## 1 The trapdoor

It works as follows,  $A, B \in \mathcal{M}_b$  will be scalar matrices.

Public parameters:  $E_0, d_1, d_2$ .

Trapdoor parameters (public key, secret key):  $(pk, sk) = (E_A, (A, \phi_A))$ .

Input of the trapdoor:  $K_1 \subset E_0[d_1], K_2 \subset E_A[d_2], B$ .

## **Evaluation:**

Output:  $(E_1, R_1, S_1, E_2, R_2, S_2)$ .

Now to inverse the map, we have access to:

- the secret key  $(A, \phi_A : E_0 \to E_A)$
- the image points

$$\begin{pmatrix} R_1 \\ S_1 \end{pmatrix} = B * \begin{pmatrix} \phi_1(P_b) \\ \phi_1(Q_b) \end{pmatrix}$$

• and the image points

$$\begin{pmatrix} R_2 \\ S_2 \end{pmatrix} = B * A * \begin{pmatrix} \phi_2 \circ \phi_A(P_b) \\ \phi_2 \circ \phi_A(Q_b) \end{pmatrix}$$

Consider  $\psi = \phi_2 \circ \phi_A \circ \widehat{\phi}_1$ , which has degree  $= d_2 d_A d_1$ , we have

$$B * A * B^{-1} * \begin{pmatrix} \psi(R_1) \\ \psi(S_1) \end{pmatrix} = [d_1] \begin{pmatrix} R_2 \\ S_2 \end{pmatrix}$$

But A and B commute so that since we know A and  $d_1$  we can recover  $\begin{pmatrix} \psi(R_1) \\ \psi(S_1) \end{pmatrix}$ . Now we would like to recover  $\psi$ . We have the torsion point images of order  $2^b > d_1 d_A d_2$  so that we can apply the usual torsion attacks. The parameters just need to be worked out.

It happens that, under the  ${\rm CIST^2}$  assumption, the FESTA trapdoor verifies the following definition:

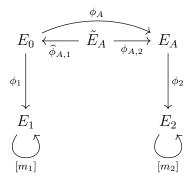
**Definition 1.0.1** (Quantum partial domain one-way function). Let  $X_0$ ,  $X_1$  and Y be three finite sets. A function  $f: X_0 \times X_1 \to Y$  is a quantum partial-domain one-way function if, for any polynomial-time quantum adversary A, the following holds:

$$P(s' = s | s \leftarrow X_0, t \leftarrow X_1, s' \leftarrow A(f(s, t)))$$

Then the OAEP transform, as described here builds a PKE from such a trapdoor functions.

## 2 The concrete instantiation

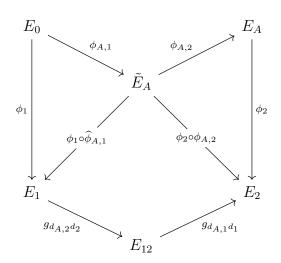
Consider the diagram:



Where we decomposed  $\phi_A$  in  $\phi_{A,1} \circ \phi_{A,2}$ . The main idea here would be to directly get

$$\phi_2 \circ \phi_A \circ \widehat{\phi}_1$$

from the  $2^b$  torsion point images. We would need to have  $2^b - d_2 * d_A * d_1$  smooth. Which gives few choices and usually low efficiency. Instead, since we already have  $\phi_A$  to invert the trapdoor. The idea would be to decompose  $\phi_A$  as  $\phi_{A,1} \circ \phi_{A,2}$  and use the hidden diagram



In which finding good parameters amounts to solving

$$m_1^2 d_{A,1} d_1 + m_2^2 d_{A,2} d_2 = 2^b$$

The trick of decomposing with some scalar multiplication doesn't change anything to the security! The paper proposes a way to find solutions with the desired properties efficiently. The  $d_i's$  are all squares.