

PC3261: Classical Mechanics II

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Lecture 10: Hamiltonian Mechanics I

Legendre transformation

- Conjugate pair of variables: (u, x) and (v, y) are conjugate pairs

$$df = u dx + v dy$$

- **Legendre transformation** converts a function with dependence on variable(s) to another function with dependence on conjugate variable(s)

$$f(x, y) \Rightarrow df = \frac{\partial f(x, y)}{\partial x} dx + \frac{\partial f(x, y)}{\partial y} dy \equiv u(x, y) dx + v(x, y) dy$$

$$f(x, y) \rightarrow g(u, y) \equiv f(x(u, y), y) - x(u, y)u$$

- Examples: thermodynamic internal energy $E(S, V)$ to Helmholtz free energy $F(T, V)$, internal energy $E(S, V)$ to Gibbs free energy $G(T, P)$, internal energy to enthalpy $H(S, P)$, etc

EXERCISE 10.1: Starting from $g = g(u, y)$, perform a Legendre transformation to another function $h = h(x, v)$.

$$df = u(x, y) dx + v(x, y) dy$$

$$u = u(x, y) = \left(\frac{\partial f}{\partial x} \right)_y \quad \Rightarrow \quad x = x(u, y)$$

$$g(u, y) \equiv f(x(u, y), y) - x(u, y)u$$

$$dg = df - x du - u dx$$

$$\Rightarrow dg = (u dx + v dy) - x du - u dx$$

$$\Rightarrow dg = -x du + v dy$$

$$\Rightarrow g(u, y) \quad \blacksquare$$

$$df = u dx + v dy \equiv \frac{\partial f}{\partial x} dx + \frac{\partial f}{\partial y} dy$$

$$g = g(u, y) \equiv f(x(u, y)) - x(u, y)u \quad \Rightarrow \quad dg = -x du + v dy$$

$$\begin{cases} u = u(x, y) = \left(\frac{\partial f}{\partial x} \right)_y \\ v = v(x, y) = \left(\frac{\partial f}{\partial y} \right)_x \end{cases} \Rightarrow \begin{cases} u = u(x, v) \\ y = y(x, v) \end{cases}$$

$$h = h(x, v) \equiv g(u(x, v), y(x, v)) + u(x, v)x - y(x, v)v$$

$$\Rightarrow dh = (-x du + v dy) + (u dx + x du) - (y dv + v dy) = u dx - y dv \quad \blacksquare$$

$$h = h(x, v) \equiv -u(x, v)x + y(x, v)v - g(u(x, v), y(x, v))$$

$$\Rightarrow dh = -(u dx + x du) + (y dv + v dy) - (-x du + v dy) = -u dx + y dv \quad \blacksquare$$

Hamiltonian function

- Lagrangian function:

$$\mathcal{L} \equiv \mathcal{L}(\{q_i(t), \dot{q}_i(t)\}, t) \quad \Rightarrow \quad d\mathcal{L} = \sum_{i=1}^M \left(\frac{\partial \mathcal{L}}{\partial q_i} dq_i + \frac{\partial \mathcal{L}}{\partial \dot{q}_i} d\dot{q}_i \right) + \frac{\partial \mathcal{L}}{\partial t} dt$$

- **Hamiltonian function** (or **Hamiltonian**) has explicit dependences on generalized coordinates q_i , generalized momenta p_i and time t

$$\mathcal{H} \equiv \mathcal{H}(\{q_i(t), p_i(t)\}, t)$$

$$\equiv \sum_{i=1}^M \dot{q}_i(\{q_k(t), p_k(t)\}, t) p_i(t) - \mathcal{L}(\{q_i(t), \dot{q}_i(\{q_k(t), p_k(t)\}, t)\}, t)$$

- Be cautious on the flip of signs in the Legendre transformation from Lagrangian to Hamiltonian!

Hamiltonian function – cont'd

- Generalized momenta:

$$p_i \equiv \frac{\partial \mathcal{L}}{\partial \dot{q}_i} \quad \Rightarrow \quad \dot{q}_i = \dot{q}_i(\{q_k(t), p_k(t)\}, t)$$

- A couple of extra steps (not necessarily trivial) in the construction of Hamiltonian from the Lagrangian are to write down the generalized momenta p_i and solve for the generalized velocities in terms of generalized coordinates, generalized momenta and time, $\dot{q}_i(\{q_k, p_k\}, t)$
- The set of generalized coordinates and generalized momenta, $\{q_k(t), p_k(t)\}$, used in Hamiltonian mechanics is generally known as **canonical coordinates**

EXERCISE 10.2: Construct the Hamiltonian for a particle of mass m subjected to a conservative central force field with potential energy $U(r)$ using usual polar coordinates r and ϕ as generalized coordinates.

$$\mathcal{L} \equiv \mathcal{L}(r, \phi, \dot{r}, \dot{\phi}, t) = \frac{1}{2} m (\dot{r}^2 + r^2 \dot{\phi}^2) - U(r)$$

$$\begin{cases} p_r = \frac{\partial \mathcal{L}}{\partial \dot{r}} = m\dot{r} \\ p_\phi = \frac{\partial \mathcal{L}}{\partial \dot{\phi}} = mr^2 \dot{\phi} \end{cases} \Rightarrow \begin{cases} \dot{r} = \frac{p_r}{m} \\ \dot{\phi} = \frac{p_\phi}{mr^2} \end{cases} \quad \blacksquare$$

$$\mathcal{H} \equiv \mathcal{H}(r, \phi, p_r, p_\phi, t)$$

$$\equiv \sum_i p_i \dot{q}_i(r, \phi, p_r, p_\phi, t) - \mathcal{L}(r, \phi, \dot{r}(r, \phi, p_r, p_\phi, t), \dot{\phi}(r, \phi, p_r, p_\phi, t), t)$$

$$= p_r \dot{r} + p_\phi \dot{\phi} - \left[\frac{1}{2} m (\dot{r}^2 + r^2 \dot{\phi}^2) - U(r) \right]$$

$$= \frac{1}{2m} \left(p_r^2 + \frac{p_\phi^2}{r^2} \right) + U(r) \quad \blacksquare$$

Hamilton equations of motion

- **Hamilton equations of motion** (or **canonical equations of motion**):

$$\left\{ \begin{array}{l} \dot{q}_i = \frac{\partial \mathcal{H}}{\partial p_i} \\ \dot{p}_i = -\frac{\partial \mathcal{H}}{\partial q_i} \end{array} \right., \quad i = 1, 2, \dots, M, \quad \frac{\partial \mathcal{L}}{\partial t} = -\frac{\partial \mathcal{H}}{\partial t}$$

- Hamiltonian approach gives $(2M + 1)$ first-order differential equations instead of the M second-order differential equations in the Lagrangian approach
- Solution of Hamiltonian equations of motion is represented by a curve parameterized by t in the $2M$ -dimensional space known as **cotangent bundle** $\mathbf{T}^*\mathbb{Q}$

$$(q_1(t), q_2(t), \dots, q_M(t), p_1(t), p_2(t), \dots, p_M(t))$$

EXERCISE 10.3: Derive Hamilton equations of motion.

$$\mathcal{H} \equiv \mathcal{H}(\{q_i(t), p_i(t)\}, t) \quad \Rightarrow \quad d\mathcal{H} = \sum_{i=1}^M \left(\frac{\partial \mathcal{H}}{\partial q_i} dq_i + \frac{\partial \mathcal{H}}{\partial p_i} dp_i \right) + \frac{\partial \mathcal{H}}{\partial t} dt$$

$$\mathcal{H} \equiv \sum_{i=1}^M \dot{q}_i p_i - \mathcal{L}(\{q_i(t), \dot{q}_i(t)\}, t)$$

$$\Rightarrow \quad d\mathcal{H} = \sum_{i=1}^M (\dot{q}_i dp_i + p_i d\dot{q}_i) - \left[\sum_{i=1}^M \left(\frac{\partial \mathcal{L}}{\partial q_i} dq_i + \frac{\partial \mathcal{L}}{\partial \dot{q}_i} d\dot{q}_i \right) + \frac{\partial \mathcal{L}}{\partial t} dt \right]$$

$$= \sum_{i=1}^M (\dot{q}_i dp_i - \dot{p}_i dq_i) - \frac{\partial \mathcal{L}}{\partial t} dt$$

$$\sum_{i=1}^M \left(\frac{\partial \mathcal{H}}{\partial q_i} dq_i + \frac{\partial \mathcal{H}}{\partial p_i} dp_i \right) + \frac{\partial \mathcal{H}}{\partial t} dt = \sum_{i=1}^M (\dot{q}_i dp_i - \dot{p}_i dq_i) - \frac{\partial \mathcal{L}}{\partial t} dt$$

$$\Rightarrow \quad \dot{q}_i = \frac{\partial \mathcal{H}}{\partial p_i}, \quad \dot{p}_i = -\frac{\partial \mathcal{H}}{\partial q_i}, \quad \frac{\partial \mathcal{L}}{\partial t} = -\frac{\partial \mathcal{H}}{\partial t} \quad \blacksquare$$