

CS2040 Lab 11

SSSP

One Day Assignment 9 – Lost Map

- Shortest path from u to v is given in the adjacency matrix
- Also know that the original graph is a tree
- Pick the smallest edge (u, v) where $u \neq v$, and which does not form a cycle. Edge must be part of the original graph
 - Proof on next slide
- Basically an MST

One Day Assignment 9 – Lost Map

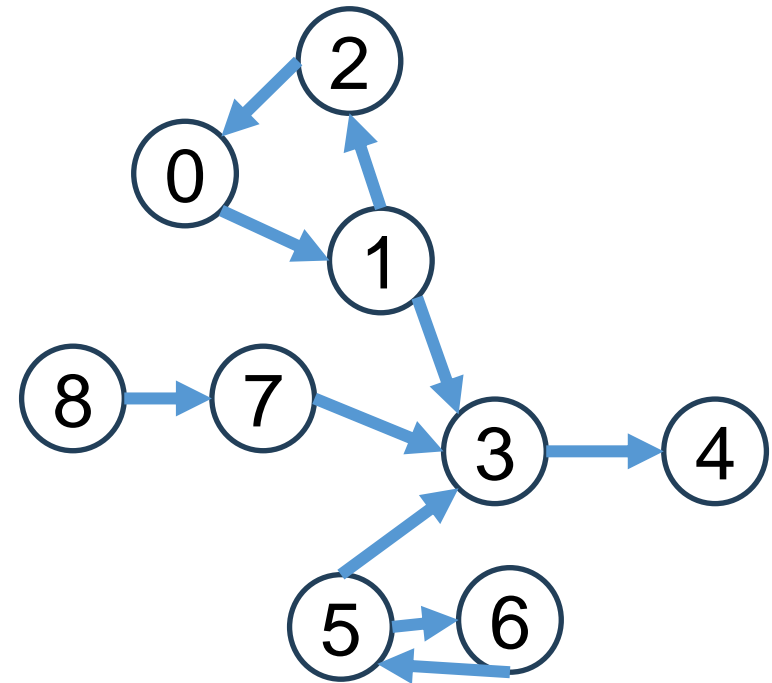
- In the proof below, $(u \rightsquigarrow v)$ (curly arrow) represents a path (ie. may be more than one edge), while $(u \rightarrow v)$ represents a direct edge
- Proof by contradiction: Suppose a different path from $u \rightsquigarrow k \rightsquigarrow v$ for some vertex k exists, such that $\text{cost}(u \rightsquigarrow k \rightsquigarrow v) \leq \text{cost}(u \rightarrow v)$, where $u \rightarrow v$ is the edge selected by the MST algorithm
- Cost of paths $(u \rightsquigarrow k)$ and $(k \rightsquigarrow v)$ must both be less than $\text{cost}(u \rightarrow v)$, since no edge between two distinct vertices has cost 0 (ie. neither $(u \rightsquigarrow k)$ nor $(k \rightsquigarrow v)$ are cost 0)
- But $u \rightarrow v$ is the smallest edge, therefore a contradiction occurs
- Therefore $u \rightarrow v$ must be part of the original graph

Take Home Assignment 4a – Millionaire Madness

- Finding the minimum ladder length required to reach the lower right corner: standard minimax problem
- Can be solved by finding MST
- However, edges in this graph are bidirectional (different edge weights in different directions)
 - Kruskal's may not work as a result
- Perform Prim's from the starting point to get a directed MST, and perform BFS/DFS to find the largest edge along the path
 - Alternatively, return the weight of the largest edge found so far when the ending point is added to the MST when running Prim's

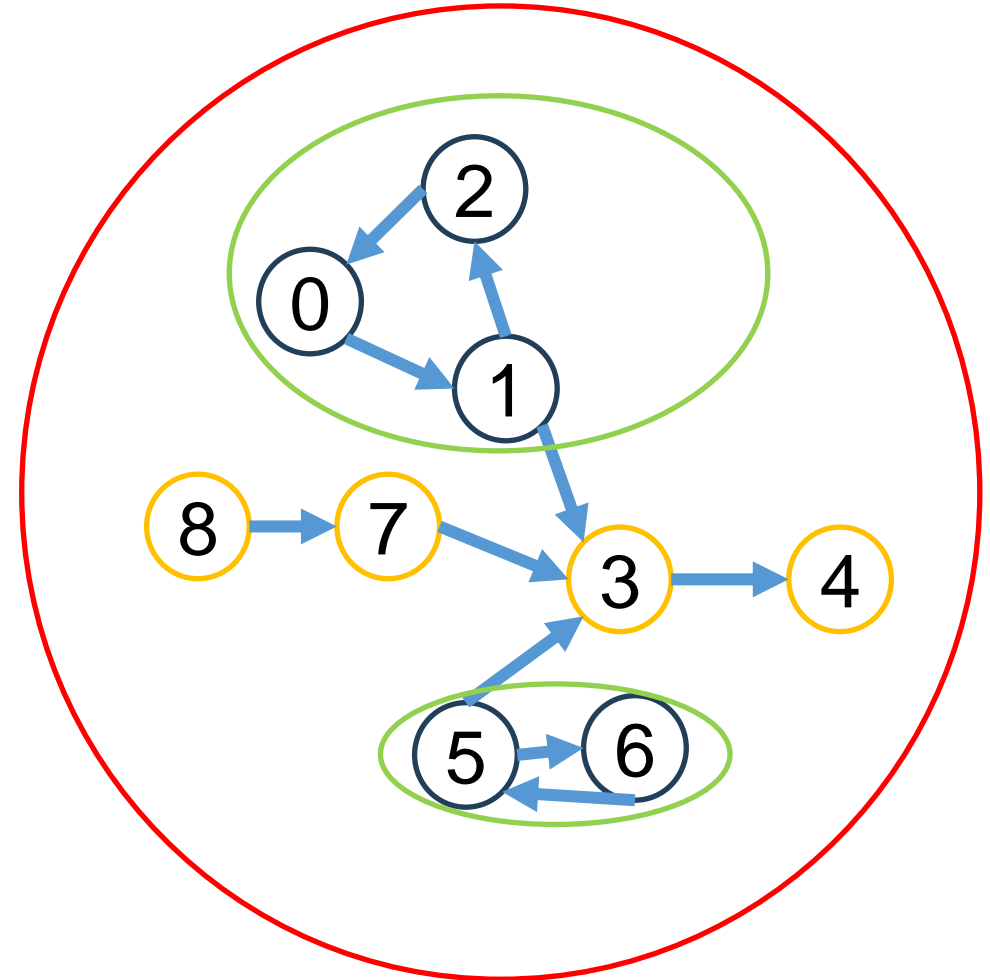
Take Home Assignment 4b – Bots

- Glossary
 - Network -> Graph
 - Bot -> Vertex
 - Signal(u, v) -> HasDirectedEdge(u, v)
 - Message(u, v) -> IsReachable(u, v)
 - Botnet -> SCC of size > 1
 - Solobot -> SCC of size == 1



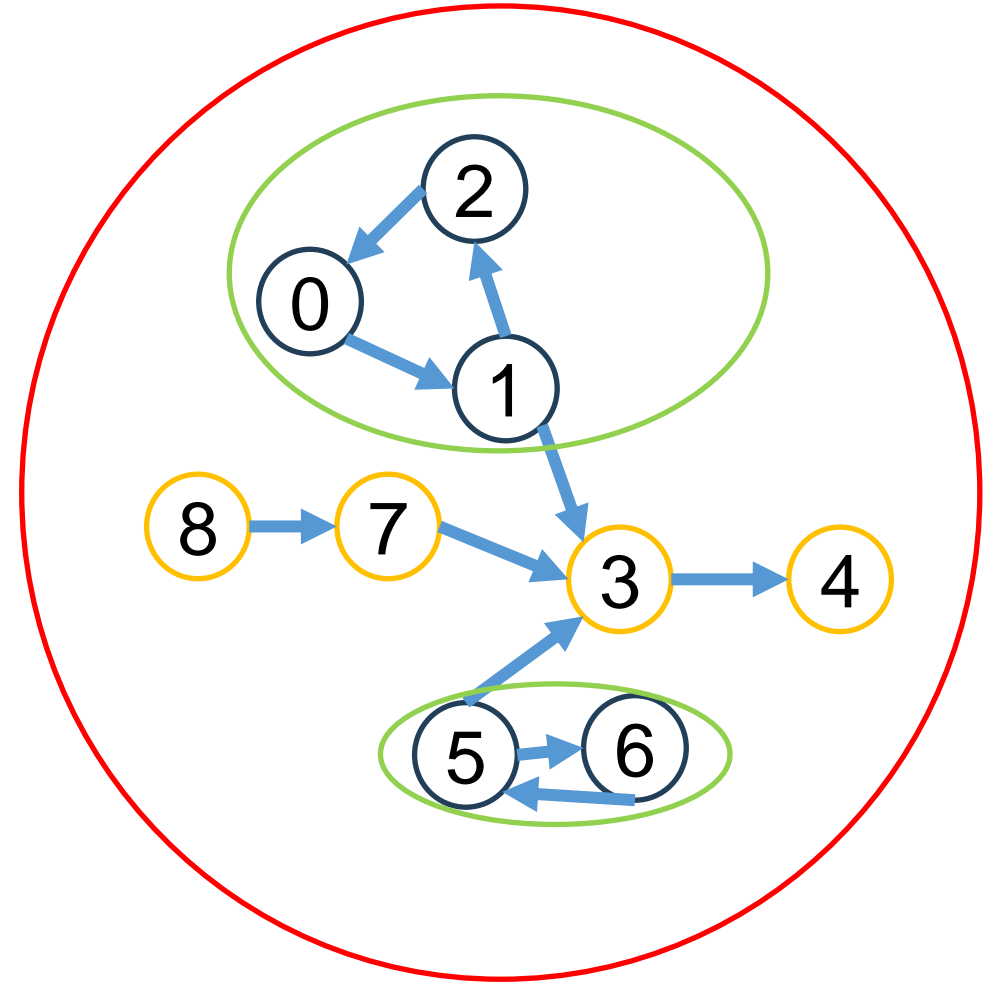
Take Home Assignment 4b – Bots

- Glossary
 - Network -> Graph
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 - Signal(u, v) -> HasDirectedEdge(u, v)
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 - Botnet -> SCC of size > 1
 - Solobot -> SCC of size == 1
- SCCs **CAN** be of size 1
 - Common misconception that SCC must have at least 2 nodes



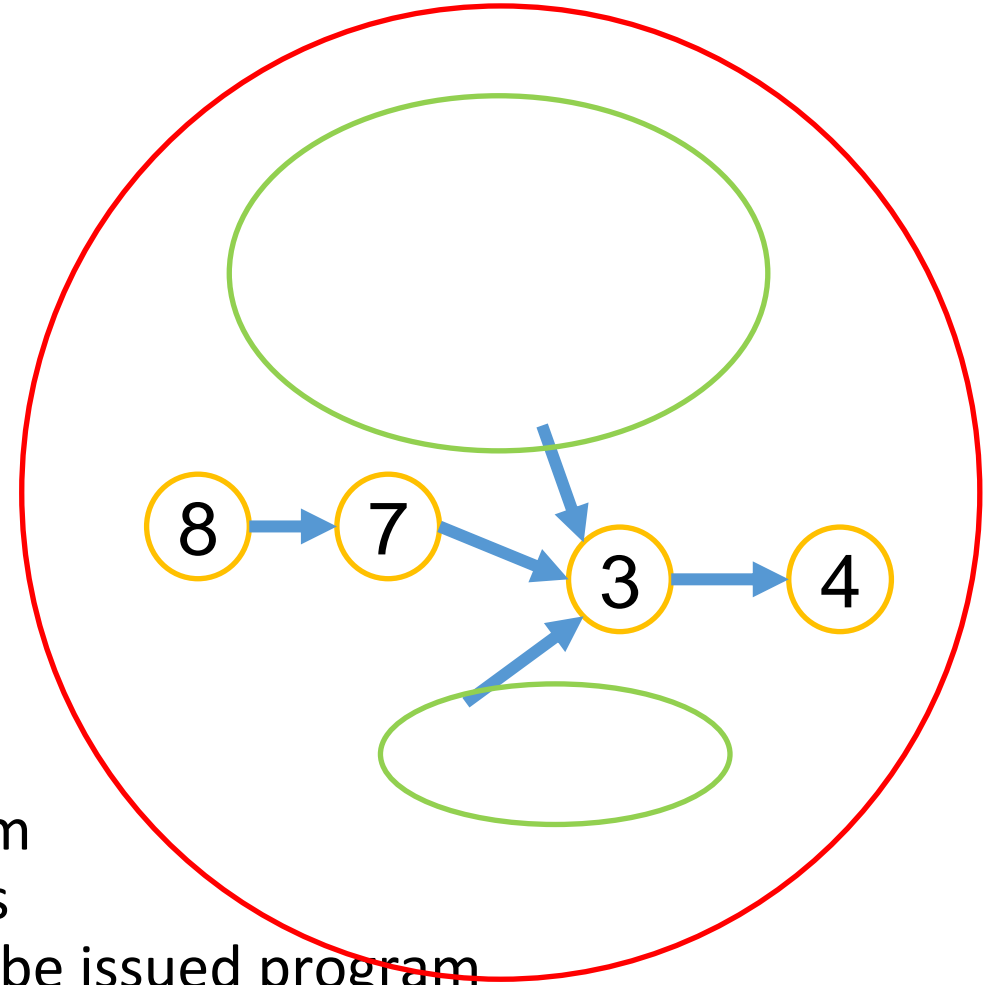
Take Home Assignment 4b – Bots

- How to minimize number of bots you have to issue program to?
- No point issuing program to:
 - 7, 3, 4
 - More than one bot in {5, 6}
 - More than one bot in {0, 1, 2}
- Only issue program to:
 - 1 bot in {5, 6}
 - 1 bot in {0, 1, 2}
 - solobot 8



Take Home Assignment 4b – Bots

- Consider SCC kernel graph
 - Treat one SCC as one super-vertex
 - No cycles, Kernel graph is a DAG (original graph can be cyclic)
- Find SCCs that are sources in the SCC kernel graph
 - Source \leftrightarrow in-degree 0
 - Sink \leftrightarrow out-degree 0 e.g. solobot 4
 - Source solobot has to be issued program
 - Each source SCC (in kernel graph) needs exactly 1 bot (doesn't matter which) to be issued program



Take Home Assignment 4b – Bots

1. Construct the directed, unweighted graph
2. Find the SCCs using Kosaraju's algorithm in **$O(V + E)$** time
 - Also label the SCCs, and get the size of each SCC
3. Check which SCCs are “source SCC”
4. Among the “source SCC”, count the number of singleton and non-singleton SCCs

Take Home Assignment 4b – Bots

- Kosaraju's algorithm
 - Why do we need to transpose graph $G \rightarrow G^T$?
 - Runs of 2 types of DFS for different purposes
 - First type on G^T to find source SCCs in G^T , i.e. sink SCCs in G
 - Run **post-order** DFS – “visit” neighbours first, then myself
 - Accumulate **post-order visited** nodes, then reverse
 - Second type to label SCCs in G
 - Run the usual **pre-order** DFS – “visit” myself first, then neighbours
- Common mistake:
 - “Run first type of DFS on G but don't reverse the post-order”
 - “Run second type of DFS on G following that post-order visitation sequence”
 - You **may not** be following a sequence from sink SCC to source SCC

Lab 11 – SSSP

- By this point, several different SSSP algorithms have been covered, each suited for a different kind of graph
- As such, when attempting any problem involving SSSP, it might be best to consider the graph types first
 - 1. Is the graph a tree? (use DFS/BFS)
 - 2. Is the graph unweighted? (use BFS)
 - 3. Is the graph a DAG? (use one-pass Bellman Ford)
 - 4. Does the graph have only nonnegative edges? (use Original/Modified Dijkstra's)
 - 5. Does the graph have no negative cycles? (use Modified Dijkstra's)
 - 6. If all else fails, use standard Bellman Ford

Lab 11 – SSSP



Disclaimer: you can use Floyd Warshall to solve SSSP problems too, though Floyd Warshall will typically run slower as it solves a different problem (APSP)

One Day Assignment 10 – Human Cannonball Run

- Given a starting point, an end point, and a number of cannon (note: plural of cannon is cannon), determine the shortest time required to reach the end point from the starting point
- Running speed is 5 m/s
- A cannon launches you a distance of exactly 50m (this cannot be changed), and takes 2 seconds to do so

One Day Assignment 10 – Human Cannonball Run

- The following may be useful in solving the problem
- Pythagorean Theorem: Given a right-angled triangle, $a^2 + b^2 = c^2$
 - c can also be calculated using Java's `Math.hypot(a, b)` method

