

$$+1$$

A

I returns 0
 \uparrow
 $C \propto t_0$
 $I \downarrow$

from
 $b^2 - \hbar b - a \leq 0 \quad (2)$

$$\|J_- |a, b\rangle\|^2 \geq 0$$

'=' holds iff

$$J_- |a, b\rangle = 0$$

$$(b = -a\hbar \text{ iff } J_- |a, b\rangle = 0)$$

\uparrow
 b_{\min}

Possible values of α :

$$b \longrightarrow \hbar b$$

If $p = \alpha - \hbar b$ is not an integer,

apply J_+ multiple times to $|a, b\rangle$ will lead to an eigenvector of J_+ that is not null, and has an eigenvalue $> a\hbar$.

Contradiction $\Rightarrow p = \alpha - \hbar b$ is an integer.

Similarly, $q = \hbar b - (-a) = \hbar b + a$ must be an integer.

$$\left. \begin{aligned} p &= \alpha - \hbar b \\ q &= a + \hbar b \end{aligned} \right\} \text{ are integers.}$$

$$\Rightarrow p + q = 2a \text{ is an integer.}$$

α is either integer or half-integer. ($\alpha \geq 0$ by definition)

Standard notation: $\alpha \longrightarrow j$
 $\hbar b \longrightarrow m$

Poll questions:

a) $|j = \frac{2}{3}, m = -\frac{2}{3}\rangle$ X

b) $|j = 5, m = 3\rangle$ ✓

c) $|j = 2, m = \frac{1}{2}\rangle$ X $m = -2, -1, 0, 1, 2$ only

d) $|j = \frac{1}{2}, m = \frac{1}{2}\rangle$ ✓

e) $|j = 1, m = 2\rangle$ X $m = -1, 0, 1$ only

f) $|j = -\frac{1}{2}, m = \frac{1}{2}\rangle$ X j cannot be negative

Now, let's obtain $J_{\pm} |j, m\rangle = c_{\pm} |j, m \pm 1\rangle$ ($J_+ |j, m_{\max}\rangle = 0$
 $J_- |j, m_{\min}\rangle = 0$)

Note: Each $|j, m\rangle$ is normalized to 1.

We need the norms of $J_{\pm} |j, m\rangle$.

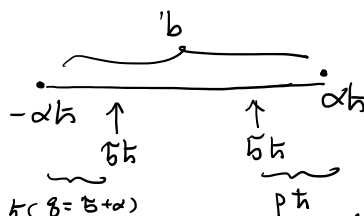
$$b^2 + \hbar b - a \leq 0 \quad (1)$$

$$\|J_+ |a, b\rangle\|^2 \geq 0$$

'=' holds iff

$$J_+ |a, b\rangle = 0$$

\uparrow
 b_{\max}



J_+ returns $-\alpha\hbar$
 J_- returns $(\alpha+1)\hbar$

J_+ returns $(-\alpha+1)\hbar$
 J_- returns 0

$$\begin{aligned}
\|J_+ |j, m\rangle\|^2 &= \langle j, m | J_+^\dagger J_+ |j, m\rangle \\
&= \langle j, m | J_- J_+ |j, m\rangle \\
&= \langle j, m | J^2 - J_z^2 - \hbar J_z |j, m\rangle \\
&\quad (\text{from W4L1}) \\
&= \hbar^2 j(j+1) - (m\hbar)^2 - \hbar(m\hbar) \\
&= \hbar^2 (j(j+1) - m(m+1))
\end{aligned}$$

$$\text{So } J_+ |j, m\rangle = \hbar \sqrt{j(j+1) - m(m+1)} |j, m+1\rangle$$

(When $m = m_{\max} = j$, RHS = 0 ✓)

$$\begin{aligned}
\text{Similarly, } \|J_- |j, m\rangle\|^2 &= \langle j, m | J_-^\dagger J_- |j, m\rangle \\
&= \langle j, m | J_+ J_- |j, m\rangle \\
&= \langle j, m | J^2 - J_z^2 + \hbar J_z |j, m\rangle \\
&\quad (\text{from W4L1}) \\
&= \hbar^2 j(j+1) - m^2 \hbar^2 + m\hbar^2 \\
&= \hbar^2 (j(j+1) - m(m-1))
\end{aligned}$$

$$\text{So } J_- |j, m\rangle = \hbar \sqrt{j(j+1) - m(m-1)} |j, m-1\rangle$$

(When $m = m_{\min} = -j$, RHS = 0 ✓)

$$J_\pm |j, m\rangle = \hbar \sqrt{j(j+1) - m(m \pm 1)} |j, m \pm 1\rangle, \quad -j \leq m \leq j$$

useful relation

Eg of how J_\pm is useful. → to construct matrix representations of J_x and J_y , given J_z .

Start with a basis $\{|j, m\rangle\}$ - eigenvectors of J^2 and J_z .

chooses axis \hat{z} .

(Note: j is fixed in the description for a given physical system)

eg This is a spin- $\frac{1}{2}$ system $\Rightarrow j = \frac{1}{2}$

" " " spin-1 system $\Rightarrow j = 1$

m can take $(2j+1)$ values.

$$J^2 \text{ and } J_z \text{ act on } \mathcal{V} \text{ spanned by } \left\{ |j, m=j\rangle, |j, m=j-1\rangle, \dots, |j, m=-j\rangle \right\}$$

$$\left\{ \begin{pmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ \vdots \\ 0 \end{pmatrix}, \dots, \begin{pmatrix} 0 \\ 0 \\ \vdots \\ 1 \end{pmatrix} \right\} \quad (2j+1)$$

Using this basis,
 J^2 and J_z are diagonal.

1 / j ...

matrix, vector

$$J_z \begin{pmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{pmatrix} = \hbar j \begin{pmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{pmatrix}$$

J_z and J_z are diagonal.

$$J_z = \hbar \begin{pmatrix} j & & & \\ & (j-1) & & \\ & & (j-2) & \\ & & & \ddots \\ & & & & -j \end{pmatrix}$$

How to get matrix representations of J_x and J_y ?

Use $J_+ = J_x + iJ_y$

$J_- = J_x - iJ_y$

Construct J_{\pm} .

Then $J_x = \frac{1}{2} (J_+ + J_-)$

$J_y = \frac{1}{2i} (J_+ - J_-)$

$$J_+ = \begin{pmatrix} \vec{c}_1 & \vec{c}_2 & \dots & \vec{c}_n \end{pmatrix}$$

$\uparrow \quad \uparrow$
 $J_- \begin{pmatrix} 1 \\ 0 \\ \vdots \end{pmatrix} \quad J_+ \begin{pmatrix} 0 \\ 1 \\ \vdots \end{pmatrix}$
 $\uparrow \quad \uparrow$
 $|j, m=j\rangle \quad |j, m=-j\rangle$

eg. $j = \frac{1}{2}$ system.

$2j+1 = 2, \quad m = -\frac{1}{2}, \frac{1}{2}$

$$J_z = \frac{\hbar}{2} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

$$\begin{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} \rightarrow |j = \frac{1}{2}, m = \frac{1}{2}\rangle \\ \begin{pmatrix} 0 \\ 1 \end{pmatrix} \rightarrow |j = \frac{1}{2}, m = -\frac{1}{2}\rangle \end{pmatrix}$$

$$J_+ = \begin{pmatrix} 0 & \hbar \\ 0 & 0 \end{pmatrix}$$

$\uparrow \quad \uparrow$
 $J_+ \begin{pmatrix} 1 \\ 0 \end{pmatrix} \quad J_+ \begin{pmatrix} 0 \\ 1 \end{pmatrix}$

$$= \hbar \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}$$

$J_+ \begin{pmatrix} 1 \\ 0 \end{pmatrix} ?$

$J_+ | \frac{1}{2}, \frac{1}{2} \rangle = 0$ (because $m = \frac{1}{2}$ is m_{\max})

$J_+ \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$

$J_+ \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \hbar \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{pmatrix} \hbar \\ 0 \end{pmatrix}$

$J_+ \begin{pmatrix} 0 \\ 1 \end{pmatrix} ?$

$J_+ | \frac{1}{2}, -\frac{1}{2} \rangle = \hbar \sqrt{j(j+1) - m(m+1)} | \frac{1}{2}, \frac{1}{2} \rangle$

$\overset{j}{\frac{1}{2}} \quad \overset{m}{-\frac{1}{2}} = \hbar \sqrt{\frac{1}{2}(\frac{3}{2}) - (-\frac{1}{2})(\frac{1}{2})} | \frac{1}{2}, \frac{1}{2} \rangle$

$= \hbar \sqrt{\frac{3}{4} + \frac{1}{4}} | \frac{1}{2}, \frac{1}{2} \rangle$

$= \hbar | \frac{1}{2}, \frac{1}{2} \rangle$

$$J_- = \begin{pmatrix} 0 & 0 \\ \hbar & 0 \end{pmatrix}$$

$\begin{pmatrix} 1 \\ 0 \end{pmatrix} \rightarrow | \frac{1}{2}, \frac{1}{2} \rangle$

$J_z \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \hbar j \begin{pmatrix} 1 \\ 0 \end{pmatrix}$

matrix \vec{v} vector
 $A \vec{v}$
 \uparrow

$$\begin{pmatrix} \vec{c}_1 & \vec{c}_2 & \vec{c}_3 & \dots & \vec{c}_n \end{pmatrix}$$

$\vec{c}_1 = A \vec{e}_1 = A \begin{pmatrix} 1 \\ 0 \\ \vdots \end{pmatrix}$

$\vec{c}_2 = A \vec{e}_2 = A \begin{pmatrix} 0 \\ 1 \\ \vdots \end{pmatrix}$

$$J_- = \begin{pmatrix} 0 & \hbar \\ \hbar & 0 \end{pmatrix}$$

$$\begin{matrix} \nearrow & \uparrow \\ J_-(\uparrow) & J_-(\downarrow) \end{matrix}$$

$$= \hbar \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}$$

$$|0\rangle \rightarrow |\frac{1}{2}, \frac{1}{2}\rangle$$

$$\begin{aligned} J_- |\frac{1}{2}, \frac{1}{2}\rangle &= \hbar \sqrt{j(j+1) - m(m-1)} |\frac{1}{2}, -\frac{1}{2}\rangle \\ &= \hbar \sqrt{\frac{3}{2}(\frac{3}{2}) - \frac{1}{2}(\frac{1}{2}-1)} |\frac{1}{2}, -\frac{1}{2}\rangle \\ &= \hbar \sqrt{\frac{3}{4} + \frac{1}{4}} |\frac{1}{2}, -\frac{1}{2}\rangle \\ &= \hbar |\frac{1}{2}, -\frac{1}{2}\rangle \end{aligned}$$

$$J_-(\downarrow) = \hbar \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 0 \\ \hbar \end{pmatrix}$$

$$J_-(\uparrow) = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$J_+ = \hbar \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}, \quad J_- = \hbar \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}$$

$$J_x = \frac{1}{2} (J_+ + J_-) = \frac{\hbar}{2} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$

$$J_y = \frac{1}{2i} (J_+ - J_-) = \frac{\hbar}{2i} \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} = \frac{\hbar}{2} \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}$$

$$J_z = \frac{\hbar}{2} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

For spin $\frac{1}{2}$ system,

we define $\vec{S} = \frac{\hbar}{2} \vec{\sigma}$
angular momentum

$$\left[\sigma_x = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, \sigma_y = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}, \sigma_z = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \right] \text{ Pauli matrices. (cf W3L2)}$$

Eigenstates of σ_z are $\{ |z, +\rangle \leftrightarrow \begin{pmatrix} 1 \\ 0 \end{pmatrix}, |z, -\rangle \leftrightarrow \begin{pmatrix} 0 \\ 1 \end{pmatrix} \}$

" σ_x " $\{ |x, +\rangle \leftrightarrow \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 1 \end{pmatrix}, |x, -\rangle \leftrightarrow \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ -1 \end{pmatrix} \}$

W3L2

" σ_y " $\{ |y, +\rangle \leftrightarrow \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ i \end{pmatrix}, |y, -\rangle \leftrightarrow \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ -i \end{pmatrix} \}$

Ex. work out.