## 6.3 Orthogonal Projections

note: 
$$\vec{y} = \vec{g} + \vec{z}$$
, where  $\vec{g} = \text{proj}_{\vec{q}} \vec{y} \notin \vec{z} \perp \vec{y}$ .

Idea: y can be projected onto larger subspaces!

Thm: Let  $W \subset \mathbb{R}^n$  be a subspace, then each  $\vec{y} \in \mathbb{R}^n$  (not necessarily W) has the form  $\vec{y} = \hat{y} + \vec{z}$ , where  $\hat{y} \in W \notin \vec{z} \in W^{\perp}$ 

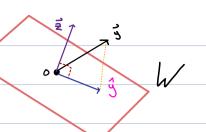
In fact, if 
$$\{\vec{u}_1,...,\vec{u}_p\}$$
 is an orthogonal basis of  $W$ , we get  $\vec{y} = \frac{\vec{y} \cdot \vec{u}_1}{\vec{u}_1 \cdot \vec{u}_1} \cdot \vec{u}_1 + ... = \frac{\vec{y} \cdot \vec{u}_p}{\vec{u}_p \cdot \vec{u}_p}$   
In this case,  $(\vec{z} = \vec{y} - \hat{y})$ 

Def: g or Proj w g is the Projection of g onto W

ex: Let 
$$u_1 = \begin{bmatrix} 2 \\ -1 \end{bmatrix}$$
  $u_2 = \begin{bmatrix} -2 \\ 1 \end{bmatrix}$  let  $y = \begin{pmatrix} 2 \\ 3 \end{pmatrix}$  Orthogonally views implies Linear Independence

Thus: 
$$\vec{2} = \vec{y} - \vec{y}$$
  $\begin{pmatrix} \frac{1}{2} \\ \frac{2}{3} \end{pmatrix} - \begin{pmatrix} \frac{.215}{1/6} \end{pmatrix} = \begin{pmatrix} \frac{715}{14/5} \end{pmatrix} = \vec{2}$ 

Thus:  $y = \begin{pmatrix} -215 \\ 1/5 \end{pmatrix} + \begin{pmatrix} 7/5 \\ 0 \\ 1/5 \end{pmatrix}$ , where these vectors are Orthogonal

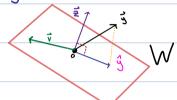


Prop: If is EW then projus = is Note: Projection onto a subspace is a Linear Transformation

( Not tested on )

st Approx Thm: Let W C B" be a subspace & g & B". Then g is the "closest" vector in W to g

4: i.e., if VEW (distinct from 3), then NJ-4 NL NJ-VN



6.4 Gram-Schmidt Process

Qi: Is there a way to make a bosis orthogonal? Yes

ex: 
$$\vec{X}_1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$
  $\vec{X}_2 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$   $\vec{X}_3 = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$  Clearly not orthogonal

$$S = \{\vec{x_1}, \vec{x_2}, \vec{x_3}\}\ is\ LI$$
 so it's a bosis of  $SAnS = : W < B^4$ , a subspace

By design, v2 1 vi

1. Let 
$$V_1 = x_1 + spon \{V_1\} = : W_1$$
2. Let  $V_2 = x_2 - proj_W x_2$ 

$$\begin{bmatrix}
0 \\
1 \\
1
\end{bmatrix} - \frac{\vec{\chi}_2 \cdot \vec{V}_1}{\vec{V}_1 \cdot \vec{V}_1} \cdot \vec{V}_1 \quad \rightarrow \begin{bmatrix}
0 \\
1 \\
1
\end{bmatrix} - \begin{bmatrix}
3/4 \\
3/4 \\
3/4
\end{bmatrix} = \begin{bmatrix}
-3/4 \\
1/4 \\
1/4
\end{bmatrix} \text{ or } \vec{V}_1 \cdot \vec{V}_2 \quad \rightarrow \begin{bmatrix}
-3 \\
1 \\
1
\end{bmatrix} = \vec{V}_2$$

Then:  $W_2 := Span \left\{ \left( \frac{1}{2} \right) \left( \frac{-3}{2} \right) \right\}$ 

3. Let 
$$\vec{v_2} : \vec{x_3} - \rho_{10}; \vec{w_2} \times \vec{x_3}$$
  $\begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix} - \frac{\vec{x_3} \cdot \vec{v_2}}{\vec{v_2} \cdot \vec{v_2}} : \frac{2}{3} \times \vec{v_2} = \begin{pmatrix} 0 \\ 115 \\ 212 \\ 212 \end{pmatrix}$ 

$$\begin{bmatrix} 0 \\ 0 \\ 1 \\ 1 \end{bmatrix} - \frac{\sqrt{3}}{\sqrt{4}} \cdot \frac{\sqrt{4}}{\sqrt{4}} - \frac{\sqrt{4}}{\sqrt{2}} \cdot \frac{\sqrt{2}}{\sqrt{2}} \cdot \frac{\sqrt{2}}{\sqrt{2}} \\ 0 \\ 1 \\ 1 \end{bmatrix} - \begin{bmatrix} 0 \\ 213 \\ 213 \\ 213 \\ 213 \end{bmatrix} = \begin{bmatrix} 0 \\ -213 \\ 1/3 \\ 1/3 \end{bmatrix} \text{ or } \frac{1}{3} \begin{bmatrix} 0 \\ -2 \\ 1 \\ 1 \end{bmatrix}$$

Thun: (Gram - Schmidt Process): Given any basis  $\{\vec{x}_1, ..., \vec{x}_p\}$  of  $W \subset \mathbb{R}^n$ , define  $V_1 = x_1$ ,  $V_2 = x_2 \cdot \frac{\vec{x}_2 \cdot \vec{v}_1}{\vec{v}_1 \cdot \vec{v}_2} v_1$ ,  $V_3 = \vec{x}_3 - \frac{\vec{x}_3 \cdot \vec{v}_1}{\vec{v}_1 \cdot \vec{v}_2} v_1 - \frac{\vec{x}_3 \cdot \vec{v}_2}{\vec{v}_2 \cdot \vec{v}_2} v_2 \dots$   $\vec{v}_p = \vec{x}_p - \sum_{i=1}^{p-1} \frac{\vec{x}_p \cdot \vec{v}_i}{\vec{v}_i \cdot \vec{v}_i} \vec{v}_i$ .

Then:  $\{\vec{v}_1, ..., \vec{v}_p\}$  is an orthogonal Basis for W.

(orrelary: In this case, {NYN, VIN, 1, ..., VION) is an ONB for W.

## 6.5) Least Squares

(ecall: For WCR & \$\vec{y} \in \text{ERR}, \$\vec{y} := Proj\_w \vec{y} is the closest point in W to \$\vec{y} : i.e., \$V\vec{y} = 3U \in V\vec{y} = VV for any \$\vec{v} \in VV

Def: For A & Mat(m,n) & b & R a least-squares solution (LSS) of Ax = b is x & R S.E. U b-Ax U & V b-Ax U  $\forall \vec{x} = R^n$ 

Idea: Consider b:= Proj (16) => Ax=b is consistent i.e., there's some x & R s.6. Ax=b -> This x is the

Definition of Dot Product

By orthogonal decomposition,  $\vec{b} - \vec{b}$  is orthogonal to (old  $\Rightarrow \vec{b} - A\hat{x}$  is orthogonal to each column vector  $\vec{a}_j$ ,  $\vec{a}_j^T$  ( $\vec{b} - A\hat{x}^2$ ). Equiv.,  $\vec{A}^T$  ( $\vec{b} - A\hat{x}^2$ ) = 0.  $\iff$   $\vec{A}^T \vec{A} \hat{x} = \vec{A}^T \vec{b}$ 

Thm: The set of Reast-square solutions of A= b is the set of solutions to A= A b.

(e(a)): The set of floot-square solutions of A= b is the set of solutions to A= A b. "The normal equations"

ex: Find leost-squies solution to Ax=b, A=(00) to=[0] Word ATA & ATB (401) (40) = (17 5) = ATA (40) (7) = (19) = ATB now solve  $\begin{bmatrix} 17 & 1 \\ 1 & 5 \end{bmatrix} \stackrel{\checkmark}{x} = \begin{bmatrix} 19 \\ 11 \end{bmatrix} \xrightarrow{\text{DID}} \stackrel{\checkmark}{x} = \begin{bmatrix} 17 & 1 \\ 1 & 5 \end{bmatrix} \stackrel{?}{[19]} = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$ 

# 6.7 Inner Product spaces

Def: Inner Product on V is a findom L. 7: V=v -> B s.t. for u,v, w eV & CER.

(4) (4, 4,7) = 0, and (4,4) = 0 => 4=0. We som: (v, 4,7) is an inner product space

ex: (12, 2.7 = 0) is an IPS

ex: Consider te:= (([0,17]): Differentiable Functions on [0,17]

Consider:  $(f,g) = \int_{0}^{1} f(x)cg(x) dx$ 

Thm: H with (Fig) = from gooder is an IPS Basis of H is infinite

Q: con we find a basis for H?

This is the for coscnr) Consider:  $\angle \cos x$ ,  $\sin x > = \int_{0}^{\pi} \cos x \sin x dx = 0$  I.e.,  $\cos x \perp \sin x$ \$ sin(nx)

Moreover: 
$$\langle \sqrt{\frac{2}{\pi}} \cos(nx), \sqrt{\frac{2}{\pi}} \cos(mx) \rangle = \begin{cases} 1 & \text{if } n=m \\ 0 & \text{if } n\neq m \end{cases}$$
  
Why?  $\langle \cos(nx), \cos(nx) \rangle = \frac{\pi}{2} \begin{cases} 1 & \text{if } n=m \\ 0 & \text{if } n\neq m \end{cases}$ 

Fact: The Set 
$$\left\{ \left( \frac{2}{\pi} \cos(nx), \sqrt{\frac{3}{4}} \sin(nx) \right) \right\}_{n=0}^{\infty}$$
 is an orthonormal basis for  $\mathcal{H}$ .

In particular: If  $f \in \mathcal{H}$ , we can decompose it as  $f(x) = \sum_{n=0}^{\infty} a_n \left( \sqrt{\frac{3}{4}} \cos(nx) \right) + b_n \left( \sqrt{\frac{3}{4}} \sin(nx) \right) \frac{1}{2} \left( -\frac{1}{2} \sin(nx) \right) + \frac{1}{2} \left( -\frac{1}{2} \cos(nx) \right) + \frac{1}{2} \left($ 

#### 7.1 Symmetric Matrices

Def: A matrix is symmetric if 
$$A=A^{T}$$
 ex:  $A=\begin{pmatrix} a & b & c \\ c & b & a_{1} & d \\ c & d & a_{1} \end{pmatrix}$ 

Fact: Any symmetric mater is square

Thin: IF A is symmetric the evectors corresponding to distant everyones are orthogonal

Proof: Let  $A\vec{v_1} = \lambda\vec{v_1} + A\vec{v_2} = \lambda\vec{v_2}$  where  $\lambda_1 = \lambda_2$ 

Then: 
$$\lambda(\vec{v}_1.\vec{v}_2) = (\lambda_1v_1)\cdot\vec{v}_2 = Av_1^2\cdot\vec{v}_2^2$$
 by  $deF(Av_1^2)^Tv_2 = \vec{v}_1^T(A^Tv_2^T) = \vec{v}_1^2\cdot Av_2^2 = \vec{v}_1^2\cdot \lambda_1\vec{v}_2^2$ 

$$= \lambda_2(\vec{v}_1.\vec{v}_2) \iff (\lambda_1-\lambda_2)(\vec{v}_1.\vec{v}_2^2) = O. \quad \text{Thos} \quad \vec{v}_1.\vec{v}_2 = O. \quad \Box$$

Def: A EMAL(Mm) is orthogonally diagonalizable if 3 orthogonalizable if 3 orthogonalizab

Spectral Theorem: IF AE(n,n) is symmetrical, then:

(a) A has a eigenvalues (counting multiplicities)

(b) dim (E(1,2)) = (multiplicity of 2 in Pa(2))

(c) The eigenspaces of A are muhally orthogonal

(d) A is orthogonally diagnose

## 7.2 - ish Quadrate Forms

ex: Let 
$$\vec{x} = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$$
 (ompute  $\vec{x}^T A \vec{x} = \vec{x} \cdot A \vec{x}$  For  $A = \begin{pmatrix} 4 & 0 \\ 3 & 0 \end{pmatrix}$  \$  $A^2 = \begin{pmatrix} 3 & 3 \\ -2 & 7 \end{pmatrix}$ 

(2) 
$$\frac{1}{x}$$
  $\left(\frac{3-2}{27}\right)\frac{1}{x^2} = \left(\kappa_1, \kappa_2\right)\left(\frac{3\kappa_1, 2\kappa_2}{-2\kappa_1+7\kappa_2}\right) = 3\kappa_1^2 - 4\kappa_1 \kappa_2 + 7\kappa_2^2$ 

A is positive define if 
$$\vec{x}^T A \vec{x} \geq 0 \quad \forall \vec{x} \in \mathbb{R}^2$$

Fact: 
$$\int_{-\infty}^{9(r)} e^{-\frac{1}{2}r^2} dx = \int_{2\pi}^{2\pi}$$

$$I^{2} = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} e^{-\frac{1}{2}(x^{2}+y^{2})} dxdy = \int_{0}^{\infty} \int_{0}^{\infty} e^{-r^{2}} r drd0 = \dots = 2 \text{ ft} \Rightarrow I = \int_{0}^{\infty} \int_{0}^{\infty} e^{-r^{2}} r drd0 = \dots = 2 \text{ ft} \Rightarrow I = \int_{0}^{\infty} \int_{0}^{\infty} e^{-r^{2}} r drd0 = \dots = 2 \text{ ft} \Rightarrow I = \int_{0}^{\infty} \int_{0}^{\infty} e^{-r^{2}} r drd0 = \dots = 2 \text{ ft} \Rightarrow I = \int_{0}^{\infty} \int_{0}^{\infty} e^{-r^{2}} r drd0 = \dots = 2 \text{ ft} \Rightarrow I = \int_{0}^{\infty} \int_{0}^{\infty} e^{-r^{2}} r drd0 = \dots = 2 \text{ ft} \Rightarrow I = \int_{0}^{\infty} \int_{0}^{\infty} e^{-r^{2}} r drd0 = \dots = 2 \text{ ft} \Rightarrow I = \int_{0}^{\infty} \int_{0}^{\infty} e^{-r^{2}} r drd0 = \dots = 2 \text{ ft} \Rightarrow I = \int_{0}^{\infty} \int_{0}^{\infty} e^{-r^{2}} r drd0 = \dots = 2 \text{ ft} \Rightarrow I = \int_{0}^{\infty} \int_{0}^{\infty} e^{-r^{2}} r drd0 = \dots = 2 \text{ ft} \Rightarrow I = \int_{0}^{\infty} \int_{0}^{\infty} e^{-r^{2}} r drd0 = \dots = 2 \text{ ft} \Rightarrow I = \int_{0}^{\infty} \int_{0}^{\infty} e^{-r^{2}} r drd0 = \dots = 2 \text{ ft} \Rightarrow I = \int_{0}^{\infty} \int_{0}^{\infty} e^{-r^{2}} r drd0 = \dots = 2 \text{ ft} \Rightarrow I = \int_{0}^{\infty} \int_{0}^{\infty} e^{-r^{2}} r drd0 = \dots = 2 \text{ ft} \Rightarrow I = \int_{0}^{\infty} \int_{0}^{\infty} e^{-r^{2}} r drd0 = \dots = 2 \text{ ft} \Rightarrow I = \int_{0}^{\infty} \int_{0}^{\infty} e^{-r^{2}} r drd0 = \dots = 2 \text{ ft} \Rightarrow I = \int_{0}^{\infty} \int_{0}^{\infty} e^{-r^{2}} r drd0 = \dots = 2 \text{ ft} \Rightarrow I = \int_{0}^{\infty} \int_{0}^{\infty} e^{-r^{2}} r drd0 = \dots = 2 \text{ ft} \Rightarrow I = \int_{0}^{\infty} \int_{0}^{\infty} e^{-r^{2}} r drd0 = \dots = 2 \text{ ft} \Rightarrow I = \int_{0}^{\infty} \int_{0}^{\infty} e^{-r^{2}} r drd0 = \dots = 2 \text{ ft} \Rightarrow I = \int_{0}^{\infty} \int_{0}^{\infty} e^{-r^{2}} r drd0 = \dots = 2 \text{ ft} \Rightarrow I = \int_{0}^{\infty} \int_{0}^{\infty} e^{-r^{2}} r drd0 = \dots = 2 \text{ ft} \Rightarrow I = \int_{0}^{\infty} \int_{0}^{\infty} e^{-r^{2}} r drd0 = \dots = 2 \text{ ft} \Rightarrow I = \int_{0}^{\infty} \int_{0}^{\infty} e^{-r^{2}} r drd0 = \dots = 2 \text{ ft} \Rightarrow I = \int_{0}^{\infty} \int_{0}^{\infty} e^{-r^{2}} r drd0 = \dots = 2 \text{ ft} \Rightarrow I = \int_{0}^{\infty} \int_{0}^{\infty} e^{-r^{2}} r drd0 = \dots = 2 \text{ ft} \Rightarrow I = \int_{0}^{\infty} \int_{0}^{\infty} r drd0 = \dots = 2 \text{ ft} \Rightarrow I = \int_{0}^{\infty} \int_{0}^{\infty} r drd0 = \dots = 2 \text{ ft} \Rightarrow I = \int_{0}^{\infty} \int_{0}^{\infty} r drd0 = \dots = 2 \text{ ft} \Rightarrow I = \int_{0}^{\infty} \int_{0}^{\infty} r drd0 = \dots = 2 \text{ ft} \Rightarrow I = \int_{0}^{\infty} \int_{0}^{\infty} r drd0 = \dots = 2 \text{ ft} \Rightarrow I = \int_{0}^{\infty} \int_{0}^{\infty} r drd0 = \dots = 2 \text{ ft} \Rightarrow I = \int_{0}^{\infty} \int_{0}^{\infty} r drd0 = \dots = 2 \text{ ft} \Rightarrow I = \int_{0}^{\infty} \int_{0}^{\infty} r drd0 = \dots = 2 \text{ ft} \Rightarrow I = \int_{0}^{\infty} r drd0 = \dots = 2 \text{ ft} \Rightarrow I = \int_{0}^{\infty} r drd0 = \dots = 2$$

			1	( ( /-1	- 1 - 2	
Thm: For A EMUT(nin)	Symm t Po	s. def. ,	CZP)"/2	J J exp ( 2	* 4* ) dx	= Jde+A