Assignment 1	Project Summary
Course	Practical Robotics and Smart Things - 2020

Project author		
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Project name	Pet Feeder

## 1. Short project description (Business needs and system features)

Nowadays IoT is facing great development. Its various applications range in all kind of human activities. The following project concentrates in its use in the everyday life, and more precisely pet care. The idea is to build smart widget that will take care of pet feeding throughout the day while the owner is not home.

The hardware implementation is based on Raspberry Pi 3 (Model B) single board computer, equipped with following sensors:

- Raspberry Pi camera (v2) used to take user's pictures and send them to the face recognition service;
- PIR motion detector activating the camera and the detection;

## ICM actuators include:

• Continuous rotation servo – rotating the portion wheel

The ICM has the following main modes of operation:

- Sleeping mode during which the pet feeder is inactive:
- Dog recognition mode activated around feeding times and on owner demand:
- Feeding mode activated when dog is recognized;

There will also be a mobile application through which the owner can monitor whether the pet has eaten its portion and to manually give additional one.

The main user roles (actors in UML) are:

- *Unregistered User* his only option is to register;
- Registered User can register a pet feeding machine, obtain information about current feeding process and manually feed pet from one of the registered machines;

2. Main Use Cases / Scenarios		
Use case name	Jse case name Brief Descriptions Actors Involve	
2.1. Register	Unregistered user can register in the system through the mobile application.  Unregistered user can register in the system through use	
2.2. Add feeding machine	Registered user can add a feeding machine to configure and monitor.	Registered user
2.3. Delete feeding machine	Registered user can remove feeding machines from the ones it has registered.	Registered user
2.4. Login	Registered user must log in the system so to identify himself.	
2.5. Manually feed	7. Manually feed Registered user can choose to manually feed his pet from some of his registered feeding machines.	
2.6. Set feeding times		

3.	3. Main Views (Mobile Web App)			
Vi	View name Brief Descriptions			
1.	Home	The entry page of the mobile app. It has a welcoming message and buttons navigating to the only possible pages a user can enter at that stage: the register page and the login page.	/	
	Feeding Machines	Contains listed created feeding machines for the current user. The user can enter each feeding machine by clicking on it.	/machines	
3.	Create a feeding machine	In this view the registered user can create new feeding machines and connect them with the corresponding device. Also, he can set feeding hours and dose.	/create	
4.	Feeding Machine Status	This view presents a singular feeding machine: its status, whether the pet has been fed, an option for manual feed, and an option to delete the concrete machine.		
5.	Register	In this view an Unregistered user can register himself by entering sufficient information.	/register	
6.	Login	This view present the user with a login form which is used to identify him/her in the system and enable him to use it.	/login	

7. Profile	7. Profile In this view a registered user can review and update his	
	personal information.	

API Resources (REST/SSE/WebSocket Backend)			
View	name	Brief Descriptions	URI
4.1.	Users	GET list of all users of the system	/api/users
4.2.	User	GET, PUT, DELETE User Data for User with specified userId	/api/users/{userId}
4.3.	Login	POST User Credentials (e-mail address and password) and perform user login.	/api/login
4.4.	Logout	POST a logout request	/api/logout
4.5.	Register	POST User data (email address, name, password) and create user account in the system corresponding to that data.	/api/register
4.6.	Machines	GET all feeding machines for the user with id userid. POST Machine data to register a new feeding machine to this user.	/api/machines/{userid}
4.7.	Machine	GET, PUT, DELETE machine data to operate over machine specified by <i>mid</i> .	/api/machine/{mid}

## **Resources:**

[1]  $\underline{\text{https://www.youtube.com/watch?v=sCOkuyH7CPo\&t=259s}}$  – from here I got the basic idea for the portion wheel

[2] <a href="https://create.arduino.cc/projecthub/circuito-io-team/iot-pet-feeder-10a4f3?ref=tag&ref\_id=pet%20feeder&offset=0">https://create.arduino.cc/projecthub/circuito-io-team/iot-pet-feeder-10a4f3?ref=tag&ref\_id=pet%20feeder&offset=0</a> – information about what kind of servo is sufficient for my purposes and the motion detecting sensor