

# Neutron star cooling by axion emission

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August 8, 2023

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## 1 Introduction

The goal of this project is to evaluate the integral

### Emissivity integral

$$\varepsilon_{3'} = \int f_1 f_2 (1 - f_{1'}) (1 - f_{2'}) (1 + f_{3'}) \times E_{3'} \sum_{\sigma, \sigma'} |\mathcal{M}|^2 d\Phi_3((p_1 + p_2)^2; 1', 2', 3') \frac{d^3 p_1}{(2\pi)^3 2E_1} \frac{d^3 p_2}{(2\pi)^3 2E_2} \quad (1.1)$$

where,

$$d\Phi_n((p_a + p_b)^2; 1, \dots, n) \equiv \prod_{i=1}^n \left[ \delta(p_i^2 - m_i^2) \Theta(p_i^0) \frac{d^4 p_i}{(2\pi)^3} \right] (2\pi)^4 \delta^4 \left( p_a + p_b - \sum_{i=1}^n p_i \right) \quad (1.2)$$

is the Lorentz-invariant phase space measure, and

$$f_i \equiv f_{FD}(E_i) \equiv \frac{1}{e^{(E_i - \mu_i)/T} + 1}$$

is the Fermi-Dirac distribution. The spin-summed matrix element squared is given by

### Spin-summed matrix element

$$\sum_{\sigma, \sigma'} |\mathcal{M}|^2 = \frac{128 g_{ae\mu}^2 e^4}{(m_1^2 - m_{1'}^2)^2} \frac{(p_1 \cdot p_{1'} - m_1 m_{1'})(p_2 \cdot p_{3'})(p_{2'} \cdot p_{3'})}{(p_2 - p_{2'})^4}. \quad (1.3)$$

### 1.1 Integration in terms of momentum variables (didn't work)

*The first strategy I used to evaluate this integral was to do the integration directly in terms of the momentum variables. Below are the notes I wrote detailing my strategy.*

We can use the momentum conserving Dirac delta to evaluate the  $\mathbf{p}_{2'}$  integral, setting

$$\mathbf{p}_{2'} = \mathbf{p}_1 + \mathbf{p}_2 - \mathbf{p}_{1'} - \mathbf{p}_{3'}. \quad (1.4)$$

We now choose to align the  $z$ -axis with  $\mathbf{p}_1$  and measure angles with respect to this axis. Converting to spherical polar coordinates gives, for example,  $d^3 p_{3'} = p_{3'}^2 dp_{3'} d\cos\theta_{13'} d\phi_{13'}$ <sup>1</sup>. Then the energy conserving Dirac delta can be used to evaluate the  $dp_{3'}$  integral in the following way. First, we use  $E = \sqrt{p^2 + m^2}$  to rewrite the masses. Then we use momentum

<sup>1</sup>The angle  $\phi_{13'}$  is not measured with respect to  $\mathbf{p}_1$ , it is measured to some axis orthogonal to  $\mathbf{p}_1$ . We don't need to define that axis explicitly as long as the other angles  $\phi_{1i}$  are measured with respect to the same axis.

conservation to make the replacement  $\mathbf{p}_{2'} \rightarrow \mathbf{p}_1 + \mathbf{p}_2 - \mathbf{p}_{1'} - \mathbf{p}_{3'}$ :

$$\begin{aligned}
E_1 + E_2 &= E_{1'} + E_{2'} + E_{3'} \\
\Rightarrow \sqrt{p_1^2 + m_1^2} + \sqrt{p_2^2 + m_2^2} &= \sqrt{p_{1'}^2 + m_{1'}^2} + \sqrt{p_{2'}^2 + m_{2'}^2} + \sqrt{p_{3'}^2 + m_{3'}^2} \\
\Rightarrow \sqrt{p_1^2 + m_1^2} + \sqrt{p_2^2 + m_2^2} &= \sqrt{p_{1'}^2 + m_{1'}^2} + \sqrt{(\mathbf{p}_1 + \mathbf{p}_2 - \mathbf{p}_{1'} - \mathbf{p}_{3'})^2 + m_{2'}^2} + \sqrt{p_{3'}^2 + m_{3'}^2}.
\end{aligned} \tag{1.5}$$

We would like to solve eqn. (1.5) for  $p_{3'}$ , but there is a problem coming from the fact that  $p_{3'}$  appears under two square root symbols which makes it impossible to get an expression of the form  $p_{3'} = \dots$ . Instead, we will make the approximation that because  $p_{3'} \ll p_i$  for  $i \in \{1, 2, 1', 2'\}$  that we can ignore the  $p_{3'}$  that shows up in  $\sqrt{(\mathbf{p}_1 + \mathbf{p}_2 - \mathbf{p}_{1'} - \mathbf{p}_{3'})^2 + m_{2'}^2}$ . The result we obtain when solving for  $p_{3'}$  is then

$$\begin{aligned}
p_{3'} &= \left[ m_1^2 + m_{1'}^2 + m_2^2 + m_{2'}^2 - m_{3'}^2 + 2p_1^2 - 2p_1 p_{1'} c_{11'} + 2p_{1'}^2 - 2E_1 E_{1'} \right. \\
&\quad + 2p_1 p_2 c_{12} - 2p_2 p_{1'} c_{21'} + 2p_2^2 + 2E_1 - 2E_{1'} E_2 \\
&\quad - 2E_1 E_{2'}(p_1, p_2, p_{1'}, c_{11'}, c_{12}, c_{21'}) + 2E_{1'} E_{2'}(p_1, p_2, p_{1'}, c_{11'}, c_{12}, c_{21'}) \\
&\quad \left. - 2E_2 E_{2'}(p_1, p_2, p_{1'}, c_{11'}, c_{12}, c_{21'}) \right]^{1/2}
\end{aligned} \tag{1.6}$$

where  $E_i \equiv \sqrt{p_i^2 + m_i^2}$ ,  $c_{ij} \equiv \cos \theta_{ij} \equiv \mathbf{p}_i \cdot \mathbf{p}_j / (p_i p_j)$  and

$$E_{2'}(p_1, p_2, p_{1'}, c_{11'}, c_{12}, c_{21'}) = \sqrt{p_1^2 - 2p_1 p_{1'} c_{11'} + p_{1'}^2 + 2p_1 p_2 c_{12} - 2p_2 p_{1'} c_{21'} + p_2^2 + m_{2'}^2}. \tag{1.7}$$

Now that we have an expression for  $p_{3'}$  the requirement that  $p_{3'}$  must be real and non-negative restricts the domain of integration of the other variables. I am not sure how to derive the new limits so I got stuck here.

## 1.2 A recursive expression for phase space integrals

The following regurgitates parts of [1, 2]. The problem I ran into at the end of the last section was how to use the energy-momentum delta functions to restrict the bounds of integration. Ref. [1] provides a means to circumvent this problem by performing a change of variables. Consider the phase space integral  $R_n(p_a + p_b)$  defined by (where  $p_i$  now denotes a four-momentum vector in contrast to the previous section where it represented a three-momentum magnitude.)

$$R_n(p_a + p_b) = \int \cdots \int \prod_{i=1}^n \delta(p_i^2 - m_i^2) \Theta(p_i^0) d^4 p_i \delta^4(p_a + p_b - p_1 - \cdots - p_n). \tag{1.8}$$

This is manifestly Lorentz invariant and therefore  $R_n$  may only be a function of  $s \equiv (p_a + p_b)^2$ . Define the new integration variable  $M_{n-1}^2 \equiv (p_a + p_b - p_n)^2$ . The physical significance of  $M_{n-1}$  is that it is the invariant mass of the first  $n-1$  particles, which can be seen using four-momentum conservation:  $p_a + p_b - p_n = p_1 + p_2 + \cdots + p_{n-1}$ . It is possible to show that the following recursive relation holds (eqn. (3) of [1])

$$R_n(s) = \int_{(m_1 + m_2 + \cdots + m_{n-1})^2}^{(\sqrt{s} - m_n)^2} dM_{n-1}^2 \int d\Omega_n \frac{\sqrt{\lambda(s, M_{n-1}^2, m_n^2)}}{8s} R_{n-1}(M_{n-1}^2) \tag{1.9}$$

where  $\lambda(x, y, z) = x^2 + y^2 + z^2 - 2xy - 2xz - 2yz$  and the solid angle  $d\Omega_n \equiv d\cos\theta_n d\varphi_n$  defines the direction of  $\mathbf{p}_n$  in the frame where  $p_a + p_b = (\sqrt{s}, \mathbf{0})$ . The upper limit is obtained by requiring that

$$|\mathbf{p}_n|^2 = \frac{\lambda(s, M_{n-1}^2, m_n^2)}{4s} \quad (1.10)$$

be positive whereas the lower limit is threshold below which  $R_{n-1}(M_{n-1}^2) = 0^2$ . Repeated application of eq. (1.9) yields

$$\begin{aligned} R_n(s) &= \int_{(m_1+m_2+\dots+m_{n-1})^2}^{(\sqrt{s}-m_n)^2} dM_{n-1}^2 \int d\Omega_n \frac{\sqrt{\lambda(s, M_{n-1}^2, m_n^2)}}{8s} \\ &\times \int_{(m_1+m_2+\dots+m_{n-2})^2}^{(M_{n-1}-m_{n-1})^2} dM_{n-2}^2 \int d\Omega_{n-1} \frac{\sqrt{\lambda(M_{n-1}^2, M_{n-2}^2, m_{n-1}^2)}}{8M_{n-1}^2} \\ &\times \dots \times \int_{(m_1+m_2)^2}^{(M_3-m_3)^2} dM_2^2 \int d\Omega_3 \frac{\sqrt{\lambda(M_3^2, M_2^2, m_3^2)}}{8M_3^2} \times \int d\Omega_2 \frac{\sqrt{\lambda(M_2^2, m_1^2, m_2^2)}}{8M_2^2}. \end{aligned} \quad (1.11)$$

The important case for me is when  $n = 3$ :

#### Phase space measure for $n = 3$

$$R_3(s) = \int d\Phi_3(s) = \int_{(m_1+m_2)^2}^{(\sqrt{s}-m_3)^2} dM_2^2 \int d\Omega_3 \frac{\lambda(s, M_2^2, m_3^2)}{8s} \int d\Omega_2 \frac{\lambda(M_2^2, m_1^2, m_2^2)}{8M_2^2}. \quad (1.12)$$

It's easy to verify that the number of integration variables matches our expectation of  $3(3) - 4 = 5$  since we are integrating over one invariant mass, and two pairs of two angles.

In the above discussion we have considered  $p_a$  and  $p_b$  to be fixed. However, for my purposes I will also be integrating over  $p_a$  and  $p_b$ . This case seems to be similar to the one considered in [2] (cf. the example given between their eqs. (12) and (13)).

### 1.3 Writing integral in terms of momentum transfers

In sec 1.2 we wrote the phase space integral in terms of invariant masses and angles of the three-momenta  $\mathbf{p}_i$  defined in the center-of-mass frame where  $\sum_{k=1}^i p_k = (M_i, \mathbf{0})$ . The matrix element in eq. (1.3) is a function of the Lorentz invariants  $(p_a \cdot p_1)$ ,  $(p_b \cdot p_3)$ ,  $(p_2 \cdot p_3)$ , and  $(p_b \cdot p_2) = -(p_a - p_1 - p_2 - p_3) \cdot p_2$ . It is cumbersome to write this matrix element explicitly in terms of the angles  $\{(\theta_i, \varphi_i) : i = 1, 2, \dots, n\}$  so we would rather use kinematic Lorentz invariants analogous to the Mandelstam variables for  $2 \rightarrow 2$  scattering<sup>3</sup>. To this end it is convenient to introduce the so-called ‘momentum transfers’  $t_i \equiv Q_i^2 \equiv (p_a - p_1 - \dots - p_i)^2 = (p_n + p_{n-1} + \dots + p_{i+1} - p_b)^2$ .

<sup>2</sup>In eq. (3) of [1] the authors allude that the angular  $d\Omega$  integrals can be performed. They do not perform the integrals because “the variables defining a momentum vector should appear explicitly if a Monte Carlo method is to be applied for the generation of events.” In my case I think that we still can’t do these integrals trivially because the matrix element depends on them, although I’m not 100% sure if this is correct.

<sup>3</sup>At least, I think that is the motivation for introducing these variables.

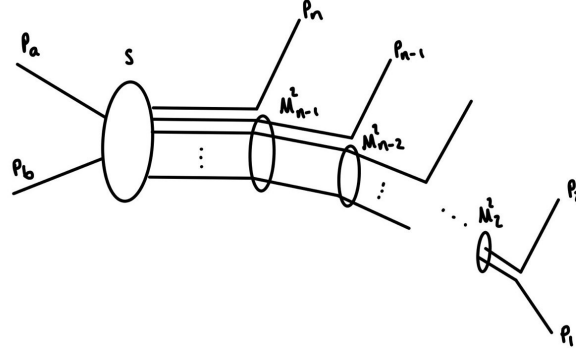


Figure 1: Illustration of the recursion relation as a sequence of effective  $2 \rightarrow 2$  scattering events.

Some of the dot products (but not all) may be written exclusively in terms of the kinematic variables. For example,

$$\begin{aligned}
 t_1 &\equiv (p_a - p_1)^2 && \rightarrow && 2p_a \cdot p_1 = m_a^2 + m_1^2 - t_1 \\
 t_2 &\equiv (p_a - (p_1 + p_2))^2 && \rightarrow && 2p_a \cdot p_2 = M_2^2 - m_1^2 + t_1 - t_2 \\
 t_3 &\equiv (p_a - (p_1 + p_2 + p_3))^2 && \rightarrow && 2p_a \cdot p_3 = M_3^2 - M_2^2 + t_2 \\
 M_2^2 &\equiv (p_1 + p_2)^2 && \rightarrow && 2p_1 \cdot p_2 = M_2^2 - m_1^2 - m_2^2 \\
 M_3^2 &\equiv (p_1 + p_2 + p_3)^2 && \rightarrow && 2(p_1 + p_2) \cdot p_3 = M_3^2 - 2M_2^2 + m_1^2 + m_2^2 - m_3^2 \\
 &&& && 2p_b \cdot p_3 = 2(p_1 + p_2) \cdot p_3 + 2m_3^2 - 2p_a \cdot p_3 = m_1^2 + m_2^2 + m_3^2 - M_2^2 - t_2
 \end{aligned}$$

However I was unable to write  $p_2 \cdot p_3$  in terms of the invariants alone.  $p_b \cdot p_2$  is really just  $p_2 \cdot p_3$  in disguise so it has the same problem. I believe this is because these variables are not enough to fully describe the system and some angles are required in addition. We need  $3(3) - 4 = 5$  integration variables but only 3 of them are prescribed by the kinematic invariants  $M_2^2$ ,  $t_1$ , and  $t_2$ <sup>4</sup>. I haven't followed their derivation through in enough detail to understand precisely how they show up in the expression .

The two additional degrees of freedom can be seen in eq. (14) of [1]. They are the azimuthal angles  $\varphi_1$ ,  $\varphi_2$  as seen in a frame where  $p_a = (m_a, \mathbf{0})$ .

## 2 Monte Carlo integration

### 2.1 The basics

Suppose you are interested in evaluating the integral

$$I = \int_a^b f(x) dx. \quad (2.1)$$

<sup>4</sup> $M_1^2 = m_1^2$ ,  $M_3^2 = s$  and  $t_3 = (-p_b)^2 = m_b^2$  are all constants, not integration variables.

Understand how to write the matrix element explicitly in terms of the angles  $\varphi_1$ ,  $\varphi_2$  as well as the invariants  $M_2^2$ ,  $t_1$ , and  $t_2$ .

The most obvious method of approximating this is with a Riemann sum or trapezoidal integration where you divide the domain into bins of width  $\Delta x$  and calculate the area of a rectangle or trapezoid using the values of  $f$  at the bin edges.

Monte Carlo integration, on the other hand, takes a different approach altogether whereby points in the domain are sampled at random and the integral is approximated as an average. To see this, note that the average value of  $f$  on the domain is

$$\langle f \rangle = \frac{1}{b-a} \int_a^b f(x) dx = \frac{I}{b-a}. \quad (2.2)$$

The average  $\langle f \rangle$  can be approximated by uniformly sampling  $N$  i.i.d random numbers  $x_i$  on the domain  $x \in [a, b]$  where  $i \in 1, 2, \dots, N$  and calculating the mean of  $f(x_i)$ :

$$\langle f \rangle \approx \langle f \rangle_N \equiv \frac{1}{N} \sum_{i=1}^N f(x_i). \quad (2.3)$$

Therefore we can approximate the integral  $I$  as

$$I \approx (b-a) \langle f \rangle_N. \quad (2.4)$$

This argument can be extended to higher dimensions, i.e. in  $n$  dimensions we have

$$I = \int_V f(\mathbf{x}) d^n x = V \langle f \rangle. \quad (2.5)$$

One important result is that this strategy always converges as  $N^{-1/2}$  in all dimensions, whereas techniques like trapezoidal integration converge rapidly in one dimension ( $N^{-2}$ ), but significantly slower for higher dimensions ( $N^{-2/n}$ ). For example in 5 dimensions, trapezoidal integration converges like  $N^{-2/5}$ , which is slower than Monte Carlo integration.

## 2.2 Importance sampling

In sec. 2.1 we sampled  $x$  uniformly at random on the domain of integration. However, we can choose to sample  $x$  from any arbitrary distribution  $p(x)$  and compute the same expectation value by weighting the sample  $f(x)$  by  $1/p(x)$  so that

$$I \approx \frac{V}{N} \sum_{i=1}^N \frac{f(x_i)}{p(x_i)}. \quad (2.6)$$

With an appropriate choice of  $p$  our Monte Carlo integration technique can be made to converge significantly faster than by sampling  $x$  uniformly at random. To see why this is, suppose  $f(x) = e^{-x^2}$  and  $[a, b] = [-1000, 1000]$ . Sampling uniformly on  $[-1000, 1000]$  means that the majority of points we pick will be in the tails of the Gaussian and will hardly affect the value of the integral. If instead we sampled from a standard normal distribution we would mostly choose  $x$  values near the peak at  $x = 0$  and our result would converge much more rapidly. Clearly the choice of  $p$  is heavily dependent on the particular shape of the integrand  $f$ . The Metropolis-Hastings algorithm is one way to generate samples  $x$  from  $p(x)$  and can be used for importance sampling.

VEGAS algorithm:

The discussion of the VEGAS algorithm at [https://www.ippp.dur.ac.uk/~krauss/Lectures/QuarksLeptons/Basics/PS\\_Vegas.html](https://www.ippp.dur.ac.uk/~krauss/Lectures/QuarksLeptons/Basics/PS_Vegas.html) is quite good. In case the link breaks in the future I reproduce some of the main points below.

“The VEGAS algorithm starts by dividing the  $n$ -dimensional hypercube  $[0, 1]^n$  into smaller ones – usually of identical size – and performs a sampling in each of them. The results are then used to refine the integration grid for the next iteration of the sampling procedure.”

## A Derivation of recursive relation

This appendix fills in the details for the derivation of eq. (1.9) which are left out in [1]. Our starting point is

$$\begin{aligned} R_n(s) &= \int \prod_{i=1}^n \delta(p_i^2 - m_i^2) \Theta(p_i^0) d^4 p_i \delta^4(p_a + p_b - p_1 - \cdots - p_n) \\ &= \int \delta(p_n^2 - m_n^2) \Theta(p_n^0) d^4 p_n \left[ \prod_{i=1}^{n-1} \delta(p_i^2 - m_i^2) \Theta(p_i^0) \right] \delta^4(p_a + p_b - p_n - p_1 - \cdots - p_{n-1}) \\ &= \int \delta(p_n^2 - m_n^2) \Theta(p_n^0) d^4 p_n R_{n-1}(p_a + p_b - p_n) \end{aligned}$$

Multiply the RHS by  $\int dM_{n-1}^2 \delta(M_{n-1}^2 - (p_a + p_b - p_n)^2)$ .

$$\int dM_{n-1}^2 \delta(M_{n-1}^2 - (p_a + p_b - p_n)^2) \delta(p_n^2 - m_n^2) \Theta(p_n^0) d^4 p_n R_{n-1}(p_a + p_b - p_n).$$

Use the on-shell delta function to do the  $p_n^0$  integral and write  $d^3 p_n$  in terms of spherical coordinates:

$$\begin{aligned} &\int dM_{n-1}^2 \delta(M_{n-1}^2 - (p_a + p_b - p_n)^2) \frac{d^3 p_n}{2E_n} R_{n-1}(p_a + p_b - p_n) \\ &= \int dM_{n-1}^2 \delta(M_{n-1}^2 - (p_a + p_b - p_n)^2) \frac{|\mathbf{p}_n|^2 d|\mathbf{p}_n| d\Omega_n}{2E_n} R_{n-1}(p_a + p_b - p_n). \end{aligned}$$

Then use the  $M_{n-1}^2$  Dirac delta to do the  $d|\mathbf{p}_n|$  integral. This requires us to (i) solve  $M_{n-1}^2 - (p_a + p_b - p_n)^2 = 0$  for  $|\mathbf{p}_n|$ ; (ii) evaluate  $d/d|\mathbf{p}_n|(M_{n-1}^2 - (p_a + p_b - p_n)^2)$ ; and (iii) impose  $|\mathbf{p}_n|^2 \geq 0$  to derive bounds of integration for  $\int dM_{n-1}^2$ .

(i) We start by expanding the LHS

$$\begin{aligned} M_{n-1}^2 - (p_a + p_b - p_n)^2 &= M_{n-1}^2 - (p_a + p_b)^2 - p_n^2 + 2(p_a + p_b) \cdot p_n \\ &= M_{n-1}^2 - s - m_n^2 + 2(E_a + E_b)E_n + 2(\mathbf{p}_a + \mathbf{p}_b) \cdot \mathbf{p}_n. \end{aligned}$$

Now we choose the center of mass frame so that  $\mathbf{p}_a + \mathbf{p}_b = 0$ . This is valid because the integral is a Lorentz invariant, so the final result is independent of the reference frame.

$$\begin{aligned} &M_{n-1}^2 - s - m_n^2 + 2(E_a + E_b)E_n + 2(\mathbf{p}_a + \mathbf{p}_b) \cdot \mathbf{p}_n \\ &= M_{n-1}^2 - s - m_n^2 + 2\sqrt{s} \sqrt{|\mathbf{p}_n|^2 + m_n^2} = 0. \end{aligned}$$

Now we can rearrange and solve for  $|\mathbf{p}_n|$

$$\begin{aligned} |\mathbf{p}_n|^2 &= \frac{(s + m_n^2 - M_{n-1}^2)^2}{4s} - m_n^2 = \frac{s^2 + m_n^4 + M_{n-1}^4 - 2sm_n^2 - 2sM_{n-1}^2 - 2m_n^2M_{n-1}^2}{4s} \\ &\equiv \boxed{\frac{\lambda(s, M_{n-1}^2, m_n^2)}{4s}}. \end{aligned}$$

$\lambda(x, y, z) = x^2 + y^2 + z^2 - 2xy - 2xz - 2yz$  is called the Källén function.

(ii)

$$\begin{aligned} &\frac{d}{d|\mathbf{p}_n|} \left( M_{n-1}^2 - (p_a + p_b - p_n)^2 \right) \\ &= \frac{d}{d|\mathbf{p}_n|} \left( M_{n-1}^2 - s - m_n^2 + 2\sqrt{s} \sqrt{|\mathbf{p}_n|^2 + m_n^2} \right) \\ &= \boxed{\frac{2\sqrt{s} |\mathbf{p}_n|}{E_n}} \end{aligned}$$

(iii)

$$\begin{aligned} &|\mathbf{p}_n|^2 \geq 0 \\ &\Rightarrow \lambda(s, M_{n-1}^2, m_n^2) \geq 0 \\ &\Rightarrow [M_{n-1}^2 - (s + m_n^2)]^2 - 4sm_n^2 \geq 0 \\ &\Rightarrow [M_{n-1}^2 - (s + m_n^2)]^2 \geq 4sm_n^2 \\ &\Rightarrow M_{n-1}^2 - (s + m_n^2) \geq 2\sqrt{s m_n^2} \parallel M_{n-1}^2 - (s + m_n^2) \leq -2\sqrt{s m_n^2} \\ &\Rightarrow M_{n-1}^2 \geq (s + m_n^2) + 2\sqrt{s m_n^2} \parallel M_{n-1}^2 \leq (s + m_n^2) - 2\sqrt{s m_n^2} \\ &\Rightarrow \boxed{M_{n-1}^2 \geq (\sqrt{s} + m_n)^2 \parallel M_{n-1}^2 \leq (\sqrt{s} - m_n)^2}. \end{aligned}$$

With these results established we find that

$$\delta(M_{n-1}^2 - (p_a + p_b - p_n)^2) = \frac{\delta(|\mathbf{p}_n| - \sqrt{\lambda(s, M_{n-1}^2, m_n^2)} / (2\sqrt{s}))}{2\sqrt{s} |\mathbf{p}_n| / E_n}. \quad (1.1)$$

Hence,

$$\begin{aligned} &\int dM_{n-1}^2 \delta(M_{n-1}^2 - (p_a + p_b - p_n)^2) \frac{|\mathbf{p}_n|^2 d|\mathbf{p}_n| d\Omega_n}{2E_n} R_{n-1}(p_a + p_b - p_n) \\ &= \int dM_{n-1}^2 \frac{\delta(|\mathbf{p}_n| - \sqrt{\lambda(s, M_{n-1}^2, m_n^2)} / (2\sqrt{s}))}{2\sqrt{s} |\mathbf{p}_n| / E_n} \frac{|\mathbf{p}_n|^2 d|\mathbf{p}_n| d\Omega_n}{2E_n} R_{n-1}(p_a + p_b - p_n) \\ &= \int dM_{n-1}^2 \frac{\sqrt{\lambda(s, M_{n-1}^2, m_n^2)}}{8s} d\Omega_n R_{n-1}(M_{n-1}^2). \end{aligned}$$



## References

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