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Motion Controller with a Feedback System Algorithm

Step1:
Connect the circuit of the feedback system using servo motors and Arduino.
Step2:
Rotate one servo motor.
Step3:
The potentiometer value inside the motor will change.
Step4:
The value will be passed to the other motors through the analog input pin in the Arduino.
Step5:
The other motors receive the feedback value.
Step6:
The motors mimic the same motion.

"Flowchart for the Algorithm"