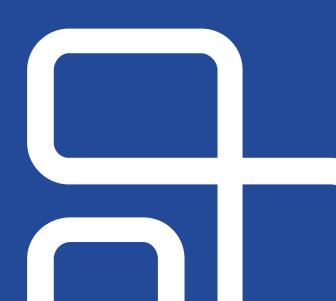
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Ray: 大模型时代的 Al Infra

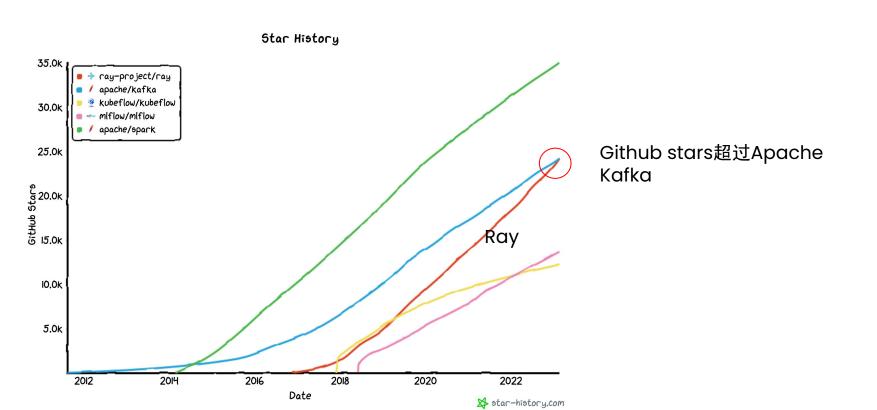
张喆, Anyscale Ray团队负责人

zhz@anyscale.com zhethoughts

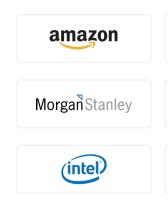
07.02.2023



Ray: Fastest Growing Distributed Compute Framework



Ray: Fastest Growing Distributed Compute Framework













































25,000+ GitHub stars **820+**Community
Contributors

5,000+Repositories
Depend on Ray

1,000+
Organizations
Using Ray

ChatGPT / GPT-4 Trained on Ray!



Fast iterations at Hyper-scale!

"We looked at a half-dozen distributed computing projects, and **Ray** was by far the winner. ... We are using **Ray** to train our largest models. It's been very helpful to us to be able to scale up to unprecedented scale. ... Ray owns a whole layer, and not in an opaque way."



This Talk

Adoption Highlights

Ray Intro

Use Case Details

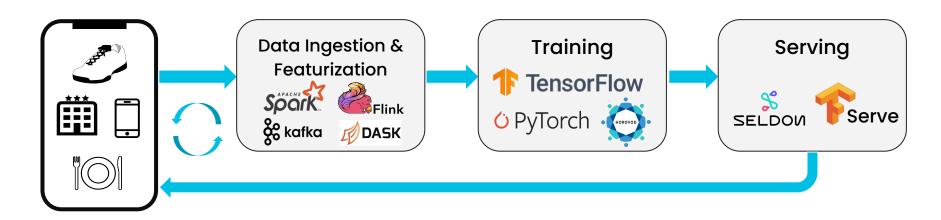
Getting Hands Dirty

Ray: a short history



- **2016**: Started as a class project
 - . Goal: scale real time ML and RL
- 2017: RLlib and Ray Tune released
- **2019**: Anyscale founded (company behind Ray)
- 2020: Ray v1.0 release; Ray Serve released
- 2022: Ray v2.0 release; Ray Al Runtime
- 2023: LLM / Generative Al

Example Use Case: Online learning



Solution: stitch together a bunch of distributed systems

Challenge with stitching distributed systems

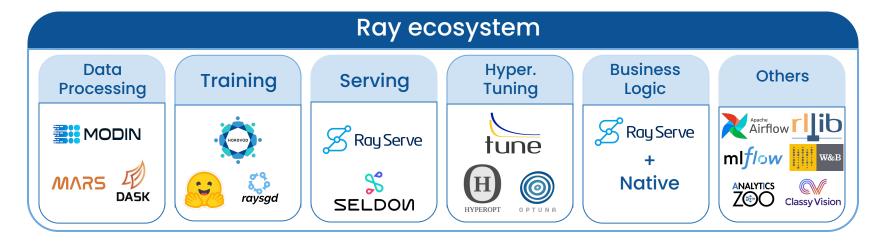


Hard to develop: different APIs

Hard to deploy & manage

Slow: high overhead of moving data between different systems

Ray Unifies Distributed Workloads



Best ecosystem of distributed libraries Instead of stitching systems, call libraries in **same** system **Easy** to develop, manage, and deploy



History and Intro

1. Why was Ray created

2. API and architecture basics

Minimalist API

Initialize Ray context.

rav.init()

.remote

ray.put()

ray.get()



@ray.remote	Function or class decorator specifying that the function will be executed as a task or
	the class as an actor in a different process.

Postfix to every remote function, remote class declaration, or invocation of a remote class method. Remote operations are asynchronous.

Store object in object store, and return its ID. This ID can be used to pass object as an argument to any remote function or method call. This is a *synchronous* operation.

Return an object or list of objects from the object ID or list of object IDs. This is a synchronous (i.e., blocking) operation.

Ray in a nutshell

Functions → Tasks : stateless computations (essentially RPC)

Classes → Actors : stateful computations

Distributed futures : enables parallelism

In-memory object store: enables passing args/results by reference

Extension of existing languages, rather than a new language

Function

```
def read array(file):
  # read ndarray "a"
  # from "file"
  return a
def add(a, b):
  return np.add(a, b)
a = read array(file1)
b = read_array(file2)
sum = add(a, b)
```

Class

```
class Counter(object):
  def init (self):
     self.value = 0
  def inc(self):
     self.value += 1
     return self.value
c = Counter()
c.inc()
c.inc()
```



Function → **Task**

```
@ray.remote
def read_array(file):
  # read ndarray "a"
  # from "file"
  return a
@ray.remote
def add(a, b):
  return np.add(a, b)
a = read array(file1)
b = read_array(file2)
sum = add(a, b)
```

Class → **Actor**

```
@ray.remote
class Counter(object):
  def init (self):
     self.value = 0
  def inc(self):
     self.value += 1
     return self.value
c = Counter()
c.inc()
c.inc()
```

Function → **Task**

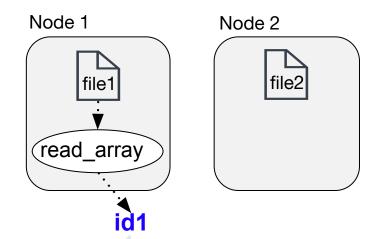
```
@ray.remote
def read array(file):
  # read ndarray "a"
  # from "file"
  return a
@ray.remote
def add(a, b):
  return np.add(a, b)
id1 = read_array.remote(file1)
id2 = read_array.remote(file2)
id = add.remote(id1, id2)
sum = ray.get(id)
```

Object → **Actor**

```
@ray.remote
class Counter(object):
  def init (self):
     self.value = 0
  def inc(self):
     self.value += 1
     return self.value
c = Counter.remote()
id4 = c.inc.remote()
id5 = c.inc.remote()
```

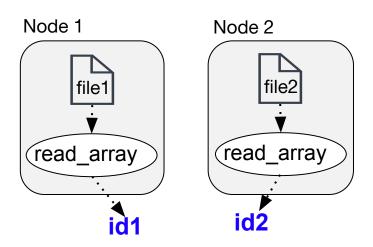
```
@ray.remote
def read_array(file):
  # read ndarray "a"
  # from "file"
  return a
@ray.remote
def add(a, b):
  return np.add(a, b)
id1 = read array.remote(file1)
id2 = read_array.remote(file2)
id = add.remote(id1, id2)
sum = ray.get(id)
```

id1: distributed future (object id)



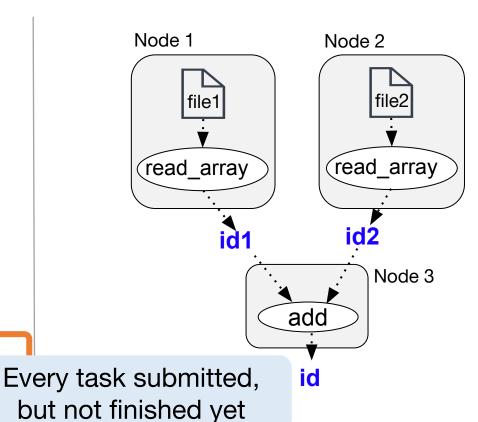
Return future id1; before read_array() finishes

```
@ray.remote
def read_array(file):
  # read ndarray "a"
  # from "file"
  return a
@ray.remote
def add(a, b):
  return np.add(a, b)
id1 = read array.remote(file1)
id2 = read array.remote(file2)
id = add.remote(id1, id2)
sum = ray.get(id)
```

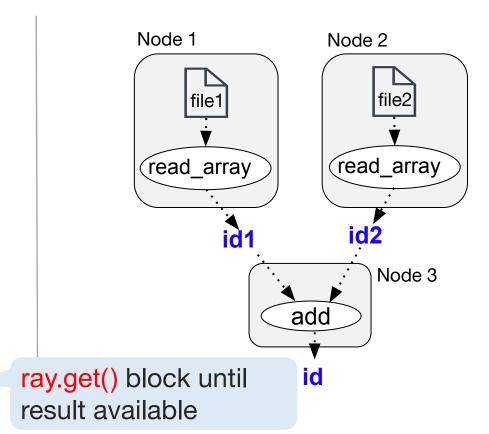


Dynamic task graph: build at runtime

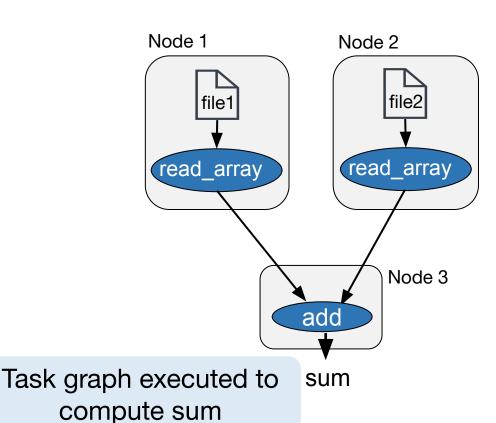
```
@ray.remote
def read_array(file):
  # read ndarray "a"
  # from "file"
  return a
@ray.remote
def add(a, b):
  return np.add(a, b)
id1 = read_array.remote(file1)
id2 = read array.remote(file2)
id = add.remote(id1, id2)
sum = ray.get(id)
```



```
@ray.remote
def read_array(file):
  # read ndarray "a"
  # from "file"
  return a
@ray.remote
def add(a, b):
  return np.add(a, b)
id1 = read_array.remote(file1)
id2 = read_array.remote(file2)
id = add.remote(id1, id2)
sum = ray.get(id)
```



```
@ray.remote
def read_array(file):
  # read ndarray "a"
  # from "file"
  return a
@ray.remote
def add(a, b):
  return np.add(a, b)
id1 = read_array.remote(file1)
id2 = read_array.remote(file2)
id = add.remote(id1, id2)
sum = ray.get(id)
```



Function → **Task**

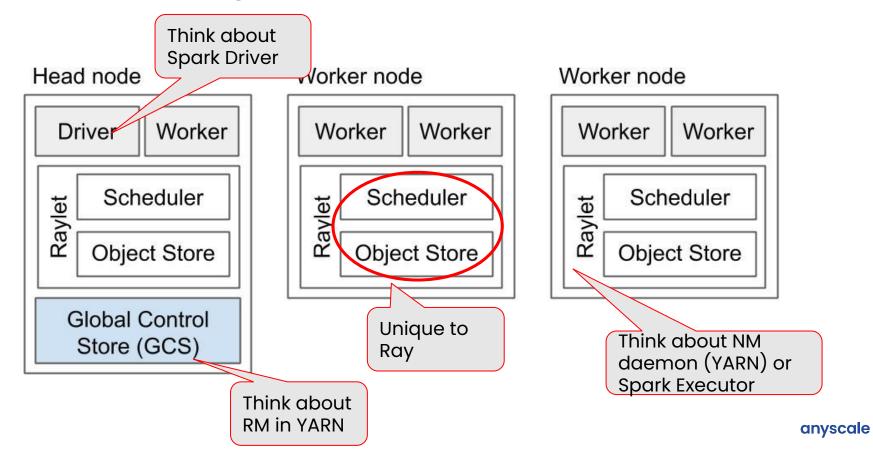
```
@ray.remote
def read array(file):
  # read ndarray "a"
  # from "file"
  return a
@ray.remote
def add(a, b):
  return np.add(a, b)
id1 = read_array.remote(file1)
id2 = read_array.remote(file2)
id = add.remote(id1, id2)
sum = ray.get(id)
```

Class → **Actor**

```
@ray.remote(num_cpus=2, num_gpus=1)
class Counter (iect):
   can specify
   resource demands;
   support heterogeneous hardware
     self.value += 1
     return self.value
c = Counter.remote()
id1 = c.inc.remote()
id2 = c.inc.remote()
val = ray.qet(id2)
```



What is Ray? A Cluster Looks Like...





This Talk

Adoption Highlights

Ray Intro

Use Case Details

Getting Hands Dirty

Trend: Ray as the "New Al Infra"

ML Platform

- Easy access to GPU
- Prototype -> production

Deep Learning

- High performance data ingest
- CPU / GPU heterogeneous cluster

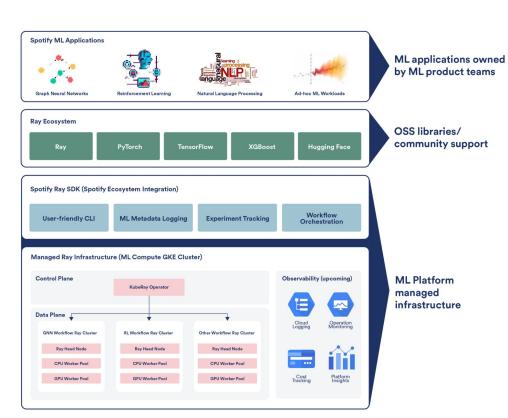
Batch Inference

- Efficiently "cache" the model
- High performance data pipeline

LLM / Generative AI

- Flexible model parallelism
- Utilizing smaller / cheaper GPUs

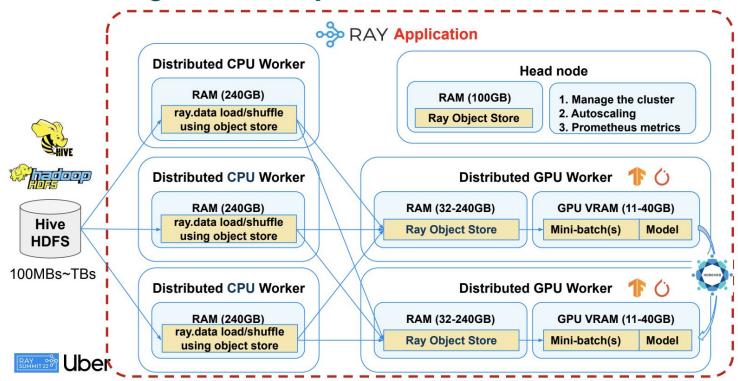
Unleashing ML Innovation at Spotify



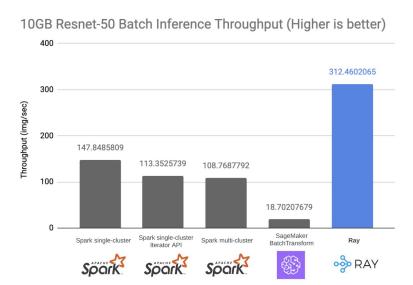
- Broadening production support for ML frameworks beyond TensorFlow to support nove ML solutions for Spotify
- Providing a more user-friendly way for users to access GPU and distributed compute
- Accelerating the user journey for ML research an prototyping
- Providing solutions to productionize more advanced ML paradigms, such as reinforcement learning (RL) and graph neural networks (GNN) workflows

Deep Learning Cluster at Uber

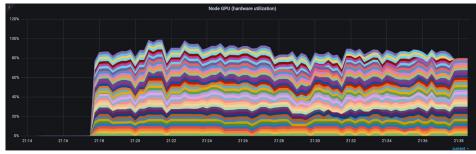
Heterogeneous Ray Cluster (v2): Architecture



Batch Inference







Batch Inference

```
import ray
  from ray.data import ActorPoolStrategy
  Model = \dots
  preprocess_fn = ...
   class MyModelCallableCls:
      def __init__(self):
           self.model = Model(...)
      def __call__(self, batch: Dict[str, np.ndarray]) ->
           return {"results": self.model(batch)}
16 ray.data.read_parquet(...) \
       .map_batches(preprocess_fn) \
       .map_batches(
            MyModelCallableCls,
            num_gpus=1,
             compute=ActorPoolStrategy(size=N)) \
       .write_parquet(...)
```

Ray provides generic platform for LLMs

01	Simplify orchestration and scaling	 Spot instance support for data parallel training Easily spin up and run distributed workloads on any cloud Can run on a lot of cheap preemptible GPUs
02	Inference and serving	 Ability to support complex pipelines integrating business logic Ability to support multiple node serving
03	Training	 Integrates distributed training with distributed hyperparameter tuning Very fast interactive development model Minimal code changes to enable training



High Performance Inference

T_{i}	Tz	T3	Ty	Ts	T6	To	Tg
Sil	Si	S.	Silve				
Sa	Sz	SX					
Sz	S	Si	S				
Sy	Sy	Sy	Sy	Sy			

T,	Tz	T3	Ty	Ts	T6	To	Tg
Si	Si	Si	SNI	8,	end	56	56
Sa	Sz	SX	Sx	Sall	81	SAL	END
Si	Si	S	S	END	Ss	Sg	\$5/A
Sy	Sy	Sy	Sy	Sy	SX	END	S7

Completing seven sequences using continuous batching. Left shows the batch after a single iteration, right shows the batch after several iterations. Once a sequence emits an end-of-sequence token, we insert a new sequence in its place (i.e. sequences S5, S6, and S7). This achieves higher GPU utilization since the GPU does not wait for all sequences to complete before starting a new one.



This Talk

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Getting 🖐 🖐 Dirty! – Simple Stuff

Linux grep on TBs of data?

```
import ray
import sys
import re
regex_pattern = sys.argv[2]
pattern = re.compile(regex_pattern)
ds = ray.data.read_text(sys.argv[1])
result = ds.map_batches(lambda batch: [v if pattern.search(v) else
None for v in batch])
for r in result.iter_rows():
    if r != None:
        print(r)
```

Getting 🖐 🖐 Dirty!

Back to interview time!

QuickSort (but on 100s of nodes)? CloudSort Benchmark

Cost to sort 100 TeraBytes of data

2016 Record

\$1.44 per TB

on Alibaba Cloud

2022 Record

\$0.97 per TB



```
def quick_sort(collection):
    length = len(collection)
   if length <= 1:
        return collection
    else:
        pivot = collection.pop()
        greater, lesser = \Pi, \Pi
        for element in collection:
            if element > pivot:
                greater.append(element)
            else:
                lesser.append(element)
        return quick_sort(lesser) + [pivot] + quick_sort(greater)
@ray.remote
def quick_sort_distributed(collection):
    length = len(collection)
                            llection)
                            op()
                             ction:
                             nd(element)
                             (element)
                              istributed.remote(lesser)
                              distributed.remote(greater)
                               + [pivot] + ray.get(greater)
```

unsorted = random.randint(1000000, size=(4000000)).tolist() ray.get(quick_sort_distributed.remote(unsorted))

GPT-J-6B Fine-Tuning with Ray AIR and DeepSpeed

In this example, we will showcase how to use the Ray AIR for **GPT-J fine-tuning**. GPT-J is a GPT-2-like causal language model trained on the Pile dataset. This particular model has 6 billion parameters. For more information on GPT-J, click here.

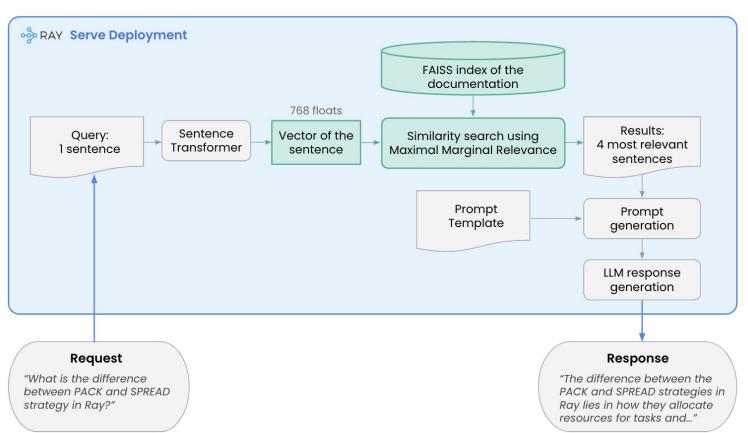
```
from ray.train.huggingface import HuggingFaceTrainer
from ray air config import ScalingConfig
from ray.data.preprocessors import Chain
trainer = HuggingFaceTrainer(
    trainer_init_per_worker=trainer_init_per_worker,
    trainer_init_config={
        "batch size": 16, # per device
       "epochs": 1,
    scaling_config=ScalingConfig(
        num_workers=num_workers,
        use_gpu=use_gpu,
        resources_per_worker={"GPU": 1, "CPU": cpus_per_worker},
    datasets={"train": ray_datasets["train"], "evaluation":
ray_datasets["validation"]},
   preprocessor=Chain(splitter, tokenizer),
```

Finally, we call the **fit()** method to start training with Ray AIR. We will save the **Result** object to a variable so we can access metrics and checkpoints.

```
results = trainer.fit()
```

Answer Questions with





Roadmap

- Performance
 - First, define clear benchmarks (need your input!)
 - o Optimizations: GPU, scheduling, etc.
- Usability / Quality
 - Push Ray Al Runtime to GA
 - Simpler APIs, easier onboarding
- Better support for LLM
 - Integrations with new models (e.g. Falcon)
 - Integrations with new optimizations (e.g. vLLM)

Summary

Ray is positioned to be the **New Al Infra** in the large model / generative Al era. Let's collaborate and make it happen!

Call to action

- Get started at <u>docs.ray.io</u>
- Dive deeper on https://github.com/ray-project/ray/
- Ray Summit 2023 is coming up!