

Global Illumination Methods

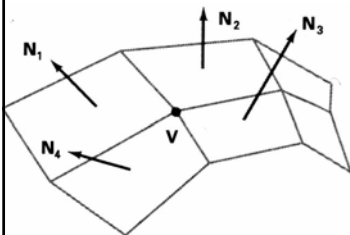
- Recap: Gouraud, Phong
- Ray-tracing
- Radiosity

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Global Illumination Models

Gouraud Shading Overview

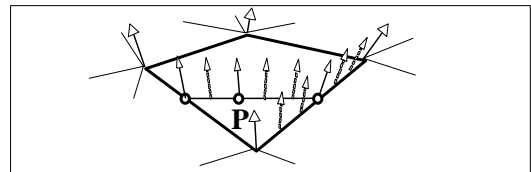
- intensity-interpolation
 - ◆ determine average unit normal vector at each polygon vertex
 - ◆ apply illumination model to each vertex
 - ◆ linearly interpolate vertex intensities



$$N_v = \frac{\sum_{k=1}^n N_k}{\left| \sum_{k=1}^n N_k \right|}$$

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Phong Shading

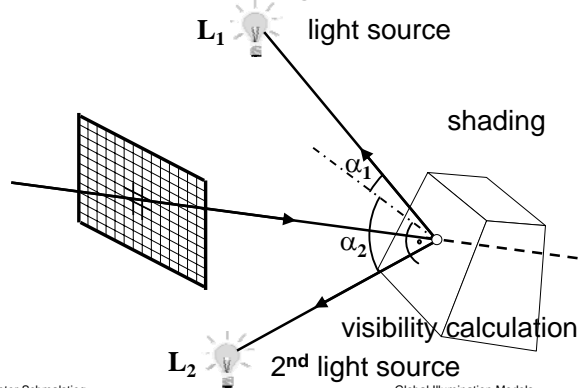


1. normal vectors at corner points
2. interpolate normal vectors along the edges
3. interpolate normal vectors along scanlines & calculate shading (intensities) for every pixel

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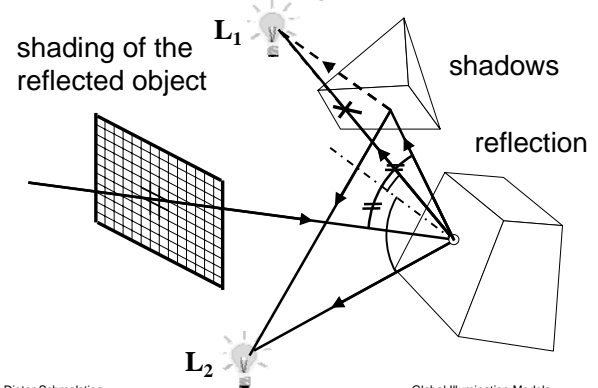
Ray Tracing Concepts



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Global Illumination Models

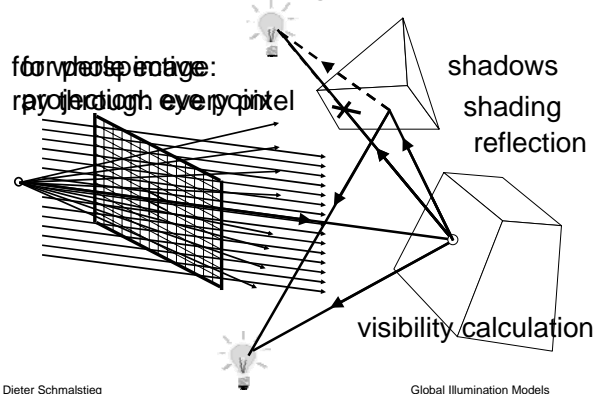
Ray Tracing Concepts



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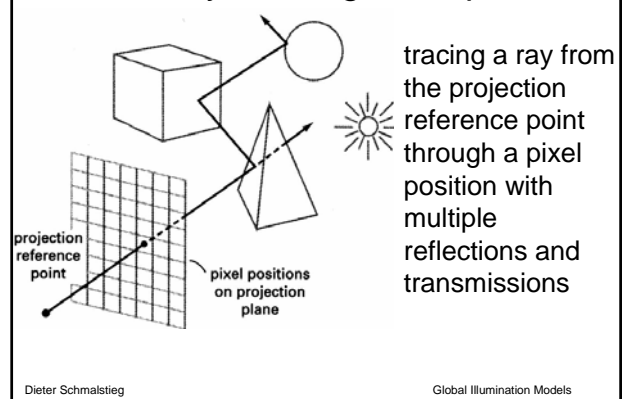
Ray Tracing Concepts



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Ray-Tracing Principle

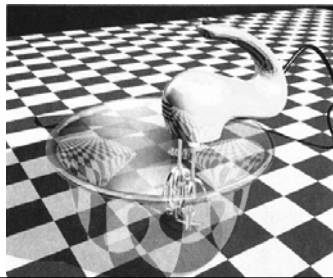


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Ray-Tracing Properties

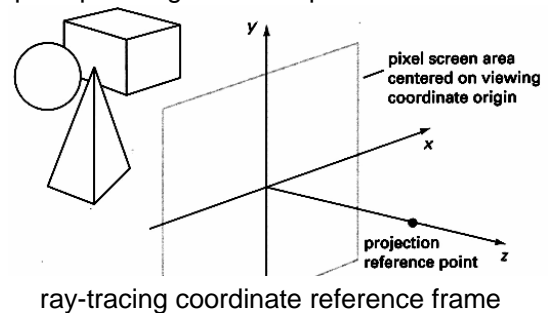
- highly realistic images
- very time consuming
- global reflection, transmission
- visible-surface detection
- shadows
- transparency
- multiple light sources



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Ray-Tracing

- principles of geometric optics



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Global Illumination Models

Shading: Diffuse Shading

$$I_d = xxx$$

I_d ... illumination caused by diffuse shading
 xxx ... any shading model
 (Phong, Blinn, Cook/Torrance,...)

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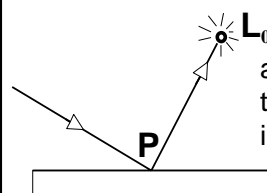
Ray-Tracing: Shadows

ray = intersection point + $s \cdot$ vector to light source

$$\text{ray} = P + s \cdot (L_0 - P)$$

P ... intersection point

L_0 ... light source position



a light source influences the result only if there is no intersection with $0 < s < 1$

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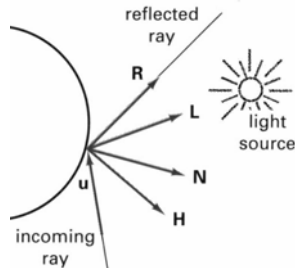
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Ray-Tracing: Shadows and Shading

- shadow ray along L
- ambient light $k_a I_a$
- diffuse reflection $k_d(N \cdot L)$
- specular reflection $k_s(H \cdot N)^{n_s}$

$$I_d = k_d I_a + k_d(N \cdot L) + k_s(H \cdot N)^{n_s}$$

unit vectors at the surface of an object intersected by an incoming ray along direction u

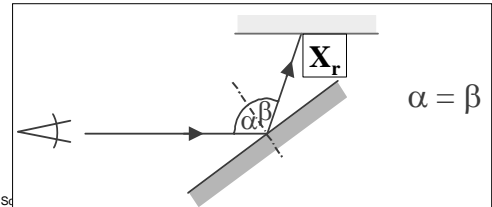


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Ray-Tracing: Reflection

$$I_r = k_r \cdot X_r$$

I_r ... illumination caused by reflexion
 k_r ... reflection coefficient of the material
 X_r ... shading in the reflected direction



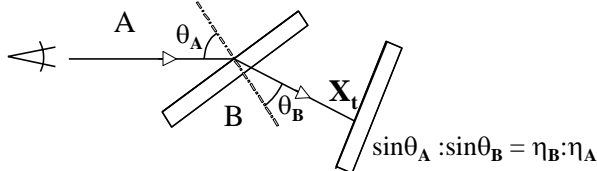
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dels

Ray-Tracing: Transparency

$$I_t = k_t \cdot X_t$$

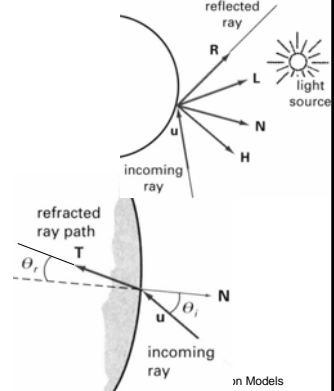
I_t ... illumination caused by transparency
 k_t ... transparency coefficient of the material
 X_t ... shading in the transparency direction



Ray-Tr.: Reflection & Transparency

- reflection ray
 $R = u - (2u \cdot N)N$
- transparency ray
 ♦ Snell's law

$$\sin \theta_r = \frac{\eta_i}{\eta_r} \sin \theta_i$$

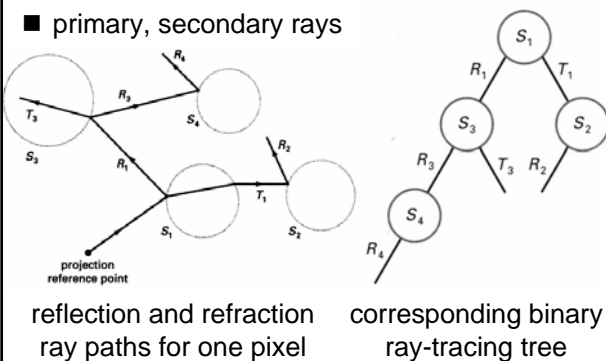


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in Models

Ray-Tracing: Rays & Ray Tree

- primary, secondary rays



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Ray-Tracing: A Complete Shading Method

$$I = I_d + I_r + I_t$$

additional requirement: $k_d + k_r + k_t \leq 1$

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Ray-Tracing: Basic Algorithm

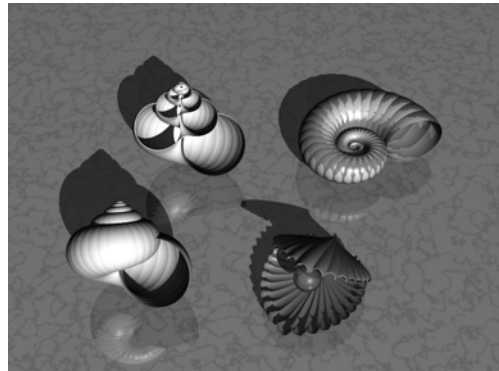
```

FOR all pixels p DO
1.trace primary ray eye -> p
  find closest intersection S
2.FOR all light sources L DO
  trace shadow feeler S -> L
  IF no inters. between S, L
  THEN shading+=influence of L
3.IF surface of S is reflective
  THEN trace secondary ray;
  shading+=influence of refl.
4.IF surface of S is transparent
  THEN trace secondary ray;
  shading+=influence of transp.
    
```

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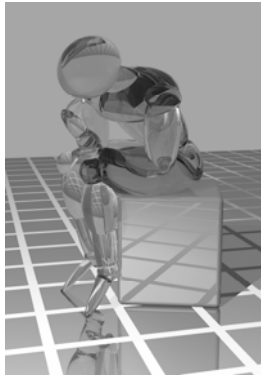
Ray-Tracing Examples



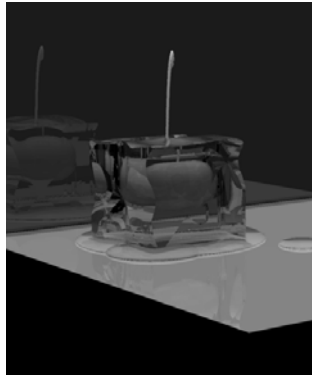
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Ray-Tracing Examples



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Global Illumination Models

True Global Illumination Example



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Global Illumination Models

„Professional“ Raytracing



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Global Illumination Models

Requirements for Object Data (to use them for ray-tracing)

- intersection calculation ray - object possible
- surface normal calculation possible
 - ◆ B-Rep: simple
 - ◆ CSG: recursive evaluation

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Global Illumination Models

Ray-Surface Intersection

- ray equation

$$P = P_0 + s \cdot u$$

- for primary rays

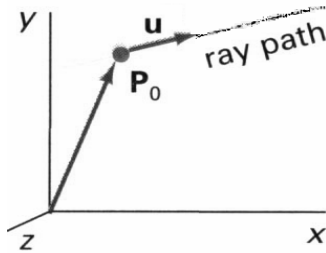
$$u = \frac{P_{pix} - P_{prp}}{|P_{pix} - P_{prp}|}$$

- for secondary rays

$$u = R$$

$$u = T$$

describing a ray with an initial-position vector P_0 and unit direction vector u



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Ray-Sphere Intersection

- parametric ray equation inserted into sphere equation

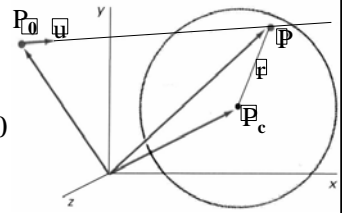
$$|P - P_c|^2 - r^2 = 0$$

$$|(P_0 + su) - P_c|^2 - r^2 = 0$$

$$\Delta P = P_c - P_0$$

$$s^2 - 2(u \cdot \Delta P)s + (|\Delta P|^2 - r^2) = 0 \quad (u^2 = 1)$$

$$s = u \cdot \Delta P \pm \sqrt{(u \cdot \Delta P)^2 - |\Delta P|^2 + r^2}$$



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Ray-Sphere Intersection

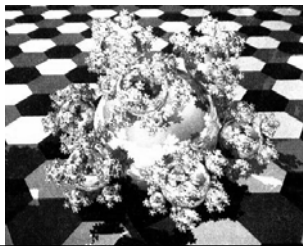
- discriminant negative \Rightarrow no intersections

$$s = u \cdot \Delta P \pm \sqrt{(u \cdot \Delta P)^2 - |\Delta P|^2 + r^2}$$

$$\Rightarrow s = u \cdot \Delta P \pm \sqrt{r^2 - |\Delta P - (u \cdot \Delta P)u|^2} \quad \text{because } u^2=1$$

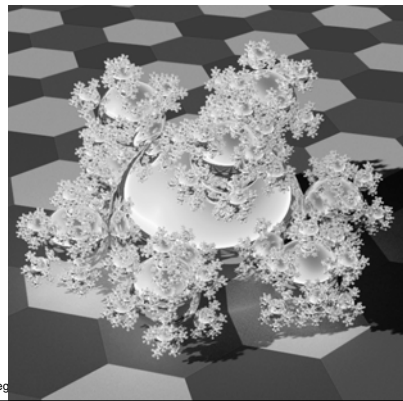
(to avoid roundoff errors when $r^2 \ll |\Delta P|^2$)

"sphereflake":
7381 spheres
3 light sources



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Sphereflake



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Global Illumination Models

Ray-Polyhedron Intersection

- use bounding sphere to eliminate easy cases

- locate front faces $u \cdot N < 0$

- solving plane equation

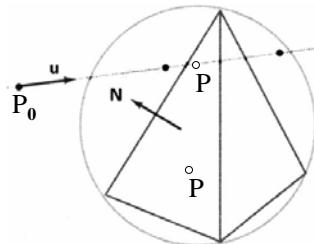
$$Ax + By + Cz + D = 0$$

$$N = (A, B, C)$$

$$N \cdot P = -D$$

$$N \cdot (P_0 + su) = -D$$

$$s = -\frac{D + N \cdot P_0}{N \cdot u}$$



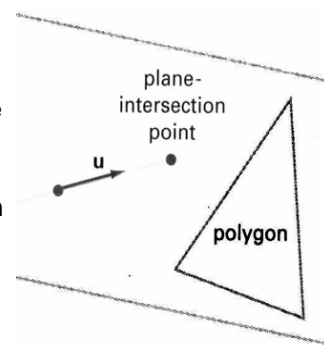
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Ray-Polyhedron Intersection

- intersection point inside polygon boundaries?

- inside-outside test

- smallest s to inside point is first intersection point of polyhedron

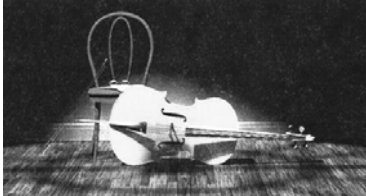


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Ray-Surface Intersection

- quadric, spline surfaces:
 - ◆ parametric ray equation inserted into surface definition
 - ◆ methods like numerical root-finding, incremental calculations

ray-traced scene
with global
reflection of texture

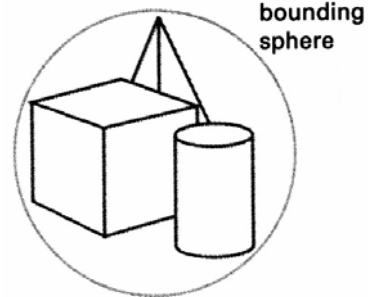


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Global Illumination Models

Reducing Object-Intersection Calc.

- bounding volumes
- bounding volume hierarchies

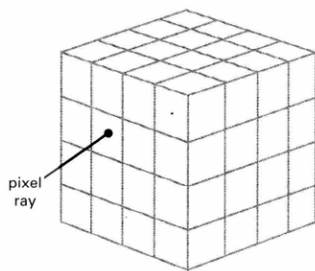


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Reducing Object-Intersection Calc.

- space-subdivision methods
 - ◆ regular grid
 - ◆ octree

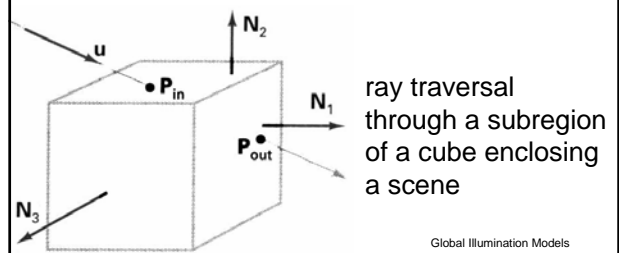


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Reducing Object-Intersection Calc.

- space-subdivision methods
 - ◆ incremental grid traversal
 - 3D Bresenham
 - processing of potential exit faces

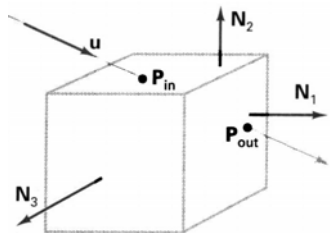


Global Illumination Models

Incremental Grid Traversal

- ray direction u / ray entry position P_{in}
- potential exit faces $u \cdot N_k > 0$
- normal vectors

$$N_k = \begin{cases} (\pm 1, 0, 0) \\ (0, \pm 1, 0) \\ (0, 0, \pm 1) \end{cases}$$



- check signs of components of u

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Incremental Grid Traversal

- calculation of exit positions, select smallest s_k

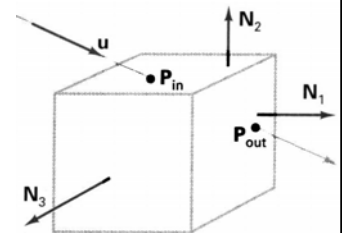
$$P_{out,k} = P_{in} + s_k u$$

$$N_k \cdot P_{out,k} = -D_k$$

$$s_k = \frac{-D_k - N_k \cdot P_{in}}{N_k \cdot u}$$

- example:

$$N_k = (1, 0, 0) \quad s_k = \frac{-x_k - x_0}{u_x}$$

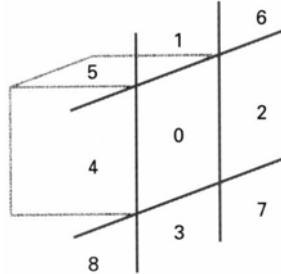


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Incremental Grid Traversal

- variation: trial exit plane
 - ◆ perpendicular to largest component of u
 - ◆ exit point in 0
 - => done
 - ◆ {1, 2, 3, 4}
 - => side clear
 - ◆ {5, 6, 7, 8}
 - => extra calc.

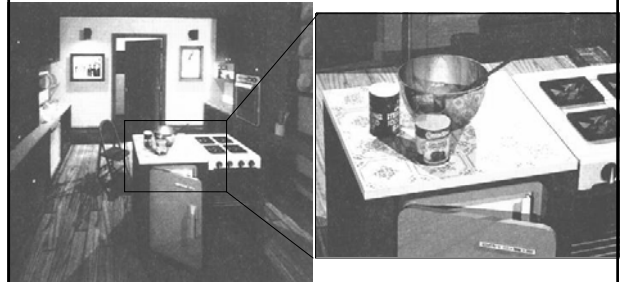


sectors of the
trial exit plane

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Ray-Tracing Examples

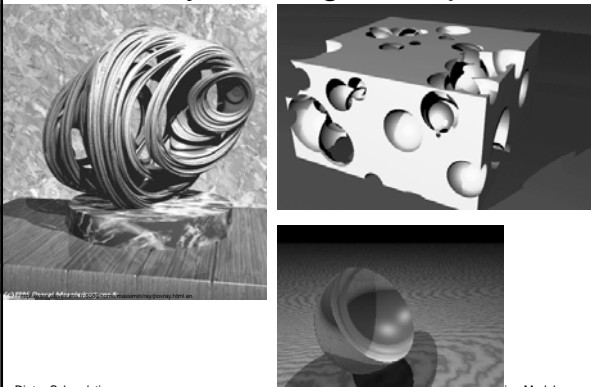


1298 polygons, 4 spheres, 76 cylinders, 35 quadrics
5 light sources

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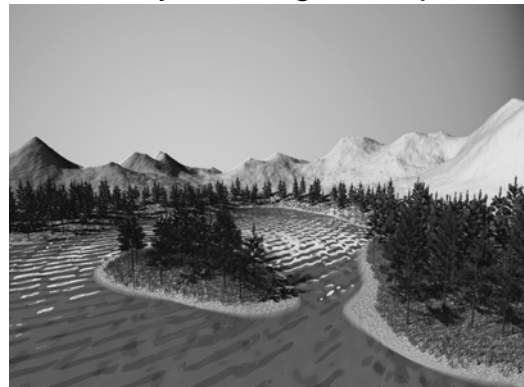
Ray-Tracing Examples



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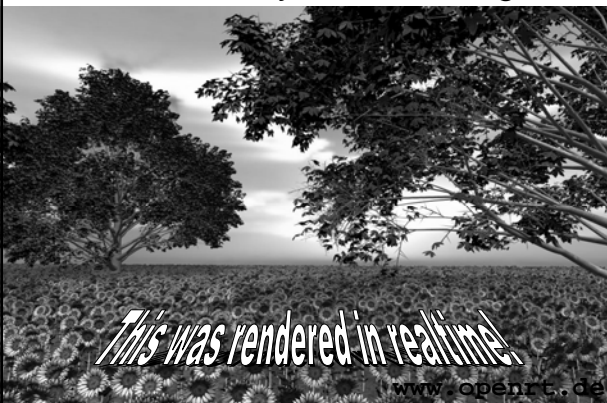
Ray-Tracing Example



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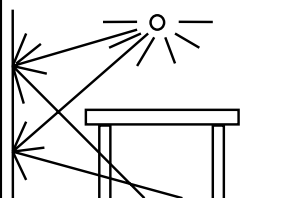
1 Billion Raytraced Triangles



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Radiosity Method

- describes the physical process of light distribution in a diffuse reflecting environment



areas that are not
illuminated directly
are also not
completely dark

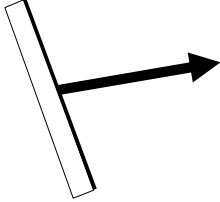
every object acts as a secondary light source

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Radiosity

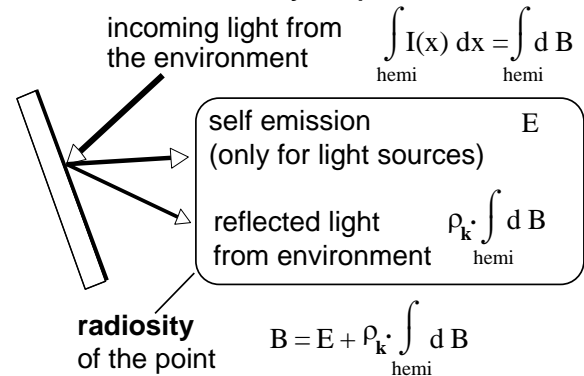
- Radiosity **B** is the „radiant flux per unit area“ that is leaving a surface



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Radiosity Equation



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Radiosity Equation

- to calculate the light influence between surfaces

Radiosity = total light leaving a surface point

$$B = E + \rho_k \cdot \int_{\text{hemi}} d B$$

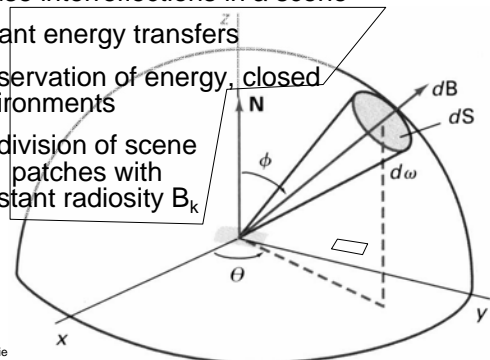
B...radiosity	hemi...half space over point
E...self emission	ρ_k ...reflection coefficient

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Radiosity Properties

- diffuse interreflections in a scene
- radiant energy transfers
- conservation of energy, closed environments
- subdivision of scene into patches with constant radiosity B_k



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Radiosity: Subdivision into Patches

the scene is discretized into **n "patches"** (plane polygons) P_k , for each of these patches a constant radiosity B_k is assumed:

$$B = E + \rho_k \cdot \int_{\text{hemi}} d B \quad \Rightarrow \quad B_k = E_k + \rho_k \cdot \sum_{j=1}^n B_j \cdot F_{jk}$$

ρ_k	diffuse reflection coefficient of patch k
F_{jk}	“formfactor”: describes how much % of the influence on patch k comes from patch j; geometric size

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Radiosity Model

$$B_k = E_k + \rho_k \sum_{j \neq k} B_j F_{jk}$$

- B_k radiosity of patch k
- E_k self-emission of patch k
- $\sum B_j F_{jk}$ contribution of other patches
- F_{jk} form factor, contribution of B_j to B_k
- ρ_k reflectivity factor of patch k

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Radiosity Equation

- solving the radiosity equation

$$B_k = E_k + \rho_k \sum_{j \neq k} B_j F_{jk}$$

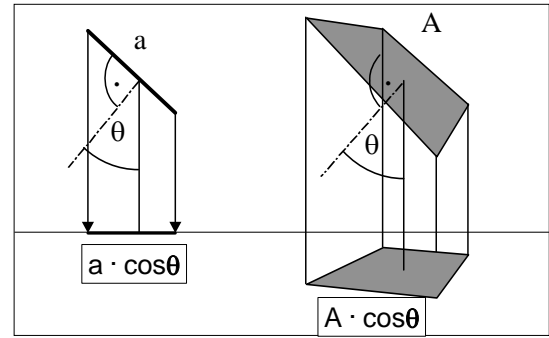
$$B_k - \rho_k \sum_{j \neq k} B_j F_{jk} = E_k$$

$$\begin{bmatrix} 1 & -\rho_1 F_{21} & \dots & -\rho_1 F_{n1} \\ -\rho_2 F_{12} & 1 & \dots & -\rho_2 F_{n2} \\ \vdots & \vdots & \ddots & \vdots \\ -\rho_n F_{1n} & -\rho_n F_{2n} & \dots & 1 \end{bmatrix} \cdot \begin{bmatrix} B_1 \\ B_2 \\ \vdots \\ B_n \end{bmatrix} = \begin{bmatrix} E_1 \\ E_2 \\ \vdots \\ E_n \end{bmatrix}$$

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Global Illumination Models

Projection of a Polygon

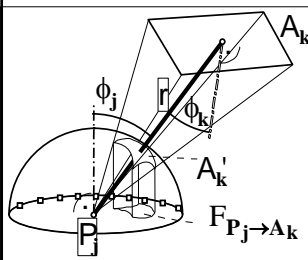


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Radiosity: Form Factors

- form factor F_{jk} : contribution of patch j to patch k



$$F_{dA_j, dA_k} = \frac{\cos \phi_j \cos \phi_k dA_k}{\pi r^2}$$

$$\sum F_{jk} = 1$$

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Radiosity: Form Factors

- form factor F_{jk} : contribution of patch j to patch k

$$F_{dA_j, dA_k} = \frac{\cos \phi_j \cos \phi_k dA_k}{\pi r^2}$$

emitted energy
from dA_j on A_k

$$F_{dA_j, A_k} = \int_{A_k} \frac{\cos \phi_j \cos \phi_k}{\pi r^2} dA_k$$

form factor is
average over
area A_j

$$F_{jk} = \frac{1}{A_j} \int_{A_j} \int_{A_k} \frac{\cos \phi_j \cos \phi_k}{\pi r^2} dA_k dA_j$$

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Radiosity: Form Factors

- form factor properties

- ◆ conservation of energy

$$\sum_{k=1}^n F_{jk} = 1$$

- ◆ uniform light reflection

$$A_j F_{jk} = A_k F_{kj}$$

- ◆ no self-incidence

$$F_{jj} = 0$$

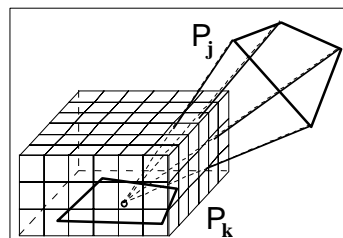
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Radiosity: Form Factors

- form factor calculation

- ◆ most expensive step in radiosity calculation
- ◆ numerical integration (Monte Carlo methods)
- ◆ hemicube approach (hemisphere replaced by hemicube)



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Global Illumination Models

Radiosity Equation

■ solving the radiosity equation

- ◆ Gaussian elimination
- ◆ Gauss-Seidel iteration

$$\begin{bmatrix} 1 & -\rho_1 F_{21} & \dots & -\rho_1 F_{n1} \\ -\rho_2 F_{12} & 1 & \dots & -\rho_2 F_{n2} \\ \vdots & \vdots & \ddots & \vdots \\ -\rho_n F_{1n} & -\rho_n F_{2n} & \dots & 1 \end{bmatrix} \cdot \begin{bmatrix} B_1 \\ B_2 \\ \vdots \\ B_n \end{bmatrix} = \begin{bmatrix} E_1 \\ E_2 \\ \vdots \\ E_n \end{bmatrix}$$

■ very time and storage intensive

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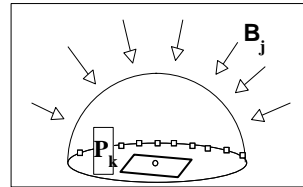
Global Illumination Models

Radiosity Equation

■ solving the radiosity equation

- ◆ Gauss-Seidel iteration

$$B_k^{i+1} = E_k + \rho_k \sum_{j \neq k} B_j^i F_{jk}$$



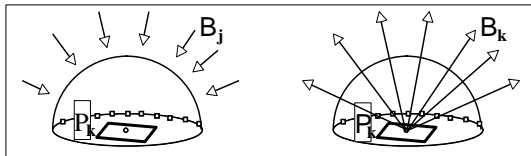
“gathering”

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Global Illumination Models

Radiosity Equation

■ “gathering” vs. “shooting” $B_k^{i+1} = E_k + \rho_k \sum_{j \neq k} B_j^i F_{jk}$



$$\begin{pmatrix} x \\ x \\ x \\ x \\ x \\ x \\ x \end{pmatrix} = \begin{pmatrix} x \\ x \\ x \\ x \\ x \\ x \\ x \end{pmatrix} + \begin{pmatrix} x & x & x & x & x & x & x \\ x & x & x & x & x & x & x \\ x & x & x & x & x & x & x \\ x & x & x & x & x & x & x \\ x & x & x & x & x & x & x \\ x & x & x & x & x & x & x \\ x & x & x & x & x & x & x \end{pmatrix} \cdot \begin{pmatrix} x \\ x \\ x \\ x \\ x \\ x \\ x \end{pmatrix}$$

$$\begin{pmatrix} x \\ x \\ x \\ x \\ x \\ x \\ x \end{pmatrix} = \begin{pmatrix} x \\ x \\ x \\ x \\ x \\ x \\ x \end{pmatrix} + \begin{pmatrix} x & x & x & x & x & x & x \\ x & x & x & x & x & x & x \\ x & x & x & x & x & x & x \\ x & x & x & x & x & x & x \\ x & x & x & x & x & x & x \\ x & x & x & x & x & x & x \\ x & x & x & x & x & x & x \end{pmatrix} \cdot \begin{pmatrix} x \\ x \\ x \\ x \\ x \\ x \\ x \end{pmatrix}$$

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Global Illumination Models

Progressive Refinement Radiosity (1)

■ “shooting”

- ◆ select brightest patch k and distribute its radiosity B_k

$$B_k = E_k + \rho_k \sum_{j \neq k} B_j F_{jk} \Rightarrow \begin{matrix} B_k \text{ due to } B_j = \rho_k B_j F_{jk} \\ B_j \text{ due to } B_k = \rho_j B_k F_{kj} \end{matrix}$$

⇓

$$B_j \text{ due to } B_k = \rho_j B_k F_{jk} \frac{A_j}{A_k} \leftarrow A_k F_{kj} = A_j F_{jk}$$

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Progressive Refinement Radiosity (2)

[one refinement step]

```

for selected patch k
/* set up hemicube,
   calculate form factors  $F_{jk}$  */

for each patch j {
     $\Delta rad := \rho_j * B_k * F_{jk} * A_j / A_k$ 
     $\Delta B_j := \Delta B_j + \Delta rad$ 
     $B_j := B_j + \Delta rad$ 
}
 $\Delta B_k := 0$ 
    
```

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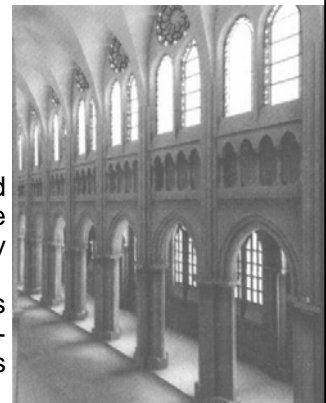
Progressive Refinement Radiosity (3)

- initially $\Delta B_k = B_k = E_k$,

- select patch with highest $\Delta B_k A_k$

cathedral rendered
with progressive
refinement radiosity

form factors
computed with ray-
tracing methods



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Radiosity Example Images (1)



image of a
constructivist
museum
rendered with
progressive
refinement
radiosity

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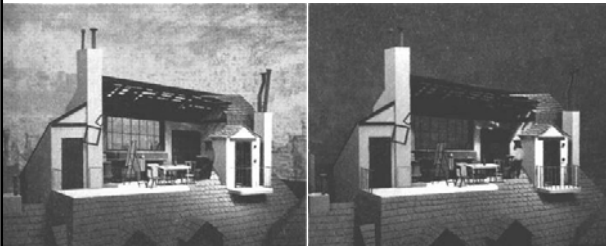
Radiosity Example Images (2)



stair tower of a
building at Cornell
University rendered
with progressive
refinement radiosity

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Radiosity Example Images (3)



2 lighting schemes for an opera production:
(left) day view (right) night view

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