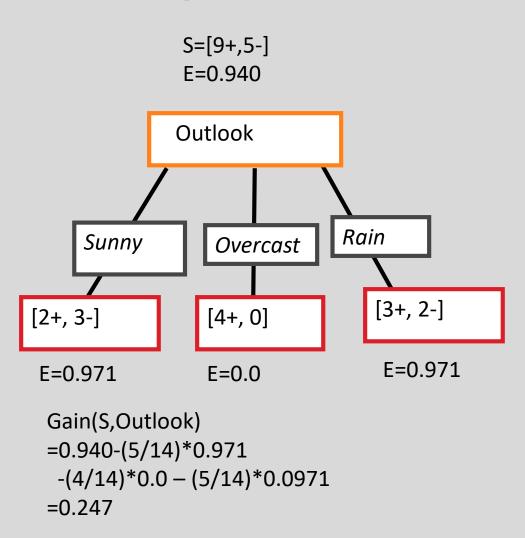
| Day | Outlook  | Temp | Humidity | Wind   | Tennis? |
|-----|----------|------|----------|--------|---------|
| D1  | Sunny    | Hot  | High     | Weak   | No      |
| D2  | Sunny    | Hot  | High     | Strong | No      |
| D3  | Overcast | Hot  | High     | Weak   | Yes     |
| D4  | Rain     | Mild | High     | Weak   | Yes     |
| D5  | Rain     | Cool | Normal   | Weak   | Yes     |
| D6  | Rain     | Cool | Normal   | Strong | No      |
| D7  | Overcast | Cool | Normal   | Strong | Yes     |
| D8  | Sunny    | Mild | High     | Weak   | No      |
| D9  | Sunny    | Cool | Normal   | Weak   | Yes     |
| D10 | Rain     | Mild | Normal   | Weak   | Yes     |
| D11 | Sunny    | Mild | Normal   | Strong | Yes     |
| D12 | Overcast | Mild | High     | Strong | Yes     |
| D13 | Overcast | Hot  | Normal   | Weak   | Yes     |
| D14 | Rain     | Mild | High     | Strong | No      |

### Selecting the Next Attribute



Humidity provides greater info. gain than Wind, w.r.t target classification.

## Selecting the Next Attribute



### Selecting the Next Attribute

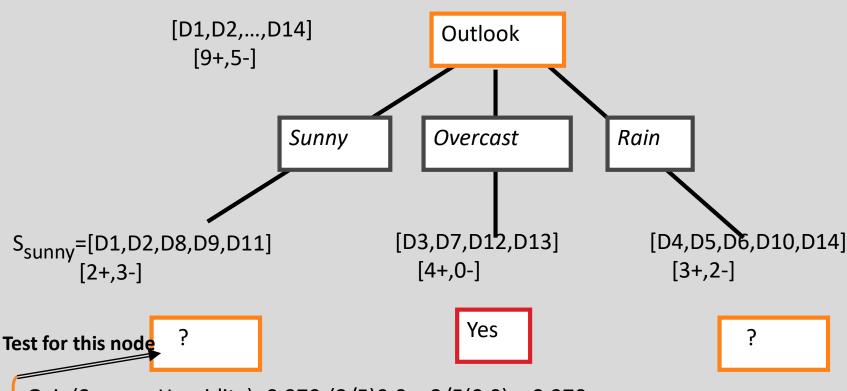
The information gain values for the 4 attributes are:

- Gain(S,Outlook) =0.247
- Gain(S, Humidity) = 0.151
- Gain(S,Wind) =0.048
- Gain(S,Temperature) = 0.029

where S denotes the collection of training examples

Note:  $0Log_20 = 0$ 

## **ID3** Algorithm

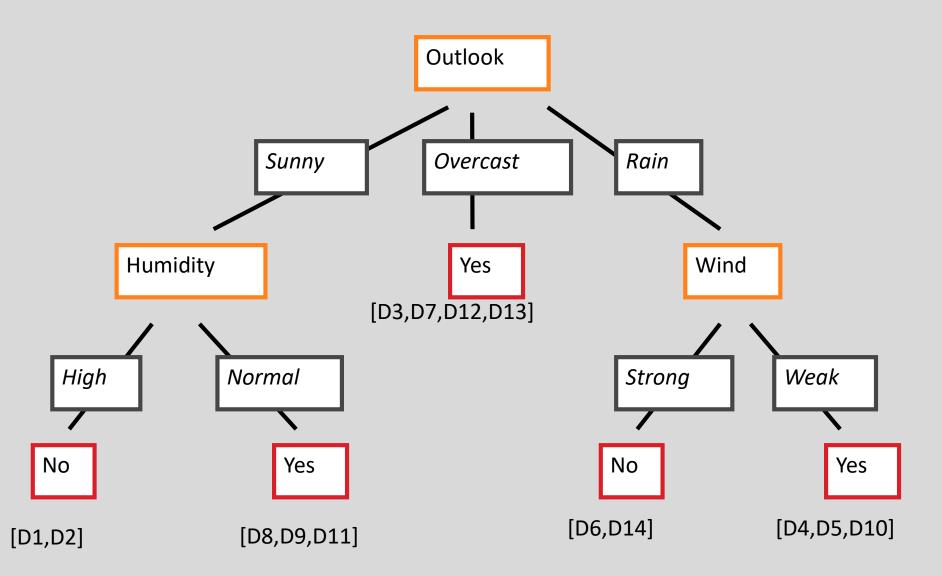


 $Gain(S_{sunny}, Humidity)=0.970-(3/5)0.0-2/5(0.0)=0.970$ 

 $Gain(S_{sunny}, Temp.)=0.970-(2/5)0.0-2/5(1.0)-(1/5)0.0=0.570$ 

 $Gain(S_{sunny}, Wind)=0.970=-(2/5)1.0-3/5(0.918)=0.019$ 

# **ID3 Algorithm**



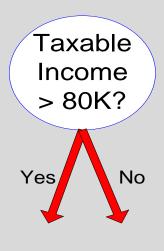
### Splitting Rule: GINI Index

- GINI Index
  - Measure of node impurity

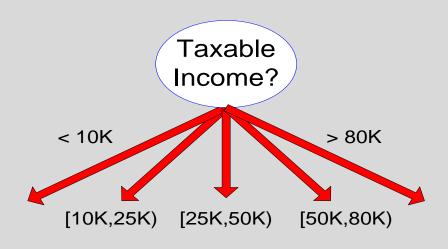
$$GINI_{node}(Node) = 1 - \sum_{c \in classes} [p(c)]^{2}$$

$$GINI_{split}(A) = \sum_{v \in Values(A)} \frac{|S_{v}|}{|S|} GINI(N_{v})$$

### Splitting Based on Continuous Attributes



(i) Binary split



(ii) Multi-way split

### Continuous Attribute – Binary Split

- For continuous attribute
  - Partition the continuous value of attribute A into a discrete set of intervals
  - Create a new boolean attribute  $A_{\rm c}$  , looking for a threshold c,

$$A_{c} = \begin{cases} true & \text{if } A_{c} < c \\ false & \text{otherwise} \end{cases}$$

How to choose c?

consider all possible splits and finds the best cut

#### Practical Issues of Classification

Underfitting and Overfitting

Missing Values

Costs of Classification

#### Hypothesis Space Search in Decision Trees

- Conduct a search of the space of decision trees which can represent all possible discrete functions.
- Goal: to find the best decision tree
- Finding a minimal decision tree consistent with a set of data is NP-hard.
- Perform a greedy heuristic search: hill climbing without backtracking
- Statistics-based decisions using all data

#### Bias and Occam's Razor

Prefer short hypotheses.

#### Argument in favor:

- Fewer short hypotheses than long hypotheses
- A short hypothesis that fits the data is unlikely to be a coincidence
- A long hypothesis that fits the data might be a coincidence

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