

Digital Image Processing

COSC 6380/4393

Lecture – 11

Sept. 26th, 2023

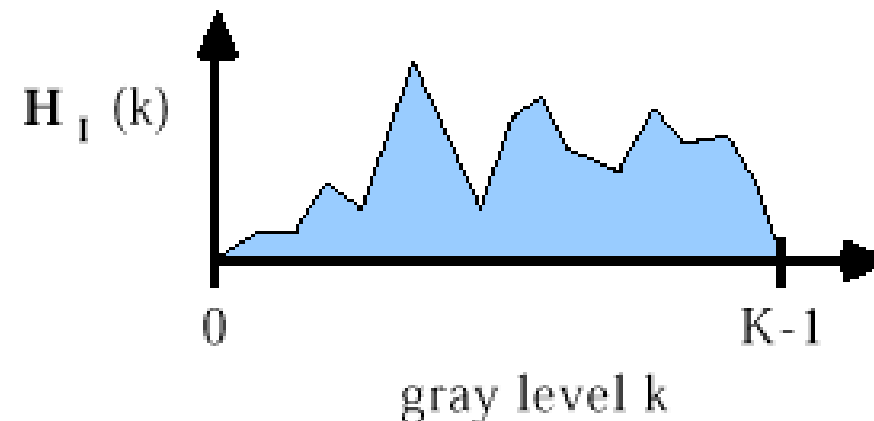
Pranav Mantini

Slides from Dr. Shishir K Shah and Frank (Qingzhong) Liu

Point Operations

SIMPLE HISTOGRAM OPERATIONS

- Recall: the gray-level histogram H_I of an image I is a graph of the frequency of occurrence of each gray level in I
- H_I is a one-dimensional function with domain $0, \dots, K-1$:
- $H_I(k) = n$ if gray-level k occurs (exactly) n times in I , for each $k = 0, \dots, K-1$



SIMPLE HISTOGRAM OPERATIONS

- The histogram H_I contains **no spatial information** about I - only information about the relative frequency of intensities
- Nevertheless
 - Useful information can be obtained from the histogram
 - Image quality is effected (enhanced, modified) by altering the histogram

Average Optical Density

- A measure of the average intensity of the image **I**:

$$\text{AOD}(\mathbf{I}) = \left[\frac{1}{N^2} \right] \sum_{i=0}^{N-1} \sum_{j=0}^{N-1} I(i, j) = \left[\frac{1}{N^2} \right] \sum_{j=0}^{N-1} \sum_{i=0}^{N-1} I(i, j)$$

- Can compute it from the histogram as well:

Average Optical Density

- A measure of the average intensity of the image **I**:

$$\text{AOD}(\mathbf{I}) = \left(\frac{1}{N^2} \right) \sum_{i=0}^{N-1} \sum_{j=0}^{N-1} I(i, j) = \left(\frac{1}{N^2} \right) \sum_{j=0}^{N-1} \sum_{i=0}^{N-1} I(i, j)$$

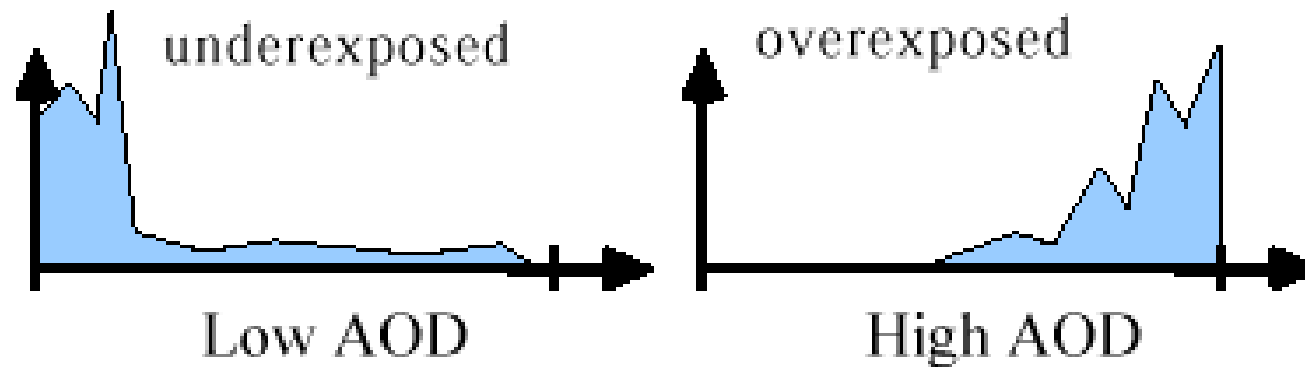
- Can compute it from the histogram as well:

$$\left(\frac{1}{N^2} \right) \sum_{k=0}^{K-1} kH_I(k)$$

- k^{th} term = (brightness level k) x (# occurrences of k)

Average Optical Density

- Examining the histogram can reveal possible errors in the imaging process:



- Methods for correcting such errors utilize the histogram
- The histogram will arise throughout this lecture

POINT OPERATIONS

- A **point operation** on an image **I** is a **function f** that maps **I** to another image **J** by operating on **individual pixels** in **I**:

$$J(i, j) = f[I(i, j)], 0 \leq i, j \leq N-1$$

- The same function **f** is applied at every image coordinate
- This is different from **local operations** such as OPEN, CLOSE, etc., since those are functions of both **I(i, j)** and **its neighbors**

POINT OPERATIONS

- Point operations **do not** modify **spatial relationships** between pixels
- They **do** modify the **image histogram**, and therefore the overall appearance of the image

LINEAR POINT OPERATIONS

- **Linear point operations** are the simplest class of point operations

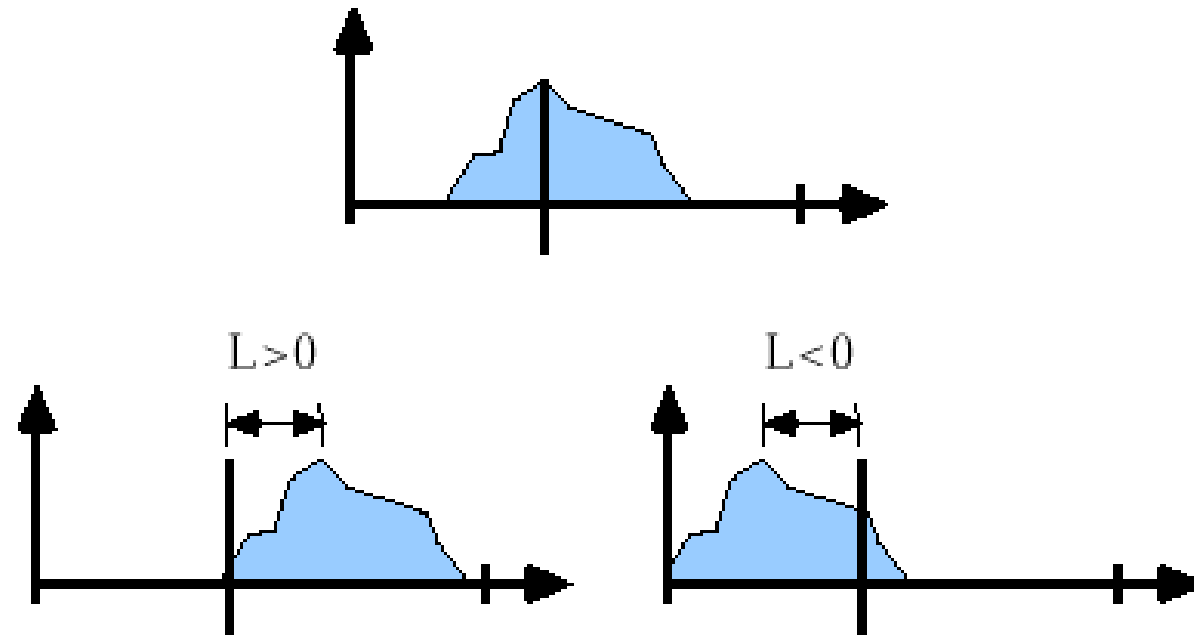
$$F(X) = P.X + L$$

Image Offset

- Suppose **L** falls in the range $-(K-1) \leq L \leq K-1$ (\pm the nominal gray scale)
- An **additive image offset** is defined by the function
$$J(i, j) = I(i, j) + L, \text{ for } 0 \leq i, j \leq N-1$$
- Thus, the same constant **L** is added to every image pixel value
- If $L > 0$, **J** will be a **brightened** version of the image **I**
- Otherwise its appearance will be essentially the same

Image Offset

- If $L < 0$, J will be a **dimmed** version of the image I
- Adding offset L **shifts** the histogram by amount L to left or right:



Histograms of additive image offsets

- The input and output histograms are related by:

$$H_J(k) = H_I(k-L)$$

Image Offset Example

- Suppose it is desired to **compare** multiple images I_1, I_2, \dots, I_n of the same scene
- However, the images were taken with a variety of different exposures or lighting conditions
- One solution: **equalize** the AOD's of the images
- If the gray-scale range of the images is $0, \dots, K-1$, a reasonable AOD is $K/2$
- Let $L_m = \text{AOD}(I_m)$, for $m = 1, \dots, n$
- Then define "AOD-equalized" images J_1, J_2, \dots, J_n according to $J_m(i, j) = I_m(i, j) - L_m + K/2$, for $0 \leq i, j \leq N-1$

Image Offset Example

- The effect:

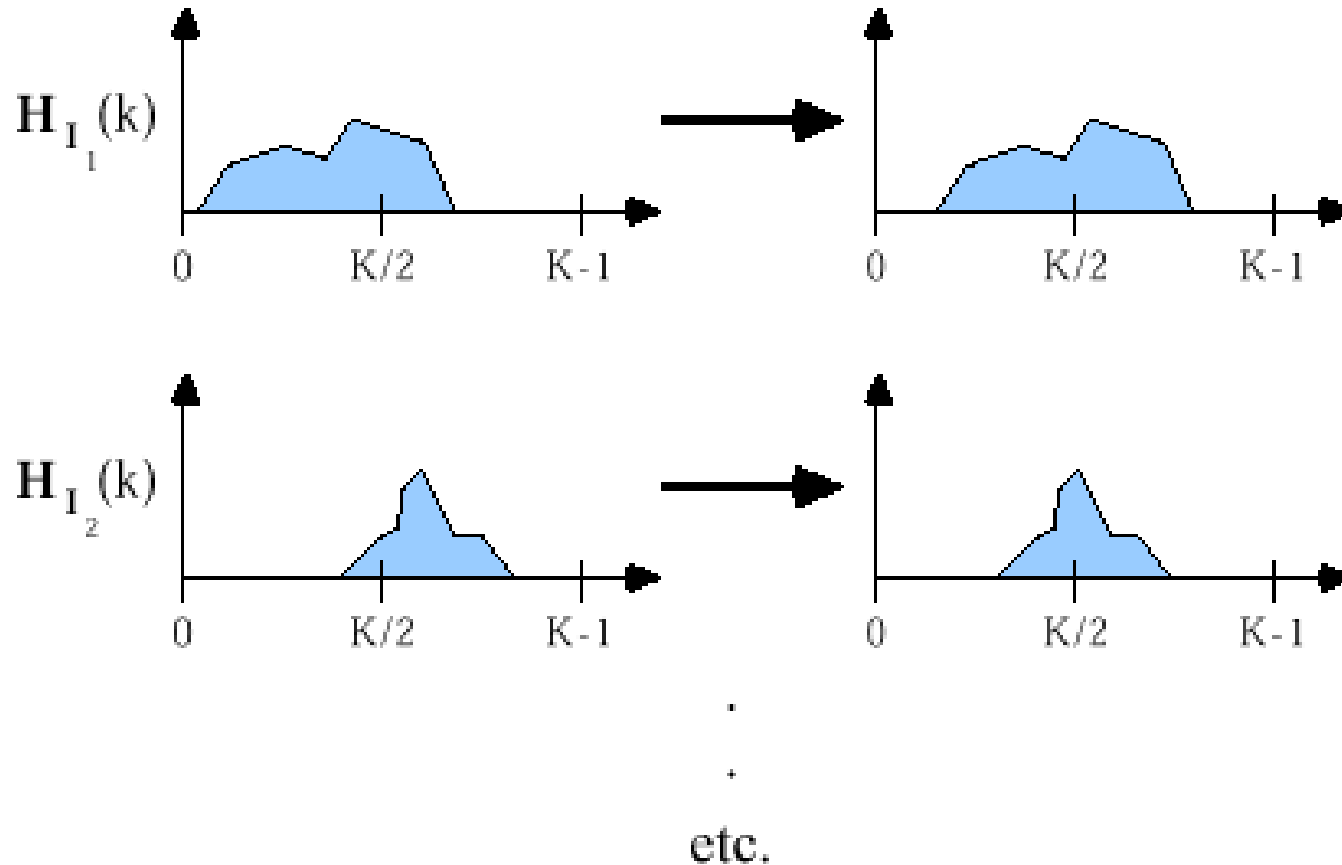


Image Scaling

- Suppose $P > 0$ (not necessarily an integer)
- **Image scaling** is defined by the function

$$J(i, j) = P \cdot I(i, j), \text{ for } 0 \leq i, j \leq N-1$$

- Thus, P **multiplies** every image pixel value
- In practice:

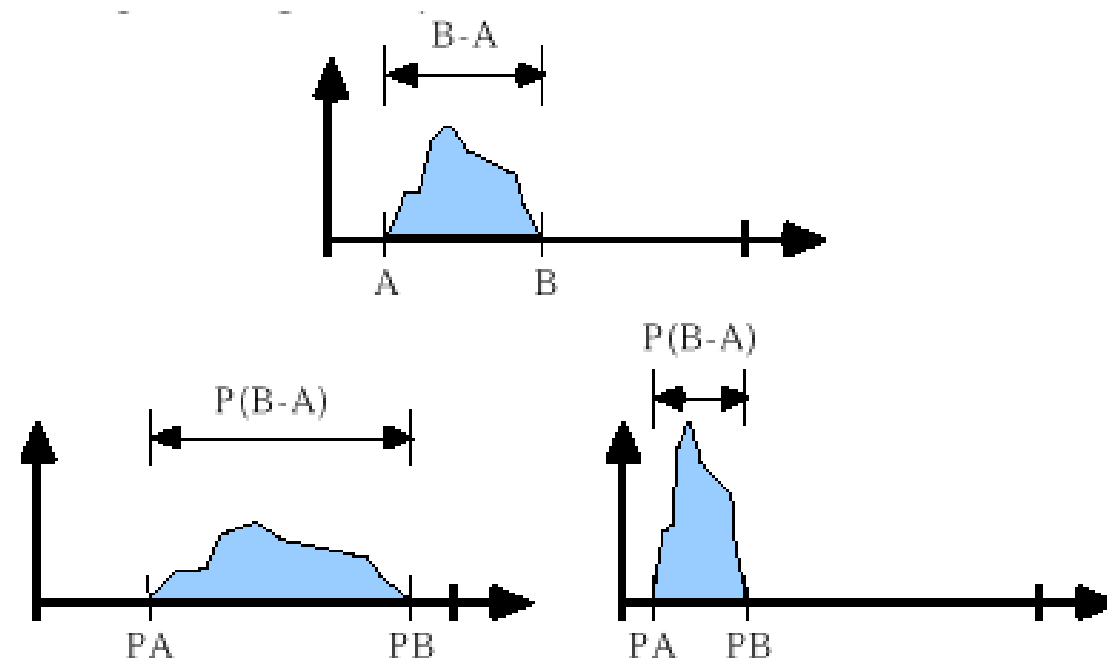
$$J(i, j) = \text{INT}[P \cdot I(i, j) + 0.5], \text{ for } 0 \leq i, j \leq N-1$$

where $\text{INT}[R] =$ nearest integer that is $\leq R$

- If $P > 1$, **J** will have a **broader grey level range** than image **I**

Image Scaling

- If $P < 1$, J will have a **narrower grey-level range** than I
- Multiplying by a constant P **stretches** or **compresses** the "width" of the image histogram by a factor P :



Comments

- An image with a compressed gray level range generally has a **reduced visual contrast**
- Such an image may have a **washed-out** appearance
- An image with a wide range of gray levels generally has an **increased visual contrast**
- Such an image may have a more striking, viewable appearance

Linear Point Operations: Offset & Scaling

- Suppose L and P are real numbers (not necessarily integers)
- A **linear point operation** on I is defined by the function

$$J(i, j) = P \cdot I(i, j) + L, \text{ for } 0 \leq i, j \leq N-1$$

- In practice:

$$J(i, j) = \text{INT}[P \cdot I(i, j) + L + 0.5], \text{ for } 0 \leq i, j \leq N-1$$

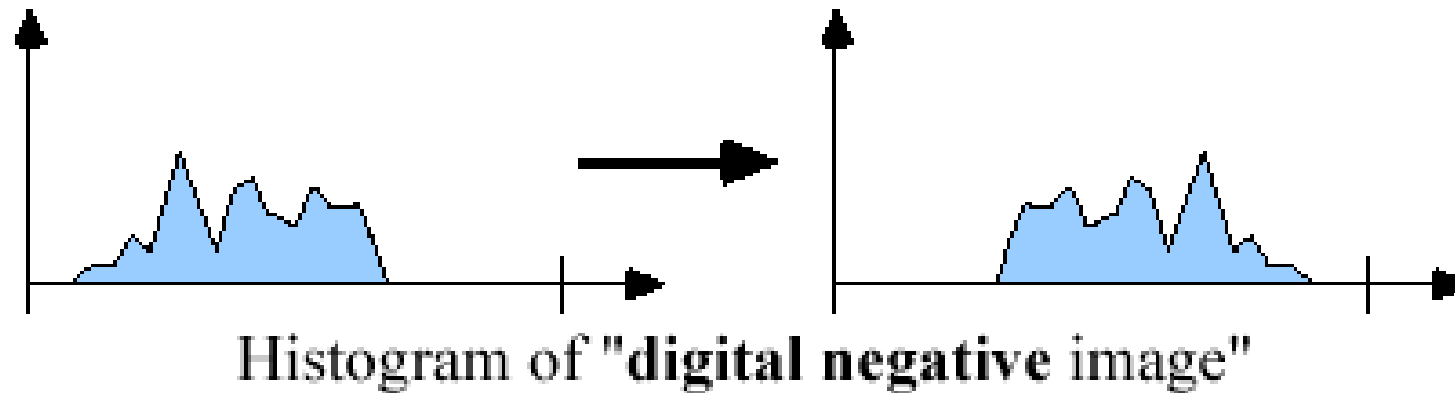
- The image J is a version of I that has been scaled and given an additive offset

Linear Point Operations: Offset & Scaling

- If $P < 0$, the histogram is **reversed**, creating a **negative** image
- By far the most common use is $P = -1$ and $L = K-1$:

$$J(i, j) = (K-1) - I(i, j), \text{ for } 0 \leq i, j \leq N-1$$

- Hereafter w

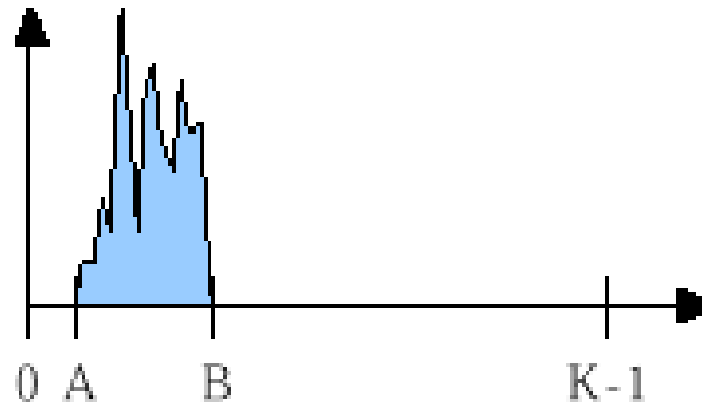


Caveat

- Generally, the available gray-scale of the transformed image **J** is the same as that of the original image **I**: $\{0, \dots, K-1\}$
- When making the transformation
$$J(i, j) = P \cdot I(i, j) + L, \text{ for } 0 \leq i, j \leq N-1$$
- care must be taken that the maximum and minimum values J_{\max} and J_{\min} satisfy
$$J_{\max} \leq K-1 \text{ and } J_{\min} \geq 0$$
- **At best**, values outside these ranges will be "clipped"
- At worst, an overflow or sign-error condition may occur
- In that instance, the gray-scale value assigned to an error pixel will be highly unpredictable

Full-Scale Contrast Stretch

- The **most common** linear point operation. Suppose **I** has a compressed histogram:



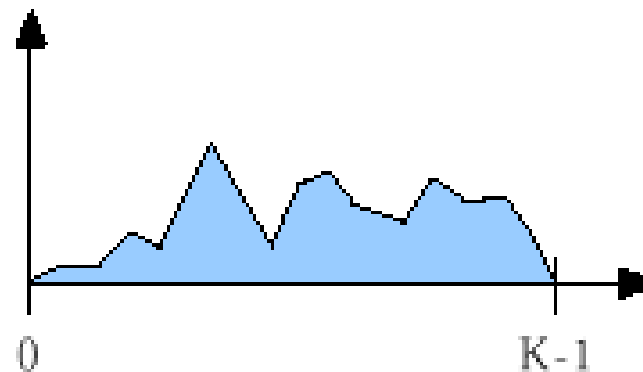
- Let A and B be the min and max gray levels in **I**
- Define

$$J(i, j) = P \cdot I(i, j) + L$$

- such that $P \cdot A + L = 0$ and $P \cdot B + L = (K-1)$

Full-Scale Contrast Stretch

- The result of solving these **2 equations in 2 unknowns** (P, L) is an image **J** with a full-range histogram:



- The solution to the above equations is

$$P = \left\lfloor \frac{K-1}{B-A} \right\rfloor \quad \text{and} \quad L = -A \left\lfloor \frac{K-1}{B-A} \right\rfloor$$

or

$$J(i, j) = \left\lfloor \frac{K-1}{B-A} \right\rfloor [I(i, j) - A]$$

NONLINEAR POINT OPERATIONS

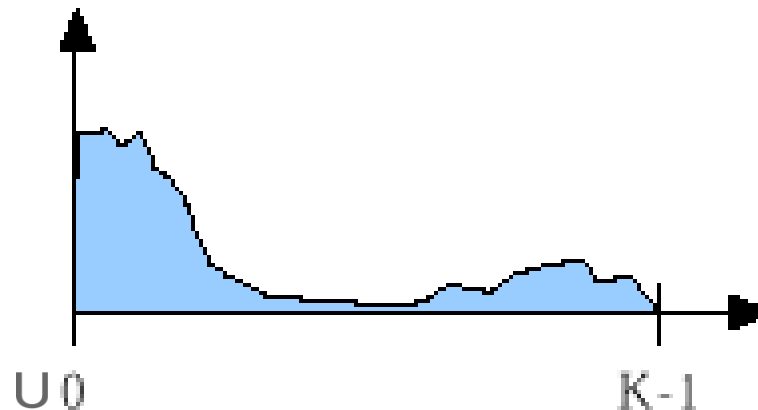
- A **nonlinear point operation** on I is a **pointwise function** f mapping I to J :

$$J(i, j) = f[I(i, j)] \text{ for } 0 \leq i, j \leq N-1$$

- where f is a **nonlinear function**.
- This is of course a very broad class of functions
- However, only a few are used much:
 - $J(i, j) = |I(i, j)|$ (absolute value or magnitude)
 - $J(i, j) = [I(i, j)]^2$ (square-law)
 - $J(i, j) = I(i, j)^{1/2}$ (square root)
 - $J(i, j) = \log[1+I(i, j)]$ (logarithm)
 - $J(i, j) = \exp[I(i, j)] = e^{I(i, j)}$ (exponential)

Logarithmic Range Compression

- **Motivation:** An image may contain information-rich, smoothly-changing low intensities - and small very bright regions
- Useful for detecting faint **objects**
- The bright pixels will dominate our visual perception of the image
- A typical histogram:



Logarithmic Range Compression

- **Logarithmic transformation** $J(i, j) = \log[1+I(i, j)]$
nonlinearly **compresses** and **equalizes** the gray-scales
- Bright intensities are compressed much more heavily -
thus **faint details** emerge
- A full-scale contrast stretch then utilizes the full gray-scale
range:

