

Machine Learning (Lab support)

Regularization and feature selection

Abdelkrime Aries

*Laboratoire de la Communication dans les Systèmes Informatiques (LCSI)
École nationale Supérieure d'Informatique (ESI, ex. INI), Algiers, Algeria*

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Machine Learning (Lab support)

Regularization and feature selection: Introduction

- You saw in the lecture ...
 - the overfitting problem;
 - regularization by penalty (L2 as an example);
 - the different approaches to feature selection.
- In this lab support, we will present ...
 - some regularization approaches;
 - three penalty regularization techniques;
 - a reminder about feature selection approaches
 - detailing the techniques of each approach (with example from scikit-learn)

Machine Learning (Lab support)

Regularization and feature selection: Plan

1 Regularization

- L2 Loss
- L1 Loss
- ElasticNet

2 Feature selection

- Filter
- Embedded
- Wrapper

Section 1

Regularization

Regularization and feature selection

Regularization

- used to reduce overfitting
- can cause faster convergence
- **By augmentation**: add more data
 - automatic data generation
 - Ex. **Generate new images by rotation**
- **Early stopping**: use validation in the stopping decision
 - train on one dataset and use another for validation in each iteration
 - when the validation error increases, stop
- **By penalty**: add a penalty to the objective function
 - reduce model complexity
 - by adding another constraint on the parameters (penalty)

Regularization and feature selection

Regularization: By penalty

$$\begin{cases} \min J_{\text{cost}}(\theta) \\ \wedge \\ \min J_{\text{complexity}}(\theta) \end{cases} \Rightarrow \min J_{\text{cost}}(\theta) + J_{\text{complexity}}(\theta)$$

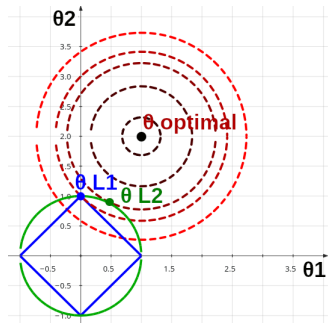
- minimize the complexity by increasing the bias: θ_0 has no constraint, so the model gives it more importance during training
- the complexity penalty uses a hyper-parameter λ
 - if λ is too big, the model will be too simple (not dependent on attributes). So, **underfitting**.
 - if λ is too small, the model will be too complex (too dependent on attributes). So, **overfitting**.

Regularization and feature selection: Regularization

L2 Loss: Tikhonov regularization, L2 loss

$$J_{L2} = \frac{\lambda}{2M} \sum_{j=1}^N \theta_j^2$$

- θ_0 is not affected by regularization
- θ_j converges to 0, but does not equal 0
- $\lambda \rightarrow \infty \Rightarrow \theta_j \rightarrow 0$
- $L2$ tries to pull the values of θ inside a sphere
- the size of the sphere is inversely proportional to λ

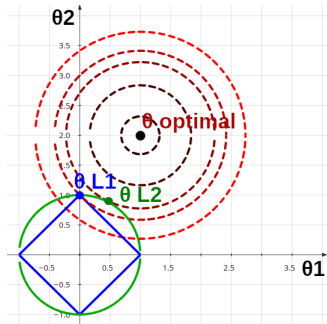


Regularization and feature selection: Regularization

L1 Loss: L1 loss

$$J_{L1} = \frac{\lambda}{M} \sum_{j=1}^N |\theta_j|$$

- least absolute shrinkage and selection operator
- θ_0 is not affected by regularization
- θ_j is canceled after a few iterations (it will last depending on the importance of its attribute)
- $it \rightarrow \infty \Rightarrow \theta_j = 0$
- $L1$ tries to pull the values of θ inside a cube
- the size of the cube is inversely proportional to λ



Regularization and feature selection: Regularization

L1 Loss: Optimization

- L1 is not differential in 0
- Several techniques have been proposed to find the solution path $L1$
 - Subgradient methods; ex. **least-angle regression (LARS)**
 - Coordinate descent
 - Proximal gradient methods (by operator **soft thresholding**)

$$S_{\frac{\lambda}{M}}(\theta_j) = \begin{cases} \theta - \frac{\lambda}{M} & \theta_j > \frac{\lambda}{M} \\ 0 & \theta_j \in [-\frac{\lambda}{M}, \frac{\lambda}{M}] \\ \theta + \frac{\lambda}{M} & \theta_j < -\frac{\lambda}{M} \end{cases}$$

- In case of the proximal gradient, the parameters are updated as follows:
- $\theta = S_{\frac{\lambda}{M}}(\theta - \alpha \frac{\partial}{\partial \theta} J_{\text{cost}}(\theta))$

Regularization and feature selection: Regularization

ElasticNet

$$J_{EN} = \frac{\lambda}{M} \sum_{j=1}^N \left(r|\theta_j| + \frac{(r-1)}{2} \theta_j^2 \right)$$

- θ_0 is not affected by regularization
- $r \in [0, 1]$ controls the percentage of $L1$ regularization

Section 2

Feature selection

Regularization and feature selection

Feature selection

- can reduce overfitting: the model can overfit over noise features
- can improve system accuracy
- reduce training time
- **Filter**: independently of the estimator, the best features are selected based on univariate statistical tests
- **Embedded**: the best features are selected during training
- **Wrapper**: the best features are selected for a given estimator before training

Regularization and feature selection: Feature selection

Filter: Score

Output	Input	
	Numerical	Categorical
Numerical (Regression)	Pearson	Mutual information
Categorical (Classification)	ANOVA, Mutual information	Chi-2, Mutual information

- **Pearson:** `sklearn.feature_selection.f_regression`
- **ANOVA:** `sklearn.feature_selection.f_classif`
- **Chi2:** `sklearn.feature_selection.chi2`
- **Mutual information:** `feature_selection.mutual_info_classif`
- **Mutual information:** `feature_selection.mutual_info_regression`

Regularization and feature selection: Feature selection

Filter: Selection

- Based on previous scores, the most important features can be selected in several ways
- **Number**: number of features to select
 - `sklearn.feature_selection.SelectKBest`
- **Percentile**: percentile of highest scores.
 - `sklearn.feature_selection.SelectPercentile`
- **P-value**: max threshold of accepted p-values
 - `sklearn.feature_selection.SelectFpr`

Regularization and feature selection: Feature selection

Filter: One-Way ANOVA (logic)

- Given a feature A (M samples) with numerical values
- the values are split on sets A_j where j is a class among N classes. We call them **Treatments**
- an attribute is representative (well correlated) of the output classes, if ...
 - values of the same class have less variance (intra-class variance)
 - class values have more variance with the rest (inter-class variance)
 - **SO**, the ratio (inter-class variance)/(intra-class variance) must be large
 - We call this ratio: **F-value** of ANOVA

Regularization and feature selection: Feature selection

Filter: One-Way ANOVA (math)

- Correlation factor: $CF = \frac{(\sum_{ij} A_{ij})^2}{M}$
- Total Sum of Squares: $TotalSS = \sum_{ij} A_{ij}^2 - CF$
- Treatment Sum of Squares: $TreatmentSS = \sum_j \frac{(\sum_i A_{ij})^2}{|A_j|} - CF$
- Error Sum of Squares: $ErrorSS = TotalSS - TreatmentSS$
- Mean of Squares Between: $MSB = \frac{TreatmentSS}{(N-1)}$
- Mean of Squares Within: $MSW = \frac{ErrorSS}{(M-N)}$
- $Fvalue = \frac{MSB}{MSW}$

Regularization and feature selection: Feature selection

Embedded

- **Decision trees**

- In each node, the best split feature is chosen.
- Certain features will not be considered.
- Finally, the tree will only use features with high separation capacity.

- **L1 regularization**

- It forces parameters to have small values.
- In L1, certain parameters are set to 0 after convergence.
- In this case, during the estimation the model does not take into account features with parameters of zero.

Regularization and feature selection: Feature selection Wrapper

- use an estimator and try to find feature combination giving more performance `sklearn.feature_selection.SequentialFeatureSelector`
- **Ascending (Forward selection)**
 - the initial set of features is empty
 - start by selecting a single feature that maximizes cross-validation
 - add more features in the same way until reaching the desired number
 - `SequentialFeatureSelector(direction="forward")`
- **Backward elimination**
 - the initial set of features equals to N
 - start by eliminating a single feature which minimizes cross-validation
 - eliminate more features in the same way until reaching the desired number
 - `SequentialFeatureSelector(direction="backward")`

The end of the ~~world~~ presentation

Stop scrolling

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It is the end!