## Math 250, Linear Algebra: Homework 5 Fall 2024

"The purpose of computing is insight, not numbers." – Richard Hamming

## Name:

Read the directions *very carefully* and then solve the problem, providing thorough details and steps. If you are not sure about what a particular symbol or word means, please ask me!

- 1. 2.1.1.
- 2. 2.1.9.
- 3. 2.1.25 (2.1.17 in 5E).
- 4. 2.2.9 (2.2.7 in 5E).
- 5. 2.2.11, 13, 15, 17, 19 (2.2.9 in 5E).
- 6. 2.2.23 (2.2.13 in 5E).
- 7. 2.2.31 (2.2.21 in 5E).
- 8. 2.3.11, 13, 15, 17, 19 (2.3.11 in 5E).
- 9. 3.1.5.
- 10. 3.1.13.
- 11. 3.1.20 (3.1.21 in 5E, somehow).

2.1.1 
$$-2\begin{bmatrix}20 & -1\\4 & -32\end{bmatrix} = \begin{bmatrix}-4 & 0 & 2\\-8 & 6 & -4\end{bmatrix} = -2A$$

B-2A=  $\begin{bmatrix}7 & -5 & 1\\1 & -4 & -3\end{bmatrix} - \begin{bmatrix}-4 & 0 & 2\\-8 & 6 & -4\end{bmatrix} = \begin{bmatrix}11 & -5 & -1\\9 & -10 & 1\end{bmatrix}$ 

AC not possible because A has 3 columns while C has 2 rows, Number of columns in A must match the number of rows in C

$$CO = \begin{bmatrix} -2 & 1 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} 3 & 5 \\ -1 & 4 \end{bmatrix} = \begin{bmatrix} 1 & 13 \\ -7 & -6 \end{bmatrix}$$

2.1.9 
$$AB = \begin{bmatrix} 23 & -10+5K \\ -9 & 15+12 \end{bmatrix}$$
  $BA = \begin{bmatrix} 23 & 15 \\ 6-3K & 15+K \end{bmatrix} \begin{bmatrix} -10+5K=15 & K=5 \\ -9=6-5K & -15=-12 & K=5 \end{bmatrix}$   $AB = BA$  when  $K=5$ 

$$\begin{bmatrix} 1 & -2 \\ -2 & 5 \end{bmatrix} \cdot \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} -1 \\ 6 \end{bmatrix} \qquad \begin{bmatrix} 1 & -2 \\ -2 & 5 \end{bmatrix} \cdot \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} -2 \\ -2 & 5 \end{bmatrix} \cdot \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} -2 \\ -2 & 5 \end{bmatrix} \cdot \begin{bmatrix} -2 \\ y \end{bmatrix} = \begin{bmatrix} -2 \\ -2 & 5 \end{bmatrix} \cdot \begin{bmatrix} -2 \\ y \end{bmatrix} = \begin{bmatrix} -2 \\ -2 & 5 \end{bmatrix} \cdot \begin{bmatrix} -2 \\ y \end{bmatrix} = \begin{bmatrix} -2 \\ -2 & 5 \end{bmatrix} \cdot \begin{bmatrix} -2 \\ y \end{bmatrix} = \begin{bmatrix} -2 \\ -2 & 5 \end{bmatrix} \cdot \begin{bmatrix} -2 \\ y \end{bmatrix} = \begin{bmatrix} -2 \\ -2 & 5 \end{bmatrix} = \begin{bmatrix} -2 \\ -2 & 5$$

2.2.9 
$$A = \begin{bmatrix} 1 & 7 \\ 5 & 12 \end{bmatrix} \xrightarrow{\delta \to 0} \begin{bmatrix} 12 & -2 \\ -5 & 1 \end{bmatrix} \xrightarrow{1} \det = 2 A^{-1} = \begin{bmatrix} 6 & 1 \\ \frac{1}{2} & \frac{1}{2} \end{bmatrix} \begin{bmatrix} \frac{3}{5} \end{bmatrix}$$

$$Q. \quad A^{-1} \times b_{1} = \begin{bmatrix} -9 \\ 4 \end{bmatrix} \qquad A^{-1} \times b_{2} = \begin{bmatrix} 11 \\ -5 \end{bmatrix} \qquad A^{-1} \times b_{3} = \begin{bmatrix} 6 \\ -2 \end{bmatrix} \qquad A^{-1} \times b_{4} = \begin{bmatrix} 13 \\ -5 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 2 & -9 & 11 & 6 & 13 \\ 5 & 12 & 4 & -5 & -2 & -5 \end{bmatrix} R_{2} - 5A_{1} \begin{bmatrix} 1 & 2 & -9 & 11 & 6 & 15 \\ 0 & 2 & 4 & -5 & -2 & -5 \end{bmatrix} R_{2} \begin{bmatrix} 1 & 2 & -9 & 11 & 6 & 15 \\ 0 & 1 & 4 & -5 & -2 & -5 \end{bmatrix} R_{2} \begin{bmatrix} 1 & 2 & -9 & 11 & 6 & 15 \\ 0 & 1 & 4 & -5 & -2 & -5 \end{bmatrix} R_{2} - 5A_{1} \begin{bmatrix} 1 & 2 & -9 & 11 & 6 & 15 \\ 0 & 2 & 4 & -5 & -2 & -5 \end{bmatrix} R_{2} \begin{bmatrix} 1 & 2 & -9 & 11 & 6 & 15 \\ 0 & 1 & 4 & -5 & -2 & -5 \end{bmatrix} R_{2} - 5A_{1} \begin{bmatrix} 1 & 2 & -9 & 11 & 6 & 15 \\ 0 & 2 & 4 & -5 & -2 & -5 \end{bmatrix} R_{2} - 5A_{1} \begin{bmatrix} 1 & 2 & -9 & 11 & 6 & 15 \\ 0 & 2 & 4 & -5 & -2 & -5 \end{bmatrix} R_{2} - 5A_{1} \begin{bmatrix} 1 & 2 & -9 & 11 & 6 & 15 \\ 0 & 2 & 4 & -5 & -2 & -5 \end{bmatrix} R_{2} - 5A_{1} \begin{bmatrix} 1 & 2 & -9 & 11 & 6 & 15 \\ 0 & 2 & 4 & -5 & -2 & -5 \end{bmatrix} R_{2} - 5A_{1} \begin{bmatrix} 1 & 2 & -9 & 11 & 6 & 15 \\ 0 & 2 & 4 & -5 & -2 & -5 \end{bmatrix} R_{2} - 5A_{1} \begin{bmatrix} 1 & 2 & -9 & 11 & 6 & 15 \\ 0 & 2 & 4 & -5 & -2 & -5 \end{bmatrix} R_{2} - 5A_{1} \begin{bmatrix} 1 & 2 & -9 & 11 & 6 & 15 \\ 0 & 2 & 4 & -5 & -2 & -5 \end{bmatrix} R_{2} - 5A_{1} \begin{bmatrix} 1 & 2 & -9 & 11 & 6 & 15 \\ 0 & 2 & 4 & -5 & -2 & -5 \end{bmatrix} R_{2} - 5A_{1} \begin{bmatrix} 1 & 2 & -9 & 11 & 6 & 15 \\ 0 & 2 & 4 & -5 & -2 & -5 \end{bmatrix} R_{2} - 5A_{1} \begin{bmatrix} 1 & 2 & -9 & 11 & 6 & 15 \\ 0 & 2 & 4 & -5 & -2 & -5 \end{bmatrix} R_{2} - 5A_{1} \begin{bmatrix} 1 & 2 & -9 & 11 & 6 & 15 \\ 0 & 2 & 4 & -5 & -2 & -5 \end{bmatrix} R_{2} - 5A_{1} \begin{bmatrix} 1 & 2 & -9 & 11 & 6 & 15 \\ 0 & 2 & 4 & -5 & -2 & -5 \end{bmatrix} R_{2} - 5A_{1} \begin{bmatrix} 1 & 2 & -9 & 11 & 6 & 15 \\ 0 & 2 & 4 & -5 & -2 & -5 \end{bmatrix} R_{2} - 5A_{1} \begin{bmatrix} 1 & 2 & -9 & 11 & 6 & 15 \\ 0 & 2 & 4 & -5 & -2 & -5 \end{bmatrix} R_{2} - 5A_{1} \begin{bmatrix} 1 & 2 & -9 & 11 & 6 & 15 \\ 0 & 2 & 4 & -5 & -2 & -5 \end{bmatrix} R_{2} - 5A_{1} \begin{bmatrix} 1 & 2 & -9 & 11 & 6 & 15 \\ 0 & 2 & 4 & -5 & -2 & -5 \end{bmatrix} R_{2} - 5A_{1} \begin{bmatrix} 1 & 2 & -9 & 11 & 6 & 15 \\ 0 & 2 & 4 & -5 & -2 & -5 \end{bmatrix} R_{2} - 5A_{1} \begin{bmatrix} 1 & 2 & -9 & 11 & 6 & 15 \\ 0 & 2 & 4 & -5 & -2 & -5 \end{bmatrix} R_{2} - 5A_{1} \begin{bmatrix} 1 & 2 & -9 & 11 & 6 & 15 \\ 0 & 2 & 4 & -5 & -2 & -5 \end{bmatrix} R_{2} - 5A_{1} \begin{bmatrix} 1 & 2 & -9 & 11 & 6 & 15 \\ 0 & 2 & 4 & -5 & -2 & -5 \end{bmatrix} R_{2} - 5A_{1} \begin{bmatrix} 1 & 2 & -9 & 11 & 6 & 15 \\ 0 & 2 & 4 & -5 & -2 & -5 \end{bmatrix} R_{2} - 5A_{1} \begin{bmatrix} 1 & 2 & -9 & 11 & 6 & 15$$

11. T. Invertible if there is an 1xn matrix C sun that CA=I & AC=I

13. F, Invese of AB+ (AB) is B'A'

15. F. would have to be ad-bc ≠0 for A to be invertible

17.7, x= A-1b

19.T. And operations are reversible, so elementary matrices are invertible

2.2.23 AB-AC

A'A=I

A'AB) = A'ACB) = A'ACC) 
$$\rightarrow \pm B = \pm C$$

B=C

Not generally the when A is not invertible

LiNear independence is when the vectors armost be written on scalars of embrother

For example, a 2x2 mother has the determinant ad-actor if #=0, then it is beenly department. If \$0, you on And the inverse of the matrix.

I believe the determinant determines if the Motric is inventible, the determinant is only able to do that if vectors are lineary Independent

11. T, according to Statements to Ed in the invertible matrix thereon, All statements are equivalent

13. T, according to Statements In the in the IMT, TFA

15.T. Statement gin IMT. IMT only applies to nixn (square Matrices)

17. T, only when Ax=0 has the trivial solution, can A have n pivot positions.

3.1.5. 
$$\begin{vmatrix} 2 & 3 & -3 \\ 4 & 0 & 3 \end{vmatrix}$$
  $\begin{vmatrix} A_{11} = \begin{bmatrix} 0 & 3 \\ 1 & 5 \end{bmatrix} \Rightarrow A_{12} = \begin{bmatrix} 4 & 3 \\ 6 & 5 \end{bmatrix} \Rightarrow A_{13} = \begin{bmatrix} 40 \\ 61 \end{bmatrix}$   
 $\begin{vmatrix} 0 & 3 \\ 0 & 3 = -3 = bdr(A_{11}) \end{vmatrix}$   $\begin{vmatrix} 0 & 3 \\ 20 & 48 = 2 = bdr(A_{12}) \end{vmatrix} \Rightarrow \begin{vmatrix} 40 \\ 61 \end{vmatrix}$   $\begin{vmatrix} 40 \\ 61 \end{vmatrix}$ 

3.1.20 
$$\begin{bmatrix} a & b \\ c & d \end{bmatrix}$$
,  $\begin{bmatrix} a & b \\ kc & kd \end{bmatrix}$  Scales determinant by a Factor of K ad-bc  $\alpha(kd)$  -  $b(kc)$