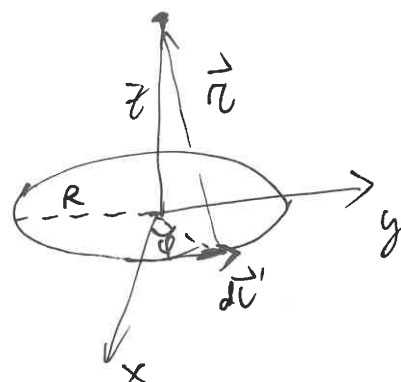


Homework 4 Solution

1.

(1) Biot-Savart law:

$$\vec{B} = \frac{\mu_0}{4\pi} I \int \frac{d\vec{l}' \times \hat{r}}{r^2} = \frac{\mu_0 I}{4\pi} \int \frac{d\vec{l}' \times \vec{r}}{r^3}$$



For $d\vec{l}'$, we pick the one shown on the graph

$$\text{where } d\vec{l}' = dl \hat{\varphi} = R d\varphi (-\sin\varphi \hat{x} + \cos\varphi \hat{y})$$

$$\vec{r} = (-R\cos\varphi, -R\sin\varphi, +z) = -R\cos\varphi \hat{x} - R\sin\varphi \hat{y} + z\hat{z}$$

$$|\vec{r}| = (R^2 + z^2)^{\frac{1}{2}}$$

$$\vec{B} = \frac{\mu_0 I}{4\pi} \int_0^{2\pi} \frac{R d\varphi (-\sin\varphi \hat{x} + \cos\varphi \hat{y}) \times (-R\cos\varphi \hat{x} - R\sin\varphi \hat{y} + z\hat{z})}{(R^2 + z^2)^{\frac{3}{2}}}$$

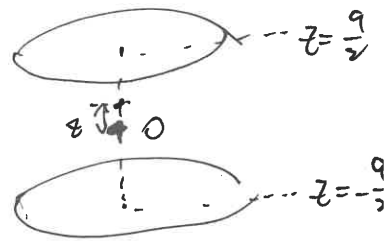
For the cross product term, we only care about the \hat{z} component because \hat{x} & \hat{y} components would vanish by symmetry (field points center on the loop wire), so

$$\vec{B} = \frac{\mu_0 I}{4\pi} \int_0^{2\pi} \frac{R d\varphi (R\sin^2\varphi \hat{x} \times \hat{y} - R\cos^2\varphi \hat{y} \times \hat{x})}{(R^2 + z^2)^{\frac{3}{2}}}$$

$$= \frac{\mu_0 I}{4\pi} \int_0^{2\pi} \frac{R d\varphi R \hat{z}}{(R^2 + z^2)^{\frac{3}{2}}} = \frac{\mu_0 I}{4\pi} \cdot \frac{R^2 \cdot 2\pi \hat{z}}{(R^2 + z^2)^{\frac{3}{2}}} = \frac{\mu_0 I R^2}{2(R^2 + z^2)^{\frac{3}{2}}} \hat{z} \quad (1)$$

(2)

(i) Suppose we pick the origin at the middle point between the wires, any offset in the z direction is denoted by z .



$$B(z) = \frac{\mu_0 I R^2}{2} \left[(R^2 + (\frac{a}{2} + z)^2)^{-\frac{3}{2}} + (R^2 + (\frac{a}{2} - z)^2)^{-\frac{3}{2}} \right]$$

where $z < \frac{a}{2}$

(ii)

$$\frac{dB}{dz} = -\frac{3}{2} \frac{\mu_0 I R^2}{2} \left[(R^2 + (\frac{a}{2} + z)^2)^{-\frac{5}{2}} \cdot 2 \cdot (\frac{a}{2} + z) + (R^2 + (\frac{a}{2} - z)^2)^{-\frac{5}{2}} \cdot 2 \cdot (\frac{a}{2} - z) \cdot (-1) \right]$$

$$= -\frac{3 \mu_0 I R^2}{2} \left[(R^2 + (\frac{a}{2} + z)^2)^{-\frac{5}{2}} \cdot (\frac{a}{2} + z) - (R^2 + (\frac{a}{2} - z)^2)^{-\frac{5}{2}} (\frac{a}{2} - z) \right]$$

From this, $\left. \frac{dB}{dz} \right|_{z=0, a=R} = 0$

$$\frac{d^2 B}{dz^2} = -\frac{3 \mu_0 I R^2}{2} \frac{d}{dz} \left[(R^2 + (\frac{a}{2} + z)^2)^{-\frac{5}{2}} (\frac{a}{2} + z) - (R^2 + (\frac{a}{2} - z)^2)^{-\frac{5}{2}} (\frac{a}{2} - z) \right]$$

①

$$\begin{aligned} \text{①} &= (R^2 + (\frac{a}{2} + z)^2)^{-\frac{5}{2}} + (\frac{a}{2} + z)^2 (-\frac{5}{2}) (R^2 + (\frac{a}{2} + z)^2)^{-\frac{7}{2}} \cdot 2 \\ &+ (R^2 + (\frac{a}{2} - z)^2)^{-\frac{5}{2}} - (\frac{a}{2} - z)^2 (-\frac{5}{2}) (R^2 + (\frac{a}{2} - z)^2)^{-\frac{7}{2}} \cdot 2 \cdot (-1) \end{aligned}$$

②

$$\Rightarrow \textcircled{1} = (R^2 + (\frac{a}{2} + z)^2)^{-\frac{5}{2}} + (R^2 + (\frac{a}{2} - z)^2)^{-\frac{5}{2}} \\ - 5(\frac{a}{2} + z)^2 (R^2 + (\frac{a}{2} + z)^2)^{-\frac{7}{2}} - 5(\frac{a}{2} - z)^2 (R^2 + (\frac{a}{2} - z)^2)^{-\frac{7}{2}}$$

When $a=R$, $z=0$,

$$\textcircled{1} = (\frac{5}{4}R^2)^{-\frac{5}{2}} \times 2 - 5\frac{R^2}{4} (\frac{5}{4}R^2)^{-\frac{7}{2}} \times 2 = 0$$

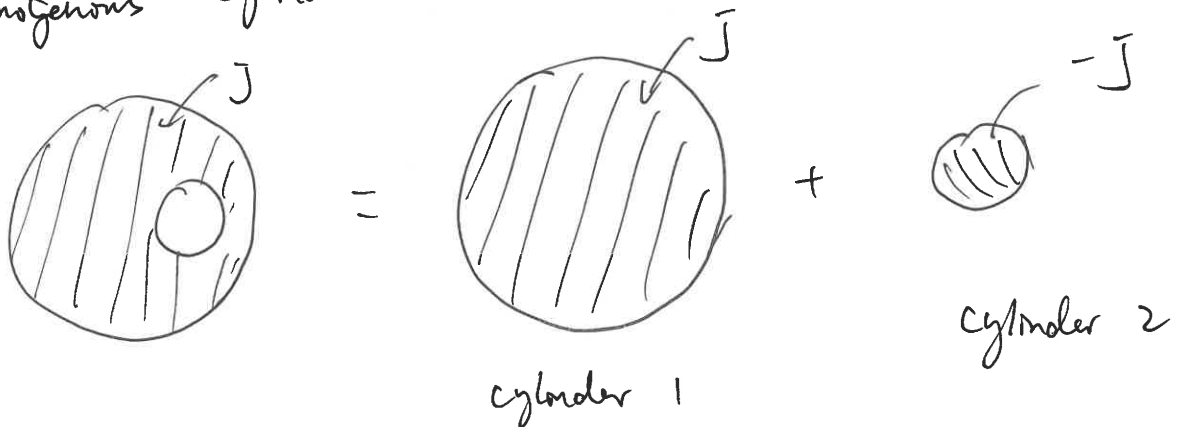
In conclusion, $\frac{dB}{dz} \Big|_{z=0} = \frac{d^2B}{dz^2} \Big|_{z=0} = 0$ when $a=R$

Therefore field is most uniform.

2.

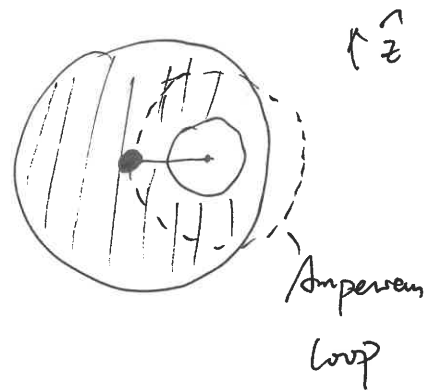
$$(1) \quad J = \frac{I}{A_L} = \frac{I}{\pi R_1^2 - \pi R_2^2} \quad \text{since current density is uniform.}$$

(2) We can imagine the geometry as the addition of two homogenous cylinders



③

At the center of the rod, cylinder 1
does not contribute any field (infinitesimal
Amperean loop, so $B_1 = 0$



cylinder 2 contributes B_2 can be calculated by the Amperean loop above.

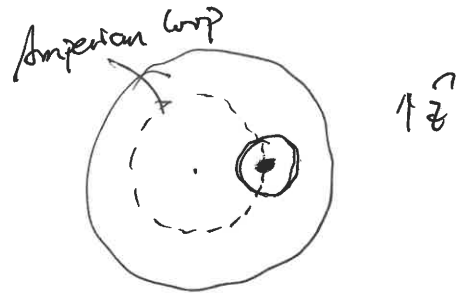
$$\oint \vec{B}_2 \cdot d\vec{l} = \mu_0 I_{enc, 2}$$

$$\Rightarrow B_2 \cdot 2\pi a = \mu_0 \pi R_2^2 \cdot J = \mu_0 \frac{[\pi R_2^2]}{\pi R_1^2 - \pi R_2^2}$$

$$\Rightarrow B_2 = \frac{\mu_0 I}{2\pi a} \frac{R_2^2}{R_1^2 - R_2^2} \Rightarrow \vec{B}_2 = \frac{\mu_0 I}{2\pi a} \frac{R_2^2}{R_1^2 - R_2^2} \cdot (-\hat{z})$$

determined by direction
of current in cylinder 2

(3) At the center of the hollow region, cylinder 2 contributes zero field, to



calculate cylinder 1 contribution, we choose the Amperean loop as above

$$\oint \vec{B}_1 \cdot d\vec{l} = \mu_0 I_{enc, 1}$$

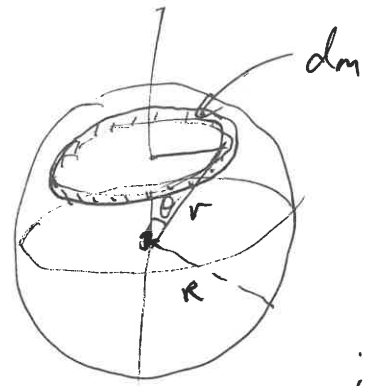
$$B_1 \cdot 2\pi a = \mu_0 \frac{\pi a^2 I}{\pi R_1^2 - \pi R_2^2}$$

$$\Rightarrow \vec{B}_1 = \frac{\mu_0 I}{2\pi} \frac{a^2}{R_1^2 - R_2^2} (-\hat{z})$$

(4)

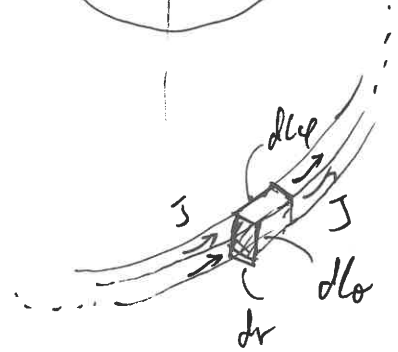
3.

(1) Breakdown the sphere with rings
 orienting along \hat{z} with radial and polar
 coordinates r and θ ($\varphi \in (0, 2\pi)$)



Total dipole moment $m = \int dm$

$dm = \underset{\substack{\text{area} \\ \text{of loop}}}{a} dI = \pi (r \sin \theta)^2 dI$



$$dI = J \cdot da_{\perp} = J dr d\theta = J r dr d\theta$$

Current density $J = \rho v = \frac{q}{\frac{4}{3}\pi R^3} w (r \sin \theta) = \frac{3q}{4\pi R^3} w r \sin \theta$

$$\Rightarrow dm = \pi (r \sin \theta)^2 \frac{3q}{4\pi R^3} w r \sin \theta \cdot r dr d\theta$$

$$= \frac{3qw}{4R^3} r^4 \sin^3 \theta dr d\theta$$

$$m = \int dm = \int_0^{\pi} \int_0^R \frac{3qw}{4R^3} r^4 \sin^3 \theta dr d\theta$$

$$= \frac{3qw}{4R^3} \int_0^{\pi} \sin^3 \theta d\theta \int_0^R r^4 dr$$

$$= \frac{3qw}{4R^3} \int_1^{-1} -(1-u^2) du \quad \left| \frac{1}{5} r^5 \right|_0^R$$

(5)

$$= \frac{3 q \omega}{4 R^3} \left(\frac{1}{3} u^3 - u \right) \Big|_1^{-1} \cdot \frac{R^5}{5}$$

$$= \frac{3 q \omega R^2}{20} \left(-\frac{1}{3} + 1 - \frac{1}{3} + 1 \right) = \frac{q \omega R^2}{5}$$

$$\vec{m} = \frac{q \omega R^2}{5} \hat{z}$$

(2) For $m = \frac{q \omega R^2}{5}$

where $m = \mu_B = 9.27 \times 10^{-24} \text{ A} \cdot \text{m}^2$

$$q = 1.6 \times 10^{-19} \text{ C}$$

$$R = 2.8 \times 10^{-15} \text{ m}$$

We have $\omega = 3.69 \times 10^{25} \text{ rad/s}$

velocity at equator $v = \omega R = 1.03 \times 10^{11} \text{ m/s}$

which is much larger than the speed of light ($3 \times 10^8 \text{ m/s}$)

4. * Note: the solution for this problem is not unique

(1) In the Cartesian coordinate $\vec{B} = \nabla \times \vec{A} = B_z \hat{z}$

converts into

(6)

$$\hat{x} \left(\frac{\partial A_z}{\partial y} - \frac{\partial A_y}{\partial z} \right) + \hat{y} \left(\frac{\partial A_x}{\partial z} - \frac{\partial A_z}{\partial x} \right) + \hat{z} \left(\frac{\partial A_y}{\partial x} - \frac{\partial A_x}{\partial y} \right) = B_z \hat{z}$$

$$\Rightarrow \frac{\partial A_z}{\partial y} = \frac{\partial A_y}{\partial z}, \quad \frac{\partial A_x}{\partial z} = \frac{\partial A_z}{\partial x}, \quad \frac{\partial A_y}{\partial x} - \frac{\partial A_x}{\partial y} = B_z$$

We can choose $A_z = 0$, $A_y = B_z x$, $A_x = 0$

$$\text{or } A_z = 0, \quad A_y = \frac{1}{2} B_z x, \quad A_x = -\frac{1}{2} B_z y$$

So two possible solutions: $\vec{A}_1 = (0, B_z x, 0)$

$$\text{or } \vec{A}_2 = \left(-\frac{1}{2} B_z y, \frac{1}{2} B_z x, 0\right)$$

$$(2) \quad \vec{A}_2 = \left(-\frac{1}{2} B_z y, \frac{1}{2} B_z x, 0\right) = -\frac{1}{2} B_z y \hat{x} + \frac{1}{2} B_z x \hat{y}$$

can be converted to cylindrical coordinates

$$\text{Use identity } \left\{ \begin{array}{l} x = s \cos \phi \\ y = s \sin \phi \\ \hat{x} = \cos \phi \hat{s} - \sin \phi \hat{\phi} \\ \hat{y} = \sin \phi \hat{s} + \cos \phi \hat{\phi} \end{array} \right.$$

$$\vec{A}_2 = -\frac{1}{2} B_z \left(s \sin \phi (\cos \phi \hat{s} - \sin \phi \hat{\phi}) - s \cos \phi (\sin \phi \hat{s} + \cos \phi \hat{\phi}) \right)$$

$$= \frac{1}{2} B_z s \hat{\phi}$$

Alternatively one can also get an answer by examining $\nabla \times \vec{A}$ in the cylindrical coordinate

(7)

(3) $\vec{B} = \nabla \times \vec{A}$ must satisfy for \vec{A}_1 and \vec{A}_2 because we derived these expressions using this identity, so no need to prove.

Regarding $\nabla \cdot \vec{A} = 0$

$$\nabla \cdot \vec{A}_1 = \frac{\partial}{\partial x}(0) + \frac{\partial}{\partial y}(B_z x) + \frac{\partial}{\partial z}(0) = 0$$

$$\nabla \cdot \vec{A}_2 = \frac{\partial}{\partial x}(-\frac{1}{2}B_z y) + \frac{\partial}{\partial y}(\frac{1}{2}B_z x) + \frac{\partial}{\partial z}(0) = 0$$

or, in cylindrical coordinates,

$$\nabla \cdot \vec{A}_2 = \frac{1}{s} \frac{\partial}{\partial s}(s \cdot 0) + \frac{1}{s} \frac{\partial}{\partial \phi}(\frac{1}{2}B_z s) + \frac{\partial}{\partial z}(0) = 0$$

5.

Biot-Savart law that works for surface

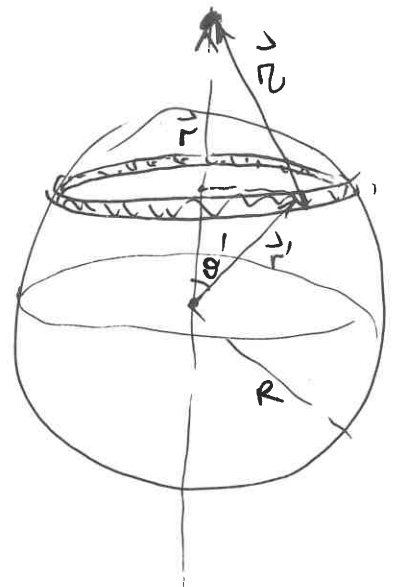
$$\text{Current: } \vec{B}(\vec{r}) = \frac{\mu_0}{4\pi} \int \frac{\vec{K}(\vec{r}') \times \vec{r}}{r^2} da'$$

$$\text{Where } \vec{K} = \vec{K}_\perp = M \sin \theta' \hat{\phi}$$

From law of Cosines

$$r^2 = r'^2 + R^2 - 2r'R \cos \theta'$$

$$\text{And we have } \vec{r} = (0, 0, r), \vec{r}' = (R \sin \theta' \cos \phi', R \sin \theta' \sin \phi', R \cos \theta')$$



$$\Rightarrow \vec{r} = (R \sin \theta' \cos \varphi', -R \sin \theta' \sin \varphi', -R \cos \theta' + r)$$

Further, in cylindrical coordinates $\hat{\varphi} = (-\sin \varphi', \cos \varphi', 0)$

So $(\hat{\varphi} \times \vec{r}) \cdot \hat{z}$, the z-component of $\hat{\varphi} \times \vec{r}$

$$+ \sin \varphi' \cdot R \sin \theta' \sin \varphi' + \cos \varphi' R \sin \theta' \cos \varphi' = +R \sin \theta'$$

Therefore,

$$\hat{z} \cdot \vec{B}(\vec{r}) = \frac{\mu_0}{4\pi} \int \frac{\vec{K}_L(\vec{r}') \times \vec{r}}{r^2} da' \cdot \hat{z} \quad (\text{where } da' = R^2 \sin \theta' d\theta' d\varphi')$$

$$= \frac{\mu_0}{4\pi} \int \frac{\vec{K}_L(\vec{r}') \times \vec{r}}{r^3} da' \cdot \hat{z}$$

$$= \frac{\mu_0}{4\pi} \int_0^{2\pi} \int_0^\pi \frac{M \sin \theta' (\hat{\varphi} \times \vec{r}) \cdot \hat{z}}{(r^2 + R^2 - 2rR \cos \theta)^{\frac{3}{2}}} \cdot R^2 \sin \theta' d\theta' d\varphi'$$

$$= \frac{\mu_0}{4\pi} \int_0^{2\pi} \int_0^\pi \frac{M \sin \theta' \cdot R \sin \theta' \cdot R^2 \sin \theta'}{(r^2 + R^2 - 2rR \cos \theta)^{\frac{3}{2}}} d\theta' d\varphi'$$

$$= \frac{\mu_0 M R^3}{2} \underbrace{\int_0^\pi \frac{\sin^3 \theta}{(r^2 + R^2 - 2rR \cos \theta)^{\frac{3}{2}}} d\theta}_{(2)}$$

Assume Substitution $u = r^2 + R^2 - 2rR \cos \theta$

(9)

$$du = 2rR \sin\theta \, d\theta$$

$$\sin^2\theta = 1 - \cos^2\theta = 1 - \left(\frac{r^2 + R^2 - u}{2rR} \right)^2$$

$$\Rightarrow \textcircled{2} = \int_{(r-R)^2}^{(r+R)^2} \frac{1}{2rR} \left[1 - \left(\frac{r^2 + R^2 - u}{2rR} \right)^2 \right] u^{-\frac{3}{2}} du$$

$$= \int_{(r-R)^2}^{(r+R)^2} \frac{1}{2rR} \frac{4r^2R^2 - (r^2 + R^2 - u)^2}{4r^2R^2} u^{-\frac{3}{2}} du$$

$$= \frac{1}{8r^3R^3} \int_{(r-R)^2}^{(r+R)^2} [(r+R)^2 - u][u - (r-R)^2] u^{-\frac{3}{2}} du$$

$$= \frac{1}{8r^3R^3} \int_{u=(r-R)^2}^{u=(r+R)^2} [(r+R)^2 - u][u - (r-R)^2] (-2) d(u^{-\frac{1}{2}})$$

↙ integrate by parts

↙ This term is zero

$$= \frac{-2}{8r^3R^3} \left\{ [(r+R)^2 - u][u - (r-R)^2] u^{-\frac{1}{2}} \right\} \Big|_{(r-R)^2}^{(r+R)^2}$$

$$- \int_{(r-R)^2}^{(r+R)^2} u^{-\frac{1}{2}} \{ [(r+R)^2 - u] - [u - (r-R)^2] \} du$$

$$= \frac{1}{4r^3R^3} \int_{(r-R)^2}^{(r+R)^2} u^{-\frac{1}{2}} (-2u + 2r^2 + 2R^2) du$$

$$= \frac{-1}{2r^3R^3} \int_{(r-R)^2}^{(r+R)^2} [u^{\frac{1}{2}} - (r^2 + R^2) u^{-\frac{1}{2}}] du$$

$$= -\frac{1}{3} \frac{1}{r^3 R^3} u^{\frac{3}{2}} \left| \frac{(r+R)^2}{(r-R)^2} + \frac{r^2+R^2}{r^3 R^3} u^{\frac{1}{2}} \right| \frac{(r+R)^2}{(r-R)^2}$$

(1) When $r < R$

$$\begin{aligned} \textcircled{2} &= -\frac{1}{3} \frac{1}{r^3 R^3} u^{\frac{3}{2}} \left| \frac{(r+R)^2}{(R-r)^2} + \frac{r^2+R^2}{r^3 R^3} u^{\frac{1}{2}} \right| \frac{(R+r)^2}{(R-r)^2} \\ &= -\frac{1}{3 r^3 R^3} [(R+r)^3 - (R-r)^3] + \frac{r^2+R^2}{r^3 R^3} (R+r - R+r) \\ &= -\frac{1}{3 r^3 R^3} (2r^3 + 6R^2 r) + \frac{2r^3 + 2rR^2}{r^3 R^3} = \frac{4}{3} \frac{1}{R^3} \end{aligned}$$

$$\text{Therefore } \frac{1}{2} \cdot \vec{B}(\vec{r}) = \frac{\mu_0 M R^3}{2} \cdot \textcircled{2} = \frac{\mu_0 M R^3}{2} \cdot \frac{4}{3} \frac{1}{R^3} = \frac{2}{3} \mu_0 M$$

(2) When $r > R$

$$\begin{aligned} \textcircled{2} &= -\frac{1}{3} \frac{1}{r^3 R^3} u^{\frac{3}{2}} \left| \frac{(R+r)^2}{(r-R)^2} + \frac{r^2+R^2}{r^3 R^3} u^{\frac{1}{2}} \right| \frac{(r+R)^2}{(r-R)^2} \\ &= -\frac{1}{3 r^3 R^3} [(R+r)^3 - (r-R)^3] + \frac{r^2+R^2}{r^3 R^3} \cdot 2R \\ &= -\frac{1}{3 r^3 R^3} (2R^3 + 6r^2 R) + \frac{2Rr^2 + 2R^3}{r^3 R^3} = \frac{4}{3 r^3} \end{aligned}$$

$$\text{Therefore } \frac{1}{2} \cdot \vec{B}(\vec{r}) = \frac{\mu_0 M R^3}{2} \cdot \frac{4}{3 r^3} = \frac{2}{3} \mu_0 M \frac{R^3}{r^3}$$

(11)

This can be rearranged as

$$\hat{z} \cdot \vec{B}(\vec{r}) = \frac{2}{3} \mu_0 M \frac{R^3}{r^3} = \frac{\mu_0}{2\pi} \left(\frac{4}{3} \pi M R^3 \right) \frac{1}{r^3} = \frac{\mu_0}{2\pi} \frac{m}{r^3}$$

This is the field expected for magnetic dipole with $m = \frac{4}{3} \pi R^3 M$

according to textbook eq. (5.88)

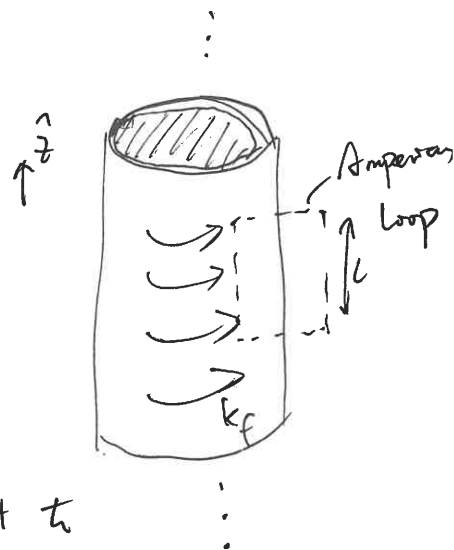
6.

(1) Using symmetry arguments, we can argue

that $\vec{B} \parallel \vec{H} \parallel \vec{M} \parallel \hat{z}$ everywhere

and $\vec{B} = \vec{H} = \vec{M} = 0$ outside the coil. ($s > R$)

Use the rectangular Amperian loop on the right to



calculate \vec{H} : $\oint \vec{H} \cdot d\vec{l} = I_{fenc}$

$$\Rightarrow H \cdot L = n I L \Rightarrow \vec{H} = n I \hat{z} \text{ inside the coil. } (s < R)$$

In the magnetic medium $\vec{B} = \mu \vec{H} = \mu_0 (1 + \chi_m) \vec{H} = \mu_0 (1 + \chi_m) n I \hat{z}$
for ($s < R$)

$$\vec{M} = \chi_m \vec{H} = \chi_m n I \hat{z} \quad (s < R)$$

For calculating vector potential \vec{A} , we use

$$\oint \vec{A} \cdot d\vec{l} = \int \vec{B} \cdot d\vec{a} \text{ and choose the Amperian loop below}$$

Symmetry analysis suggests $\vec{A} \parallel \hat{\phi}$, as in textbook example 5.9

For $s < R$, $2\pi s A = \pi s^2 \cdot \mu_0 (1 + \chi_m) n I$

$$\Rightarrow \vec{A} = \frac{s \mu_0 (1 + \chi_m) n I}{2} \hat{\phi}$$



For $s > R$, $2\pi s A = \pi R^2 \cdot \mu_0 (1 + \chi_m) n I$

$$\Rightarrow \vec{A} = \frac{R^2 \mu_0 (1 + \chi_m) n I}{2s} \hat{\phi}$$

(2) $\vec{k}_f = nI \hat{\phi}$ is the effective surface current.

$$\vec{B}_{above} - \vec{B}_{below} = \vec{k}_f \times \hat{n}$$

This is satisfied by $\hat{z} (H_z(s > R) - B_z(s < R)) = k_f (\hat{\phi} \times \hat{z}) = -nI \hat{z}$

$$\Rightarrow 0 - nI \hat{z} = -nI \hat{z} \quad \checkmark$$

$$\vec{B}_{above}^\perp - \vec{B}_{below}^\perp = -M_{above}^\perp - M_{below}^\perp$$

Here \perp components mean components along \hat{s} , while neither

\vec{B} nor \vec{M} has \hat{s} component, so $0 = 0 \quad \checkmark$

$$\vec{B}_{above}^\perp = \vec{B}_{below}^\perp$$

Because there is no \hat{s} component, $0 = 0 \quad \checkmark$

$$\underline{\vec{B}'_{above} - \vec{B}''_{below} = \mu_0 (\vec{K} \times \hat{n})}$$

Here $\vec{K} = \vec{K}_f + \vec{K}_b$, where \vec{K}_b is the bound current on surface

$$\vec{K}_b = \vec{M} \times \hat{n} = \chi_m n I \hat{z} \times \hat{s} = \chi_m n I \hat{\phi}$$

$$\therefore \vec{K} = \vec{K}_f + \vec{K}_b = (1 + \chi_m) n I \hat{\phi}$$

Boundary condition satisfied by

$$\begin{aligned} \hat{z} (B_z(s > R) - B_z(s < R)) &= \mu_0 K (\hat{\phi} \times \hat{s}) \\ &= -\mu_0 (1 + \chi_m) n I \hat{z} \end{aligned}$$

$$0 - \mu_0 (1 + \chi_m) n I \hat{z} = -\mu_0 (1 + \chi_m) n I \hat{z} \quad \checkmark$$

$$\underline{\vec{A}_{above} = \vec{A}_{below}}$$

Match solutions for $s < R$ & $s > R$ @ $s = R$

$$\vec{A}_{below}|_{s=R} = \frac{R \mu_0 (1 + \chi_m) n I}{2} \hat{\phi}$$

$$\vec{A}_{above}|_{s=R} = \frac{R^2 \mu_0 (1 + \chi_m) n I}{2R} \hat{\phi} = \frac{R \mu_0 (1 + \chi_m) n I}{2} \hat{\phi} = \vec{A}_{below}|_{s=R} \quad \checkmark$$

$$\frac{\partial \vec{A}_{above}}{\partial n} - \frac{\partial \vec{A}_{below}}{\partial n} = -\mu_0 \vec{K}$$

Here $\vec{K} = \vec{K}_f + \vec{K}_b = (1 + \chi_m) n I \hat{\phi}$

$$\frac{\partial \vec{A}_{above}}{\partial n} = \left. \frac{\partial \vec{A}(s > R)}{\partial s} \right|_{s=R} = \frac{R^2 \mu_0 (1 + \chi_m) n I \hat{\phi}}{-2s^2} \bigg|_{s=R} = \frac{\mu_0 (1 + \chi_m) n I \hat{\phi}}{-2}$$

$$\frac{\partial \vec{A}_{below}}{\partial n} = \left. \frac{\partial \vec{A}(s < R)}{\partial s} \right|_{s=R} = \frac{\mu_0 (1 + \chi_m) n I \hat{\phi}}{2}$$

$$\Rightarrow \frac{\partial \vec{A}_{above}}{\partial n} - \frac{\partial \vec{A}_{below}}{\partial n} = -\mu_0 (1 + \chi_m) n I \hat{\phi} = -\mu_0 \vec{K} \quad \checkmark$$